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THE JORDAN FORMS OF $AB$ AND $BA$*

ROSS A. LIPPERT† AND GILBERT STRANG‡

Abstract. The relationship between the Jordan forms of the matrix products $AB$ and $BA$ for some given $A$ and $B$ was first described by Harley Flanders in 1951. Their non-zero eigenvalues and non-singular Jordan structures are the same, but their singular Jordan block sizes can differ by 1. We present an elementary proof that owes its simplicity to a novel use of the Weyr characteristic.

Key words. Jordan form, Weyr characteristic, eigenvalues

AMS subject classifications. 15A21, 15A18

1. Introduction. Suppose $A$ and $B$ are $n \times n$ complex matrices, and suppose $A$ is invertible. Then $AB = A(BA)A^{-1}$. The matrices $AB$ and $BA$ are similar. They have the same eigenvalues with the same multiplicities, and more than that, they have the same Jordan form. This conclusion is equally true if $B$ is invertible.

If both $A$ and $B$ are singular (and square), a limiting argument involving $A + \epsilon I$ is useful. In this case $AB$ and $BA$ still have the same eigenvalues with the same multiplicities. What the argument does not prove (because it is not true) is that $AB$ is similar to $BA$. Their Jordan forms may be different, in the sizes of the blocks associated with the eigenvalue $\lambda = 0$. This paper studies that difference in the block sizes.

The block sizes can increase or decrease by 1. This is illustrated by an example in which $AB$ has Jordan blocks of sizes 2 and 1 while $BA$ has three 1 by 1 blocks. We could begin with Jordan matrices $A$ and $B$:

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

The product $AB$ is zero. The product $BA$ also has a triple zero eigenvalue but the

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† 123 West 92 Street #1, New York, NY 10025, USA (ross.lippert@gmail.com).
‡ MIT Department of Mathematics, 77 Massachusetts Avenue, Building Room 2-240, Cambridge, MA 02139, USA (gs@math.mit.edu).
rank is 1. In fact, $BA$ is in Jordan form:

$$BA = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

A different 3 by 3 example illustrates another possibility:

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

with

$$AB = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad BA = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Those examples show all the possible differences for $n = 3$, when $AB$ is nilpotent. More generally, we want to find every possible pair of Jordan forms for $AB$ and $BA$, for any $n \times m$ matrix $A$ and $m \times n$ matrix $B$ over an algebraically closed field. The solution to this problem, generalized to matrices over an arbitrary field, was given over 50 years ago by Harley Flanders [3], with subsequent generalizations and specializations [4, 6]. In this article, we give a novel elementary proof by using the Weyr characteristic.

2. The Weyr Characteristic. There are two dual descriptions of the Jordan block sizes for a specific eigenvalue. We can list the block dimensions $\sigma_i$ in decreasing order, giving the row lengths in Figure 2.1. This is the Segre characteristic. We can

![Fig. 2.1. A tableau representing the Jordan structure $J_4 \oplus J_4 \oplus J_2 \oplus J_1$.](image)

also list the column lengths $\omega_1, \omega_2, \ldots$ (they automatically come in decreasing order).
This is the Weyr characteristic. By convention, we define $\sigma_i$ and $\omega_i$ for all $i > 0$ by setting them to 0 for sufficiently large $i$. If we consider \{\sigma_i\} and \{\omega_i\} to be partitions of their common sum $n$, then they are conjugate partitions: $\sigma_i$ counts the number of $j$’s for which $\omega_j \geq i$ and vice versa. The relationship between conjugate partitions \{\sigma_i\} and \{\omega_i\} is compactly summarized by $\omega_{\sigma_i} \geq i > \omega_{\sigma_{i+1}}$ (or by $\sigma_{\omega_i} \geq i > \sigma_{\omega_{i+1}}$), the first inequality making sense only when $\sigma_i > 0$. Tying the two descriptions to linear algebra is the nullity index $\nu_j$:

$$\nu_j(A) = \dim \text{Null}(A^j) = \text{dimension of the nullspace of } A^j \quad \text{(with } \nu_0(A) = 0).$$

Thus $\nu_j$ counts the number of generalized eigenvectors for $\lambda = 0$ with height $j$ or less. In the example in Figure 2.1, $\nu_0, \ldots, \nu_5$ are 0, 4, 7, 9, 11. Then $\omega_j = \nu_j - \nu_{j-1}$ counts the number of Jordan blocks of size $i$ or greater for $\lambda = 0$. Further exposition of the Weyr characteristic can be found in [5] and some geometric applications in [1, 2].

Our main theorem is captured in the statement that $\omega_i(AB) \geq \omega_{i+1}(AB)$. Reversing $A$ and $B$ gives a parallel inequality that we re-index as $\omega_{i-1}(AB) \geq \omega_i(AB)$. This observation, although in different terms, was central to the original proof by Flanders [3].

