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RESEARCH ARTICLE

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Key Points:

- New IASI-NH₃ retrieval approach based on a neural network
- Flexible NH₃ vertical profiles ease comparison with model and in situ data
- The impact of using ECMWF or GEOS-Chem vertical profile information leads to differences in the retrieved columns up to 50–60%

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A flexible and robust neural network IASI-NH₃ retrieval algorithm

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Abstract In this paper, we describe a new flexible and robust NH₃ retrieval algorithm from measurements of the Infrared Atmospheric Sounding Interferometer (IASI). The method is based on the calculation of a spectral hyperspectral range index (HRI) and subsequent conversion to NH₃ columns via a neural network. It is an extension of the method presented in Van Damme et al. (2014a) who used lookup tables (LUT) for the radiance-concentration conversion. The new method inherits the advantages of the LUT-based method while providing several significant improvements. These include the following: (1) Complete temperature and humidity vertical profiles can be accounted for. (2) Third-party NH₃ vertical profile information can be used. (3) Reported positive biases of LUT retrieval are reduced, and finally (4) a full measurement uncertainty characterization is provided. A running theme in this study, related to item (2), is the importance of the assumed vertical NH₃ profile. We demonstrate the advantages of allowing variable profile shapes in the retrieval. As an example, we analyze how the retrievals change when all NH₃ is assumed to be confined to the boundary layer. We analyze different averaging procedures in use for NH₃ in the literature, introduced to cope with the variable measurement sensitivity and derive global averaged distributions for the year 2013. A comparison with a GEOS-Chem modeled global distribution is also presented, showing a general good correspondence (within $\pm 3 \times 10^{15}$ molecules.cm⁻²) over most of the Northern Hemisphere. However, IASI finds mean columns about $1 - 1.5 \times 10^{16}$ molecules.cm⁻² (~50–60%) lower than GEOS-Chem for India and the North China plain.

1. Introduction

Ammonia (NH₃) is released to the atmosphere primarily by agricultural activities and biomass burning. It greatly impacts air quality and human health as a precursor of secondary aerosols and leads to acidification and eutrophication of ecosystems. We refer the reader to *Behera et al.* [2013, and references therein] for a review on the biogeochemical impacts of NH₃ and its role in the global nitrogen cycle.

Our present knowledge of atmospheric NH₃ levels comes from a combination of in situ measurements, from emission inventories coupled with models, and from satellite measurements. In situ measurements [e.g., *Flechard et al.*, 2011] are useful on local scales and can give insight into emission sources and different atmospheric processes at play. However, because of the highly reactive nature of NH₃—and thus its short lifetime—in situ observations contribute only indirectly to our knowledge of the global spatiotemporal variability of NH₃. Emission inventories, based mainly on livestock numbers, fertilizer application rates, and fire counts coupled with global chemistry-transport models, were until recently the only way of estimating the global distribution. But this modeling approach is still limited by the lack of reliable inventories and observations at a suitable spatial and temporal resolution. Current uncertainties on local and also global emissions hence remain very large, even when averaged over longer time periods [*Sutton et al.*, 2013].

The possibility of measuring NH₃ with infrared satellite sounders has allowed measuring NH₃ on a daily global basis. Since the first satellite observations of NH₃ were reported [*Beer et al.*, 2008; *Clarisse et al.*, 2009], continuous improvements have been made to the retrieval algorithms, increasing both sensitivity and accuracy. The potential of such measurements to improve our understanding and knowledge of emission sources, sinks,

and transport pathways through comparison and assimilation with models is huge [Streets *et al.*, 2013]. First exploitations of satellite data in this direction have appeared recently in the literature. Direct comparisons with global and regional models were performed in Heald *et al.* [2012] and Van Damme *et al.* [2014b]. Zhu *et al.* [2013] and Fortems-Cheiney *et al.* [2016] used satellite observations to constrain NH_3 emission used as input for modeling activities. Finally, Whitburn *et al.* [2015] made a first assessment of state-of-the-art fire inventories, while Luo *et al.* [2015] investigated NH_3 :CO ratios. However, satellite data are currently not exploited to the fullest, in part because satellite measurements of NH_3 are challenging to work with due to the variable accuracy of the measurements and lack of vertical profile information. In this paper we outline a novel flexible and robust NH_3 retrieval algorithm, which was specifically designed to overcome some shortcomings of the current algorithms and more importantly facilitate future assimilation in models and comparison with ground-based measurements. In the rest of section 1, we give a brief historical account of NH_3 satellite measurement techniques, highlighting the strengths and weaknesses of the different algorithms before introducing the benefits of this new neural-network-based retrieval.

Satellite observations of NH_3 were first reported from measurements of the Tropospheric Emission Spectrometer (TES) [Beer *et al.*, 2008]. Shortly after that, the Infrared Atmospheric Sounding Interferometer (IASI) was also shown capable of measuring NH_3 , first in fire plumes [Coheur *et al.*, 2009] and later on a global scale [Clarisse *et al.*, 2009]. This first global study relied on conversion of a brightness temperature difference to a column via a constant multiplicative factor. While this method allows processing of large amounts of data in a short time, it is neither very sensitive nor accurate. An accurate but typically computationally heavy method for the retrieval of trace gas concentrations is the optimal estimation method [Rodgers, 2000]. It has been applied to NH_3 measurements from IASI on a local scale in Clarisse *et al.* [2010] and later on a global scale as reported by Heald *et al.* [2012] over the U.S. Unfortunately, the latter reported problems with the measurement characterization, which hampers comparison with models. For this, and also computational reasons, the global IASI product based on optimal estimation has not been developed further. Note that a successful global implementation of optimal estimation (with realistic averaging kernels) was reported in Shephard *et al.* [2011] from TES measurements, albeit TES has significantly less data than IASI. More recently, Shephard and Cady-Pereira [2015] and Warner *et al.* [2015] successfully implemented an optimal estimation method on tropospheric NH_3 for Cross-track Infrared Sounder (CrIS) and Atmospheric Infrared Sounder (AIRS) measurements, respectively.

Optimal estimation techniques are based on iterative spectral fitting, minimizing at the same time the residual between the measured and calculated spectrum and the distance between the measurement outcome and a priori information. Fitting spectrally interfering species and using full radiative transfer calculations allows for potentially very accurate measurements. The use of a priori information allows dealing efficiently with the general ill-conditioned nature of inverse problems in remote sensing and with variable measurement sensitivity. In addition, the optimal estimation framework provides a full measurement characterization (measurement errors and averaging kernels) that is useful for model assimilation and comparison with other in situ observations. A disadvantage of this type of method includes slow computational performance (which in case of sounders with a high spatial sampling like IASI is a real issue). In the infrared, variable surface emissivity and cloud coverage are very important parameters to take into account for accurate forward simulations. In practice, retrievals are often performed on a restricted spectral range to avoid systematic errors due to interfering gases and so that accurate simulation of the baseline is not needed. While this choice also has computational benefits, by restricting the spectral range, the raw spectral measurement is not used to its full potential. Another argument against optimal estimation methods for the retrieval of NH_3 is that choosing a representative a priori and covariance matrix for each single measurement on a global scale is not always straightforward because of the extreme variability in NH_3 concentrations.

In parallel with these first global quantitative products, Walker *et al.* [2011] proposed a pseudoquantitative detection method specifically developed for highly variable weak absorbers which are not observed in each spectrum. One key element of the method is a covariance matrix S_y built from measurements where the target species is not observed (so here spectra not containing observable amounts of NH_3). Such a covariance matrix is a powerful statistical characterization of the expected correlations between the different spectral channels in the absence of observable NH_3 . The detection method itself is a covariance weighted projection

of an arbitrary spectrum y onto the NH_3 spectral signature (a spectral Jacobian K corresponding to a change in NH_3) resulting in a single pseudoquantitative number (called hereafter HRI, for “hyperspectral range index”):

$$\text{HRI} = \frac{K^T S_y^{-1} (y - \bar{y})}{\sqrt{K^T S_y^{-1} K}}, \quad (1)$$

with \bar{y} a mean background spectrum associated with S_y . Note that the HRI defined here is normalized such that it has a mean of zero and a standard deviation of 1 for spectra without observable quantities of NH_3 . When the HRI exceeds 3 or 4 (standard deviations) one can be reasonably confident that detectable NH_3 are present in the observed scene. This method is derived from the main formula appearing in optimal least squares estimates but turns out to be equivalent to the statistical method called “linear discrimination analysis,” which is commonly used in classification problems [Clarisse *et al.*, 2013]. The HRI detection method is fast and extremely sensitive (up to an order of magnitude more sensitive than brightness temperature difference techniques), because very wide spectral ranges can be used and because it captures spectral correlation better than forward models can. A forward model is used only for the calculation of the Jacobian, but since Jacobians are essentially spectral *differences*, the majority of the forward model errors cancel out. Thus, the errors introduced to the HRI by the forward model are, in general, unimportant. As such, the detection method avoids a lot of the problems of regular optimal estimation methods.

