**A THEORY OF FIRM SCOPE**

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<td>As Published</td>
<td><a href="http://dx.doi.org/10.1162/qjec.2010.125.2.483">http://dx.doi.org/10.1162/qjec.2010.125.2.483</a></td>
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<tr>
<td>Publisher</td>
<td>MIT Press</td>
</tr>
<tr>
<td>Version</td>
<td>Final published version</td>
</tr>
<tr>
<td>Accessed</td>
<td>Mon Apr 15 10:38:53 EDT 2019</td>
</tr>
<tr>
<td>Citable Link</td>
<td><a href="http://hdl.handle.net/1721.1/58806">http://hdl.handle.net/1721.1/58806</a></td>
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A THEORY OF FIRM SCOPE

OLIVER HART AND BENGT HOLMSTROM

The formal literature on firm boundaries has assumed that \textit{ex post} conflicts are resolved through bargaining. In reality, parties often simply exercise their decision rights. We develop a model, based on shading, in which the use of authority has a central role. We consider two firms deciding whether to adopt a common standard. Nonintegrated firms may fail to coordinate if one firm loses. An integrated firm can internalize the externality, but puts insufficient weight on employee benefits. We use our approach to understand why Cisco acquired StrataCom, a provider of new transmission technology. We also analyze delegation.

I. INTRODUCTION

In the last twenty years or so, a theoretical literature has developed that argues that the boundaries of firms—and the allocation of asset ownership—can be understood in terms of incomplete contracts and property rights. The basic idea behind the literature is that firm boundaries define the allocation of residual control rights, and these matter in a world of incomplete contracts. In the
standard property rights model, parties write contracts that are *ex ante* incomplete but can be completed *ex post*. The ability to exercise residual control rights improves the *ex post* bargaining position of an asset owner and thereby increases his or her incentive to make relationship-specific investments. As a consequence, it is optimal to assign asset ownership to those who have the most important relationship-specific investments.¹

Although the property rights approach provides a clear explanation of the costs and benefits of integration, the theory has a number of features that have limited its applicability.² One that we focus on here is the assumption that *ex post* conflicts are resolved through bargaining with side payments. Although direct empirical evidence on this topic is not readily available, casual inspection suggests that bargaining with unrestricted side payments is not ubiquitous. Many decisions made in a firm will be carried out without consultation or negotiation with other firms even when these decisions impact the other firms in a major way. It is rare, for instance, for a firm to go to a competitor with the intention of extracting side payments for avoiding aggressive moves.³

We present a new model of firm boundaries, which is designed to deal with strategic decisions that are taken in the absence of *ex post* bargaining. To justify the use of authority rather than bargaining, we adopt the “contracts as reference points” approach of Hart and Moore (2008). According to this approach, a contract (in our model, an organizational form), negotiated under competitive conditions, circumscribes or delineates parties’ senses of entitlement. Parties do not feel entitled to outcomes outside the contract, but may have different views of what they are entitled to within the contract. More specifically, each side interprets the contract in a way that is most favorable to him. When he does not get the most favored outcome within the contract, he feels aggrieved and shades by performing in a perfunctory rather than a consummate fashion, creating deadweight losses. Given these assumptions, a more open-ended contract leads to more aggrievement, implying

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². For a discussion of this, see Holmstrom and Roberts (1998) and Holmstrom (1999).

³. Of course, where there is an opportunity for mutual gains, a firm may approach another firm to explore various ways of cooperating, either through the market or through a joint venture or merger. However, it is also possible that the parties will simply do what is unilaterally in their best interest.
that ex post bargaining with side payments is costly. We rule out renegotiation on these grounds.

Our model comprises two units that have a lateral relationship (this is another departure from the literature, which has focused on vertical integration). We think of a unit as an irreducible set of activities that it would be meaningless to break up further. Each unit is operated by a manager and has a decision that affects the other unit; that is, there are externalities. We have in mind strategic decisions that are so significant that they warrant consideration of an organizational structure that best supports them. For example, the units may be deciding whether to adopt a common standard or platform for their technology or product.

As an application, we will use the model to understand Cisco’s approach to acquisitions, especially its decision to purchase StrataCom. Cisco’s Internet Operating System (IOS) is a platform that came to dominate the network industry in the 1990s. StrataCom emerged as the leading provider of a small, but rapidly expanding, new transmission technology, Asynchronous Transmission Mode (ATM). The question for Cisco and StrataCom was whether to coordinate their technologies. Initially they tried to do this as separate firms, but apparently this did not work out. Cisco then acquired StrataCom.

Each unit has a binary decision: it can choose “Yes” or “No.” Moreover, we simplify matters further by supposing that there are only two aggregate outcomes, which we term “coordination” or “noncoordination.” Coordination occurs if and only if both units choose Yes. That is, each party can veto coordination by choosing No.

The decision in each unit is ex ante noncontractible, but ex post contractible. Each unit has a boss. The boss has the right to make the decision in that unit ex post; that is, the boss has residual control rights. In the simplest version of our model the boss is equivalent to an owner; however, in extensions, the boss and owner can be different. We will compare two leading organizational forms. In the first, nonintegration, the units are separate firms, and the unit managers are the bosses. In this case the unit managers make the Yes/No decisions. In the second, integration,

4. For a discussion, see Hart (2008).
5. There is thus a parallel between Cisco–StrataCom and the famous case of General Motors and Fisher Body. General Motors and Fisher Body initially transacted as separate firms, but General Motors then acquired Fisher Body. See, for example, Klein (2007).
the units are part of a single firm, and an outside manager is the boss. In this case the boss instructs the managers whether to choose Yes or No, and the managers must follow these instructions (they are contractible); however, the managers may shade on performance.  

A key ingredient in our model is the assumption that each unit generates two kinds of benefit: monetary profit, which is transferable with ownership, and private benefits, which are nontransferable. Private benefits represent job satisfaction, broadly defined. They may arise from various sources. Employees often have their human capital tied to particular technologies. They like to work with technologies with which they are familiar. If a new technology is introduced the employees need to learn new skills, which is costly. Also, the future wages and career prospects of employees may depend on how well their human capital fits the firm’s needs: the firm’s choices will therefore affect them. In sum, employees care about the decisions of the firm they work for. The evidence that smaller companies pay less on average than larger companies (see, e.g., Schoar [2002] on pay in conglomerate versus stand-alone plants) is consistent with the idea that employees are affected by the size and scope of their companies.

Private benefits can also be viewed as a way of capturing different beliefs held by managers and workers about the consequences of strategic choices (for an explicit analysis of differences in beliefs with organizational implications, see Van den Steen [2005]). In high-tech industries, different visions about the future path of particular technologies are held with passion and influence both the costs of hiring and the decisions undertaken. Our discussion of the Cisco case suggests that private benefits were very important to Cisco and influenced its decision making.

The role of the two types of benefits in our analysis can be illustrated as follows. Denote the pair of profits and private benefits (measured in money) accruing to each unit by \((v_A, w_A)\) and \((v_B, w_B)\), respectively. To simplify the analysis, assume that the manager is the only worker and hence private benefits refer to his job satisfaction. As well, assume that the boss of a unit can use her residual rights of control to divert all the profit from that

6. These are not the only possibilities. For example, one could consider another form of integration where one of the unit managers is the boss. We discuss this in Section III.

