Audio-band coating thermal noise measurement for Advanced LIGO with a multimode optical resonator

The MIT Faculty has made this article openly available. Please share how this access benefits you. Your story matters.

<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>As Published</td>
<td><a href="http://dx.doi.org/10.1103/PhysRevD.95.022001">http://dx.doi.org/10.1103/PhysRevD.95.022001</a></td>
</tr>
<tr>
<td>Publisher</td>
<td>American Physical Society</td>
</tr>
<tr>
<td>Version</td>
<td>Final published version</td>
</tr>
<tr>
<td>Accessed</td>
<td>Wed Apr 03 05:25:19 EDT 2019</td>
</tr>
<tr>
<td>Citable Link</td>
<td><a href="http://hdl.handle.net/1721.1/106973">http://hdl.handle.net/1721.1/106973</a></td>
</tr>
<tr>
<td>Terms of Use</td>
<td>Article is made available in accordance with the publisher’s policy and may be subject to US copyright law. Please refer to the publisher's site for terms of use.</td>
</tr>
<tr>
<td>Detailed Terms</td>
<td></td>
</tr>
</tbody>
</table>

The MIT Faculty has made this article openly available. Please share how this access benefits you. Your story matters.
Audio-band coating thermal noise measurement for Advanced LIGO with a multimode optical resonator

S. Gras,* H. Yu, W. Yam, D. Martynov, and M. Evans

Massachusetts Institute of Technology, 185 Albany St, NW22-295, 02139 Massachusetts, USA
(Received 21 September 2016; published 10 January 2017)

In modern high precision optical instruments, such as in gravitational wave detectors or frequency references, thermally induced fluctuations in the reflective coatings can be a limiting noise source. This noise, known as coating thermal noise, can be reduced by choosing materials with low mechanical loss. Examination of new materials becomes a necessity in order to further minimize the coating thermal noise and thus improve sensitivity of next generation instruments. We present a novel approach to directly measure coating thermal noise using a high finesse folded cavity in which multiple Hermite-Gaussian modes coresonate. This method is used to probe surface fluctuations on the order $10^{-17} \text{ m}/\sqrt{\text{Hz}}$ in the frequency range 30–400 Hz. We applied this technique to measure thermal noise and loss angle of the coating used in Advanced LIGO.

DOI: 10.1103/PhysRevD.95.022001

I. INTRODUCTION

Dielectric coatings used in high precision optical instruments consist of alternating layers of materials with low and high index of refraction. Thermal noise in these coatings arises from mechanical dissipation in the coating materials described by the fluctuation dissipation theorem. This noise limits the sensitivity of the current gravitational wave detectors [1–3], of the best frequency references [4], and of macroscopic quantum measurements [5,6].

Further improvement of these instruments calls for reduction of the coating thermal noise. The materials presently in use belong to the class of amorphous glassy oxides including SiO$_2$, Ta$_2$O$_5$, ZrO$_2$, Nb$_2$O$_5$, HfO$_2$ and Al$_2$O$_3$. The search for the new high reflectivity surfaces with low mechanical loss explores a wide range of possibilities: from new amorphous coatings produced with conventional ion beam sputtering techniques [7,8], to crystal coatings [9] and grating reflectors [10].

The loss angle of new coating materials is most frequently obtained based on the measurement of the mechanical quality factor. The techniques presented in the literature include, among others, suspended disks [11,12], clamped cantilevers [13], and the gentle nodal suspension [14]. The level of coating thermal noise is then calculated from the measured parameters, such as mechanical loss angles, Poisson ratio, and Young’s modulus. However, due to uncertainties in the multilayer parameters a robust experimental setup is necessary to directly measure coating thermal noise of a particular sample.

Such a measurement is complicated by multiple noise sources such as table vibrations, laser frequency and amplitude noise, and various readout noises. In the past, direct measurements of the coating thermal noise have been accomplished using suspended free-space Fabry-Perot cavities [15,16]. Seismic motion limits the sensitivity of these experiments below 100 Hz. On the other hand, fixed-sparer cavities with optically contacting mirrors were recently developed to observe coating thermal noise below 100 Hz [17]. However, the readout of this experiment is located in transmission of the cavities. This sets an upper limit on the reflectivity of the measured sample.

This paper describes a novel technique for the direct observation of the coating thermal noise which uses only one free-space Fabry-Perot cavity, and in which there is no upper limit on the sample reflectivity. Multiple transverse electromagnetic modes (TEM) coresonate in the cavity: 00, 02 and 20. These modes have orthogonal spacial profiles, and probe different areas of the sample coating, while other displacement noises of the cavity are common to all resonating modes. Coating thermal noise is extracted from the frequency difference between the two higher order modes.

In Sec. II we describe analytical calculations of the coating thermal noise for the fundamental and higher order modes in the linear and folded cavities. Section III describes our experimental setup. We have used it to measure the coating thermal noise of an Advanced LIGO [18] witness sample. In Sec. V we discuss the sensitivity of our experiment, measured coating thermal noise of Advanced LIGO sample and the estimation of TiO$_2$Ta$_2$O$_5$ loss angle.

