Why Is Platform Pricing Generally Highly Skewed?

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Why is Platform Pricing Generally Highly Skewed?

Richard Schmalensee

April, 2011

Bolt and Tieman (2008) suggested that profit function non-concavities may account for the prevalence of skewed pricing by two-sided platform businesses. In the Rochet-Tirole (2003) model, however, non-concavity is not necessary for highly skewed pricing. Ubiquitous high pass-through rates are sufficient but implausible. In the Armstrong (2006) model, non-concavity is neither necessary nor sufficient for skewed pricing. In both models, non-concavity is associated with strong indirect network effects; in the Armstrong (2006) model such effects are also associated with dynamic instability. It seems most plausible that the prevalence of skewed platform pricing reflects the prevalence of substantial differences between side-specific demand functions.

Two-sided platform businesses (often labeled two-sided markets) commonly set price at or below marginal cost to one of the groups they serve, and some groups may even pay a zero price even though positive costs are incurred to serve them – see, e.g., Evans (2003) or Evans and Schmalensee (2007) for lists of examples. Thus Suarez and Cusumano (2009, p. 84) speak in generic terms of “the subsidy side” and “the money side” of such businesses. It is thus a bit surprising that the usual first-order conditions for profit maximization in standard models of multi-sided platforms do not immediately reveal why such highly skewed pricing should be the norm.

A recent paper by Bolt and Tieman (2008) shows that the second-order conditions for a maximum are violated in the Rochet-Tirole (2003) two-sided platform model if the demands of the two sides have constant elasticities. In this example, the first-order conditions identify a saddle-point of the profit function, not a maximum, and profits are maximized at a corner.

1 Massachusetts Institute of Technology. I am indebted to two anonymous referees, the editor, and, especially, Glen Weyl for extremely valuable comments on earlier versions of this paper. Of course, only I can be blamed for shortcomings that remain.

solution. Bolt and Tieman suggest that this outcome may be general, so that the prevalence of highly skewed pricing in multi-sided platforms could be explained by the prevalence of such non-concave profit functions.³

This note investigates the plausibility of that intriguing suggestion in the canonical two-sided platform models of Rochet and Tirole (2003) (Section 1) and Armstrong (2006) (Section 2) and, in the process, explores the association between non-concavity and strong indirect network effects in these models.⁴ Section 3 summarizes our main results and conclusions: it seems more likely that pervasive highly skewed pricing by platform reflects generally substantial differences between demand functions on the two sides of the business rather than pervasive profit function non-concavities.


In this model, the monopoly’s objective function can be written as

\[ \Pi(P_1, P_2) = (P_1 + P_2 - C)D_1(P_1)D_2(P_2), \]

where the \( P_i \) are the per-transaction prices charged to each of the two participating groups, \( C \) is the constant marginal cost of executing a transaction, and the \( D_i \) are (partial) demand functions. This model may be most directly relevant to payment cards, with the volume of transactions proportional to the product of the number of merchants accepting a particular card brand and the number of consumers carrying cards of that brand and the participation decisions of merchants and consumers assumed to depend only on the per-transaction prices they face.⁵

Assume that both demand functions in (1) exhibit declining marginal revenue. Then, using subscripts to indicate partial derivatives of the profit function, it is straightforward to show that for \( i = 1,2, \Pi_{ii} < 0 \) so that the point at which \( \Pi_i = 0 \) maximizes \( \Pi \) with respect to \( P_i \), treating \( P_j, j \neq i \), as constant. We can then define the functions

-3 Bolt and Tieman (2008) define highly skewed pricing as arising when all potential participants on one side of the market actually participate. Here I use what I think is a more generally useful definition: one price is at the lower bound of the set of feasible prices – typically either zero or marginal cost. Few would disagree that pricing by network broadcast television is highly skewed, for instance, since all revenue comes from advertisers, even though some potential viewers don’t in fact watch television.
-4 Rochet and Tirole (2006) present a more general model that includes both these models as special cases and in which both access and intereractions may be priced. See Weyl (2010) for an extensive analysis of that model.
-5 See, for instance, Schmalensee (2002).
These yield a natural summary measure of the strength of indirect network effects in this model, based on the geometric mean sensitivity of the optimal prices each side to the price on the other side:

\[
T_p = \left( \frac{d\hat{P}_1}{dP_2} \right) \left( \frac{d\hat{P}_2}{dP_1} \right) = \frac{\Pi_{i2}^2}{\Pi_{11} \Pi_{22}}.
\]

But \(T_p < 1\) is one of the second-order conditions for a stationary point of \(\Pi\), a point at which the first-order conditions are satisfied, to be a local maximum. Thus, if the demand functions exhibit declining marginal revenue, a necessary and sufficient condition for concavity of the profit function is that average indirect network effects, as measured by \(T_p\), not be too strong.

