A.C. MEASUREMENTS WITH A
DEPLETION-MODE CHARGE-FLOW TRANSISTOR

by

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Submitted to the Department of Electrical Engineering
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ABSTRACT

A new MOS device for use in measuring the dielectric properties of
high-impedance materials has been developed. The device consists of
a depletion-mode FET, and a planar interdigitated capacitor (lock and
key) that is coated with the material of interest. One electrode of
the lock and key is driven with a sinusoid, while the other is tied
to the gate of the FET. The signal that reaches this floating gate
electrode is a function of the dielectric properties of the material
under study. This signal is monitored via the channel conductance
modulation of the FET.

A measurement technique that employs a second matched FET as
reference has been developed. The technique allows indirect measure-
ment of the floating electrode voltage, by the use of external feedback
circuitry that maintains matched operation by the two FET's. The gate
voltage which the circuit supplies to the reference FET mirrors the
floating-electrode voltage. One measurement is required to calibrate
each FET pair.

The technique has been used to examine the properties of thin
films of the moisture-sensitive polymer, poly ethylene oxide (PEO).
A model describing the transfer function of the system has been derived,
assuming surface-dominated conductance by the thin film, negligible
contact impedance, and no dispersion. The model and data are in excel-
lent agreement, making possible the extraction of the sheet resistance.
The PEO thin film exhibits a sheet resistance that varies over more
than four orders of magnitude, for 3% to 75% relative humidity. The
study has demonstrated that the technique may be successfully employed
to measure sheet resistances as high as $10^{16}$ ohms per square.

Thesis Supervisor: Stephen D. Senturia

Title: Professor of Electrical Engineering
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CHAPTER 1: INTRODUCTION

In recent years, MOS technology has been applied to the problem of making small and inexpensive sensing devices. These sensing devices are typically based upon the measurement of the electrical properties of a high-impedance film.

This project was begun with the goal of making an MOS pH sensor based upon the measurement of a pH-sensitive impedance, rather than of a D.C. potential, as is the case with current pH sensors (1). The project had three main divisions: 1) the characterization of various thin films of pH glass to determine if they exhibited an exploitable pH-sensitive admittance; 2) the development of a device structure and corresponding measurement technique suitable for use with the pH-sensitive thin film; and 3) the development of an immersible device package.

The first of the above was the subject of work done by J. Adcock (2) and R. Johns (3). Thin films of various pH-sensitive glasses, fabricated by sputtering, silk screening, and by blowing, as well as a pH-sensitive polymer were examined. The basic conclusion of their work is that there is no intrinsic pH sensitivity of the electrical admittance in any of the above samples.

While the above studies proceeded, the design of the device and its package was undertaken by the author. Because the thin films under study were primarily capacitive, the device was designed to be suitable for use in an A.C. measurement system. In addition, both the device and package design included special features for resistance against the hazards of immersion. It became obvious, however, that a pH-sensitive thin film was not going to be available.

Nevertheless, the technique that had been designed for making
A.C. measurements of high-impedance films was not limited to the field of ion sensing. On the contrary, the technique seemed to have immediate applications in the areas of moisture sensing and resin cure monitoring. To test these applications, the requirement of immersibility of the device was dropped, and a simplified version of the device was designed, built, and successfully tested.

This paper reports on the results of this work. There are essentially five contributions to be reported:

1) The development of a process for the fabrication of n-channel depletion-mode FET's in the MIT Microelectronics Laboratory.

2) A new device structure which combines a lock and key device with a floating-gate CFT, for improved sensitivity.

3) A measurement scheme which employs a reference FET and external feedback circuitry that allows easy measurement of the pertinent transfer function.

4) The addition of a stray capacitance to the existing device model to account for high-frequency behavior of the device.

5) The analysis of a moisture-sensitive thin-film system by systematic application of the model to the observed response.

Background on the use of MOS structures to examine high-impedance films is presented in Chapter 2. Chapter 3 follows with a description of the new device and its associated measurement technique. In Chapter 4, the technique is applied to the examination of thin-film PEO. Finally, Chapter 5 contains a discussion concerning limitations of the technique.
CHAPTER 2: BACKGROUND

This chapter summarizes work previously done at MIT involving the characterization of high-impedance films. This work has been done with the aid of two MOS structures: 1) the lock and key, and 2) the charge-flow transistor.

A. THE LOCK AND KEY

The lock and key is a planar, interdigitated electrode pair (Figure 1). Recent studies at MIT have employed the lock and key to measure the sheet resistance of moisture-sensitive thin films (4), and to monitor the dielectric properties of epoxy resin during cure (5).

When a thin film is applied over a lock and key, a resistor is formed. The resistor's value ideally depends only upon the sheet resistance of the thin film (in ohms per square) and the number of squares in the path between the two electrodes of the lock and key. The smaller the number of squares between electrodes, the easier it is to measure the current through the device.

For example, assume the sheet resistance of the thin film is $10^{15}$ ohms per square, and the lock and key has 1/100th of a square between its electrodes—in other words, the ratio of the interelectrode spacing to the inner-electrode circumference is 1/100. The resistor value is $10^{13}$ ohms. This means that the resistor will draw .1 pA from a one volt supply, a difficult current to measure. If a lock and key with 1/10,000th of a square (a practical limit) is used, the resistor value becomes $10^{11}$ ohms. The current becomes 10 pA—still a difficult current to measure accurately, but a factor of 100 improvement over the previous case.

This example illustrates perhaps the biggest problem with the use
Figure 1A) Top view of lock and key

Figure 1B) Cross section of two fingers of the lock and key
of the lock and key to characterize thin films: the inability to measure sheet resistances on the order of $10^{15}$ ohms per square and greater accurately. There are other difficulties. When the lock and key is used to make a D.C. measurement, error may result from high resistance in the contact between electrode and thin film. This problem may be avoided by making an A.C. measurement, but this leads to a new difficulty, since capacitive current may be much greater than that conducted by the thin film, even at low frequencies.

The lock and key may also be employed in the characterization of infinite-medium systems such as a curing resin. The term "infinite medium" refers to the case of a film that is thick compared to relevant device dimensions. Modeling of this type of system is much more difficult than for the thin film, since current paths are highly two dimensional. The model to be presented in this paper was developed specifically for thin-film systems and may or may not be applicable to the infinite-medium case.

B. THE CHARGE-FLOW TRANSISTOR

The charge-flow transistor (CFT) is an MOS-compatible sensing device (6). The floating-gate version of the CFT is depicted in Figure 2. To date, the CFT has been applied primarily to the problem of monitoring the sheet resistance of thin films (7,8).

The measurement technique is pictured in Figure 3. A voltage step greater than threshold is applied to the driven gate of the CFT. Charge migrates from the driven gate to the floating gate through the highly-resistive path of the thin film. After some delay (typically ranging from milliseconds to microseconds), the voltage on the floating gate reaches threshold, and the FET begins to conduct current. When
Figure 2A) Cross section of floating-gate CFT

Figure 2B) Top view of floating-gate CFT
Figure 3A) Schematic Representation of Turn-on Measurement Technique

Figure 3B) Illustration of Turn-on Waveforms
FET current reaches the predefined level $I_{on}$ (typically 1 microampere), the device is said to have turned on. The turn-on delay $t_{on}$ is heavily dependent upon the sheet resistance of the thin film.

While this time-delay measurement scheme does give a reflection of the value of the sheet resistance, it is very hard to determine this value from the turn-on data. The primary difficulties are attributable to the variation of threshold from device to device, and the uncertainty of charge distribution in the thin film prior to application of the voltage step. The A.C. measurement technique presented in this paper represents a major improvement over CFT turn-on time for the determination of sheet resistance.

The CFT has also been applied recently to the problem of resin cure monitoring (5). Initial measurements in these studies were made using the turn-on time technique. However, in this case, an A.C. measurement technique that employed the CFT was developed, and shown to be more suitable (9).

In the A.C. method, a D.C. bias greater than threshold is applied to the driven gate, upon which an A.C. signal is superimposed. The effective FET is in this way biased into its linear region of operation, and the channel conductance is modulated by the sinusoid. This channel modulation is measured and compared to the applied sinusoid. The result is expressed in terms of the gain and phase of the ratio of the two sinusoids. Given the proper model, the conductivity and dielectric constant of the device medium can presumably be computed from the gain-phase data.

To date, this model has consisted of a capacitively-loaded RC transmission line (8) (Figure 4). The model assumes negligible contact
Figure 4A) Transmission Line Model of CFT

Figure 4B) Incremental CFT Model
impedances, and lumps the two-dimensional distributed effects into a one-dimensional transmission line. The transmission line may be represented incrementally as a two-port network, with parameters $Z_1$ and $Z_2$ that are functions of device geometry and the electrical properties of the resin. The FET is biased such that it operates in its "linear" regime, and is represented incrementally as a capacitor and a voltage-controlled current source. A similar model will be shown to apply to the device developed here.

The major problem with the A.C. method is keeping the device biased properly. Not only may it be difficult to establish the initial bias voltage, but as the properties of the medium change, so may the bias voltage on the floating gate. This effect has caused device to turn off during the course of epoxy resin cure. One driving force behind the effort to make depletion-mode charge-flow transistors for the project reported here is to remove the D.C. bias as an issue in such measurements.
CHAPTER 3: THE NEW METHOD FOR
A.C. MEASUREMENT OF DIELECTRIC PROPERTIES

A. THE NEW DEVICE

Theory of Operation. A new device has been designed and fabricated which takes advantage of the best properties of the CFT and the lock and key (Figure 5), and in addition, operates with zero D.C. bias. The device consists of a depletion-mode n-channel FET and a lock and key, combined into a single structure. One electrode of the lock and key is driven externally, while the other electrode ties directly to the gate of the FET. The source and drain of the FET are available externally, just as with the CFT. In a sense, the new structure is simply a modified version of the floating-gate CFT, the differences being that the FET is depletion-mode, and the gate structure is interdigitated, rather than simply ringed.

As compared to the simple lock and key, the new structure has the primary advantage that the lock and key current is buffered by an on-chip amplifier: the FET. In addition, a secondary advantage is gained by the uninterrupted guarding of the floating electrode by the driving electrode.

The new structure has three main advantages over previous CFT's for making A.C. measurements. The first is that the transistor is depletion-mode, and may therefore be operated with zero D.C. gate voltage bias. Secondly, the floating-gate electrode has been shaped into the form of a lock and key, primarily for ease of modeling, while remaining entirely guarded by the driving electrode. An additional advantage of this adaptation is the averaging of process variations. The third key improvement is that the high-impedance path between electrodes, as well
Figure 5) Top View of Fingered-Gate CFT
as the floating electrode is now fabricated over the relatively thick field oxide. This leads to a lessening of the capacitive loading to the substrate.

The advantage of this third improvement can be illustrated by estimating the voltage divider ratio of the FET gate capacitor and the lock and key interelectrode capacitance, for the uncoated device (an infinite-medium system of air). The existing model of the lock and key structure will be employed in making this estimate (10).

The interelectrode capacitance of the lock and key is approximated by

\[
C_{lk} \approx \frac{9NL}{\pi^2} \left( \varepsilon_m + \varepsilon_{\text{sub}} + \frac{t_{ox}}{2W} \varepsilon_{\text{ox}} \right),
\]

where \( \varepsilon_m, \varepsilon_{\text{sub}}, \) and \( \varepsilon_{\text{ox}} \) are the dielectric permittivity of the medium (air in this example), the substrate, and silicon dioxide. The oxide thickness is \( t_{ox} \), and the lock and key is described by \( N, L, \) and \( W, \) the number of inner-electrode fingers, and the length and width of each one (assuming the finger width and the interelectrode spacing are equal). The new device has a lock and key with \( N=10, L=37.5 \) mils, and \( W=.5 \) mils.

In this case, the silicon substrate is at a constant potential, and resembles a ground plane. If it is assumed that the field lines in the medium are not drastically affected by the effective ground plane, the interelectrode capacitance can be approximated as

\[
C_{lk} \approx NLE_0.
\]

The channel capacitor \( C_{ch} \) can be approximated by

\[
C_{ch} \approx \frac{NWLE_{\text{ox}}}{t_{ox}}.
\]
so the voltage divider ratio becomes

\[ \frac{V_{FG}}{V_{DG}} = \frac{C_{lk}}{C_{lk} + C_{ch}} \approx \frac{C_{lk}}{C_{ch}} \approx \frac{t_{ox}}{W} \frac{\varepsilon_0}{\varepsilon_{ox}}, \]

where \( t_{ox} \) is the oxide thickness over which the floating electrode is fabricated. This illustrates that the fingered-gate structure will not have a greater response than the floating-gate structure simply due to the added electrode area. However, because the floating electrode of the fingered-gate structure is fabricated over field oxide, whereas it is over channel oxide for the ringed structure, an improvement of about a factor of ten is achieved. Using a \( t_{ox} \) of one micron, and a \( W \) of 12.5 microns, the formula estimates that the new structure should have a voltage divider relation of about 1/50 for the uncoated device (this approximation, of course, neglects the effect of the ground plane).

