

SMA6304 M2 ---Factory Planning and scheduling

Lecture Discrete Event Simulation of Manufacturing Systems

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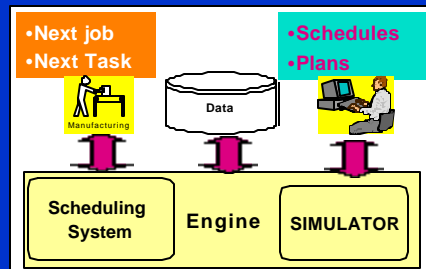
Lecture: 12

Simulation

Simulation - A Predictive Tool



Simulation - A decision support



Simulation



Lecture (12 December 2002)

- 1. Introduction
- 2. Input probability distributions
- 3. Generating Random Numbers & Random Variates
- 4. Verification and Validation
- 5. Output data analysis
- 6. Simulation life cycle

References

- Law, A. M., Kelton, W. D. Simulation Modeling and Analysis, McGraw-Hill
- Banks, J. Handbook of Simulation, EMP

1. Introduction



The Meaning of Simulation Oxford English Dictionary



● Simulation:

- The technique of imitating the behavior of some situation or system (Manufacturing, etc) by means of an analogous situation, model or apparatus, either to gain information more conveniently or.....

● Simulator:

- An apparatus or system for reproducing the behavior of some situation or system;, and gives the illusion of behaving like the real thing.

System Modeling



Model:

- ◆ A simplified or idealized description of a system, situation, or process, often in mathematical terms, devised to facilitate calculations and predictions
- ◆ a representation of an object, system or idea in a form other than that of the entity / system itself.
- ◆ an abstraction and simplification of the real world.

System Modeling -Functions of models



● As an analytical tool

- Analyze manufacturing systems
- Evaluating equipment requirements
- Design transportation facility
- Ordering policy for an inventory system

● As an aid for experimentation

● For planning and scheduling

- as an aid to thought
- as an aid to communicating
- for education and training

Classification of models



● Physical models

- analog models of continuous systems e.g. traffic flow.
- iconic models e.g. pilot training simulators.

● Analytical/Mathematical model [Most scheduling systems](#)

- Representing a system in terms of quantitative relationships.

● Static simulation models

- Time does not play a role; e.g. Monte Carlo simulation.

● Conventional simulation models

- System as it evolves over time - therefore it is dynamic
- Have I/O and internal structure; run rather than solved.
- Empirical
- Stochastic, (can be deterministic for scheduling application).

● Online simulation models

- As conventional; but near-real-time; useful for decision support

Classification of simulation models



● **Deterministic vs. Stochastic Simulation models**

- If no probabilistic components then it is *deterministic*
- If random input components used then it is *Stochastic*.

● **Continuous vs. Discrete-event Simulation models**

- Discrete-event simulation concerns modeling a system as it evolves over time by a representation where state variables change instantaneously at the event
- Continuous simulation covers modeling over time by a representation where state variables change continuously with respect to time (e.g. using differential equations)

● **Combined Discrete-Continuous Simulation**

- For systems that are neither completely discrete nor completely continuous e.g arrival of a tanker and filling it.

Simulation models



Manual model generation

Conventional Simulation Model

- For analytical work
- For decisions or confirmation of decisions
- Rapid model building
- Manually intensive
- Hard to maintain

Auto model generation

Dynamic (near-real-time) Simulation Model

- Most suitable for planning and scheduling
- Uses near-real-time data
- Fully automatic
- Integrated with info. systems
- No direct maintenance

Some basic definitions



● System state variables

- Collection of information needed to define what is happening in a system to a sufficient level at given point in time

● Events

- *Exogenous* e.g. order arrival; *Endogenous* e.g. a machine down

● Entities and attributes

- *Dynamic entity* e.g. a customer, *Static entity* e.g. a machine.
- An entity is defined by its *attributes*, e.g. quantity of a lot

● Resources

- *Resource* is a static entity that provides service to dynamic entity (a lot)

● Activity and delay

- *Activity* is a period whose duration is known; *Delay* is an indefinite duration caused by a combination of systems conditions

