

#### 2.29 Numerical Fluid Mechanics Fall 2011 – Lecture 19

#### **REVIEW Lecture 18:**

- Finite Volume Methods
  - Integral and conservative forms of the cons. laws
  - Introduction
  - Approximations needed and basic elements of a FV scheme
    - Time-Marching and Grid generation
    - FV grids: Cell centered (Nodes or CV-faces) vs. Cell vertex; Structured vs. Unstructured
    - Approximation of surface integrals (leading to symbolic formulas)
    - Approximation of volume integrals (leading to symbolic formulas)
    - Summary: Steps to step-up a FV scheme
  - One Dimensional examples
    - Generic equation:  $\frac{d\left(\Delta x \,\overline{\Phi}_{j}\right)}{dt} + f_{j+1/2} f_{j-1/2} = \int_{x_{j-1/2}}^{x_{j+1/2}} s_{\phi}(x,t) \, dx$
    - Linear Convection (Sommerfeld eqn): convective fluxes
      - 2<sup>nd</sup> order in space



### Summary: 3 basic steps to set-up a FV scheme

- Grid generation (CVs)
- Discretize integral/conservation equation on CVs

– This integral is: 
$$\frac{d\Phi}{dt} + \int_{S} \vec{F}_{\phi} \cdot \vec{n} \, dA = S_{\phi}$$

- Which becomes for V fixed in time:  $V \frac{d\overline{\Phi}}{dt} + \int_{S} \vec{F}_{\phi} \cdot \vec{n} \, dA = S_{\phi}$ where  $\overline{\Phi} = \frac{1}{V} \int_{V} \rho \phi dV$  and  $S_{\phi} = \int_{V(t)} s_{\phi} \, dV$
- This implies:
  - The discrete state variables are the averaged values over each cell (CV):  $\bar{\Phi}_{_P}$ 's
  - Need rules to compute surface/volume integrals as a function of  $\phi$  within CV
    - Evaluate integrals as a function of  $\phi_e$  values at points on and near CV.
    - Need to interpolate to obtain these  $\phi_e$  values on and near CV from averaged  $\overline{\Phi}_P$ 's of nearby CVs
  - Other approach: impose piece-wise function  $\phi$  within CV, ensures that it satisfies  $\overline{\Phi}_{p}$ 's constraints, then evaluate integrals (surface and volume)
  - Select scheme to resolve/address discontinuities
- Solve resultant discrete integral/flux eqns: (Linear) algebraic system for  $\overline{\Phi}_{P}$ 's



#### FV METHODS Basic Elements of FV Scheme

- 1. Given  $\overline{\Phi}$  for each CV, construct an approximation to  $\phi(x, y, z)$ in each CV and evaluate fluxes  $F_{\phi}$ 
  - Find  $\phi$  at the boundary using this approximation, evaluate fluxes  $F_{\phi}$
  - This generally leads to two distinct values of the flux for each boundary
- 2. Apply some strategy to resolve the flux discontinuity at the CV boundary to produce a single  $F_{\phi}$  over the whole boundary
- 3. Integrate the flux  $F_{\phi}$  to obtain  $\int_{S} \vec{F}_{\phi} \cdot \vec{n} \, dA$  : Surface Integrals
- 4. Compute  $S_{\phi}$  by integration over each CV: Volume Integrals
- 5. Advance the solution in time to obtain the new values of  $\overline{\Phi}$

$$V\frac{d\bar{\Phi}}{dt} + \int_{S} \vec{F}_{\phi}.\vec{n} \, dA = S_{\phi}$$

Time-Marching



#### TODAY (Lecture 19): FINITE VOLUME METHODS

- Summary: Steps to step-up a FV scheme
- Examples: One Dimensional examples
  - Generic equations
  - Linear Convection (Sommerfeld eqn): convective fluxes
    - 2<sup>nd</sup> order in space, 4<sup>th</sup> order in space, links to CDS
  - Unsteady Diffusion equation: diffusive fluxes
    - Two approaches for 2<sup>nd</sup> order in space, links to CDS
- Approximation of surface integrals and volume integrals revisited
- Interpolations and differentiations
  - Upwind interpolation (UDS)
  - Linear Interpolation (CDS)
  - Quadratic Upwind interpolation (QUICK)
  - Higher order (interpolation) schemes
- Time-Marching Methods: Euler's methods



