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Computational model of cardiovascular response to centrifugation and lower body cycling exercise

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Citation: Diaz-Artiles, Ana et al. "Computational model of cardiovascular response to centrifugation and lower body cycling exercise." Journal of Applied Physiology 127, 5 (November 2019): 1453-1468 © 2019 the American Physiological Society

As Published: https://doi.org/10.1152/japplphysiol.00314.2019

Publisher: American Physiological Society

Persistent URL: https://hdl.handle.net/1721.1/130133

Version: Author's final manuscript: final author's manuscript post peer review, without publisher's formatting or copy editing

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32		cardiovascular modeling aspects and interpretation of the experimental data. He also edited,
33 34		revised, and approved the final version of the manuscript. Prof. Young contributed with the overall supervision and management of the research project, including its relevance to artificial
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48 **ABSTRACT:**

49 Short-radius centrifugation combined with exercise has been suggested as a potential countermeasure 50 against spaceflight deconditioning. Both the long-term and acute physiological responses to such 51 combination are incompletely understood. We developed and validated a computational model to study 52 the acute cardiovascular response to centrifugation combined with lower-body ergometer exercise. The 53 model consisted of 21 compartments, including the upper body, renal, splanchnic, and leg circulation, as 54 well as a four-chamber heart and pulmonary circulation. It also included the effects of gravity gradient 55 and ergometer exercise. Centrifugation and exercise profiles were simulated and compared to 56 experimental data gathered on twelve subjects exposed to a range of gravitational levels (1G and 1.4G 57 measured at the feet) and workload intensities (25-100W). The model was capable of reproducing 58 cardiovascular changes (within ± 1 SD from the group-averaged behavior) due to both centrifugation and 59 exercise, including dynamic responses during transitions between the different phases of the protocol. 60 The model was then used to simulate the hemodynamic response of hypovolemic subjects (blood 61 volume reduced by 5-15%) subjected to similar gravitational stress and exercise profiles, providing 62 insights into the physiological responses of experimental conditions not tested before. Hypovolemic 63 results are in agreement with the limited available data and the expected responses based on 64 physiological principles, although additional experimental data are warranted to further validate our predictions, especially during the exercise phases. The model captures the cardiovascular response for a 65 66 range of centrifugation and exercise profiles, and it shows promise in simulating additional conditions 67 where data collection is difficult, expensive, or infeasible.

68

69 **KEYWORDS**:

Mathematical model, short-radius centrifuge; orthostatic intolerance; cardiovascular simulation; lower
 body ergometer exercise.

72

73 NEW & NOTEWORTHY:

Artificial gravity combined with exercise is a potential countermeasure for spaceflight deconditioning, but the long-term and acute cardiovascular response to such gravitational stress is still largely unknown. We provide a novel mathematical model of the cardiovascular system that incorporates gravitational stress generated by centrifugation and lower-body cycling exercise, and we validate it with experimental measurements from human subjects. Simulations of experimental conditions not used for model development corroborate the model's predictive capabilities.

81 INTRODUCTION

82 Artificial gravity (AG) generated by centrifugation is a promising countermeasure to mitigate 83 the detrimental effects of weightlessness during space missions (7). Previous ground-based studies have 84 shown that exposure to centrifugation can improve cardiovascular responses to orthostatic stress (18, 35, 85 44, 55), especially if centrifugation is combined with exercise (20, 27–30, 51–53). Artificial gravity has 86 also been proposed as a potential countermeasure to mitigate the recently discovered Spaceflight 87 Associated Neuro-Ocular Syndrome (SANS) (6). Before implementing AG in space, however, 88 additional research efforts are needed to determine the parameters that are most effective, including the 89 angular velocity and radius of the centrifuge, and to characterize the cardiovascular response to these 90 stressors under varying physiological baseline conditions (6). The expensive and time-consuming nature 91 of these experimental studies with human subjects makes the use of computational tools a very 92 attractive approach to systematically study human responses under these conditions.

93

94 Computational cardiovascular models can be used to describe and, more importantly, to predict, 95 human responses in cases where data collection is difficult, expensive, or infeasible. Despite the 96 complexity of the human body, computational approaches of various kinds and anatomical resolution 97 have been successfully applied to a variety of applications, from very detailed three-dimensional models 98 of selected regions, to low-dimensional models representing more aggregate system behavior (i.e. 99 lumped-parameter models). The selection of the type of model is primarily driven by the objectives of 100 the analysis as well as the availability of computational resources (46) and data to specify model 101 parameters and validate the model behavior. In the present work we are interested in the overall, short-102 term, cardiovascular response to centrifugation combined with exercise and thus, the implementation of 103 a lumped-parameter model seems the appropriate approach.

104

105 One of the first systematic approaches of quantitative, system-level modeling of cardiovascular 106 regulation was developed by Guyton (21, 22). He was one of the first to apply a system engineering 107 approach to quantify and analyze various aspects of cardiovascular function using mathematical and 108 graphical techniques before computers became widely available. Since then, multiple models have been 109 developed to study cardiovascular responses to gravitational stress, including head up tilt (HUT) (25, 110 26, 34), lower-body negative pressure (25, 37), standing-up (15, 38, 39), and centrifugation (54). 111 However, none of these studies have evaluated the effects of centrifugation combined with exercise. The 112 incorporation of the exercise response to the already very complex cardiovascular regulatory 113 mechanisms brings additional physiological and methodological challenges (36) that we attempt to 114 address in our modeling efforts.