**Theorem 2.1.** Let $F$ be an algebraically closed field. Given $A, B \in F^{n \times m}$, the non-singular Jordan blocks of $AB$ and $BA$ have matching sizes, i.e., their Weyr characteristics are equal:

$$\omega_i(AB - \lambda I) = \omega_i(BA - \lambda I) \quad \text{for } \lambda \neq 0 \text{ and all } i. \quad (2.1)$$

For the eigenvalue $\lambda = 0$, the Jordan forms of $AB$ and $BA$ have Weyr characteristics that satisfy

$$\omega_{i-1}(AB) \geq \omega_i(AB) \geq \omega_{i+1}(AB) \quad \text{for all } i, \quad (2.2)$$

which is equivalent to

$$|\sigma_i(AB) - \sigma_i(BA)| \leq 1 \quad \text{for all } i. \quad (2.3)$$

If $P \in F^{n \times n}$ and $Q \in F^{m \times m}$ satisfy $\omega_i(P - \lambda I) = \omega_i(Q - \lambda I)$ for $\lambda \neq 0$ and $\omega_{i-1}(P) \leq \omega_i(Q) \leq \omega_{i+1}(P)$, then there exist $A, B^t \in F^{n \times m}$ such that $P = AB$ and $Q = BA$.

The equivalence of (2.2) and (2.3) is purely a combinatorial property of conjugate partitions (see Lemma 3.2).

The Jordan block sizes are hence restricted to change by at most 1 for $\lambda = 0$. Taking Figure 2.1 as the Jordan structure of $AB$ at $\lambda = 0$, Figure 2.2 is an admissible modification (by + and −) for $BA$. 

If $\text{AB}$ is nilpotent with Jordan structure $J_4 \oplus J_4 \oplus J_2 \oplus J_1$, then a permitted $BA$ structure is $J_3 \oplus J_3 \oplus J_2 \oplus J_2 \oplus J_1$.

3. Main results. Our results are ultimately derived from the associativity of matrix multiplication. A typical example is $B(AB \cdots AB) = (BA \cdots BA)B$.

**Theorem 3.1.** If $A$ and $B^t$ are $n \times m$ matrices over a field $\mathbb{F}$, then for all $i > 0$

$$\omega_i(AB - \lambda I) = \omega_i(BA - \lambda I) \quad \text{for } \lambda \in \mathbb{F} - \{0\}$$

$$\omega_i(BA) \geq \omega_{i+1}(AB) \quad \text{(for } \lambda = 0).$$

**Proof.** (For $\lambda \neq 0$) For any polynomial $p(x)$, $p(BA)B = Bp(AB)$. Thus $p(AB)v = 0$ implies $p(BA)Bv = 0$. Since $Bv = 0$ implies $p(AB)v = p(0)v$, we have $\dim \text{Null}(p(AB)) = \dim \text{Null}(p(BA))$ when $p(0) \neq 0$. Hence $\nu_i(AB - \lambda I) = \nu_i(BA - \lambda I)$ when $\lambda \neq 0$.

(For $\lambda = 0$) We define the following nullspaces for $i \geq 0$:

$$\mathcal{R}_i = \{v \in \mathbb{F}^n : B(AB)^i v = 0\}$$

$$\mathcal{R}'_i = \{v \in \mathbb{F}^n : (AB)^i v = 0\}$$

$$\mathcal{L}_i = \{v \in \mathbb{F}^m : v^t (BA)^i = 0\}$$

$$\mathcal{L}'_i = \{v \in \mathbb{F}^m : v^t (BA)^i B = 0\}$$

We see that $\mathcal{R}_i \subset \mathcal{R}'_{i+1}$ and $\mathcal{L}_i \subset \mathcal{L}'_{i+1}$, and $\dim \{\mathcal{R}_{i+1}\} - \dim \{\mathcal{R}_i\} = \dim \{\mathcal{L}'_{i+1}\} - \dim \{\mathcal{L}'_i\}$.

Let $v_1, \ldots, v_k \in \mathcal{R}'_{i+2}$ be a set of vectors that are linearly independent modulo $\mathcal{R}_{i+1}$. Thus $\sum_{i=1}^k c_i v_i \in \mathcal{R}_{i+1}$ only if $c_1 = \cdots = c_k = 0$. Then the vectors
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**Fig. 3.1.** A tableau representing the Jordan structure $\sigma_i = (10, 10, 7, 4, 3, 3, 1, 1, 0, \ldots)$, with Weyr characteristic $\omega_i = (9, 6, 6, 4, 3, 3, 2, 2, 2, 0, \ldots)$.