The existing CFT model must be modified to account for this interelectrode capacitance (Figure 6). When this new model is applied to a thin-film system in which conductance is predominately across the surface, the elements represent the following: 1) \( R_a \) and \( C_a \) are the parallel conductance and capacitance across the thin film, and may model bulk conduction as well as surface conduction; 2) \( C_l \) is the capacitance of the floating electrode to substrate; 3) \( C_t \) is the distributed capacitance from the (surface of the) thin film to substrate; and 4) \( C_x \) is the interelectrode capacitance, as determined above. It is assumed that contact impedances are negligible, and that electrical properties are not dispersive, i.e., not functions of frequency in the range of interest.

If sinusoidal steady state is assumed, the transfer function from driven electrode to floating electrode may be solved exactly
Figure 6A) Transmission Line Model of CFT with Addition of Stray Capacitance

Figure 6B) Incremental Section of Transmission Line
(Appendix B). The solution contains essentially four parameters: 
\[ \frac{C_i}{C_t}, \frac{C_t}{C_a}, \frac{C_x}{C_t}, \text{ and } \gamma = \frac{1}{R_a C_a \omega}. \] It is important to note that sheet resistance and frequency appear in only one place in the solution, and they scale with each other (11). This fact will be used to great advantage in using the model in experimental contexts (Chapter 4).

**Device Fabrication.** The basic steps of device fabrication are depicted in Figure 7. For a detailed step-by-step process description, refer to Appendix C. The process is an adaptation of the aluminum-gate p-channel process currently in use at the MIT Microelectronics Laboratory. It is not intended that this process be the ultimate in processing technology, but rather the simplest process with which the device objectives may be obtained.

The substrate is a <100> p-type silicon wafer, with a relatively low resistivity. As in the PMOS process, the first step is the growth of a thick field oxide. This oxide will be approximately one micron thick; oxides of greater thickness require extremely long growth times, even in steam. A masking step is then performed in which holes are etched through the oxide to the silicon in the regions of the wafer where source or drain regions are desired.

An implant is now used to introduce the n-type dopant, arsenic, into the exposed regions of the silicon. Arsenic was chosen because of its low diffusivity as compared to phosphorous at the temperature of gate oxide growth (1100 degrees centigrade).

A layer of oxide 2500 Angstroms thick is then grown over the arsenic-doped regions. A masking step follows in which holes are etched through the oxide to the silicon in the gate and contact hole areas of the wafer. A gate oxide of approximately 1000 Angstroms is then
Figure 7A) Wafer cross section following arsenic implant

Figure 7B) Wafer cross section following phosphorous implant

Figure 7C) Wafer cross section of completed device
grown over these regions.

A second ion implantation is now done, this time with phosphorous as the dopant. The implant strength is such that only the regions of the wafer under the thin gate oxide receive any impurities. This implant dopes the channel regions n-type, forming the depletion-mode devices.

A masking step in which the contact holes are opened to the silicon now takes place. The entire wafer is then coated with a layer of aluminum by evaporation. The aluminum is patterned in a final masking step to form the gates, electrodes, bonding pads, and interconnections for the devices.

The proposed processing sequence was simulated on the device fabrication computer simulation program SUPREM (12) (Appendix D).

A mask set was designed which included both a fingered-gate and ringed-gate CFT (Appendix E). In addition, a standard FET is included in the mask design. This FET will serve as a reference in the measurement scheme to be described in the next section.

Mask sets were produced from hand-cut ruby lith at 100x, using the mask-making facilities at the MIT Center for Materials Science and Engineering. Masks have been produced that will yield a 12 x 12 matrix of square dies, each die being 75 mils per side.

Wafers of p-type <100> silicon were selected for fabrication. Wafer resistivity was .1-.4 ohm-cm, low enough to prevent unwanted inversion under the field oxide. Devices were fabricated in the MIT Microelectronics Laboratory over a period of about two weeks.

The first processing run produced very satisfactory devices, with a yield excluding wafer edges of better than 90%. Typical FET I-V curves are presented in Figures 8 and 9, and a comparison between predicted and
Figure 8) Typical FET I-V Curve for Constant Substrate Bias
experimental results may be found in Table 1. These curves were generated and data analysis was performed with the aid of the computer-based MOS Characterization System at the MIT Microelectronics Laboratory.

In general, there was good agreement between predicted and experimental results. Perhaps the widest discrepancy is in the prediction of the gain factor, $k$. This is due to a lower than expected carrier mobility, probably resulting from the larger than typical surface state density present in our process. This is partially made up for by the extremely low mobility degradation exhibited by the devices. It should be noted that a surface state density of $2.5 \times 10^{11}$ was used in predicting threshold, rather than the typical $1 \times 10^{11}$ for $<100>$ silicon. The value $2.5 \times 10^{11}$ has proven to best account for thresholds obtained in our PMOS process.

B. THE MEASUREMENT TECHNIQUE

In the past, A.C. measurements with CFT's have consisted of measuring the incremental drain current as compared to the sinusoid applied to the driven gate (9). Several parameters such as device gain and stray resistances interfere with the interpretation of such data. It would be more desirable to make an indirect reading of the floating-gate voltage. A measurement scheme built around the new device accomplishes this goal.

The block diagram of the measurement scheme is presented in Figure 10. The technique employs a CFT, a matched FET, and external circuitry. The circuit consists of two major feedback loops: a primary loop which forces FET current equal to that of the CFT, and a secondary loop which maintains the D.C. operating point of the CFT.

The drain of the CFT and matched FET are connected to a variable
| TABLE 1 |
|-------------------|-------------------|
| **Oxide Thickness** | **PREDICTED** | **MEASURED (average)** |
| Field | .91 μm | -- |
| Source/Drain | .28 μm | .25 μm |
| Channel | 840 Angstroms | 1050 Angstroms |

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<th><strong>Sheet Resistance of</strong></th>
<th><strong>Source/Drain Implant</strong></th>
<th><strong>Threshold Voltage</strong></th>
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<tr>
<td>Channel</td>
<td>-4.3 v</td>
<td>-4.5 v</td>
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<th><strong>Gain (k)</strong></th>
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<td>--</td>
<td>18.0 v</td>
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<tr>
<td>Gain (k)</td>
<td>11.7 μmhos/v *</td>
<td>75 μmhos/v</td>
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<tr>
<td>Body Effect Factor (m)</td>
<td>2.92 √v</td>
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<tr>
<td>Mobility Degradation (θ)</td>
<td>--</td>
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</table>

*This value was predicted using an expected value of electron channel mobility of 570 cm²/v·sec (13).*
Figure 10) Block Diagram of Measurement Technique
D.C. voltage source. The sources of the two transistors are connected to the inputs of transimpedance current amplifiers, and are thus at virtual ground. In the primary loop, the outputs of the current amplifiers are compared, and the difference is amplified by a high-gain differential amplifier. The output of this differential amplifier drives the gate of the FET, forcing both A.C. and D.C. components of the FET current to be equal to those of the CFT.

The secondary loop takes the CFT transimpedance amplifier output, and adds it to a user-selected D.C. set point. The result is integrated, and added to a variable-frequency sinusoid to provide gate drive for the CFT. This loop serves to maintain CFT D.C. current at the user-selected set point. This feature is optional, and does not function when the D.C. Level Control Switch is opened.

Given that the drain, source, and substrate voltages are the same for both the CFT and the FET, and since the drain to source currents are forced to be the same as well, the gate voltage of the FET must be equal to the floating-gate voltage of the CFT. Thus, the floating-gate voltage of the CFT can be determined indirectly simply by measuring the FET gate voltage which is supplied by the external circuitry.

As long as the CFT and FET have well matched transistor properties, the circuit will successfully subtract out all common-mode properties, and output a signal that reflects only the desired property: the voltage of the floating gate as compared to the driven gate. It may be argued that the same result may be accomplished more simply by constructing a differential pair by grounding both sources, and loading the drains with a resistor. However, if this technique was employed, the drain voltage would no longer be a constant. This complicates the
analysis of the data.

The detailed circuit diagram is presented in Figure 11. The circuit employs six operational amplifiers, four of which are user-compensatable for improved high-frequency response. The circuit was initially tested using bipolar devices to model the as yet unfabricated FET's, and compensation was adjusted accordingly. On completion of device fabrication, circuit performance was retested by inserting FET's in both the FET and CFT slots. For frequencies up to 4 kHz, the circuit responded with less than one degree of phase error. This limiting frequency is less than hoped for, and could presumably be improved by adjusting the compensation to match the lower than expected device gain. However, because we are interested primarily in the low-frequency response, no effort has been made to correct this at this time.

As a final check, uncoated CFT's were tested for frequency response at room humidity, using the experimental set-up depicted in Figure 12. The devices behaved as expected. For low frequencies, the presence of SiO$_2$ surface conduction could be observed by a relatively high gain, and a negative phase shift. As frequency was increased, gain decreased, and eventually levelled off, while the phase returned to zero. This high-frequency response is due to the interelectrode capacitance.

For the fingered-gate devices, this response was $-49 \pm 1$ decibels, or 1/280. This is more than a factor of 5 down from the estimate of 1/50. Part of this error in the estimate can be attributed to the fact that the channel capacitance is not negligible, and actually contributes about 1/3 of the total capacitance. The rest of the error should be attributable to the effects of the ground plane.
The ringed structure has a typical gain of -60 decibels in the
high-frequency limit, or 1/1000. This is one half the estimated value.
There is approximately a factor of four difference between the high-
frequency gain of the two devices.
CHAPTER 4: ANALYSIS OF A THIN-FILM SYSTEM: POLY ETHYLENE OXIDE

In order to establish the usefulness of the measurement scheme, the moisture-sensitive polymer poly ethylene oxide was examined. Prior to dicing, wafer slices were coated with a thin film of the polymer by coating the slice with a delute aqueous solution of the polymer, and then spinning at 4000 RPM for 4 minutes. The slices were then carefully diced, and mounted on headers using non-conducting epoxy (since the polymer cannot stand the 120 degrees centigrade heat used to cure our conducting epoxy). The devices were then wire bonded, and tested for basic functionality.

Packaged devices were placed in our humidity-controlled flow system (Figure 12), and response was measured versus frequency and moisture content of the device ambient at room temperature. Studies were made on six samples, with three of the samples having been aged approximately one month. One of the aged samples failed. Data presented below were taken from the five remaining samples, two of which had been aged.

Measurements were taken in as near identical fashion as allowable by our flow system. The response of each sample was measured at ten different dew points, although the exact dew points varied from one device to the next, due to the inability to accurately tune the flow system. Measurements were taken at room temperature, which was observed to fluctuate between 22.5 and 25.0 degrees centigrade. Frequency of measurement was varied from 1 Hz to 2 kHz, taken with two points per decade. The D.C. Level Control Switch was left off for these measurements, and drain voltage was adjusted to one volt. Data was collected by hand, then entered into the HP-9835A calculator for aid in analysis (Appendix F).
Figure 12) Block Diagram of Experimental Arrangement
Figure 13 shows typical data from these experiments plotted on axes of gain vs. phase. This particular data is for the fingered-gate device; similar results were observed with the ringed-gate device. Data is seen to behave qualitatively as expected: 1) for low frequency and high dew point (low sheet resistance) the transfer function $\frac{V_{FG}}{V_{DG}}$ was approximately unity (zero dB gain and zero degrees of phase shift); 2) as dew point decreases (increasing sheet resistance) or frequency increases, the gain decreases and the phase falls because the system resembles an RC filter; 3) for low enough dew point or high enough frequency, the gain levels off and phases approaches zero because of the capacitive coupling between electrodes. Not surprisingly, this high-frequency gain was the same -49 decibels that had been observed with the uncoated devices.

The first step in calibration of the devices was taken at this point. As mentioned, at high dew point and low frequency, the gain approaches unity (0 dB) and the phase nears zero. However, this maximum gain varied from sample to sample, with values ranging from -1.2 to 1.6 decibels. This offset is primarily due to the mismatch in gain of the two transistors, and possibly partially due to a slight mismatch in gain of the two transimpedance current amplifiers. It is assumed that this gain offset is independent of frequency and dew point. The first step in processing the data is to subtract this gain offset, as determined for each device, from all measurements.

An attempt was now made to match the data of the fingered-gate devices to the model of Figure 4 and Appendix B. To reiterate, if the three capacitive ratios of the model are independent of both frequency and dew point, there remains but the parameter $\gamma$ which accounts for both frequency and dew point variations. This means that in gain-phase
Figure 13) Data for Various Dew Points and Frequencies for an Aged Sample
space, points of both varying sheet resistance and varying frequency will lie on a single smooth curve. For both of the aged samples, the data, for the most part, did in fact behave in this manner (Figure 13). However, this was not the case for the three freshly-coated devices (Figure 14).

The next step was to compute, when possible, the model parameters from device geometry. The parameter $\gamma$ cannot be computed, since it depends on sheet resistance, the quantity of interest. The parameters $C_x/C_{t_a}$ and $C_{t_a}/C_a$ are also not calculable from device geometry. However, the final parameter, $C_{t_a}/C_t$, may be computed.

The values of $C_{t_a}$ and $C_t$ were first computed separately by measuring the area of each capacitor over each oxide thickness. Areas were determined from the mask layout (Table 2). The field, source/drain, and channel oxides were assumed to be 1, .25, and .1 microns thick. The transmission line capacitor was assumed to lie entirely over field oxide plus .2 micron thick polymer. The polymer dielectric constant was equated to that of silicon dioxide (3.9). The capacitor $C_{t_a}$ was computed to be 4.3 pF. This value compares very favorably to a measured value of 4.35 pF. The ratio $C_{t_a}/C_t$ was computed to be 1.1.