116 We developed a lumped-parameter model of the cardiovascular system able to capture transient 117 hemodynamic responses to lower-body ergometer exercise under gravitational stress generated by a 118 short-radius centrifuge. The model was built on previous work developed to study short-term 119 hemodynamic responses to centrifugation (54) and exercise (8), but not both mechanisms together at the 120 same time. Our cardiovascular model includes the systemic circulation, four cardiac chambers, and the 121 pulmonary circulation, divided in several parallel branches to account for the gravity gradient associated 122 with short-radius centrifugation. The model also includes the two major short-term neural control 123 mechanisms, the arterial baroreflex and the cardiopulmonary reflex, as well as important exercise 124 mechanisms such as the muscle-pump effect. Experimental measurements collected during a human 125 subject experiment at the Massachusetts Institute of Technology (MIT) short-radius centrifuge were 126 used for validation purposes.

127

128 DESCRIPTION OF THE CARDIOVASCULAR MODEL

The cardiovascular system was represented using a lumped-parameter model in which the different vascular segments are represented using electric circuit analogs grouped in compartments. Extensive details of the model architecture and parameters have been published elsewhere (14) and are summarized in the Appendix. A general description of the most relevant features of the model is presented in the following paragraphs.

134

The model architecture is shown in **Figure 1**. It contains 21 compartments grouped into four main sections (head and arms, thorax, abdomen, and legs), representing the systemic circulation (15 vascular compartments including the arterial system, microcirculation, and the venous system), the cardiac chambers (4 cardiac compartments represented by time-varying elastance models), and the pulmonary circulation (2 additional compartments connected by a microvascular resistance, which we assumed to be linear).

141

Figure 2 shows the architecture of a generic compartment (25, 50). The lumped physical characteristics of each compartment are defined by a resistance R_n and a capacitive element C_n that relates the distending volume $V_{d,n}$ stored in the segment to transmural pressure $\Delta P_n = P_n - P_{ext,n}$. The pressure source $P_{ext,n}$ represents the external pressure acting on the vessels, such as intra-thoracic pressure, intra-abdominal pressure, or muscle-pump pressure. Additionally, the pressure source $P_{h,n}$ represents the hydrostatic pressure related to the gravitational orthostatic stress. Other parameters

- 148 associated with each compartment (not shown in Figure 2) include zero-pressure filling volume $V_{0,n}$,
- and the anatomical vertical length $l_{\nu,n}$ (superior-to-inferior extension of the vascular segment).
- 150

151 The flow in each compartment q_n is calculated using the following constitutive relation:

$$q_n = \frac{P_{n-1} - P_n + P_{h,n}}{R_n}$$
(1)

152 where P_{n-1} , P_n are the compartment pressures, $P_{h,n}$ is the hydrostatic pressure induced by 153 centrifugation, and R_n is the resistance of the n^{th} compartment.

154

155 The transmural pressure in each compartment, defined as $P_n - P_{ext,n}$, depends on the 156 distending volume $V_{d,n}$, and the compliance of the compartment C_n , through the following linear 157 relationship (except for Compartments 11–splanchnic, 13–leg, and 14–abdominal; see **Figure 1** for 158 compartment numbering scheme):

$$P_n - P_{ext,n} = \frac{V_{d,n}}{C_n} \tag{2}$$

159

160 Some compartments incorporate non-linear elements that affect their behavior. For example, the 161 four cardiac chambers (left atrium, left ventricle, right atrium, right ventricle) are described using time-162 varying elastance models, and the generation of heartbeats is represented using an Integral Pulse 163 Frequency Modulation (IPFM) model (3, 54). Thus, the contractile force of the myocardial wall is 164 represented by the time-varying capacitors that cycle between a low capacitance (systolic) and a high 165 capacitance (diastolic) state of the myocardium. The intra-thoracic pressure (i.e. external pressure in the 166 thoracic compartments) modulates the filling status of the heart. Further details are included in the 167 Appendix. Moreover, the heart compartments also incorporate unidirectional diodes that represent the 168 cardiac valves and prevent reversal flow. Two vein compartments (Compartments 4-upper body and 169 13-leg) also include diodes to capture the unidirectional nature of the venous flow due to the presence 170 of venous valves.

171

Non-linear pressure-volume relationships are also incorporated in some compartments (Compartments 11–splanchnic, 13–leg, and 14–abdominal) to capture their non-linear response when operating at high transmural pressures. In those compartments, the pressure-volume relationship is defined as:

$$V_{t,n} = V_{0,n} + \frac{2V_{max,n}}{\pi} \cdot \arctan\left(\frac{\pi C_{0,n}}{2V_{max,n}} \cdot \Delta P_n\right) \quad for \, \Delta P > 0, \qquad n = 11,13,14$$
(3)

176 where $V_{t,n}$ denotes the total volume, $V_{0,n}$ denotes the venous unstressed volume or zero-pressure filling 177 volume, $V_{max,n}$ denotes the distending volume limit ($V_{max,11} = 1500$ mL, $V_{max,13} = 1000$ mL, 178 $V_{max,11} = 650$ mL), $C_{0,n}$ denotes the vascular compliance at zero transmural pressure, and ΔP_n denotes 179 the transmural pressure in the nth compartment.

