

Lecture Notes 2, 2/6/03

Figures all drawn from Electromagnetic Fields and Energy by Hermann A. Haus and James R. Melcher.

I Conditions for Electroquasistatic Fields

A. Order of Magnitude Estimate [Characteristic length  $L$ , characteristic time  $\tau$ ]

$$\nabla \cdot \vec{E} = \rho / \epsilon \Rightarrow \frac{E}{L} = \rho / \epsilon \Rightarrow E = \frac{\rho L}{\epsilon}$$

$$\nabla \times \vec{H} = \epsilon \frac{\partial \vec{E}}{\partial t} \Rightarrow \frac{H}{L} = \epsilon \frac{E}{\tau} \Rightarrow H = \frac{\epsilon E L}{\tau} = \frac{L^2 \rho}{\tau}$$

$$\nabla \times \vec{E} = -\mu \frac{\partial \vec{H}}{\partial t} \Rightarrow \frac{E_{\text{error}}}{L} = \frac{\mu H}{\tau} = \frac{\mu \rho L}{\tau^2} \Rightarrow E_{\text{error}} = \frac{\mu \rho L^3}{\tau}$$

$$\frac{E_{\text{error}}}{E} = \frac{\mu \rho L^3}{\tau \rho L} = \frac{\mu \epsilon L^2}{\tau^2} = \frac{L^2}{(c\tau)^2}$$

$$\frac{E_{\text{error}}}{E} \ll 1 \Rightarrow \frac{L}{c\tau} \ll 1$$

B. Estimate of Error Introduced by EQS approximation

Figure 3.3.1 Prototype systems involving one typical length. (a) EQS system in which source of EMF drives a pair of perfectly conducting spheres having radius and spacing on the order of  $L$ .

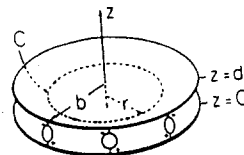
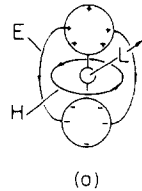


Figure 3.3.2 Plane parallel electrodes having no resistance, driven at their outer edges by a distribution of sources of EMF.

$$\vec{E} = \frac{V}{d} \vec{e}_z = E_0 \vec{e}_z$$

$$\sigma_{su} = \begin{cases} -\epsilon E_0 & z=d \\ +\epsilon E_0 & z=0 \end{cases}$$

$$K_r 2\pi b + \pi b^2 \frac{d\sigma_{su}}{dt} = 0 \Rightarrow K_r = -\frac{b}{z} \frac{d\sigma_{su}}{dt} = -\frac{b}{z} \epsilon \frac{dE_0}{dt}$$

$$\oint_C \vec{H} \cdot d\vec{s} = \int_S \frac{\partial(\epsilon \vec{E})}{\partial t} \cdot d\vec{a} \Rightarrow H_\phi 2\pi r = \pi r^2 \epsilon \frac{dE_0}{dt} \Rightarrow H_\phi = \frac{r}{z} \epsilon \frac{dE_0}{dt}$$

$$\oint_C \vec{E} \cdot d\vec{s} = - \int_S \mu \frac{\partial \vec{H}}{\partial t} \cdot d\vec{a}$$

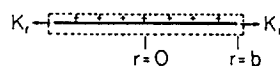


Figure 3.3.3 Parallel plates of Figure 3.3.2, showing volume containing lower plate and radial surface current density at its periphery.

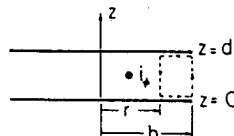


Figure 3.3.4 Cross-section of system shown in Figure 3.3.2 showing surface and contour used in evaluating correction E field.