The HRI, a measure for the NH_3 signature strength in the spectrum, is not only dependent on the amount of NH_3 but through the radiative transfer also on the thermal state of the atmosphere. The principal parameter here is the thermal contrast defined as the temperature difference between the atmospheric boundary layer and the surface. For a fixed NH_3 column, a larger thermal contrast (TC) will give rise to larger spectral signatures and vice versa. HRIs can therefore be converted into reasonably accurate columns by taking into account the thermal contrast via two-dimensional lookup tables (LUT) mapping the pair (HRI, TC) to NH_3 columns. A retrieval algorithm based on this idea was developed in Van Damme *et al.* [2014a], who also presented a way to realistically estimate uncertainties for each measurement. The high sensitivity of this LUT-based HRI method was apparent in this first study with the discovery of a large number of new highly localized hot spots, retrieval results for the evening overpass of IASI, and for the first time detection of NH_3 transport over oceans. Quantitatively, the algorithm showed a good correlation with independent retrievals using optimal estimation techniques. These measurements were compared with the LOTOS-EUROS model output in Van Damme *et al.* [2014b] and to in situ measurements in Van Damme *et al.* [2015a], and agreement was overall achieved within measurement uncertainty, although limitations of both models and in situ measurements were also exposed. These studies also highlighted the difficulties in comparing satellite measurements with models or in situ data and stressed the need to very carefully take into account the measurement uncertainties. They also exposed the following limitations of the LUT-based HRI method: (1) Using constant NH_3 vertical profiles can introduce potentially large errors (in Van Damme *et al.* [2014a], one fixed profile over land is used which peaks at the surface and one over oceans which peaks around 1400m). (2) While TC is taken into account, residual dependencies on, for instance, the complete temperature profile are not. (3) Instrumental noise causes a high bias of the measurements [Van Damme *et al.*, 2015a], as a result of the fact that each HRI is always converted into a *positive* column. Especially for observations where the sensitivity to NH_3 is low this can lead to drastic positive mean biases (even if the associated estimated uncertainty on the individual observations are correct).

In this paper we propose an extension of the LUT-based HRI method from Van Damme *et al.* [2014a]. Instead of using a two-dimensional LUT, we use here a feedforward neural network (NN) for the conversion of HRI to NH_3 columns. A NN can approximate any (unknown or difficult to calculate) function $Y = f(x)$ (under mild assumptions) by a transfer function $F(W, x)$ which can be readily evaluated. The weights W of the function F are obtained via training on a training set $\{y_i = f(x_i)\}$ (see, e.g., Hadji-Lazaro *et al.* [1999] and Turquety *et al.* [2004] for earlier satellite retrieval schemes that used NNs). As both rely on a database of training data, a NN can be seen as a generalization of a LUT. However, the important difference is that a LUT needs to store an output value for each combination of its input parameters, and the size of the LUT therefore grows exponentially with the dimension of the table. The great strength of a NN lies in its ability to cope with hundreds of input parameters, thereby offering a lot more flexibility than a two-dimensional LUT, while not requiring the expensive and, in many cases, repetitive calculations of spectral fitting approaches. So rather than using TC as an input parameter, the NN allows use of the full temperature profile as input. Other input parameters that we will use are surface emissivity, surface temperature, the pressure and water vapor vertical profiles, satellite viewing angle, and information on the vertical profile shape of NH_3 .

Cases	1	2	3	4	5	6	7	8	9
% deviation from NH ₃ column based on land LUT (Van Damme <i>et al.</i> , 2014)	-53.4	-44.9	-32.2	-8.4	+11.8	0	+3	+14.9	+41.4
NH ₃ profile shape (* in km)	A * = 0.1	A * = 0.5	A * = 1	A * = 2	A * = 3	B	C * = 0.5	C * = 1	C * = 2

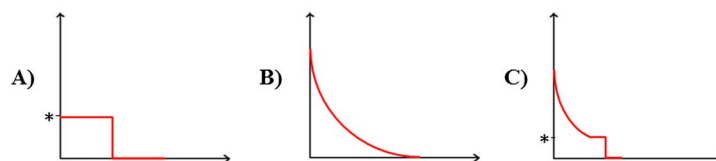


Figure 1. (top) Deviation (%) between total columns retrieved from simulated spectra based on various vertical profiles and the total column obtained with the reference land profile (case 6). (bottom) profile shapes considered in volume mixing ratios (VMR). Cases 1 to 5 (profile A) correspond to a well-mixed distribution up to a maximum altitude of 100 m, 500 m, 1 km, 2 km, and 3 km and with absence of NH₃ above these limits; case 6 (profile B) is the reference land profile used for the LUT over land in Van Damme *et al.* [2014a]; cases 7 to 9 (profile C) correspond to well-mixed distribution up to 500 m, 1 km, and 2 km and with the case 6 distribution above these limits.

In the next section we explore the importance of NH₃ vertical profiles for satellite retrievals and propose a three-parameter formula which can be used to describe NH₃ vertical profiles. The NN retrieval itself is detailed in section 3 (setup, training, evaluation, and uncertainty characterization). In section 4 we give a first assessment of the impacts of using variable NH₃ profiles on a global scale. In sections 5 and 6, we provide global annual mean distributions of retrieved NH₃ columns and compare the satellite measurements with Goddard Earth Observing System (GEOS)-Chem modeled distributions. Note that for this study the retrieval algorithm was developed for the IASI sounder [Clerbaux *et al.*, 2009; Hilton *et al.*, 2011] but that it could easily be adapted to any other high-resolution infrared sounder capable of sounding NH₃ such as AIRS, TES [Shephard *et al.*, 2011], or CrIS [Shephard and Cady-Pereira, 2015].

2. NH₃ Vertical Profiles

As a highly reactive compound, NH₃ has a relatively short lifetime ranging from a few hours to 5 days [Baek and Aneja, 2004] and a large spatiotemporal variability [Van Damme *et al.*, 2015b]. In addition to an important horizontal heterogeneity, NH₃ can also present highly variable vertical distributions which will affect the sensitivity of IASI to the NH₃ column. In this section, we first give an assessment of the sensitivity of infrared IASI-NH₃ column retrievals to the vertical profile used as input in the processing chain and then detail how the vertical distributions were characterized in the NN.

2.1. Infrared Sensitivity to Profile

Here we illustrate the impact of assumed NH₃ vertical distributions on retrieved IASI-NH₃ columns. For this, we have simulated a set of spectra based on different profile shapes (shown in volume mixing ratios (VMR) at the bottom of Figure 1), while other input parameters were kept constant. From these spectra, a NH₃ column was retrieved using the LUT method of Van Damme *et al.* [2014a] which uses a fixed profile (see case 6 in Figure 1). Results of the impact assessment of varying vertical distributions are presented in Figure 1 as a percentage of deviation from the true NH₃ column. Errors introduced by an inappropriate vertical profile can be as large as 50%. A complementary analysis (not shown here) revealed that for transported NH₃ plumes or NH₃ at higher altitude, the errors can be even larger.

A good representation of the NH₃ vertical profile is therefore needed to increase the accuracy of NH₃ satellite retrievals. Table 1 gives a list of representative NH₃ profile measurements. The vertical evolution of NH₃ emitted from the ground can be observed in the first atmospheric layers with surface instruments [e.g., Erisman *et al.*, 1988], but the majority of the measured profiles useful for satellite retrievals are acquired by airborne instruments. These cover a larger part of the tropospheric column, provide useful probing of the vertical distribution inside the column, and allow consistent validation of satellite quantities [e.g., Sun *et al.*, 2015; Shephard *et al.*, 2015; Van Damme *et al.*, 2015a]. Nevertheless, the spatial and temporal coverage of such data sets is very heterogeneous, as the majority of observations are acquired during dedicated campaigns.

Table 1. NH₃ Vertical Measurements in the Literature

Authors	Location	Measurement Technique	Altitude Range	Period Covered	Comments
<i>Geordii and Muller</i> [1974]	Bavaria, Germany	automated wet chemical methods (airborne)	0–4,000 m	November 1969 to September 1972	
<i>Hoell et al.</i> [1980]	Virginia, United States	remote infrared heterodyne radiometer (ground-based)	0–15,000 m	1979	
<i>LeBel et al.</i> [1985]	Maryland and Virginia, United States	tungsten oxide denuder system (airborne)	0–3,000 m	March and September 1983	
<i>LeBel et al.</i> [1985]	North Atlantic ocean and Bermuda	tungsten oxide denuder system (airborne)	0–5,300 m	August 1982	First NH ₃ profile measured over oceans
<i>Alkezweeny et al.</i> [1986]	Kentucky, United States	tungsten oxide denuder system (airborne)	380–3,580 m	Summer 1983	Poor vertical resolution (2 to 4 observations/flight)
<i>Ziereis and Arnold</i> [1986]	Federal Republic of Germany	modified ion mass spectrometer (airborne)	0–10,000 m	11, 14, and 15 May 1985	
<i>Erismann et al.</i> [1988]	Cabauw, Netherlands	two denuder tubes and a filterpack (ground-based and tower)	0–200 m	30 days (not specified)	
<i>Yokelson et al.</i> [1999]	North Carolina, United States	Fourier transform infrared spectrometer (airborne)	84–598 m	April 1997	not a dedicated campaign
<i>Nowak et al.</i> [2007]	New York City and Georgia, United States	chemical ionization mass spectrometer (airborne)	not specified	July–August 2004	2004 NEAQS-ITCT campaign
<i>Nowak et al.</i> [2010]	Houston, United States	chemical ionization mass spectrometer (airborne)	0–5,500 m	16 September to 13 October 2006	
<i>Nowak et al.</i> [2012]	California, United States	chemical ionization mass spectrometer (airborne)	not specified	4 May to 20 June 2010	CalNex campaign [Parrish, 2014]
<i>Leen et al.</i> [2013]	Washington, United States	quantum cascade laser (airborne)	100–2,800 m	24–25 May 2012	
<i>Müller et al.</i> [2014]	Fresno, California, United States	proton transfer reaction time-of-flight mass spectrometer (airborne)	30–2,500 m	January/February 2013	Discover-AQ campaign
<i>Schiferl et al.</i> [2014]	California, United States	chemical ionization mass spectrometer (airborne)	0–6,000 m	May–June 2010	CalNex campaign [Parrish, 2014]
<i>Sun et al.</i> [2015]	California, United States	cavity ring down spectrometer and a proton transfer reaction time-of-flight mass spectrometer (airborne)	30–2,500 m	21, 28, and 30 January 2013	Discover-AQ campaign (additional flights on 23 January and 6 February)
<i>Shephard et al.</i> [2015]	Canadian oil sands, Canada	dual quantum cascade laser (airborne)	150–6,400 m	3 and 5 September 2013	

As we will demonstrate, the proposed NN retrieval product can make optimal use of ancillary vertical profile data. However, given the limitations of in situ data, we will in first instance make use of vertical distributions from atmospheric models. While these have generally not been validated, a few local assessments have been performed when NH₃ vertical profile observations were available [e.g., *Schiferl et al.*, 2014]. The spatial resolution of global models is also more representative for satellite instruments and allows a direct implementation of the NH₃ vertical distributions in the retrieval processing chain.