- Chapter 29.4 on "The control-Volume approach for Elliptic equations" of "Chapra and Canale, Numerical Methods for Engineers, 2010/2006."
- Chapter 4 on "Finite Volume Methods" of "J. H. Ferziger and M. Peric, Computational Methods for Fluid Dynamics. Springer, NY, 3<sup>rd</sup> edition, 2002"
- Chapter 5 on "Finite Volume Methods" of "H. Lomax, T. H. Pulliam, D.W. Zingg, *Fundamentals of Computational Fluid Dynamics (Scientific Computation).* Springer, 2003"
- Chapter 5.6 on "Finite-Volume Methods" of T. Cebeci, J. P. Shao, F. Kafyeke and E. Laurendeau, Computational Fluid Dynamics for Engineers. Springer, 2005.



#### **One-Dimensional Example II**

Linear Convection (Sommerfeld) Eqn: 4<sup>th</sup> order approx.

1D exact integral equation still

$$\frac{d\left(\Delta x \,\overline{\Phi}_{j}\right)}{dt} + f_{j+1/2} - f_{j-1/2} = 0$$



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- Use 4<sup>th</sup> order accurate surface/volume integrals
  - Replace piecewise-constant approx. to  $\phi(x)$  with piece-wise quadratic approx ( $\xi = x x_j$ ):  $\phi(\xi) = a\xi^2 + b\xi + c$
  - Satisfy  $\overline{\Phi}_{P}$ 's (average) constraints, i.e. choose a, b, c so that:

$$\frac{1}{\Delta x} \int_{-3\Delta x/2}^{-\Delta x/2} \phi(\xi) \, d\xi = \overline{\phi}_{j-1} \,, \quad \frac{1}{\Delta x} \int_{-\Delta x/2}^{+\Delta x/2} \phi(\xi) \, d\xi = \overline{\phi}_{j} \,, \quad \frac{1}{\Delta x} \int_{\Delta x/2}^{3\Delta x/2} \phi(\xi) \, d\xi = \overline{\phi}_{j+1}$$

– This gives:

$$a = \frac{\overline{\phi}_{j+1} - 2\overline{\phi}_j + \overline{\phi}_{j-1}}{2\Delta x^2}, \quad b = \frac{\overline{\phi}_{j+1} - \overline{\phi}_{j-1}}{2\Delta x}, \quad c = \frac{-\overline{\phi}_{j-1} + 26\overline{\phi}_j - \overline{\phi}_{j+1}}{24}$$

– We still need to evaluate the values of  $\phi(x)$  at the boundaries so as to compute the advective fluxes at these boundaries:  $f_{j-1/2}^L$ ,  $f_{j-1/2}^R$ ,  $f_{j+1/2}^L$ ,  $f_{j+1/2}^R$ 

#### One-Dimensional Example II Linear Convection (Sommerfeld) Eqn: 4<sup>th</sup> order approx.

• Since 
$$f = c \phi \Rightarrow$$
 compute  $\phi$  at surfaces:  
 $\phi_{j-1/2}^{L} = \frac{2\overline{\phi}_{j} + 5\overline{\phi}_{j-1} - \overline{\phi}_{j-2}}{6}, \quad \phi_{j+1/2}^{L} = \frac{2\overline{\phi}_{j+1} + 5\overline{\phi}_{j} - \overline{\phi}_{j-1}}{6},$ 

 $\phi_{j-1/2}^{R} = \frac{-\overline{\phi}_{j+1} + 5\overline{\phi}_{j} + 2\overline{\phi}_{j-1}}{6}, \quad \phi_{j+1/2}^{R} = \frac{-\overline{\phi}_{j+2} + 5\overline{\phi}_{j+1} + 2\overline{\phi}_{j}}{6}$ 