$ABv_1, \ldots, ABv_k \in R_{i+1}'$ are linearly independent modulo $R_i$. Thus, $\dim \{R_{i+1}'/R_i\} \geq \dim \{R_{i+2}'/R_{i+1}\}$. If $v_1, \ldots, v_k \in L_{i+2}'$ is a set of vectors, linearly independent modulo $L_{i+1}$, then the vectors $(BA)^tv_1, \ldots, (BA)^tv_k \in L_{i+1}'$ are linearly independent modulo $L_i$. Thus, $\dim \{L_{i+1}'/L_i\} \geq \dim \{L_{i+2}'/L_{i+1}\}$. Notice that

$$\dim \{R_{i+2}'/R_{i+1}\} = \nu_{i+2}(AB) - \dim \{R_{i+1}\}$$
$$\dim \{L_{i+2}'/L_{i+1}\} = \dim \{L_{i+2}'\} - \nu_{i+1}(BA).$$

Then $\dim \{R_{i+1}'/R_i\} \geq \dim \{R_{i+2}'/R_{i+1}\}$ implies

$$\dim \{R_{i+2}\} - \dim \{R_{i+1}\} \geq \nu_{i+2}(AB) - \nu_{i+1}(AB)$$

and $\dim \{L_{i+1}'/L_i\} \geq \dim \{L_{i+2}'/L_{i+1}\}$ implies

$$\nu_{i+1}(BA) - \nu_i(BA) \geq \dim \{L_{i+2}'\} - \dim \{L_{i+1}'\}.$$

Therefore, $\omega_{i+1}(BA) \geq \omega_{i+2}(AB)$, since $\omega_{i+1} = \nu_{i+1} - \nu_i$.

The first part of Theorem 3.1 says that the Jordan structures of $AB$ and $BA$ for $\lambda \neq 0$ are identical, if $F$ is algebraically closed. For a general field, the results can be adapted to show that the elementary divisors of $AB$ and $BA$, that do not have zero as a root, are the same. An illustration is helpful in understanding the constraints implied by the second part, $\omega_{i-1}(AB) \geq \omega_i(BA) \geq \omega_{i+1}(AB)$. Suppose the tableau in Figure 3.1 represents the Jordan form of $AB$ at $\lambda = 0$. Theorem 3.1 constrains the tableau of the Jordan form of $BA$ at $\lambda = 0$ to be that of $AB$ plus or minus the areas covered by the circles of Figure 3.2.

The constraints on Weyr characteristics are equivalent to constraining the block sizes of the Jordan forms of $AB$ and $BA$ to differ by no more than 1. Although this
Fig. 3.2. Given $AB$ (boxes), Theorem 3.1 imposes these constraints on the Weyr characteristic of $BA$ (a circle can be added or subtracted from each row of the tableau): $\omega_1 \geq 6,9 \geq \omega_2 \geq 6,6 \geq \omega_3 \geq 4,6 \geq \omega_4 \geq 3,4 \geq \omega_5 \geq 3,6 \geq \omega_6 \geq 2,3 \geq \omega_7 \geq 2,2 \geq \omega_8 \geq 0,2 \geq \omega_9 \geq 0.$

equivalence “is not hard to see” [3] from Figure 3.1, it warrants a short proof. Taking $d = 1$, Lemma 3.2 establishes the equivalence of (2.2) and (2.3).

**Lemma 3.2.** Let $p_1 \geq p_2 \geq \cdots$ and $p'_1 \geq p'_2 \geq \cdots$ be partitions of $n$ and $n'$ with conjugate partitions $q_1 \geq q_2 \geq \cdots$ and $q'_1 \geq q'_2 \geq \cdots$. Let $d \in \mathbb{N}$. Then

$q'_i \geq q_{i+d}$ and $q_i \geq q'_{i+d}$ for all $i > 0$ if and only if $|p_i - p'_i| \leq d$ for all $i > 0$.

**Proof.** If $p'_i > d$, then $q'_{p'_i} \geq i > q_{p_i+1}$ by the conjugacy conditions. By hypothesis, $q_{p'_i - d} \geq q'_{p'_i} > q_{p_i+1}$ and thus $p'_i - d < p_i + 1$ since $q_j$ is monotonically decreasing in $j$. Thus $p'_i \leq p_i + d$ (trivially true when $p'_i \leq d$). By a symmetric argument (switching primed and unprimed), we have $p_i \leq p'_i + d$.

