6.003 Homework 4

Please do the following problems by **Wednesday**, **March 3**, **2010**. You need not submit your answers: they will NOT be graded. Solutions will be posted.

Problems

1. Z transforms

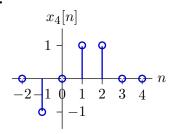
Determine the Z transform (including the region of convergence) for each of the following signals:

a.
$$x_1[n] = \left(\frac{1}{2}\right)^n u[n-3]$$

b.
$$x_2[n] = (1+n) \left(\frac{1}{3}\right)^n u[n]$$

c.
$$x_3[n] = n \left(\frac{1}{2}\right)^{|n|}$$

d.



2. Inverse Z transforms

Determine and sketch all possible signals with Z transforms of the following forms. For each signal, indicate the associated region of convergence.

a.
$$X_1(z) = \frac{1}{z-1}$$

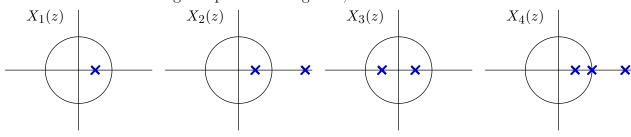
b.
$$X_2(z) = \frac{1}{z(z-1)^2}$$

c.
$$X_3(z) = \frac{1}{z^2 + z + 1}$$

d.
$$X_4(z) = \left(\frac{1-z^2}{z}\right)^2$$

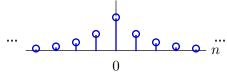
3. More symmetries

Consider the following DT pole-zero diagrams, where the circles have unit radius.



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a. Which if any of the pole-zero plots could represent the Z transform of the following DT signal?



- **b.** Which if any of the pole-zero diagrams could represent a system that is stable?
- c. Which if any of the pole-zero diagrams could represent a system that is causal?
- **d.** Which if any of the pole-zero diagrams could represent a system that is both causal and stable?

4. Z transform

Let X(z) represent the Z transform of x[n], and let $r_0 < |z| < r_1$ represent its region of convergence (ROC).

Let x[n] be represented as the sum of even and odd parts

$$x[n] = x_e[n] + x_o[n]$$

where $x_e[n] = x_e[-n]$ and $x_o[n] = -x_o[-n]$.

- **a.** Under what conditions does the Z transform of $x_e[n]$ exist?
- **b.** Assuming the conditions given in part a, find an expression for the Z transform of $x_e[n]$, including its region of convergence.

5. DT approximation of a CT system

Let H_{C1} represent a **causal** CT system that is described by

$$\dot{y}_C(t) + 3y_C(t) = x_C(t)$$

where $x_C(t)$ represents the input signal and $y_C(t)$ represents the output signal.

$$x_C(t) \longrightarrow H_{C1} \longrightarrow y_C(t)$$

a. Determine the pole(s) of H_{C1} .

Your task is to design a **causal** DT system H_{D1} to approximate the behavior of H_{C1} .

$$x_D[n] \longrightarrow H_{D1} \longrightarrow y_D[n]$$

Let $x_D[n] = x_C(nT)$ and $y_D[n] = y_C(nT)$ where T is a constant that represents the time between samples. Then approximate the derivative as

$$\frac{dy_C(t)}{dt} = \frac{y_C(t+T) - y_C(t)}{T}.$$

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- **b.** Determine an expression for the pole(s) of H_{D1} .
- **c.** Determine the range of values of T for which H_{D1} is stable.

Now consider a second-order causal CT system H_{C2} , which is described by

$$\ddot{y}_C(t) + 100y_C(t) = x_C(t)$$
.

d. Determine the pole(s) of H_{C2} .

Design a **causal** DT system H_{D2} to approximate the behavior of H_{C2} . Approximate derivatives as before:

$$\dot{y_C}(t) = \frac{dy_C(t)}{dt} = \frac{y_C(t+T) - y_C(t)}{T}$$
 and

$$\frac{d^2y_C(t)}{dt^2} = \frac{\dot{y_C}(t+T) - \dot{y_C}(t)}{T}.$$

- **e.** Determine an expression for the pole(s) of H_{D2} .
- **f.** Determine the range of values of T for which H_{D2} stable.

6. Avoiding excitation

Consider the system described by the following difference equation:

$$y[n] = x[n] + \frac{5}{2}y[n-1] - y[n-2]$$
.

Find an input x[n] such that the output y[n] is proportional to $\left(\frac{1}{2}\right)^n$ for large values of n. Try to minimize the number of non-zero samples in x[n].

7. Periodic system

Consider this variant of the Fibonacci system:

$$y[n] = y[n-1] - y[n-2] + x[n]$$

where x[n] represents the input and y[n] represents the output.

- a. Compute the unit-sample response and show that it is periodic. What is the period?
- **b.** Determine the poles of the system.
- **c.** Decompose the system functional into partial fractions, and use the result to determine a closed-form expression for h[n], the unit-sample response.

8. Growth

Here is a system of difference equations:

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$$a[n] = \frac{1}{3}a[n-1] + x[n],$$

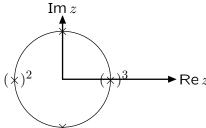
$$\frac{3}{2}c[n] = c[n-1] + x[n],$$

$$y[n] = 2a[n] + 3c[n]$$

in which x[n] represents the input and y[n] represents the output. Estimate, to within 0.01%, the ratio h[2009]/h[2007] where h[n] represents the unit-sample response of the system.

9. Lots of poles

All of the poles of a system fall on the unit circle, as shown in the following plot, where the '2' and '3' means that the adjacent pole, marked with parentheses, is a repeated pole of order 2 or 3 respectively.



Which of the following choices represents the order of growth of this system's unit-sample response for large n? Give the letter of your choice plus the information requested.

- **a.** y[n] is periodic. If you choose this option, determine the period.
- **b.** $y[n] \sim An^k$ (where A is a constant). If you choose this option, determine k.
- **c.** $y[n] \sim Az^n$ (where A is a constant). If you choose this option, determine z.
- **d.** None of the above. If you choose this option, determine a closed-form asymptotic expression for y[n].

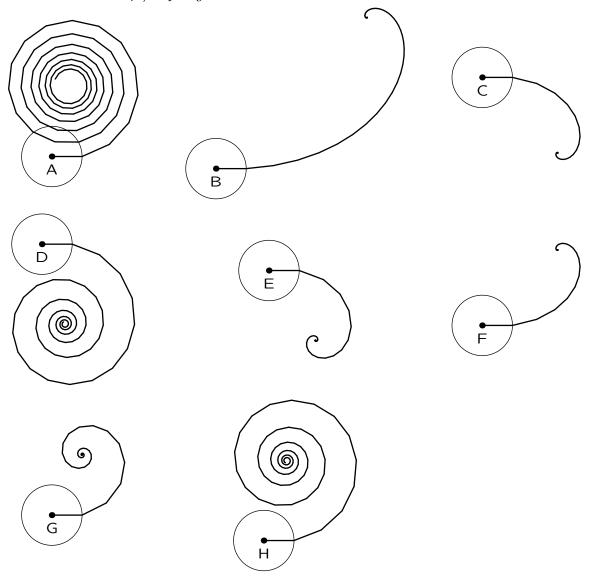
10. Complex Sum

Each diagram below shows the unit circle in the complex plane, with the origin labeled with a dot.

Each diagram illustrates the sum

$$S = \sum_{n=0}^{100} \alpha^n.$$

Determine the diagram for which $\alpha = 0.8 + 0.2j$.



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