Design of a Laboratory System for the Prediction of Wireline Tool Sticking

by

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B.S., Mechanical Engineering (1998) Massachusetts Institute of Technology

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Abstract

This thesis is the design of an apparatus that simulates differential pressure sticking downhole in an oil well. This equipment is to be used to further understand differential pressure sticking and to observe how Schlumberger measurement tool designs can be changed to reduce this effect. The apparatus builds a mudcake, embeds a test piece in the mudcake and measures the force required to pull the test piece free. This apparatus was designed, built and tested.

Thesis Supervisor: Ernesto Blanco Title: Adjunct Professor of Mechanical Engineering

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Chapter 1

Overview

1.1 Introduction

In the oil industry, tools are lowered downhole in an oil well to perform a series of tasks ranging from drilling to taking measurements of the formation to determine the location of oil. These tools repeatedly get stuck and cannot be raised, lowered or rotated. This is even more frequent for tools that have to remain stationary for a long period of time. Once a tool gets stuck, special procedures have to be taken to pull the tool free. These procedures can take a long time and in the oil industry, time is extremely expensive.

This is the case for Schlumberger, the leading supplier of services and technology to the international petroleum industry. Its tools, in particular its measurement tools provided by the division Wireline & Testing, get stuck due to a phenomenon called differential pressure sticking. This occurs when a tool or cable is pinned against the borehole wall due to a differential pressure between the borehole and the rock formation. Because of this differential pressure, mud filters through the rock and starts building a mudcake around the wall. The tool gets stuck when it becomes embedded in the mudcake. A theoretical model of this type of tool sticking has been developed [10]. However, the phenomenon is still not completely understood nor is it known how these incidents can be reduced. Thus, this thesis develops the design of a laboratory test equipment to simulate the conditions downhole where differential pressure sticking occurs. This apparatus, referred to as the Wireline Stickance Tester, is to be used to further understand differential pressure sticking and to observe how tool designs can be changed to reduce this effect.

This chapter provides a background and an explanation of differential pressure sticking. It also states, in further detail, the motivation for the design of the laboratory equipment and the functional requirements for the equipment.

Chapter 2 describes the development of the equipment, certain design issues which had to be considered and a small prototype of the final design.

Chapter 3 presents the final design and Chapter 4 shows the performance of the tester and a discussion of possible improvements.

1.2 Motivation

When a tool gets stuck, special procedures are taken to pull the tool out, which requires all pending work to stop. These procedures can take up to 24 hours and it becomes extremely expensive since the daily rig costs around \$100,000 per day. If for example, the customer needs to determine if there is oil at a particular rock formation, a measurement tool is lowered down into the oil well and the cost of the rig, the cost of the the measurement tool and the service provided is charged to the customer. Thus the longer a job takes to complete, the more expensive it becomes to the customer.

As described previously, the most common problem for Wireline tools is differential pressure sticking, especially for the tools that must remain stationary for long periods of time. This is the case for the RFT (Repeat Formation Tester) and the MDT (Modular Dynamics Formation Tester) tools, which stop to take samples from different formations in the well. Wireline & Testing, like the competition, has always considered differential sticking, a phenomenon that cannot be changed. Therefore, up until now, most of the attention has been focused on tool reliability in order to minimize the occurrence of failures while the job is running and thus, reducing the cost to the customer. However, as seen in Figure 1-1, sticking is far worse of a problem than tool failure. Therefore, Wireline & Testing is beginning to believe that if differential pressure sticking can be understood then, tool sticking frequency may be reduced.



Figure 1-1: Frequency of Tool Sticking vs. Tool Failure

Several ideas to reduce sticking has been suggested. It is believed, for example, that the tool geometry can influence sticking. Changing the surface of the tool to a golf ball type of surface or making the cross-sectional area smaller could reduce the sticking frequency. A slimmer or a lower density tool might help. Designing microstandoffs on the cable or tool, or drilling holes on the cable so that the differential pressure on the surface is reduced are some other ideas. Applying a voltage across the tool or cable has been suggested as well as applying a thinly lubricated surface or designing a cable that could inflate and deflate .

These ideas have raised more questions. It is undetermined, for example, if the spiral type of surface on the cable reduces the likelihood of differential sticking or if it actually embeds itself deeper into the mudcake and increases sticking probability. If the surface of the cable were to be made smoother, would this reduce sticking?

Such issues remain unanswered. Therefore, this thesis proposes the design of the Wireline Stickance Tester, which reproduces differential pressure sticking. This apparatus can be used to test the effectiveness of these ideas and to gain a better understanding of this phenomenon. The Tester simulates the conditions downhole by building a mudcake inside an annulus filter, embedding different test pieces in the mudcake and measuring the force required to pull the test piece free.

1.3 Schlumberger

Schlumberger is a company whose main activity is providing oilfield services. This involves exploration, production and completion services needed in the industry. Schlumberger is divided into smaller companies, specializing in different aspects of the oil industry. Two of these companies will be mentioned in this thesis: Dowell and Wireline & Testing.

Dowell provides services in well construction, well production and well intervention. This includes cementing of the well, providing and developing drilling fluids used at the well, and the control of sand and water. The drilling fluid, whose main purpose is lubrication for drilling, is what is commonly called mud. This mud is the main contributor to differential pressure sticking.

Wireline & Testing is the company that funded this thesis and is the interested party in the design of the Stickance Tester. This division provides tools and services to make measurements of physical properties of underground formation. The measurements taken using these tools are crucial to reveal where oil and gas are deposited and to indicate the producibility of the formation. After the well is drilled, Wireline & Testing brings a computerized mobile laboratory to the well and lowers its instruments on a cable called a wireline. These instruments are encased in a slim cylindrical tool known as a sonde. After they have been lowered to a desired depth, they are pulled slowly back to the surface, continuously measuring the properties of the rock formation that they pass through. The data is then transmitted on the wireline to the surface and is digitally recorded and plotted on a graph called a log. Depending on the type of tool that is used, the tool may also stop to take particular samples of the formation. Figure 1-2 shows a schematic of the system.



Figure 1-2: Wireline & Testing

1.4 Sticking

Sticking happens when a tool or the cable gets stuck in the well and cannot be raised, lowered or rotated and special procedures have to be taken into "fish" the tool out. The reasons for sticking are many but generally they are broken down to three categories: differential, mechanical and formation related, as illustrated in Figure 1-3 [13].

One form of mechanical sticking is key seating, where a tool or cable becomes wedged in a groove cut by the cable or the drillpipe. Another form of mechanical sticking is when the well passage is blocked by ledges or overhangs. The tool can



Figure 1-3: Modes of Sticking

easily slide past the overhang but when it is pulled upwards it is caught and trapped. Formation-related sticking is caused by the constriction of the borehole by mechanically or chemically unstable formations. Unconsolidated or reactive rock can block the borehole and constrain the tool from moving up. Differential pressure sticking, which is the most common form of sticking for Wireline tools, occurs when the tool or the cable becomes embedded in mudcake and is pinned to the borehole wall by the forces created by the pressure difference between the mud and the formation.

1.5 Differential Pressure Sticking

Differential pressure sticking occurs in permeable zones where gas and other pore fluids are found. In addition to acting as a lubricator for drilling, mud is also used to prevent the ingress of these fluids from pouring into the borehole. The mud density is adjusted so that the hydrostatic pressure is greater than the pressure within the pores of the surrounding rock. Because the pressure at the well is higher than the pressure at the formation, the mud starts filtering through the permeable rock. Over time, a low permeability layer called filter cake or mudcake is formed around the wall. This mudcake acts as a seal of the formation to the borehole.

Sticking occurs when the tool or cable becomes embedded in this mudcake. Because it is unlikely a well bore is drilled so straight that the wireline cable or tool does not come into contact with a borehole wall, the cable or tool starts to interact with the compacted layer of the mudcake. The cable acts almost as dental floss, as it is moved up and down, destroying the layer of mudcake and embedding itself in it. Once the mudcake has been destroyed, mud filtration begins again and a new mudcake is formed, sucking the cable or tool in. If the tool then stops, the new mudcake starts forming, bonding the tool or cable to the well. The combination of differential pressure, the new formation of a mudcake, and the stopping of the tool, causes the tool to get stuck. See Figure 1-4 [13].



Figure 1-4: Differential Pressure Sticking

In summary, four simultaneous conditions have to exist for a tool or cable to get differentially stuck:

- 1. An overbalance or pressure difference between the formation and the well bore
- 2. A permeable zone for mud filtration to occur
- 3. Damage of mudcake by the tool or cable
- 4. Stopping of the tool

If these conditions do not occur simultaneously, differential pressure sticking will not occur. For example: an overbalance and permeable rock can exist and the tool can stop. But if the tool has not damaged the mudcake then a new filtration will not occur and the mudcake will not build around the tool. Therefore, the force required to pull out the tool would only be the frictional force acting on the tool. Any type of "suction" force on the tool would not be observed.