$$[E_z(b) - E_z(r)]d = + \frac{\mu\epsilon}{2} \int_r^b r' dr' d \frac{d^2 E_0}{dt^2}$$

$$= \frac{\mu\epsilon d}{4} (b^2 - r^2) \frac{d^2 E_0}{dt^2}$$

$$E_z(r) = E_0 + \frac{\mu\epsilon}{4} \frac{d^2 E_0}{dt^2} (r^2 - b^2)$$

If  $E_0(t) = A \cos \omega t$

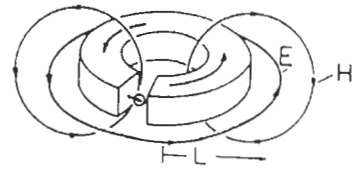
$$\left| \frac{E_{\text{error}}}{E_0} \right| = \frac{\mu\epsilon}{4\epsilon_0} \frac{d^2 E_0}{dt^2} (b^2 - r^2) = \frac{1}{4} \omega^2 \epsilon\mu (b^2 - r^2)$$

$$\left| \frac{E_{\text{error}}}{E_0} \right| \ll 1 \Rightarrow \frac{\omega^2 \epsilon\mu b^2}{4} \ll 1$$

$$f\lambda = c = \frac{1}{\sqrt{\epsilon\mu}}$$

$$\frac{\omega}{2\pi} \lambda = c \Rightarrow \omega = \frac{2\pi c}{\lambda} \Rightarrow \frac{\omega^2 \epsilon\mu b^2}{4} = \frac{\pi^2 b^2}{\lambda^2} \ll 1 \Rightarrow b \ll \frac{\lambda}{\pi}$$

$f = 1 \text{ MHz}$  in free space  $\Rightarrow \lambda = \frac{3 \times 10^8}{10^6} = 300 \text{ m}$   
 If  $b \ll 100 \text{ m}$  EQS approximation is valid.



(b)

## II. Conditions for Magnetostatic Fields

$$\nabla \times \vec{H} = \vec{J} \Rightarrow \frac{H}{L} \approx J \Rightarrow H = JL$$

$$\nabla \times \vec{E} = -\mu \frac{\partial \vec{H}}{\partial t} \Rightarrow \frac{E}{L} = \frac{\mu H}{\tau} \Rightarrow E = \frac{\mu H L}{\tau} = \frac{\mu J L^2}{\tau}$$

$$\nabla \times \vec{H}_{\text{error}} = \epsilon \frac{\partial \vec{E}}{\partial t} \Rightarrow \frac{H_{\text{error}}}{L} = \frac{\epsilon E}{\tau} \Rightarrow H_{\text{error}} = \frac{\epsilon E L}{\tau} = \frac{\epsilon \mu J L^3}{\tau^2}$$

$$\frac{H_{\text{error}}}{H} = \frac{\epsilon \mu J L^3}{\tau^2 J L} = \frac{\epsilon \mu L^2}{\tau^2} \ll 1 \Rightarrow L \ll c\tau$$

(b) MQS system consisting of perfectly conducting loop driven by current source. The radius of the loop and diameter of its cross-section are on the order of  $L$ .

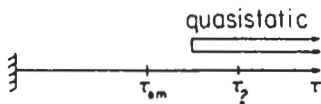


Figure 3.4.1 Range of characteristic times over which quasistatic approximation is valid. The transit time of an electromagnetic wave is  $\tau_{em}$  while  $\tau_2$  is a time characterizing the dynamics of the quasistatic system.

$$\tau_{em} = \frac{L}{c} = L\sqrt{\epsilon\mu}$$

## I. Quasistatics

Electroquasistatics (EQS)

$$\nabla \times \vec{E} = -\frac{\partial}{\partial t} (\mu_0 \vec{H}) \approx 0$$

$$\nabla \cdot (\epsilon_0 \vec{E}) = \rho$$

$$\nabla \times \vec{H} = \vec{J} + \frac{\partial}{\partial t} (\epsilon_0 \vec{E})$$

$$\nabla \cdot \vec{J} + \frac{\partial \rho}{\partial t} = 0$$

Magnetostatics (MQS)

$$\nabla \times \vec{E} = -\frac{\partial}{\partial t} (\mu_0 \vec{H})$$

$$\nabla \times \vec{H} = \vec{J} + \frac{\partial}{\partial t} (\epsilon_0 \vec{E})$$

$$\nabla \cdot (\mu_0 \vec{H}) = 0$$

$$\nabla \cdot \vec{J} = 0$$

$$\nabla \cdot (\epsilon_0 \vec{E}) = \rho$$

## II. Irrrotational EQS Electric Field

1. Conservative Electric Field

$$\oint_C \vec{E} \cdot d\vec{s} = -\frac{d}{dt} \int_S \mu_0 \vec{H} \cdot d\vec{a} \approx 0$$

$$\oint_C \vec{E} \cdot d\vec{s} = \int_{\text{I}}^b \vec{E} \cdot d\vec{s} + \int_{\text{II}}^a \vec{E} \cdot d\vec{s} = 0 \Rightarrow \int_{\text{I}}^b \vec{E} \cdot d\vec{s} = \int_{\text{II}}^b \vec{E} \cdot d\vec{s}$$