Four types of modeling structures



● Event-Scheduling method

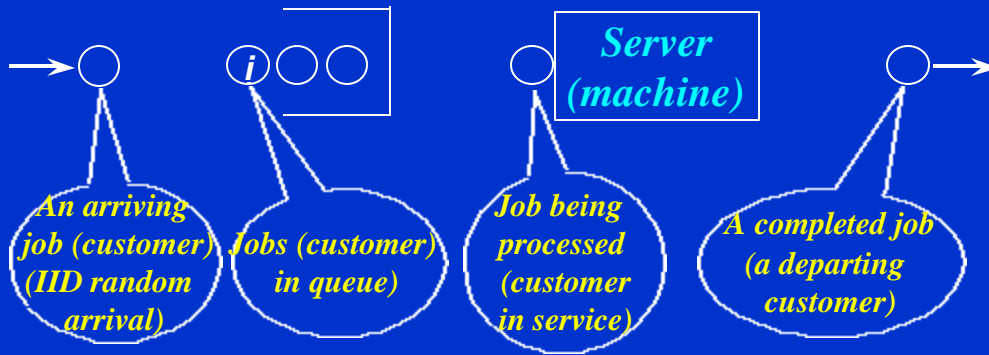
- Events are scheduled by advancing the simulation clock exactly to the time of the next event. This is one of the most accurate structures.

● Activity Scanning method

● Three-Phase method

● Process interaction method

Example: M/M/1 queue



Next-event time advance mechanism in Event-Scheduling method of an M/M/1 queue

$t_i =$ Time of arrival of i^{th} customer

$A_i = t_i - t_{i-1} =$ Inter arrival time = IID random variables

$S_i =$ Service time of i^{th} customer = IID ran. variable

$D_i =$ Observed delay of i^{th} customer in queue

$c_i = t_i + D_i + S_i =$ Completion time of i^{th} customer

$e_i =$ Time of occurrence of i^{th} event of any type

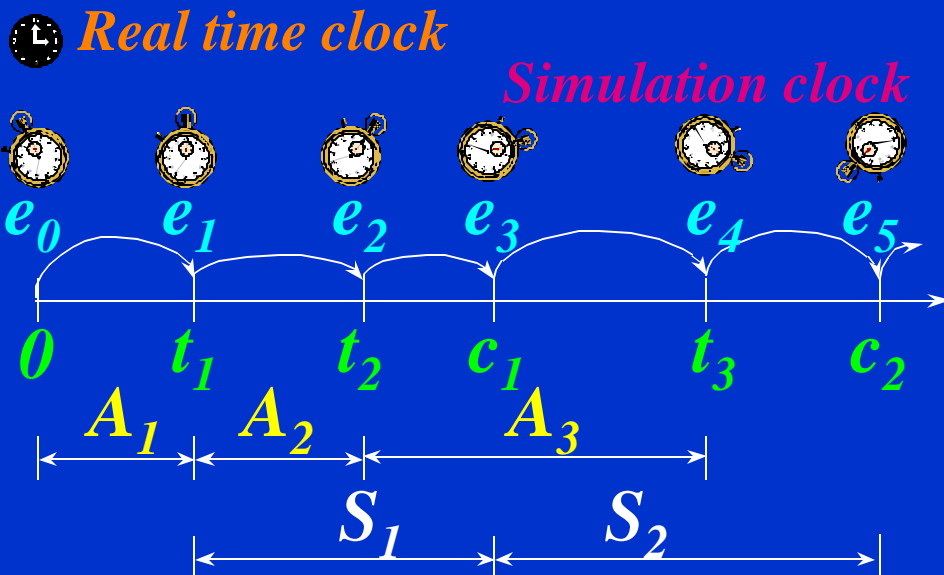
B_t (or \blacksquare) = "Busy function" defined as 1 if server is busy at time t and 0 if server is idle at time t

Next-event time advance mechanism in Event-Scheduling method of an M/M/1 queue



- Inter arrival times A_i , and service times S_i have cumulative distribution functions F_a and F_s , which are determined by collections of actual past data and fitting distributions. (2. Input probability distributions)
- Each value of t_i is computed using generated values of A_i , using random observations from a specific distribution. (3. Generating Random Numbers and Random Variates)