Once these four conditions occur, a sticking force begins acting on the tool. This sticking force has been quantified in a theoretical model developed by Gerry Meeten and John Sherwood [10]. The model is based on laboratory measurements and research on compressible mudcakes. It states that the sticking force or the force required to pull the tool free once it becomes differentially stuck is:

$$F_{free} = (2L_{cyl}D_e^{1/2})(\beta^{1/2}\tau_o)t^{1/4}$$
(1.1)

where,

 $L_{cyl} = \text{contact length}$ $D_e = \frac{D}{1 - \frac{D}{D_W}} = \text{effective diameter}$ D = diameter of tool or cable $D_w = \text{diameter of borehole wall}$ $\beta = \text{mudcake thickness parameter}$ $\tau_o = \text{mudcake yield strength}$ t = time the tool has remained stationary

The magnitude of the sticking force is believed to be subject to mud properties $(\beta^{1/2}\tau_o)$, geometry of the tool $(2L_{cyl}D_e^{1/2})$, and the time the tool is stationary $(t^{1/4})$.

The contact length can vary depending on the straightness of the borehole wall. The well does not have to deviate much in order for the cable tension to force large cable length into the mudcake. Hole size and tool diameter are also important. The larger the ratio of well diameter to cable or tool diameter, the easier the tool can get stuck.

The mudcake properties that influence the probability of sticking are many. The mudcake thickness parameter, β , is a function of solids volume fraction of the mud, mud density and temperature. It is a parameter that determines the rate at which the mudcake is built, where the thickness of the mudcake δ is:

$$\delta = \beta t^{1/2} \tag{1.2}$$

The shear stress of the mud, τ_o , is a function of differential pressure, temperature (mud gels with increasing temperature) and mud type. The mud type can be waterbased, oil-based or polymer water-based mud. In addition, lubricants can be added to the mud and these also influence the shear strength of the mudcake. Notice that the temperature and pressure influence the sticking force only implicitly by affecting the mud composition.

The significance of stationary time is important as well. The sticking forces grow rapidly immediately after the tool stops and slows down as time passes. This means that the first few minutes that the tool stops could be the most critical time with the highest probability of the tool getting stuck. A hypothetical pulling limit for the wireline cable or tool with the following values is shown in Figure 1-5:

 $D_w = 8.5$ in D = 5 in (diameter of tool) D = 0.5 in (diameter of cable) $L_{cyl} = 1$ ft (effective contact length for tool) $L_{cyl} = 10$ ft (effective contact length for cable)



Figure 1-5: Sticking Forces

 $\beta = 0.001 \ in/s^{1/2}$ (moderately weighted water-based mud) $\tau_o = 50$ psi (water-based mud with 500 psi overbalance)

The sticking force increases until the force becomes larger than the pulling limit at the rig and the tool or cable gets stuck. Whether the cable or tool will get stuck first depends on the contact length of the cable or tool. In this hypothetical case, the cable will exceed the pulling limit first. This is the general case because the contact length of the cable is normally much larger than that of the tool. However, because the area of the tool is larger than that of the cable, the effective diameter D_e is larger, and the tool could get stuck first if the contact length is not large enough.

1.6 Existing Designs and Other Published Testing Procedures

Dowell, the Schlumberger division that engineers the mud, has already tried reducing sticking by designing a mud that will form a less "sticky" mudcake. It has developed a laboratory test equipment called a Stickance Tester which is used to quantify the nature of the filter cake and the probability of tools getting stuck. The body of the device is a modified high temperature, high pressure (HTHP) mud filtration cell (see Figure 2-3). This HTHP cell is a standard piece of equipment used frequently in Dowell and Dowell field sites. For the Stickance Tester, the top end-cap of the cell has been modified to allow entry of a spring-steel wire through an o-ring seal set in the center of the cap. A new entry port is drilled to allow the cell to be pressurized via a gas line or a cylinder. The end of the steel wire in the cell is fixed to a 1.5 inch diameter polished steel ball which rests on the filter medium. The end of the wire protruding from the cell is connected to an electronic torque meter. Because the Tester has the same dimensions as the HTHP cell, it can be placed on a standard heater used for the HTHP cells to raise the temperature to $150^{\circ}F$.



Figure 1-6: Dowell Stickance Tester

The Stickance Test is carried out by filling the cell with mud and heating it to a desired temperature. A differential pressure of 500 psi is applied and the mudcake begins to firm as the fluid flows through the filter paper. Approximately every five

minutes, the torque meter is turned and the force required to move the sphere is measured. This is done for 30 min, applying a torque every 5 min. The torque data versus time to the power of 3/4 is plotted which normally gives a straight line. The slope of the line is calculated and it is called the "stickance" factor of the mud.



Figure 1-7: Torque vs. Time

From the theory in the previous section, the relationship between the stickance of the mudcake and the torque to free the ball can be derived to be [10]:

$$M_o = 2/3\pi D_{ball}{}^{3/2}\beta^{3/2}\tau_o t^{3/4} \tag{1.3}$$

where M_o is the torque required to free the stuck ball, D_{ball} is the diameter of the ball, τ_0 is the shear yield stress of the cake and t is the filtration time. Therefore, the stickance, S, becomes equal to :

$$S = 2/3\pi D_{ball}^{3/2} \beta^{3/2} \tau_o \tag{1.4}$$

so that,

$$M_o = S \cdot t^{3/4} \tag{1.5}$$

As the stickance increases the torque required to free the ball increases, as shown

Authors	Substrate	Pipe	Cake	Direction of	Max Temp	Max Diff.		
	Geometry	Geometry	Formation	Force	$(^{\circ}F)$	Pressure		
	, v					(psi)		
Krol	Cylinder	Cylinder	Static or	Axial	300	2000		
	-		Dynamic					
Helmick and	Cylinder or	Cylinder	Static or	Axial or	Ambient	100		
Longley	disc		Dynamic	radial				
Annis and	Disc	Disc	Static	Axial	Room	500		
Monaghan								
Bushnell-	Cylinder	Cylinder	Static or	Rotation	150	100		
Watson			Dynamic					
Reid (Dowell	Disc	Sphere	Static	Rotation	400	1200		
Stickance Tester)								
Clark and	Cylinder	Cylinder	Static or	Axial	300	2000		
Almquist			Dynamic					
Park and	Disc	Sphere	Static	Axial	400	3000		
Lummus								
Courteille	Cylinder	Cylinder	Dynamic	?	255	1000		
and Zurdo								
Haden and	Cylinder	Cylinder	Dynamic	Axial	Room	15		
Welch								

Table 1.1: Differential Pressure Apparatus

in Figure 1-7. Therefore the "stickance" is a measurable parameter to describe the likelihood of tools getting stuck.

For Dowell, this tester works well to design drilling muds that have a low stickance factor. However, for Wireline, this tester does not fully describe the conditions its tools are subject to. First, Wireline can only apply axial pull to its tools. Thus a torque measurement is not accurate. Secondly, Wireline wants to modify its tools to reduce sticking and the ball does not simulate the tool geometry correctly. Thus, Wireline wants a modified Stickance Tester where a modified stickance factor can be measured for different geometries and compare their tendencies of sticking.

Other methods of assessing the differential sticking tendencies have been developed previously. Some were designed to understand sticking for drilling tool; others were designed to take direct measurements on mud and mudcakes. A list of published differential pressure apparatus is summarized in Table 1.1. These apparatus vary in pressures, temperatures, geometries and simulated dynamic or static conditions in the well. (Unlike Wireline tools, drilling tools are subject to dynamic mud flow in the well.)

1.7 Functional Requirements for the Design of the Wireline Stickance Tester

It is desired to design a Stickance Tester that can measure the tendency of objects with different geometries to get stuck. Most of the above apparatus are large and complicated and do not have the desired requirements. The apparatus that measure axial pulling forces provide dynamic mud flow and filtration. This is not a critical factor since Wireline tools are used under static filtration. Therefore, a simpler mechanism without dynamic flow is desired. The Dowell Stickance Tester is the closest to what is needed but, for Wireline tools, torque measurements are irrelevant. In addition a cylindrical filter medium and a pipe geometry are desired since this simulates Wireline downhole conditions better.

The following are the design requirements for the Stickance Tester:

- Build mudcake inside an annulus to simulate a wellbore hole
- Measure axial force to pull free stuck object
- Allow changeable test objects so that different geometries or designs can be tested
- Apply differential pressure of 1000 psi
- Withstand temperature of $450^{\circ}F$
- Be able to test existing cable
- Scale tool and well diameters so the diameter ratio is the same as real conditions
- Provide safety

Chapter 2

Development

2.1 Initial Design Overview

The Stickance Tester has to perform the following steps:

- 1. Build a mudcake inside a cylinder simulating the mudcake formation around the well bore wall.
- 2. Embed a test piece in the mudcake.
- 3. Apply axial pull to the test piece and measure the force required to pull the test piece free from the mudcake.
- 4. Perform the test several times and plot force against time.
- 5. Test different test piece geometries.

Figure 2-1 is a sketch of what an initial design might look like. The filter is cylindrical and, unlike the Dowell Stickance Tester, the mudcake forms vertically inside the filter. The vessel is pressurized at 1000 psi and the filter, which is open to the atmosphere, will have a 1000 psi differential pressure across its walls. This will allow the mud to pass through the filter and build a mudcake. The rod penetrates the vessel and a sensor measures an axial force outside the vessel.