2.2. A General Formula

From the previous section, it is clear that better accuracy in the retrieval will be achieved by considering realistic vertical profiles. Therefore, vertical profile information should be incorporated in the input parameters in the NN. For this, it is necessary to parametrize the continuous vertical profile using a suitable analytical function. An analysis was made of the GEOS-Chem (www.geos-chem.org) v8.03.01 global chemical

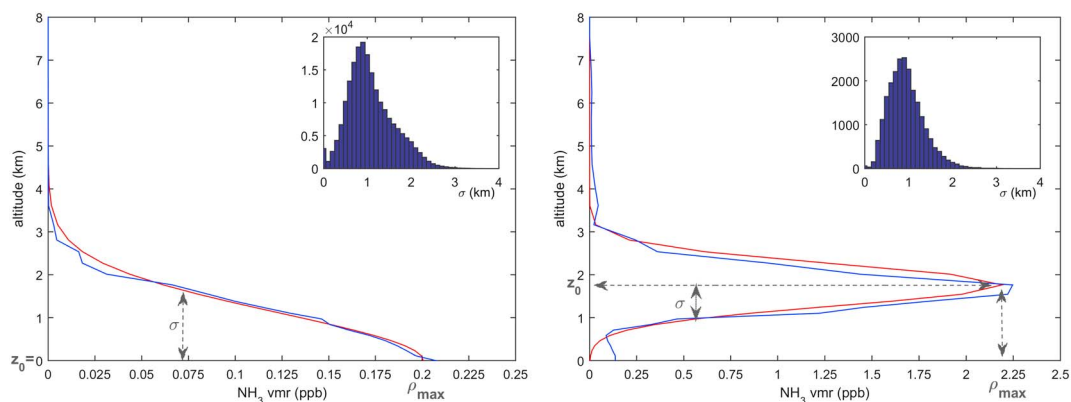


Figure 2. Example of GEOS-Chem model (blue) and fitted (red) profiles (left) above a source area and (right) characteristic of transport with z_0 , σ , and ρ_{\max} indicated. The top right insets are histograms of σ derived from fitting to a representative set of GEOS-Chem profiles.

transport model (CTM) profiles for the year 2009. The GEOS-Chem oxidant-aerosol simulation includes H_2SO_4 - HNO_3 - NH_3 aerosol thermodynamics coupled to an ozone- NO_x -hydrocarbon-aerosol chemical mechanism [Park et al., 2004]. Partitioning of total ammonia and nitric acid between the gas and particle phases is calculated using the ISORROPIA II thermodynamic equilibrium model [Fountoukis and Nenes, 2007] as implemented in GEOS-Chem by Pye et al. [2009]. Among the functions that were tried, the following three-parameter Gaussian function was found to be able to approximate most GEOS-Chem profiles to good accuracy:

$$\rho = \rho_{\max} e^{-\left(\frac{z-z_0}{\sigma}\right)^2}, \quad (2)$$

with ρ_{\max} the maximum NH_3 concentration (in ppb), z_0 the peak height of the profile (in km), and σ a measure for the spread or thickness of the NH_3 layer (in km). As an example, Figure 2 shows two vertical NH_3 profiles from GEOS-Chem (one representative for source (left), one for transport (right)), together with their Gaussian fit. We found that about 73% of the GEOS-Chem profiles could be fitted to a high accuracy with the proposed formula. The remaining profiles were found to have multiple maxima. The insets in Figure 2 are histograms of the σ parameter of representative GEOS-Chem profiles with a NH_3 total column larger than 5×10^{14} molecules. cm^{-2} , separately for source (profiles peaking at the surface) and transported conditions. They show that most profiles have a σ around 1 and virtually all modeled profiles a σ between 0 and 2.

3. The Neural Network

3.1. Training Set

The main idea of the proposed retrieval approach is to map the HRI to NH_3 columns via a NN. As explained in section 1 a NN is built via training. Ideally, the training set should be as large, as accurate, and as extensive as possible, and input data in the training should be representative of the real input data. A description of the principles of operation of a supervised NN for atmospheric remote sensing can be found in Hadji-Lazaro et al. [1999], Turquety et al. [2004], and Blackwell and Chen [2009]. In this section, we explain how the NN training set was built.

Since a reference data set of IASI- NH_3 is not available, we built a synthetic training set using forward simulations with the Atmosphit line-by-line radiative transfer model [Coheur et al., 2005]. To be representative for IASI observations, background atmospheric conditions were taken from 1 year of thermodynamic atmospheric profiles provided by the meteorological Level 2 information from the operational IASI processor [August et al., 2012]. Most profiles (about 88%) were taken above land because of the larger variability encountered in the atmospheric conditions (e.g., thermal contrast, pressure profiles, and emissivity). NH_3 vertical profiles were constructed following equation (2), where the three input parameters were varied randomly: σ values were taken randomly between 0.25 and 2.5 km, and z_0 was set to 0 for 90% of the profiles (representative for source profiles) and set randomly between 0 and 10 km for the remaining 10% (representative for transported profiles). ρ_{\max} was taken randomly between 0 and 20 ppb. To account for background trace levels of NH_3 , a mean constant NH_3 background profile was added to each polluted profile. This background profile was

calculated as the mean of GEOS-Chem profiles with a NH_3 column below 5×10^{14} molecules. cm^{-2} . For the simulations, the vertical sampling of these NH_3 profiles was set to 1 km with a finer division of 0.2 km applied in a layer of 4 km around the peak height (z_0). About 250,000 IASI spectra were simulated both with and without NH_3 (500,000 spectra in total).

We do not need the actual spectra as training data, but rather the derived HRI values. These were calculated following equation (1) but with one important difference. From early tests, it was clear that simulated spectra with a zero NH_3 column often had a rather large HRI value, probably related to inaccuracies in the forward model. To make the training data set as accurate as possible, we simulated for each spectrum y a twin spectrum y_{wo} , with a zero NH_3 column and calculated the HRI as

$$\text{HRI} = \frac{K^T S_y^{-1} (y - y_{\text{wo}})}{\sqrt{K^T S_y^{-1} K}}. \quad (3)$$

The HRI calculated in this way is noise free (as mentioned in section 1, HRIs of spectra without observable NH_3 do have a mean HRI of 0 but a standard deviation of 1). Finally, note that in the calculation of the HRI (equation (3)) we used angular dependent K , \bar{y} , and S as in *Bauduin et al.* [2016] because of the dependence of the signal strength on the viewing angle. We refer to this paper also for a detailed explanation for the rationale behind this.

3.2. The Setup, Training, and Evaluation

With the calculated HRI and the atmospheric parameters used for the construction of the associated spectra, we next trained the NN. We chose a supervised two-layer feedforward network: one hidden layer of 15 neurons with sigmoid transfer functions and one output layer of one linear neuron. The training was performed using the Levenberg-Marquardt backpropagation algorithm. For the training, the training set was divided into three distinct groups: (1) the training set strictly speaking, (2) a validation set, and (3) a test set. The selection of the training, validation, and test sets was performed randomly by considering a distribution of 85%-10%-5%. Eight different parameters were selected as inputs for the NN. These are the surface temperature, the temperature, pressure, and humidity profiles, all four provided by the meteorological Level 2 information from the operational IASI processor [August et al., 2012]; the σ and z_0 parameters describing the shape of the NH_3 vertical profiles; the surface emissivity (ϵ); and the viewing angle of the satellite. The temperature, pressure, and humidity profiles are described by 12, 11, and 7 levels, respectively. Surface emissivities over land were taken from the 2014 monthly mean spectral emissivity database provided by *Zhou et al.* [2011]. Over sea, emissivities were taken from the *Nalli et al.* [2008] emissivity database. These spectral emissivities were averaged over the range [800–1010; 1065–1200] cm^{-1} . The 1010–1065 cm^{-1} region was excluded to avoid interferences from the ν_3 ozone band. The NN output parameter was set as the ratio of the NH_3 total column to the HRI. The relationship between the input and the output parameters can be written as

$$\text{NH}_3 \text{ column} = \text{HRI} \times f(T, T_{\text{surf}}, P, \text{H}_2\text{O}, \sigma, z_0, \epsilon, \text{angle}). \quad (4)$$

The rationale of using the ratio rather than the NH_3 total column itself is that the ratio has a smaller dynamic scale, which allows for a much better training of the network. Also, working with the ratio ensures that the uncertainty on the HRI (mainly caused by instrumental noise) is translated in a linear way to the retrieved column. The sign of the ratio f will depend on the exact vertical profile of NH_3 and the atmospheric temperature but will mostly follow the sign of the TC. Note that the ratio itself is totally independent of the HRI value (owing to the linear relationship between the HRI and the NH_3 column in the range of NH_3 column values usually encountered), and that noise on the HRI can result in negative NH_3 columns. This has a number of benefits which will be discussed further on.