To be more precise, it is easy to show that the second derivatives of the profit function (1) can be written as follows, where primes indicate derivatives of the demand functions:

\[
\Pi''_i = -MD'_iD'_i(1/\rho_i) < 0, \quad i = 1, 2, \quad \text{and}
\]
\[
\Pi_{i2} = \Pi_{2i} = -MD'_iD'_i < 0, \quad \text{where}
\]
\[
M \equiv (P_1 + P_2 - C), \quad \text{and} \quad \rho_i = \frac{(D'_i)^2}{[2(D'_i)^2 - D_iD''_i]}, i = 1, 2.
\]

That is, \(\rho_i\) is the pass-through rate on side \(i\), the amount by which a monopolist with constant marginal cost and facing demand curve \(D_i\) would optimally increase price in response to a small unit increase in marginal cost (Weyl and Fabinger (2009)).

A close look at equation (2) makes it clear why pass-through rates determine the strength of the indirect network effects in this model: an exogenous increase in \(P_j\) affects the optimal value of \(P_i, i \neq j\), exactly as an equivalent decrease in unit cost, \(C\). It follows immediately from (4) that \(T_p = \rho_1\rho_2\), and we have immediately

**Proposition 1 (Weyl (2009, 2010)):** If both demand functions in the Rochet-Tirole (2003) model exhibit declining marginal revenue, a necessary and sufficient
condition for a stationary point of (1) to be a local maximum is $\rho_1 \rho_2 < 1$. If 
$\rho_1 \rho_2 \geq 1$, the stationary point is a saddlepoint.

If the profit function (1) has a unique stationary point at which $T_P \geq 1$, the maximum of $\Pi$ must occur on the boundary of the feasible set.

For log-linear demand curves, $\rho > 1$, while for linear demand curves $\rho = 1/2$. Most economists seem to think that pass-through rates below one are more common than pass-through rates above one, though Weyl and Fabinger (2009) argue that there is not much evidence supporting that belief. Proposition 1 indicates that pass-through rates above one must nonetheless be pervasive if saddle-points are to be the norm in situations well-modeled by the Rochet-Tirole (2003) model. But this does not seem plausible. If one imagines pass-through rates being determined by independent draws from a uniform distribution over [0, 2], for instance, so that the average rate is above most economists’ expectations, the probability that the product of two such draws will exceed unity is only about 0.40. While it is true that evidence on pass-through rates is scarce, it does not seem plausible that the pervasiveness of skewed pricing in two-sided markets is explained by the unusually frequent occurrence of pass-through rates above unity in those markets.

On the other hand, highly skewed pricing can easily arise when the profit function is concave when demand functions differ substantially. Suppose, for example, that individual $h$ in group $i$, $i = 1, 2$, will participate in the market under consideration if and only if $\theta_i h \geq P$, where the $\theta_i h$ are uniformly distributed between 0 and $A_i > 0$. If the number of potential participants in group $i$ is $N_i$, the two demand functions can be written as

\begin{equation}
D_i(P_i) = N_i - b_i P_i = b_i (\hat{P}_i - P_i), \quad i = 1, 2,
\end{equation}

where $b_i = N_i/A_i$ and $\hat{P}_i$ is the choke price at which demand on side $i$ falls to zero, $i = 1, 2$. The first-order conditions for maximizing expression (1) in this case signal a regular unconstrained optimum, but they imply $P_i \leq 0$ if and only if

\begin{equation}
2 \hat{P}_1 \leq \hat{P}_2 - C.
\end{equation}
Condition (6) requires substantial differences in demand, but, particularly when marginal cost is low, such differences are not implausible for groups as different those linked by two-sided platforms in practice. Consider merchants and shoppers, for instance. In any case, if condition (6) is satisfied and, as is usually the case, negative prices are infeasible, the optimum of (1) will involve highly skewed pricing with \( P_1 = 0 \) and \( Q_1 = N_1 \). We have thus proven by example

**Proposition 2**: Non-concavity is not necessary for highly skewed pricing in the Rochet-Tirole (2003) model.


In the Armstrong (2006) model, participation is priced but transactions are not, and participation, \( Q_i \), is influenced via indirect network effects by participation on the other side, as well as the participation price, \( P \). We can write the demand functions for participation by the two sides as

\[
Q_i = D_i(P_i, Q_j), \quad i, j \in \{1, 2\}, i \neq j.
\]

We assume these functions are decreasing in price and non-decreasing in other-side quantity.