Figure 2-1: Schematic of an Initial Design

2.2 Identifying Issues

Proceeding with the design of the Stickance Tester, requires the resolution of several key issues. For example, the time it takes to build a mudcake thick enough to produce a measurable sticking force on a test piece must be determined. In real conditions, mud can be inside a well for weeks before a Wireline tool is lowered downhole, thus the sticking forces are very high. Equation 1.2 shows that the mudcake thickness builds by $t^{1/2}$. This means that after a long period of time, the mudcake will reach a maximum thickness. However, the time that it takes to build a mudcake thick enough to perform realistic measurements is unknown.

The Dowell Stickance Tester uses filter paper to build a mudcake. However, for this design, a cylindrical solid filter is needed. Ceramic filters have been thought to work but whether these will simulate a real permeable rock formation is not known. Also questionable is whether the mudcake will have uniform thickness along the length of the filter. The gravity could influence the solid contents of the mud and build a mudcake thicker at the bottom of the filter than at the top. Where the test piece is touching the mudcake along the length the filter could influence the force measurements.

To choose the type of force sensor in the design, the magnitude of the sticking forces must be determined for a particular filter diameter and a certain mudcake thickness. Whether the seals on the rod will influence greatly the force measurements if the force sensor is placed outside the pressurized vessel is also a concern. If this were to be the case, then it is uncertain whether the frictional force of the seals could be subtracted from the total measured force.

Finally, because several size test pieces have to be tested, the gap between the mudcake and the side of the test piece will vary depending on the size of each piece. This gap might be adjusted by making several parts of the tester non-concentric. However, this idea needs to be evaluated.

To resolve these issues a prototype of a Stickance Tester was designed.

2.3 Design of a Prototype of a Stickance Tester

This prototype uses the bottom assembly of a Dynamic Fluid Loss Cell which is used by Dowell to run mud experiments. This assembly, Figure¹ 2-2 has a cylindrical ceramic filter with an inside diameter of 1 in, outside diameter of 1.5 in and a length of 1.5 in. The filter is placed inside a housing that has a low pressure line connected to the atmosphere. The top and bottom of the filter are sealed so that the mud can only filter through its wall if it is pressurized from the inside.

A housing and a top cap assembly were designed to screw to the bottom piece of the Dynamic Fluid Loss Cell. The test piece penetrates through the top cap assembly²as shown in Figure 2-3.

¹This drawing has been modified with Photoshop to show the part of the cell that was used in the prototype. However this is not an accurate picture. See Figure Appendix A.1 for the engineering drawing of the Dynamic Fluid Loss Cell

²See Appendix A.2 for engineering drawings of these machined parts



Figure 2-2: Bottom Part of the Dynamic Fluid Loss Cell



Figure 2-3: Prototype Assembly without the Fluid Loss Cell

The top assembly that screws to the housing is made of three parts: a top cap that screws to the housing, a middle cap that screws to the the top cap and the rod that penetrates the middle cap. These three pieces are non-concentric to each other. Thus, the gap between the rod and the housing can vary depending on how far each piece has been screwed in with respect to the others. Figure 2-4 illustrates this idea. This is the mechanism that was designed to vary the gap between the filter and the test piece.



Figure 2-4: Top Views of Top Cap Assembly

The test piece for this prototype is a 2 inch long and 0.5 inch diameter steel rod (the ratio of this rod diameter to the inside diameter of the filter is the same as the ratio of the tool diameter to the diameter of the borehole) which is press-fitted to a 3/8 in steel rod. A seal which is composed of a nitrile o-ring and a graphite filled PTFE gland (see Appendix A.3 for further specifications) fits at the inside diameter of the middle cap. This seal has good low friction and wear properties. At the bottom of the inside diameter of the middle cap, an excluder is placed in order to maintain the seal free of mud and give the rod more stability if it were to slip out of plumb.

The top cap has a 1/4-18NPT thread opening to allow pressurization of the vessel.

2.4 Test Set-Up and Experimental Procedure

The assembled cell is filled with mud and it is placed on a stand. This stand has a bottom platform attached to a ball screw actuator which can be moved up or down to an accuracy of 0.002 inches. The steel rod connects to a load cell at the top of the stand and a nitrogen tank connects to the top cap to pressurize the cell (see Figure 2-5).



Figure 2-5: Test Set-Up of Prototype

Before the cell is placed on the stand, the non-concentric top caps are rotated relative to each other until the rod touches the side of the filter (this can be easily felt). Once the cell is placed on the stand, the stand is lowered until the top of the 0.5 in diameter test piece touches the top cap. (This allows the mudcake to form without the interference of the rod). The cell is pressurized to a 1000 psi and the mud starts filtering through the bottom part of the dynamic fluid loss cell. Once the mudcake is built, the rod is lowered relative to the vessel (the platform is displaced upwards) until it hits the dynamic fluid loss cell. The load cell force measurement increases drastically when this happens. During the displacement of the rod, the mudcake is destroyed and a new mudcake starts forming around the test piece. The rod is left for 5 min at that position. It is then displaced up very slowly (the platform moves down) measuring the force. The force increases as the rod is pulled upwards until it hits a peak force when it decreases drastically. The peak force indicates the rod has been pulled free. Once pulled free, the rod is moved 1/8 inch up and left there for 5 min. This procedure is repeated 5 times and the force is plotted against time. Note that the test piece always touches the whole surface of the filter because the dynamic cell has a 0.75 inch vertical length for the rod to move down to. However, this constrains the experiment to six measurements per test.



Figure 2-6: Picture of Temperature Test

2.5 Test Results and Conclusions

Six experiments were completed (see Figure 2-6 for picture of a test). All tests used 9 lb/gal water-based mud and were pressurized at 1000 psi. The first three were performed using filters that had a pore size of 10 micro-inches. The other three tests used 35 micro-inch filters. The final test was heated to $217^{\circ}F$ using heating coils. To measure the force applied to the rod by the pressure and friction forces, a breakaway force was measured before the rod touched the mudcake. Appendix A.4 shows the force minus the initial breakaway force against time. All experiments showed that



Figure 2-7: O-rings Dynamics

the friction due to the o-rings could not be considered negligible. When the system was pressurized and static, the load cell read a certain force, Fo, which would be considered to be force due to the rod's being pushed upwards by the pressure. If the rod was lowered, a force F_1 , was measured which was higher than the initial force Fo. Thus, F_1 was considered to be the pressure force plus the friction force of

the seals. However, if the rod was lowered again, another force, F_2 , was measured which was lower than F_1 even though it was expected that the friction force plus the pressure force would remain the same. If then the rod was displaced upwards, the force measured, F_3 , was higher than F_1 , the force required to move the rod down initially. Finally, if the rod was initially moved upwards before moving it down at all, the force measured, F_4 , was about the same as the force to move it down initially, F_1 .

These force measurements were found to be affected by the o-rings energizing and grabbing the rod as shown in Figure 2-7. If the o-ring had already been deformed downwards, the force to move further down is less than if the o-ring had been deformed in the other direction. The combination of the o-ring's energizing and the constant pressure force made it hard to obtain an accurate force measurement.

Finally, for the last experiment, the temperature measured was considered inaccurate since a thermocouple was placed between the heating coils and the housing. Therefore, the temperature reading did not reflect the temperature inside the cell.

In summary, the following issues were established:

- For this specific filter size, a 1/4 inch thick mudcake was built in 30 to 40 minutes.
- The mudcake formed was uniform along the length of the filter.
- Force measurements were in the order of 50 lb force with the above conditions.
- 35 micro-inch pore size filters built a mudcake faster than a 10 micro-inch filter for a 9 lb/gal density mud.
- The non-concentric method to vary gap worked well.
- Seals should be eliminated in the force reading.
- Disassembling between experiments was messy; a drain value to drain the mud should be designed.
- Temperature measurement was inaccurate.

Chapter 3

Wireline Stickance Tester Design

3.1 Overview

The Stickance Tester final design has maintained some features of the prototype. It uses the non-concentric method and a similar filtering mechanism. An actuator rod which penetrates the vessel is used to move the test piece axially. Finally, the system can be pressurized with a nitrogen tank and it is rated to withstand 1000 psi and $400^{\circ}F$. See Figure 3-1 for a schematic of the design and Figure 3-2 for a cross section of the pressure vessel.

However, to eliminate the inaccurate force measurements due to the seals, a load cell is placed inside the pressure vessel in between the test piece and the actuator rod. The actuator rod is hollow so that the wires of the load cell can exit the vessel through the inside of the rod. An air cylinder is used as an actuator and it is placed on top of the stand and connected to the rod. In order to measure the temperature inside the vessel, this tester has a thermocouple housing which allows a thermocouple to penetrate inside the tester. In addition, a drain valve is located at the bottom of the tester to drain the mud before disassembly takes place.

The Stickance Tester has been scaled up. The filter is half the scale of a real oil-well diameter. A well diameter varies between 6.6 to 8.5 inches. The inside diameter of the filter measures 3.5 inches. For this particular size, the sticking forces are estimated



Figure 3-1: Stickance Tester on the Test Stand

to vary between 100 to 500 lbs force¹. Thus, the load cell has been rated to measure forces up to 500 lbs.

Appendices B.1 and B.2 show all engineering drawings of machined parts and outsourced parts.

3.2 Filter Housing Assembly

The Filter Housing Assembly holds the filter and produces a differential pressure across its walls leading to the formation of a mudcake. The pressure difference is created by pressurizing the vessel and connecting the outside diameter of the filter

¹This number was determined by applying equation 1.1 and approximating β and τ_o from experiments performed in the previous section



Figure 3-2: Cross-Section of the Pressure Vessel

to the atmosphere through a low pressure line. Because the filter is sealed at the top and at the bottom, the pressure gradient exists only across its wall.