In addition, we know from the model that given $C_{t_a}/C_t$, the high-frequency gain is determined uniquely by the two parameters $C_x/C_t$ and $C_{t_a}/C_a$. From the low-dew-point, high-frequency measurements we know the value of the high-frequency gain for all devices to be $-49 \pm 1$ decibels. On this basis, it was assumed that this high-frequency gain of $-49$ dB is a device constant. Given a value of $C_{t_a}/C_a$ (and $C_{t_a}/C_t$), the value of $C_x/C_t$ that is required for a high-frequency model gain of $-49$ dB may be determined.
Figure 14) Data for Various Dew Points and Frequencies for a Freshly-Coated Sample
<table>
<thead>
<tr>
<th>DIELECTRIC</th>
<th>AREA (mil$^2$)</th>
<th>THICKNESS (μm)</th>
<th>DIELECTRIC PERMITIVITY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Field oxide</td>
<td>$C_1$ 129.0</td>
<td>$C_t$ --</td>
<td>1.0</td>
</tr>
<tr>
<td>Source/Drain Oxide</td>
<td>$C_1$ 3.5</td>
<td>$C_t$ --</td>
<td>0.25</td>
</tr>
<tr>
<td>Channel Oxide</td>
<td>$C_1$ 5.0</td>
<td>$C_t$ 0.10</td>
<td>0.10</td>
</tr>
<tr>
<td>Field Oxide and Polymer</td>
<td>$C_t$ --</td>
<td>$C_1$ 203</td>
<td>1.2</td>
</tr>
<tr>
<td>CAPACITANCE (pF)</td>
<td>$C_1$ 4.30</td>
<td>$C_t$ 3.77</td>
<td></td>
</tr>
</tbody>
</table>
Thus, of the four model parameters, two may be treated as device constants: \( C_t/C_a \) and high-frequency gain. These two may be considered as independent of frequency and of dew point. The remaining two parameters may be expressed as a family of curves in gain-phase space (Figure 15). These curves were generated by first selecting a value for \( C_t/C_a \), and then computing the value for \( C_x/C_t \) necessary to maintain the high-frequency gain of -49 dB. The parameter \( \gamma \) was then varied logarithmically from very low to very high, each value yielding a gain and phase which was subsequently plotted as a continuous curve. The ratio of \( C_t/C_a \) is limited to a minimum of approximately 21 by the high-frequency gain restriction, but has no such restriction as far as maximum value.

In general, the effect of increasing \( C_t/C_a \) is to increase the bowing of the curve in gain-phase space. If \( C_t/C_a \) is large enough, phase will fall to -360 degrees and settle there, rather than returning to zero. This phenomenon has been observed on some samples (14).

The measured data can be plotted in gain-phase space and compared to the model curves. For the two aged samples, most of the data lie on one curve, for a value of \( C_t/C_a \) of 44 (Figure 16). For the freshly-coated samples, the data are seen to fall between the curves for which \( C_t/C_a \) has values 21 and 45 (Figure 17).

An effort was made to determine why the data for freshly-coated samples did not fall on a single curve. Data were plotted for constant frequency (Figure 18) and for constant dew point (Figure 19) in the gain-phase space. For both constant frequency and constant dew point, the data do fall on a single, smooth curve. However, in neither case do these curves exhibit a unique value for \( C_t/C_a \). This indicates that \( C_t/C_a \), or perhaps some other component of the model, is a weak function of
Figures 15) Model curves for $C_1/C_t = 1.1$, high-frequency gain = $-49\text{dB}$, and varying $C_t/C_a$. 
Figure 16) Model Curve Plotted with Data for all Frequencies and Dew Points for an Aged Sample

$C_t/C_a = 44$
Figure 17) Model Curves Plotted with Data for all Frequencies and Dew Points for a Freshly-Coated Sample
Figure 19) Comparison of Model Curves to Data of Constant Dew Point for a Freshly-Coated Sample
frequency and/or dew point. In general, for both the case of constant frequency and of constant dew point, the ratio $C_t/C_a$ appears to increase as gain decreases. Perhaps, the portion of the interelectrode capacitance which interacts with the thin film conductance decreases for decreasing gain, or maybe an element, such as contact admittance, must be added to the model. This phenomenon has not as yet been explained satisfactorily.

The final unknown to be extracted from the data is sheet resistance, $\rho$. This may be done with relatively little effort, since $R_a$ and frequency scale with one another.

For each dew point, the measured data are plotted on two sets of axes: gain vs. frequency, and phase vs. frequency. An arbitrary value for the product $R_{a}C_{a}$ is selected. A model curve is plotted for this value of $R_{a}C_{a}$, using the extracted $C_t/C_a$ and the computed $C_{l}/C_t$ and $C_x/C_t$. When $R_{a}C_{a}$ is varied, the model curves simply shift along the frequency axis. The value of $R_{a}C_{a}$ is selected which results in best agreement between the model and the data for the particular dew point. The value of the sheet resistor for that dew point is then determined from the formula

$$R_a = \frac{R_{a}C_{a}}{C_l} \frac{C_{l}}{C_t} \frac{C_t}{C_a}$$

The sheet resistance in ohms per square is then computed by dividing by the number of interelectrode squares—in this case, $1/812$.

The value of sheet resistance was extracted in this way for the two aged samples, using a value of 45 for the ratio $C_t/C_a$. After extraction of this final unknown, data is replotted versus model curves for several dew points (Figure 20). Agreement between the model and
Figure 20) Model curves plotted with data for various dew points for an aged sample.
the data is excellent.

For the freshly-coated devices, this extraction was performed using three values for $C_{t/a}$: the limiting case values of 21 and 45, as well as an intermediate value of 35. Agreement between the three cases is very good (Table 3)—only at very high sheet resistances was there noticeable discrepancy. This is due to the fact that the extraction concentrates on the data at the high-gain end of the spectrum, where variations in $C_{t/a}$ are unimportant. For the high sheet resistances, however, the 1 Hz minimum frequency limitation of our measurements, forced extraction from the low-gain data.

Because of the relative insensitivity to the ratio $C_{t/a}$, all further extractions of sheet resistance were done with $C_{t/a} = 45$. The resulting comparison of experimental data and model for a freshly-coated sample is presented in Figure 21. Agreement is again quite good.

The extracted values of sheet resistance for all five samples are plotted versus dew point in Figure 22. For dew point values greater than approximately +5 degrees centigrade, reproducibility between the samples is good. The existing variation from device to device appears to be an offset in temperature, more than one of sheet resistance. This temperature offset is at most 4 degrees centigrade, slightly greater than the temperature fluctuation observed during the measurement period.

At low dew points, the sheet resistance saturates at some high value. This saturation value varies from one sample to the next by a maximum of about an order of magnitude, the two highest values being those measured on the aged samples. It is suggested that this high-frequency value of sheet resistance is determined by the bulk conduction
<table>
<thead>
<tr>
<th>DEW POINT (°C)</th>
<th>SHEET RESISTANCE (Ω/□)</th>
<th>% VARIATION</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$C_{t}/C_{a}=21$</td>
<td>$C_{t}/C_{a}=35$</td>
</tr>
<tr>
<td>-26.6</td>
<td>$1.71 \times 10^{15}$</td>
<td>$1.30 \times 10^{15}$</td>
</tr>
<tr>
<td>-3.6</td>
<td>$5.26 \times 10^{14}$</td>
<td>$4.86 \times 10^{14}$</td>
</tr>
<tr>
<td>+3.6</td>
<td>$2.10 \times 10^{14}$</td>
<td>$1.93 \times 10^{14}$</td>
</tr>
<tr>
<td>+6.1</td>
<td>$1.07 \times 10^{14}$</td>
<td>$1.07 \times 10^{14}$</td>
</tr>
<tr>
<td>+8.2</td>
<td>$5.07 \times 10^{13}$</td>
<td>$4.91 \times 10^{13}$</td>
</tr>
<tr>
<td>+10.5</td>
<td>$1.60 \times 10^{13}$</td>
<td>$1.56 \times 10^{13}$</td>
</tr>
<tr>
<td>+13.0</td>
<td>$2.88 \times 10^{12}$</td>
<td>$2.91 \times 10^{12}$</td>
</tr>
<tr>
<td>+15.2</td>
<td>$4.70 \times 10^{11}$</td>
<td>$4.60 \times 10^{11}$</td>
</tr>
<tr>
<td>+17.2</td>
<td>$1.40 \times 10^{11}$</td>
<td>$1.42 \times 10^{11}$</td>
</tr>
<tr>
<td>+18.7</td>
<td>$3.73 \times 10^{10}$</td>
<td>$3.80 \times 10^{10}$</td>
</tr>
</tbody>
</table>
Figure 21) Model Curves Plotted with Data for Various Dew Points for a Freshly Coated Sample
Figure 22) Plot of Extracted Sheet Resistance vs. Dew Point for All Samples
through the polymer, and that the bulk conduction for freshly-coated samples is greater than for aged samples, perhaps due to incomplete removal of the solvent (water) from the freshly cast films. For higher dew points, surface conduction dominates, independent of polymer age, and bulk conductivity variations from device to device are unimportant.
CHAPTER 5: LIMITATIONS OF THE NEW TECHNIQUE

Thus far, the fingered-gate device has been used to measure sheet resistances in the range $10^{10}$ to $10^{16}$ ohms per square. At the high end of this range, there has been no information in the gain of the measured transfer function—extraction relied entirely on the information contained in the phase. For sheet resistances higher than approximately $10^{16}$ ohms per square, even information in the phase of the response is lost.

This, however, does not arise from a fundamental limitation of the device or measurement technique, but from the frequency limitation of the equipment employed. Presumably, for any value of sheet resistance, there is a frequency of measurement at which any portion of the transfer function curve may be measured. From the theory, this is seen from the important fact that frequency and sheet resistance scale. This arises physically due to the fact that all impedances in the system are capacitive, other than the sheet resistance itself.

The low-frequency limitation of 1 Hz is contributed by the gain-phase measuring instrument. The high-frequency limitation of 3 kHz is attributable to the operational amplifiers in the measurement circuitry. Both of these could be extended. Reasonable measurement times prevent the use of frequencies less than about .1 Hz, however.

In addition, device geometry may be modified to adjust the range of sensitivity, given a restricted frequency range. Effects of device geometry variations may be estimated by making a simplified model of the system (Figure 23). In this model, the capacitances $C_a$ and $C_x$ have been lumped together to form a single capacitor, $C_x'$. Likewise, $C_1$ and $C_e$ have been joined to form a single load capacitor, $C_1'$. The transfer
Figure 23) Simplified CFT Mo. 31
function $V_{FG}/V_{DG}$ for this model is

$$\frac{V_{FG}}{V_{DG}} = \frac{R_a C_x' \omega j + 1}{R_a (C_x' + C_1') \omega j + 1} .$$

The values of the three elements are estimated as before:

$$R_a = \frac{\rho W}{2NL} ,$$

$$C_1' = 3NWL \frac{\varepsilon_{ox}}{t_{ox}} ,$$

$$C_x' = NL\varepsilon_0 .$$

At high sheet resistances, the imaginary terms of the transfer function dominate. To retain sensitivity,

$$R_a C_x' = \omega \rho \varepsilon_0 \frac{W}{2} \geq 10 .$$

Therefore, the maximum sheet resistance that may be measured is

$$\rho_{\text{max}} = \frac{20}{\omega \min \varepsilon_0 W} .$$

The formula says that the maximum measurable sheet resistance is indirectly proportional to the electrode spacing and minimum frequency.

For the current device dimensions, the formula predicts a $\rho_{\text{max}} = 3 \times 10^{16}$ ohms per square for 1 Hz measurements. If devices were made with lock and keys having 1 micron spaces, an increase of $\rho_{\text{max}}$ to $4 \times 10^{17}$ ohms per square is predicted.

At low sheet resistances, the real terms of the transfer function dominate. To retain sensitivity,

$$R_a (C_x' + C_1') \omega = R_a C_1' \omega = \frac{3}{2} \frac{\varepsilon_{ox}}{t_{ox}} \rho W^2 \geq 0.1 .$$

Therefore,
\[ \rho_{\text{min}} = \frac{2}{3} \frac{t_{\text{ox}}}{\varepsilon_{\text{ox}}} \frac{1}{\omega_{\text{max}} \omega^2} . \]

This formula indicates that minimum measurable sheet resistance is indirectly proportional to oxide thickness, and proportional to the square of the interelectrode spacing. For a maximum frequency of 3 kHz, and current device dimensions, the formula predicts

\[ \rho_{\text{min}} = 6 \times 10^8 . \]

This value is not unreasonable, since during the course of the PEO experiments, this minimum sheet resistance limit was not pushed.