II. COATING THERMAL NOISE

The reflectivity of an optical coating scales with the number of coating layers and for typical coating materials, a transmission of a few parts-per-million can be achieved with a coating roughly ten optical wavelengths thick. While
excellent optical properties are available for large (>10 cm) optics with ion beam sputtered coatings, the metal oxides are mechanically much lossier than the fused silica or silicon substrates. This loss makes coatings a dominant source of thermal noise [9].

The fluctuation-dissipation theorem [19] connects the properties of an observable, in our case the displacement of the mirror surface, with the conversion of mechanical energy to heat (i.e., dissipation in the mirror coating). The single sided power spectral density (PSD) of the observable is given by

$$S_x(f) = \frac{2k_B T W_{\text{diss}}(f)}{\pi^2 f^2 F_0^2},$$

(1)

where $T$ is the temperature, $k_B$ the Boltzmann constant, and $W_{\text{diss}}$ is the time averaged dissipated power in the coating when subjected to a sinusoidally varying force $F(t) = F_0 \cos 2\pi f t$ [20]. Though there are a variety of dissipation mechanisms in the coating which can cause the observable to fluctuate [21,22], in this paper we focus on the dominant dissipative mechanism, mechanical loss of the coating materials. Though this is a subset of all coating thermal noises, we will refer to the noise related to this dissipation mechanism as coating thermal noise (CTN).

The features of coating thermal noise can be clearly examined if we consider a simplified model of the coating as a single lossy layer of thickness $d$. The power dissipation in a single layer can be written as

$$W_{\text{diss}}(f) = \frac{2F_0^2 d(1+\sigma)(1-2\sigma)\phi}{\omega_0^2 Y} \times f,$$

(2)

where $\sigma$ and $Y$ are the Poisson ratio and Young’s modulus, $\omega_0$ is the beam waist size, and $\phi$ is the mechanical loss angle. By combining Eqs. (1) and (2) we can see a $1/f$ dependence of the PSD of CTN, assuming that $\phi$ and other mechanical properties are frequency independent [8].

While direct measurements of the coating thermal noise are associated with a particular set of parameters, i.e., beam size, beam spatial profile, and cavity geometry, it is often necessary to predict the level of the coating thermal noise for different parameters. In particular, our experiment measures the thermal noises sensed by TEM02 and TEM20 modes, shown in Fig. 1 and referred to as $N_{\text{CTN}}$. On the other hand, the lowest-order transverse mode TEM00 is commonly used in optical experiments such as gravitational wave observatories for which the coating thermal noise equals to $N_{\text{CTN}}^{00}$. In order to estimate $N_{\text{CTN}}^{00}$ from $N_{\text{CTN}}$, we employ the correction factor $C$

$$C = N_{\text{CTN}}^{00}/N_{\text{CTN}}.$$

(3)

A detailed description of our computation of this correction factor can be found in Sec. IV.

 III. EXPERIMENTAL SETUP

The key component of the measurement technique presented in this article is the folded cavity with three co-resonant optical modes: TEM02, TEM20, and TEM00. The TEM02 and TEM20 second order transverse modes, collectively referred to as “higher order modes” (HOMs), are shown in Fig. 1. The thermal noise sensed by the TEM02 mode differs from the noise sensed by the TEM20 mode since these modes sample different areas of the coating. Both resonant modes have, on the other hand, nearly identical response to the common mode noises such as laser frequency noise, cavity length noise, and mirror substrate thermal noise. The TEM00 mode, which also shares the same sensitivity to the laser frequency and cavity length, is used to suppress these common noises (see Sec. III B). The primary output of the experiment is the difference between the resonant frequencies of the TEM02 and TEM20 modes, ideally all cavity length noises cancel leaving only the desired coating thermal noise.

A. Optical cavity

The experiment uses a 3-mirror folded cavity, with the sample to be measured as the folding mirror (see Fig. 2).
FIG. 2. While the multimode approach can be applied to any optical cavity, this experiment benefits greatly from a folded geometry. Among the numerous advantages of this geometry are the use of a flat high-reflectivity sample mirror, and the ability to change the size of the beam on the sample mirror without changing the optical modes resonant in the cavity. The inset image shows the TEM20 and TEM02 modes, highlighting the fact that they overlap only in a small central area and otherwise sample distinct regions of the coating.

The cavity is located in vacuum at a pressure of 10⁻⁵ Torr and at room temperature. This folded configuration allows us to test high reflectivity coatings, and, since the sample mirror is flat, we can use the witness flats commonly included in the coating fabrication process of large optics. This configuration also allows us to change the size of the beam on the sample mirror by changing the location of the sample mirror in the cavity (without changing the cavity length), thereby enabling an exploration of the scaling of coating thermal noise with beam size.