Figure 3-3 shows the Filter Housing Assembly. The filter is placed inside the filter housing (mrcd308) and it is sealed at the top and bottom by putting it in between two gaskets (3). The filter and the gaskets are held in place by a a snap ring (2) and a filter ring (mrcd309) which has an o-ring (6) to prevent any ingress of mud through its side. The filter housing, which is already screwed to the pressure line screw (mrcd307), can be screwed in further. This compresses the filter between the snap ring and the line screw, sealing the top and bottom of the filter. The pressure line screw has a pressure line that connects to the atmosphere through the bottom cap (mrcd306). Thus the outside diameter of the filter is at atmospheric pressure and the inside diameter is at the pressure of the vessel. To replace the filter, the snap ring is taken out and the housing is screwed further into the pressure line screw so that it pushes the filter out.

See Figure 3-4 for a picture of the Filter Housing Assembly and Figure 3-5 for a picture of the ceramic filter, gaskets and filter ring.



Figure 3-3: Cross-Section of the Filter Assembly

3.3 Load Cell Assembly

The load cell (1), is connected between the test piece (mrcd312) and the actuator rod (mrcd316); see Figure 3-6. The load cell is custom made, can measure compression and tension forces up to 500 lbs and is designed to withstand 1000 psi and $400^{\circ}F$. It requires an excitation voltage of 10Vdc and its output is measured in microvolts (see Figure B-30 in Appendix B.3 for calibration data). The actuator rod is hollow and the signal and excitation wires of the load cell pass through the inside of the rod and are connected to a pressure bulk head (DH549219). The pressure bulk head, which is



Figure 3-4: Picture of the Filter Housing Assembly

held in place by a snap ring (2), allows the signal to be read at the atmosphere but still maintains a full seal. Finally, the shaft connector (mrcd317) is screwed to the actuator rod.

However, before the load cell is assembled, the actuator rod needs to penetrate the top cap first, then the rod can be connected to the load cell and the wires to the pressure bulk head. See Figure 3-7 for a picture of the completed assembly and Figure 3-8 for a picture of load cell components. Before the pressure bulk head can be secured in place, the load cell has to be filled with silicon grease in order to protect all the electronics inside. The load cell has a grease fitting installed so that it can be filled with grease using grease gun. The grease is forced into all internal recesses within the cell and into the internal diameter of the actuator rod. Once the grease excrudes out to the other end of the rod, the pressure bulk head can be snapped in place. The load cell is now protected from the mud environment that it will be submerged in. The grease will act as a displacement barrier to moisture and other


Figure 3-5: Picture of the Filter, Gaskets and Filter Ring

contaminants.

This assembly is designed for different test pieces. However, a coupling, such as the mrcd311, needs to be machined for each test piece. The coupling requires a 1/4-28UNF-2B thread at one end and the pressfitting of the test piece at the other end. For example, for the experiments performed, a real wireline cable was also used as a test piece. In this case, a different coupling was machined for the cable and the cable was pressfitted and welded to the coupling; see Figure B-19 in Appendix B.1.



Figure 3-6: Cross-Section of the Load Cell Assembly



Figure 3-7: Picture of Load Cell Assembly



Figure 3-8: Picture of Load Cell Components



3.4 Housing Assembly

Figure 3-9: Cross-Section of the Housing Assembly

Figure 3-9 shows a cross sectional drawing of the housing assembly. The rod penetrates the pressurized vessel through the o-ring cap (mrcd301) and the top cap (mrcd302). It maintains a seal with a Green Tweed 2510 rod seal (6), which is the same low friction seal used in the prototype (see Appendix A.3 for specifications). During the assembly of the prototype, it was very difficult to place the o-ring inside

the top cap because of its small size and required tight tolerances. Thus, in this design, an o-ring cap is machined leaving enough space in the top cap for the o-ring to slide in easily. The o-ring is then secured in place with the o-ring cap.

A Shamban Turcite Excluder(7) sits at the end of the top cap to scrape the mud off from the rod and give the rod more stability. This is the same excluder used in the prototype and it is held in place with a seal retainer (see Figure A-5 in Appendix A.2 for part drawing).

To measure the temperature inside the vessel, the thermocouple housing (mrcd303) is screwed to the bottom of the cap. This housing allows a thermocouple to slide from the top of the cap to the inside of the housing. The top cap also has a 1/4 inch diameter orifice with a 1/4-18NPT thread which is connected to the pressure line of the nitrogen tank. See Figure B-7 in Appendix B.1 for engineering drawing of the top cap to see this feature.

Standard o-rings used at Schlumberger (1), (2), (4) and (5) are placed in this assembly to maintain a full seal of the pressurized vessel.

3.5 Air Cylinder Actuator

A Bimba Stainless Steel Body Air Cylinder is used to displace the actuator rod (see Figure B-27 in Appendix B.2 for air cylinder specifications). It is connected to the rod (mrcd316) by screwing it to the shaft connector (mrcd317). Once the vessel has been pressurized, the rod will be pushed up by the pressure force ². Thus to maintain the rod stationary, the cylinder has to counter acts this force, acting as a stopper. To pull the test piece free, air is let out slowly from the air cylinder until the rod begins to move. The main function of the actuator, then, is to control the speed of the upward motion. If however, the sticking force is higher than the pressure force, the air cylinder needs to apply an additional upward force, acting as an actuator. The air cylinder can apply up to 500 lbs of force in either direction if given an air

 $^{^{2}}$ If pressurized at a 1000 psi, the rod will push upwards with 250 lbs. This is calculated by multiplying the pressure times the area the pressure is applying. This area corresponds to the diameter of the pressure bulk head.

pressure of 100 psi (this is the air pressure at the Schlumberger laboratory facility).

Note that the inside diameter of the actuator rod is at the same pressure as the vessel because it has not been sealed. Therefore, the load cell is pressure balanced and it does not measure any pressure force.

3.6 Full Assembly

The test stand is assembled by screwing three 1/2-20UNF-2A thread rods to the bottom plate (mrcd318). These rods are held in place by screw nuts and with a spacer between the nut and the plate to secure the rods. The middle plate (mrcd319) is placed 21.25 inches above the bottom plate resting on the nuts, which have been screwed into the rods at that height. Three additional nuts are screwed on top of the middle plate to secure it. See Figure 3-1 and Figure 3-10 for a schematic of the total assembly.

The housing assembly (Figure 3-9) and the load cell assembly (Figure 3-6) are fitted together and placed on the middle plate. The bottom filter assembly (Figure 3-3) is then screwed to the housing assembly. However, because the test piece and the filter assembly are non-concentric, the test piece could jam against the inside of the filter during the process. To prevent this from happening, the test piece and actuator rod must be pulled up as far as possible. When the assembly process is almost completed, the actuator rod is slid down until it hits the bottom cap and the bottom filter assembly is screwed in until the side of the test piece hits the inside of the filter. This final step can be easily done even though one cannot see the point of contact.

Next, the top plate (mrcd 320) is placed about 1/2 inch above the vessel and the air cylinder is assembled on top of it as shown in Figure 3-10. An aluminum plate, which is held above the plate with two rods, has a hole cut out for the air cylinder. The cylinder is placed face down on this plate and it is screwed to the shaft connector (mrcd 317). It should be noted that because the aluminum plate and rods were machined in the laboratory, precise engineering drawings do not exist. Finally



Figure 3-10: Schematic of Full Assembly

the nitrogen tank is hooked to the tester through a hose connected to the 1/4-18NPT opening in the top cap.

3.7 Testing Procedures

To perform a test, the following steps are necessary:

- 1. Fill the vessel with mud.
- 2. Pressurize the vessel to filter mud and build mudcake.

- 3. Move test piece down until it touches the bottom of the Pressure Line Screw. (This procedure will scrape the mudcake of the filter wall, breaking the seal).
- 4. Let the test piece stand stationary for a determined time interval.
- 5. Pull up the test piece slowly and measure the peak force.
- 6. Let the test piece remain stationary for a time interval and and repeat step (5).
- 7. Repeat step (5) and (6) until the test piece has moved up 2 inches from its original position (the point at which the test piece is no longer touching the whole face of the filter).
- 8. Plot the force against time.
- 9. Depressurize the vessel.
- 10. Drain the mud.
- 11. Unscrew the bottom piece to change filter or test piece.

To fill the vessel with mud, a vacuum pump is connected to the 1/4-18NPT opening on the top cap and the bottom cap is connected to a hose and a bucket of mud. To control the mud flow, an open/close valve is screwed to the bottom cap and connected to the hose. The vacuum pump sucks the mud into the vessel until the mud starts flowing out of the top cap. The valve is then closed and the vacuum pump is unhooked from the vessel. The nitrogen tank is hooked at that same point.

Place an open/close value to the 1/4-NPT pressure line opening on the bottom cap. Open this value as soon as the vessel is pressurized. This will produce a differential pressure across the filter and begin filtering the mud.

To perform force measurements, hook the load cell wires coming out of the shaft connector to a 10VDC power supply and a ohm meter. The microvolt measurements are converted to force. (see Figure B-30 in Appendix B.3 for calibration sheet).