7. The interpretation that private benefits are enjoyed by a single manager is restrictive. In the Conclusions we discuss briefly the case where the units are large companies, and private benefits refer to the aggregate job satisfaction of workers.
unit to herself. This rules out profit sharing as a way to influence incentives. Profit sharing would alleviate, but not eliminate, the effects we describe.\footnote{8} If the units are nonintegrated, manager $A$ is the boss of unit $A$, and manager $B$ the boss of unit $B$; manager $A$’s payoff will be $v_A + w_A$, because he diverts the profit from unit $A$ and cares about his own private benefits, and manager $B$’s payoff will be $v_B + w_B$, for similar reasons. In contrast, if units $A$ and $B$ are integrated, then, if a (professional) outsider is the boss, her payoff will be $v_A + v_B$, because she diverts all the profit and does not care about private benefits. As a benchmark, note that social surplus is given by $v_A + v_B + w_A + w_B$.

The key point is that integration results in less weight being placed on private benefits than under nonintegration. Under nonintegration, $w_A, w_B$ each appears in one boss’s objective function. In contrast, under integration the $w$’s fail to appear in the overall objective function. However, this diminished influence of private benefits is offset by the fact that, under integration, total profits, rather than individual unit profits, are maximized.

The actual analysis is more complicated because the deadweight losses from shading must be taken into account. Shading causes some internalization of externalities: a boss puts some weight on the payoffs of other parties, given their ability to shade.

We assume that the opportunity to shade under nonintegration also depends on the nature of the relationship between the parties. We make a distinction between two forms of nonintegration. In one, “nonintegration without cooperation,” the relationship between the units is a limited one that terminates if noncoordination occurs; the units cannot shade against each other in this eventuality. In the other, “nonintegration with cooperation,” the relationship persists; shading can occur under noncoordination. In contrast, we assume that shading is always possible under integration: the parties continue to have a relationship.

In summary, under nonintegration, bosses have the right balance between private benefits and profits, but are parochial (they do not take into account their effect on the other unit), whereas, under integration, they have the right balance between units, but ignore private benefits. In our model, where the only issue is whether the units coordinate, we show that nonintegration and integration make opposite kinds of mistakes. Nonintegration can lead to too little coordination when the benefits from coordination

8. We return to this issue briefly in Section V.
are unevenly divided across the units. One unit may then veto coordination even though it is collectively beneficial. In contrast, under a weak assumption—specifically, that coordination represents a reduction in “independence” and therefore causes a fall in private benefits—integration leads to *too much* coordination.9,10

We analyze the above model in Sections II and III. In Section IV, we generalize the model to allow delegation of decision-making authority under integration. We argue that it is hard to make sense of delegation in much of the literature, because it is unclear why the boss cannot change her mind *ex post* and take back the decision rights that she has delegated. The presence of aggrievement can help here. We assume that reversing delegation is regarded by subordinates as a “breach of promise” and leads to increased levels of aggrievement. This makes delegation a credible commitment device: the boss will reverse herself only in “extreme” states of the world. We show that integration with delegation can be a valuable intermediate organizational form between nonintegration and integration. Under delegation, managers get their way in states of the world where decisions matter significantly more to them than to the boss. However, in states of the world where the boss cares a lot about the outcome, either managers will do what the boss wants of their own accord, given the threat of shading by the boss, or the boss will take back the decision rights.

Our paper is related to a number of ideas that have appeared in the literature. First, there is an overlap with the literature on internal capital markets; see particularly Stein (1997, 2002), Rajan, Servaes, and Zingales (2000), Scharfstein and Stein (2000), Brusco and Panunzi (2005), and Inderst and Laux (2005). This

9. In our model the boss of an integrated firm has relatively broad objectives because he diverts (all of) the profit from the units under his control. We believe that a boss may have broad objectives for other reasons: he may be judged according to how well the units under his control perform, or obtain job satisfaction from their success.

10. In a previous version of the paper we assumed that decisions were noncontractible both *ex ante* and *ex post*, and did not adopt the “contracts as reference points” approach. We obtained a similar trade-off between nonintegration and integration, but our approach raised some questions. (In independent work, Baker, Gibbons, and Murphy [2008] also obtain a trade-off similar to ours under the assumption that decisions are *ex post* noncontractible.) First, if a decision is *ex post* noncontractible, how does a boss get it carried out except by doing it herself? Second, even if decisions are *ex post* noncontractible, as long as decision rights can be traded *ex post*, it is unclear why *ex ante* organizational form matters (in the absence of noncontractible investments). The parties could just rely on *ex post* bargaining of decision rights to achieve an optimum. Finally, the “*ex post* noncontractibility” approach by itself does not yield an analysis of delegation (see below).
literature emphasizes the idea that the boss of a conglomerate firm, even if she is an empire builder, is interested in the overall profit of the conglomerate, rather than the profits of any particular division. As a result, the conglomerate boss will do a good job of allocating capital to the most profitable project (“winner-picking”). Our idea that the professional boss of an integrated firm maximizes total profit is similar to this; the main differences are that the internal capital markets literature does not stress the same cost of integration as we do—the boss’s insufficient emphasis on private benefits—or allow for the possibility that the allocation of capital can be done through the market (in our model, the market is always an alternative to centralized decision making), or consider standard-setting. Second, the idea that it may be efficient for the firm to have narrow scope and/or choose a boss who is biased toward particular workers is familiar from the work of Shleifer and Summers (1988), Rotemberg and Saloner (1994, 2000), and Van den Steen (2005). These papers emphasize the effect of narrow scope and bias on worker incentives rather than on private benefits or wages, but the underlying premise, that workers care about the boss’s preferences, is the same. However, none of these papers analyzes firm boundaries. Third, several recent works explore firm boundaries and internal organization using the idea that some actions are noncontractible ex ante and ex post but may be transferable through ownership; see, for example, Holmstrom (1999), Aghion, Dewatripont, and Rey (2004), Mailath, Noce, and Postlewaite (2004), Bolton and Dewatripont (2005), Hart and Moore (2005), Alonso, Dessein, and Matouschek (2008), Baker, Gibbons, and Murphy (2008), and Rantakari (2008). We discuss in footnote 10 some reasons that we have not followed the “ex post noncontractibility” approach here.

We should point out how our analysis of delegation differs from the treatment of authority in Aghion and Tirole (1997) (see also Baker, Gibbons, and Murphy [1999]). In Aghion and Tirole, a boss defers to a subordinate in situations where the subordinate has superior information. In this case, even though the boss has “formal” authority, the subordinate has “real” authority. In contrast, we are interested in situations where allocating authority to someone inside a firm has meaning. As Baker, Gibbons, and Murphy (1999) point out, this corresponds to real rather than formal authority: if the boss appoints someone as unit head, say, she can legally change her mind and take the authority back. In our model, allocating authority inside a firm nonetheless has
meaning. The reason is that there is a friction: designating someone as unit head and then reversing the decision is costly, given that reversal increases aggrievement (by the unit manager, and possibly by unit workers to the extent that the new boss’s preferences are less aligned with theirs).\footnote{In Baker, Gibbons, and Murphy (1999), reversal is also costly given that it is a breach of a relational contract.}

The paper is organized as follows. The basic model is presented in Sections II and III. In Section IV we analyze delegation. Section V illustrates the model using Cisco’s approach to platform leadership through acquisitions. Finally, Section VI concludes.