Next-event time advance mechanism in Event-Scheduling method of an M/M/1 queue



Next-event time advance mechanism in Event-Scheduling method of an M/M/1 queue

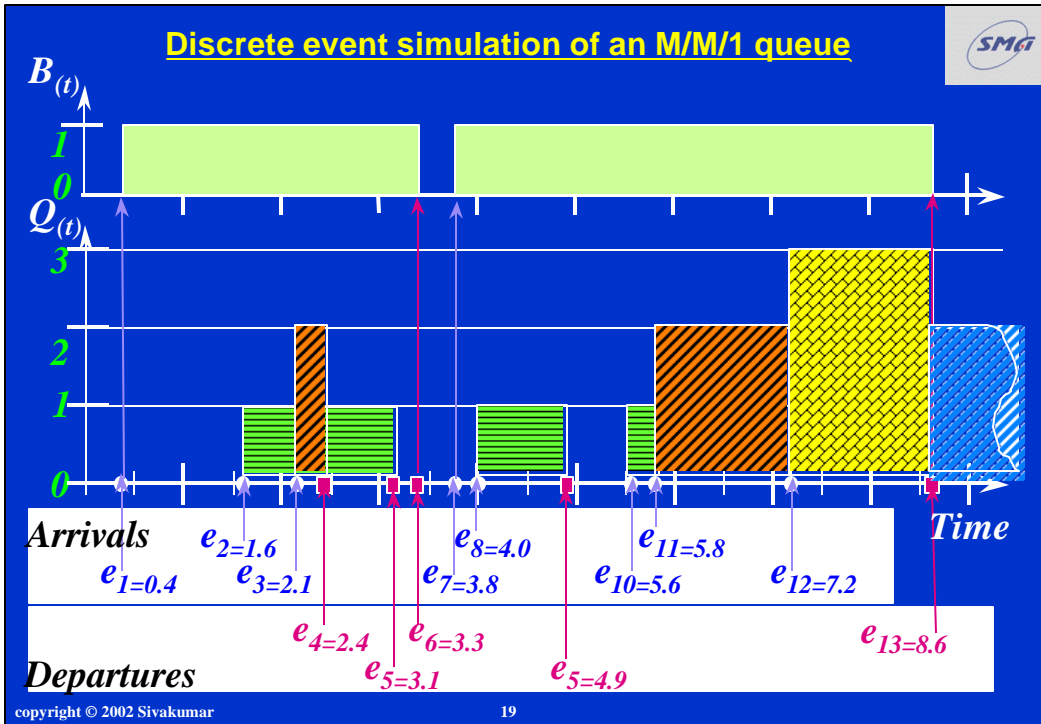


- The simulation clock is advanced from each event to the next event based on the event times of the event list.
- A machine starting to process is an activity and the end time is known from S_i & F_a
- When a customer (or a job) arrives and if the server is busy then it joins a queue and the end time is unknown. This is a delay

Discrete event simulation of an M/M/1 queue



| Job | Arrival | Service | Start | End | Delay |
|-----|---------|---------|-------|-----|-------|
| | t_i | S_i | c_i | | D_i |
| J1 | 0.4 | 2.0 | 0.4 | 2.4 | 0 |
| J2 | 1.6 | 0.7 | 2.4 | 3.1 | 0.8 |
| J3 | 2.1 | 0.2 | 3.1 | 3.3 | 1.0 |
| J4 | 3.8 | 1.1 | 3.8 | 4.9 | 0 |
| J5 | 4.0 | 3.7 | 4.9 | 8.6 | 0.9 |
| J6 | 5.6 | 2.8 | | | |
| J7 | 5.8 | 1.6 | | | |
| J8 | 7.2 | 3.1 | | | |



Expected average delay in M/M/1 queue

From a single run of simulation of n jobs (customers), a point estimate for $\overline{D}(n)$, expected average delay in queue of the n jobs (customers) is

$$\overline{D}(n) = \frac{\sum_{i=1}^n D_i}{n}$$

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Expected average number of jobs in M/M/1 queue



T_i = Total time during the simulation in which the queue of customers(jobs) is observed as length i

T_n = Time to observe n delays in queue

$Q_{(t)}$ = Number of customers in queue at time t

q_n = Average number of customers(jobs) in queue during n observations

$$q(n) = \frac{\sum_{i=1}^{\infty} iT_i}{T_n}$$

Expected average number of jobs in M/M/1 queue



Since

$$\sum_{i=1}^{\infty} iT_i = \int_0^{T_{(n)}} Q(t) dt$$

We get

$$q(n) = \frac{\int_0^{T_{(n)}} Q(t) dt}{T_n}$$

Expected utilization of the machine in M/M/1 system



u_n = Expected proportion of time the server (machine) is busy during n observations