180

181 The cardiovascular model was implemented in MATLAB Simulink. The distending volume is 182 used as the state variable, yielding the following expression for each compartment based on volume 183 conservation principles:

$$\frac{d}{dt}V_{d,n}(t) = q_{in_n} - q_{out_n} \tag{4}$$

184 where q_{in_n} and q_{out_n} correspond to the inward and outward flow in the n^{th} compartment. The complete 185 cardiovascular model is defined by a set of coupled-first order differential equations.

186

187 Arterial baroreflex and cardiopulmonary control systems

188 The arterial baroreceptors and the cardiopulmonary receptors are the two major neurally-189 mediated control systems that ensure short-term cardiovascular regulation in the presence of external 190 disturbances such as orthostatic stress or exercise. They are represented in our model as set-point 191 controllers that serve to minimize an error signal, namely the deviation of a specific local pressure from 192 a pre-defined set-point value, by adjusting various effector mechanisms in a feedback configuration via 193 autonomic pathways. To model the arterial baroreflex, we considered a single lumped baroreceptor in 194 the carotid sinus, assumed to be located 25 cm cranial of the heart. Thus, the carotid sinus pressure, P_{CS} , 195 is calculated as the aortic arch pressure P_1 minus the hydrostatic column acted upon by short-radius 196 centrifugation. The error signal between the measured pressure and the arterial pressure set-point, P_A^{sp} , 197 is fed into two linear time-invariant filters (sympathetic and parasympathetic (54)). The resultant signals 198 are then scaled by effector-specific gain values and then applied to the effector variables. The arterial 199 baroreflex effector variables include heart rate, right and left ventricular contractility, and the peripheral 200 resistance and venous unstressed volume of the upper body, renal, splanchnic, and leg compartments.

201

The cardiopulmonary reflex is represented using a similar feedback control loop in which the measured variable is the right atrial transmural pressure, ΔP_{RA} , and is compared to the cardiopulmonary set-point pressure, P_{CP}^{sp} . The gains of the sympathetic filter are also specific to each effector variable. The cardiopulmonary reflex effector variables include peripheral resistances and venous unstressed volumes of the upper body, renal, splanchnic, and leg compartments. Both contributions from the arterial baroreflex and the cardiopulmonary reflex constitute the total neurally-mediated global reflexcontribution to each effector variable.

209

210 Centrifugation

211 We aim to simulate the short-term cardiovascular responses to gravitational stress during short-212 radius centrifugation. Centrifugation is modeled by: 1) changes in the hydrostatic pressure in all 213 systemic compartments; 2) changes in intrathoracic pressure due to the weight of the liver being pulled 214 in the caudal direction, implemented as changes in the external pressures of the thoracic compartments; 215 and 3) changes in total blood volume due to the increase in transcapillary fluid flow into the dependent 216 vasculature. Short-radius centrifugation induces a gravity gradient along the long body axis in which the 217 hydrostatic pressure depends on the angular velocity and the distance from the center of rotation. 218 Compartments in the lower body are subjected to a higher hydrostatic pressure than compartments in the 219 upper body. The compartmental nature of the model, particularly on the Gz axis, facilitates the 220 representation of these hydrostatic changes along the body's longitudinal axis. Important variables 221 during centrifugation are angular velocity and distances of the CV compartments to the center of 222 rotation (which are dependent of subjects' anthropometry and positioning). The expressions in Table 1 223 define the gravitational stress imposed on the individual compartments during gradual exposure to 224 short-radius centrifugation with angular velocity ranging from $\omega = 0$ to $\omega = \omega_{max}$. Additional details 225 of these mathematical expressions and their implementation in the model are included in our previous 226 publications (13, 14).

227

228 Exercise

Exercise causes circulatory adjustments that are essential to satisfy the metabolic needs of exercising muscles. These adjustments include local vasodilation in exercising muscle groups, sympathetic nervous system activation, an increase in cardiac output, and an increase in arterial blood pressure above the baseline level. In our modeling effort the effects of exercise are represented using the following four mechanisms:

234

Decrease in leg arterial resistance. Due to the higher metabolic demand during exercise, arterial resistance decreases locally in the exercising muscles to increase local blood flow to satisfy the local metabolic demand, and remove metabolic end products. In our modeling effort, we simulate lower-body cycling exercise by disconnecting the leg resistance from the control systems at the onset of exercise and manually adjusting it to match previously gathered experimental data (10) according to the following expression:

$$R_{lc}(t) = R_{lc}^{-} + \left(R_{lf} - R_{lc}^{-}\right)(1 - e^{-t/\tau})$$
(5)

where R_{lc}^- is the leg vascular resistance immediately before the onset of an exercise phase, R_{lf} is the final leg vascular resistance for a given exercise intensity, and τ is the time constant governing the changes in local vascular resistance.