• Resolve flux discontinuity  $\Rightarrow$  again, use average values

$$\hat{f}_{j-1/2} = \frac{f_{j-1/2}^{L} + f_{j-1/2}^{R}}{2} = \frac{c\phi_{j-1/2}^{L} + c\phi_{j-1/2}^{R}}{2} \qquad \qquad \hat{f}_{j+1/2} = \frac{f_{j+1/2}^{L} + f_{j+1/2}^{R}}{2} = \frac{c\phi_{j+1/2}^{L} + c\phi_{j+1/2}^{R}}{2} \\ \Rightarrow \hat{f}_{j-1/2} = c\frac{-\overline{\phi}_{j+1} + 7\overline{\phi}_{j} + 7\overline{\phi}_{j-1} - \overline{\phi}_{j-2}}{12} \qquad \qquad \Rightarrow \hat{f}_{j+1/2} = c\frac{-\overline{\phi}_{j+2} + 7\overline{\phi}_{j+1} + 7\overline{\phi}_{j} - \overline{\phi}_{j-1}}{12}$$

• Done with integrals  $\Rightarrow$  we can substitute in 1D conv. eqn:

$$\frac{d\left(\Delta x \ \overline{\Phi}_{j}\right)}{dt} + f_{j+1/2} - f_{j-1/2} \approx \frac{d\left(\Delta x \ \overline{\phi}_{j}\right)}{dt} + \hat{f}_{j+1/2} - \hat{f}_{j-1/2} \qquad \Rightarrow \quad \Delta x \frac{d\overline{\phi}_{j}}{dt} + c \frac{-\overline{\phi}_{j+2} + 8\overline{\phi}_{j+1} - 8\overline{\phi}_{j-1} + \overline{\phi}_{j-2}}{12} = 0$$

• For periodic domains:

$$\frac{d \,\overline{\mathbf{\Phi}}}{dt} + \frac{c}{2\Delta x} \,\mathbf{B}_P(-1, -8, 0, 8, 1) \,\overline{\mathbf{\Phi}} = 0$$

Numerical Fluid Mechanics



Centered

Differences

First Derivative
 Error

 
$$f'[x_i] = \frac{f(x_{i+1}) - f(x_{i-1})}{2h}$$
 $O(h^2)$ 
 $f'[x_i] = \frac{-f(x_{i+2}) + 8f(x_{i+1}) - 8f(x_{i-1}) + f(x_{i-2})}{12h}$ 
 $O(h^4)$ 

 Second Derivative
  $P''(x_i) = \frac{f(x_{i+1}) - 2f(x_i) + f(x_{i-1})}{h^2}$ 
 $O(h^2)$ 
 $f''(x_i) = \frac{-f(x_{i+2}) + 16f(x_{i+1}) - 30f(x_i) + 16f(x_{i-1}) - f(x_{i-2})}{12h^2}$ 
 $O(h^2)$ 
 $f'''(x_i) = \frac{-f(x_{i+2}) - 16f(x_{i+1}) + 2f(x_{i-1}) - f(x_{i-2})}{12h^2}$ 
 $O(h^2)$ 

 Third Derivative
  $f'''(x_i) = \frac{-f(x_{i+3}) + 8f(x_{i+2}) - 13f(x_{i+1}) + 13f(x_{i-1}) - 8f(x_{i-2}) + f(x_{i-3})}{2h^3}$ 
 $O(h^2)$ 
 $f'''(x_i) = \frac{-f(x_{i+3}) + 8f(x_{i+2}) - 13f(x_{i+1}) + 13f(x_{i-1}) - 8f(x_{i-2}) + f(x_{i-3})}{8h^3}$ 
 $O(h^2)$ 

 Fourth Derivative
  $f'''(x_i) = \frac{f(x_{i+2}) - 4f(x_{i+1}) + 6f(x_i) - 4f(x_{i-1}) + f(x_{i-2})}{h^4}$ 
 $O(h^2)$ 
 $f''''(x_i) = \frac{-f(x_{i+3}) + 12f(x_{i+2}) + 39f(x_{i+1}) + 56f(x_i) - 39f(x_{i-1}) + 12f(x_{i-2}) + f(x_{i-3})}{6h^4}$ 
 $O(h^2)$ 

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2<sup>nd</sup> order approx. of diffusion equation:

$$\frac{\partial \phi(x,t)}{\partial t} = v \frac{\partial^2 \phi(x,t)}{\partial x^2}$$

1D exact integral equation same form!