A natural measure of the (geometric) average strength of indirect network effects in this model is

\[
S \equiv \left( \frac{\partial D_1}{\partial Q_2} \right) \left( \frac{\partial D_2}{\partial Q_1} \right).
\]

This measure, however, is directly related not to the concavity of the profit function in this model but to the stability of equilibria in a family of myopic disequilibrium dynamic systems in the in the spirit of Rohlfs (1974):

\[
\text{sgn} \left( \frac{dQ_i}{dt} \right) = \text{sgn} \left[ D_i(P_i, Q_j) - Q_i \right], \quad i, j \in \{1, 2\}, i \neq j.
\]

**Proposition 3 (Evans and Schmalensee (2010))**: An equilibrium of (9) is stable if and only if \( S < 1 \) at that point. If \( S \geq 1 \), the equilibrium is a saddlepoint.
Equilibria of (9) in the interior of the feasible set of quantities that are unstable when prices are constant do not seem likely to be observed in practice.\footnote{Weyl (2010) shows that any pair of non-negative quantities can in general be sustained by what he terms insulating tariffs: schedules that make the price to each side conditional on the level of participation on the other side. (See also White and Weyl (2010) for a model of platform competition with insulating tariffs.) Price schedules of this sort do not seem common in practice, however, but, as noted below, prices that rise over time as participation grows can accomplish the same objective if (9) holds.}

It is generally most convenient in this model to solve the demand functions (7) for prices, so the profit function can be written as

\begin{equation}
\Pi(Q_1, Q_2) = Q_1 \left[ d_1(Q_1, Q_2) - C_1 \right] + Q_2 \left[ d_2(Q_2, Q_1) - C_2 \right].
\end{equation}

The $C_i$ are the constant side-specific unit costs of participation. It is useful to recognize that the problem of maximizing (10) is formally identical to the problem of maximizing the profit of a monopolist selling complements.

In general the second-order conditions for this model involve second derivatives of the $d_i$ with respect to other-side quantities and are consequently difficult to interpret.\footnote{See Theorem 4 in Weyl (2010) and its discussion in the paper’s online appendix.} Declining marginal revenues are no longer sufficient for the $\Pi_{ij}$ to be negative, for instance. When those quantities are negative, however, we can define conditionally optimal quantities as above:

\begin{equation}
\hat{Q}_i(Q_j) = \arg \max_{Q_i} \Pi(Q_i, Q_j), \quad i = 1, 2, \ j \neq i.
\end{equation}

With this definition, the third second-order condition for a stationary point of (10) to be at least a local optimum becomes a condition on the (geometric) average indirect network effect:

\begin{equation}
T_Q = \left( \frac{d\hat{Q}_1}{dQ_2} \right) \left( \frac{d\hat{Q}_2}{dQ_1} \right) = \frac{(\Pi_{12})^2}{\Pi_{11}\Pi_{22}}.
\end{equation}

We have immediately

\textit{Proposition 4:} If $\Pi_{11} < 0$ and $\Pi_{22} < 0$ at a stationary point in the Armstrong (2006) model, a necessary and sufficient condition for that point to be a local maximum is $T_Q < 1$. If $T_Q \geq 1$, the stationary point is a saddlepoint.

As in Proposition 1, if the unique stationary point is a saddlepoint, profit is maximized on the boundary of the feasible set. It is clear that the measures $S$ and $T_Q$ of average indirect network
effects are not in general equal, since $S$ involves first derivates only, while $T_Q$ involves a variety of second derivatives, but it is also clear that they are not unrelated.