244

Leg muscle pump effect. During exercise, muscles exert a pump effect by squeezing the veins while contracting, thus facilitating the return of blood to the heart. In our model, muscle pump effects are simulated by varying the external pressure at the venous leg compartment periodically, following a cycling cadence of 1 rev/sec (similar to the subjects' experimental data). The leg external pressure due to the muscle pump effect, P_{ext}^{pump} , is represented according to:

$$P_{ext}^{pump} = \begin{cases} P_{max}^{pump} \frac{1}{2} (1 - \cos(4\pi t)) & 0 \le t \le 1/4 \text{ sec} \\ P_{max}^{pump} & 1/4 \le t < 1/2 \text{ sec} \\ P_{max}^{pump} \frac{1}{2} (1 + \cos(4\pi (t - 1/2))) & 1/2 \le t < 3/4 \text{ sec} \\ 0 & 3/4 \le t < 1 \text{ sec} \end{cases}$$
(6)

where P_{max}^{pump} is the maximal leg external pressure and depends on the exercise intensity. In addition to the periodic muscle pump effect during cycling, an external muscle pump pressure P_{spin} , proportional to the centrifugal force, was added to the venous leg compartment when subjects were not cycling while they were being centrifuged (i.e. spin-up phase, AG-alone phases, and spin-down phase, see **Figure 3**). This pressure models the effects of continuous leg muscle activation when subjects are pushed against the pedals by centrifugal force (similar to the muscle pump caused by "active" standing).

256

Increase in intra-abdominal pressure. Abdominal pressure increases during exercise due to the contraction of abdominal muscles. This effect is represented as an increase in external pressure in the abdominal compartments (7, 8, 9, 10, 11, and 14), according to the following exponential function:

$$P_{ext}^{abd} = P_{max}^{abd} \left(1 - e^{-t/\hat{\tau}}\right) \tag{7}$$

where $\hat{\tau}$ is a time constant on the order of a few seconds and P_{max}^{abd} is the maximal external pressure that depends on the intensity of the exercise.

262

263 Increase in arterial blood pressure. With increasing exercise intensity, arterial blood pressure 264 progressively increases over baseline conditions, which cannot be explained on the basis a simple set-265 point feedback control system as implemented here. To capture the increased arterial blood pressure, we 266 made the set-point reference pressure, P_A^{sp} , an adjustable parameter that depends on the exercise 267 intensity. Thus, P_A^{sp} is considered a tunable parameter to the model. Increases in P_A^{sp} increase sympathetic activity through the arterial baroreceptor control systems previously described. Thus, consequences of increasing the set-point pressure P_A^{sp} include increases in heart rate, ventricular contractility, total peripheral resistance (except in the working muscles), and venous tone.

271

272 Parameters

Most of the numerical values assigned to the model parameters have been estimated from the literature (24, 25). For each compartment, the parameter assignments include values for resistance R, compliance C, zero-pressure filling volume $V_{0,n}$, and anatomical vertical length $l_{v,n}$. The compartmental parameters and, in addition, the microvascular resistance values, pulmonary and cardiac parameters, as well as parameters related to the control systems are provided in **Table 4** in the Appendix. The parameters related to exercise are specific to our individual simulation profile and are detailed below.

279

280 SIMULATION PROFILE AND EXPERIMENTAL DATA

281 We simulated a centrifugation profile identical to the one implemented in a human experiment 282 conducted on the MIT centrifuge (10). The experiment was approved by the Committee on the Use of 283 Humans as Experimental Subjects at MIT. Each subject gave written informed consent to participate in 284 the study. Experimental methods and data analysis are fully described in a previous publication (10). In 285 summary, twelve subjects were positioned in the right-side-down lateral decubitus position with their 286 head positioned at the center of rotation of the MIT centrifuge. The radius of the centrifuge was limited 287 to 1.4m to simulate the space limitations inherent to the short-radius centrifuge proposed for the 288 International Space Station, as part of the "Artificial Gravity with Ergometric Exercise as the 289 Countermeasure for Space Deconditioning in Humans" (AGREE) project (13). Thus, subjects adopted a 290 crouched posture that was taken into account in our simulations by adjusting the leg anatomical vertical 291 lengths l_{v12} and l_{v13} . Subjects were exposed to different levels of centrifugation while performing 292 ergometer exercise at three intensities (25W, 50W, and 100W). The protocol, shown in Figure 3, 293 includes the following phases: baseline at rest (3 min), spin-up to the desired G-level (~100 sec), AG 294 phase for subjects to get used to the new gravitational environment ($\sim 2 \text{ min}$), the exercise portion of the 295 protocol, which includes three exercise intensities and transitions between them (15 min), another AG 296 phase with no exercise for subjects to partially recover (2 min), and spin-down deceleration phase (1 297 min). The entire protocol was completed in 25 minutes. During the centrifugation runs, continuous, 298 beat-to-beat cardiovascular data were collected using a non-invasive monitoring system (Nexfin 299 monitor, Edwards Lifesciences Corporation, Irvine, CA). Collected variables include heart rate (HR), 300 mean arterial pressure (MAP), systolic blood pressure (SBP), diastolic blood pressure (DBP), pulse 301 pressure (PP), stroke volume (SV), cardiac output (CO), and total peripheral resistance (TPR).

303 Simulation approach

A comparatively small set of physiologically plausible parameters from our model were adjusted to simulate the centrifugation and exercise profiles described above. First, total blood volume was set to $V_{tot} = 5175$ ml to closely represent our study population. This choice was based on an average of 75 ml of blood per kg of body mass (17, 25, 42) and our experimental subjects' average weight (± standard deviation) of 69.3 ± 11.6 kg.