To assess the performance of the training, we have calculated for the whole training set the mean relative error and relative bias of the retrieved columns (\hat{y}) over the actual columns y per bin of 1 K of TC and 2.5×10^{15} molecules. cm^{-2} of NH_3 total column:

$$\overline{\text{Error}} = \frac{1}{n} \sum_{k=1}^n \left| \frac{\hat{y}_k - y_k}{y_k} \right| \times 100, \quad (5)$$

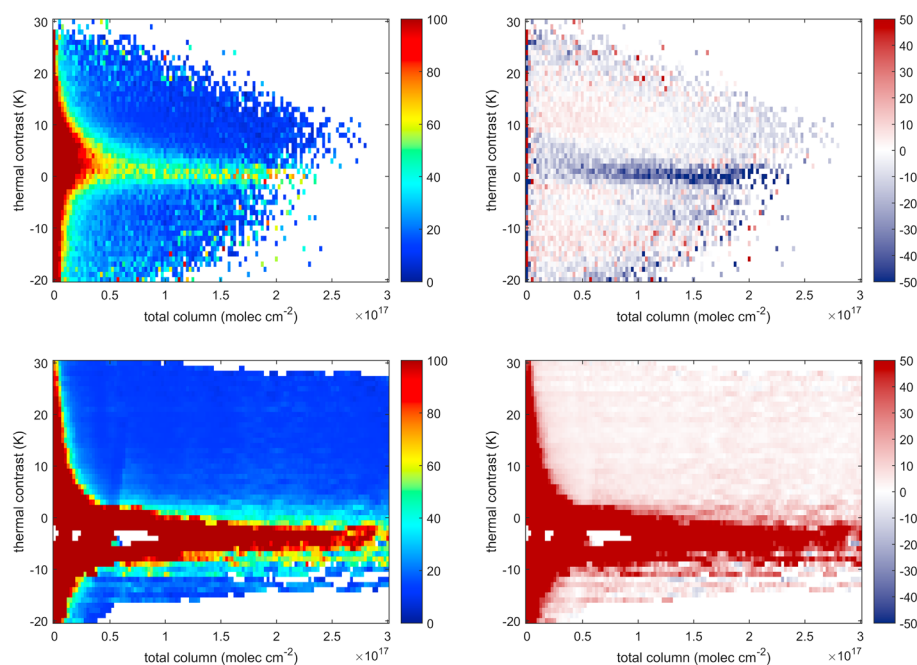


Figure 3. Evaluation of the training of the neural network. The color bar represents (left column) the mean error (%) and (right column) bias (%) between the real state and the output from (top row) the NN-based and (bottom row) the LUT-based HRI method used in *Van Damme et al.* [2014a].

$$\overline{\text{Bias}} = \frac{1}{n} \sum_{k=1}^n \frac{\hat{y}_k - y_k}{y_k} \times 100. \quad (6)$$

To make the assessment more representative of real IASI measurements, we have added normally distributed noise on the HRI. The results are shown in Figure 3 as a function of TC and NH_3 column. To compare, the mean error and bias calculated from the LUT-based HRI method are given as well (here we used the forward simulations used to build the LUT). The TC (K), which drives the sensitivity of the IR measurements to boundary layer concentrations, is defined here as the difference between the surface temperature and the temperature at 1.5 km of altitude. The comparison between the two methods shows a clear improvement of the NN compared to the LUT, both in the mean and the bias, especially for low TCs. As expected, largest errors ($>100\%$) are found for low TCs (low sensitivity) since a large fraction of NH_3 vertical profiles peak at the surface ($z_0 = 0$) and rapidly decrease with altitude. Relative errors are also large for low NH_3 total columns (but in this case absolute errors can still be small).

For the NN-based method, the mean error rapidly decreases with increasing TC and total column and becomes lower than 30% (40%) for TC above (below) +10 K (−10 K) and total column higher than about 5×10^{16} molecules. cm^{-2} . The corresponding mean bias is generally below 10% except at low TC (between 0 and 5 K) for high NH_3 columns ($>1 \times 10^{17}$ molecules. cm^{-2}) where an underestimation of about 40% is observed. For the LUT-based method in contrast, a large mean overestimation ($>50\%$) is observed at low NH_3 columns or low TC up to high total columns ($>3 \times 10^{17}$) but associated with large mean uncertainties ($>100\%$). This overestimation is due to the instrumental error on the HRI (represented here by the random noise added on the HRI) which results in a nonzero HRI, even in the absence of NH_3 . In the LUT-based HRI method, these nonzero HRIs are converted into positive NH_3 total columns introducing therefore a systematic positive bias in the mean. In contrast, in the NN-based method this bias is lower owing to the parametrization of the NN which allows negative value of NH_3 columns for low (positive or negative) values of HRI, resulting in a mean bias close to 0.

3.3. Retrieval, Uncertainty Estimate, and Example

For the actual retrieval we first filtered out observations with a cloud fraction inside the IASI field of view above 25%, since our training data did not include clouds. Then for the remaining observations the different input parameters of the NN were gathered. Atmospheric profiles (water vapor, pressure, and temperature) were

taken from the IASI meteorological L2. Surface emissivities were taken as the mean of the spectral emissivity in the range [800–1010; 1065–1200] cm^{-1} from the 2014 monthly mean database provided by Zhou *et al.* [2011] (for land measurements) and from the Nalli *et al.* [2008] database for sea measurements. HRIs were calculated following equation (1) (with again angular dependent K , \bar{y} , and S). In first instance, and to ease comparison with the LUT product, we used fixed values for the σ and z_0 input parameters by fitting the single NH_3 profiles used for land and sea in the LUT-based HRI method [Van Damme *et al.*, 2014a]. We found $z_0 = 0$; $\sigma = 1.07$ km and $z_0 = 1.4$; $\sigma = 1.28$ km for land and sea profiles respectively. These are used as default values for σ and z_0 , unless specifically otherwise stated.

After application of the network, a filter is applied to remove unphysical retrievals associated with errors in the input parameters. Retrievals are removed when (1) negative columns are associated with a HRI above 1.5 in absolute value and (2) the ratio of NH_3 column to the HRI is higher than 3×10^{16} . The first criterion guarantees that negative columns are only possible for NH_3 retrievals within the IASI noise. The second criterion removes retrievals where a large HRI is observed corresponding to an almost zero TC (thus likely caused by errors in the TC or NH_3 profile). This procedure removes between 5% and 10% of the data, mostly with evening overpasses.

To each retrieved NH_3 total column an associated uncertainty can be estimated by propagating the uncertainties of the different parameters of the NN following

$$s_{\text{NH}_3} = \sqrt{\left(\frac{\partial \text{NH}_3}{\partial \text{HRI}}\right)^2 s_{\text{HRI}}^2 + \left(\frac{\partial \text{NH}_3}{\partial T}\right)^2 s_T^2 + \left(\frac{\partial \text{NH}_3}{\partial T_{\text{skin}}}\right)^2 s_{T_{\text{skin}}}^2 + \left(\frac{\partial \text{NH}_3}{\partial \text{H}_2\text{O}}\right)^2 s_{\text{H}_2\text{O}}^2 + \left(\frac{\partial \text{NH}_3}{\partial \sigma}\right)^2 s_{\sigma}^2.} \quad (7)$$

Here s_{NH_3} is the absolute uncertainty on the NH_3 column. s_T and $s_{\text{H}_2\text{O}}$ are the uncertainty on the temperature profile and the water vapor profile, respectively, which are set at 1 K for each level of the temperature profile and at 10% for the levels of water vapor profile, based on early validation of the IASI Level 2 meteorological fields [Pougatchev *et al.*, 2009]. $s_{T_{\text{skin}}}$ is the uncertainty on the surface temperature and is conservatively set to 1 K. s_{HRI} and s_{σ} are the standard deviation of the HRI and σ and are set to 1 (per definition) and 0.5 (see histogram of σ in Figure 2), respectively. s_{σ} is used to evaluate the uncertainty associated with the retrieval sensitivity to the vertical distribution of NH_3 . Note that cloud coverage, by affecting the value of the calculated HRI, also influences the retrieval. An analysis over Europe in the summer showed that the impact of clouds on the HRI is almost linear up to high values with a slope close to -1 (a 25% cloud coverage causes on average a roughly equal decrease of the HRI). Although the 25% threshold is arbitrary, it is a good compromise between keeping the number of measurements high and the impact of clouds low. This is important to keep in mind for the utilization of the product.

An example of retrieved NH_3 total columns ($\text{molecules}\cdot\text{cm}^{-2}$) on 2 June 2013 for the morning (top) and the evening (bottom) overpasses of IASI is given in Figure 4. Light gray points correspond to cloudy pixels. The corresponding distributions of the uncertainty are shown in the inset. Large columns are, for example, observed above the usual agricultural hot spots. The large columns observed over the Pacific Ocean near the west coast of Mexico correspond to transported plumes emitted by biomass burning in this region. Differences observed between morning and evening overpasses of IASI could be due to diurnal variations of NH_3 but have not been further investigated.