$$\frac{d\left(\Delta x \,\overline{\Phi}_{j}\right)}{dt} + f_{j+1/2} - f_{j-1/2} = 0$$

but with: 
$$f = -v \nabla \phi = -v \frac{\partial \phi}{\partial x}$$



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Approximation of surface (flux) integral: Approach 1

- Direct: we know that to second-order (since  $\overline{\phi}_{j} = \phi_{j} + O(\Delta x^{2})$  and CDS)  $\frac{f_{j+1/2} = -v \frac{\partial \phi}{\partial x}\Big|_{j+1/2} = -v \frac{\overline{\phi}_{j+1} - \overline{\phi}_{j}}{\Delta x} + O(\Delta x^{2}) \implies \hat{f}_{j+1/2} = -v \frac{\overline{\phi}_{j+1} - \overline{\phi}_{j}}{\Delta x} \text{ and } \hat{f}_{j-1/2} = -v \frac{\overline{\phi}_{j} - \overline{\phi}_{j-1}}{\Delta x}$ 

- Substitute into integral equation:

$$\frac{d\left(\Delta x \ \overline{\phi}_{j}\right)}{dt} + \hat{f}_{j+1/2} - \hat{f}_{j-1/2} = \Delta x \frac{d \ \overline{\phi}_{j}}{dt} + v \frac{\overline{\phi}_{j-1} - 2\overline{\phi}_{j} + \overline{\phi}_{j+1}}{\Delta x} = 0$$

- In the matrix form, with Dirichlet BCs:
  - Semi-discrete FV scheme is as CDS in space,

but in terms of cell-averaged data

$$\frac{d \, \bar{\mathbf{\Phi}}}{dt} = \frac{\nu}{\Delta x^2} \, \mathbf{B}(1, -2, 1) \, \bar{\mathbf{\Phi}} + (\mathbf{bc})$$

#### One-Dimensional Example III 2<sup>nd</sup> order approx. of diffusion equation:



- Approximation of surface (flux) integral: Approach 2
  - Use a piece-wise quadratic approx.:  $\underline{\phi(\xi) = a\xi^2 + b\xi + c} \Rightarrow \frac{\partial \phi}{\partial x} = \frac{\partial \phi}{\partial \xi} = 2a\xi + b$ 
    - Note that a, b, c remain as before, they are set by the volume average constraints

• Since *a*, *b* are symmetric:  

$$f_{j+1/2}^{R} = f_{j+1/2}^{L} = -v \frac{\partial \phi}{\partial x}\Big|_{j+1/2} = -v \frac{\overline{\phi}_{j+1} - \overline{\phi}_{j}}{\Delta x} + O(\Delta x^{2})$$

$$f_{j-1/2}^{R} = f_{j-1/2}^{L} = -v \frac{\partial \phi}{\partial x}\Big|_{j-1/2} = -v \frac{\overline{\phi}_{j} - \overline{\phi}_{j-1}}{\Delta x} + O(\Delta x^{2})$$

- There are no flux discontinuities in this case
- Substitute into integral equation:

$$\frac{d\left(\Delta x \ \overline{\phi}_{j}\right)}{dt} + \hat{f}_{j+1/2} - \hat{f}_{j-1/2} = \Delta x \frac{d \ \overline{\phi}_{j}}{dt} + \nu \frac{\overline{\phi}_{j-1} - 2\overline{\phi}_{j} + \overline{\phi}_{j+1}}{\Delta x} = 0$$

- In the matrix form, with Dirichlet BCs:
  - Semi-discrete FV scheme is as CDS in space,

but in terms of cell-averaged data

$$\frac{d \,\overline{\Phi}}{dt} = \frac{v}{\Delta x^2} \,\mathbf{B}(1,-2,1) \,\overline{\Phi} + (\mathbf{bc})$$



Expressing fluxes at the surface based on cell-averaged (nodal) values: Summary of Two Approaches and Boundary Conditions

- Set-up of surface/volume integrals: 2 approaches (do things in opposite order)
  - 1. (i) Evaluate integrals using classic rules (symbolic evaluation); (ii) Then, to obtain the unknown symbolic values, interpolate based on cell-averaged (nodal) values

2. (i) Select shape of solution within CV (piecewise approximation); (ii) impose volume constraints to express coefficients in terms of nodal values; and (iii) then integrate. (this approach was used in the examples).