In summary, the present technique is applicable over a wide range of sheet resistance. The range of sensitivity may be improved by either extending the range of frequency of measurement, or by modifying the device geometry.
APPENDIX A. SYMBOL DEFINITIONS

$C_a$  Horizontal capacitive component of transmission line model

$C_{ch}$  Channel capacitance

$C_l$  Load capacitor of transmission line model

$C_{lk}$  Interelectrode capacitance of the lock and key

$C_t$  Vertical capacitive component of transmission line model

$C_x$  Stray capacitor in the transmission line model

$G_a$  Horizontal conductance of transmission line model, $1/R_a$

$g_m$  FET transconductance

$I$  Complex current variable

$k$  FET gain

$L$  Length of lock and key fingers

$m$  Body-effect factor

$N$  Number of lock and key fingers

$R_a$  Interelectrode resistance of the transmission line model, $1/G_a$

$\omega$  Natural frequency of the transmission line model

$p$  Time

$t_{ox}$  Oxide thickness

$V$  Complex voltage variable

$V_{DG}$  Driven-gate voltage

$V_{DS}$  Drain to source voltage

$V_{FG}$  Floating-gate voltage

$V_{GS}$  Gate to source voltage

$V_{SB}$  Source to substrate voltage

$W$  Width of lock and key finger (and gap)

$x$  Spacial variable in the transmission line model

$Y$  Complex admittance

$Z$  Complex impedance

$\varepsilon_m$  Dielectric permittivity of sensing medium

$\varepsilon_{ox}$  Dielectric permittivity of silicon dioxide

$\varepsilon_{sub}$  Dielectric permittivity of substrate

$\omega$  Radial frequency

$\rho$  Sheet resistance in ohms/square

$\theta$  Mobility degradation parameter

$\gamma$  Transmission line model parameter, $1/(R_a C_{a \omega})$
APPENDIX B. SOLUTION TO TRANSMISSION LINE MODEL

Refer to Figure 12. Voltage on the transmission line varies both with time \( t \) and position \( x \). The driven gate is at position \( x = 0 \), and the floating gate is at \( x = W \). The variation with time is assumed to be sinusoidal, and complex notation is employed:

\[
V(x,t) = V(x) e^{j\omega t}.
\]

All elements are also converted to complex notation, for example,

\[
Y_a = G_a + C_a \omega j.
\]

The voltage and current variation along the line may be described by the following two equations:

\[
I_x = (V_x - V_{x+dx}) Y_a (W/dx) = -WY_a \frac{dV}{dx};
\]

\[
V_{x+dx} Y_t (dx/W) = I_x - I_{x+dx}, \text{ or } V_{x+dx} = -\frac{W}{Y_t} \frac{dI}{dx}.
\]

The variable \( I(x) \) may be eliminated from the above equations, to yield a single expression for the voltage distribution:

\[
\frac{d^2V}{dx^2} = \frac{Y_t}{YW_a^2} V(x).
\]

The general form of the solution is

\[
V(x) = A \sinh s_0 x + B \cosh s_0 x,
\]

where \( s_0 = \frac{1}{W} (Y_t/Y_a)^{1/2} \). The values of the constants \( A \) and \( B \) may be determined by application of the appropriate boundary conditions:

1) \( V(x=0) = V_0 \)

2) \( I(x=W) = -WY_a \frac{dV}{dx}(x=W) = Y_a V(x=W) + Y_x(V(x=W) - V(x=0)) \).
The first boundary condition yields \( B = V_0 \). The second boundary condition is expressed as the following equation:

\[
-aY_a (A \cosh \alpha + B \sinh \alpha) = (Y_x + Y_1)(A \sinh \alpha + B \cosh \alpha) - Y_x B,
\]

where \( \alpha = s_0 W = (Y_x / Y_a)^{1/2} \).

This expression may be solved for the constant \( A \) yielding

\[
A = \frac{-V_0 \alpha Y_a \sinh \alpha + (Y_1 + Y_x) \cosh \alpha - Y_x}{(\alpha Y_a \cosh \alpha + (Y_1 + Y_x) \sinh \alpha)}.
\]

The transfer function from driven gate to floating gate is expressed as

\[
\frac{V_{FG}}{V_{DG}} = \frac{V(x=W)}{V(x=0)} = \frac{A}{V_0} \sinh \alpha + \cosh \alpha.
\]

The result may be expressed as

\[
\frac{V_{FG}}{V_{DG}} = \frac{\alpha Y_a + Y_x \sinh \alpha}{\alpha Y_a \cosh \alpha + (Y_1 + Y_x) \sinh \alpha}
\]

by taking advantage of the identity \( \cosh^2 \alpha - \sinh^2 \alpha = 1 \).

By dividing this expression by \( \alpha Y_a \), and reconvertting from complex admittances to conductances and capacitances, the solution may be expressed as

\[
\frac{V_{FG}}{V_{DG}} = \frac{1 + (C_x/C_t) \alpha \sinh \alpha}{\cosh \alpha + (C_1/C_t + \frac{C_x}{C_t}) \alpha \sinh \alpha}.
\]

Note that \( \alpha \) may be expressed as

\[
\alpha = \frac{(C_t/C_a)^{1/2} j}{1/R_a C_a \omega + j}.
\]

Expressed in this form, the model has essentially four parameters: \( C_1/C_t, C_x/C_t, C_t/C_a, \) and \( \gamma = 1/(R_a C_a \omega) \).
APPENDIX C. DEVICE FABRICATION PROCEDURE

1. Wafer Characterization—use a <100>, p-type silicon wafer, .1-.4 ohm-cm
   a. Hot probe check for wafer carrier type
   b. 4-point probe measurement of sheet resistance
   c. Wafer thickness measurement with the micrometer

2. Field Oxidation
   a. I-Clean
   b. 15 minutes in dry $O_2$ @ 1100°C
      120 minutes in wet $O_2$ @ 1100°C
      10 minutes in dry $O_2$ @ 1100°C

3. Source/Drain Photolithography
   a. Apply KTFR
   b. Expose wafer for 5 seconds using Source/Drain Mask
   c. Develop and postbake KTFR
   d. 10 minute etch in buffered etch, rinse in DH$_2$O, and blow dry ($N_2$)
   e. Strip KTFR

4. Source/Drain Implant
   a. Element—Arsenic
   b. Dose—8 x 10$^{15}$
   c. Energy—100 keV

5. Source/Drain Anneal and Oxidation
   a. G-Clean
   b. 20 minutes in wet $O_2$ @ 1000°C

6. Thin Oxide Photolithography
   a. Apply KTFR
   b. Expose wafer for 5 seconds using Thin Oxide Mask
   c. Develop and postbake KTFR
   d. 10 minute etch in buffered etch, rinse in DH$_2$O, and blow dry ($N_2$)
   e. Strip KTFR

7. Gate Oxidation
   a. G-Clean
   b. 40 minutes in dry $O_2$ @ 1100°C
      10 minutes in $N_2$ @ 1100°C
8. Channel Implant Photolithography
   a. Apply Shipley B photoresist
   b. Expose wafer for 5 seconds using Contact Mask
   c. Develop and postbake Shipley B photoresist

9. Channel Implant
   a. Element—Phosphorous
   b. Dose—$2.5 \times 10^{12}$
   c. Energy—90 keV

10. Channel Implant Activation and Anneal
    a. Strip Shipley B photoresist
    b. G-Clean
    c. 20 minutes in $N_2 @ 950^\circ C$

11. Contact Photolithography
    a. Apply KTFR
    b. Expose wafer for 5 seconds using Contact Mask
    c. Develop and postbake KTFR
    d. Etch for 2 minutes in buffered etch, rinse in $DH_2O$, blow dry ($N_2$)
    e. Strip KTFR

12. Clean Metal Aluminization—as per instructions (15)

13. Metallization Photolithography
    a. Apply Shipley B photoresist
    b. Expose wafer for 5 seconds using Metallization Mask
    c. Develop and postbake Shipley B photoresist
    d. Etch in PAN etch for approximately 5 minutes (do by inspection),
       rinse in $DH_2O$, blow dry ($N_2$
    e. Strip Shipley B photoresist

14. Alloying
    a. Rinse wafers in Trico, acetone, $DH_2O$, and blow dry ($N_2$
    b. Alloy in $N_2 @ 450^\circ C$ for 5 minutes, leave in tube and for
       5 additional minutes
I-Clean
   a. 10 minutes in #3 stripping solution @ 90°C
   b. 1 minute rinse in DH₂O
   c. 15 seconds in concentrated HF
   d. 1 minute rinse in DH₂O
   e. 10 minutes in nitric acid @ 90°C
   f. 3 minute rinse in DH₂O, blow dry (N₂)

G-Clean
   a. 10 minutes in #3 stripping solution @ 90°C
   b. 1 minute rinse in DH₂O
   c. 15 seconds in 10:1 HF
   d. 1 minute rinse in DH₂O
   e. 10 minutes in nitric acid @ 90°C
   f. 3 minute rinse in DH₂O, blow dry (N₂)

Procedure for Application of KTFR
   a. Spin on resist for 15 seconds @ 6000 RPM
   b. Pre-bake for 20 minutes @ 90 degrees centigrade

Procedure for Application of Shipley B photoresist
   a. Spin on resist for 15 seconds @ 3000 RPM
   b. Pre-bake for 2-1/2 minutes @ 90°C
   c. Repeat steps a. and b.

Procedure for the Developing and Postbaking of KTFR
   a. Develop by spraying with KTFR developer for 60 seconds
   b. Postbake for 30 minutes @ 180°C

Procedure for the Developing and Postbaking of Shipley B photoresist
   a. Develop by immersion in beaker of Az Developer for 25 seconds
   b. Postbake for 30 minutes @ 180°C

Procedure for Stripping Photoresist (KTFR or Shipley B)
   a. Strip resist for 5 minutes in A-20 @ 90°C
   b. Rinse in warm DH₂O, cool DH₂O, and blow dry (N₂)
APPENDIX D. SUPREM SIMULATION OF DEVICE FABRICATION

The device fabrication procedure was designed with the aid of the computer simulation program SUPREM (Stanford University Process Engineering Models Program), executed on the MIT CMS system. The program output is presented in condensed form in the following pages. Simulation was performed over three areas of the device: the field, the source/drain, and the channel regions.
*** STANFORD UNIVERSITY PROCESS ENGINEERING MODELS PROGRAM ***

*** VERSION 0-03A ***

1. TITLE FIELD REGION
2. GRID DYSI=.01,DPTH=.1,YMAX=3
3. SUBS ORNT=100,ELEM=B,CONC=6.3E16
4. MODEL NAME=SPM1,GATE=AL,QSSQ=2.5E11,CBLK=0
5. STEP TYPE=OXID,TEMP=1100,TIME=15,MODL=DRY0
6. STEP TYPE=OXID,TEMP=1100,TIME=120,MODL=WET0
7. STEP TYPE=OXID,TEMP=1100,TIME=10,MODL=DRY0
8. STEP TYPE=OXID,TEMP=1100,TIME=20,MODL=WET0
9. STEP TYPE=OXID,TEMP=1100,TIME=40,MODL=DRY0
10. PRINT HEAD=Y
11. PLOT TOTL=Y,CMIN=14,NDEC=7,WIND=3,DIV=Y
12. STEP TYPE=OXID,TEMP=1100,TIME=10,MODL=NIT0,MODL=SPM1
13. END

*** STANFORD UNIVERSITY PROCESS ENGINEERING MODELS PROGRAM ***

*** VERSION 0-03A ***

1. TITLE MODEL OF ARSENIC-DOPED REGIONS
2. GRID DYSI=.001,DPTH=.5,YMAX=4
3. SUBS ORNT=100,ELEM=B,CONC=6.3E16
4. MODEL NAME=SPM1,CBLK=0,QSSQ=2.5E11,GATE=AL
5. STEP TYPE=OXID,TIME=40,TEMP=1100,MODL=DRY0
6. STEP TYPE=OXID,TIME=10,TEMP=1100,MODL=NIT0
7. STEP TYPE=IMPL,DOSE=2.5E12,AKEV=90,ELEM=P
8. PRINT HEAD=Y
9. PLOT TOTL=Y,DIV=N,CMIN=14,NDEC=7,WIND=2
10. STEP TYPE=OXID,TEMP=1100,TIME=10,MODL=NIT0
11. END

*** STANFORD UNIVERSITY PROCESS ENGINEERING MODELS PROGRAM ***

*** VERSION 0-03A ***

1. TITLE CHANNEL REGION
2. GRID DYSI=.01,DPTH=.5,YMAX=2
3. SUBS ORNT=100,ELEM=B,CONC=6.3E16
4. MODEL NAME=SPM1,CBLK=0,QSSQ=2.5E11,GATE=AL
5. STEP TYPE=OXID,TIME=40,TEMP=1100,MODL=DRY0
6. STEP TYPE=OXID,TIME=10,TEMP=1100,MODL=NIT0
7. STEP TYPE=IMPL,DOSE=2.5E12,AKEV=90,ELEM=P
8. PRINT HEAD=Y
9. PLOT TOTL=Y,CMIN=14,NDEC=7,WIND=5
10. STEP TYPE=OXID,TIME=20,TEMP=950,MODL=NIT0,MODL=SPM1
11. END
FIELD REGION

STEP # 6

NEUTRAL AMBIENT DRIVE-IN
TOTAL STEP TIME = 10.0 MINUTES
INITIAL TEMPERATURE = 1100.00 DEGREES C.
OXIDE THICKNESS = .9131 MICRONS

I OXIDE I SILICON I I SURFACE I
I DIFFUSION I DIFFUSION I SEGREGATION I TRANSPORT I
I COEFFICIENT I COEFFICIENT I COEFFICIENT I

BORON I 2.0972E-07 I 8.9033E-04 I .66145 I 1.3113E-02 I

SURFACE CONCENTRATION = 4.04126E+16 ATOMS/CM^3

GATE MATERIAL = ALUMINUM SILICON UNDER GATE = P - TYPE
OXIDE THICKNESS = 9131.4 ANG. CAPACITANCE/AREA = 3.78E-05 PF/UM2
INTERFACE CHARGES = 2.50E+11 CM^-2 INTF CHARGE VOLT. =-10.596 Volts
FLATBAND VOLTAGE = -11.652 VOLTS
/VSB/ 0.0 0.50 1.00 1.50 2.00 3.00 4.00 5.00 6.00 7.00 10.00 15.03
VTHR 16.68 24.46 30.85 36.42 41.44 50.35 58.20 65.31 71.87 78.00 94.5217 97
XDPL 0.16 0.21 0.24 0.27 0.30 0.34 0.38 0.42 0.45 0.48 0.55 0.65

JUNCTION DEPTH I SHEET RESISTANCE
I I 1114.77 OHMS/SQUARE

NET ACTIVE CONCENTRATION

OXIDE CHARGE = 3.69384E+12 IS 19.7 % OF TOTAL
SILICON CHARGE = 1.50836E+13 IS 80.3 % OF TOTAL
TOTAL CHARGE = 1.87774E+13 IS 100.0 % OF INITIAL
INITIAL CHARGE = 1.87772E+13

CHEMICAL CONCENTRATION OF BORON

OXIDE CHARGE = 3.69384E+12 IS 19.7 % OF TOTAL
SILICON CHARGE = 1.50836E+13 IS 80.3 % OF TOTAL
TOTAL CHARGE = 1.87774E+13 IS 100.0 % OF INITIAL
INITIAL CHARGE = 1.87772E+13

-64-
**FIELD REGION**

STEP = 6  
TIME = 10.0 MINUTES.

