The Oceanic Variability Spectrum and Transport Trends

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Abstract
Oceanic meridional transports evaluated over the width of the Pacific Ocean from altimetric observations become incoherent surprisingly rapidly with meridional separation. Even with 15 years of data, surface slopes show no significant coherence beyond 5° of latitude separation at any frequency. An analysis of the frequency/zonal-wavenumber spectral density shows a broad continuum of motions at all time and space scales, with a significant excess of energy along a “non-dispersive” line extending between the simple barotropic and first baroclinic mode Rossby waves. It is speculated that much of that excess energy lies with coupled barotropic and first mode Rossby waves. The statistical significance of apparent oceanic transport trends depends upon the existence of a reliable frequency/wavenumber spectrum and for which only a few observational elements now exist.

1 Introduction
A quantitative description of oceanic variability is useful for a number of reasons including the detection of climate trends, the testing of oceanic GCMs, and the identification and understanding of basic physical mechanisms in the ocean circulation. In particular, detection of supposed trends in the ocean circulation is now the subject of impressive expenditures (Schiermeier, 2004), and the interest of a large community worried about climate change (e.g., IPCC, 2007). A growing literature is accumulating around the goal of detecting oceanic trends, some of which is aimed at “early warning” of abrupt climate shifts. But the ocean is a very noisy place with variability on all time and space scales and with very long intrinsic memory (e.g., Peacock and Maltrud, 2006; Wunsch and Heimbach, 2008). Because of the long memory, most oceanographic time series display some form of apparent trend and the main issue is assigning a confidence
interval to the result to distinguish it from the random-walk behavior always present in long
time-scale systems (e.g., Percival et al., 2001). Determination of the significance of true trends
involves a deep understanding of the nature of oceanic variability generally. (Here, a “true
trend” is defined as one that would persist for several multiples of the data duration.) The goal
of understanding the apparent fluctuations in meridional volume transports as determined from
sea level variations is used to motivate a discussion of the nature of altimetric data sets. Trends
in sea level variations are of intense interest in their own right, but are not directly pursued here
(but see Wunsch et al., 2007 for discussion and references).

2 Altimetric Velocities and Transports

The longest observed time series available with near-global coverage are the high accuracy al-
timetry records that became available with the TOPEX-POSEIDON satellite beginning at the
end of 1992, providing (at the time of writing) about 15 years of usable data. We here briefly
describe the way in which altimetric data can be used to make some inferences about transport
variability and their link to the problem of trend determination. In practice, one seeks (Wunsch
and Heimbach, 2009) to combine the altimetric data with all available oceanographic data, but
the domination of the calculations by the volume of satellite data suggests the utility of the
present focus.

The major issue, and the one that provides the theme for what follows later, is that altimetry
produces estimates of the sea surface slope and hence of the surface geostrophic flow (to a high
degree of approximation) and discussions of climate variables require inferences about the entire
water column. Altimetry is only readily interpreted in volume (or mass) transport terms to the
extent that the surface geostrophic flow is primarily controlled by, or controls, a known vertical
structure. To interpret the results here, the approximation in Wunsch (1997) will be employed:
that the surface kinetic energy is dominantly that of the first baroclinic mode. The expression
“transport” is then used as a short-hand for the approximate volume transport in the first
baroclinic mode above some arbitrary depth, possibly it zero crossing near 1000m as used
in Wunsch (2008). The reader is strongly cautioned, however, that as depicted in Wunsch (1997),
and as discussed below, water column variability is dominated in many, if not most, places
by the barotropic flow—and which is sometimes wholly omitted from theoretical discussions.
Here the terminology “barotropic” is used to denote the projection onto a vertically constant
horizontal velocity as determined e.g., from a flat-bottom linear dynamics ocean. Lapeyre and
Klein (2006), have shown that there can exist near-surface trapped balanced motions owing
to a finite buoyancy flux through the sea surface. In the linear limit, these are the trapped,
forced, modes reviewed e.g., by Philander (1978). Motions not consistent with free modes can exist because they are externally forced, or because turbulent cascades generate them through nonlinear interactions. But at the present time, little observational data exists indicating their importance—other than the altimetric spectral densities—and these surface-trapped motions are ignored in what follows.)