$$\begin{array}{l} (i) \ \phi_{a_i}(x) \equiv J_{a_i}(x) \\ (ii) \ \int\limits_{V_P} \phi_{a_i}(x) \equiv \overline{\phi_P} \end{array} \end{array} \Longrightarrow \phi_{a_i}(x) \equiv \phi_{\overline{\phi_P}}(x) \\ \Rightarrow F_e = F_e (\overline{\phi_P} \ s) \\ (iii) \ F_e = \int_{S_e} f_{\phi_{\overline{\phi_P}}} \ dA \end{array}$$

Similar for higher dimensions:

$$\phi(x, y) \equiv J_{a_i}(x, y); \quad etc$$
  
$$\phi_{a_i}(x_P, y_P) \equiv \phi_P; \quad etc$$

- Boundary conditions:
  - Directly imposed for convective fluxes
  - One-side differences for diffusive fluxes



Approach 1: Evaluate integrals symbolically, then interpolate based on neighboring cell-averages

- Surface/Volume integrals: Approach 1
  - (i) Evaluate integrals based on classic rules (symbolic evaluation)
  - (ii) Then, to obtain the unknown symbolic values, interpolate based on neighboring cell-averaged (nodal) values
- If we utilize the first approach
  - Symbolic evaluation:
    - To evaluate total surface fluxes (convective + diffusive),

$$\int_{S} \vec{F}_{\phi} \cdot \vec{n} \, dA = \int_{S} \underline{\rho \phi (\vec{v} \cdot \vec{n})} dA + \int_{S} \underline{\vec{q}}_{\phi} \cdot \vec{n} \, dA$$

values of  $\phi$  and its gradient normal to the cell face at one or more locations on that face are needed. They have to be expressed as a function of nodal values.

- Similar for volume integrals
- Next is interpolation:
  - Express the \u00f6's as a function of nodal values. Numerous possibilities. Only most common mentioned next.



## Approx. of Surface/Volume Integrals:

**Classic symbolic formulas** 

- Surface Integrals  $F_e = \int_{S_e} f_{\phi} \, dA$ 
  - -2D problems (1D surface integrals)
    - Midpoint rule (2<sup>nd</sup> order):
    - Trapezoid rule (2<sup>nd</sup> order):
    - Simpson's rule (4<sup>th</sup> order):
  - -3D problems (2D surface integrals)
    - Midpoint rule (2<sup>nd</sup> order):  $F_e = \int_{S_e} f_{\phi} dA \approx S_e f_e + O(\Delta y^2, \Delta z^2)$
    - Higher order more complicated to implement in 3D
- Volume Integrals:
  - -2D/3D problems, Midpoint rule (2<sup>nd</sup> order):  $S_P = \int_V s_{\phi} dV = \overline{s}_P V \approx s_P V$

- 2D, bi-quadratic (4<sup>th</sup> order, Cartesian):  $S_p = \frac{\Delta x \Delta y}{36} [16s_p + 4s_s + 4s_n + 4s_w + 4s_e + s_{sw} + s_{ne} + s_{nw}]$ 



Notation used for a Cartesian 2D and 3D grid. Image by MIT OpenCourseWare

$$F_e = \int_{S_e} f_{\phi} \, dA = \overline{f_e} S_e = f_e S_e + O(\Delta y^2) \approx f_e S_e$$
$$F_e = \int_{S_e} f_e \, dA \approx S_e \frac{(f_{ne} + f_{se})}{(f_{ne} + f_{se})} + O(\Delta y^2)$$

$$F_e = \int_{S_e} f_{\phi} \, dA \approx S_e \frac{2}{2} + O(\Delta y^{-1})$$
$$F_e = \int_{S_e} f_{\phi} \, dA \approx S_e \frac{(f_{ne} + 4f_e + f_{se})}{6} + O(\Delta y^{-1})$$



(to obtain fluxes " $F_e$ " as a function of cell-average values)

- Upwind Interpolation (UDS) for convective fluxes
  - Approximates  $\phi_e$  by its value at the node upstream of "e". This is equivalent to using backward or forwarddifference approx for a first derivative (depends on direction of flow) => Upwind Differencing Scheme, which is also called or Donor-cell.