309 Second, the angular velocity, $\omega(t)$, closely replicated the experimental protocol, increasing 310 from 0 rpm to ω_{max} during the spin-up phase, and decreasing back to 0 rpm during the spin-down 311 phase, in both cases following quarter-sine profiles. The experimental AG conditions included 1G and 312 1.4G at the feet, which were the settings of the MIT centrifuge corresponding to a maximum angular 313 velocity of 28.6 and 33.9 rpm, respectively. P_{spin} was also adjusted according to the centrifugation 314 level.

Third, the three exercise-related parameters $(P_A^{sp}, P_{max}^{pump}, R_{lf})$ were manually adjusted at each 315 316 workload stage to match the population-averaged MAP and TPR responses (as judged by visual 317 inspections). The decreases in total vascular resistance were simulated by disconnecting the leg 318 peripheral resistance $R_{lc}(t)$ from the control systems at the onset of exercise, and matching the 319 experimentally observed decreases by appropriately setting the resistance parameters of Eqn. (5). This 320 process was repeated at every workload transition, adjusting the final leg resistance and the time 321 constant to match the experimental data. Similarly, the arterial blood pressure set-point, P_A^{sp} , and the external pressure due to leg muscle pump, P_{max}^{pump} , were manually adjusted such that the simulated MAP 322 matched the experimental data. The nominal P_A^{sp} was 93 mmHg; it was increased with increasing 323 exercise intensity. The external pressure, P_{max}^{pump} , was zero at rest and also increased with increasing 324 exercise intensity. Finally, the maximal intra-abdominal pressure, P_max, was also increased with 325 326 increasing exercise intensity in accordance with measurements from the literature (24, 25). For all 327 parameters, transitions between exercise phases were defined by exponential functions with the 328 appropriate time constants to match the experimental data. Table 2 summarizes all exercise input 329 parameters used in our simulations.

- 330
- 331
- 332 RESULTS
- 333 Baseline Steady State Simulation

Results during steady-state simulations in supine position show that blood flow and volume distributions to the different vascular beds are within the range of the normal population (47). The distribution of CO to the upper body is 22% (normal range is 15%-29%), 20% to the kidney (18%-24%), 35% to the splanchnic compartment (24%-48%), and 22% to the lower body (14%-33%). Additional details about flow and volume distributions among the compartments are given in **Table 5** in the Appendix.

340

341 *Centrifugation Simulation*

Figure 4 and Figure 5 show the simulated and experimental cardiovascular responses to centrifugation and ergometer exercise at 1G and 1.4G (measured at the feet), respectively. All major hemodynamic parameters generated by the model stayed within \pm 1SD of the experimental data at almost all times throughout the entire protocol.

346

347 To simulate the exercise protocol, the simulated MAP and TPR responses were matched to the population-averaged experimental responses by adjusting the values of the pressure set-point P_A^{sp} , leg 348 349 external pressure P_{max}^{pump} , and R_{lc} leg arterial resistance were selected for each exercise level (see **Table** 350 2). The top graphs in Figure 4 and Figure 5 show that our matching approach captures MAP and TPR very closely. The nominal arterial set-point P_A^{sp} was 93 mmHg, and this value was maintained until the 351 352 beginning of exercise, when the arterial set-point increased according to the exercise intensity (see 353 Table 2). Similarly, during the spin-up phase the simulated TPR responded appropriately to the 354 gravitational stress created by centrifugation: at the beginning of the spin-up phase, the simulated 355 resistance slightly decreased followed by a noticeable increase due to the control system reflexes. This 356 behavior of the TPR is typical of active standing maneuvers (26, 43). At the beginning of the exercise 357 (once the spin-up and AG phases were completed) the leg microvascular resistance was disconnected 358 from the controls and adjusted to decrease such that the simulated TPR matched the experimental data. 359 Thus, the R_{lc} dynamics was composed of three transitions corresponding to the three workload 360 intensities simulated, as shown in the figures.

361

The rest of the cardiovascular variables are considered outputs of the simulation. They largely reproduced the general trend of the experiment data, including baseline steady-state conditions as well as the dynamic changes during spin-up/spin-down and exercise transitions. The arterial baroreflex and the cardiopulmonary reflex responded properly to the cardiovascular stress created by centrifugation. In addition, the three exercise phases were very distinguishable from one another, and the time constants during transitions were particularly well matched. During the exercise portion of the protocol, the cyclic muscle pump action is noticeable in most of the simulated cardiovascular variables, making the computational responses oscillate around their mean responses. Thus, during exercise, the simulated responses in **Figure 4** and **Figure 5** manifest themselves as "thicker" lines, due to the periodic external pressure imposed in the venous leg compartment simulating the effects of the cycling exercise

372

373 The simulated heart rate response replicates the experimental data well during all phases of the 374 protocol. Simulated SBP, DBP, SV, and CO are slightly underestimated, especially at higher workloads, 375 though they match the general trends of the data and generally stay within ± 1 SD of the experimental 376 data. The PP simulations reproduce the experimental data for lower work rates (25W and 50W) but 377 underestimate the experimental results for higher work rates (100W). The underestimation of the PP 378 seemed to be driven by the underestimation of systolic pressures, particularly during the intensive 379 exercise phase at 100W (~7% underestimation in both gravitational scenarios), causing the PP underestimation to reach 17% (1G) and 19% (1.4G) at this particular exercise phase. All in all, the 380 381 systolic, diastolic, and mean ABP were maintained within 10% of experimental values. Table 3 382 summarizes the simulated and experimental averages of the CV variables during the different phases of 383 the simulation: baseline, AG alone, exercise at 25W, exercise at 50W, and exercise at 100W. Averages 384 were calculated using the last two minutes of each protocol period, in order to avoid the transient 385 episodes between phases.