Electromotive Force (EMF)

EMF between 2 points (a, b) independent of path

$\vec{E}$  field is conservative

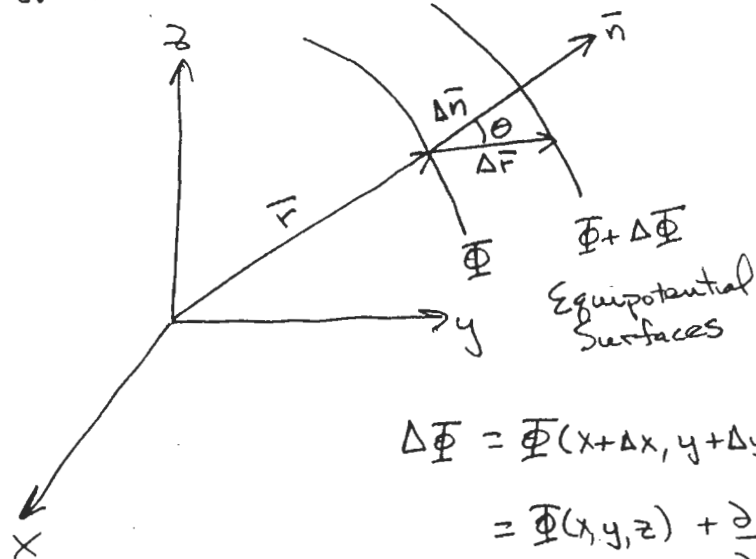
$$\Phi(\vec{r}) - \Phi(\vec{r}_{\text{ref}}) = \int_{\vec{r}_{\text{ref}}}^{\vec{r}} \vec{E} \cdot d\vec{s}$$

Scalar electric potential

$$\int_a^b \vec{E} \cdot d\vec{s} = \int_a^{\vec{r}_{\text{ref}}} \vec{E} \cdot d\vec{s} + \int_{\vec{r}_{\text{ref}}}^b \vec{E} \cdot d\vec{s} = \Phi(a) - \Phi(\vec{r}_{\text{ref}}) + \Phi(\vec{r}_{\text{ref}}) - \Phi(b) = \Phi(a) - \Phi(b)$$

(4)

## 2. The Electric Scalar Potential



$$\begin{aligned}\vec{r} &= x\vec{i}_x + y\vec{i}_y + z\vec{i}_z \\ \Delta\vec{r} &= \Delta x\vec{i}_x + \Delta y\vec{i}_y + \Delta z\vec{i}_z \\ \Delta n &= \Delta r \cos \theta\end{aligned}$$

$$\Delta\Phi = \Phi(x+\Delta x, y+\Delta y, z+\Delta z) - \Phi(x, y, z)$$

$$= \Phi(x, y, z) + \frac{\partial\Phi}{\partial x}\Delta x + \frac{\partial\Phi}{\partial y}\Delta y + \frac{\partial\Phi}{\partial z}\Delta z - \Phi(x, y, z)$$

$$= \frac{\partial\Phi}{\partial x}\Delta x + \frac{\partial\Phi}{\partial y}\Delta y + \frac{\partial\Phi}{\partial z}\Delta z$$

$$= \left[ \frac{\partial\Phi}{\partial x}\vec{i}_x + \frac{\partial\Phi}{\partial y}\vec{i}_y + \frac{\partial\Phi}{\partial z}\vec{i}_z \right] \cdot \Delta\vec{r}$$