$$\phi_e = \begin{cases} \phi_P \text{ if } (\vec{v} \cdot \vec{n})_e > 0\\ \phi_E \text{ if } (\vec{v} \cdot \vec{n})_e < 0 \end{cases}$$



Notation used for a Cartesian 2D and 3D grid. Image by MIT OpenCourseWare

- This approximation never yields oscillatory solutions (boundedness criterion), but it is <u>numerically diffusive</u>:
  - Taylor expansion about  $x_{\rm P}$ :  $\phi_e = \phi_P + (x_e x_P) \frac{\partial \phi}{\partial x}\Big|_P + \frac{(x_e x_P)^2}{2} \frac{\partial^2 \phi}{\partial x^2}\Big|_P + R_2$
  - UDS retains only first term: 1<sup>st</sup> order scheme in space

$$\hat{f}_e = \rho \,\phi_e \left( \vec{v} \cdot \vec{n} \right)_e \approx \rho \phi_P \left( \vec{v} \cdot \vec{n} \right)_e \qquad \Rightarrow \quad \tau_{\Delta x} = \rho \left( \vec{v} \cdot \vec{n} \right)_e \Delta x \frac{\partial \phi}{\partial x} \bigg|_P + \dots$$

- Leading truncation error is "diffusive", it has the form of a diffusive flux
- The numerical diffusion is  $\rho(\vec{v}.n)_e \Delta x$  (has 2 components when flow is oblique to the grid)



(to obtain fluxes " $F_e$ " as a function of cell-average values)

- Linear Interpolation (CDS) for convective/diffusive
  - Approximates  $\phi_{e}$  (value at face center) by its linear fluxes interpolation between two nearest nodes:

$$\phi_e = \phi_E \lambda_e + \phi_P (1 - \lambda_e)$$
 where  $\lambda_e = \frac{x_e - x_P}{x_E - x_P}$ 

+  $\lambda_{e}$  is the interpolation factor



Notation used for a Cartesian 2D and 3D grid. Image by MIT OpenCourseWare

- This approx. is 2<sup>nd</sup> order accurate (for convective fluxes):
  - Taylor expansion of  $\phi_{\rm E}$  about  $x_{\rm P}$  to eliminate first derivative:

$$\phi_{E} = \phi_{P} + (x_{E} - x_{P}) \frac{\partial \phi}{\partial x} \Big|_{P}^{L} + \frac{(x_{E} - x_{P})^{2}}{2} \frac{\partial^{2} \phi}{\partial x^{2}} \Big|_{P} + R_{2} \implies \frac{\partial \phi}{\partial x} \Big|_{P} = \frac{\phi_{E} - \phi_{P}}{x_{E} - x_{P}} - \frac{(x_{E} - x_{P})}{2} \frac{\partial^{2} \phi}{\partial x^{2}} \Big|_{P} - \frac{R_{2}}{x_{E} - x_{P}} \implies \phi_{e} = \phi_{P} + (x_{e} - x_{P}) \frac{\partial \phi}{\partial x} \Big|_{P} + \frac{(x_{e} - x_{P})^{2}}{2} \frac{\partial^{2} \phi}{\partial x^{2}} \Big|_{P} + R_{2} = \phi_{E} \lambda_{e} + \phi_{P} (1 - \lambda_{e}) - \frac{(x_{e} - x_{P})(x_{E} - x_{e})}{2} \frac{\partial^{2} \phi}{\partial x^{2}} \Big|_{P} + R_{2}^{*} = \frac{\phi_{E} \lambda_{e}}{2} + \phi_{P} (1 - \lambda_{e}) - \frac{(x_{e} - x_{P})(x_{E} - x_{e})}{2} \frac{\partial^{2} \phi}{\partial x^{2}} \Big|_{P} + R_{2}^{*} = \frac{\phi_{E} \lambda_{e}}{2} + \phi_{P} (1 - \lambda_{e}) - \frac{(x_{e} - x_{P})(x_{E} - x_{e})}{2} \frac{\partial^{2} \phi}{\partial x^{2}} \Big|_{P} + R_{2}^{*} = \frac{\phi_{E} \lambda_{e}}{2} + \phi_{P} (1 - \lambda_{e}) - \frac{(x_{E} - x_{P})(x_{E} - x_{e})}{2} \frac{\partial^{2} \phi}{\partial x^{2}} \Big|_{P} + R_{2}^{*} = \frac{\phi_{E} \lambda_{e}}{2} + \frac{\phi_{E} \lambda_$$