Let $\eta(x, y, t)$ be the surface elevation at any lateral point $x, y$, and let $\Delta \eta(y, t)$ be the difference $\eta(x + L, y, t) - \eta(x, y, t)$. If the vertical structure of a geostrophic flow field, $V(z)$, is known, then the total transport of volume or mass above any depth $z_1$, is readily computed as,

$$T(y, t) = \frac{g}{f} \Delta \eta(y, t) L \int_{z_1}^{\eta} V(z) \, dz = \frac{g}{f} \Delta \eta(y, t) \int_{z_1}^{\eta} V(z) \, dz$$  \hspace{1cm} (1) \hspace{1cm} \{\text{transport1}\}

independent of $L$, as long as bottom topography does not intervene over the distance $L$. We now explore the consequences of this relationship, for illustration purposes, in the region shown in Fig. 1 and which occupies a large region of the subtropical gyre of the North Pacific Ocean. The western side is under the influence of the Kuroshio and its extension, while the eastern side might be regarded as typical of an oceanic interior. Pacific data are used here simply because they permit use of the largest distances and thus perhaps show the strongest spatial coherences.

Suppose now that the simplification is made that the water column structure $V(z) \propto F_1(z)$
where $F_1 (z)$ is the first flat-bottomed baroclinic mode (Fig. 2), which has a zero crossing above about 1400m (the shape is a slowly changing function of position). Consider the AVISO gridded altimeter data (see Le Traon et al., 1998, for a discussion), at weekly intervals at the four corners of the box shown in 1. The time series for the altimetric heights, are shown in Fig. 3 and Fig. 4 displays their power densities. The latter have a general red noise character, becoming nearly white at periods longer than about 3 years. Records from the northern limit of the box show a weak annual cycle as indicated in the figure.

Visually there is little resemblance among the time series. Of more immediate interest is the coherence related to the meridional volume transport. Fig. 5 shows the coherence of $\Delta \eta$ over the box width at meridional separations of $1^\circ, 3^\circ, 5^\circ, ..$ of latitude relative to the box southern boundary. With a latitudinal separation of 1 degree, there is a high coherence, although not uniformly, down to periods as short as about 100 days. By three degrees of latitudinal separation, there is no statistically significant coherence at 95% confidence until periods of almost three years are reached. At five degrees of meridional separation, even 15 years of data produces no apparent coherence and what coherence there is would account for a very small fraction of the total variance.

These results are an extension to a much longer space scale of the results sketched by Wunsch (2008) who suggested that many decades would be required to obtain results indicative of circulation trends in the large-scale ocean circulation. (H. Johnson and D. Marshall, personal communication, 2009, have suggested that eddy noise might be substantially reduced as one approaches the western boundary. Although that is possibly true for the North Atlantic near $25^\circ N$, the present results apply to the open ocean, and the increase of energy toward the west, which is apparent in the power density spectra of Fig. 4, is consistent with expectations of the most elementary physics.)

The incoherence seen in Fig. 5 is not a consequence of the presence of the Kuroshio. Fig. 6 shows the coherence estimate for a 12-degree meridional separation using only the data east of the dashed line in Fig. 1. Thus even in the reduced eddy energy region, there is no useful coherence at $12^\circ$ latitudinal separation after 15 years. Whatever large-scale trends are present in the circulation are invisible here.

3 Frequency-Wavenumber Spectra

The lack of large-scale coherence and the general dominance of the spectra by low frequencies raises the question of the nature of the variability making up the altimetric records, and attention is now turned toward obtaining a partial understanding. One useful quantitative descriptor
Figure 2: Shapes of the first 3-modes ($n = 0, ..., 2$) at longitude $\lambda = 220^\circ$E for horizontal velocity or pressure (left panel) and vertical displacement (right panel). Vertical displacements in the barotropic mode are linear with depth (increasing upwards), but much too small to be visible in the plot. Note that the surface boundary condition here precludes a buoyancy disturbance there—an issue of concern in a different context.

Figure 3: Upper panel is the altimetric height at the southeast (solid) and northeast (dashed) corners of the box, and lower panel shows them for the southwest (solid) and northwest (dashed) corners. That there is little visual coherence is apparent.
of oceanic variability is its frequency/wavenumber spectrum. Such a description, although incomplete because of the strong spatial inhomogeneity, is an essential element in determining the significance of apparent trends and other low frequency variations, and its reproduction is a central test of skill in a general circulation model. Zang and Wunsch (2001, hereafter ZW2001) made an attempt to synthesize such a description from the data then available to them. A specific analogy to the original strawman internal wave model of Garrett and Munk (1972) was intended. The result assumed a restricted form of velocity component isotropy and did not represent the known anisotropic propagation of disturbances preferentially to the west. This supposedly universal form was spatially modulated by a complicated function of latitude and longitude independent of $k, s$. The present paper discusses some of the elements needed in future attempts at an improved synthesis.