$\underbrace{\hspace{10em}}_{\text{grad } \Phi = \nabla\Phi}$

$$\nabla = \vec{i}_x \frac{\partial}{\partial x} + \vec{i}_y \frac{\partial}{\partial y} + \vec{i}_z \frac{\partial}{\partial z}$$

$$\text{grad } \Phi = \nabla\Phi = \vec{i}_x \frac{\partial\Phi}{\partial x} + \vec{i}_y \frac{\partial\Phi}{\partial y} + \vec{i}_z \frac{\partial\Phi}{\partial z}$$

$$\int_{\vec{r}}^{\vec{r}+\Delta\vec{r}} \vec{E} \cdot d\vec{s} = \Phi(\vec{r}) - \Phi(\vec{r}+\Delta\vec{r}) = -\Delta\Phi = -\nabla\Phi \cdot \Delta\vec{r} = \vec{E} \cdot \Delta\vec{r}$$

$$\vec{E} = -\nabla\Phi$$

$$\Delta\Phi = \frac{\Delta\Phi}{\Delta n} \Delta r \cos \theta = \frac{\Delta\Phi}{\Delta n} \vec{n} \cdot \Delta\vec{r} = \nabla\Phi \cdot \Delta\vec{r}$$

$$\nabla\Phi = \frac{\Delta\Phi}{\Delta n} \vec{n} = \frac{\partial\Phi}{\partial n} \vec{n}$$

The gradient is in the direction perpendicular to the equipotential surfaces

## III. Vector Identity

$$\nabla \times \vec{E} = 0$$

$$\vec{E} = -\nabla\Phi$$

$$\nabla \times (\nabla\Phi) = 0$$

## IV. Sample Problem

$$\Phi(x, y) = \frac{V_0 xy}{a^2} \quad (\text{Equipotential lines hyperbolas: } xy = \text{constant})$$

$$\begin{aligned} \vec{E} &= -\nabla\Phi = -\left[ \frac{\partial\Phi}{\partial x} \vec{i}_x + \frac{\partial\Phi}{\partial y} \vec{i}_y \right] \\ &= -\frac{V_0}{a^2} (y \vec{i}_x + x \vec{i}_y) \end{aligned}$$

Electric Field Lines [lines tangent to electric field]

$$\frac{dy}{dx} = \frac{E_y}{E_x} = \frac{x}{y} \Rightarrow y dy = x dx$$

$$\frac{y^2}{2} = \frac{x^2}{2} + C$$

$y^2 - x^2 = y_0^2 - x_0^2$  (lines pass through point  $(x_0, y_0)$ )  
(hyperbolas orthogonal to  $xy$ )

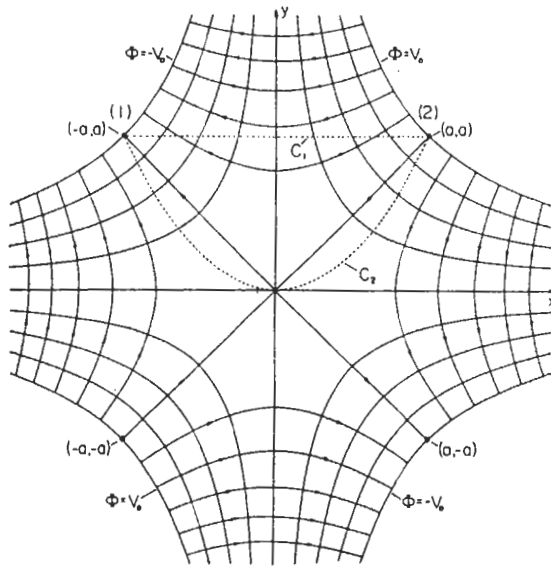


Figure 4.1.3 Cross-sectional view of surfaces of constant potential for two-dimensional potential given by (18).

## V. Poisson's Equation

$$\nabla \cdot \vec{E} = \nabla \cdot (-\nabla\Phi) = \rho/\epsilon_0 \Rightarrow \nabla^2\Phi = -\rho/\epsilon_0$$

$$\begin{aligned} \nabla^2\Phi &= \nabla \cdot (\nabla\Phi) = \left[ \vec{i}_x \frac{\partial}{\partial x} + \vec{i}_y \frac{\partial}{\partial y} + \vec{i}_z \frac{\partial}{\partial z} \right] \cdot \left[ \frac{\partial\Phi}{\partial x} \vec{i}_x + \frac{\partial\Phi}{\partial y} \vec{i}_y + \frac{\partial\Phi}{\partial z} \vec{i}_z \right] \\ &= \frac{\partial^2\Phi}{\partial x^2} + \frac{\partial^2\Phi}{\partial y^2} + \frac{\partial^2\Phi}{\partial z^2} \end{aligned}$$