1. Geometrical parameters

We chose a folded cavity of nominal length \( L = 9.8 \) cm and input and output couplers with radius of curvature \( R = 5.0 \) cm. These parameters imply that a waist size \( \omega_0 \), free spectral range \( f_{\text{FSR}} \), and the transverse mode spacing \( f_{\text{TMS}} \) [22] of

\[
\omega_0 = \sqrt{\frac{\lambda L}{\pi}} \approx 49 \ \mu\text{m}
\]

\[
f_{\text{FSR}} = \frac{c}{2L} \approx 1.53 \ \text{GHz}
\]

\[
f_{\text{TMS}} = \frac{c}{\pi L} \sqrt{\frac{2}{\pi}} \approx 138 \ \text{MHz},
\]

where \( c = R - L/2 \approx 1 \) mm. This value of \( f_{\text{TMS}} \) implies that the frequency difference between TEM00 and TEM02 or TEM20 is 276 MHz if the modes are in the same polarization. In practice, the horizontal and vertical radii of curvature are slightly different, and TEM02 and TEM20 modes experience different frequency shifts. The separation between these frequencies can be tuned by rotating the input coupler relative to the output coupler. The frequency difference of the two modes defines the beat note frequency used for the main readout, described in Sec. III B. We tuned the frequency separation \( \Delta f_{20/02} \) to 4.5 MHz in order to minimize laser frequency noise coupling and other technical noises (see Sec. III C).

The distance from the waist to the sample mirror is \( \approx 3 \) mm, while to the input and output couplers are \( \approx 49 \) mm from the waist. These distances determine the geometry of the resonant modes in the cavity, and thus the beam size on the sample mirror \( \omega_i = 55 \ \mu\text{m} \) and on the couplers \( \omega_c = 344 \ \mu\text{m} \). For our design with \( \omega_c/\omega_i = 7 \) the CTN from the couplers is expected to contribute only a few percent of the total power spectral density.

2. Optical parameters

The transmission of the input and output couplers was chosen to be \( T = 200 \) ppm (finesse of \( \approx 15000 \)). The total round-trip optical loss due to the coating roughness and dust particles on the mirror surface was found to be \( \delta = 20 \) ppm. Since our cavity is critically coupled, most of the input power is transmitted through the cavity.

The lower limit on the beam size and the upper limit on the resonating power is determined by the following requirements. Firstly, the intensity on the mirrors should be sustainable by the optical coating and be less than \( \sim 1 \) MW/cm². Secondly, the beam size should be much larger than the coating thickness (i.e., \( \omega_0 \gg d \sim 10\lambda \)). The thermal propagation length in the coating, roughly \( r_T \sim 40 \mu\text{m} \) at 100 Hz for coatings involving silica, is also of interest since the beams smaller than this size will experience thermo-optic noise which differs from those of gravitational wave detectors, where \( \omega_0 \gg r_T [2] \).

For input power of \( P_{\text{in}} \), the power resonating in the cavity \( P_{\text{cav}} \), and the peak intensity \( I_c \) on the sample mirror are approximately

\[
P_{\text{cav}} \approx \frac{M}{T} P_{\text{in}} = 15 \ \text{W} \left( \frac{P_{\text{in}}}{100 \ \text{mW}} \right)
\]

and

\[
I_c \approx \frac{2P_{\text{cav}}}{\pi \omega_c^2} \approx 380 \ \text{W/cm}^2 \left( \frac{P_{\text{in}}}{100 \ \text{mW}} \right) \left( \frac{50 \ \mu\text{m}}{\omega_c} \right)^2.
\]

For our mode matching to the cavity \( M = 0.03 \) and beam size \( \omega_c = 50 \ \mu\text{m} \), the input power of \( P_{\text{in}} \approx 14 \) mW for each higher order mode is clearly safe.

B. Input and output ports

The optical layout is shown in Fig. 3. The Nd:YAG laser output in the fundamental mode is split into three paths:
10% of the power is fiber coupled into the TEM00 path (beam 1) and 45% of the power goes into each of the TEM02 and TEM20 paths (beams 2a and 2b). The beams 2a and 2b are shifted in frequency relative to the beam 1 using acousto-optic modulators (AOMs). The AOMs are configured for down-conversion, double passed, and driven at $f_{TMS}$ to match the frequency of the input beam to the resonant frequencies of the cavity 02 and 20 modes. The output beams of each AOM are coupled into optical fibers, which provide convenient transport and spatial mode stability.

All three optical paths are phase modulated using broadband electro-optic modulators (EOMs) for the feedback control presented in Sec. III C. In addition to phase modulation with EOMs, the first and second beams are mixed using a 50/50 coupler. The two output beams of this coupler are used to excite the cavity 02 and 20 modes and to produce the beat note readout. All three beams are recombined on the polarizing beam splitter (PBS) before the input to the folded cavity.