To drain the mud, apply a few psi to the vessel and open the mud valve.

Chapter 4

Testing and Recommendations

4.1 Test Results

See Figure 4-1 for a picture of the assembled Stickance Tester during testing. The tester is connected to the nitrogen tank, and the mud is filtered and drained to a container at the bottom. To the left of the Tester is the vacuum pump, which has been used to fill the Tester with mud. The air cylinder is connected to an air pressure line.

A total of six tests were performed. For the first test, the Tester was filled with water and pressurized to 1000 psi in order to check for any leaks and for overall functionality. The low pressure line valve was opened, and the water flowed through the filter as expected.

The next five tests were performed with 9 lb/gal, 10 lb/gal and 11 lb/gal density water-based mud. Two different pore size ceramic filters were tested, 35 micro-inch and 60 micro-inch. However, when the Tester was filled with mud and pressurized, the filters were found to break at 400 psi. The manufacturer of the filters had not guaranteed a 1000 psi differential pressure but had believed that it would not be a problem. This was not the case.

Because the filters were found to break at 400 psi, the tests were completed only to 350 psi. The lower pressure caused the mudcake to form at a slower rate. After four hours of filtering, only 1/4 inch mudcake was built. See Figure 4-2 for a picture



Figure 4-1: Picture of The Full Assembled Stickance Tester

of the mudcake formed inside the filter. In addition, the thin mudcake caused the sticking forces to be much smaller than predicted. Because the load cell was designed to measure forces up to 500 lbs, the accuracy was reduced when smaller forces were measured. Thus, the force measurements did not show a drastic change when plotted against time.

During assembly and disassembly, it became very hard to screw the filter assembly to the Stickance Tester. The large weight of the filter assembly and the necessity of screwing it in from below made the process extremely difficult. A lever arm was finally used to help with the weight.



Figure 4-2: Picture of Mudcake Inside the Filter

4.2 Conclusion and Recommendations

The Stickance Tester design worked well. The load cell inside the pressurized vessel maintained a simple design and eliminated any force measurement errors resulting from the pressure force or the seal. The air cylinder also worked well allowing easy control of the displacement of the rod. The filtering mechanism was effective and the filling, pressurizing and draining of mud was simple.

However, other types of filters need to be found. Even though the present ceramic filters are effective, they can not withstand the 1000 psi differential pressure that is required to build a thick mudcake in a short amount of time. Therefore, it is recommended to change the type of filter or design a filter retainer to prevent the filter from expanding and breaking.

Even though the filtering mechanism worked well, a solution to screwing and unscrewing the Filter Assembly needs to be designed. If this same design is maintained, then a lifting mechanism needs to be added to the tester. A hydraulic pump or a ball screw actuator could be used to lift the filter assembly and screw it to the bottom of the tester.

Finally, a sensor with higher accuracy for smaller forces needs to be used. It is predicted, that the sticking forces will be high when pressurized at 1000 psi. However, for a more flexible design, a load cell that is accurate for a whole range of forces would be optimal.

Appendix A

Prototype

A.1 Dynamic Fluid Loss Cell



Figure A-1: Engineering Drawing of the Dynamic Fluid Loss Cell

A.2 Machined Parts







Figure A-3: Top Cap



Figure A-4: Middle Cap



Figure A-5: Seal Retainer



Figure A-6: Housing



 ς_{i}^{2}



Figure A-8: Test Piece



A.3 Seal and Excruder Specifications

GREENE, TWEED A**DVANC**AP[™] 2510 ROD SEALS

FOR NO-BACKUP RING GLAND PER MIL-G-5514F

OPERATE WITH LOW FRICTION

- ELIMINATE "O" RING SPIRAL FAILURE
- PREVENT EXTRUSION
- USE STANDARD "O" RINGS

HOW TO SPECIFY



TABLE 1 CAP MATERIAL SELECTION

MATERIAL CODE	DESCRIPTION	USE				
019	(P4) Graphite Filled PTFE	Low friction material with good wear properties. Recommended for static and dynamic applications at low and high pressure.				
022	(P5) Glass & MoS ₂ Filled PTFE	Good extrusion resistance & wear properties. Recommended for high pressure & loads. (Not recommended with soft metals i.e., aluminum.)				
041	(P1) ENERLON™ Pigmented PTFE	Similar to virgin PTFE, but with improved wear properties.				
069	AVALON 50	High-temperature, wear resistant. For high-temperature, high surface speed applications. (May abrade soft metals)				
096	ROTOLON 100 Glass, MoS ₂ , PTFE	High-pressure-, wear-, extrusion-resistant. For high-pressure, high-temperature, high loads, high surface speed applica- tions. (Not recommended for sealing against soft metals)				

TABLE 2 OPTIONAL "O" RING ENERGIZER SELECTION

DESIGNATOR	ELASTOMER MATERIAL	ELASTOMER SPECIFICATION	TEMPERATURE RANGE	SERVICE		
11	Nitrile	MIL-P-25732	- 65 to 275F	MIL-H-5606 Fluid		
- 12	Nitrile	MIL-P-83461	- 65 to 275F	MIL-H-83282 Fluid		
13	Nitrile	MIL-P-5315	- 65 to 225F	Jet fuels		
21	Ethylene Propylene	NAS 1613	- 65 to 300F	Skydrol, Aerosafe and similar phosphate-based fluids		
31	Fluorocarbon	MIL-R-83248 Class 1	- 20 to 437F	High-temperature hydrocarbon and synthetic fluids. Di-ester. lubricant, MIL-L-7808, Oronite 8515, MIL-L-6085, and silicone fluids and greases.		
00	If "O" ring is to be ordered as separate component.					

NOTE: For pressures above 3000 psi, clearances above standard and alternative cap and energizer materials, contact Advantec, Division of Greene, Tweed Industries, (714) 893-0903.

Figure A-10: Green Tweed Rod Seals

2510 ROD SEALS

FOR NO-BACKUP RING GLAND PER MIL-G-5514F

ROD SEAL INSTALLATION

4



TABLE 3 DIMENSIONAL INFORMATION

AS 568A UNIFORM DASH NO	E DIA.	B DIA.	AS 568A UNIFORM DASH NO.	E DIA.	B DIA,	AS 568A UNIFORM DASH NO.	E DIA.	B DIA.	AS 568A UNIFORM DASH NO.	E DIA.	B DIA.
	+.001 000	+ 000 - 001	,	+.002 000	+.000		+.002 000	+ .000 002		+.002 000	+.000
			125 126 127	1.488	1.310	228 229	2.491 2.616	2.248 2.373	348 349	4.744 4.869	4.372 4.497
006 007	.235	.123	128 129	1.676 1.738	1.498 1.560	230 231 232	2.741 2.866 2.991	2.498 2.623 2.748		+.003 000	+.000
008	.297	185	130 131	1.801 1.863	1.623 1.685	233 234	3.116 3.240	2.873 2.997	425 426 427	4.974 5.099 5.224	4.497 4.622 4.747
010	360	248	132 133	1.926	1.748	235 236	3.365 3.490	3.122 3.247	428 429	5.349 5.474	4.872 4.997
C012	485	.373	134	2.051	1.936	237 238	3.615	3.372 3.497	430 431	5.599 5.724	5.122 5.247
013	000 .547	002	130 137 138	2.239 2.301	2.061	240	3.990	3.747	432 433	5.849 5.974	5.372 5.497 5.672
014 015 016	.610 .672 .735	.498 .560 .623	139 140	2.364 2.426	2.186 2.248	242 243	4.240 4.365	3.997 4.122	435	6.224	5.747
017	.797	685	141 142	2.489	2.311	244 245	4.490 4.615	4.247 4.372	430 437 438	6.474	5.997 6.247
019 020	.922 .985	.810 873	144	2.676	2.498	246 247	4,740 4.865	4.497 4.622	439 440	6.974 7.224	6.497 6.747
021	1.047	.935 .9 9 8	145 146 147	2.801 2.864	2.623	325 326 327	1.870 1.995 2.120	1.498 1.623 1.748	441	7.474	6.997 7.247 7.407
023 024 025	1.172 1.235 1.297	1.060	148 149	2.926 2.989	2.7 48 2.811	328 329	2.245 2.370	1.873 1.998	444	8.224	7.747
026 027	1.360	1.248	210 211 212	.991	.748	330 331	2.495 2.620	2.123 2.248	446	8.974	8.497
110	.551	.373	213 214	1.178 1.241	.935	332 333 334	2.745 2.870 2.995	2.498 2.623	447	+.004 000	+.000 003 (
1 12 1 13	676_ 738	498	215 216	1.303 1.366	1.060 1.123	335 336	3.120 3.245	2.748 2.873	448 449	9.974 10.474	9.497 9.997
114 115	.801 .863	.623 .685	217 218 219	1.428 1.491 1.553	1.185 1.248 1.310	337 338 339	3,369 3,494 3,619	2.997 3.122 3.247	450 451	10.974 11.474	10.497 10.997
116 117 118	.926 .988 1.051	.748 .810 .873	220 221	1.616 1.678	1.373	340 341	3.744	3.372	452 453 454	11.974 12.474 12.974	11.497 11.997 12.497
119 120	1.113	.935 .998	222 223	1.741	1.498 1.623	342 343	3.994 4.119	3.622 3.747	455 456	13.474	12.997 13.497
121 122	1.238	1.060	224	2.116	1.748	344 345	4.244 4.369	3.872 3.997	457 458	14.474 14.974	13.997 14.497
123	1.363	1.185	226	2.241	1.998 2.123	346 347	4.494 4.619	4.122	459 460	15.4/4	14.997 15.497

TABLE 4 GLAND DIMENSIONS

GROOVE	R RADIUS	D DIAMETRAL CLEARANCE
+.010 000		MAX.
.094	.005/.015	.004
.094	005/.015	:'005
.141	005/.015	.005
.141	.905/.015	.006
.141	005/.015	.007
.188	010/.025	.005
.188	010/.025	.006
.188	010/.025	.007
.188	010/.025	.008
.281	020/.035	.006
.281	020/.035	.007
.375	020/.035	.00(
.375	020/.035	.010
	G GROOVE WIDTH 000 .094 .094 .141 .141 .141 .188 .188 .188 .188 .18	G GROOVE WIDTH R ADJUS - 300 - 300

***O-RING SQUEEZE LEVEL**

The addition of any cap to an O-ring gland will increase O-ring squeeze and gland occupancy. This may result in excessive friction, unsatisfactory service life or installation difficulty. By increasing the gland diameter, as shown in Table 5, these problems can be alleviated without reducing O-ring squeeze below the minimum of MIL-G-5514F.