An appealing feature is that the retrieved NH_3 total columns ($\text{molecules}\cdot\text{m}^{-2}$) for areas far away from source regions (such as over most of the oceans) are close to 0. As explained, this is due to the fact that retrieval noise is translated in a linear way into the retrieved columns. Therefore, and because of the definition of HRI, the retrieved values over remote areas will follow a Gaussian distribution around zero, guaranteeing an average close to 0. However, over certain regions (e.g., for this day, over Bolivia and Peru), negative NH_3 columns are predominant, especially for the evening overpass. This bias is either caused by a bias in the HRI (e.g., due to surface effects) or by incompatible meteorological L2 data (for instance, relative high HRI values corresponding to areas with a negative TC). Most of these observations are already removed by the filter mentioned above, but as it is quite conservative it does not remove all the anomalies. An analysis of data from different years (2008–2015) revealed that the anomalous negative values occur less frequently with newer L2 data, indicating improvements in the IASI L2 products. The analysis of the uncertainty distribution reveals uncertainties generally below 30% (50%) over the identified source areas for the morning (evening) overpass time measurements. For regions with low NH_3 columns in contrast, the uncertainty is typically larger than 150%.

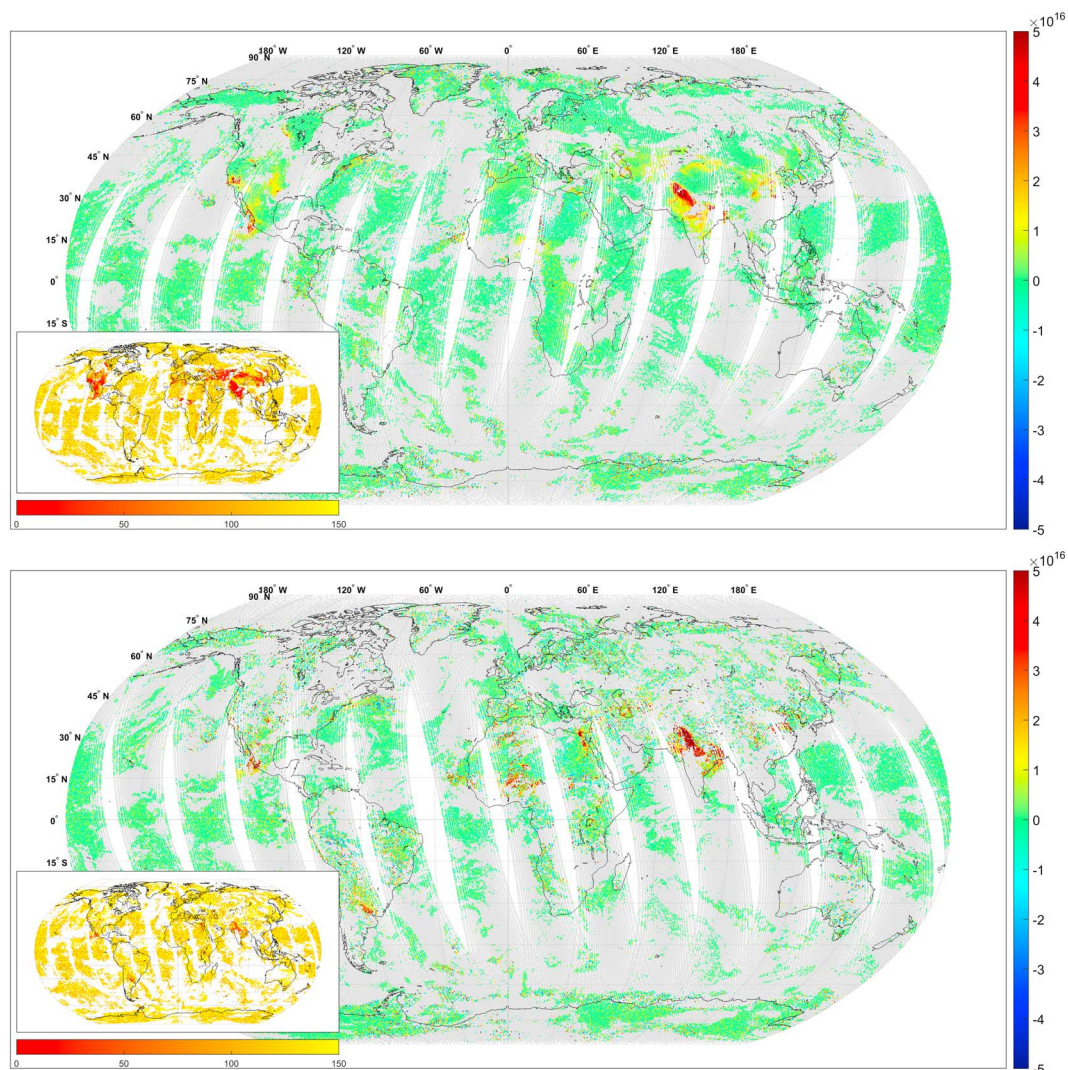


Figure 4. NH_3 total column distributions (molecules.cm^{-2}) for (top) the morning and (bottom) the evening overpasses of IASI on Metop-A for 2 June 2013. Associated uncertainty distributions (%) are shown as well (bottom left inset).

3.4. Uncertainty Characterization

An example of uncertainties and their partitioning in the different uncertainty contributions is shown in Figure 5 for measurements selected on 15 June 2013 (morning overpass time). Four cases characterized by different sensitivity to the measurement (TC) and NH_3 column were considered: (1) high NH_3 column ($\sim 9 \times 10^{16}$ molecules.cm^{-2}) and high TC (~ 15 K, high sensitivity); (2) high NH_3 column ($\sim 9 \times 10^{16}$ molecules.cm^{-2}) and low TC (~ 3 K, low sensitivity); (3) low NH_3 column ($\sim 4.5 \times 10^{15}$ molecules.cm^{-2}) and high TC (~ 14 K); and (4) low column ($\sim 4.5 \times 10^{15}$ molecules.cm^{-2}) and low TC (~ 2 K).

The lowest uncertainties are around 25% when high columns and high TC coincide. When either of these decrease, the uncertainty progressively increases. For these cases, uncertainties are found up to 85–148%. When both the TC and column are low, all sensitivity to NH_3 is lost. In case of high TC and high NH_3 columns (high HRI), the major relative contribution to the total uncertainty comes from the thickness of the NH_3 layer (σ) (36%) followed by the surface temperature (24%) and the temperature profile (16%). The relative contribution of the HRI is low (11%) since HRI is large in absolute value (because of the large TC and large column). For low TC and high NH_3 column, the sensitivity of the retrieved NH_3 total column to small variations of the TC and HRI is larger. This results in a higher relative contribution of the HRI (17%), surface temperature (25%), and temperature profile (19%), while the relative contribution of the σ parameter is reduced (22%).

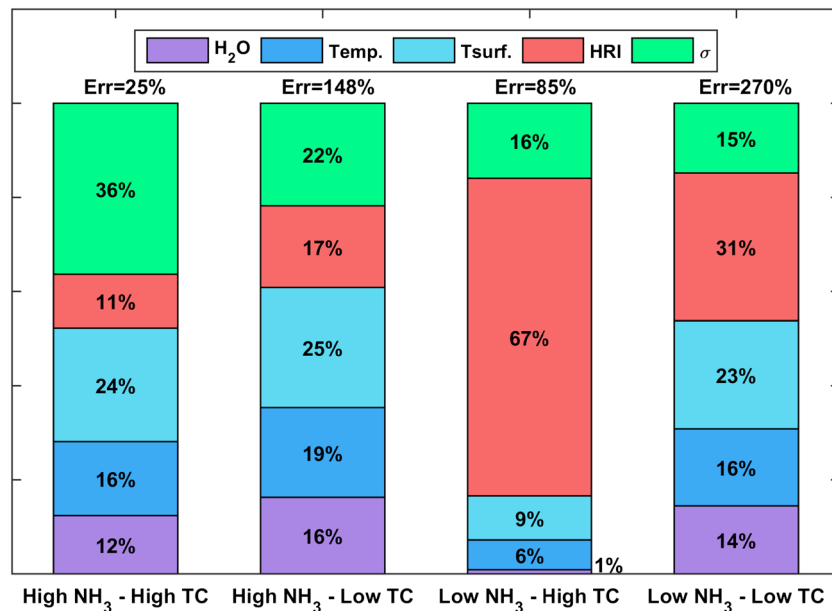


Figure 5. Example of error distributions of the NH₃ retrieved columns for different situations characterized by different sensitivity to the measurements and NH₃ total column. From left to right: (1) high NH₃ column ($\sim 9 \times 10^{16}$ molecules.cm⁻²) and high TC (~ 15 K), (2) high column ($\sim 9 \times 10^{16}$ molecules.cm⁻²) and low TC (~ 3 K), (3) low column ($\sim 4.5 \times 10^{15}$ molecules.cm⁻²) and high TC (~ 14 K), and (4) low column ($\sim 4.5 \times 10^{15}$ molecules.cm⁻²) and low TC (~ 2 K). The total relative error for each case is given as well.

For high TC and low NH₃ column in contrast, the major contribution to the total uncertainty is on the HRI, reaching 67%, because in this case the uncertainty on the HRI (one by definition) can be comparable or even larger than the value of the HRI. In this case this uncertainty dominates all other contributions. Finally, for low TC and low NH₃ column (low HRI), the relative uncertainty on the retrieved column is very large (270%), and compared to the previous case, also uncertainties on the other parameters become more important. It is clear that such measurements are of limited usefulness.