Since the ZW2001 work, the high accuracy altimetric record has been extended from the four years available to them, to 15 years (at the time of writing) and this extended record opens the possibility of a more refined result. One element of the data—its representation of the altimetric data as showing “too-fast” Rossby waves (Chelton and Schlax, 1996)—received a remarkable degree of theoretical attention, notwithstanding its subsequent repudiation by Chelton et al. (2007). The latter authors concluded that there is no evidence for linear Rossby waves (D.
Figure 5: Coherence estimate of the apparent transport between the eastern and western sides of the box at separations of $1^\circ, 3^\circ, 5^\circ$ meridional separation. At $5^\circ$ separation there is no apparent coherence even with 15 years of data and results for larger separations are not shown. (A multitaper coherence estimate. An approximate level-of-no-significance at 95% confidence is shown as the horizontal line.) Phases are not statistically meaningful when the amplitude is below the level-of-no-significance, and are thus not shown for separations beyond $3^\circ$ latitude separation.
Figure 6: As in Fig. 5 except over 12 degrees meridional separation with the east-west separation taken from the center of the box to the eastern boundary. There is no significant coherence at any frequency at this separation.

Chelton, private communication, 2009). Furthermore, the issue of the vertical structure, which was the focus of the mooring study of Wunsch (1997), has been put into context by theoretical and modeling studies (e.g., Smith and Vallis, 2001; Scott and Arbic, 2007; Ferrari and Wunsch, 2009) of the existence of both up- and down-scale cascades in oceanic balanced motions. These discussions and debates have consequences for an improved representation of the frequency-wavenumber spectrum and ultimately its use in discussions of trend determination. Altimetric data now exceed in duration almost all oceanographic data sets and represent the only near-global dynamically relevant measurements that we have. Thus their understanding is in turn central to understanding of ocean circulation variability and the particular problem of trend determination. The present analysis is not comprehensive, but is intended to call attention to some of the issues in understanding the mid-latitude variability producing the incoherent results of the previous section.

Visual displays of the altimetric behavior in time and longitude (e.g., Fig. 7) show striking westward propagation of patterns and usually interpreted as Rossby waves. Chelton and Schlax (1996) interpreted the visual phase lines as linear, first baroclinic mode Rossby waves and showed that their apparent phase velocity tended to be higher than the theory predicted.

It is worth listing the major assumptions underlying what it is reasonable to call the “basic textbook theory” (BTT)\(^1\) that was being compared to the observations. Those assumptions

\(^1\)The long history of Rossby waves is summarized by Platzman (1968).
Figure 7: Longitude/time diagram for sea surface elevation, $\eta$, (cms) at latitude 29.25°N in the area in
Fig. 1, confined to the east of the obvious Kuroshio extension. The westward phase propagation is
visually dominant and important, but raises the question of how much of the variability is not described
by these non-dispersive waves.

constitute a model of an ocean that:

1. has a flat bottom
2. has horizontally uniform stratification
3. is otherwise at rest
4. is represented by a tangent plane approximation to a sphere (the $\beta$–plane)
5. is unforced
6. has completely linear dynamics
7. is laterally unbounded

This list is not complete (e.g., the Boussinesq approximation is also made). Of course, none
of these assumptions is strictly correct and that the BTT works as well as it seems to is perhaps
the real surprise.

Consider, as an example, the region shown in Fig. 1, the eastern side of the box used above
to discuss the transport variability. The region is a representative one (to the extent that any
ocean region can be so described), at least of the subtropical gyres. The data are again the
gridded fields provided by AVISO and smoothed using the algorithm of Le Traon et al. (1998).
Smoothing and gridding change the spectral content of a data set, but in the present case are
not believed to introduce any significant distortion. Fig. 7 displays a time-longitude diagram
for surface elevation, $\eta(x,y,c,t)$ along latitude 29.25°N in the box. The human eye evolved into
an extremely powerful instrument for pattern detection, and which one here sees very clearly as
the westward propagation in Fig. 7. The eye is not, however, very good at producing estimates
of the other motions present—motions that produce less marked patterns. Zang and Wunsch
(1999) using Fourier methods to separate different frequencies and wavenumbers, concluded that
at the longest wavelengths and lowest frequencies, with about 40% of the observed variance, the
motions had structures in frequency/wavenumber space indistinguishable from the BTT. As
the wavenumber and frequency magnitudes increased, significant deviations from the BTT were
plainly present—as Chelton and Schlax (1996) had pointed out. The results appeared to apply
at all low and mid-latitudes of the North Pacific that they examined.