II. A BASIC MODEL OF COORDINATION

Our model concerns two units, $A$ and $B$, that have a lateral relationship: they operate in the same output or input markets. A unit has a manager and no workers. Each unit makes a decision that affects the other unit. For example, the units may be deciding whether to adopt a common standard or platform for their technology or products. It is natural to model such a strategic coordination decision as a binary choice. Each unit can choose “Yes” ($Y$) or “No” ($N$). There are two aggregate outcomes: “coordination” or “noncoordination.” Coordination occurs if and only if both units choose $Y$. The timeline is as in Figure I. At the beginning, an organizational form is selected—specifically, whether the units should be separate firms (nonintegration, i.e., there are two bosses) or should merge into one firm (integration, i.e., there is one boss). Next, each unit chooses $Y$ or $N$. Finally, the payoffs are realized.

Each unit generates two kinds of benefit: monetary profit $v$ and private (nontransferable) benefits $w$ in the form of job satisfaction for the manager working in the unit (private benefits are measured in money). We assume that the boss of the unit can divert all the profit from that unit to herself.\footnote{One justification is that the boss can use her residual control rights to authorize side-deals with other companies she owns, and this enables her to siphon profit out of the unit.} In contrast, the private benefits always reside with the managers. We represent payoffs from different outcomes in the matrix in Table I. We assume that these payoffs are nonverifiable and, for simplicity,
perfectly certain. Without loss of generality we normalize so that monetary profit and private benefits under noncooperation are zero in both units. Unit A is the row player, and unit B is the column player. Subscripts refer to units, with \( v \) representing profit and \( w \) private benefits.

It will be convenient to introduce the notation

\[
\Delta z_A \equiv \Delta v_A + \Delta w_A, \quad \Delta z_B \equiv \Delta v_B + \Delta w_B.
\]

Here, \( \Delta z_A \) (resp. \( \Delta z_B \)) refers to the change in total surplus in unit A (resp. unit B) from coordination, and \( \Delta z_A + \Delta z_B \) equals the change in aggregate social surplus. Note that (1) does not account for the costs of aggrievement, which depend on the \textit{ex ante} contract as well as the \textit{ex post} decision.

As discussed in the Introduction, private benefits refer (broadly) to job satisfaction or on-the-job consumption. It is reasonable to assume that part of job satisfaction stems from the ability to pursue an independent course or agenda. Thus, we will assume that coordination leads to a reduction in private benefits:

\[
\Delta w_A \leq 0, \quad \Delta w_B \leq 0.\tag{2}
\]

We put no restrictions on whether coordination increases or decreases profits; moreover, even if coordination increases total profits, profits may rise by more or less than the fall in private benefits.

We will focus on two leading organizational forms:

1. \textit{Nonintegration}:\textsuperscript{14} Manager A is the boss of unit A and manager B is the boss of unit B. Each manager diverts

\textsuperscript{13} Our main results generalize to the case \( \Delta w_A + \Delta w_B \leq 0 \). We make the stronger assumption (2) for expositional simplicity.

\textsuperscript{14} We will actually consider two subcases of nonintegration, one without cooperation and one with cooperation, as discussed below.
profit and receives private benefits from his unit, and so manager $A$'s payoff is $v_A + w_A$, and manager $B$'s is $v_B + w_B$.

2. Integration: A professional manager (an outsider) is the boss of both units and managers $A$ and $B$ are subordinates. The boss receives $v_A + v_B$. The unit managers are under fixed-wage employment contracts and each manager receives the sum of the wage and private benefit in his unit.

Organizational form and contracts are determined \textit{ex ante}. We will assume, as in the standard incomplete contracts literature, that at this stage the coordination decisions are too complicated to specify; however, authority over these decisions can be allocated. We will take the view that the boss of each unit has residual rights of control, which gives her the legal authority to make the $Y/N$ decisions in her unit. \textit{Ex post} the $Y/N$ decisions can be contracted on. Under nonintegration each unit manager chooses $Y$ or $N$ in his unit. Under integration, the overall boss instructs the unit managers to choose $Y$ or $N$. We will assume that the unit managers must follow these instructions—they are contractible—but the managers may choose to shade.\textsuperscript{15} Shading may also occur under nonintegration.

As discussed in the Introduction, we use the “contracts as reference points” approach of Hart and Moore (2008) to justify the particular contracting assumptions that we make. According to this approach a contract—an organizational form in this case—negotiated under \textit{ex ante} competitive conditions delineates or circumscribes parties’ feelings of entitlement \textit{ex post}. In particular, a contracting party does not feel entitled to an outcome \textit{outside} those specified by the contract or organizational form. However, parties may feel entitled to different outcomes \textit{within} the contract or organizational form. A party who does not receive what he feels entitled to is aggrieved and shades on performance. We assume that shading reduces the payoff of the shaded against party but does not affect the payoff of the party doing the shading. Shading creates deadweight losses.\textsuperscript{16}

Specifically, following Hart and Moore (2008), we assume that each party feels entitled to his most preferred outcome or decision within the contract, and that a party who receives $k_i$ less than his

\textsuperscript{15} We do not allow managers to quit within a period; see footnote 22.

\textsuperscript{16} The reference points approach resembles in some respects relational contracting (see, e.g., Baker, Gibbons, and Murphy [2008]). Shading is like punishment in relational contracting models, but shading does not hurt the person doing the shading.
maximum payoff will be aggrieved by $k_i$ and will shade to the point where the other parties’ payoffs fall by $\theta k_i$. Here $\theta$ is an exogenous shading parameter, assumed to be the same for all parties, and $0 < \theta < 1$. Thus the total deadweight loss from shading is $\theta \sum_i k_i$.

The assumption that contracts are reference points provides a natural reason for parties to pin things down in an initial contract. A contract that is too flexible, that is, that specifies too little, can lead to a lot of aggrievement and shading ex post. The downside of a rigid contract is that it is harder for the parties to adjust to new circumstances. Even though there is no payoff uncertainty in our model, our assumption that decisions become contractible only $ex$ $post$ implies a change in circumstances that makes the $ex$ $ante$ choice of organizational form relevant for the deadweight losses from aggrievement, as will become clear below.

There is a further consideration about shading: the ability of a party to shade may depend on the nature of the transaction that the party is engaged in. For example, under nonintegration, if the units fail to coordinate on a standard or platform, they may no longer have dealings with each other, which will reduce shading possibilities. For this reason, we will distinguish between two forms of nonintegration. In one, “nonintegration without cooperation,” the parties’ relationship ends in the absence of adoption of a standard and so shading is not possible under noncoordination. In the second, “nonintegration with cooperation,” the parties have a broader relationship that continues beyond the standardization decision and so shading is possible even under noncoordination. In contrast, under integration, we assume that shading is always possible: the parties continue to have a relationship.\footnote{In our discussion of the Cisco–StrataCom relationship in Section V we suggest that, before StrataCom was acquired, their relationship was probably best described as “nonintegration with cooperation.”}

Under the shading assumption, $ex$ $post$ renegotiation is not costless because each party will feel entitled to the best possible outcome in the renegotiation, and they cannot all be satisfied and will shade. Moreover, to the extent that renegotiation reopens consideration of the terms and entitlements underlying existing contracts, renegotiation can make all parties worse off. In the analysis below, we will rule out $ex$ $post$ renegotiation on these grounds. However, we believe that our results could be generalized to $ex$ $post$ renegotiation along the lines of Hart (2009).