The spectrum of the coating thermal noise is obtained by mixing beams 2a and 2b on a photodetector. Note that the beams 2a and 2b are in their fundamental TEM00 mode all the way to the cavity and on the beat photodetector. The conversion to TEM02 and TEM20 transverse modes takes place in the cavity. Optical power produces a beat note signal at 4.5 MHz, which is demodulated using an rf delay line, shown in Fig. 4. The delay line is composed of an rf splitter, a 225 m long cable, and an rf phase detector.

### C. Control scheme

Three analog servo loops are set to keep the TEM00, TEM02 and TEM20 spatial modes on resonance in the cavity. Additional narrow band loops suppress the laser noise.

![Diagram](image-url)
amplitude and frequency noise at 102 kHz and 204 kHz to improve sensitivity as described in Sec. V A 6.

The laser frequency is stabilized to the cavity length using TEM00 with bandwidth of 45 kHz. The control loop is shown in Fig. 5. The Pound–Drever–Hall (PDH) error signal is derived from the reflection port. The residual frequency noise below 1 kHz is less than $10^{-2}$ Hz/$\sqrt{\text{Hz}}$. Ideally, the difference between TEM02 and TEM20 resonant frequencies is weakly sensitive to the residual frequency noise; however, experimental imperfections make the TEM00 loop an important first layer of protection from these noise sources.

The frequency of rf oscillators used to shift frequencies of the beam 2a and 2b are stabilized to the 02 and 20 mode resonances using control loops shown in Fig. 6. The error signal is derived from the PDH signal in the transmission port. During initial testing we found that PDH signal derived from the reflection port has extra noise due to the fact that only 3% of the power from 2a and 2b beams is converted to TEM02 and TEM20 modes. The residual power reflects from the cavity in the fundamental mode and adds noise to the readout. On the other hand, only the TEM02 and TEM20 cavity modes reach the transmission port of the cavity, and the two modes can be separated on a quadrant photodetector. While offering lower noise, this control scheme implies that modulation sidebands should also resonate in the cavity, and this limits their frequency $\lesssim$100 kHz. This frequency limits the bandwidth of TEM02 and TEM20 modes to $\lesssim$10 kHz and adds noises from the down-conversion process described in Sec. V A 6.

IV. EXTRAPOLATION TO TEM00 BEAMS

In this section we describe our procedure to evaluate the correction factor required to estimate coating thermal noise for an arbitrary TEM00 beam spot size (see Eq. (3)). Based on the value of computed here $C$, we estimate CTN in the Advanced LIGO gravitational wave detector, see Sec. V B.

The correction factor $C$ in Eq. (3) is defined as a product of individual factors related to distinct cavity parameters,

$$C = C_{\text{fringe}} \times C_{\text{TEM}} \times C_{\text{thick}} \times C_{\text{DCF}} \times C_{\text{FTM}},$$

where $C_{\text{thick}}$ is the ideal beam size scaling factor, and $C_{\text{fold}}$ is the conversion factor from a folded to linear cavity. The other correction factors, which are all close to unity, are $C_{\text{TEM}}$ accounts for the difference in the coating thermal noise sensed by TEM02 and TEM00 beams. $C_{\text{DCF}}$ corrects for the finite coating thickness, and $C_{\text{fringe}}$ accounts for to the fringe pattern on the sample mirror in the folded cavity [24]. Finally, $C_{\text{thick}}$ and $C_{\text{FTM}}$ correct for finite coating thickness and finite mirror size [25,26].

A. Beam size

In the limit of thin coatings and large optics (relative to the beam radius), coating thermal noise PSD simply scales inversely with area of the beam, thus

$$C_{\text{thick}} = \left( \frac{\omega_S}{\omega_L} \right)^2,$$

where $\omega_L$ is the desired beam size (e.g., in LIGO) and $\omega_S$ is the beam size on the sample mirror in our experiment (see Table I).

B. Higher order modes

The correction factors $C_{\text{TEM}}$, $C_{\text{thick}}$, and $C_{\text{fringe}}$ are calculated using the stored strain energy in the coating. Since dissipation is a product of the stored energy and the tangent