Since B_t is always either 0 or 1

$$u(n) = \frac{\int_0^{T(n)} B(t) dt}{T n}$$

Simple output from discrete event simulation



Let take a case of the earlier table of arrival and service with the first 5 observation of completion ($T_n = 8.6$)

$$\sum_{i=1}^{\infty} iT_i = (0 \times 3.2) + (1 \times 2.3) + (2 \times 1.7) + (3 \times 1.4) = 9.9$$

$T_i = 0$ for $i \geq 4$

and therefore $Q(n) = 9.9/8.6 = 1.15$

and

$$u(n) = [(3.3 - 0.4) + (8.6 - 3.8)]/8.6 = 0.90$$

Discrete event simulation

- These values are simple illustrations of statistics of discrete event simulation
 - Discrete-time statistics (e.g. average delay in queue) or
 - Continuous-time statistics (e.g. proportion of server busy time)
- A very large number of other useful statistics could be obtained from each simulation run.
- In addition very complex manufacturing systems could be modeled using this simple approach.

Discrete event simulation

- However model **MUST** be verified and validated to add credibility to the results. (4. *verification and validation*)
- Experimental runs should then be carried out using the validated model.

Discrete event simulation

- However values of each experimental run are based on “sample” size of 1 (one complete simulation run) and sample size of 1 is not statistically useful.
- Multiple replications and confidence interval are therefore essential elements of simulation output data analysis. (5. *Output data analysis*)

Probability & statistics and Simulation

- Probability and statistics are integral part of simulation study
- Need to understand how to model a probabilistic system
- Validate a simulation model
- Input probability distributions,
- Generate / use random samples from these distributions
- Perform statistical analysis of output data
- Design the simulation experiments.

2. Input probability distributions

Randomness in Manufacturing

- Process time
- MTTR
- MTTF
- Inter arrival time
- Job types or part mix
- Yield
- Rework
- Transport time
- Setup time
- and so on

Using past data



- Use past data directly in simulation. This is trace driven simulation. (*Effective for model validation*)
- Use the sample data to define an empirical distribution function and sample the required input data from this distribution.
- Use a standard technique (e.g. regression) to fit a theoretical distribution form to the sample data (e.g. exponential etc.), and sample the required data from it.

Steps in selecting Input probability distributions



- **Assess sample independence:**
 - Must confirm the observations X_1, X_2, \dots, X_n are independent using techniques such as correlation plot.
- **Hypothesizing families of distributions:**
 - Without concern for specific parameters, we must select general family e.g. normal, exponential etc.
- **Estimation of parameters:**
 - Use the past numerical data to *estimate* parameters.
- **Determine the best fit:**
 - Use a technique such as probability plot or chi-square test and identify the most suitable distribution function

● **The last three steps are integral part of available software and therefore we may not have to manually carryout these steps**

3. Generating Random Numbers and Random Variates

Status

- Early simulation studies required random number generation and generation of random variates from the distributions, often manually coded in computers.
- Most of the current simulation languages and simulators have built in features for this.

Random number generation for simulation



- Built in feature should have the following:
- Generate random numbers, uniformly distributed on $U[0,1]$ that do not exhibit any correlation with each other.
- Reproduce a given *stream* of random numbers exactly (i.e. Identical random numbers) for verification etc.
- Have ability to generate large number of streams for *multiple replications* (i.e. Different streams are separate and independent generators.)

Random variate generation for simulation



- Built in feature should also have the following:
- Generate random variates.
- This means: Produce observations for each selected variable (e.g. MTTR) from the parameters of the desired distribution function (e.g. Gamma) using the IID $U(0,1)$ random numbers with computational efficiency.

4. Verification and Validation

Definition

- **Model verification**: Building model right
 - Correct translation of conceptual simulation model in to a working program
 - Debugging
- **Model validation**: Building the right model
 - Determine if the conceptual simulation model is an accurate representation.
- **Credible Model**: Objectives fulfilled using model
 - When the model is accepted by user / client and used for the purpose it was built

Verification



- Errors arise from data, conceptual model, computer model, even computer system.
- Test sub-models first, then complete model.
- Common techniques
 - *Static*: a structured, walk-through technique.
 - *Dynamic*: run program under different conditions, then check if the output is reasonable.
 - *Trace*: Identify selected state variables (event list) after each event and check with manual calculations
 - *Animation*: observe animation

What is Validation?