We assume that bargaining at the $ex$ $ante$ stage ensures that organizational form is chosen to maximize expected future surplus net of $ex$ $post$ shading costs (lump sum transfers are used to
redistribute surplus). In particular, we assume that at least one side of the market is competitive \textit{ex ante}, so that each side achieves the best outcome it can get in the negotiation. Therefore there is no shading at the \textit{ex ante} stage. In contrast, there is the potential for shading at the \textit{ex post} stage, because the parties are then locked in.

The \textit{ex ante} bargaining also determines managerial wages. In the special case where there is a competitive market for managers, wages plus expected private benefits will equal the reservation utility for managers. An implication of this is that an organizational change that reduces private benefits will lead to an increase in wages.\textsuperscript{18}

III. OPTIMAL ORGANIZATIONAL FORM

In this section we analyze optimal organizational form. We compare “nonintegration without cooperation,” “nonintegration with cooperation,” and “integration.”\textsuperscript{19} In each case we assume that the \textit{ex ante} incomplete contract that the parties write fixes prices or wages and allocates authority.\textsuperscript{20} Also, there is no renegotiation.

From now on, we will use $S$ to denote the social surplus \textit{net of shading costs}, that is, the relevant payoff from Table I less any costs of shading. For simplicity, we refer to $S$ as social surplus. \textit{First-best} refers to cases where aggregate surplus is maximized and shading costs are zero. Similarly, we say that a decision is \textit{first-best efficient} if it maximizes total surplus ignoring shading costs.

III.A. Nonintegration without Cooperation

Under nonintegration, manager $A$’s payoff is $v_A + w_A$, manager $B$’s payoff is $v_B + w_B$, and either manager can veto coordination by choosing $N$.

It is useful to distinguish three cases.

\textsuperscript{18} There is some evidence consistent with this. Schoar (2002), in a study of the effects of corporate diversification on plant-level productivity, finds that diversified firms have on average 7% more productive plants, but also pay their workers on average 8% more, than comparable stand-alone firms.

\textsuperscript{19} We take the view that both forms of nonintegration are feasible choices. In reality, past and expected future interactions between the parties may dictate the nature of their relationship under nonintegration. In other words, whenever nonintegration is chosen, its type is determined.

\textsuperscript{20} We do not consider contracts that specify a price range rather than a single price. For a discussion of such contracts, see Hart and Moore (2008).
Case 1: $\Delta z_A \leq 0$, $\Delta z_B \leq 0$. The managers’ preferences are aligned. Coordination does not occur because nobody wants it, and given that there is no disagreement, there is no aggrievement. Social surplus is given by

\begin{equation}
S = 0.
\end{equation}

Case 2: $\Delta z_A \geq 0$, $\Delta z_B \geq 0$. The managers’ preferences are aligned. This time both parties want coordination and so coordination occurs without aggrievement. Social surplus is given by

\begin{equation}
S = \Delta z_A + \Delta z_B.
\end{equation}

Case 3: $\Delta z_i < 0$, $\Delta z_j > 0$ ($i \neq j$). Now there is a conflict. Manager $i$ does not want coordination and can veto it by choosing $N$. Because under “nonintegration without cooperation” shading by manager $j$ is infeasible if the parties do not coordinate, manager $i$ will not hesitate to exercise his veto, and the outcome will be noncoordination. Social surplus is given by

\begin{equation}
S = 0.
\end{equation}

We see that the first-best, coordinate if and only if

\begin{equation}
\Delta z_A + \Delta z_B \geq 0,
\end{equation}

is achieved in Cases 1 and 2, but may not be achieved in Case 3. This is the critical problem of winners and losers. Even though aggregate surplus may rise, the distribution of the gains may be such that one party loses out, and this party will veto coordination.

In summary, there is too little coordination under “nonintegration without cooperation.” Whenever coordination occurs it is first-best efficient (Case 2 implies (6)); but coordination may not occur when it is first-best efficient ((6) does not imply Case 2). Finally, there is no shading in equilibrium under “nonintegration without cooperation,” whether the outcome is coordination or noncoordination.

III.B. Nonintegration with Cooperation

Now shading is possible even under noncoordination. Cases 1 and 2 remain the same and achieve first-best (in particular, no

21. Note that, in Case 2, $(N, N)$ is a Nash equilibrium along with $(Y, Y)$; however, we will assume that parties do not pick a Pareto-dominated equilibrium.
shading). However, under Case 3, manager \(i\) may choose not to veto coordination, given that manager \(j\) will be aggrieved if \(i\) does this—by the difference between manager \(j\)’s payoff under his preferred outcome, coordination, and what he actually gets—and will shade in proportion to this difference. That is, manager \(j\) will be aggrieved by \(\Delta z_j\) and will shade by \(\theta \Delta z_j\). Coordination will occur if manager \(i\)’s utility from coordination exceeds the costs of shading imposed on \(i\) by manager \(j\), \(\Delta z_i \geq -\theta \Delta z_j\), that is,

\[
\Delta z_i + \theta \Delta z_j \geq 0. 
\]

If (7) holds, manager \(i\) is a reluctant coordinator and will be aggrieved by \(-\Delta z_i\) because the best outcome for him would have been not to coordinate. Thus manager \(i\) will shade by \(-\theta \Delta z_i\), and there will be deadweight losses of that amount. Note that (7) implies

\[
\Delta z_j + \theta \Delta z_i > 0. 
\]

and so manager \(j\) still wants to coordinate in spite of this shading. On the other hand, if (7) does not hold, coordination will not occur but manager \(j\) will shade by \(\theta \Delta z_j\).

Social surplus is thus given by

\[
S = \Delta z_A + \Delta z_B + \theta \Delta z_i \quad \text{if (7) holds (coordination),} \\
-\theta \Delta z_j \quad \text{if (7) does not hold (noncoordination).}
\]

Whereas first-best is achieved in Cases 1 and 2, Case 3 does not lead to first-best. It is easy to see that (7) \(\Rightarrow\) (6), so there is too little coordination relative to first-best. In addition, social surplus, given in (9), always entails a strictly positive cost of shading; regardless of the decision, one side will be unhappy.

It is evident that “nonintegration with cooperation” is potentially desirable (to the extent that it is a choice) only if coordination is the outcome (i.e., (7) holds). When (7) does not hold, the parties are better off with “nonintegration without cooperation.” In the case where there is uncertainty (to be discussed later) it is possible that parties attempt “nonintegration with cooperation,” only to find that (7) fails.

III.C. Integration

We divide the analysis into two cases.