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Sample mirror</th>
<th>aLIGO test mass</th>
</tr>
</thead>
<tbody>
<tr>
<td>Diameter</td>
<td>25.4 mm</td>
<td>340 mm</td>
</tr>
<tr>
<td>Thickness</td>
<td>6.35 mm</td>
<td>200 mm</td>
</tr>
<tr>
<td>Beam spot size</td>
<td>55 $\mu$m</td>
<td>62 mm</td>
</tr>
<tr>
<td>Pressure profile</td>
<td>TEM00 (02-20), TEM00</td>
<td>TEM00</td>
</tr>
<tr>
<td>$P_{\text{fringe}}$</td>
<td>$P_{\text{fringe}}$</td>
<td>$P_{\text{fringe}}$</td>
</tr>
<tr>
<td>Substrate material</td>
<td>SiO$_2$</td>
<td>SiO$_2$</td>
</tr>
<tr>
<td>Coating material</td>
<td>SiO$_2$/TiO$_2$:Ta$_2$O$_5$</td>
<td>SiO$_2$/TiO$_2$:Ta$_2$O$_5$</td>
</tr>
<tr>
<td>Coating model</td>
<td>monolayer</td>
<td>monolayer</td>
</tr>
<tr>
<td>Coating thickness, $d$</td>
<td>6.2 $\mu$m</td>
<td>6.2 $\mu$m</td>
</tr>
<tr>
<td>Analysis</td>
<td>harmonic</td>
<td>analytical</td>
</tr>
<tr>
<td>Frequency</td>
<td>100 Hz</td>
<td>dc</td>
</tr>
<tr>
<td>Element type</td>
<td>solid185</td>
<td>N/A</td>
</tr>
<tr>
<td>Output</td>
<td>$E_{\text{thick}}^\text{TEM}$, $E_{\text{thick}}^\text{DCF}$, $E_{\text{thick}}^\text{FTM}$, $E_{\text{thick}}^\text{INF}$</td>
<td>$E_{\text{thick}}^\text{INF}$</td>
</tr>
</tbody>
</table>
of the coating material loss angle, the spectral density of the coating thermal noise scales with energy [19].

The strain energy associated with the TEM00 mode, $E_{00}$, is produced by a pressure associated with the optical field intensity profile, $\Psi$, [20]

$$p_{00} = \int \Psi_{00} d\bar{r}$$

while for the experiment readout, the energy, $E_{02/20}$, results from

$$p_{02/20} = \int \Psi_{02} d\bar{r} - \int \Psi_{20} d\bar{r},$$

where the integration is carried over sample mirror surface. The negative sign between TEM02 and TEM20 intensities corresponds to their opposite sign in the readout, and results in the signal cancellation of the overlapping central part of the TEM20 and TEM02 modes, see Figs. 2 and 7.

In order to obtain strain energy corresponding to each intensity profile, we performed a harmonic finite element analysis [27] in which an oscillating pressure profile with dimensions and shape of the optical mode is applied onto the coating surface. Both the substrate and coating models were meshed with low order 3D elements and the coating was simulated as a monolayer with effective material properties [28]. An example of calculated energy profiles in the coating is shown in Fig. 7.

We define the multimode correction factor as

$$C_{\text{TEM}} = \frac{E_{\text{thick}}}{E_{\text{HOM}}} = 1.13,$$

where $E_\alpha$ is the strain energy stored in a coating corresponding to the TEM00 and TEM02-20 modes, and the superscript “thick” indicates that this energy is computed with a finite coating thickness, see Table I. The value of $C_{\text{TEM}}$ indicates that TEM02 and TEM20 sense a smaller coating thermal noise compared to the TEM00 of the same Hermite-Gaussian modal basis. Interestingly, $C_{\text{TEM}}$ goes to unity for a thin coating on a stiff substrate, and thus is entirely due to the details of the mechanical response of the mirror to the applied pressure profile.

### C. Folded cavities

The folded cavity conversion factor $C_{\text{fold}}$ is the ratio of the coating thermal noise of the folded cavity to that of a linear cavity,

$$C_{\text{fold}} = \frac{S_{\text{linear}}}{S_{\text{folded}}} = \frac{1}{4},$$

since the sample mirror is encountered twice in a cavity round-trip. This doubles the amplitude of the coating thermal noise, and thus requires a factor of 4 correction in the power spectrum density.

The fringe correction factor $C_{\text{fringe}}$ is related to the fact that folded cavities have increased thermal noise due to the fringe pattern on the folding mirror [24]. For the folding angle of 17.23° used in our test bed

$$C_{\text{fringe}} = \frac{E_{\text{thick}}}{E_{\text{fringe}}} = 0.98,$$

where $E_{\text{dc}}$ corresponds to the energy due to the uniform pressure field $p_{\text{dc}} = 1/2$ applied to the mirror, and $E_{\text{fringe}}$ is the energy corresponding to the pressure profile

$$P_{\text{fringe}} = \cos^2\left(\frac{\pi}{\Lambda} \cdot y\right)$$

with fringe separation $\Lambda = 1.79 \mu m$, see Fig. 8. Note that this is rather different than the limit of an infinitesimally thin coating in which $C_{\text{fringe}}$ approaches 2/3.