In order to obtain further insight into the determinants of non-concavity and the relations between these two measures of average indirect network effects, it is useful to consider two examples. Suppose first that the $D_i$ are log-linear:

\begin{equation}
D_i(P_i, Q_j) = \alpha_i P_i^{-\beta_i} Q_j^{\delta_i}, \quad i, j \in \{1, 2\}, i \neq j,
\end{equation}

where the $\alpha$, $\beta$, and $\delta$ are positive constants. It is immediate that $S = \delta_i \delta_j$ here. Then straightforward but tedious analysis of first- and second-order conditions yields

**Proposition 5:** If demands in the Armstrong (2006) model are given by (12) with $\beta_1, \beta_2 > 1$, then $\delta_1 < \beta_i \Rightarrow \Pi_i < 0$ at a stationary point, $i = 1, 2$. If both these conditions are satisfied, then if $\delta_1, \delta_2 < 1$, then $T_Q < 1$ (and $S < 1$), while if $\delta_1, \delta_2 \geq 1$, then $T_Q \geq 1$ (and $S \geq 1$).

Thus indirect network elasticity on side $i$ must be weaker than the corresponding price elasticity in order for $\Pi_i = 0$ to indicate a conditional maximum of $\Pi$ rather than a conditional minimum. If the profit function is well-behaved in this sense and if both network elasticities are less than (greater than or equal to) one, then both $T_Q$ and $S$ are less than (greater than or equal to) one.

A second, somewhat more tractable example is obtained by assuming that typical individual $h$ on side $i$, $i = 1, 2$, participates if and only if

\begin{equation}
\theta_i^h \geq P_i - \delta_i Q_j, \quad i, j \in \{1, 2\}, i \neq j,
\end{equation}

where the $\delta_i$ are positive constants. Let $N_i > 0$ be the maximum number of potential participants on side $i$, and assume the $\theta_i^h$ are uniformly distributed between 0 and $\alpha_i$, with $\alpha_i > C_i$, $i = 1, 2$.

Under these assumptions the demands for participation are given by

\begin{align}
(14a) \quad D_i(P_i, Q_j) &= N_i - B_i P_i + G_i Q_j, \quad i, j \in \{1, 2\}, i \neq j, \quad \text{where} \\
(14b) \quad B_i &= N_i / \alpha_i, \quad \text{and} \quad G_i = \delta_i N_i / \alpha_i, \quad i = 1, 2.
\end{align}

In this example, $S = G_1 G_2$.

Solving equations (14) for prices yields
(15a) \[ P_i = d_i(Q_i, Q_j) = \alpha_i - b_i Q_i + \delta_j Q_j, \quad i, j \in \{1, 2\}, i \neq j, \quad \text{where} \]

(15b) \[ b_i = 1/B_i = \alpha_i/N_i, \quad i = 1, 2. \]

The firm’s profit function can then be written as

(16) \[ \Pi = Q_i (\alpha_i - b_i Q_i + \delta_i Q_i - C_i) + Q_j (\alpha_j - b_j Q_j + \delta_j Q_j - C_j), \]

Using subscripts to indicate partial differentiation as above, the first-order conditions for maximization of \( \Pi \) are

(17) \[ \Pi_i = (\alpha_i - C_i) + (\delta_1 + \delta_2) Q_j j - 2b_i Q_i = 0, \quad i, j \in \{1, 2\}, i \neq j, \]

and the second-order necessary conditions for (17) to yield a maximum are

(18a) \[ \Pi_{ii} = -2b_i < 0, \quad i = 1, 2, \quad \text{and} \]

(18b) \[ T_\theta = \frac{(\Pi_{i2})^2}{\Pi_{ii} \Pi_{22}} = \frac{(\delta_1 + \delta_2)^2}{4b_1 b_2} < 1. \]

Condition (18b) says that the arithmetic mean of the cross-quantity effects on price must be less than the geometric mean of the own-quantity effects.\(^8\) Using (15b) to re-write this condition, we can re-write this condition in a form that is easier to compare with \( S = G_1 G_2 \) and obtain

**Proposition 6:** The point satisfying (17) maximizes \( \Pi \) if and only if

\[ \sqrt{T_\theta} = \frac{1}{2} \left[ G_1 B_1^{1/2} + G_2 B_2^{1/2} \right] < 1 \]

If \( T_\theta \geq 1 \), that point is a saddlepoint, and \( \Pi \) is maximized on the boundary of the feasible set. \( T_\theta < 1 \) is sufficient for \( S < 1 \). It is also necessary for \( S < 1 \) if and only if the two demand functions are identical.