Case 1: \(\Delta v_A + \Delta v_B \leq 0\). The managers’ and bosses’ preferences are aligned (given (2)). Coordination does not occur because
no one wants it, and, given that there is no disagreement, there is no shading. Social surplus is given by

\[ S = 0. \]

**Case 2:** \( \Delta v_A + \Delta v_B > 0 \). Now the boss wants coordination, but the managers do not, and they will be aggrieved by \( \Delta w_A + \Delta w_B \) and will shade by \( \theta(\Delta w_A + \Delta w_B) \) if it occurs. The boss will coordinate if and only if her payoff net of shading costs is higher:

\[ \Delta v_A + \Delta v_B + \theta(\Delta w_A + \Delta w_B) \geq 0. \]

In other words, the boss partly internalizes the wishes of her subordinates. If (11) does not hold, the boss will go along with what the managers want and will not coordinate. In this case, the boss is aggrieved by \( \Delta v_A + \Delta v_B \) because she is not getting her preferred outcome, and so she will shade to the point where the unit managers’ payoffs fall by \( \theta(\Delta v_A + \Delta v_B) \).

Social surplus is thus given by

\[ S = \Delta z_A + \Delta z_B + \theta(\Delta w_A + \Delta w_B) \text{ if (11) holds (coordination),} \]
\[ - \theta(\Delta v_A + \Delta v_B) \text{ if (11) does not hold (noncoordination).} \]

The first-best is achieved in Case 1 but not in Case 2. In Case 2, there is too much coordination relative to the first-best ((6) \( \Rightarrow \) (11) but not vice versa) and too much shading.

We have established

**Proposition 1.** Nonintegration errs on the side of too little coordination (when coordination occurs it is first-best efficient, but it may be first-best efficient and not occur), whereas integration errs on the side of too much coordination (when coordination is first-best efficient it occurs, but it may occur even when it is not first-best efficient). If noncoordination is first-best efficient, “nonintegration without cooperation” achieves the first-best. If coordination is first-best efficient then (a) integration leads to coordination, but may not be optimal given the deadweight losses from shading; (b) integration is optimal if the changes in private benefits from coordination are
sufficiently small; and (c) integration is uniquely optimal if in addition the distribution of profits is sufficiently uneven.\textsuperscript{22}

An extension: So far we have assumed that the integrated firm is run by a professional manager. We now consider whether it might be better to put manager A, say, in charge. Case 1 remains unchanged. However, Case 2 will be different. Instead of (11), manager A’s decision rule will be to coordinate if and only if

\begin{equation}
\Delta v_A + \Delta v_B + \Delta w_A + \theta \Delta w_B \geq 0.
\end{equation}

So manager A, like the professional manager, coordinates too often. However, because (13) implies (11), manager A is less biased toward coordination. This is an improvement. The social surplus in the event that manager A coordinates will be

\begin{equation}
S = \Delta z_A + \Delta z_B + \theta \Delta w_B,
\end{equation}

which is greater than the social surplus when the professional manager coordinates (see (12)). The reason is that when manager A coordinates, he does not shade against himself. The upshot is that it is always at least as good to have manager A (or manager B by symmetry) run the integrated enterprise as to have a professional boss.

One way to rationalize our assumption that the boss of the integrated firm is a professional manager is to assume that as well as the strategic decision that we have focused on, there are additional 0–1 decisions that need to be taken, which will be chosen in an inefficient way if manager A or manager B becomes the boss in the integrated firm. To illustrate, suppose that there is an auxiliary decision that has no financial consequences, just private ones. Specifically, let the effects of going ahead with the decision be

\begin{equation}
\Delta \hat{w}_A > 0 > \Delta \hat{w}_B \quad \text{and} \quad \Delta \hat{w}_A + \Delta \hat{w}_B < 0.
\end{equation}

\textsuperscript{22} We assume that unit managers are locked in for a period and cannot quit, that is, we assume that their employment contract is binding for one period. (See Hart and Moore [2008] and Van den Steen [2009] for discussions of the employment contract, and Hart and Moore [2008] for a model where quitting can occur within a period.) If quitting were possible, then under integration the boss would be forced to internalize some of the managers’ private benefits because if she pursued profit too much at the expense of private benefits, managers would leave. Obviously, quitting becomes more of an issue in a multiperiod model where decisions are long-term, and a decision that reduces managerial independence might force the boss to pay higher wages to retain workers. In many interesting situations, however, it is plausible that managers and workers are not on the margin of quitting, perhaps because they have made relationship-specific investments or they are paid efficiency wages.
Thus, manager $A$ would like to see the decision taken, even though it is inefficient. As the boss, he will go ahead with the decision whenever

$$\Delta \hat{w}_A + \theta \Delta \hat{w}_B > 0.$$  

(16)

The social payoff of going ahead is

$$\Delta \hat{w}_A + \Delta \hat{w}_B + \theta \Delta \hat{w}_B < 0.$$  

(17)

A professional manager would never go ahead with the decision. Manager $A$, but not manager $B$, will feel aggrieved by this, which results in a social payoff $-\theta \Delta \hat{w}_A < 0$. Comparing this with (17), we see that social surplus from the auxiliary decision is strictly higher when a professional manager is in charge than when manager $A$ is in charge.

Manager $B$ would make the same auxiliary choice as the professional manager and be more effective than the professional manager with respect to the strategic decision, as we argued earlier. So, when both the strategic decision and the auxiliary decisions are considered together, manager $B$ would be the best boss. To avoid this conclusion, we can add a second auxiliary decision, with the payoffs for $A$ and $B$ reversed. This decision would be just as inefficient, but favors manager $B$ rather than $A$. With both decisions thrown in, it is easy to see that the professional manager can be the best boss. The benefit of a professional boss is that she will not make decisions that are inefficient and exclusively favor one or the other manager. This is an economically plausible argument for having a professional boss run the integrated firm, though obviously there are interesting cases where manager $A$ or manager $B$ would do better.

Finally, we note that instead of introducing auxiliary decisions, we can add uncertainty about private benefits into our original model, allowing them to be negatively correlated as in the discussion above. This requires that we replace our earlier assumption that both $A$'s and $B$'s private benefits suffer from coordination, condition (2), with the assumption that the sum of the changes in private benefits is negative. With uncertainty and negatively correlated private benefits, a professional manager can be the optimal choice, exactly for the reasons illustrated by considering auxiliary decisions.
IV. DELEGATION

We now consider delegation, a form of governance that is intermediate between integration and nonintegration, where a professional boss delegates her formal authority over decision rights to the unit managers. However, because the boss is legally in charge, there is nothing to stop her from changing her mind and taking back the decision rights ex post. We refer to the taking back of decision rights as a reversal: we assume that the timing is such that a reversal takes place ex post before managers make their decisions. We assume that the subordinates regard a reversal as a “breach of promise,” and this leads to increased levels of aggrievement and shading: the shading parameter rises from $\theta$ to $\bar{\theta}$, where $1 \geq \bar{\theta} \geq \theta$. If $\bar{\theta} > \theta$, and there is uncertainty, we will see that delegation can have value as a partial commitment device.

As in our discussion of integration in Section III, there are two cases:

Case 1: $\Delta v_A + \Delta v_B \leq 0$. Preferences are aligned, and no one wants coordination. So coordination does not occur, and there is no shading. Social surplus is given by $S = 0$.