A full quantitative oceanic description, however, attempts to break the motions down by
frequencies and wavenumbers, separates eastward/westward and northward/southward propa-
gation and distinguishes motions consistent with elementary theory from those requiring more
complicated explanation. (Chelton and Schlax (1996) and several others (e.g. Lecointre et al.,
2008—a model study) have used a so-called Radon transform to determine the dominant phase
velocity in these data. The Radon transform, perhaps best known in its tomographic appli-
cations (see Rowland, 1979), is computed by integrating the field along all straight pathways
defined along all angles in data fields such as in Fig. 7. One can then find those path angles
which maximize the integral and use them used to define the signal phase velocity. All fre-
quencies and wavenumbers contributing to the dominant phase velocity are lumped together.
Of equal interest, however, is knowledge of the fraction of the total energy accounted for by
that phase velocity band. Because the Radon transform can be converted into a Fourier trans-
form (e.g., Rowland, 1979) its information content is no more nor less than that of the Fourier
approach used here. The information content of the Fourier transform is complete—as is the
Radon transform if the integrals along all pathways are provided. Information by frequency and
wavenumber band has typically proved enlightening in wave propagation problems, even those
containing important nonlinearities.)

Another consideration worth keeping in mind is that phase velocity structures in observed
fields are commonly not fundamental physical properties of the motions. The best known dis-
cussion of the problem is probably that by A. Sommerfeld and L. Brillouin who showed that
electromagnetic phase velocities exceeding the speed of light were not a contradiction to special
relativity. Rather it was the group velocity, which has physical meaning as the rate and direction
with which energy and information flow, that remained fundamental (see Brillouin, 1960, for an
extended discussion). In a general context, phase lines are kinematic interference patterns and
so subject to distortion by a wide variety of phenomena including boundary positions. So for
example, Frankignoul et al. (1997) point out that introducing an eastern wall in the presence of
Figure 8: Frequency (cycles/day) and zonal wavenumber (cycles/km) along the southern edge of the box. Left panel is from the two-dimensional periodogram plotted on a linear power scale, smoothed in frequency and wavenumber so as to be $\chi^2$ variables with about 8 degrees of freedom in each estimate (averaged over two frequencies and two wavenumbers). Right panel displays the logarithm of the power.

Dashed curves indicate the first baroclinic mode, $l=0$, basic dispersion curve. The “non-dispersive line” defined in the text lies along the ridge of maximum energy density and closely approximated by the dotted white line (slope is 4km/day).

BTT Rossby waves immediately produces naively-determined zonal phase velocities that are a factor of two larger than the BTT dispersion relationship. A full Fourier procedure, as we use, that accounts for standing wave components would not display such a discrepancy.

Figure 8 shows the estimated frequency-wavenumber spectra, $\Phi(k,s)$ for a fixed latitude ($27^\circ$ — the southern edge of the area) from a mildly smoothed (over two frequency and two wavenumber bands). The dispersion curves are shown for the barotropic, and lowest vertical baroclinic mode with $l=0$, and a first mode having a deformation radius, $R_d = 35\text{km}$. Consistent with the result of Zang and Wunsch (1999, their Figs. 4, 5), at the very lowest observable frequencies and wavenumbers, the energy maximum is indistinguishable from the dispersion curve. With increasing frequency (and corresponding wavenumber), deviations from the curve are seen, as pointed out by Chelton and Schlax (1998). Consistency with the dispersion curve of the BTT does not prove that those low frequency motions are BTT Rossby waves, but does remove the main evidence that they are incompatible with it. For larger magnitude frequencies and wavenumbers, the deviation is quite marked, with higher apparent phase and group veloc-
ities and phase velocities tending toward the much higher values predicted for the barotropic mode.