- Valid if it's output behavior is sufficiently accurate to fulfill the purpose. Absolute accuracy is not essential and it is too time-consuming and expensive.
 - check underlying theories, assumptions, approximation.
 - check model structure and logic, math and relationships (by tracing entities in all sub-models and main model).
 - Model should be validated relative to the measures in the objective.

Validation



- **Data have to be validated:**
 - difficult, time-consuming and costly to obtain relevant, sufficient and most importantly consistent and accurate factory data.

A three step Validation process



- **Conventional simulation studies :**
 - Step 1. Face validation: ask people knowledgeable / experienced about the system under study
 - Step 2. Empirically Test & compare with other models, e.g. analytical models
 - Step 3. Detail output data validation
 - (a) **Confidence Intervals**
 - (b) **Correlated Inspection Approach**

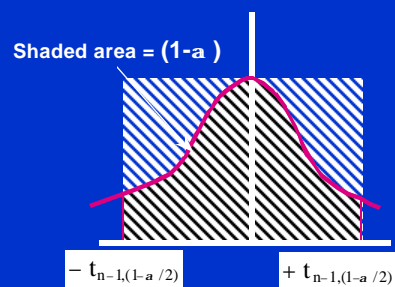
Confidence Intervals



- Let Y_1, Y_2, \dots, Y_n be IID random variables with mean \bar{y}_n and sample variance $S^2_{(n)}$
- It can be shown using central limit theorem that, when n is “sufficiently large”, that an approximate $100(1-\alpha)$ percent confidence interval (assuming a t distribution with $(n-1)$ degrees of freedom) is given by the following:

$$l(n, \alpha) = \bar{Y}_{(n)} - t_{n-1, (1-\alpha/2)} \sqrt{\frac{S^2(n)}{n}}$$

$$u(n, \alpha) = \bar{Y}_{(n)} + t_{n-1, (1-\alpha/2)} \sqrt{\frac{S^2(n)}{n}}$$



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43

Validation: Confidence Intervals approach



- Assume we collect m independent sets of data from the system and n independent sets of data from the model.
- Let X_j be the average of the observations of a desired variable (e.g. throughput) in the j^{th} set of system data and U_j be the average of the observations in the j^{th} set of model data of the same variable.

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44

Validation: Confidence Intervals approach



- If we assume the m sets of system data are homogeneous, then X_j 's are IID random variables with the mean μ_x .
- If the n sets of simulation model data were generated using independent replications then U_j 's are IID random variables with the mean μ_y .

Validation: Confidence Intervals approach



- One of the methods to compare the model with the system is by constructing a confidence interval for x where $\mathbf{x} = \mathbf{m}_x - \mathbf{m}_y$
- Let $l(n, \mathbf{a})$ and $u(n, \mathbf{a})$ correspond to lower & upper confidence interval end points of \mathbf{x} .
- If $0 \notin [l(\mathbf{a}), u(\mathbf{a})]$, then the observed difference between \mathbf{m}_x and \mathbf{m}_y is said to be statistically significant at level \mathbf{a}

Validation: Confidence Intervals approach

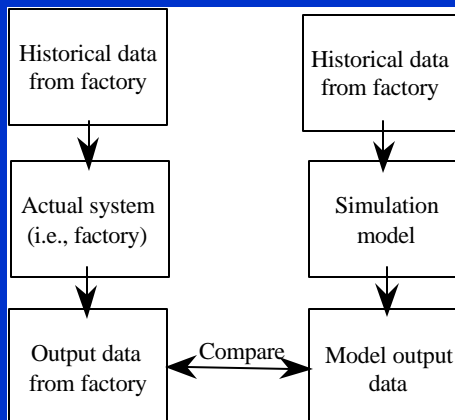


- However, even though the difference is statistically significant, the model may still be a valid representation of the system to fulfill the objectives of the simulation.
- On the other hand if $0 \in [l(\mathbf{a}), u(\mathbf{a})]$, then the observed difference between \mathbf{m}_x and \mathbf{m}_y is said to be statistically not significant at level \mathbf{a} and may be explained by sampling fluctuations.

Validation : Correlated Inspection Approach



- Statistics of the desired variable from the systems is compared with corresponding statistics of the model.