Case 2: $\Delta v_A + \Delta v_B > 0$. Now there is a conflict. Ignore reversal for the moment. If the managers do not coordinate, the boss will be aggrieved. Suppose that the boss divides her shading 50:50 between the two parties. Then the managers’ payoffs are given by $-\frac{\theta}{2} (\Delta v_A + \Delta v_B)$, $i = A, B$. So the managers will choose to coordinate if

$$\Delta w_A + \frac{\theta}{2} (\Delta v_A + \Delta v_B) \geq 0,$$

$$\Delta w_B + \frac{\theta}{2} (\Delta v_A + \Delta v_B) \geq 0.$$  

When (18) holds, the managers coordinate reluctantly. They feel aggrieved and will shade, reducing the social surplus to

$$S = \Delta z_A + \Delta z_B + \theta (\Delta w_A + \Delta w_B).$$

Suppose next that (18) does not hold. Then coordination will not occur unless the boss reverses the decision and forces coordination. Forced coordination leads to aggrievement levels of $\Delta w_A + \Delta w_B$ for the managers. Shading costs equal $\bar{\theta} (\Delta w_A + \Delta w_B)$.

23. Although the boss delegates the right to make $Y/N$ decisions, we assume that she retains the ability to divert unit profit.
24. This is a simplifying assumption and other possibilities could be explored.
given that the shading parameter rises from $\theta$ to $\bar{\theta}$. Thus, the boss reverses if and only if

$$\Delta v_A + \Delta v_B + \bar{\theta}(\Delta w_A + \Delta w_B) \geq 0.$$  

So if neither (18) nor (20) holds, coordination does not occur and

$$S = -\theta(\Delta v_A + \Delta v_B),$$

whereas, if (18) does not hold but (20) does, coordination occurs, and

$$S = \Delta z_A + \Delta z_B + \bar{\theta}(\Delta w_A + \Delta w_B).$$

We summarize this discussion in the following proposition.

**PROPOSITION 2.** In the delegation model,

A. If $\Delta v_A + \Delta v_B \leq 0$, coordination does not occur and social surplus is given by

$$S = 0.$$

B. If $\Delta v_A + \Delta v_B > 0$ and (18) holds, managers will coordinate reluctantly and

$$S = \Delta z_A + \Delta z_B + \theta(\Delta w_A + \Delta w_B).$$

C. If $\Delta v_A + \Delta v_B > 0$ and (18) does not hold but (20) does, the boss forces coordination and

$$S = \Delta z_A + \Delta z_B + \bar{\theta}(\Delta w_A + \Delta w_B).$$

D. If $\Delta v_A + \Delta v_B > 0$ and neither (18) nor (20) holds, then coordination does not occur, but the boss is aggrieved and

$$S = -\theta(\Delta v_A + \Delta v_B).$$

It is useful to compare the outcome under delegation with that under integration. It is easy to see that (18) implies (11), given that $\theta < 1$. Also, (20) implies (11). It follows that, whenever coordination occurs under delegation, that is, in case B or C above, coordination occurs under integration too. However, because (6) implies (20) (given that $\bar{\theta} \leq 1$), there is still too much coordination under delegation relative to the first-best; that is, coordination occurs whenever it is efficient, but also sometimes when it is inefficient.
Proposition 3. Under delegation there is (weakly) less coordination than under integration, but still too much coordination relative to the first-best.

Proposition 3 is intuitive. If unit managers reluctantly coordinate under delegation, that is, reversal is not required, then a professional manager would also coordinate under integration. And if a professional manager would reverse delegation to achieve coordination, incurring higher aggrieve ment and shading costs, then she would surely coordinate if reversal were not required. Finally, because $\bar{\theta} \leq 1$, if coordination is efficient, the boss will be prepared to incur the costs of reversal to achieve it.

Thus, the trade-off between integration and delegation is the following: both yield coordination too much of the time, but delegation yields it less of the time and therefore comes closer to the first-best. However, to the extent that the boss reverses delegation to achieve coordination, the deadweight losses from shading are higher under delegation than under integration.

The next proposition shows that delegation is never strictly optimal under certainty.

Proposition 4. Under perfect certainty, “nonintegration without cooperation” or integration can be strictly optimal, but delegation is never strictly optimal.

Proof. Suppose first that the equilibrium outcome under delegation is $(N, N)$. Then the equilibrium outcome under “nonintegration without cooperation” cannot be worse than this: either it is $(N, N)$ with less shading, or it is $(Y, Y)$, which is Pareto superior.

Suppose next that the equilibrium outcome under delegation is $(Y, Y)$. If (18) holds, so does (11), and so coordination occurs under integration with the same shading costs. On the other hand, if (18) does not hold, then (20) must hold, because otherwise the outcome would be $(N, N)$. But if (20) holds, then (11) holds, and so coordination again occurs under integration with lower shading costs.

Finally, it is easy to find parameters such that $(N, N)$ is socially optimal, and “nonintegration without cooperation” yields $(N, N)$, whereas integration and delegation yield $(Y, Y)$; and parameters such that $(Y, Y)$ is socially optimal, and integration yields $(Y, Y)$, whereas “nonintegration without cooperation” and delegation yield $(N, N)$. In other words, nonintegration and integration can each be uniquely optimal. QED
Delegation may, however, be superior to either nonintegration or integration in a world of uncertainty. For delegation to be better, it is important that $\theta > \tilde{\theta}$. To see this, note that if $\tilde{\theta} = \theta$, (18) implies (20), and (20) and (11) are equivalent. Thus, cases B and C above are both ones where (11) holds. A comparison of cases B–D and (12) then shows that the outcome under integration with delegation is identical to that under integration. From now on, therefore, we assume that $\tilde{\theta} > \theta$.

Assume that payoffs are drawn from a commonly known probability distribution and are observed by both parties ex post (there is symmetric information). To understand how delegation can be strictly optimal, it is useful to focus on the special case where $\Delta w_A = \Delta w_B = \Delta w$. Also, write $\Delta v = \frac{1}{2}(\Delta v_A + \Delta v_B)$. Then the first-best condition for coordination, (6), is $\Delta v \geq |\Delta w|$, where $||$ denotes absolute value. If $\Delta v \leq 0$, all organizational forms—nonintegration, integration and delegation—yield the same outcome: noncoordination. So assume that $\Delta v > 0$. Then the condition for coordination without reversal under delegation (reluctant coordination) becomes $\theta \Delta v \geq |\Delta w|$, whereas the condition for coordination with reversal under delegation (forced coordination) becomes $\Delta v > \tilde{\theta} |\Delta w|$. In contrast, the condition for coordination under integration can be written as $\Delta v \geq \theta |\Delta w|$.

The situation is illustrated in Figure II, where $\Delta w$ is fixed and $\Delta v$ varies. For low values of $\Delta v$, $\Delta v \leq \theta |\Delta w|$, there is no coordination under integration or delegation. For values of $\Delta v$ above $\theta |\Delta w|$, there is coordination under integration. In contrast, under
delegation, \( \Delta v \) has to reach \( \bar{\theta} |\Delta w| \) before coordination occurs. The good news about delegation relative to integration, then, is that, in the range \( \theta |\Delta w| \leq \Delta v \leq \bar{\theta} |\Delta w| \), it achieves a more efficient outcome. The bad news is that, in the range \( \bar{\theta} |\Delta w| \leq \Delta v \leq |\Delta w|/\theta \), delegation achieves coordination, but with higher shading costs because reversal is required.