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MODEL OF ARSENIC-DOPED REGIONS

STEP # 4

NEUTRAL AMBIENT DRIVE-IN
TOTAL STEP TIME = 10.0 MINUTES
INITIAL TEMPERATURE = 1100.00 DEGREES C.
OXIDE THICKNESS = .2936 MICRONS

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<thead>
<tr>
<th></th>
<th>OXIDE DIFFUSION</th>
<th>SILICON DIFFUSION</th>
<th>SEGREGATION</th>
<th>TRANSPORT COEFFICIENT</th>
<th>SURFACE COEFFICIENT</th>
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<tbody>
<tr>
<td>BORON</td>
<td>2.0972E-07 I</td>
<td>8.9033E-04 I</td>
<td>.66145</td>
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<td>4.4701E-02 I</td>
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SURFACE CONCENTRATION = -1.06986E+20 ATOMS/CM^2

JUNCTION DEPTH SHEET RESISTANCE
------------------------ ------------------------
.774699 MICRONS 1849.62 OHMS/SQUARE
1844.844 OHMS/SQUARE

NET ACTIVE CONCENTRATION

OXIDE CHARGE = 3.12483E+15 IS 39.9 % OF TOTAL
SILICON CHARGE = 4.70315E+15 IS 60.1 % OF TOTAL
TOTAL CHARGE = 7.82799E+15 IS 100. % OF INITIAL
INITIAL CHARGE = 7.81584E+15

CHEMICAL CONCENTRATION OF BORON

OXIDE CHARGE = 1.04950E+12 IS 4.17 % OF TOTAL
SILICON CHARGE = 2.41363E+13 IS 95.8 % OF TOTAL
TOTAL CHARGE = 2.51858E+13 IS 100. % OF INITIAL
INITIAL CHARGE = 2.51837E+13

CHEMICAL CONCENTRATION OF ARSENIC

OXIDE CHARGE = 3.30221E+15 IS 41.1 % OF TOTAL
SILICON CHARGE = 4.73577E+15 IS 58.9 % OF TOTAL
TOTAL CHARGE = 8.03798E+15 IS 100. % OF INITIAL
INITIAL CHARGE = 8.03770E+15
## MODEL OF ARSENIC-DOPED REGIONS

**STEP = 4**  
**TIME = 10.0 MINUTES.**

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**SUPREM END.**
CHANNEL REGION
STEP # 4

NEUTRAL AMBIENT DRIVE-IN
TOTAL STEP TIME = 20.0 MINUTES
INITIAL TEMPERATURE = 950.000 DEGREES C.
OXIDE THICKNESS = 8.407E-02 MICRONS

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<th>OXIDE</th>
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<td>COEFFICIENT</td>
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BORON | 5.4047E-09 | 2.5566E-05 | .24457 | 1.0023E-03 |

PHOSPHORUS | 1.7279E-07 | 1.9182E-05 | 10.000 | 5.6835E-03 |

SURFACE CONCENTRATION = -2.28879E+17 ATOMS/CM^3

GATE MATERIAL = ALUMINUM
SILICON UNDER GATE = N-TYPE
OXIDE THICKNESS = 840.7 ANG. CAPACITANCE/AREA = 4.11E-04 PF/UM2
INTERFACE CHARGES = 2.50E+11 CM^-2 INF CHARGE VOLT. = -0.976 VOLTS
FLATBAND VOLTAGE = -2.031 VOLTS
/VSB/ | 0.0 | 0.50 | 1.00 | 1.50 | 2.00 | 3.00 | 4.00 | 5.00 | 6.00 | 7.00 | 10.00 | 15.00
VTHR | -4.28 | -3.55 | -2.95 | -2.64 | -2.81 | -1.16 | -0.45 | 0.21 | 0.83 | 1.41 | 3.00 | 5.26
XDPL | 0.22 | 0.25 | 0.27 | 0.30 | 0.31 | 0.35 | 0.38 | 0.41 | 0.44 | 0.46 | 0.54 | 0.62

JUNCTION DEPTH | SHEET RESISTANCE
| .100110 MICRONS | 8625.84 OHMS/SQUARE | 1496.56 OHMS/SQUARE

NET ACTIVE CONCENTRATION

OXIDE CHARGE = 5.43101E+11 IS 4.15 % OF TOTAL
SILICON CHARGE = 1.25525E+13 IS 95.9 % OF TOTAL
TOTAL CHARGE = 1.30956E+13 IS 99.7 % OF INITIAL
INITIAL CHARGE = 1.31320E+13

CHEMICAL CONCENTRATION OF BORON

OXIDE CHARGE = 5.45771E+11 IS 4.36 % OF TOTAL
SILICON CHARGE = 1.19650E+13 IS 95.6 % OF TOTAL
TOTAL CHARGE = 1.25108E+13 IS 100. % OF INITIAL
INITIAL CHARGE = 1.25109E+13

CHEMICAL CONCENTRATION OF PHOSPHORUS

OXIDE CHARGE = 6.77489E+11 IS 27.1 % OF TOTAL
SILICON CHARGE = 1.82889E+12 IS 72.9 % OF TOTAL
TOTAL CHARGE = 2.50038E+12 IS 100. % OF INITIAL
INITIAL CHARGE = 2.50086E+12

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SUPREM END.
APPENDIX E. DETAILED MASK LAYOUT

The device fabrication procedure as detailed in Appendix C employs four photomasks: 1) Source/Drain, 2) Thin Oxide, 3) Contact, and 4) Metalization. In addition, a fifth mask for overglass passivation was designed and fabricated, but not as yet used in device fabrication. The following pages include an overlay of the four utilized masks, followed by an individual presentation of each of the five masks (Figures E1-6).

The layout contains a fingered-gate CFT, a floating-gate CFT, and a standard FET. The devices are surrounded by eight bonding pads, labeled as follows:

FD: the FET drain;
FG: the FET gate;
FS: the FET source;
CG: the driven gate for both CFT's;
CD1: the drain of the floating-gate CFT;
CS: the source of both CFT's;
CD2: the drain of the fingered-gate CFT;
SUB: the substrate contact.

The interdigitated portion of the inner electrode has 10 fingers, each finger being .5 mils wide and 37.5 mils long. The interelectrode gap is a constant .5 mils. The circumference of the inner electrode is 406 mils.

The FET's have a channel length of .5 mils, and a channel width of 5 mils. Bonding pads are 10 mils to the side, and separated by 20 mils. The unusually large bonding pads are required for the flip-chip packaging scheme described in Appendix G.
APPENDIX F. DESCRIPTION OF THE COMPUTER PROGRAM DEWPNT

To aid in the analysis of the moisture-sensing data, the computer program DEWPNT was written on the MIT Microelectronics Laboratory HP-9835A calculator. The program is written in BASIC, and employs the HP-2631A line printer and the HP-7225A plotter. The user controls the flow of the program with the twelve Special Function Keys, number zero through eleven (SFK#0-11).

Keys SFK#0-2 initiate the data handling routines within the program. Data files managed by the program consist of a collection of data points. Each data point in the file consists of four numbers: 1) dew point, 2) frequency, 3) gain, and 4) phase. SFK#0 is used to create new data files, SFK#1 is used to edit existing files, and SFK#2 is used to load existing files from the cassette tape on which they are stored.

Keys SFK#3-4 are used to create the plots of gain vs. phase. SFK#3 initiates the plot (draws the axes, does the labeling, etc.) and allows the user to plot data in the gain-phase space. Data of selected dew point values, or all data, may be plotted.

SFK#4 is used to plot model curves in the gain-phase space. When this key is pressed the user is asked to enter values for $C_1/C_t$, measured high-frequency gain (Mhfg), and $C_t/C_a$. The parameter $\gamma$ (Gamma) is varied logarhythmically from negligibly small, to very large. At each Gamma, the value of the transfer function $V_{FG}/V_{DG}$ is computed using the solution of Appendix B, and subsequently plotted as a smooth curve in gain-phase space.

Pressing SFK#5 initiates the sheet resistance extraction routine.
For each dew point, this routine determines the value of the product $R \frac{C}{\alpha \alpha}$ which results in the best fit of model to data. Most recently entered model parameters are used in the extraction, and in addition the user is asked to enter the value of two more quantities: the load capacitor $C_l$ (in pF), and the reciprocal number of interelectrode squares (Nsq).

The first step in the extraction algorithm is to generate an array of values for gain and phase, calculated from the model with a wide range of values for the parameter Gamma. This step consumes the bulk of the computing time (about 1 minute). Next, the high-frequency gain (Hfg) as predicted by the model is computed. Then, for each value of dew point contained in the data file, the following is done:

1. the data file is searched for all data points of the particular dew point, and a new list of these points only is formed;
2. the data point list is searched for points that have gain less than $-3$ dB but greater than $Hfg+3$ dB. If one or more such points exist, the routine continues with a gain-based extraction. If no such points exist, then a phase-based extraction is employed;
3. the value of $R \frac{C}{\alpha \alpha}$ (Raca), and the computed value of sheet resistance are printed on the line printer. Sheet resistance is computed from extracted Racas using the relation

$$R \alpha \alpha = \frac{C_{t}}{C_{\alpha}} \frac{C_{l}}{N_{sq}} \frac{N_{sq}}{C_{\alpha}} \frac{C_{t}}{C_{l}} .$$

The gain-based extraction begins by finding the value of Gamma for each of the selected data points. These values of Gamma are determined by searching the array of model points for the two surrounding values of gain, and interpolating. The product Racas is then computed for each data point using the relation
Raca = Gamma/\omega ,

where \omega is the frequency in radians of the data point.

These values of Raca are then averaged with a weighting factor of Gslope, the slope of the gain curve. In other words, data points that are located near the flat portion of the gain curve receive a small weighting factor, while the data points on the steep portion of the gain curve are heavily weighted. The weighted average of Raca is returned as the extracted value.

When it is determined that the gain of the data points contain little information, a phase-based extraction is attempted. The list of data points is searched for the point with minimum phase. If this minimum phase is greater than -5 degrees, the routine returns a value of Raca=0, to indicate the lack of sufficient information in the data. Otherwise, the value of Raca that best fits the minimum phase data point is determined by the method discussed above, and is returned as the extracted value.

The keys SFK#6-7 are used to generate gain and phase vs. frequency plots. Pressing SFK#6 initiates the plot. When SFK#7 is pressed, the user may have data for selected dew points plotted on the gain and phase vs. frequency axes. Each set of dew point data is accompanied by a smooth curve as calculated from the model using the extracted values of Raca.

Pressing SFK#8 activates a routine that plots sheet resistance vs. dew point and relative humidity. The user must enter the value of R.H. for each dew point.

SFK#9, 10, and 11 are used respectively to modify plotter limits, enter values for the model parameters, and display the SFK menu. Included
with the plotter parameters is Perdec, which sets the number of model points per decade that will be calculated by all routines within the program. Included with the model parameters is Goffset, which is the gain offset of the data, as determined experimentally as a first step in calibration. The SFK menu includes the following information: 1) a short description of the function that each SFK performs, 2) current values of the plotter limits, and 3) current values of the model parameters. The SFK menu is normally redisplayed after returning from each of the subroutines.