386

387 *Case study: Centrifugation of Hypovolemic Subjects due to Microgravity Exposure*

388 Having developed and validated the model for centrifugation and exercise, we can use this 389 model to characterize the cardiovascular response in subjects with specific health conditions, or 390 subjected to new gravitational stress configurations. Additionally, the model can also be used to help 391 test hypotheses about the cardiovascular response in additional scenarios. Physiological reasoning can 392 be used to predict in a qualitative manner specific responses driven by changes in certain parameters. 393 However, the specific magnitude of a response, or degree of impact of particular parameter changes are 394 harder to predict by reasoning alone, given the nonlinear and time-varying nature of the cardiovascular 395 system. As an example, we chose to explore the cardiovascular response to hypovolemic conditions. 396 This scenario is particularly relevant for human spaceflight, since astronauts lose approximately 10% of 397 their blood volume when exposed to extended microgravity (5, 49), which has proven to be problematic 398 when returning to a gravitational environment such as Earth (4, 33), or may become an issue in the 399 future when microgravity adapted individuals are exposed to artificial gravity during spaceflight (12, 19, 400 44, 45). We conducted additional simulations using the same exercise protocol and the centrifugation

401 profile at 1G to investigate cardiovascular responses when blood volume was reduced by 5, 10, and 15%

402 with respect to the euvolemic baseline (nominal V_{tot} =5175 mL).

403

404 Results are shown in **Figure 6** and provide quantitative information about the changes in cardiovascular 405 variables to centrifugation combined with lower-body ergometer exercise. MAP decreases with 406 decreasing levels of blood volume, despite the progressively larger increases in heart rate. The MAP 407 reduction seems to be driven by reduction in SBP, especially during the no-exercise portions of the 408 protocol (BL and AG) where DBP stays relatively constant across all blood volumes tested. PP, SV, and 409 CO also decrease with reducing levels of blood volume. All changes are generally exacerbated at higher 410 work rates, except for HR and TPR, where the responses at 100W across the different blood volume 411 conditions do not differ greatly.

412

413 **DISCUSSION**

414 Several studies have investigated the short-term hemodynamics response of exercise in the 415 upright and supine posture (1, 11), and as a potential countermeasure in ground-based bedrest studies 416 (40). Our focus here is on the acute cardiovascular response to a gravitational stress that can be 417 recreated in space and that is not constant along the major body axis. We developed a lumped-parameter 418 model of the cardiovascular system to simulate the short-term hemodynamic responses to combined 419 gravitational stress and exercise. In particular, gravitational stress was generated by centrifugation of 420 subjects using a short-radius centrifuge, therefore generating a high gravity gradient along the long axis 421 of the body. The model simulates the hydrostatic pressures among cardiovascular compartments caused 422 by the gravity gradient. In addition, the effects of ergometer exercise were also incorporated in the 423 model, including the increase in blood pressure, the muscle pump effect, the decrease in vascular 424 resistance, and changes in intra-abdominal pressure. Finally, the model was programmed to recreate the 425 25-min exercise protocol experienced by 12 subjects in a previous human experiment conducted at MIT 426 (10). Although there have been other studies investigating centrifugation combined with ergometer 427 exercise (16, 27-29, 45, 48, 51), these studies have mainly focused on physiological responses before 428 and after a specific intervention (e.g. bed rest or training protocol) and not during the centrifugation 429 sessions. Thus, the cardiovascular data taken during the MIT centrifugation experiments were used to 430 calibrate and evaluate the computational model. Thus, we are combining mathematical modeling and 431 human experiments in a synergistic manner. On the one hand, experiments are necessary for specifying 432 model parameters and for model validation; on the other hand, models allow for flexibility to investigate 433 physiological mechanisms under consideration, enhance experimental data interpretation, and serve as a 434 vehicle to test competing hypothesis.

436 Generally, the cardiovascular model matched the dynamic cardiovascular response during the 437 25-min exercise protocol quite well. It showed a slight tendency to underestimate some of the 438 cardiovascular variables, particularly SV, and PP at higher workload intensities, and to a lesser extent, 439 CO. These results could be better adjusted by modifying some of the numerous parameters that are built 440 in the model. However, it is important to emphasize that the purpose of these simulations is to 441 intentionally limit the number of inputs and not to exert the full flexibility of the model to reduce the 442 error between the experimental and simulated responses. A small number of parameters, namely TPR 443 and MBP, have been constrained to determine if the resulting simulations capture the physiologic 444 response over a range of exercise levels and AG regimes. The multi-compartment model has more than 445 100 parameters and it can be manipulated to perfectly match the cardiovascular responses. However, the 446 value of such an exercise is small, as most parameters will have negligible influence on the output and 447 the resultant solution will therefore not be unique and will not provide much physiological insights.