It is fairly clear when delegation will dominate integration. Suppose that the probability distribution of \( \Delta v \) is such that \( \Delta v \) is either in the range \( \theta |\Delta w| \leq \Delta v \leq \bar{\theta} |\Delta w| \) or in the range \( \Delta v \geq |\Delta w|/\theta \). Then delegation achieves noncoordination when this is efficient, and coordination when this is efficient; moreover, the shading costs are low when coordination occurs because reversal is not required. In contrast, under integration coordination would occur also when it is inefficient—that is, in the range \( \theta |\Delta w| \leq \Delta v \leq \bar{\theta} |\Delta w| \).

The intuition is simple. Delegation can be a good way for the boss to commit not to intervene when this is inefficient, given that the costs of intervening, that is, reversal, are high. Note finally, that over the range where integration with delegation is superior to integration without delegation, integration with delegation will also be superior to nonintegration if, when the gains from coordination are large, they are unevenly divided.

V. PLATFORM LEADERSHIP AND STANDARDS—CISCO’S PURCHASE OF STRATACOM

In this section we describe a context where we think our approach, broadly interpreted, is particularly relevant—the struggle for platform leadership in the network industry. We use Cisco as an example, because Bunnell (2000) (as well as Gawer and Cusumano [2002]) provides a detailed, informative account of Cisco’s acquisition strategy. We illustrate this strategy with Cisco’s acquisition of StrataCom.

Standards are very important in rapidly evolving industries such as information and communication technology. The social benefits from a common standard can be huge, but getting independent parties to agree to a standard is often difficult, because the benefits from adopting a single standard tend to be unevenly distributed. Instead, standards are often supported through self-enforcing, multilateral cross-licensing agreements and industry consortia.

Naturally, the players owning key technological platforms have a disproportionate say in the determination of standards,
sometimes to the extent that they may be able to dominate the evolution of the industry. Therefore, the rewards from winning the battle for platform leadership are huge (Gawer and Cusumano 2002) and result in complex strategic games among the contenders. In these games, acquisition strategies play an important role, for reasons that our model captures at least in part.

Cisco’s IOS is a technological platform that came to dominate the network industry in the course of the 1990s. Cisco had originally been successful and grown rapidly, thanks to its router technology, which served the core network of the Internet. Over time, IOS, designed to run the routers, became the de facto technology platform on which Cisco built its industry dominance (Gawer and Cusumano 2002, pp. 164–176). This was no accident. When John Chambers became the CEO of Cisco in 1992, his goal was to make Cisco “the architect of a new worldwide communication system for the twenty-first century” (Bunnell 2000, p. xv). The value of controlling the architecture of the network ecosystem was accentuated by the customers’ desire to buy end-to-end solutions that integrated the underlying technologies into a seamless user experience.

Acquisitions played a key role in achieving Cisco’s goal. Under Chambers’s leadership, Cisco became a serial acquirer. Between 1993 and 2000, it bought a total of 71 companies—23 companies in 2000 alone. Most of the acquired companies were start-ups, bought to fill gaps in the expanding technological space that Cisco wanted to control. Arguably, the most critical acquisition that Cisco made in this period was the purchase in 1996 of StrataCom, the leading provider of a small, but rapidly expanding, new transmission technology, ATM. It is instructive to look at this acquisition in some detail.

ATM was a new, cheaper non–router based technology that was very different from the packet-based router technology (Internet protocol) that IOS was built for. For ATM to work with Cisco equipment, IOS and ATM had to be made compatible. Integrating ATM into IOS meant a major change in Cisco’s leading industry platform.

Deciding what to do about ATM became a big strategic decision for Cisco. The main concern was that ATM might eventually displace significant pieces of Cisco’s own router-based technology. Customers were keen to get ATM into their networks, because it was a more cost-effective technology. Even though the major ATM players (including StrataCom) were still small, they were growing fast. Cisco concluded that ATM had the potential to derail its
plans to be the architect of the networking industry and felt it had to respond.

In terms of our model, Cisco had three main ways to respond to the ATM threat:

a. **Nonintegration without coordination.** Cisco could decide not to make IOS and ATM compatible and hope that ATM would not take hold. ATM's incompatibility with IOS would make it tough for ATM players to grow very large given IOS's significant customer base, but Cisco could face a risky and costly battle that it might lose.

b. **Nonintegration with coordination.** Cisco could make IOS and ATM compatible without a major acquisition such as the purchase of StrataCom. (Cisco had already bought Lightstream, a smaller ATM player, as a safety play, but this had worked out poorly, because of skeptical customer reception; Lightstream's size was too insignificant and customers were not sure that Cisco would support the technology in the long run—a valid concern, as it turns out.) This strategy would require Cisco to work with the leading ATM firms, making it much easier for ATM to grow and usurp Cisco's technology. In fact, three years earlier, Cisco had made an agreement with StrataCom and AT&T to collaborate on the definition of standards and the development of products for ATM, but evidently these efforts did not work out. (In the context of our model, this agreement is probably best interpreted as "nonintegration with cooperation."

c. **Integration with coordination.** Cisco could buy StrataCom (or some other major ATM player), make IOS and ATM compatible internally, and become an industry leader in the ATM market. This would support Cisco's ambitions to be the architect of the network industry. By holding the decision rights to both technologies, Cisco could determine how the two technologies should be integrated to provide a seamless customer experience and maximize overall surplus—much of which would flow into Cisco's pockets, of course, if it could win the platform game.

Cisco chose option c, the same strategy that it had successfully followed when the switching technology became a threat and it bought Crescendo. Cisco paid $4.7 billion for StrataCom—by far the most expensive acquisition that it had made until then and an incredibly high price for a start-up with modest earnings.
Nevertheless, Cisco’s stock price jumped 10% on the announcement of the deal. (It seems plausible that Cisco had the bargaining power in the acquisition—Cisco had several alternatives to StrataCom, whereas StrataCom had few alternatives to Cisco.)

How well does this case fit our model?

The value of the deal makes clear that significant joint benefits from coordination were anticipated. Integrating ATM and IOS seamlessly, and in a way that maximized the joint benefits of Cisco and StrataCom rather than those of the whole industry, would give Cisco and StrataCom a much better shot at winning the platform game. Next one has to ask whether coordination would have been feasible across the market. As noted in the description of option b, coordination across the market appeared difficult. We surmise that the reason was the reluctance of StrataCom, the dwarf in the relationship, to choose Y, because this would have tilted the playing field too much in favor of the giant Cisco. Arguably, option b failed because of an uneven split of the surplus, a key driver in our model.25

Our analysis emphasizes that private benefits also should be considered in making strategic decisions. Embracing the new ATM technology met with much internal resistance at Cisco, because Cisco had been “emphatically biased toward IP [technology]” (Bunnell 2000, p. 84). Also, Cisco’s sales force disliked ATM, because it was a less sophisticated, cheaper technology, which resulted in lower commissions (Bunnell 2000, p. 85). The private losses on StrataCom’s side were probably small, and there may even have been private gains (in contrast to (2)), given that StrataCom’s technology was adopted. One common reason that entrepreneurial firms sell out to a large player like Cisco (besides the money they get from selling their shares) is that access to a huge customer base brings their projects onto a large stage quickly, enhancing the private benefits enjoyed from the development and increased recognition of their product. Seeing their product succeed on a large scale can be a big source of satisfaction for entrepreneurs.