(6)

## VI. Coulomb Superposition Integral

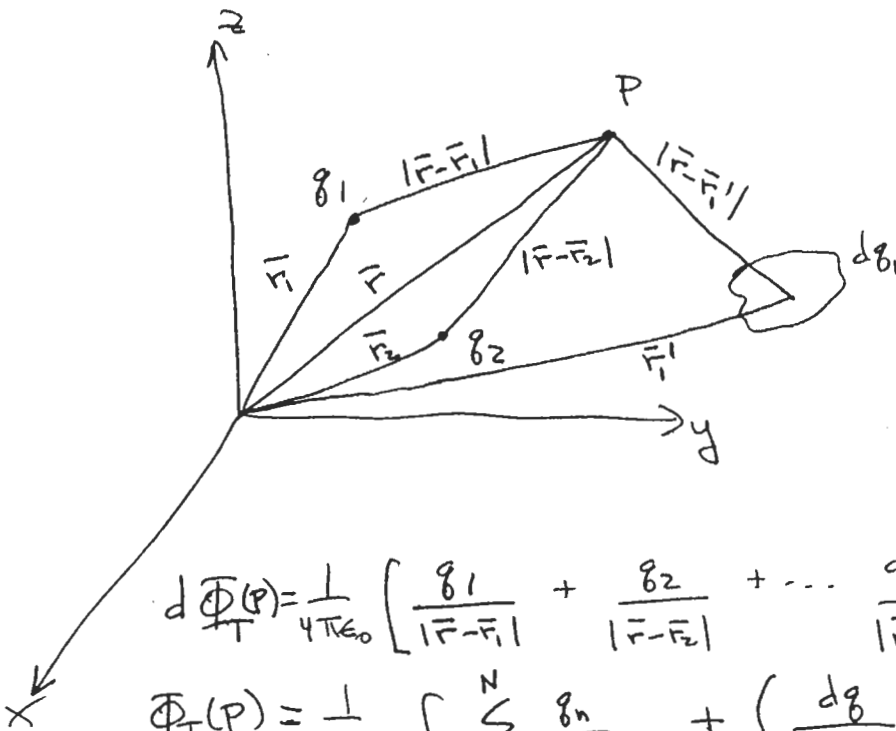
### 1. Point Charge

$$E_r = -\frac{\partial \Phi}{\partial r} = \frac{q}{4\pi\epsilon_0 r^2} \Rightarrow \Phi = \frac{q}{4\pi\epsilon_0 r} + C$$

Take reference  $\Phi(r \rightarrow \infty) = 0 \Rightarrow C = 0$

$$\Phi = \frac{q}{4\pi\epsilon_0 r}$$

### 2. Superposition of Charges



$$d\Phi_T(P) = \frac{1}{4\pi\epsilon_0} \left[ \frac{q_1}{|\vec{r} - \vec{r}_1|} + \frac{q_2}{|\vec{r} - \vec{r}_2|} + \dots + \frac{dq_1}{|\vec{r} - \vec{r}'_1|} + \frac{dq_2}{|\vec{r} - \vec{r}'_2|} + \dots \right]$$

$$\Phi_T(P) = \frac{1}{4\pi\epsilon_0} \left[ \sum_{n=1}^N \frac{q_n}{|\vec{r} - \vec{r}_n|} + \int \frac{dq}{|\vec{r} - \vec{r}'|} \right]$$

all line,  
surface, and  
volume charge

$$= \frac{1}{4\pi\epsilon_0} \left[ \sum_{n=1}^N \frac{q_n}{|\vec{r} - \vec{r}_n|} + \int_L \frac{\lambda(\vec{r}') d\ell'}{|\vec{r} - \vec{r}'|} + \int_S \frac{\sigma_s(\vec{r}') da'}{|\vec{r} - \vec{r}'|} \right]$$

$$+ \int_V \frac{\rho(\vec{r}') dv'}{|\vec{r} - \vec{r}'|} \Big]$$

Short-hand notation

$$\Phi(\vec{r}) = \int_V \frac{\rho(\vec{r}') dv'}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|}$$