3.5. NN Versus LUT Retrievals

In this section we compare retrievals of the LUT-based and the NN-based HRI method. For this, all measurements for the year 2013 with a relative uncertainty below 100% were selected. A scatterplot between the two retrievals over land is shown in Figure 6. Three main patterns stand out (numbered (1)–(3) in the figure):

1. For measurements where both algorithms give a relative uncertainty below 25%, the retrieved NH₃ columns from the NN-based and the LUT-based method are in excellent agreement (543,847 measurements in total with a correlation coefficient of 0.91 and linear regression (Pearson's major axis) of $NN = LUT \times 0.85 - 0.17 \times 10^{16}$). These correspond to measurements associated with high TC (> 15 K) and a high HRI (> 10). A similar analysis was made for retrievals over oceans only (not shown here). While the correlation coefficient for the measurements over sea is relatively good (0.87), the linear regression indicates larger differences than for land ($NN = LUT \times 1.19 - 0.72 \times 10^{16}$; 1574 measurements in total).
2. The measurements in this group are associated with a relative uncertainty mainly comprising between 25% and 75% and a high HRI (> 10) but a fairly low positive TC (5–10K). The retrieved columns derived from the NN are consistently larger than the columns retrieved from the LUT (more than a factor of 2). A possible reason for these differences is that the LUT was derived from averages of forward simulations using many different background atmospheres, which could be affected by outliers.
3. These measurements have a low HRI ($-3 < HRI < 3$) and TC ($-5 < TC < 5$ K). Here the sensitivity to atmospheric NH₃ is low. The columns retrieved from the NN are generally much smaller than for those retrieved from the LUT. The existing bias in the LUT is the largest for these retrievals, and the reduction of this bias in the NN can be seen clearly (with an average close to 0). Over sea, the majority of the observations belongs to this category, and an even larger scatter is observed between the LUT and NN.

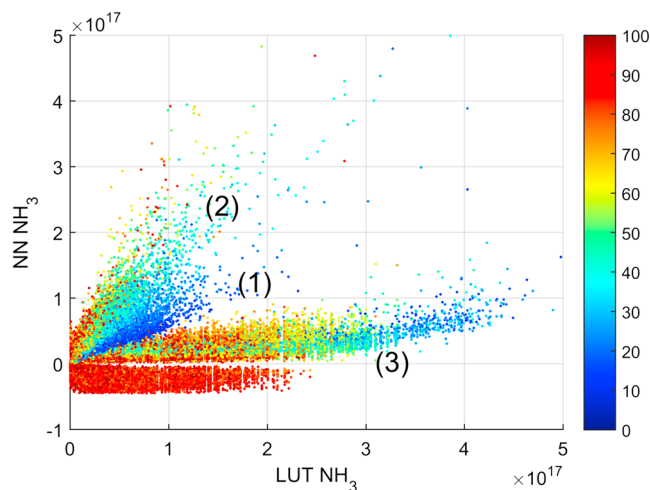


Figure 6. NH₃ total columns (molecules.cm⁻²) retrieved from the NN-based method (y axis) versus those retrieved from the LUT-based method (x axis) over the entire year 2013 (morning and evening overpasses) over land. The colors refer to the uncertainty (%) associated with the total columns retrieved from the NN-based method. Numbering (1)–(3) corresponds to the main patterns standing out. These correspond to measurements associated with (1) a high TC and a high HRI, (2) a high HRI and a low positive TC, and (3) a low HRI and TC.

4. Impact of the NH₃ Vertical Profiles

One of the advantages of the NN-based method is that it allows using variable NH₃ profiles. As shown in section 2.1, the vertical distribution can have a large impact on the retrieved total column. To give an idea of the potential impact on a global scale, we have retrieved NH₃ columns assuming that most NH₃ is located in the planetary boundary layer (PBL) by setting σ equal to the PBL height derived from the ERA-interim reanalysis [Dee *et al.*, 2011]. Note that for PBL heights lower than 250m, the σ value has been set to 250m since the NN has not been trained for lower values. Figure 7 shows the relative difference (%) between the retrieval using the fixed σ derived from the LUT (=1.07 km for land) and the retrieval using the PBL height for 2 June 2013 (morning orbits, land only). Corresponding PBL height (km) and TC distributions (now taken at 1 km) are provided as well (bottom left and bottom right insets, respectively). Highly variable PBL heights are observed

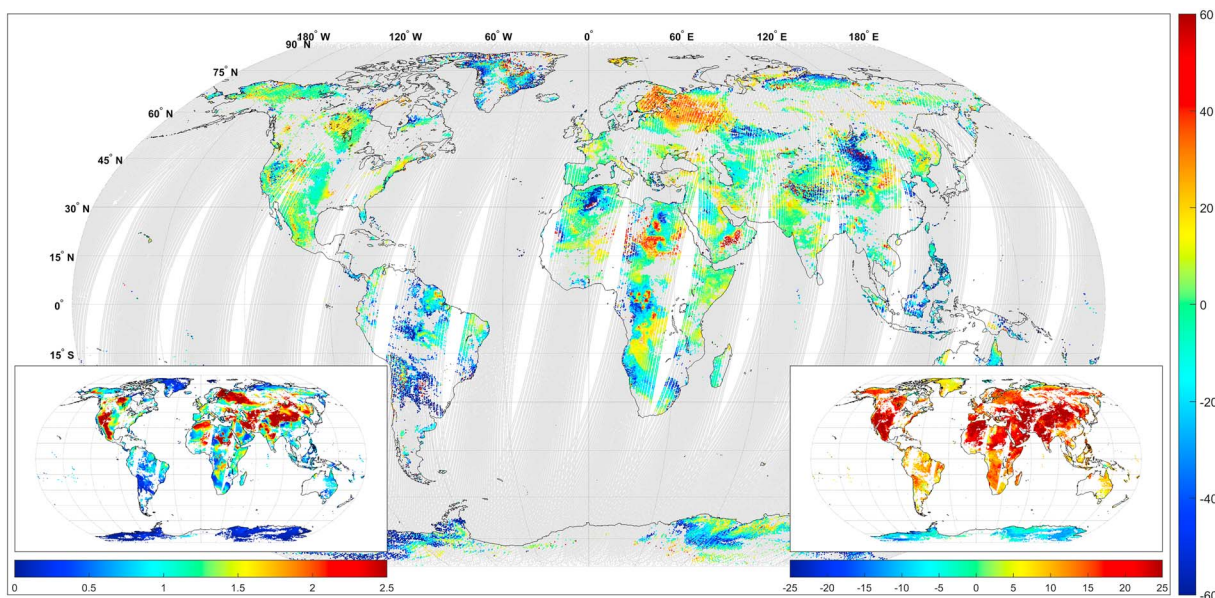


Figure 7. Relative differences (%) between NH₃ total columns (molecules.cm⁻²) retrieved over land for 2 June 2013 (morning orbits) using a fixed σ (=1.07 km for land) and using the PBL height from the ERA-interim reanalysis as σ . The bottom left and bottom right insets show the corresponding PBL height (km) and TC (K, $T_{surf} - T_{1km}$) distributions, respectively.

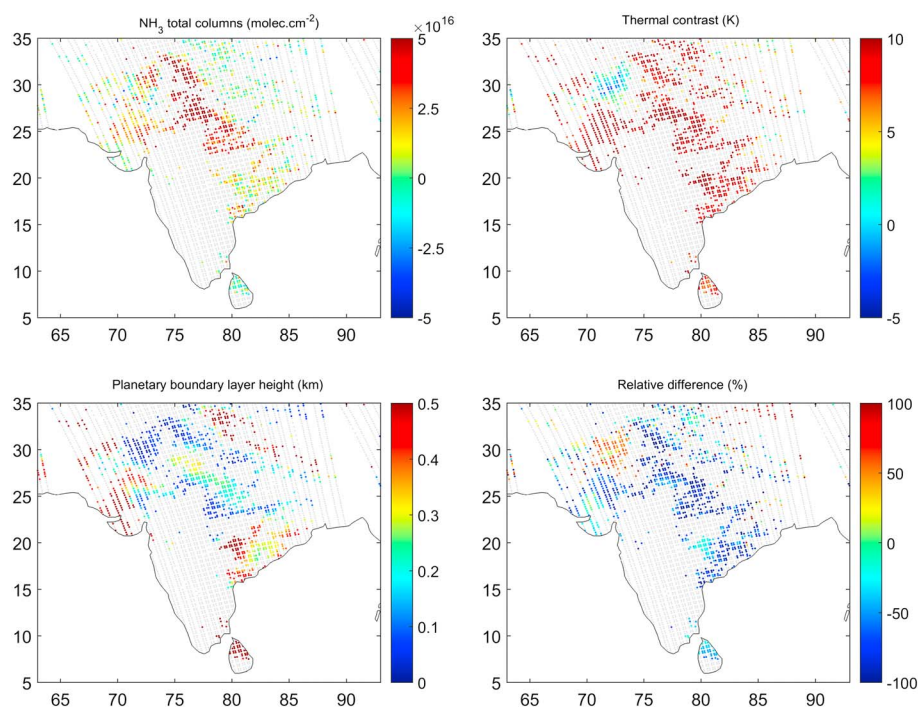


Figure 8. (top left) Nighttime IASI-NH₃ total column (molecules.cm⁻²) distribution for 2 June 2013 over India retrieved by considering a fixed σ , (top right) associated TC (K, $T_{\text{surf}} - T_{1\text{km}}$) and (bottom left) PBL height (km), and (bottom right) relative differences (%) between NH₃ total columns (molecules.cm⁻²) distributions retrieved using a fixed σ ($=1.07$ km for land) and using the PBL height from the ERA-interim reanalysis as σ .

globally ranging from above 0 km to more than 2.5 km. The largest differences in the retrieved NH₃ columns are between 60% and 100% (e.g., in the Southern Hemisphere and at high latitudes). Since the PBL height is spatially highly variable, no clear geographical patterns can be discerned. In case of positive TC (which is almost always the case here), the retrieved NH₃ columns will generally be lower for NH₃ profiles with a thicker layer because of the better sensitivity to NH₃ at higher altitude—and conversely. This is consistent with Figure 1.