Following, is a listing of the computer program DEWPNT.
THE ORIGINAL PRINT ON THE FOLLOWING PAGES IS ILLEGIBLE
620 INPUT "ENTER VALUE OF CX/CT",Cxt
630 INPUT "ENTER VALUE OF CT/CA",Cta
640 INPUT "ENTER VALUE OF CT/CA",Cta
650 INPUT "ENTER VALUE OF CX/CA",Cxa
660 INPUT "ENTER VALUE OF CL/CA",Clo
670 INPUT "ENTER GAIN OFFSET OF DEVICE",Goffset
680 GOTO Menu
681 ! SUBROUTINE TO INITIALIZE GAIN AND PHASE VS. FREQUENCY PLOT
690 Gplotinit: PLOTTER IS 7,5,"9872A"
700 CSIZE 2.5,.8
710 LOCATE 20,70,15,99
720 SCALE LGT(Fmin),LGT(Fmax),Gain,Gmax
730 AXES 1,10,0,0
740 LORG 4
750 FOR I=INT(LGT(Fmin)) TO INT(LGT(Fmax))
760 MOVE I,.02*(Gmax-Gmin)
770 LABEL 1
780 NEXT I
790 LORG 7
800 MOVE LGT(Fmax),Gmax+.05%(Gmax-Gmin)
810 LABEL "LOG(FREQUENCY)"
820 LORG 8
830 FOR I=INT(Gain/10) TO INT(Gmax/10)
840 MOVE 0,I*.1
850 LABEL I*.1
860 NEXT I
870 MOVE .03*(LG(Fmax)-LG(Fmin)),Gain
880 LORG 1
890 LABEL "GAIN (DB)"
900 LOCATE 80,130,15,91
910 SCALE LGT(Fmin),LGT(Fmax),Pmin,Pmax
920 AXES 1,30,0,0
930 LORG 4
940 FOR I=INT(LGT(Fmin)) TO INT(LGT(Fmax))
950 MOVE I,.02%(Pmax-Pmin)
960 LABEL I
970 NEXT I
980 MOVE LGT(Fmax),Pmax+.05%(Pmax-Pmin)
990 LORG 7
1000 LABEL "LOG(FREQUENCY)"
1010 LORG 9
1020 FOR I=INT(Pmin/30) TO INT(Pmax/30)
1030 MOVE 0,I*.333
1040 LABEL I*.333
1050 NEXT I
1060 LORG 1
1070 MOVE .03*(LG(Fmax)-LG(Fmin)),Pmin
1080 LABEL "PHASE"
1090 GOSUB Menu
1100 RETURN
1101 ! SUBROUTINE TO OVERRULE EXTRACTION OF SHEET RESISTANCE
1102 Extract: INPUT "ENTER NUMBER OF SQUARES FOR SHEET RESISTANCE",Nsq
1103 INPUT "ENTER VALUE OF CL (IN PF)",C1pf
1104 GOSUB Tablegen
1105 BEEP
1106 Cost=C1pf/C1t/Cto
1107 PRINTER 13 7,2,WIDTH(160)
1108 FOR Dctr=1 TO Dwellimit
1109 Dwell=Dwellimit(Dctr)
1100 GOSUB Getraca
1120 Remat(Dctr)=10*.128*Raca*Nsq/Cost
1120 PRINT USING "K,SDD.D,K.D.DDE,K,D.DDE"; Dwellimit,Dwellimit, Raca,Raca," SHEET RESISTANCE"
NCE: *,Ramat(Dctr)
1220  *NEXT Dctr
1230  GOSUB Menu
1240  RETURN
1241  *SUBROUTINE TO PLOT DATA AND MODEL CURVE ON GAIN AND PHASE VS. FREQUENCY AXES
1250  Geolot:PRINTER IS 16
1260  PRINT PAGE,"J.D.","DEW POINT"
1270  FOR I=1 TO Dewlim
1280  PRINT I,Dewmat(I)
1290  NEXT I
1300  Dewnum=0
1310  INPUT "ENTER DEW POINT NUMBER TO BE PLOTTED, OR HIT CONTINUE",Dewnum
1320  IF Dewnum=0 THEN GOTO Menu
1330  INPUT "ENTER TYPE FOR DATA PLOT (+,X,O,B,D)",T$    
1340  Glast=I/(Ramat(Dewnum)/Hsg*Ccapf/1E12*2*PI*Fmin)
1350  Gfirst=I/(Ramat(Dewnum)/Hsg*Ccapf/1E12*2*PI*Fmax)
1360  Mult=10"/(1/Perdec)
1370  CALL Modelolot(Gainmat($),Anglemat($),Npoints,Gfirst,Glast,Mult)
1380  LOCATE 20,70,15,90
1390  SCALE L(Gmmin,L(Gmmax),Gmin,Gmax
1400  PENUP
1410  W=2*PI*Fmax
1420  FOR I=1 TO Npoints
1430  PLOT L(G(W/2*PI)),Gainmat(I)
1440  W=W/Mult
1450  NEXT I
1460  PENUP
1470  W=2*PI*Fmax
1480  LOCATE 00.130,15,91
1490  SCALE L(Gfmin,L(Gfmax),Fmin,Fmax
1500  Lastangle=0
1510  FOR I=1 TO Npoints
1520  PLOT L(W/2*PI)),Anglemat(I)
1530  W=W/Mult
1540  NEXT I
1550  PENUP
1560  Dewplt=Dewmat(Dewnum)
1570  GOSUB Updatedatlot
1580  GOTO Geolot
1590  *SUBROUTINE TO PLOT SHEET RESISTANCE VS. DEW POINT AND RELATIVE HUMIDITY
1600  Rhoplot:PRINTER IS 7,2,WIDTH(160)
1610  PRINT LIN(2)
1620  PLOTTER IS 7,5,"9072A"
1630  LOCATE 20,70,15,06
1640  Ramin=1600
1650  Ramax=0
1660  Dewmin=100
1670  Dewmax=100
1674  FOR I=1 TO Dewlim
1680  IF (Ramat(I))Ramax AND (Ramat(I))(1E20) THEN Ramax=Ramat(I)
1690  IF (Ramat(I))Ramin AND (Ramat(I))(0) THEN Ramin=Ramat(I)
1700  IF Dewmat(I)Dewmax THEN Dewmax=Dewmat(I)
1710  IF Dewmat(I)Dewmin THEN Dewmin=Dewmat(I)
1720  NEXT I
1730 Ymin=INT(L(G(Ramin))
1740 Ymax=INT(L(G(Ramax))
1750 Xmin=5*INT(Dewmin/5)
1760 Xmax=5*INT(Dewmax/5)
1770 Xint=.01*(Xmax-Xmin)
1780 Yint=.01*(Ymax-Ymin)
1790 SCALE Xmin,Xmax,Ymin,Ymax
1800 AXES 5,1,0,Ymin
1810 MOVE 0,Ymax+.02*(Ymax-Ymin)
1820 LORG 1
1830 LABEL "LOG(RHD)"
1840 MOVE Xmax,Ymin-.06*(Ymax-Ymin)
1850 LORG 9
1860 LABEL "DEW POINT"
1870 FOR I=Ymin+1 TO Ymax
1880 MOVE 0,I
1890 LORG 8
1900 LABEL I
1910 NEXT I
1920 FOR I=INT(Xmin/5) TO INT(Xmax/5)
1930 MOVE 5*I,Ymin-.02*(Ymax-Ymin)
1940 LORG 6
1950 LABEL 5*I
1960 NEXT I
1970 PENUM
1980 FOR I=1 TO Dewlimit
1990 IF (Ramat(I)=0) OR (Ramat(I)<Rmax) THEN GOTO 2050
2000 MOVE Dewmat(I)-Xint,LGT(Ramat(I))
2010 DRAW Dewmat(I)-Xint,LGT(Ramat(I))
2020 MOVE Dewmat(I),LGT(Ramat(I))-Yint
2030 DRAW Dewmat(I),LGT(Ramat(I))+Yint
2040 PENUM
2050 NEXT I
2060 PENUM
2070 LOCATE 80,130,15,85
2080 SCALE 0,100,Ymin,Ymax
2090 AXES 10,1,0,Ymin
2100 MOVE 0,Ymax-.02*(Ymax-Ymin)
2110 LORG 1
2120 LABEL "LOG(RHD)"
2130 MOVE 100,Ymin-.06*(Ymax-Ymin)
2140 LORG 9
2150 LABEL "% RH"
2160 FOR I=0 TO 100 STEP 20
2170 MOVE I,Ymin-.02*(Ymax-Ymin)
2180 LORG 6
2190 LABEL I
2200 NEXT I
2210 FOR I=Ymin TO Ymax
2220 MOVE 0,I
2230 LORG 8
2240 LABEL I
2250 NEXT I
2260 FOR I=1 TO Dewlimit
2270 PRINTER IS 16
2280 PRINT PAGE,LINE(15),"ENTER RELATIVE HUMIDITY FOR DEWPOINT ":Dewmat(I)
2290 BEEP
2300 INPUT "ENTER % RH",Prh(I)
2310 NEXT I
2320 PRINTER IS 7,2,WIDTH(160)
2330 PRINT LINE(2),"DEW POINT","RELATIVE HUMIDITY"
2340 FOR I=1 TO Dewlimit
2350 PRINT Dewmat(I),Prh(I)
2360 NEXT I
2370 PENUM
2380 FOR I=1 TO Dewlimit
2390 IF (Ramat(I)=0) OR (Ramat(I)<Rmax) THEN GOTO 2450
2400 MOVE Prh(I)-1,LGT(Ramat(I))
2410 DRAW Prh(I)+1,LGT(Ramat(I))
2420 MOVE Prh(I),LCT(Ramat(I))-Yint
2430 DRAW Prh(I),LCT(Ramat(I))+Yint
2440 PENUP
2450 NEXT I
2460 PENUP
2470 GOSUB Menu
2480 RETURN
2490 Foodn:Defnum=Defnum+1
2500 FOR I=1 TO 3
2510 Values(Defnum,I)=Results(Datacr,I+1)
2520 NEXT I
2530 RETURN
2540 Lsgs=N=N+1
2550 Currentx=LCT(Values(Datacr,1))
2560 X1=X1+Currentx
2570 Y1=Y1+Values(Datacr,Ytype)
2580 X2=X2+Currentx*Currentx
2590 Z=S+Values(Datacr,Ytype)*Currentx
2600 RETURN
2601 ! SUBROUTINE TO EXTRACT RaCa FOR A GIVEN DEWPOINT
2610 Getra:Defnum=0
2620 Halpha=SGR(Ctl)
2630 CALL Cosh(Halpha,0,Sr,Cr,Ci)
2640 CALL Sinh(Halpha,0,Sr,Sl)
2650 Hfg=20*LCT((1+Cx+Halpha*Sr)/(Cr+C1+Cxt+Halpha*Sr))
2660 FOR Datacr=1 TO DataLimit
2670 IF Results(Datacr,1)=Dewont THEN GOSUB Downdrawn
2680 NEXT Datacr
2690 FOR Dewcr=1 TO Dewnum
2700 IF (Values(Datacr,2)-Goffset(-3)) AND (Values(Datacr,2)-Goffset)+Hfg+3) THEN GOTO Gainextract
2710 NEXT Dewcr
2720 ! PHASE-BASED EXTRACTION ROUTINE
2730 Phaseextract:Minimum=IE10
2740 FOR Dewcr=1 TO Dewnum
2750 IF Values(Datacr,3)(Minimum THEN GOSUB Pronfound
2760 NEXT Dewcr
2770 Race=0
2770 IF Minimum)=5 THEN RETURN
2780 IF (Values(Marker,2)-Goffset)+3) OR (Anglemat(I,-180) THEN GOTO Highend
2790 Lowend:FOR I=1 TO NoPoints
2800 IF Anglemat(I)(Minimum THEN GOTO Lowfound
2810 NEXT I
2820 Lowfound:Mark=I-(Values(Marker,3)-Anglemat(I))/(Anglemat(I_1)-Anglemat(I))
2830 Gamma=Gfs*10^((Mark_1)/Perdec)
2840 Race=1/(Gammas*Values(Marker,1)*2*PI)
2850 RETURN
2860 Highend:FOR I=NoPoints TO 1 STEP -1
2870 IF Anglemat(I)(Minimum THEN GOTO Highfound
2880 NEXT I
2890 Highfound:Mark=I+1(Values(Marker,3)-Anglemat(I))/(Anglemat(I+1)-Anglemat(I))
2900 Gamma=Gfs*10^((Mark+1)/Perdec)
2910 Race=1/(Gammas*Values(Marker,1)*2*PI)
2920 RETURN
2920 ! GAIN-BASED EXTRACTION ROUTINE
2930 Gainextract:N=Raasnum=0
2940 FOR Dewcr=1 TO Dewnum
2950 IF (Values(Datacr,2)-Goffset)+3) OR (Values(Datacr,2)-Goffset)+Hfg+3) THEN Gainkin
2960 FOR I=NoPoints TO 1 STEP -1
2970 IF Gainmat(I)(Values(Datacr,2)-Goffset) THEN GOTO Gainfound
2980 NEXT I
2990 Gainfound:Mark=I+1(Values(Dewcr,2)-Gainmat(I))/(Gainmat(I+1)-Gainmat(I))
3000 Gamma=Gfs*10^((Mark+1)/Perdec)
3010 N=N+(Gainmat(I+1)-Gainmat(I))
3020 Racasum=Racasum+LGT(1/(Comma*Values(Dewctr,1)))*(Gainmat(I+1)-Gainmat(I))
3030 Gainskip:NEXT Dewctr
3040 Racasum=Racasum/N
3050 Racal=10^Racasum/(2*PI)
3060 RETURN
3070 Pminfound=Marker=Dewctr
3080 Pminimun=Values(Dewctr,3)
3090 RETURN
3091 ! SUBROUTINE TO PLOT DATA ON GAIN AND PHASE VS. FREQUENCY AXES
3100 Goplotplot:PIEUP
3110 Fint=.01*(LGT(Fmax)-LGT(Fmin))
3120 Gint=.01*(Gmax-Gmin)*2/3
3121 Pint=.01*(Pmax-Pmin)*2/3
3140 FOR Datactr=1 TO Datalimit
3150 IF Results(Datactr,1)=Pmin THEN GOTO Sko
3160 Gain=Results(Datactr,3)-Goffset
3170 Phase=Results(Datactr,4)
3180 Freq=Results(Datactr,2)
3190 LOCATE 20,70,15,90
3200 SCALE LGT(Fmin),LGT(Fmax),Gmin,Gmax
3210 CALL Dataplot(LGT(Freq),Gain,Fint,Gint,T$)
3220 LOCATE 80,130,15,90
3230 SCALE LGT(Fmin),LGT(Fmax),Pmin,Pmax
3240 CALL Dataplot(LGT(Freq),Phase,Fint,Pint,T$)
3250 Sko:NEXT Datactr
3260 RETURN
3261 ! SUBROUTINE TO ENTER MODEL PARAMETER VALUES, AS A PREFACE TO PLOTTING GAIN/PHASE CURVE
3270 Eandm=Mfkg=1E10
3280 INPUT "ENTER MEASURED GAIN AT HIGH FREQUENCIES (DB) (HIT CONTINUE TO EXIT)".Mfkg
3290 IF Mfkg=1E10 THEN GOTO Menu
3300 INPUT "ENTER CT/CA RATIO",Cta
3310 INPUT "ENTER CL/CT RATIO",Clt
3320 INPUT "ENTER GT/GA RATIO",Gta
3330 INPUT "ENTER CX/GA RATIO",Gca
3340 INPUT "ENTER GL/CA RATIO",Gla
3360 Cxt=FMCGetxt(Mfkg,Cit,Cta)
3370 PRINT 16
3380 PRINT LIN(2)
3390 PRINT USING "#.##":Cxt
3400 PRINT USING "12A,12A,12A,12A,12A,12A,12A,12A,A":"CL/CT","CT/CA","CX/CT","CT/GA","CX/GA","CL/CA"
3410 PRINT USING "9D.2D,9D.2D,4X,D.DDE,4X,D.DDE,4X,D.DDE,4X,D.DDE":Clt,Cta,Cit,Gta,Gca,Gla
3420 GOTO Gvsomplot
3421 ! SUBROUTINE TO INITIALIZE GAIN VS. PHASE PLOT
3430 Gvsomplot:PLOTTER IS 7,5,9B72A'
3440 CSIZE 2.5,8
3450 LOCATE 20,103,15,85
3460 SCALE Gmin,Gmax,Pmin,Pmax
3470 AXES 5,30,8,Pmax
3480 AXES 5,30,Gmin,Pmin
3490 LORC 4
3500 FOR I=INT(Gmin/10) TO 0
3510 MOVE 18*I,Pmax+.01*(Pmax-Pmin)
3520 LABEL 10*I
3530 NEXT I
3540 LORC 7
3550 MOVE -I,Pmax+.04*(Pmax-Pmin)
3560 LABEL "GAIN (DB)"
3570 LORC 8
3580 FOR I=INT(Pmin/30) TO INT(Pmax/30)
3590 MOVE Gmin,30*I
3600 LABEL 30*I
3610 NEXT I