- Truncation error is proportional to square of grid spacing, on uniform/non-uniform grids.
- As all approximations of order higher than one, this scheme can provide oscillatory solutions
- Corresponds to central differences, hence its CDS name



# Interpolations and Differentiations (to obtain fluxes " $F_e$ " as a function of cell-average values)

#### Linear Interpolation (CDS) for convective/diffusive fluxes

 Linear profile between two nearest nodes leads to simplest approx. of gradient (diffusive fluxes)

$$\phi_{E}$$
  $_{P}(1)$ 

$$\left. \frac{\partial \phi}{\partial x} \right|_e \approx \frac{\phi_E - \phi_P}{x_E - x_P}$$

– Taylor expansions of  $\phi$ 's around  $x_{e}$ , one obtains:

$$\tau_{\Delta x} = \frac{(x_e - x_p)^2 - (x_E - x_e)^2}{2(x_E - x_p)} \frac{\partial^2 \phi}{\partial x^2} \bigg|_e - \frac{(x_e - x_p)^3 + (x_E - x_e)^3}{6(x_E - x_p)} \frac{\partial^3 \phi}{\partial x^3} \bigg|_e + R_e$$



Notation used for a Cartesian 2D and 3D grid. Image by MIT OpenCourseWare

- Approximation is  $2^{nd}$  order accurate if *e* is midway between *P* and *E* (e.g. uniform grid)
- When the grid is non-uniform, the formal accuracy is 1<sup>st</sup> order, but error reduction when grid is refined is asymptotically 2<sup>nd</sup> order



(to obtain fluxes " $F_e$ " as a function of cell-average values)

- Quadratic Upwind Interpolation (QUICK)
  - Approx. by quadratic profile between two nearest nodes.
  - In accord with convection, third point chosen on upstream side:
    - i.e. chose W if flow is from P to E, or EE if flow from E to P.

This gives:

$$\phi_{e} = \phi_{U} + g_{1} (\phi_{D} - \phi_{U}) + g_{2} (\phi_{U} - \phi_{UU})$$



Notation used for a Cartesian 2D and 3D grid. Image by MIT OpenCourseWare

where D, U and UU denote the downstream, first upstream and second downstream, respectively

- Coefficients in terms of nodal coordinates:  $g_1 = \frac{(x_e x_U)(x_e x_{UU})}{(x_D x_U)(x_D x_{UU})} ; \quad g_2 = \frac{(x_e x_U)(x_D x_e)}{(x_U x_{UU})(x_D x_{UU})}$
- Uniform grids: coefficients of  $\phi$ 's are 3/8 for node D, 6/8 for node U and -1/8 for node UU
- Somewhat more complex scheme than CDS (larger computational molecules by one node in each direction)
- Approximation is 3<sup>nd</sup> order accurate on both uniform and non-uniform grids. For uniform grids:

$$\phi_{e} = \frac{6}{8}\phi_{U} + \frac{3}{8}\phi_{D} - \frac{1}{8}\phi_{UU} - \frac{3\Delta x^{3}}{48}\frac{\partial^{3}\phi}{\partial x^{3}}\Big|_{U} + R_{3}$$

• But, when this interpolation scheme is used with midpoint rule for surface integral, becomes 2<sup>nd</sup> order



(to obtain fluxes " $F_e = f(\phi_e)$ " as a function of cell-average values)

- Higher Order Schemes (for convective/diffusive fluxes)
  - Interpolations of order higher than 3 make sense if integrals are also approximated with higher order formulas
  - In 1D problems, if Simpson's rule (4<sup>th</sup> order error) is used for the integral, a polynomial interpolation of order 3 can be used:

$$\phi(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3$$



Notation used for a Cartesian 2D and 3D grid. Image by MIT OpenCourseWare

=> 4 unknowns, hence 4 nodal values (W, P, E and EE) needed

= Symmetric formula for  $\phi_e$  (no need for "upwind" as with 0<sup>th</sup> or 2<sup>nd</sup> order polynomials)