TABLE 5 GLAND DIAMETER CHANGE

At the Forefront of Sealing Technology

O-RING DASH NO.	006 thru 028	110 thru 149	110 210 thru thru 149 247		425 thru 460
"E" DIA.	010"	010"	018"	018"	025″

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Figure A-11: Green Tweed Rod Seals



Shamban Turcite® Excluder®

The Multi-Purpose PTFE® Wiper for Industrial Fluid Power Piston Rods and Valve Spools

- Seals out fine particle contamination
- Protects primary rod seal and acts as secondary seal
- Scrapes and cleans without damaging rod
 Prevents r
- Offers low friction of filled PTFE®-Turcite®

Shamban has proven the effectiveness of the

Excluder in actual field tests. Dust and other

abrasive contaminating materials such as would

be encountered on skip loaders, power steering

units, machine tools and hydraulic or pneumatic

presses, are prevented by the Excluder from mi-

grating into rod end bearings and seals, or on

In critical applications when damage or wear of

a primary rod seal can cause loss of hydraulic

fluid and system pressure, the Excluder as a

secondary seal will provide an additional margin

of safety by preventing excessive leakage until

into the entire fluid power system.

- Protects primary rod sear and dots us boomdary of
 Prevents rod scoring and improves service life
- Installs quickly and easily
 Rugged and dependable









Outside View

Excluder Assembly is made up of an Excluder ring and an o-ring.

repairs can be made.

Hydraulic Actuator after cycling tests under exposure to a turbulent environment containing Arizona road dust.

Gland as removed after test of the hydraulic actuator shown above

The total effect of the Excluder means that hydraulic and pneumatic actuators and valves can be completely protected from external contamination and when unexpected rod seal replacement becomes necessary, it can be accomplished at a convenient time due to the interim fluid sealing capability of the Excluder, even at high pressure. Thus maintenance costs and unscheduled over-haul are significantly reduced.

Shamban Turcite Excluders are available in standard sizes ranging from a nominal 1/4" to 13" dia. rod. See reverse side for complete listing of standard sizes and hardware design details.

SHAMBAN SEALS DIVISION INDUSTRIAL PRODUCTS GROUP 2531 BREMER DRIVE P.O. BOX 176 FORT WAYNE, INDIANA 46801 219-749-9631 TELEX: 22-8480 TELEFAX: 219-749-0066

Figure A-12: Shamban Turcite Excluder

STANDARD SIZES AND HARDWARE DESIGN DETAILS

ROD Size No	USA Sto. Rod Dia	SERIES 23E* Regular Duty Excluders			SERIES 25E** Light duty Excluders		
190.	893.3 1968	GROOVE DIA. A	ARP O-RING Size		GROOVE DIA. A	ARP 0-Ring Size	
	+.000 003	+.003 ~.000			+.003 000		
00312	5/16	.500	012				
00375	3/8	.563	013				
00500	1/2	.768	113		.688	015	
00625	5/8	.893	115		.813	017	
00687	11/10	.900	110		.875	018	
	+.000	+.004			+.004		
00750	004	000	447		000	040	
00750	3/4	1.018	117		1.063	019	
01000	1 1	1.143	121		1 188	021	
01125	1-1/8	1.393	123		1.313	025	
01250	1-1/4	1.518	125		1.438	027	
01375	1-3/8	1.643	127		1.563	028	
	+.000	+.005			+.005		
	005	000			000		
01500	1-1/2	1.768	129	ļ	1.688	029	
01/50	1-3/4	2.018	133	ł	1.938	031	
02000	2-1/4	2.200	141	ł	2.100	035	
02500	2-1/2	2.510	145		2 688	037	
02750	2-3/4	3.098	233		1.000		
03000	3	3.348	235	1			
03500	3-1/2	3.848	239				
04000	4	4.348	243	1			
	+.000	+.006					
1	006	000					
04500	4-1/2	4.848	247		1		
05000	5	5.348	251				
05500	5-1/2	5.848	255	1			
07000	7	0.348	200				
08000	8	8 348	266	ļ	1		
08500	8-1/2	8 848	268	1	1		
09000	9	9.348	270				
10000	но	10.348	274				

 $= \frac{1}{2} \frac{1}{\frac{1}{1+1}} \frac{$

GLAND DESIGN TABLE GROOVE ROD WIDTH F MAX DIA. G +.005 -.000 SERIES NO. 23E 5/16-3/8 .144 .053 1/2-2-1/2 . 195 ,068 2-3/4-10 .240 .078 SERIES NO. 25E 1/2-2-1/2 .144 .053 Vent recommended betwee Excluder and Primary Rod Seal when system pressure exceeds 1500 psi T Q DIA HOW TO ORDER Use descriptive part number as follows EXAMPLE 23E 00750 А 42 SERIES NO. ROD SIZE NO. O-RING CODE LETTER (See Table I).

EXCLUDER TURCITE CODE NO. (See Table II) ____

TABLE I

SEAL MATERIAL SELECTION O-Ring compound code letters for Shamban sealing system						
ENVIRONM	ENT	COMPOUND CODE LETTERS				
TYPE OF FLUID	TEMPERATURE	PREFERRED	ALTERNATE			
AIR	Up to 250°F	Α	н			
Water and water based fluids		A	H			
STEAM	Up to 300°F	н	C			
Petroleum Oils	-40° to 250°F	A	G, E			
including MIL-0-5606	-65° to 250°F	G				
SYNTHETIC OILS e.g. phosphate esters, skydrol, pydraul, etc.	-65° to 300°F	н	E (Pydrauf)			
A=BUNA-N, G= E=VITON	BUNA-N, C=BU	TYL, H=ETHYLE	NE PROPYLENE			

			TABL	E				
т	SEA urcite® Code	L MA	TERIA ers for	L SE	LECTI ban Se	ON aling S	ystem	5
	MOONENT				ENVIRO	NMENT		
CU	MPUNEN		PNEU	MATIC	HYDRAULIC			
		Nitrogen, Air, Bottled Gas				Water and	Petroleum and synthetic oils	
CODE Letter	DESCRIPTION	Di	DRY LUBRICATED		water based fluids	2000 PSI	2000 PSI	
		Up to 160°F	Lip ta 250°F	Up to 160°F	Up to 250°F	3000 PSI°F	Up to 180°F	Up to 250°F
E	EXCLUDERS"	46	46	42	42	46	42	42
No	e: To specil O-Ring d	y exc	luder ound (ring c Code	niy su Letter.	ıbstitu	te X f	or

1

SD 002-A2

increased.

*Best for general purpose applications. Use in severe environments when maximum possible protection is necessary, when regular maintenance is limited or conditions of use are unpredictable. Best when Excluder must act as a secondary hydraulic seal.

**Adequate for most pneumatics.

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 W. S. Shamban & Co., Registered Trademark

Figure A-13: Shamban Turcite Excluder

-



Figure A-14: Sticking Force versus Time, Test 1



Figure A-15: Sticking Force versus Time, Test 2



Figure A-16: Sticking Force versus Time, Test 3



Figure A-17: Sticking Force versus Time, Test 4



Figure A-18: Sticking Force versus Time, Test 5



Figure A-19: Sticking Force versus Time, Test 6

Appendix B

Wireline Stickance Tester

B.1 Engineering Drawings of Machined Parts



n y ----

Figure B-1: Full Assembly, DRW0006



Figure B-2: Pressre Vessel, DRW0004



Figure B-3: Filter Assembly, DRW0001



Figure B-4: Housing Assembly, DRW0002




J

Figure B-6: O-ring Cap, MRCD301



Figure B-7: Top Cap, MRCD302



Figure B-8: Thermocouple Housing, MRCD303



Figure B-9: Upper Housing, MRCD304













Figure B-13: Filter Housing, MRCD308











Figure B-16: Test Piece Coupling, MRCD311



Figure B-17: Test Piece Assembly, MRCD312



Figure B-18: Test Piece Coupling for Cable, MRCD313



Figure B-19: Test Piece Assembly for Cable, MRCD314



Figure B-20: Load Cell Connector, MRCD315



Figure B-21: Actuator Rod, MRCD316







Figure B-23: Bottom Plate, MRCD318







Figure B-25: Top Plate, MRCD320

B.2 Outsourced Parts



Figure B-26: Pressure Bulk Head, DH549219

2-1/2" Bore Air Cylinders

- Ground and Polished, High Strength Carbon Steel Piston Rod Standard – 303 Stainless Steel Rod Available as an Option – Bronze Rod Guide Bushing Standard
- Force Exerted Approximately 5.0 of Air Line Pressure
- Double Acting Only
- Mounting Nuts Not Included

	5.191 5		OPTIC	ONS:	a senti	1. S. A.
NO	CHARGE	area anti-		Carlos -	and a for	
• 1	AGNALU	BE G (G	12:01	and the		
• F	ORTS RC	TATED	(K)	17 A.		
• ٨	O THREA	D (NT)		States and		
• S	IDE POR	ED REA	RHEAL) (Q)	i server	Service - The
A	dd .38" to	nose m	ount ove	erall leng	th.	