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MOVE .97*Gain,Pmin-.02*(Pmax-Pmin)
3630 LORG 3
3640 LABEL "PHASE"
3650 GOTO Gspddata1lot
3651 ! SUBROUTINE TO PLOT MODEL CURVE IN GAIN/PHASE SPACE
3660 GspmModelot:PENUP
3670 LOCATE 20,130,15,85
3680 SCALE Gain,Gmax,Pmin,Pmax
3690 GOSUB Tablegen
3700 FOR I=1 TO Npoints
3710 PLOT Gainmat(I),Anglemat(I)
3720 NEXT I
3730 PENUP
3740 GOTO Cond1m
3741 ! SUBROUTINE TO PLOT DATA IN GAIN/PHASE SPACE
3750 Gspddata1lot:PENUP
3760 LOCATE 20,130,15,85
3770 SCALE Gain,Gmax,Pmin,Pmax
3780 Print=.01*(Pmax-Pmin)
3790 Gint=.01*(Gain-Gain)*7/11
3810 GOSUB Getdwlimit
3820 "PRINT PAGE,"LIST OF DEW POINT VALUES CONTAINED IN THIS FILE;"
3830 PRINT LIN(1),"I.D.","DEW POINT"
3840 FOR I=1 TO Dewlimit
3850 PRINT I,Dewmat(I)
3860 NEXT I
3870 Gsppl00:Dewctr=1E10
3880 INPUT "ENTER I.D. OF DATA TO BE PLOTTED, 0 FOR ALL, OR CONTINUE TO EXIT",Dewctr
3890 IF Dewctr=1E10 THEN GOTO Menu
3900 INPUT "ENTER TYPE FOR DATA PLOT (+,X,O,B,D)",T$  
3910 FOR Datactr=1 TO Datalimit
3920 IF Dewctr=0 THEN GOTO 3931
3930 IF Results(Datactr,1)(Dewmat(Dewctr) THEN GOTO 3950
3940 Gain=Results(Datactr,3)-Goffset
3950 Phase=Results(Datactr,4)
3960 CALL Datalot(Gain,Phase,Gint,Print,T$)
3970 NEXT Datactr
3980 PENUP
3990 GOTO Gsppl00
3991 ! SUBROUTINE TO GENERATE AN ARRAY OF MODEL POINTS
4000 Tablegen:Mult=10^1(1/Perdec)
4010 Glast=100*Cta
4020 IF Cta(0) THEN Glast=100*MAt(i,Cta/Cta)
4030 Gfirst=.01
4040 IF Cta(0) THEN G=.01*MIN(1,Cta/Cta)
4050 CALL Modelot(Gainmat(1),Anglemat(1),Npoints,Gfirst,Glast,Mult)
4060 RETURN
4041 ! SUBROUTINE TO GENERATE LIST OF DEW POINT VALUES CONTAINED IN A DATA FILE
4050 Getdwlimit:Dewlimit=0
4060 FOR Datactr=1 TO Datalimit
4070 FOR Doctr=1 TO Dewlimit
4080 IF Results(Datactr,1)=Dewmat(Doctr) THEN Dewskip
4090 NEXT Doctr
4100 Dewlimit=Dewlimit+1
4110 Dewmat(Dewlimit)=Results(Datactr,1)
4120 Dewskio:Datactr=Datactr+1
4130 NEXT Datactr
4140 RETURN
4141 ! SUBROUTINE TO PERFORM EDITING OF A DATA FILE
4150 Editloop:PRINT PAGE,"LIST OF DEW POINT VALUES CONTAINED IN THIS FILE;",LIN(1)
4160 GOSUB Getdwlimit
4170 PRINT "I.D.","DEW POINT"
4180 FOR Dewctr=1 TO Dewlimit
4190 PRINT Dewctr,Dewmat(Dewctr)
4200 NEXT Dewctr
4210 Dewctr=1E10
4220 PRINT LIN(2),"ENTER DEM POINT I.D. TO SEE IT'S DATA LIST*
4230 PRINT LIN(1),"HIT CONTINUE TO ADD NEW DEM POINT, OR TO END EDITOR*
4240 INPUT *,Dewctr
4250 IF Dewctr=1E10 THEN GOTO Showdew
4260 Dewont=1E10
4270 INPUT "ENTER NEW DEM POINT VALUE, OR HIT CONTINUE TO END EDITING",Dewont
4280 IF Dewont=1E10 THEN GOTO Preclose
4290 GOTO Newdewpoint
4300 Showdew:PRINT PAGE,"DEM POINT: ";Dewmat(Dewctr),LIN(1)
4310 PRINT "I.D.","FREQUENCY","GAIN","PHASE"
4320 Dewnum=0
4330 FOR Datactr=1 TO Datalimit
4340 IF Results(Datactr,1)=Dewmat(Dewctr) THEN GOSUB Derefined2
4350 NEXT Datactr
4360 IF Dewnum=0 THEN GOTO Edloop
4370 PRINT LIN(1),"TO ADD DATA AT THIS DEM POINT, ENTER THE NEW FREQUENCY*
4380 PRINT "TO DELETE A ROW OF DATA, ENTER IT'S I.D. NUMBER*
4390 PRINT "TO GOTO NEW DEM POINT, HIT CONTINUE*
4400 Freq=1E10
4410 INPUT *,Freq
4420 IF Freq=1E10 THEN GOTO Edloop
4430 Gain=1E10
4440 INPUT "ENTER GAIN,PHASE (IF DELETING DATA HIT CONTINUE)",Gain,Phase
4450 IF Gain=1E10 THEN GOTO Droadata
4460 Datalimit=Datalimit+1
4470 Results(Datalimit,1)=Dewmat(Dewctr)
4480 Results(Datalimit,2)=Freq
4490 Results(Datalimit,3)=Gain
4500 Results(Datalimit,4)=Phase
4510 GOTO Showdew
4520 Newdewpoint:Dewctr=Datalimit=Datalimit+1
4530 Dewmat(Datalimit)=Dewont
4540 GOTO 4370
4550 Droadata:Datalimit=Datalimit-1
4560 FOR Datactr=Location(Freq) TO Datalimit
4570 FOR I=1 TO 4
4580 Results(Datactr,1)=Results(Datactr+1,I)
4590 NEXT I
4600 NEXT Datactr
4610 GOTO Showdew
4620 Derefined2:Dewnum=Dewnum+1
4630 Location(Datanum)=Datactr
4640 PRINT Dewnum,Results(Datactr,2),Results(Datactr,3),Results(Datactr,4)
4650 RETURN
4650 ! SUBROUTINE TO CREATE A NEW DATA FILE
4660 Newfile:Datalimit=0
4670 PRINT "ENTER GAIN OFFSET FOR THIS FILE",Offset
4680 Newdew:PRINT PAGE
4690 Dewont=1E10
4700 INPUT "ENTER DEM POINT (HIT CONTINUE TO END DATA INPUT)",Dewont
4710 IF Dewont=1E10 THEN GOTO Preclose
4720 PRINT PAGE, LIN(2), "DEM POINT IS: "; Dewont
4730 Writeplot:Freq=0
4740 INPUT "ENTER FREQUENCY,GAIN,PHASE (HIT CONTINUE TO CHANGE DEM POINT)",Freq,Gain,Phase
4750 IF Freq=0 THEN GOTO Newdew
4760 Datalimit=Datalimit+1
4770 Results(Datalimit,1)=Dewont
4780 Results(Datalimit,2)=Freq
4790 Results(Datalimit,3)=Gain
4800 Results(Datalimit,4)=Phase
4810 GOTO Writeplot