448

435

449 Overall, the cardiovascular model developed in this research effort provides unique information 450 about the cardiovascular responses to gravitational stress and exercise. Model results and comparisons 451 during the baseline period are particularly interesting since they provide a good indication of the 452 cardiovascular modeling performance without any stressor such as centrifugation or exercise. A finite 453 number of hemodynamic compartments and the primary exercise mechanisms were included in the 454 model. Although we recognize that exercise is a particularly complex activity form the physiological 455 modeling point of view, our results show that our model included enough vascular and exercise 456 mechanisms to attain suitable accuracy, at least within the selected ranges of AG and exercise intensity. 457 As Reisner and Heldt pointed out (41), this refers to the "immortal problem of modeling": creating a 458 model simple enough to feasibly determine the outputs with enough accuracy, without including 459 superfluous complexity that can make difficult the fundamental understanding of the model (i.e. how 460 individual parts interact with each other).

461

To explore the physiological consequences of centrifugation we further studied quantitative responses to centrifugation and exercise in hypovolemic subjects, with reduction of 5, 10, and 15% of total blood volume. There is limited experimental data in the literature to perform a direct comparison between our simulations and hemodynamic responses from hypovolemic subjects subjected to shortradius centrifugation an exercise. Thus, we base our comparison to a similar study that used tilt tests maneuvers to study orthostatic stress. Linnarsson and his colleagues (35) investigated orthostatic tolerance in hypovolemic subjects after five days of bedrest. Subjects lost between 8-14% of blood

469 volume during the 5-day bed rest, and their short-term, post-bedrest HR, SYS, and DIA responses 470 during a tilt test (80° upright) changed approximately +29%, -15%, and -5% respectively, with respect 471 to pre-bed rest. Our data indicate that hypovolemic subjects presenting blood volume losses between 10-472 15% will also experience increases in HR (+14 to 17%) and decreases in SYS (-10.5 to -15.6%) and 473 DIA (-2.8 to -5.7%). We expect to see less significant changes in a short-radius centrifuge due to the 474 presence of a strong gravity gradient that makes the gravitational stress less intense than being exposed 475 to constant 1G gravitational environment. Thus, our simulations seem to be in agreement with the 476 limited available data and the expected responses based on physiological principles. Additional 477 experiments are warranted to further validate the predicted values from our model, particularly the ones 478 involving exercise. However, these predictions are already providing insightful information about 479 experimental conditions not tested before.

480

481 Limitations

482 We chose to represent the cardiovascular behavior using a lumped-parameter model. This 483 approach is unable to simulate pulse wave propagation phenomena such as the changes in arterial 484 pressure waveform as it propagates through the arterial system (31, 50) and might therefore be 485 responsible for our underestimation of systolic blood pressure at higher centrifugation level and exercise 486 regimes. Despite this limitation our model was able to reproduce realistic responses at a lower 487 computational cost. Inertial effects were also not included in the model causing, for example, the 488 absence of the dichrotic notch typically present in the arterial and pulmonary arterial waveforms during 489 closure of the semilunar valves. Inertial effects become important when studying intra-beat changes 490 (within a cardiac cycle), which is not the case in the present study. Inertial effects have been estimated 491 to account for less than 1% of stroke volume and mean arterial pressure (9) and therefore they have been 492 neglected.

493 We have also not taken into account possible non-linear cardiac effects. Both systolic and 494 diastolic pressure-volume relationships were assumed to be linear, which is reasonable at normal filling 495 pressures, but these relationships become non-linear at higher filling pressures. Simulations of 496 pathologically high pressures were beyond of the scope of this work, and for the purpose of the 497 simulations presented here, the pressure-volume relationships were assumed linear. Additionally, the 498 unstressed volume was assumed to be static throughout the cardiac cycle and the same for the diastolic 499 and systolic pressure-volume relationships. Typically, the end-systolic unstressed volume is between 500 25-40% lower than its diastolic counterpart (2, 32), indicating a small but potentially significant 501 contribution to stroke volume, thus decreasing the underestimation seen in our simulations.

502 Viscoelastic stress-relaxation effects of the systemic veins were also not included in our 503 modeling effort. This phenomenon refers to the intrinsic ability of the vascular walls to stretch slowly 504 when the pressure rises and to contract slowly when the pressure falls (23, 26). This effect becomes 505 important when studying very short-term (~ 30 s) dynamic blood pressure responses after exposure to 506 passive head-up tilt, due to the altering of the time-course of venous pooling to the lower body and thus, 507 limiting the blood pressure dip typically seen during active standing (26). In our work we focused on 508 steady-state cardiovascular responses during active exposure to centrifugation and therefore these 509 effects were also neglected. We have also not taken into account breathing-related changes in 510 intrathoracic pressure. As the depth of breathing increases with increasing exercise, the lowering of 511 intrathoracic pressure aids in venous return at higher exercise levels. We have also assumed that the 512 resistance changes due to exercise are largely determined by the arteriolar vasodilation and that the 513 muscle pump primarily affects the filling state of the leg veins.