Enter Stroke Length as 3rd Digit



Double acting add \$15.40

DXDE add \$20.35

MODEL/PRICE	DESCRIPTION/WEIGHT (Jbs.)	DIMENSIONS	
50 - D 3//46/ 561.90 BASE PRICE Add \$2.40 per inch of stroke	Double Acting – Air Return – Front Nose Mounting Standard Stroke Lengths: ½", 1", 1½", 2", 2½", 3", 4", 5", 6" Maximum Stroke – 12" Stainless Steel Rod Add \$3.30 Optional Accessories: D-615-1 Mounting Bracket D-2540 Mounting Nut Base Weight: 1.98 Adder Per Inch of Stroke: .17	4/8 + 5002	252
50 -DXP BASE PRICE Add \$2.50 per inch of stroke	Double Acting – Universal Mounting Type – Pivot or Double End – Air Return – Bronze Rod Bushing and Bronze Pivot Bushing Standard Stroke Lengths: *, 1", 1%, 2", 2%, 3", 4", 5", 6", 7", 8", 9", 10", 11", 12", 13", 14", 15", 16", 17", 18", 19", 20", 21", 22", 23", 24" Maximum Stroke – 32" Stainless Steel Rod Standard Optional Accessories: D-231-3 Piston Rod Clevis D-620 Pivot Brackets D-2540 Mounting Nut Base Weight: 2.27 Adder Per Inch of Stroke: .17	101 552 + 5800 -101 101 -55 -2 101 -55 -2 101 -55 -2 101 -55 -2 101 -55 -2 101 -55 -2 101 -55 -2 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000 11 -57 000	2.8

Figure B-27: Bimba Stainless Steel Body Air Cylinders









Approx. NIL # 21230 MS 16023 Thickness 4 septem only 6s and testified at set of Type 310 ranks. INTERNAL rest. Thickness 4 septem only 6s and testified at set of Type 310 ranks. The set of	-	100	ISING	DIA.		TRUA	ARC RI	NG DI	MENS	IONS	GR	OOVE	DIME	NSIO	NS	AP	PLICA	TION D	ATA
Approx. Neuron INTERNAL mem. International association in the distribution of association in the d					MIL-R-21248 MS 16625	Thickn placed stainle	ess t app I rings.	For plat	to un- ed and					dia at ia		CLEAI	RANCE IETER	ALLOW. LOAD Sharp com	THRUST (Ibs.) er abutment
Date. intelli metti intelli metti intel			Approx.		INTERNAL SERIES	add 00 chickw ness less c groove	22" to the ess. Maxi will be have the width (1	Hiscod m mum rin Lat least listed m N).	tximum thick- .0002" inimum	Approx. weight	the may of conc and hou	cous indu conum sili antricity ssing.	between	FLOOAS	Nom-	When sprung	When	Rinds (Standard material)	Cold rolled steel bares and housings)
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	•	Dec. quiv. ach	inch	Approx.	N5000	FRE	E DIA.	тніс	KNESS	per 1000	DIAM	ETER	WID	тн	inal groove depth	inta hausing S	groove G	factor = 4	factor == 2 re Page 27
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		S	S	S	size—no.	D	toi.	t	tol.	lbs.	G	tol.	W	tol.	d	۹	C1	P,	Pt
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $		250	ł	6.4	N 5000-25	.280		.015	÷	.08	.268	±.001	.020	+.002	.009	.115	.133	420	190
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		312	- 14	7.9	N5000-31	.346		.015		.11	.330	T.I.R.	.020	000	.009	.173	.191	530	240
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		375	, ł	9.5	N 5000-37	.415		.025		.25	.397	±.002	.029		.011	.204	.226	1050	350
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		438	14	11.1	N5000-43	.482		.025		۶ <i>۲</i> .	.101	.002	.027		012	.23	274	1280	460
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$			11	11.3	113000-13	. 770		E.30.				1.1.6.	.027	4				1200	610
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		500		12.7	N 5000-50	.548	+.010	.035		.70	.530		.039		.015	.20	- 29	2030	570
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	<i>ش</i> ر	***		13.0	NI5000-S1	.560	005	.035		.//	.244	± .002	.037		.015	.27	305	2030	710
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $		304	11	15.9	N5000-42	.020		035		1.00	745	.004	039		.020	.34	.38	2470	1050
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		688	++	17.5	N 5000-48	.763		.035		1.2	.732	`T.I.R /	.039	1	.022	.40	.44	2700	1280
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		750		100		021		076	4		754		029	+.003	m3	45	49	3000	1460
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		777	1	19.0	N 5000-73	959		.035		1.3	825		046		.024	475	.52	4550	1580
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		812	44	20.6	N 5000-41	.901		042		1.9	.862		.046		.025	.49	.54	4800	1710
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		866	·	22.0	N 5000-86	.961		.042		2.0	.920		.046		.027	.54	.59	5100	1980
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		875	ł	22.2	N 5000-87	.971		.042	ļ	2.1	.931	± .003	.046		.028	.545	.60	5150	2080
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		901		72.9	N 5000-90	1.000	+.013	00	+ 007	22	959	.004	046	1	.029	.565	.62	5350	2200
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		938	- 14	23.8	N 5000-93	1.041		.042		2.4	1.000	T.I.R.	.046		.031	.61	.67	5600	2450
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	1.	000	1	25.4	N 5000-100	1.111		.042	i	2.7	1.066	1	.046	1	.033	.665	.73	5950	2800
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	4.	023		26.0	N 5000-102	1.136		.042	i	2.8	1.091		.046		.034	.69	.755	6050	3000
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	1.	062	1.4	27.0	N5090-106	1.180		.050		3.7	1.130		.056		.034	.685	.75	7450	3050
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	1.	125	14	28.6	N 5090-112	1.249	1	.050	1	4.0	1,197	1	.056	1	.036	.745	.815	7900	3400
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	1.	181	- I	30.0	N5000-118	1.319		.050		4.3	1.255		.056		.037	.79	.86	8400	3700
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	1.	189	14	30.2	N5000-118	1.319		.050		4.3	1.262		.056		.037	.80	.87	8400	3700
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Ι.	250	14	31.7	N 5080-125	1.388		.050		4.8	1.330		.056		.040	.875	.955	8800	4250
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	<u>,</u> 1,	259		32.0	N5000-125	1.388	+.025	.050		4.8	1.339		.056		.040	.885	.965	8900	4250
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	1	312	17	33.3	N 5000-131	1.456	- 020	.050	1	5.0	1.396	1	.056		.042	.93	1.01	9300	4700
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	- L	375	14	34.9	N5008-137	1.526		.050		5.1	1.461	±.004	.056	1.004	.043	.99	1. 07	9700	5050
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	1	378		35.0	N 5000-137	1.526		.050		5.1	1.464	TIR	.056	000	.043	.99	1.07	9700	5050
1.456	1.	438	14	36.5	N 5000-143	1.596		.050		5.8	1.528	1	.056		.045	1.06	1.15	10200	5500
1.500 1↓ 38.1 N5000-150 1.660 .050 6.5 1.594 .056 .047 1.12 1.21 10550 6000 1.542 1+ 39.7 N5000-156 1.734 .062 8.9 1.658 .068 .048 1.14 1.23 10700 6350 1.575 40.0 N5000-166 1.734 - .062 8.9 1.671 ±.005 .068 .048 1.14 1.23 13700 6350 1.625 1↓ 41.3 N5000-162 1.804 025 .062 ±.003 10.0 1.725 .005 .068 .048 1.15 1.24 13700 6350 1.625 1↓ 41.3 N5000-162 1.804 025 .062 ±.003 10.0 1.725 .005 .068 .050 1.15 1.25 14200 6900 1.633 42.0 N5000-165 1.835 .062 10.4 1.755	1.	456		37.0	N 5080-145	1.616	1	.050		6.4	1.548]	.056		.046	1.08	1.17	10300	5/00
1.522 1+7 39.7 N5000-156 1.734 .062 8.9 1.658 .068 .048 1.14 1.23 13700 6350 1.575 40.0 N5000-156 1.734 +.035 .062 8.9 1.671 ±.005 .068 .048 1.14 1.23 13700 6350 1.625 14 41.3 N5000-162 1.804 025 .062 3.9 1.671 ±.005 .068 .048 1.15 1.24 13700 6350 1.625 14 41.3 N5000-162 1.804 025 .062 ±.003 1.04 1.735 .050 .068 .050 1.15 1.25 14700 6350 1.635 42.0 N5000-162 1.835 -025 .062 ±.003 10.4 1.755 T.I.R. .068 .050 1.15 1.27 14500 7200 1.649 1.14 1.14 1.15 1.15 1.14500	1	500	14	38.1	N5000-150	1.660	L	.050	1	6.5	1.594	1	.056		.047	1.12	1.21	10550	6000
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1.	562	1#	39.7	N5000-156	1.734		.062		8.9	1.658	[.068		.048	1.14	1.23	13700	6350
1.625 14 41.3 N5000-162 1.804025 .062 ± .003 10.0 1.725 .005 .068 .050 1.15 1.25 14200 6900 1.633 42.0 N5000-165 1.835025 .062 10.4 1.755 T.I.R068 .051 1.17 1.27 14500 7200 1.690 10.4 1.755 T.I.R068 .051 1.17 1.27 14500 7200	1	575	-	40.0	N5000-156	1.734	+.035	.062		8.9	1.671	± .005	.068		.048	1.15	1.24	13700	6350
1,633 — 42,0 N\$5000-165 1.835 0.62 10.4 1.755 T.I.R. 0.68 10.51 1.17 1.27 14500 7.260	1	.625	14	41.3	N5000-162	1.804	025	.062	± .003	10.0	1.725	.005	.068	1	.050	1.15	1.25	14200	7200
	1	دده. ههه	1 m	42.0	N5000-165	1.835		.062		10.4	1.755	T.I.R.	.068	1	.051		1.27	14900	7450