### D. Finite coating size

The thick to thin coating thickness correction factor is defined as

$$C_d = \frac{E_{00}}{E_{00}} \cdot \frac{d_{\text{thick}}}{d_{\text{thin}}} = 1.33,$$

where $d_{\text{thick}}$ corresponds to the actual coating thickness and $d_{\text{thin}} \ll d_{\text{thick}}$ is chosen to approximate a coating which is much smaller than the target beam size, assuming $d_{\text{thick}} \ll \omega_t$. The result indicates that the strain energy density in the thick coating does not fully reach the bottom layers and is thus slightly smaller than in the thinner coating.
The finite mirror size correction factor $C_{FTM}$ is not directly related to the coating thermal noise measurement, but is required to correctly compute this noise in Advanced LIGO [25,26]. The finite size correction factor for a large beam spot size is defined as

$$C_{FTM} = \frac{E_{FTM}}{E_{INF}} = 1.03,$$

where $E_{FTM}$ corresponds to the coating energy of the finite size mirror to which the coating thermal noise measurement is extrapolated and $E_{INF}$ corresponds to the energy of an infinite mirror. To calculate $C_{FTM}$ we used Eqs. 26, 27, and 28 from [26].

V. EXPERIMENTAL RESULTS

This section describes the sensitivity of the experimental setup and results for the Advanced LIGO coating sample [29]. The tested coating, produced at Laboratoire des Matériaux Avancés (LMA, Lyon, France), was ion-beam sputtered and consists of alternating layers of SiO$_2$ and Ta$_2$O$_5$ alloyed with 25% TiO$_2$. The thickness of SiO$_2$ and TiO$_2$:Ta$_2$O$_5$ layers was optimized to operate at 1064 nm and 532 nm (for more details on coating structure, see Table VII in [30]). The sample mirror has a transmissivity of $T = 5$ ppm at the measurement wavelength ($\lambda = 1064$ nm).

The measured amplitude spectral density is shown in Fig. 9 and the folded cavity parameters are shown in Table II. The slope in the frequency range 30–400 Hz is a combination of the $1/\sqrt{f}$ coating thermal noise $N_{CTN}$ and white sensing noise. This noise is a sum of multiple contributors, described in the following section.

A. Noise sources

The measured noise PSD $N_{02/20}$ contains the coating thermal noise $N_{CTN}$ as well as fundamental and technical noises. In this section we describe the major noise sources that contribute to $N_{02/20}$. The only “fundamental” limit to sensitivity is the shot noise on the readout, but technical noise sources such as photothermal noise, vibration coupling through scattered light, and rf oscillator noise are also discussed here since they have the potential to limit the sensitivity of this technique.
1. Vibration noise

Mechanical motion of the optical table couples to the readout channel via several mechanisms and limits the measurement below 20 Hz, as seen in Fig. 9.

First of all, fluctuations of the cavity total length $N_{\text{len}}$ couple to the readout channel very weakly due to the common mode rejection. Residual coupling is due to the frequency difference $\Delta f_{02/20}$ between 02 and 20 modes

$$N_{02/20} = \frac{\Delta f_{02/20}}{f_0} N_{\text{len}} = 1.4 \times 10^{-8} N_{\text{len}},$$

where $f_0 = 2.82 \times 10^{14}$ Hz is the laser frequency. The measurement of the cavity length fluctuations is limited by the laser frequency noise

$$N_{\text{len}}(f) \approx 2 \times 10^{-13} \left( \frac{10 \text{ Hz}}{f} \right) \text{ m/\/Hz}.$$

Coupling to the readout channel at 10 Hz is $\approx 3 \times 10^{-21}$ m/\/Hz, which is 4 orders of magnitude below CTN.

Vibrations of the cavity mirrors can also couple to the readout channel through backscattering. Since only the total length of the cavity is controlled, optical phase $\theta$ between the couplers and the sample mirror is uncontrolled. Fluctuations of this phase introduce extra noise to the readout channel

$$N_{02/20}(f) = (\alpha_{02} \cos \theta_{02} - \alpha_{20} \cos \theta_{20}) N_{L_1}(f),$$

where $N_{L_1}(f)$ is vibration of the distance between the input coupler and the folded mirror at frequency $f$. The back-scattering coefficient $\alpha$ is determined by the equation

$$\alpha = \sqrt{\text{BRDF} \frac{\lambda^2}{\pi \omega_0^2}} \sim 10^{-5},$$

where BRDF $\sim 10^{-6} \text{ sr}^{-1}$ is the bidirectional reflectance distribution function of the sample mirror. Backscattering coefficients $\alpha_{02}$ and $\alpha_{20}$ can be slightly different since TEM02 and TEM20 reflect from the different parts of the mirror surface. Backscattering adds noise to the readout channel on the order of $N_{02/20} \sim 10^{-5} N_{L_1}$. We estimate this as $2 \times 10^{-18}$ m/\/Hz which is still an order of magnitude below the coating thermal noise. However, backscattering also occurs outside of the cavity and adds noise to the readout channel.