Conversely, if $q_{i+d} > 0$, then $p'_{q_{i+d}} \geq p_{q_{i+d}} - d \geq (i + d) - d = i > p'_{q'_i+1}$, the first inequality by hypothesis and the next two by the conjugacy conditions. Since $p'_j$ is monotonically decreasing, we have $q_{i+d} < q'_i + 1$, and thus $q_{i+d} \leq q'_i$ for all $i > 0$ (trivially true when $q_{i+d} = 0$). A symmetric argument gives $q'_{i+d} \leq q_i$. □

What remains is to show that the constraints in Theorem 3.1 are exhaustive; we can construct matrices $A, B$ that realize all the possibilities of the theorem. Here we find it easier to use the traditional Segre characteristic of block sizes $\sigma_i$:

**Theorem 3.3.** Let $\sigma_1 \geq \sigma_2 \geq \cdots$ and $\sigma'_1 \geq \sigma'_2 \geq \cdots$ be partitions of $n$ and $m$ respectively.

If $|\sigma_i - \sigma'_i| \leq 1$, then there exist $n \times m$ matrices $A$ and $B^t$ such that $\sigma_j(AB) = \sigma_j$ and $\sigma_j(BA) = \sigma'_j$. 
Proof. For each $j$ such that $\sigma_j$ and $\sigma_j'$ $\geq 1$, we construct $\sigma_j \times \sigma_j'$ matrices $A_j$ and $B_j'$ such that $A_jB_j = J_{\sigma_j}(0)$ and $B_jA_j = J_{\sigma_j'}(0)$ according to these three cases:

1. $\sigma_j = \sigma_j'$; set $A_j = J_{\sigma_j}(0)$ and $B_j = I_{\sigma_j}$,
2. $\sigma_j + 1 = \sigma_j'$; set $A_j = [0 \ I_{\sigma_j}]$ and $B_j = \begin{bmatrix} I_{\sigma_j'} \\ 0 \end{bmatrix}$,
3. $\sigma_j = \sigma_j' + 1$; set $A_j = \begin{bmatrix} I_{\sigma_j'} \\ 0 \end{bmatrix}$ and $B_j = [0 \ I_{\sigma_j'}]$.

This defines $k = \min \{\omega_1(AB), \omega_1(BA)\}$ matrix pairs $(A_j, B_j)$. Consider $\{\sigma_j\}$ as a partition for $n$ rows and $\{\sigma_j'\}$ as a partition for $m$ columns. Construct the block diagonal matrix $A = \text{diag}(A_1, \ldots, A_k, 0, \ldots, 0)$ with zeros filling any remaining lower right part. Then with partitions $\{\sigma_j'\}$ for $m$ rows and $\{\sigma_j\}$ for $n$ columns let $B = \text{diag}(B_1, \ldots, B_k, 0, \ldots, 0)$.

The final construction merely stitches together a singular piece with a non-singular piece.

**Corollary 3.4.** Let $P \in \mathbb{F}^{n \times n}$ and $Q \in \mathbb{F}^{m \times m}$ have Segre characteristics $\sigma^\lambda_i$ and $\sigma^\lambda_i'$ for each eigenvalue $\lambda$, i.e.,

$$P \sim \bigoplus_{\lambda \in \mathbb{F}} \bigoplus_{i>0} J_{\sigma^\lambda_i}(\lambda) \text{ and } Q \sim \bigoplus_{\lambda \in \mathbb{F}} \bigoplus_{i>0} J_{\sigma^\lambda_i'}(\lambda).$$

If $\sigma^\lambda_i = \sigma^\lambda_i'$ for all $\lambda \neq 0$ and $|\sigma^0_i - \sigma^0_i'| \leq 1$, then there exist matrices $A$ and $B'$ in $\mathbb{F}^{n \times m}$ such that $P = AB$ and $Q = BA$.

**Proof.** If $\tilde{P} = X^{-1}PX$ and $\tilde{Q} = Y^{-1}QY$ are in canonical form with $\tilde{P} = \tilde{A}\tilde{B}$ and $\tilde{Q} = \tilde{B}\tilde{A}$, then setting $A = XAY^{-1}$ and $B = YBX^{-1}$, we have $P = AB$ and $Q = BA$. Hence we take $P$ and $Q$ to be in canonical form.

Let $M = \bigoplus_{\lambda \neq 0} \bigoplus_{i>0} J_{\sigma_i}(\lambda)$, i.e., $M$ is a (non-singular) $k \times k$ matrix in Jordan canonical form with Segre characteristic $\sigma^\lambda_i$, where $k = \sum_{\lambda \neq 0} \sum_{i}\sigma^\lambda_i$. Let $A_0$ and $B_0$ be the $A$ and $B$ matrices from Theorem 3.3 with $\sigma_i = \sigma^0_i$ and $\sigma_i' = \sigma^0_i$. Then $A = M \oplus A_0$ and $B = I_k \oplus B_0$.

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