The energy maximum lying approximately along the straight line $\gamma k + s = 0$, $\gamma \approx 4$km/d is quite striking and as it implies non-dispersive motions, we will call it the “non-dispersive line”. It reaches all the way from the lowest estimated frequency to the barotropic dispersion curve. As in Zang and Wunsch (1999), $\gamma$ is approximately the long-wavelength (non-dispersive limit) group velocity of the first baroclinic mode. They found it to be universally present in all the areas they analyzed. No theory has so-far explained this striking characteristic of oceanic variability. Note, however, that the peak at the annual cycle is indistinguishable from $k = 0$.

Whether the non-dispersive line is truly tangent to the baroclinic dispersion curve as $s \to 0$ is not clear and as the period approaches infinity, many physical complications can ensue. From the results of Longuet-Higgins (1964), one might have anticipated an energy maximum where the zonal group velocity of the first baroclinic mode vanishes, where $\partial s/\partial k = 0$ (in analogy to the arguments of Wunsch and Gill, 1976, for the equatorially trapped gravity modes), but there is no obvious evidence for such a structure here.

It is, of course, possible that a much stronger effective $\beta$, arising from the background potential vorticity gradient (e.g., Killworth et al., 1997), would push the non-dispersive, low wavenumber end of the first baroclinic mode dispersion curve to much higher values. That the non-dispersive line touches the barotropic dispersion curve—implies a very large increase in effective $\beta$, and the general evidence, taken up below, of vertical structures involving strongly coupled barotropic and baroclinic modes. Note that the zonal mean surface velocity over the entire area is about 0.05cm/s and its RMS is about 0.2cm/s and so unlikely to cause first-order distortions in the dispersion relation. (It is important to recall, however, that the gridded altimetric data are smoothed, and thus will tend to underestimate the RMS velocity field. Time means are also subject to errors in the estimated geoid.)

Some measure of the relative importance of the energy lying along the non-dispersive line is obtained by finding the cumulative sum over $k$, for each frequency, $s$, and normalizing it by the total:

$$C(k, s) = \frac{\int_{-k_{\text{max}}}^{k} \Phi(k, s) \, ds}{\int_{-k_{\text{max}}}^{k_{\text{max}}} \Phi(k, s) \, ds}$$

and which is plotted in Fig. 13 as a function of $k$ for various values of $s$. At low frequencies, where the motions are indistinguishable from BTT Rossby waves, the non-dispersive line is the major fraction of the energy; at high frequencies, it has disappeared altogether as a noticeable feature. Thus at periods shorter than about 100 days, the unstructured spectral model of ZW2001 is reasonably accurate, but it fails to account for the excess non-dispersive motions at
Figure 9: Upper panel shows the values for three values of $s$ in cycles/day of the smoothed estimated power spectral density displayed in Fig. 8 and the lower panel shows the accumulating sum. Frequency separation is logarithmic between $s = 0$ and $s = 0.2$. The energy excess on the non-dispersive line is seen as a large near-jump in the integrated values. At the lowest frequencies, the neighborhood of the non-dispersive line contains about 80% of the energy, falling to an undetectable excess about the background at the highest frequencies (the accumulating sum is there nearly linear). All values were normalized so that the sum of the power over $k$ at fixed $s$ is unity. Most of the low frequency energy is westward going, becoming more nearly equipartitioned at the highest frequencies.

If the frequencies and wavenumbers are summed out, one obtains the zonal wavenumber, $\Phi_k(k)$, and frequency, $\Phi_s(s)$. That is,

$$
\int_0^\infty \Phi(k, s) \, ds = \Phi_k(k), \quad (2) \quad \text{analyt1}
$$

$$
\int_{-\infty}^\infty \Phi(k, s) \, dk = \Phi_s(s). \quad (3) \quad \text{analyt2}
$$

shown in Fig. 10. $\Phi_k$ shows the strong $k^{-4}$ roll-off noted by Stammer (1997) on spatial scales shorter than about 500km. (ZW2001 used $k^{-5/2}$ above 1/400km.) In this particular region, the eastward-going variance is about 29% of the total, and its wavenumber spectrum has a different, near power-law, rednoise behavior. Because Stammer (1997) used along-track data, the rapid roll-of is not a consequence of the mapping (smoothing) methodology employed at AVISO. The frequency spectrum here falls at a rate closer to $s^{-3}$ than the $s^{-2}$ value used by ZW2001 which, however, included the more energetic western part of the ocean. At low frequencies, a fit excluding the annual peak gives a power law close to $s^{-0.3}$, roughly consistent with ZW2001.