Finally, mechanical motion of the input mirrors also introduces noise to the readout channel in two ways. First, longitudinal motion $L_{\text{input}}$ modulates the phase of the beams 2a and 2b according to the equation

$$N_{20/02}(f) = \frac{L_{\text{input}}}{\lambda} \frac{2\pi f}{f_0} L.$$

Our estimations show that $L_{\text{input}} \sim 10^{-9}$ m/\/Hz at 10 Hz. This noise couples to the readout channel at this frequency at the level of $N_{20/02} \sim 10^{-17}$ m/\/Hz. This number is close to the coating thermal noise at 10 Hz. Secondly, angular motion of the input mirrors modulates the power resonating in the cavity. Power fluctuations couple to the readout channel through the photothermal noise.

2. Photothermal noise

Power fluctuation in the cavity can couple to cavity length through thermal expansion of the sample mirror, resulting in a length noise known as “photothermal” or sometimes “ thermo-optic” noise (not to be confused with the coherent combination of thermoelastic and thermoreflective noise also known as “thermo-optic” noise [2]).

The expression for the thermal expansion in the case where the beam size is large compared to the thermal propagation length in the substrate, $\tau_T = \sqrt{\kappa / 2\pi C_p}$, is

$$N_{20/02}^2(f) \omega_c \gg \tau_T = \frac{P_{\text{abs}} \alpha (1 + \sigma) S_{\text{RIN}}}{2\pi^2 f C_p \omega_c^2},$$

where $P_{\text{abs}}$ is the absorbed power, $C_p$ is the heat capacity per unit volume (written as the product of the heat capacity per unit mass and the density), $\alpha$ is the coefficient of thermal expansion, $S_{\text{RIN}}$ is the power spectrum density of the laser relative intensity noise (RIN), and $\sigma$ is the Poisson ratio (see Sec. 2.8.5 in [31]). In the opposing limit of low frequencies $\omega_c$ is replaced by $\tau_T$ [32].
which is a factor of \(=20\) below the level of the coating thermal noise at 100 Hz.

5. **Shot noise**

Photon counting noise, or “shot noise”, is an unavoidable noise source in precision optical measurements and sufficient power on the sensor is required to sustain the shot noise below the coating thermal noise level. The relevant equation for shot noise in the PDH readout of a high-finesse cavity, expressed as an equivalent displacement of the optics is

\[
N_{02/20} = \frac{\lambda}{8F} \sqrt{\frac{2h\nu}{P_{in} \sqrt{2MJ_0(\beta)J_1(\beta)}}},
\]

where \(J_n(\beta)\) are the Bessel functions, and \(\lambda = 1064\) nm is the wavelength of light used in the cavity [33]. To compute a shot noise level it is further assumed that the mode matching is \(M = 0.03\) and modulation depth is \(\beta = 0.8\) rad. The resulting shot noise, assuming a total input power of 3 mW and a finesse of \(F = 1.5 \times 10^4\), is

\[
N_{02/20} \approx 7.6 \times 10^{-18} \text{ m/\sqrt{Hz}}.
\]

6. **Down-conversion**

A significant fraction of the observed broadband white noise at the level of \(10^{-17} \text{ m/\sqrt{Hz}}\) can be explained by the process of down-conversion. High frequency laser amplitude and frequency noises are seen in the audio band due to the nonlinear demodulation processes required to produce PDH error signals.

Differential amplitude fluctuations of TEM02 and TEM20 beams at the modulation frequency (102 kHz) directly couple to the readout channel. These fluctuations arise from the imbalance in the cavity poles for two modes and due to different input paths of the beams 2a and 2b. This noise was suppressed by using the additional intensity stabilization servos described in Sec. III C, without which it would be a factor of 3 above shot noise. The readout channel sees down-converted amplitude noise at the level of

\[
N_{02/20} = 2 \times 10^{-17} \frac{1}{G_{\text{iss}}} \text{ m/\sqrt{Hz}},
\]

where \(G_{\text{iss}} = 6\) is the open loop gain of the intensity stabilization servo around 102 kHz.

Secondly, frequency noise around 102 kHz and harmonics is down-converted to the audio band during the demodulation process. We found that the biggest contribution comes from the noise around the second harmonic at 204 kHz. An addition servo has been introduced to
suppress laser noise around this frequency as shown in the Fig. 5.

Finally, rf frequency noise around the beat frequency $\Delta f_{02/20}$ is down-converted to the audio band if there is an imbalance in the pole frequencies for TEM02 and TEM20 modes. A careful analysis of optical losses and cleaning of the mirrors helped to reduce this imbalance as shown in the Table II. The beat frequency $\Delta f_{02/20}$ was also set to minimize the laser noise at this frequency.

B. Advanced LIGO coating thermal noise

The least square fitting of a series of spectra gives the following result for the coating thermal noise in our experiment:

$$N_{\text{CTN}} = (1.29 \pm 0.06) \times 10^{-17} \sqrt{\frac{100 \text{ Hz}}{f}} \sqrt{\frac{T}{300 \text{ K}}} \frac{\text{m}}{\sqrt{\text{Hz}}}. $$

The measured value is dominated by coating Brownian noise. Substrate Brownian noise is factor of ≈20 below $N_{\text{CTN}}$, and we estimate the combined thermoelastic and thermorefractive noises in the coating [2], is at least a factor of 5 smaller than $N_{\text{CTN}}$.