25. One possibility that we have not considered is that Cisco and StrataCom could have entered into some sort of profit sharing agreement to align incentives. Given that Cisco and StrataCom were both public companies at the time, profit sharing was obviously feasible. We ruled out profit sharing in our basic model by supposing that there is 100% diversion of monetary profit. In reality, profit sharing may not have been a very effective way of aligning the incentives of Cisco and StrataCom, because of the big difference in company size and substantial uncertainty about payoffs.
Cisco’s acquisition strategy, and the rules that Cisco used to select its favored partners, make clear that Cisco was sensitive to the issue of private benefits. Chambers’ five criteria for partners were these: a common vision; cultural compatibility; a quick win for the shareholders; a long-term win for all constituencies; and geographic proximity (Bunnell 2000, p. 65). Chambers also went to great length to avoid alienating employees of the acquired company, partly, we may assume, to minimize shading.26 His strategy was to allow acquired firms to stay as independent as possible within Cisco to retain the spirit of entrepreneurship. Typically, a newly acquired firm only had to make its products compatible with IOS and submit to the purchase and sales systems in Cisco. Otherwise it was largely free to pursue its own agenda. The commitment worked: Cisco had a reputation for being a benevolent, well-liked acquirer.

The Mario rule illustrates Chambers’ efforts to protect employees from the acquired company (Bunnell 2000, p. 37). The rule, named after the CEO of Crescendo, Mario Mazzola, stated that no employee of a newly acquired company could be terminated without the consent of Chambers and the CEO of the acquired company. We interpret the Mario rule as a form of delegation (regarding decision rights other than coordination). Interestingly, Cisco abandoned this rule after the dot-com crash in 2000, when it was forced to lay off thousands of employees because of the deep recession in the IT industry. Evidently, delegated rights are not as secure as ownership rights, but they are not valueless either, a distinction that fits our delegation model well.

It is worth asking whether traditional, holdup–based property rights theories fit the Cisco story as well or better than ours. In hold-up models as well as in our model, there is concern about being locked in and becoming unduly dependent on an outsider—for a service or a key element in one’s strategy. It is clear that there are hold-up concerns in this broad sense also in the Cisco–StrataCom deal. But we do think the essence of the deal was less about hold-ups in the sense of financial extraction—the hallmark of traditional hold-up models—and much more about the

26. Another important motive for not alienating employees is to prevent them from quitting. Employees may quit because they are disgruntled or because they have better prospects elsewhere, or for a combination of these reasons. Although quitting is not part of our formal model, it could be incorporated into a multiperiod version (see also footnote 22).
ability to control the path of the ATM-IOS integration and its successful development. This is supported by the whole rationale for Cisco’s acquisition strategy. In Chambers’s own words: “With a combination of IP (Internet protocol) routing and ATM we can define the Internet of the future” (Bunnell 2000, p. 88). Also, the five key criteria for acquisitions seem to have little to do with traditional hold-up stories, but they, together with the meticulous attention to employees in acquired firms, bear witness to the great significance of private benefits.

VI. CONCLUSIONS

In the traditional property rights model, asset ownership affects incentives to invest in human capital, but not ex post outcomes conditional on these investments. In our model, decision rights directly affect what happens ex post. Our structure is in many ways close to the traditional view of the firm as a technologically defined entity that makes decisions about inputs, outputs, and prices. The difference is that our firm does not necessarily maximize profits, either because a boss cares directly about non-transferable private benefits or because the boss is forced to internalize them given that employees can shade. It is this relatively small wrinkle in the traditional model that opens the door to a discussion of boundaries.

The aggrievement approach of Hart and Moore (2008) has two important benefits relative to models based on ex post noncontractibility. First, aggrievement plays a central role in explaining the need for an initial choice of ownership: without aggrievement costs (i.e., setting \( \theta = 0 \)), one could equally well choose the optimal ownership structure ex post. Second, in a dynamic model with uncertainty, one would expect to see continuous reallocations of decision rights in the absence of aggrievement. Aggrievement brings a natural source of inertia into dynamic models. That this source of inertia is empirically relevant is suggested by Cisco’s concern for cultural fit—reorganization can make employees aggrieved, sometimes so much that acquisitions will not happen.

Inertia is also what makes delegation distinct from ownership. How one allocates decision rights within the firm will make a difference. Firms do a lot of internal restructuring and many carry out major restructurings several times a decade in response to changes in their strategic situation. These restructurings have
powerful effects not only on how the organization operates, but also on how employees feel. Restructurings do not come without a cost. Our approach could be fruitful for analyzing internal organization and restructurings.

One of the features of our current model is that the outcome of integration does not depend on whether firm A takes over firm B or the other way around. But this is true only because of our assumption that the integrated firm is always run by a professional manager. As we discussed in Section III, this is not the only possibility. If firm A acquires firm B and the manager of firm A becomes the boss of the integrated firm the integrated firm's decisions and direction will undoubtedly reflect manager A's preferences, private benefits, and views of the world, and vice versa if the manager of firm B becomes the boss. Because a boss with skewed preferences is likely to take decisions that will cause grievement for employees with different preferences, our theory suggests that the cultural compatibility and fit of an acquisition partner may be of first-order importance, something that we saw in Section V is consistent with Cisco's strategy and experience.

Our model does not currently have workers. However, we could interpret a manager's private benefits as reflecting an alignment of preferences with the workers resulting either from shared interests or from a concern for the workers' well-being. To pursue this line further, it would be worthwhile thinking about what makes bosses biased toward their workers. One force is that sustained contact with workers fosters friendship and empathy. Wrestling with the same problems, sharing the same information, and having a similar professional background are all conducive to a common vision that aligns interests, particularly on issues such as the strategic direction of the firm. Shleifer and Summers (1988) argue that it may be an efficient long-run strategy for a firm to bring up or train prospective bosses to be committed to workers and other stakeholders (on this, see also Rotemberg and Saloner [1994, 2000]; Blair and Stout [1999]). Milgrom and Roberts (1988) argue that frequent interaction gives workers the opportunity to articulate their views and influence the minds of their bosses, sometimes to the detriment of the firm. All these explanations are consistent with our assumption that the boss of a firm with broad scope will put less weight on private benefits than the boss of a firm with narrow scope. With a broader range of activities, the firm's workforce will be more heterogeneous, making the boss experience less empathy for any given group. The intensity of
contact with any particular group will go down, reducing the ability of that group’s workers to influence the boss.27

Let us observe, finally, that giving private benefits a pivotal role in the analysis moves the focus of attention away from assets toward activities in the determination of firm boundaries. It is remarkable how few practitioners, organizational consultants, or researchers studying organizations within disciplines other than economics (e.g., sociology and organizational behavior) ever talk about firms in terms of asset ownership. For most of them a firm is defined by the things it does and the knowledge and capabilities it possesses. Coase (1988) makes clear that he too is looking for “a theory which concerns itself with the optimum distribution of activities, or functions, among firms” (p. 64). He goes on to say that “the costs of organizing an activity within any given firm depend on what other activities the firm is engaged in. A given set of activities will facilitate the carrying out of some activities but hinder the performance of others” (p. 63). The model we have proposed is in this spirit. In our analysis, asset ownership is the means for acquiring essential control rights, but the underlying reason that such control rights are acquired in the first place is that activities need to be brought together under the authority of one boss in order to accomplish strategic goals, such as sharing the same technological platform.

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27. Note that a boss who can divert less than 100% of profits for private gains will put relatively more weight on worker preferences in all cases discussed above.