Fig. 11 is a time-latitude diagram. Visually, the pattern is much more like a standing wave, although the amplitude modulation with latitude shows that wavenumbers other than $l = 0$ must be involved and they must be phase-locked. In the discussion of dispersion relations for
Figure 10: Frequency, $\Phi_s (s)$ (left panel), and zonal wavenumber, $\Phi_k (k)$, spectra of $\eta$ for the eastern part of the study region. Wavenumber spectra are shown as westward-(solid) and eastward- (dashed) going energy. Dash-dot line denotes the annual cycle which is only a small fraction of the total energy and which (see Fig. 8) is dominated by the lowest wavenumbers, indistinguishable here from $k = 0$.

Approximate 95% confidence limits can be estimated as the degree of high frequency or wavenumber variability about a smooth curve and are quite small.

Figure 11: A time-latitude diagram of sea surface height in cms along a meridional line ($211^\circ$E) across the box in Fig. 1. Visually, the motions are close to standing oscillations in time, and for simplicity are so regarded here, although the latitudinal wavenumbers are finite.
the zonal motions, $l = 0$ as was assumed for simplicity. Fig. 12 shows the linear and logarithmic contours of $(l, s)$ power density from the $15^\circ$ latitude band across the box. While the energy is clearly clustered around $l = 0$, significant amounts are found at finite values. Fig. 8 shows that there is finite energy at scales shorter than 1000km, but longer than the Rossby radii, that ultimately must be taken into account (postponed). In terms of the BTT dispersion relationship, finite $l$ pushes all the baroclinic modes to yet lower frequencies, and thus has little effect on the structure near $s = 0$, where much of the energy is nearly tangent to the $n = 1$ curve. Note the slightly reddish nature of the low frequency spectrum.

4 Vertical Structure

The discussion of transports as inferred from altimetry is directly dependent upon the vertical structure underlying the surface motions. In the schematic of Wunsch (2008), it was assumed that all of the motions lay in the first baroclinic mode. A rough rule of thumb is that about 50% of the mesoscale kinetic energy is in the barotropic mode (with “barotropic” specifically defined above) with about 40% in the first baroclinic one (Wunsch, 1997). This inference is based upon the current meter data available at that time and was used by ZW2001 as part of their spectral description. There was considerable evidence of “phase-locking” of the modes

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2That roughly half the kinetic energy at periods shorter than about a year is best described as “barotropic” has often been simply ignored in theories focussing on the first baroclinic mode.
in some regions, albeit the coverage was inadequate to generalize about it. Such phase-locking can be an indication of non-linearity in the system, consistent e.g. with McWilliams and Flierl (1976) and the inference of Chelton et al. (2007) that a linear Rossby wave description is at best incomplete—as one infers from Fig. 2. Apparent phase locking can also occur from the linear interaction of any particular vertical mode with topographic gradients—which necessarily then couple all the modes. Klein et al. (2008) discuss the plausible existence of trapped near-surface motions, dependent upon near-surface shear. There is no immediate evidence that such motions are visible in the altimetry on the space/time scales now accessible. In any event, vertical modes are a complete set, although possibly an inefficient one near \( z = 0 \) if surface buoyancy distributions are important. If the modes are coupled, as they appear to be, a full description requires specification of their phase, in addition to their mean-square amplitude as a function of frequency.

With very rare exceptions, current meter records have a duration of less than a year and the set of water-column spanning current meter or temperature moorings of long duration is almost empty. The question then arises as to the vertical partition of oceanic kinetic energy on the time scales exceeding that of geostrophic eddies (longer than about one year) and on spatial scales greater than a few hundred kilometers. A useful estimate is particularly important in the design of in situ arrays for trend determination in the general circulation. Using the global hydrography, Forget and Wunsch (2007) showed that vertical displacements could be interpreted in most regions as owing primarily, but not completely, to the first baroclinic mode. Hydrographic data used that way does not, however, permit any inferences about barotropic motions.