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4820 PRECLESE: GOSUB Getdewlimit
4830 Answer$="Y"
4840 INPUT "DO YOU WISH TO HAVE THIS FILE WRITTEN ONTO THE TAPE? (Y/N) ",Answer$
4850 IF Answer$="N" THEN GOTO Menu
4860 GOTO Close
4861 ! SUBROUTINE TO LOAD EXISTING DATA FILE
4870 Loaddata: INPUT "ENTER INPUT DATA FILE NAME", File$
4880 INPUT "ENTER GAIN OFFSET FOR THIS FILE", Offset
4890 Datalimit=0
4900 ASSIGN #1 TO File$
4910 ON END #1 GOTO Endload
4920 Dataloop: Datalimit=Datalimit+1
4930 FOR I=1 TO 4
4940 READ #1: Results(Datalimit,I)
4950 NEXT I
4960 GOTO Dataloop
4970 Endload: Datalimit=Datalimit-1
4980 ASSIGN #1 TO %
4990 GOSUB Getdewlimit
5000 GOSUB Menu
5010 RETURN
5020 Close: INPUT "ENTER OUTPUT FILE NAME", File$
5030 CREATE File$, #1+INT(Datalimit/16)
5040 ASSIGN #1 TO File$
5050 FOR Datactr=1 TO Datalimit
5060 FOR I=1 TO 4
5070 PRINT #1: Results(Datactr,I)
5080 NEXT I
5090 NEXT Datactr
5100 ASSIGN #1 TO %
5110 GOSUB Menu
5120 RETURN
5121 ! SUBPROGRAM TO MULTIPLY TWO COMPLEX NUMBERS
5130 SUB Multrans(A1,A2,B1,B2,C1,C2)
5140 C1=A1*B1-A2*B2
5150 C2=A2*B1+A1*B2
5160 SUBEND
5161 ! SUBPROGRAM TO DIVIDE COMPLEX NUMBERS
5170 SUB Divtrans(A1,A2,B1,B2,C1,C2)
5180 CALL Multrans(A1,A2,B1,-B2,C1,C2)
5200 C1=C1/Bsq
5210 C2=C2/Bsq
5220 SUBEND
5221 !SUBPROGRAM TO COMPUTE HYPERBOLIC SINE OF A COMPLEX NUMBER
5230 SUB Sinh(A,B,C,D)
5240 RAD
5250 Expa=EXP(A)
5260 C=COS(B)*(Expa-1/Expa)/2
5270 D=SIN(B)*(Expa+1/Expa)/2
5280 SUBEND
5281 ! SUBPROGRAM TO COMPUTE HYPERBOLIC COSINE OF A COMPLEX NUMBER
5290 SUB Cosh(A,B,C,D)
5300 RAD
5310 Expa=EXP(A)
5320 C=COS(B)*(Expa+i/Expa)/2
5330 D=SIN(B)*(Expa-i/Expa)/2
5340 SUBEND
5341 ! SUBPROGRAM TO TAKE SQUARE ROOT OF A COMPLEX NUMBER
5350 SUB Cplxsqr(A,B,C,D)
5360 Mag=SQRT(A*A+B*B)
5370 Ang=ATN(B/A)
5380 Ang=Ang/2
5390 Mag=SQRT(Mag)
5400 C=Mag*COS(Ang)
5410 D=Mag*SIN(Ang)
5420 SUBEND
5421 ! SUBPROGRAM TO COMPUTE VALUE OF MODEL TRANSFER FUNCTION
5430 SUB Model(Gain, Phase, Gamma)
5440 CD M fmin, fmax, Gain, fmax, Gain, fmax
5450 CD M CIT, CXX, CIT, CXX, C1A, G1A
5460 CALL Divtrans(Gamma, CIT, CXX, CIT, Gamma, 1, A2R, A2I)
5470 CALL Stolxar(A2R, A2I, Ar, AI)
5480 CALL Cash(Ar, AI, Cr, CI)
5490 CALL SInh(Ar, AI, Sr, SI)
5500 CALL Haltrans(Sr, SI, Ar, AI, Spr, Sop)
5510 CALL Divtrans(Gamma, CIT, Cit, Gamma, CIT, CIT, CIT, CIT, CIT, CIT, 1, Yxtx, Yxti)
5520 CALL Divtrans(Gamma, CIT, Cit, Gamma, CIT, CIT, CIT, CIT, CIT, CIT, 1, Yltx, Ylti)
5530 CALL Haltrans(Yxtx, Yltx, Spr, Sop, Spr, Spr, Spr, Spr, Spr, Spr, Doi)
5540 CALL Divtrans(i+Hpp, Hpp, Cr+i0p, Cr+i0p, Re, Im)
5550 DEG
5560 Phase=ATN(Im/Re)
5570 IF Re(0 THEN Phase=Phas-180
5590 Gain=20*LOG(SQR(Re>R+Im*Im))
5600 SUBEND
5610 ! SUBPROGRAM TO GENERATE ARRAY OF MODEL POINTS
5620 SUB Model(B, SHORT Gainmat(*), Anglemat(*), REAL Npoints, Gfirst, Clast, Mult)
5630 Lastangle=0
5640 Npoints=0
5650 Repeat:Npoints=Npoints+1
5660 CALL Model(Gain, Thisangle, Gamma)
5670 Gainmat(Npoints)=Gain
5680 Anglemat(Npoints)=Thisangle
5690 Gamma=Gain*Mult
5700 IF Gamma(Clast) THEN GOTO Repeat
5710 Lastangle=0
5720 FOR I=Npoints TO 1 STEP -1
5730 Thisangle=Anglemat(I)
5740 Back: IF ABS(Thisangle-Lastangle)180 THEN GOTO Anglecorrect
5750 Anglemat(I)=Thisangle
5760 Lastangle=Thisangle
5770 NEXT I
5780 SUBEXIT
5790 Anglecorrect: IF Thisangle)Lastangle THEN GOTO Anglefix
5800 Thisangle=Thisangle*360
5810 GOTO Back
5820 Anglefix: Thisangle=Thisangle-360
5830 GOTO Back
5840 SUBEND
5850 ! FUNCTION TO COMPUTE Cr/Ca FROM HIGH-FREQUENCY GAIN AND CI/Ct (ASSUMES Cx/Ct IS ZERO)
5850 DEF FNGetctca(Hfg, C1t)
5860 X=1
5870 Li=Xlast=X
5880 X=LOG((10)**(-1-Hfg/20)+LCT(2))-LCT(i+C1t*X))
5890 IF ABS((X-Xlact)/X)).01 THEN GOTO Li
5900 Z=EXP(1)
5910 Ctaloop2: Zlast=Z
5920 A=1+C1t*X
5930 B=2E8*(1-Hfg/20)
5940 C=1+C1t*X
5950 Z=-(1B*SG1(898-4#))/(2#A)
5960 IF ABS(Z-Zlast)/Z).01 THEN GOTO Ctaloop2
5970 RETURN LOG(Z)**2
5980 SUBPROGRAM TO COMPUTE Cx/Ct FROM HIGH-FREQUENCY GAIN, Cx/Ct, AND Ct/Ca
5990 DEF FNGetcx(Hfg, Ct, C1t)
6000 Alpha=SG1(C1t)
6010 G=10*(Hfg/20)
6020 CALL Sinh(Alpha, 0, S, Xx)
6020 CALL Cosh(Alpha,0,C,Xx)
6030 IF (G*(C+Alpha%Clr))=-1/((1-G)*Alpha%) THEN Plus
6031 I SUBPROGRAM TO PLOT DATA USING VARIOUS SYMBOLS
6040 SUB DataPlot(Short X,Y,REAL Deltax,Deltay,T$)
6050 IF T$="+" THEN Plus
6060 IF T$="x" THEN Cross
6070 IF T$="o" THEN Circle
6080 IF T$="b" THEN Box
6090 IF T$="d" THEN Del
6100 SUBEXIT
6110 Plus:MOVE X-Deltax,Y
6120 DRAW X+Deltax,Y
6130 MOVE X,Y-Deltay
6140 DRAW X,Y+Deltay
6150 PENUP
6160 SUBEXIT
6170 Cross:MOVE X-Deltax,Y-Deltay
6180 DRAW X+Deltax,Y+Deltay
6190 MOVE X-Deltax,Y+Deltay
6200 DRAW X+Deltax,Y-Deltay
6210 PENUP
6220 SUBEXIT
6230 Circle:DEC
6240 PENUP
6250 FOR Angle=0 TO 360 STEP 30
6260 PLOT X+Deltax*SIN(Angle),Y+Deltay*COS(Angle)
6270 NEXT Angle
6280 PENUP
6290 SUBEXIT
6300 Box:MOVE X+Deltax,Y+Deltay
6310 DRAW X-Deltax,Y+Deltay
6320 DRAW X-Deltax,Y-Deltay
6330 DRAW X+Deltax,Y-Deltay
6340 DRAW X+Deltax,Y+Deltay
6350 PENUP
6360 SUBEXIT
6370 Del:PENUP
6380 DEC
6390 FOR Angle=0 TO 360 STEP 120
6400 PLOT X+1.5*Deltax*SIN(Angle),Y+1.5*Deltay*COS(Angle)
6410 NEXT Angle
6420 PENUP
6430 SUBEND
APPENDIX G. DESCRIPTION OF FLIP-CHIP PACKAGE

In conjunction with the resin cure and ion sensing studies, and with the aid of D. Fulginitti of Draper Laboratory, a flip-chip packaging scheme has been designed. Packaging of devices is being currently undertaken at Draper.

The flip-chip package offers two advantages over the TO-5 header. The first is the elimination of wire bonds. The second is the conversion of the shape of the package to that of a thin sliver. Both of these make the device more suitable for insertion into a vat of hardening resin.

The heart of the package is a 20 mil thick ceramic piece of 96% Alumina, onto which a pattern of conductor has been formed by the silk screening technique (Figure G1-3). The ceramic piece has eight .025" diameter holes surrounding a single .05" hole in the center. Platinum–gold conductor is patterned around each of the outer holes and leading toward the center hole. A layer of solder is screened over each of the outer pads, and onto the tips of the wires leading toward the center hole.

Devices are prepared for the package with the addition of two steps: 1) wafers are coated with a protective overglass (probably polyimide), and patterned using the overglass mask. Only the bonding pads and the lock and key on the device remain unprotected; 2) gold balls are bonded to each of the eight bonding pads on the device using a gold ball bonder. Tails are trimmed to be as short as possible.

A die is mounted by turning it upside down, and aligning its bonding pads to the tips of the conductor surrounding the center hole on
Figure Gl) Ceramic Piece for Flip-Chip Package
Figure G2) Silk Screen Layout of Conductive Pattern for Flip-Chip Package
Figure G3) Overlay of Ceramic Piece and Conductive Pattern
the ceramic piece. While aligned, the assembly is heated until the solder melts, then cooled. If this is done properly, each bonding pad on the device will be electrically contacted to one of the big pads on the ceramic piece, via solder bonds to the gold balls. The purpose of the gold balls is twofold: 1) to provide an interface between the solder and the aluminum, since they do not adhere to one another, and 2) to lift the die slightly above the ceramic piece, thus helping to prevent short circuits that could occur if the solder flows.

Only the active surface area of the device is exposed through the center hole in the ceramic piece. If required by the device application, the gap between the die and the ceramic piece could be carefully sealed with epoxy along the inner rim of the center hole.

Contact to the outside world is to be made via thin ribbon cable. The wires are inserted from the back of the piece, through the hole in each pad. The tips of the wires are then soldered to the corresponding pads. This arrangement should guarantee sturdy electrical contacts.

If the device application demands it, the whole assembly could then be electrically insulated with epoxy, leaving exposed metal only on the active device area, and making the assembly immersible. This insulation is thus necessary for the ion-sensitive device.
APPENDIX H. PLANS FOR AN IMMERSIBLE DEVICE

In conjunction with the ion-sensing studies, a device structure was designed for the purpose of surviving the rigors of immersion over long periods of time (Figures H1-2). The process was never used due to the lack of an appropriate pH-sensitive film. However, it is described here in a series of fifteen steps:

1) A thin layer of silicon dioxide is grown in dry $O_2$ on a lightly-doped, p-type $<100>$ silicon wafer. A layer of silicon nitride is deposited on top of the oxide, by the LPCVD (Low Pressure Chemical Vapor Deposition) technique.

2) Photoresist is spun onto the wafer. A masking step takes place in which the photoresist over field areas is removed. The exposed $Si_3N_4$ is removed with a plasma etch in $CF_4$ with 5% $O_2$. The remaining exposed oxide is stripped in buffered etch.

3) An ion implantation of boron dopes the exposed silicon heavily p-type, forming the channel-stop. The remaining photoresist is stripped.

4) A thick layer of oxide is grown in steam over the field areas. The $Si_3N_4$ prevents this oxide growth over device areas.

5) The $Si_3N_4$ is removed via a plasma etch as above, and the remaining oxide over device areas is again stripped with buffered etch.

6) An oxide of approximately 1000 Angstroms is grown in dry $O_2$. The wafer receives a light implant of arsenic, to dope the silicon under the thin oxide lightly n-type. This implant creates the depletion-mode devices.

7) Photoresist is applied and patterned, leaving openings only over the source/drain areas of the chip. Oxide is etched away here with buffered etch.

8) The source/drain areas of the wafer are doped heavily n-type with a second arsenic implant.

9) Photoresist is stripped, possibly requiring an $O_2$ plasma etch,
Figure H1A) Wafer Cross Section Following Implant of Step 3

Figure H1B) Wafer Cross Section Following Step 4

Figure H1C) Wafer Cross Section Following Step 6
Figure H2A) Wafer Cross Section Following Step 8

Figure H2B) Wafer Cross Section Following Step 10

Figure H2C) Wafer Cross Section Following Step 14
due to the high implant dosage of the previous step. The thin oxide over the channel regions is stripped in buffered etch.

10) A new layer of 1000 Angstrom oxide is grown in dry \( \text{O}_2 \), followed by the deposition of a layer of \( \text{Si}_3\text{N}_4 \). This layer of silicon nitride will protect the oxide beneath from ions in the solution.

11) Photoresist is applied and patterned to have openings corresponding to contact holes. The exposed \( \text{Si}_3\text{N}_4 \) is stripped with a plasma etch as before, and the remaining exposed oxide is stripped with buffered etch.

12) Photoresist is applied to the wafer and patterned such that photoresist is removed where metal is to lie. A layer of tantalum is deposited over the wafer, either by E-beam evaporation or sputtering. The tantalum is then patterned by "lifting off" the remaining photoresist. Tantalum was chosen as the metal because it resists corrosion, it adheres to silicon dioxide, and it makes a good contact to silicon.

13) The wafer is coated with a layer of pH-sensitive glass, by whatever means proves successful.

14) Photoresist is applied and patterned to leave openings above bonding pads, etc. The exposed pH glass is then removed above the tantalum by ion milling. The photoresist is stripped.

15) Contact pads are coated with a layer of aluminum, making bonding to the device possible. This could be done by evaporating the aluminum through a shadow mask since only course alignment is required.
REFERENCES


(3) R.J. Johns, private communication.


(11) This result has been previously observed in another form: S.D. Senturia and R.J. Jachowicz, "Cooperative NBS-MIT Research on Capacitive Moisture Sensors", G8-9029, Final Grant Report, April 1979.


(13) A.G. Sabnis and J.T. Clemens, "Characterization of the Electron