Validation : Correlated Inspection Approach



- Suppose we want to validate the cycle time (e.g. makespan / duration from arrival to completion).
- We make a number of observation of the factory cycle time X_j 's and for example, the inter arrival time of the jobs.
- We then use the observed values of the inter arrival time of the factory to drive the simulation model and obtain cycle time values U_j 's from it.

Validation : Correlated Inspection Approach



- We compare j^{th} set of system data X_j and simulation model data U_j where $X_j - Y_j$ estimate for $m_x - m_y$
- We can look at the sample mean and sample variance of all $X_j - Y_j$ to $m_x - m_y$ judgment on the validity of the simulation model to fulfill the objectives.

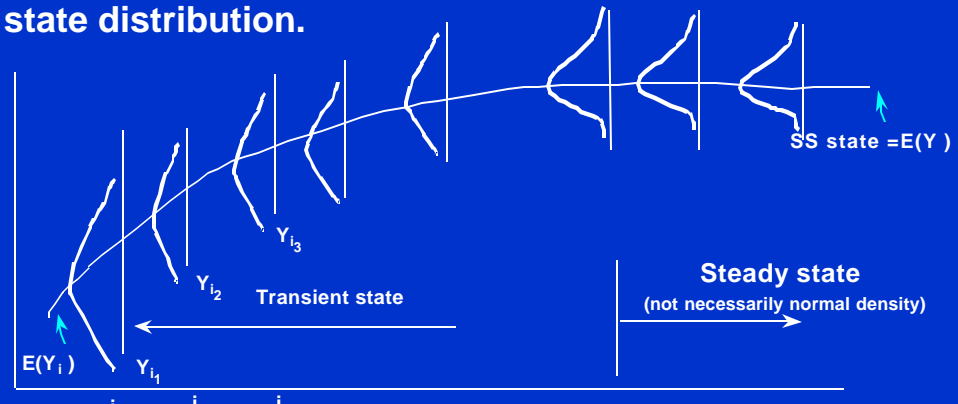
5. Output data analysis

Transient and steady state behavior

- Experimental observations for output analysis should be made at steady state, i.e. after a transient state of the stochastic simulation run.
- Consider the output of the random variable U_i for $i=1,2,\dots,m$.
- Let $F_i(y|I) = P(Y_i \leq y|I)$ where y is a real number and I represents *initial* condition.
- The *transient distribution* $F_i(y|I)$ discrete time i is different for each i and each set of I .

Transient and steady state behavior

- If $F_{i_1}(y|I) \rightarrow F(y)$ as $i \rightarrow \infty$ for all y and any initial condition I then $F(y)$ is said to be the steady state distribution.



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Random nature of simulation output

- Let $U_1, U_2, \dots, U_i \dots U_m$, be output of stochastic process from a single simulation run (e.g. U_i is throughput at i^{th} hour, m = number of observations).
- U_i 's are random variables & generally not IID.
- If we carry out n independent replication (using n different streams) then we realize a set of random observations as shown below:

| | | | | | | | | | | | | |
|----------|---|---|---|---|---|----------|---|---|---|---|---|----------|
| y_{11} | , | . | . | . | , | y_{1i} | , | . | . | . | , | y_{1m} |
| y_{21} | , | . | . | . | , | y_{2i} | , | . | . | . | , | y_{2m} |
| . | . | . | . | . | . | . | . | . | . | . | . | . |
| y_{n1} | , | . | . | . | , | y_{ni} | , | . | . | . | , | y_{nm} |

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Output analysis

- Observations from a single replication (row) are not IID.
- However $y_{1i}, y_{2i}, \dots, y_{ni}$ from n replications (column) are IID observations of the random variable, U_i for $i=1, 2, \dots, m$.
- This is the basis of statistical analysis of the observations of y_{ji} . For example an unbiased estimate of