That the dominant observed motions are a combination of barotropic and baroclinic mode-like structures embedded in a broadband (in frequency and wavenumber) background of more linear motions is an inference consistent with the frequency/wavenumber content in Fig. 8, the “too fast” phase velocity of Chelton and Schlax (1996), the coherent vortex picture of Chelton et al. (2007), and the coupled mode picture from current meter moorings of Wunsch (1997). The amount of information available about the details of the coherent vortex structures, which we tentatively identify with the non-dispersive line, is, however, minimal. We therefore propose as a strawman hypothesis that the energy density for the motions is proportional to the relative distances to the barotropic and first baroclinic mode dispersion curves with \( l = 0 \),

\[
s = -\frac{\beta k}{k^2 + 1/R_i^2}, \quad i = 0, 1, \quad R_1 = 35\text{km}. \tag{4} \{\text{dispersion1}\}
\]

For numerical purposes, \( R_0 \) was set to infinity so as to avoid the presence of the long-wave branch of the barotropic mode, which otherwise leads to a complicated multivaluedness in the distance to the dispersion curve. Define \( r_0, r_1 \) as the minimum distance from any location, \( k^*, s^* \)
Figure 13: Fraction of the variance hypothesized to lie in the barotropic mode and based upon the distance in $k, s$ space from the two BTT dispersion curves (dashed lines). Westward-going motions only. Dotted line is the non-dispersive line with an energy maximum, and for which at low frequencies the motion would be almost completely baroclinic. At the present time, there is no information concerning the vertical structures for frequencies and wavenumbers lying below the $n = 1$ dispersion curve nor those above that for $n = 0$.

A conjecture, based on only the fragmentary evidence already cited, is that we can partition the energy in the vertical as,

$$
\frac{1}{r_1^2 + r_0^2} \left[ r_1^2 (1 - r_0^2) F_0^2 (z) + r_0^2 (1 - r_1^2) F_1 (z)^2 \right]
$$

(not allowing for phase coupling), that is, depending upon the relative distances to the two dispersion curves. One could evidently extend such a rule to incorporate the distances to the dispersion curves of the higher baroclinic modes, but as we are essentially without any supporting information, that step is omitted here. Wunsch (1997) used the ratio of the surface kinetic energy computed directly from $u, v$ to that computed from the sum of squares of the estimated modal amplitudes at the surface. Uncoupled modes should produce a ratio of one and wide variations, both above and below one were found, but no simple spatial pattern could be discerned. Most mooring records are too short to produce definitive results on modal coupling. Whatever the partition, it is important to note that many other structures are also present in the data.
5 Summary Comments

At the present time, the longest accessible periods are about 15 years, and the question of the
nature of much lower frequency oceanic variability is open, and requires separate study. Although
eddy-resolving regional general circulation models now exist, little or no data are available to
test their conclusions. (The constrained state estimate with 1° horizontal resolution discussed by
Wunsch and Heimbach, 2008, shows a reduced, but non-zero, barotropic contribution at periods
exceeding a year. No information is readily available to test that result and it is not further
discussed.) To the extent that the altimetry of the particular subtropical region, supplemented
by some mooring and other data, are typical of the global ocean, a few simple summary elements
concerning the shorter periods, can be described:

Oceanic variability at these latitudes exhibits a broad-band character in both frequency and
wavenumber including significant eastward motions. Theory would suggest that much of this
motion is forced meteorologically and/or is the result of turbulent cascades, but this inference
has not been explored. At low frequencies and wavenumbers the motions are, from the proximity
to the BTT dispersion curve, indistinguishable in altimetric data alone from linear Rossby waves.

In the band of frequencies from about 1 cycle/15 years to about 1 cycle/4 months, sur-
face pressure variability (surface elevation) exhibits an excess of energy along the nearly non-
dispersive line lying between the first baroclinic and barotropic modes. These motions are
inferred to represent a non-linear coupling of these modes. It is conjectured that the relative
fraction of the energy in the modes is inversely proportional to their distance in wavenumber-
frequency space to the BTT dispersion curves, and that the coherent eddies discussed by Chelton
et al. (2007) are best described this way.

The origins of the non-dispersive motions have not been discussed. Coherent vortex dy-
namics, or Korteweg-DeVries types of soliton motions could be investigated. and some kind of
wave-turbulence interaction could conceivably give rise to such behavior. It does seem to be a
robust feature of the altimetric data.

Much more remains to be done, including making the analysis global (C. Hughes, personal
communication, 2009) and in particular a special discussion of the Southern Ocean is needed—
as it tends to be different in most ways. Better understanding of the meridional structure of
the motions, theoretical understanding of the non-dispersive line, and of the vertical partition
of the energy are all needed. Alternative and perhaps more quantitatively accurate analytic
frequency-wavenumber descriptions would be useful. How increasingly complex eddy-resolving
general circulation models are to be tested is not obvious.

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References