Once again, both the concavity of the profit function and stability of the general adjustment process are associated with limits on the importance of indirect network effects.

To see if non-concavity of the profit function is necessary for highly skewed pricing, let us assume concavity and solve (14) for both quantities as functions of both prices, to obtain

(19) \[ Q_i = \frac{N_i + G_i N_j - B_i P_i - G_i B_j P_j}{1 - S}, \quad i, j \in \{1, 2\}, i \neq j. \]

\(^8\) For an interpretation of this condition in terms of profits with and without two-sidedness, see the discussion of Proposition 4 in the online appendix to Weyl (2010).
If the profit function is concave, Proposition 4 implies $S < 1$, so these demand functions are well-behaved. Suppose, to avoid clutter, that $C_1 = C_2 = 0$. Then there is highly skewed pricing with concavity if (a) $T_Q < 1$ and (b) $\Pi_1 \leq 0$ when $\Pi_2 = 0$ and $P_I = 0$, as long as the solution is within the feasible set. The second condition can be written as

\[
N_1 \left[ 2B_2 - G_2 \left( G_1B_2 - G_2B_1 \right) \right] + N_2 \left( G_1B_2 - G_2B_1 \right) \leq 0.
\]

It is immediate (and not surprising) that $G_2 > 0$ is necessary for this condition to be satisfied. Substituting the optimal value of $P_2$ when $P_I = 0$ then establishes that $Q_I \leq N_I$ if and only if $D_I = 0$, which in turn implies $Q_I = N_I$. It is then easy to find numerical values that satisfy (18b) and (20) with $D_I = 0$. One example is $N_I = N_2 = 100$, $B_1 = 20$, $B_2 = 10$, and $G_2 = 0.8$. Thus non-concavity is not necessary for highly skewed pricing in this example.

To see whether non-concavity is sufficient for highly skewed pricing in this example, suppose demand and cost functions on the two sides are identical and $T_Q > 1$. Dropping subscripts on cost and demand parameters, if $Q_1 = Q_2 = Q$, equation (16) becomes

\[
\Pi = 2Q \left[ (\alpha - C) + Q(\delta - b) \right].
\]

Since $T_Q > 1$ implies $\delta > b$, this expression is convex in $Q$ and profits are either maximized at $Q = 0$ or $Q = N$. If

\[
(\alpha - C) + N(\delta - b) > 0,
\]

the maximum occurs at $Q = N$. It is straightforward to show that if (17) is satisfied and if, say, $Q_2 = N$, then profits are maximized by setting $Q_I = N$ also. Thus even though the profit function is maximized on the boundary of the feasible set of quantities, pricing is symmetric, not skewed:

\[
P_1^* = P_2^* = \alpha + N(\delta - b).
\]

We have thus completed the proof by example of

**Proposition 7:** Non-concavity is neither necessary nor sufficient for highly skewed pricing in the Armstrong (2006) model.

When the profit function is non-concave and the demand functions are identical in this example, $S > 1$ and interior equilibria of dynamic processes satisfying (9) are unstable. But this is not an interior equilibrium. Again in the spirit of Rohlfs (1974), as long as

\[
P_i < \alpha_i + \delta Q_j - bQ_i, \quad i, j \in \{1, 2\}, i \neq j,
\]
$D_i > Q_i$, $i = 1, 2$, and, by (9), both quantities are increasing. Once the point $Q_1 = Q_2 = N$, is reached, it can be maintained by setting prices just below the level given by (18), so that all participants have strictly positive surplus.

3. Conclusions

In the Rochet-Tirole (2003) model, Section 1 showed by example that non-concavity is not necessary for highly skewed pricing. Such pricing can arise from substantial differences in the demand functions on the two sides of the market. Moreover, I argued that it is unlikely that satisfaction of the pass-through conditions for non-concavity is ubiquitous in platform markets.

In the more complex model of Armstrong (2006), Section 2 showed that strong network effects are associated both with non-concave profit functions and with instability of a broad class of disequilibrium adjustment processes. In this model, non-concavity was shown by example to be neither necessary nor sufficient for highly skewed pricing.

In short, the analysis here strongly suggests that highly skewed pricing by two-sided platforms is not prevalent because profit is generally maximized at corner solutions for these businesses, but rather because the demand characteristics of the two groups involved generally differ substantially.

References