$$E(Y_i)$$

$$\bar{y}_i^{(n)} = \frac{\sum_{j=1}^n y_{ji}}{n}$$

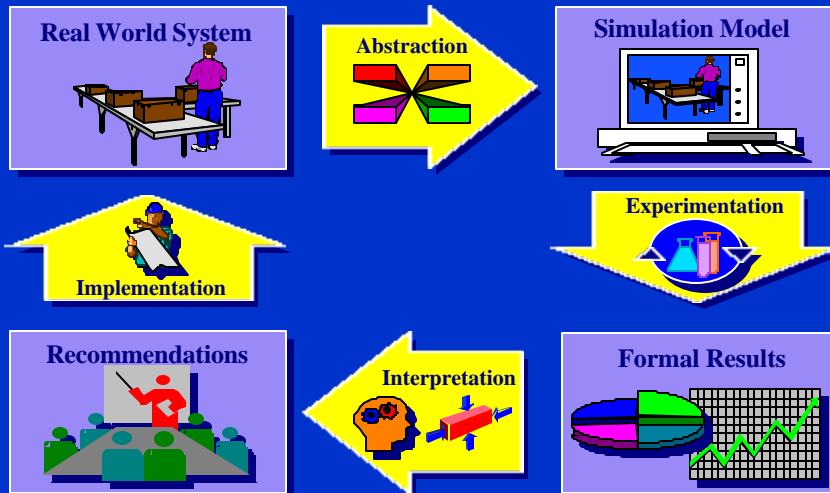
Confidence Interval of Output analysis - an example

- Comparing two systems on a given measure of performance is done by forming a confidence interval for the difference in two expected values of for example $E(Y_1)$ and check if $0 \in$
- If the number of observations $n_1=n_2=n$ then we pair with Y_{1j} and Y_{2j} $Z_j = Y_{1j} - Y_{2j}$ and Z_j 's are the IID random variables. Approximate percent confidence interval $100(1-\alpha)$

$$\bar{Z}_{(n)} \pm t_{n-1, (1-\alpha/2)} \sqrt{\frac{S^2(n)}{n}}$$

Paired-t confidence interval

Steps in conventional simulation



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57

Credibility Assessment in Simulation projects



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58

Credibility Assessment Stages



Quality Control of processes between phases

- **Credibility assessment will always be subjective because**
 - modeling is an art
 - credibility assessment is situation-dependent
- **Accuracy of assessment always relative to the objective of simulation, never absolute.**

Credibility Assessment Stages



Quality Control of processes between phases

- **Peer Assessment**
 - Panel of persons who are
 - experts of the system under study
 - expert modelers
 - simulation analysts
 - familiar with simulation projects

Credibility Assessment Stages



Quality Control of processes between phases

- **Verify formulated problem**
 - to make sure it faithfully reflects the real problem.
- **Feasibility of simulation**
 - is data available? Easy or costly to get?
 - are resources for simulation available?
 - cost-benefit: any time limit imposed to complete study?
- **The real system**
 - are system's boundaries well-defined?
 - have objectives of simulation changed with time?
 - counter-intuitive behavior accounted for?
 - any drift to low performance?

Credibility Assessment Stages



Quality Control of processes between phases

- **Qualifying the conceptual model**
 - are assumptions explicitly defined, appropriate?
- **Verifying the communicative model**
 - use techniques such as walk-through, structural analysis, data-flow analysis (Whitner & Balci, 1986).
- **Verifying the programmed model**
 - use standard software verification techniques.

Credibility Assessment Stages



Quality Control of processes between phases

- **Verify experimental design**
 - is random number generator accurate and true?
 - are statistical techniques for design and analysis of experiments appropriate?
 - initial transients accounted for?
 - have you ensured identical experimental conditions for each alternative operating policy?
- **Data validation** (of model parameters and input data)
 - are they appropriate? current? unbiased? inter-dependent? complete? accurate?
 - are instruments for data measurement and collection accurate?

Credibility Assessment Stages



Quality Control of processes between phases

- **Validating the Experimental Model**
 - always compare the behavior of the model and real system under *identical input conditions*.
 - subjective and statistical validation techniques applicable only when data are completely *observable*.
- **Interpretation of simulation results**
 - interpret numerical results based on the objective of the study. Judgment involved.
- **Documentation**
 - Embed documentation into model development cycle.

Credibility Assessment Stages



Quality Control of processes between phases

● Presentation

–communicating simulation results

- ◆ translate the jargon so non-simulation people & decision-makers can understand

–presentation techniques

- ◆ integrate simulation results with a DSS, so decision-maker can appreciate the significance of the simulation results.

Wrap-up



- We have looked at the simulation of a M/M/1 queue
- We have discussed Input probability distributions
- We talked about the Random Numbers and Random Variates
- We discussed Validation techniques
- We outlined output data analysis and confidence intervals
- Life cycle and Credibility Assessment of simulation models