Extrapolation of our measured PSD to the PSD of a large beam on an aLIGO end test mass, the total correction factor can be written as

$$C = \left( \frac{\omega_S}{2\omega_L} \right)^2 \times 1.52 = 2.99 \times 10^{-7} \quad (24)$$

Based on Eq. (3) we estimate the value of the coating thermal noise for the Advanced LIGO end test mass (ETM)

$$N_{\text{CTN}}^{(90)} = \sqrt{C} \times (1.29 \pm 0.06) \times 10^{-17}$$

$$= (7.1 \pm 0.3) \times 10^{-21} \sqrt{\frac{100 \text{ Hz}}{f}} \sqrt{\frac{T}{300 \text{ K}}} \frac{\text{m}}{\sqrt{\text{Hz}}}$$

which is slightly higher than the value used in Advanced LIGO design documents ($5.9 \times 10^{-21} \sqrt{\frac{T}{300 \text{ K}}} \text{ m/Hz}$) at 100 Hz calculated with Eqs. 1 and 2 in [1] and for the loss angle value of $\phi_{\text{Tio}_2 = 4.0 \times 10^{-3}$ and $\phi_{\text{Ti}:\text{Ta}} = 2.3 \times 10^{-4}$ [29]).

Since the Advanced LIGO input test mass coating is made out of the same materials, we estimate an overall increase of the coating thermal noise by 20% compared to [29]. Interestingly, there is some evidence that this higher estimation of the coating thermal noise can be associated with interface losses in the coating structure as reported in [34].

C. Loss angle of TiO$_2$·Ta$_2$O$_5$

To estimate the loss angle for the titania-tantala alloy used as the high refractive index material in the Advanced LIGO coatings, we use the loss angle for silicon-dioxide (the low index material) of $\phi_{\text{SiO}_2} = 5 \times 10^{-5}$ [28] and assume that the loss angles associated with shear and bulk deformation in both materials are equal.

We adopted the formula from [8] and calculate the power spectrum density

$$S = \frac{2k_B T}{\pi^2 f \omega_c^2} \frac{1 - \sigma_s - 2\sigma_j^2}{Y_s} \sum_j b_j d_j \phi_j^M $$

(25)

where $\omega_c$ is the beam spot size, $d_j$ is the coating j-layer thickness, $Y$ and $\sigma$ is the Young’s modulus and Poisson ratio of the substrate ($s$) and the coating $j$-layer, respectively. The unitless weighting factor $b_j$ for each layer is

$$b_j = \frac{1}{1 - \sigma_j} \left[ \frac{Y_j}{Y_s} + \frac{(1 - \sigma_s - 2\sigma_j^2) Y_j}{(1 + \sigma_j^2)(1 - 2\sigma_j) Y_s} \right],$$

(26)

under the approximation that no field penetrates into the coating.

Our estimation for the loss angle is $\phi_{\text{Ti}:\text{Ta}} = (3.1 \pm 0.5) \times 10^{-4}$. This number is slightly lower than the value previously reported in [28], but higher than the value reported in [7].

VI. CONCLUSIONS

We presented a novel experiment for the broadband direct measurements of the coating thermal noise. The sensitivity of $10^{-17}$ m/\sqrt{Hz} has been achieved in the frequency band 30–1000 Hz. This is made possible by our novel measurement technique, in which TEM00, 02 and 20 spatial modes all coresonate in a folded cavity.

As a first application of this technique, we measured the coating thermal noise from Advanced LIGO coating and estimated the loss angle of TiO$_2$·Ta$_2$O$_5$. Our results are broadly consistent with the previous estimations, but give a 20% higher coating thermal noise compared to the published Advanced LIGO noise estimates [29,35].

With the ever increasing sensitivity of precision optical measurements, coating thermal noise has become a significant obstacle. In terms of the gravitational wave interferometers and some macroscopic quantum measurement experiments, it is essential to reduce this noise in order to reach and surpass the standard quantum limit. Our experiment design will allow for rapid testing new coatings, thereby helping to reduce the coating thermal noise in the future generation of gravitational wave detectors, frequency references and quantum measurements.
ACKNOWLEDGMENTS

The authors would like to acknowledge the invaluable wisdom derived from interactions with members of the LIGO Scientific Collaboration’s optics working group without which this work would not have been possible. In particular, the multimode cavity design developed from a seed planted several years ago in a conversation with Koji Arai. We are also very grateful for the computing support provided by The MathWorks, Inc. LIGO was constructed by the California Institute of Technology and Massachusetts Institute of Technology with funding from the National Science Foundation, and operates under cooperative agreement Grant No. PHY-0757058. Advanced LIGO was built under Grant No. PHY-0823459. This paper carries LIGO Document No. LIGO-P1600228.

[27] ANSYS academic research, release 14.5.