The impact of the NH₃ vertical profile on the retrieved column for a nighttime distribution is shown in Figure 8 (bottom right). As the sensitivity is generally lower for nighttime measurements (due to a general lower TC), we focus only on a source region (South Asia) and land profiles. The nighttime NH₃ total column distribution retrieved for a fixed σ (Figure 8, top left), and corresponding TC (Figure 8, top right) and PBL height (Figure 8, bottom left) distributions are also shown. At night, the PBL height is generally much lower than during the day [Jacob, 1999]. For the region shown, the PBL is mostly below 500m. The TC distribution is mostly positive, except over Pakistan where slightly negative values are observed. As for the daytime distribution, for a given signal in the IASI spectra, lower σ values combined with positive TCs result in higher retrieved NH₃ columns with relative difference up to 100%. In contrast, for the area showing slightly negative values of TC, the retrieved columns are about 20–30% lower than the retrieved columns using a fixed σ . The magnitude of these differences is in line with what was shown in section 2.1.

5. Global Annual Mean and the Importance of the Averaging Procedure

For some applications, it is useful to consider monthly or yearly average distributions. However, as discussed in Van Damme *et al.* [2014a], averaging is not straightforward because of large variability of the NH₃ measurement sensitivity. It can for instance happen that the arithmetic mean of a group of observations is dominated by a single anomalous high measurement value (corresponding to a measurement with low sensitivity and high uncertainty). Averages from the LUT retrieval approach suffered from such measurements. For this reason Van Damme *et al.* [2014a] made use of weighted averages, where the weight was taken inversely proportional to the square of the estimated uncertainty of the measurement (in relative or absolute terms). Therefore, measurements thought to have a high accuracy carry a larger weight in the average. Another approach is to

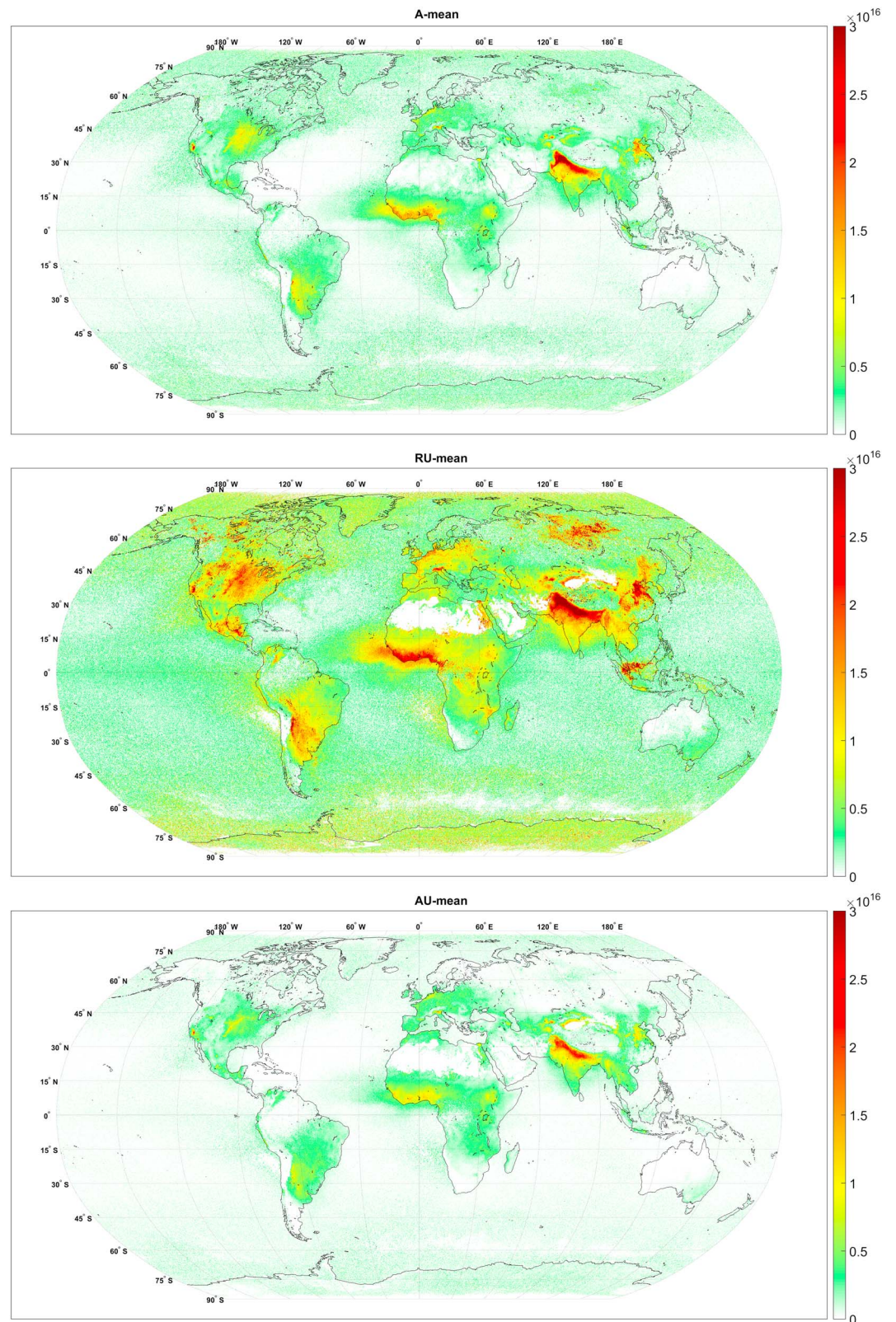


Figure 9. NH_3 total columns (molecules $\cdot \text{cm}^{-2}$) distributions from IASI measurements for the year 2013, in a 0.25° by 0.25° grid for the morning overpasses. NH_3 distributions are a mean of all measurements within a cell following (top) an arithmetic mean (A-mean), (middle) a weighted mean by the relative uncertainty (RU-mean), and (bottom) a weighted mean by the absolute uncertainty (AU-mean).

remove those measurements for which the uncertainty exceeds a certain threshold value (this is equivalent to using 0/1 weights). The disadvantage of weighting approaches is that they bias the average: for instance, 0/1 weighting or weighting with the relative error will favor the largest columns with a low uncertainty; weighting with an absolute error will favor the lowest columns. Figure 9 illustrates three different averaging procedures: arithmetic mean (A-mean, top), weighted mean by the relative uncertainty (RU-mean, middle), and the absolute uncertainty (AU-mean, bottom). In all three cases we used all retrievals of the morning overpass of the year 2013 but removed grid cells with less than 15 observations. For more details on the weighted averaging procedure, we refer to *Van Damme et al.* [2014a].

A main feature to notice in Figure 9 is that, despite the different averaging procedures, the mean NH_3 total columns are of the same order of magnitude. This indicates that anomalous high or low measurements are not as important for the NN as for the LUT. Analyzing the daytime distribution reveals the same main NH_3 hot spots that were identified by *Van Damme et al.* [2014a], mainly related to fire and agriculture. For agricultural sources, we observe large NH_3 columns especially above the Indo-Gangetic Plain, the Fergana Valley in Central Asia, the North China Plain in Asia, the US Midwest region and San Joaquin Valley, the Po valley, and the Netherlands in Europe. NH_3 hot spots associated with biomass burning are found, for example, above central Africa, Eastern Russia, Thailand, and Indonesia. For a more complete analysis of the NH_3 sources and hot spots, we refer to *Van Damme et al.* [2014a]. However, the comparison between the different averaging methods highlights important differences in the regions with large NH_3 columns. In particular, a large impact of fire plumes is revealed in the RU-mean due to the better sensitivity of IASI for NH_3 at higher altitude [*Van Damme et al.*, 2014a, 2014b]. High NH_3 columns related to fires emissions are, for example, observed above Canada, Eastern Russia, and Indonesia. Moreover, many localized hot spots show up, especially above the US and Western Russia. In contrast, in the AU-mean only the permanent hot spots of NH_3 total columns appear (these are principally related to agriculture). Hot spots associated with biomass burning are generally not visible, due to the more important weight given to the low columns (with a lower absolute uncertainty). Mean NH_3 columns are therefore also lower than in the RU-mean. The A-mean is relatively close to the AU-mean but reveals slightly better the biomass burning hot spots (e.g., Eastern Russia). We conclude that with the proposed NN product, the expected differences between the different averaging procedures are still present but less pronounced. The choice of averaging procedure will principally be determined by the specific application.

6. Comparison With GEOS-Chem

In this section we compare the mean NH_3 global distributions to those simulated with the GEOS-Chem CTM. The GEOS-Chem v8.03.01 model provides NH_3 total columns on a daily basis with a horizontal resolution of $2^\circ \times 2.5^\circ$. One of the advantages of the new product is that it can use profile information from other sources. To compare optimally with GEOS-Chem, it therefore makes sense to use collocated vertical profile shape information in the retrieval. σ and z_0 values were obtained for each IASI observation by fitting the Gaussian profile (equation (2)) to the corresponding GEOS-Chem grid cell sampled at the same time as the IASI overpass. Note that we only considered IASI observations and corresponding GEOS-Chem modeled for which the GEOS-Chem profile could be fitted to a high accuracy ($\sim 73\%$ of all profiles). The global NH_3 mean distributions derived from IASI measurements and given by the GEOS-Chem simulations for the year 2009 are shown in Figure 10 (top and middle, respectively). The absolute differences between the two distributions are also shown (Figure 10, bottom).