- With  $\phi(x)$ , one can insert in the symbolic integral formula. For a uniform Cartesian grid:
  - Convective Fluxes:

S: 
$$\phi_e = \frac{27\phi_P + 27\phi_E - 3\phi_W - 3\phi_{EE}}{48}$$

(similar formulas used for values at corners)

• For Diffusive Fluxes (1<sup>st</sup> derivative):

$$\frac{\partial \phi}{\partial x}\Big|_{e} = a_{1} + a_{2}x + a_{3}x^{2} \qquad \Rightarrow \quad \text{for a uniform Cartesian grid: } \frac{\partial \phi}{\partial x}\Big|_{e} = \frac{27\phi_{E} - 27\phi_{P} + \phi_{W} - \phi_{EE}}{24\Delta x}$$

- This FV approximation is often called a 4<sup>th</sup>-order CDS (linear FV interpol. was 2<sup>nd</sup>-order CDS)
- Polynomials of higher-degree or of multi-dimensions can be used, as well as cubic splines (to ensure continuity of first two derivatives at the boundaries). This increases the cost.



(to obtain fluxes " $F_e = f(\phi_e)$ " as a function of cell-average values)

- Compact Higher Order Schemes
  - Polynomial of higher order lead too large computational molecules => use deferred-correction schemes and/or compact (Pade') schemes
  - Ex. 1: obtain the coefficients of  $\phi(x) = a_0 + a_1x + a_2x^2 + a_3x^3$  fitting two values and two 1<sup>st</sup> derivatives at the two nodes on either side of the cell face

• 4<sup>th</sup> order scheme: 
$$\phi_e = \frac{\phi_P + \phi_E}{2} + \frac{\Delta x}{8} \left( \frac{\partial \phi}{\partial x} \Big|_P - \frac{\partial \phi}{\partial x} \Big|_E \right) + O(\Delta x^4)$$



Notation used for a Cartesian 2D and 3D grid. Image by MIT OpenCourseWare

• Use CDS to approximate derivatives. Result retains the fourth order:

$$\phi_e = \frac{\phi_P + \phi_E}{2} + \frac{\phi_P + \phi_E - \phi_W - \phi_{EE}}{16} + O(\Delta x^4)$$

 Ex. 2: use a parabola, fit the values on either side of the cell face and the derivative on the upstream side (equivalent to the QUICK scheme, 3<sup>rd</sup> order)

$$\phi_e = \frac{3}{4}\phi_U + \frac{1}{4}\phi_D + \frac{\Delta x}{4} \left. \frac{\partial \phi}{\partial x} \right|_U$$

- Similar schemes are obtained for derivatives (diffusive fluxes), see Ferziger and Peric (2002)
- Other Schemes: more complex and difficult to program
  - Large number of approximations used for convective fluxes: Linear Upwind Scheme, Skew Upwind schemes, Hybrid. Blending schemes to eliminate oscillations at higher order.



#### Methods for Unsteady Problems – Time Marching Methods ODEs – Initial Value Problems (IVPs)

- Major difference with spatial dimensions: Time advances in a single direction
  - FD schemes: discrete values evolved in time
  - FV schemes: discrete integrals evolved in time
- After discretizing the spatial derivatives (or the integrals for finite volumes), we obtained a (coupled) system of (nonlinear) ODEs, for example:

$$\frac{d \,\overline{\Phi}}{dt} = \mathbf{B} \,\overline{\Phi} + (\mathbf{bc}) \quad \text{or} \quad \frac{d \,\overline{\Phi}}{dt} = \mathbf{B}(\overline{\Phi}, t); \quad \text{with} \ \overline{\Phi}(t_0) = \overline{\Phi}_0$$

- Hence, methods used to integrate ODEs can be directly used for the time integration of spatially discretized PDEs
  - We already utilized several time-integration schemes with FD schemes. Others are developed next.
  - For IVPs, methods can be developed with a single eqn.:  $\frac{d\phi}{dt} = f(\phi, t)$ , with  $\phi(t_0) = \phi_0$
  - Note: solving steady (elliptic) problems by iterations is similar to solving timeevolving problems. Both problems thus have analogous solution schemes.

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