Figure B-28: Waldes Truarc 0.562 in Retainer Ring





 $\left(\begin{array}{c} y \end{array} \right)$

HOUSING DIA.			4	TRUARC RING DIMENSIONS				GR	GROOVE DIMENSIONS				APPLICATION DATA						
			MIL-R-21248 MS 16625	Thickn plates stainl add .0	ess tap i rings. em steel 22" to the	plies only For play i (Type h i listed m	r to un- ted and d) rings, aximum		T.I.R.	(cocal ind	icator rea	uding) is		CLEARANCE DIAMETER		CLEARANCE LOAI DIAMETER Sharp com		ALLOW. LOAD Sharp come	THRUST (lbs.) crabutment
Dec.	Approx.		INTERNAL SERIES	thickne ness lass t groove	ess. Masci will be han the width (1	mum rm at less lisced m M).	e thick- e .0002" tinimum	Appros. weight	of con- and ho	centricity using.	between	evistion	Nom-	When sprung inco	When sprung	(Slandard material)	Cold rolled steel bores and housings)		
equer. Inch	equiv. inch	Approx. mm.	N5000	FREE	DIA.	DIA. THICKN	KNESS	1000 preces	DIAN	TER	WI	отн	groove depth	housing S	G	factor = 4	factor = 2 ee Page 27		
S	S	S	size—no.	D	tol.	t	tol.	lbs.	G	toi.	W	toi.	d	G	C,	P,	Pr		
3.625	31	92.1	N5000-362	4.024	± .055	.109		73.0	3.841	i	.120	1	.108	2.91	3.12	55900	33200		
3.740		95.0	N5000-375	4.157		.109	1	78.0	3.964	1	.120		.112	3.02	3.24	57700	35600		
3.750	34	95.2	N5000-375	4.157		.109		78.0	3.974		.120		.112	3.03	3.25	57700	35600		
3.875	37	98.4	N5000-387	4.291		.109		87.0	4.107		.120		.116	3.11	3.34	59600	38000		
3.938	3+2	100.0	N5000-393	4.358		.109		88.0	4.174	1	.120		.118	3.17	3.40	60700	39300		
4.000	4	101.6	N5060-400	4.424		.109	1	93.0	4,240	1	120	+ 005	120	121	3.47	61700	40700		
4.125	44	104.8	N5000-412	4.558	±.065	.109		97.0	4.365	±.006	120		120	1 36	3.60	63600	42000		
4.250	41	108.0	N5000-425	4.691		.109	±.003	101.0	4,490	.006	120	000	120	3.49	3 77	65500	43200		
4.331	- 1	110.0	N5000-433	4.756		.109	· ·	105.0	4.571	1.3.8.	120		120	3.50	3.74	64600	44500		
4.500	41	114.3	N5000-450	4.940		.109		111.0	4.740		120		.120	3.66	3.90	69300	45800		
4.625	43	117.5	N5000-462	5.076		109	-		4.865	1	120	-	120	1 79	4.01	71300	47000		
4.724	_	120.0	N5000-475	5.213		109		124.0	4.969	1	120		172	3.88	412	71200	49000		
4.750	44	120.6	N5000-475	5.213		.109		124.0	4.995	1	120		172	3.90	414	73200	49000		
5.000	5	127.0	N5000-500	5.485		.109		136.0	5.260		120		130	4.08	4 34	77000	. 55000		
5.250	5±	133.3	N5000-525	5.770		.125		174.0	5.520		.139		.135	4.31	4.58	92700	60000		
5.375	54	136.5	N5000-537	5 910		125		179.0	5 650	+ 007	130	1	1.175	4.41	4 4 9	94900	41500		
5.500	54	139.7	N 5000-550	6.066		125	±.004	183.0	5 770	006	139	+.006	1133	4.52	4.90	97200	43300		
5.750	54	146.0	NI5000-575	6 336		125	i	1 197 0	6.000	TIR	130	000	135	4 79	5.00	101400	45900		
6.000	6	152.4	N5000-600	6 620		125		201.0	6 270	1.1.14	139		135	5.02	5.30	105900	49400		
6.250	61	158.7	N5000-625	6.895		.156		266.0	6.530		.174		.140	5.24	5.52	137700	74100		
6 500	61	165.1	N5000-450	7 170		164		281.0	6 790	-	174	4		6.40	5 70	142200	79800		
6.625	64	168.3	NI5000-442	7 308	+ 080	156		305.0	6 975	.1/4	174		140	5.47	5.70	146000	94200		
6.750	64	171.4	N5000-475	7 445	±.080	156		325.0	7.055	•	174		.150	5.60	5.70	149900	87000		
7.000	7	177.8	N/5000-700	7 720		156		744.0	7 315	1	174		.134	5.00	5.73	154300	93100		
7.250	7	184.1	N5000-725	7.995		.187		428.0	7.575		.209		.162	6.08	6.40	191500	99600		
7.500	71	190.5	N5000.750	8 270		197		495.0	7 840	ł	200	-	170	4 33	6.67	198300	109100		
7.750	71	196 B	N5800-775	8 545		197		520.0	9 100	+ 000	205		176	6.33	6.07	304900	115000		
8.000	8	203.2	N 5000-000	8.820		187	± .005	555.0	8 160	004	209	+.008	180	6.75	711	211400	172000		
8.250	84	209.5	N5000-825	9.095		187		603.0	8.620	TLR	209	000	185	7.00	7 17	219000	129300		
8.500	84	215.9	N5000-850	9.285		.187		634.0	8.890		.209		.190	7.13	7.51	224600	136900		
8,750	83	222.2	N5000-875	9.558	±.090	187		653.0	9145		209		197	7 18	777	730400	145500		
9.000	9	228.6	N5000-900	9 830		187		737.0	9.405		209		202	7 63	8.01	237800	154100		
9.250	94 1	235.0	N 5000-925	10,102		187		767.0	9.668		209		209	7 89	8 10	244400	63600		
9.500	91	241.3	N 5000-950	10.375	- 1	187		803.0	9,930		209		215	7.98	8.41	251000	173100		
9.750	94	247.7	N5000-975	0.648		.187		833.0	10.190		209		270	8.23	8.67	257600	181900		
0.000	10	254.0	NI5000-1000	10.9201		187		863.0	10.450		209		225	8.49	8.93	264200	90700		

Figure B-29: Waldes Truarc 4.0 in Retainer Ring

B.3 Load Cell Calibration Data

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1/14/99 DATE:

INDUSTRIAL SENSORS & INSTRUMENTS, INC.

308 TEXAS AVENUE, SUITE 104

ROUND ROCK, TEXAS 78684

FAX (512) 255-8655 (512) 255-3790

CALIBRATION DATA

ISI P/N:	DUG-0.5	S/N:	3655
CUST. P/N:	Engr. Proto.	CUSTOMER:	Schlumberger
CAPACITY:	±500 lbs	P.O. NO.:	3GP08542-2
EXCITATION:	10.0031 V dc	SENSITIVITY:	See Below
SOURCE:	Satec 60HVL		

LOAD (Ib)

OUTPUT (µV)

500	15680
400	12524
. 300	9378
200	6227
100	3080
0	-56
-100	-3199
-200	-6339
-300	-9489
-400	-12639
-500	-15791

Tension Sensitivity:1.5731mV/V at +500 lbs.Compression Sensitivity:-1.5730mV/V at -500 lbs.

CONNECTIONS:

RED	+ EXCITATION	
BLACK	- EXCITATION	
GREEN	+ SIGNAL	
WHITE	- SIGNAL	

Figure B-30: Calibration Data

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