The same main source areas are found both in the satellite and modeled distributions. Also, transport patterns over oceans are in very good agreement (off the west coast of Africa, Indian Ocean, Mediterranean Sea, and off the east of South America). However, some source areas appear to be more concentrated in the IASI distributions. This is in particular the case for India for which the highest IASI columns are confined to the Indo-Gangetic plain, while GEOS-Chem simulates very high columns over most of India and Pakistan. On a quantitative level, IASI and GEOS-Chem are consistent on a yearly basis over most of the Northern Hemisphere within $\pm 3 \times 10^{15}$ molecules. cm^{-2} . However, an overestimation of GEOS-Chem simulations over IASI measurements of about $1 - 1.5 \times 10^{16}$ molecules. cm^{-2} is found for India and the North China plain. Overestimations of about $0.7 - 1 \times 10^{16}$ molecules. cm^{-2} are found as well over Central Africa. IASI columns are larger only for certain hot spots (the San Joaquin Valley, the Netherlands, and West Africa). Considering the generally strong positive thermal contrast prevailing during daytime, these observed differences between IASI and GEOS-Chem distributions (about 50–70% over the source areas) appear to be too high to be only explained by the reported bias on the training data set (for $\text{TC} > 5 - 10\text{K}$) (Figure 3).

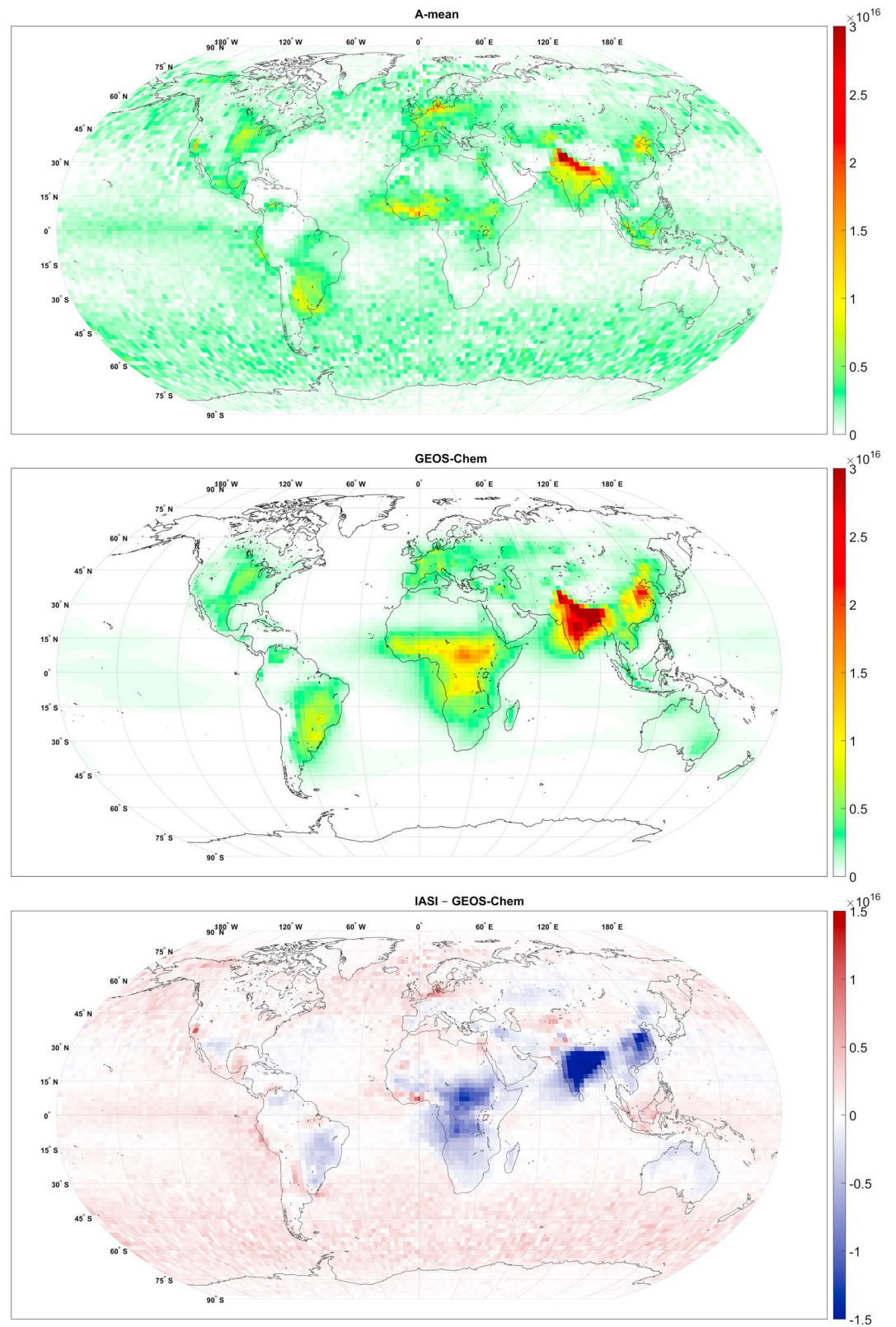


Figure 10. (top) NH₃ total columns (molecules.cm⁻²) distributions from IASI measurements for the year 2009, in a 2.5° by 2° grid for the morning overpasses. σ values were selected by fitting the corresponding GEOS-Chem NH₃ vertical profiles. (middle) NH₃ total columns (molecules.cm⁻²) distributions from the GEOS-Chem CTM. (bottom) Differences between NH₃ total columns (molecules.cm⁻²) distributions measured by IASI and simulated by GEOS-Chem.

7. Conclusion

In this paper we have introduced a new neural network (NN)-based NH_3 retrieval algorithm. It combines most advantages of full fitting approaches with HRI based approaches. To recapitulate, from the latter it inherits the following:

Computational Efficiency. The only parameter retained from the measurement is the HRI value. Calculating these is straightforward and computational time is negligible. Calculating the neural network function F is equally straightforward.

Full Spectral Range. The HRI takes into account the spectral range $800\text{--}1200\text{ cm}^{-1}$, which contains all the important NH_3 lines in the infrared, and thereby takes full advantage of the thermal infrared.

Low Dependency on the Forward Model. The forward model is only of secondary importance for the calculation of the Jacobians in the HRI and also for the HRI calculated from the NN training data. Because we use an angular dependent gain matrix, the NN-based approach removes the residual angular dependency previously reported in *Van Damme et al.* [2014a].

No A Priori Information. No a priori information on the column is used. This means that all the information from the final measurement comes from the spectral measurement (but potentially with very large associated uncertainty estimates). So in contrast to optimal estimation approaches, no averaging kernel needs to be applied when carrying out comparison with other measurements/models. A priori information on the vertical profile *shape* is used though.

The main advantages of the NN over the LUT-based HRI method are the following:

Full Atmospheric State. Because the number of input parameters is not limited in the NN, the full temperature, humidity, and pressure profiles can be taken into account. This property is shared with the spectral fitting approaches.

Full Uncertainty Analysis. By perturbing the input parameters a full uncertainty characterization can be made of how the uncertainty of each of the input parameters propagates to the final result. This analysis can be carried out on a per-pixel basis.

Reduced Bias. Rather than mapping the input parameters directly to a NH_3 column, the output of the NN is a scaling factor, which after multiplication with the HRI gives the column. In this way, the instrumental error on the HRI is translated in a linear way in an error on the column, and negative columns become possible. At the same time, this implies that the algorithm itself is not biased high as was the case with the LUT-based conversion (this is assuming that the HRI values themselves are not biased). At least for making averaged distributions, this decreased bias helps to reduce the importance of the precise averaging procedure that is used.

Flexible NH_3 Profiles. All the retrieval approaches which have been used so far assume a fixed or an a priori NH_3 vertical profile. While infrared sounders have limited or no sensitivity to the vertical profile of NH_3 , the assumptions on the profile can affect the retrieved column greatly. It is clear, even from the limited amount of in situ measurements, that the vertical profiles of NH_3 exhibit a huge variability. To deal with this, we have included two input parameters in the NN describing the profile, namely, the peak height and the thickness of the NH_3 layer. This allows to estimate robustly the uncertainty in the retrieved column due to the uncertainty in the assumed profile but also allows the following:

1. *Study of wildfire emissions.* Using a fixed NH_3 profile can yield large errors on the retrieved column especially when studying wildfire plumes which can have a peak altitude several kilometers above the surface. Coupling bottom-up [*Sofiev et al.*, 2012] or top-down [*Val Martin et al.*, 2010] height estimates could therefore greatly improve the accuracy of satellite retrievals of NH_3 in wildfire plumes.
2. *Model exploitation possibilities.* The flexibility in NH_3 vertical profiles can in the future be exploited to improve atmospheric chemistry-transport models. In evaluating a chemical transport model, retrievals can be carried out using the modeled NH_3 profile for a more consistent comparison. Improvements in, e.g., dispersion and lifetime of the model could then be evaluated from the retrievals carried out with updated profiles.
3. *In situ measurements.* In situ measurements of NH_3 profiles or boundary layer heights can be directly utilized to improve satellite retrievals and/or validation exercises, as suggested in *Van Damme et al.* [2015a]. Here we have demonstrated that these can greatly alter the retrieved columns on a global scale.

The full IASI-NH₃ data set (8years of data) is being reprocessed using the retrieval method described in this paper. The σ and z_0 values which are used in the retrieval process are derived from the fitting of the single NH₃ profiles used for land and sea in the LUT-based HRI method (see section 3.3) and will be distributed along with the NH₃ data. The data set will be available in 2016 for all users through the Ether database (<http://www.pole-ether.fr/>), along with daily quicklook plots and selection tools.

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