Finally, we have already commented on the difficulty of assigning numerical values to all the parameters of the model. The degree to which our model reproduces the experimental data suggests that we have included all the major features with a reasonable degree of parameter accuracy. Sensitivity analysis techniques could elucidate the influence of each parameter on the model outputs to determine the subset of physiological parameters that dominate the model response. This could be further related to individual differences seen in hemodynamic responses to gravitational stress across specific population, such as astronauts coming back to Earth after being exposed to microgravity conditions.

521

522 Conclusion

We have developed a computational model of the cardiovascular system capable of reproducing hemodynamic responses during gravitational stress generated by a short-radius centrifuge and lowerbody ergometer exercise. The model simulated both transient and steady-state responses that compare well with experimental data gathered on twelve subjects that underwent the same simulated protocol using the MIT short-radius centrifuge. We explored the capabilities of the model to generate new hypotheses and to quantify changes in cardiovascular responses due to variations in an individual parameter (i.e. total blood volume).

531 APPENDIX

532 A. Additional Details about the Cardiovascular Model

533 Most of the model equations have already been reported in a previous publication (14), but for 534 completeness, we are including them in this Appendix.

535

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536 Cardiac Model
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537 The four cardiac chambers are simulated using time-varying elastance models (24, 25). The 538 time-varying elastance in each one of the four cardiac chambers is represented using the equation below, 539 where the time interval of diastolic relaxation T_d^r is assumed to be one half of the systolic time interval 540 T_s :

$$E(t) = \begin{cases} E_d + \frac{E_{es} - E_d}{2} \cdot \left\{ 1 - \cos\left(\pi \frac{t}{T_s}\right) \right\} & 0 \le t \le T_s \\ E_d + \frac{E_{es} - E_d}{2} \cdot \left\{ 1 + \cos\left(2\pi \frac{t}{T_s}\right) \right\} & T_s < t \le \frac{3}{2}T_s \\ E_d & \frac{3}{2}T_s < t \end{cases}$$
(8)

and E_d and E_{es} are the diastolic elastance and end-systolic elastances in each one of the four cardiac chambers, respectively. The timing parameters include the atrial and ventricular systole duration, T_S^a and T_S^v , as well as the "P-R interval", which we defined here as the delay between the onset of the atrial and ventricular contraction T_{a-v} . Their values are assumed to be proportional to the square root of the R-R interval length T_{RR} (24, 25) and are defined as $T_S^a(s) = 0.2\sqrt{T_{RR}}$, $T_S^v(s) = 0.3\sqrt{T_{RR}}$, and $T_{a-v}(s) = 0.12\sqrt{T_{RR}}$

547

548The cardiac pacemaker is represented using an Integral Pulse Frequency Modulation (IPFM)549model (3, 24, 25, 54), according to:

$$M(t) = \int_{t_k-1}^t m(t)dt = \int_{t_k-1}^t (m_0 + m_r(t))dt$$

where M(t) mimics the behavior of the transmembrane potential in the sino-atrial node whose value at time t depends on the cumulative automaticity m_0 (assumed constant), and the contribution of neural control input $m_r(t)$ (either sympathetic or parasympathetic activity) since the end of the last heartbeat (or cardiac excitation time $t_k - 1$). A new heartbeat occurs at the time t_k when the transmembrane potential M(t) reaches a predefined threshold potential $\Gamma = 1$, and the time since the previous heartbeat is at least one fifth of the preceding cardiac cycle length:

556
$$\int_{t_{k-1}}^{t_{k}} m(t)dt = M(t_{k}) \ge \Gamma \quad \text{and} \quad t_{k} - t_{k-1} \ge 0.2(t_{k-1} - t_{k-2})$$

558

559

The function m(t) is defined as the inverse of the instantaneous R-R interval I(t):

$$m(t) = \frac{1}{I(t)} = \frac{1}{I_0 + \Delta I_{AB}(t)}$$

560 where I_0 is the nominal R-R interval, and $\Delta I_{AB}(t)$ is the control input from the arterial baroreflex 561 control system.

562

563 Control Systems

The baroreceptor control system is modeled using a negative feedback loop and an arterial pressure set-point P_A^{sp} . Assuming one lumped baroreceptor located in the carotid sinus at 25 cm above the heart, the carotid sinus pressure P_{CS} (mmHg) is defined as:

$$P_{CS} = P_1 - \frac{1}{2} \cdot \rho \cdot \omega^2(t) \cdot ((25+d)^2 - d^2)$$
(9)

where *d* is the distance between the head and the center of rotation measured in cm, ρ is the blood density in $\frac{mmHg}{1/s^2 cm^2}$, and $\omega(t)$ is the angular velocity of the centrifuge in rad/s. The feedback error signal $e_{AB}(t)$ is calculated as follows:

$$e_{AB}(t) = 18 \cdot \arctan\left(\frac{P_{CS} - P_A^{sp}}{18}\right)$$
(10)

570

571 The cardiopulmonary reflex is also modeled using a negative feedback loop and a pressure set-572 point P_{CP}^{sp} . The variable measured is the transmural right atrial pressure ΔP_{RA} and the error signal 573 $e_{CP}(t)$ is calculated as follows:

$$e_{CP}(t) = 5 \cdot \arctan\left(\frac{\Delta P_{RA} - P_{CP}^{sp}}{5}\right)$$
(11)

574

575 The sympathetic and parasympathetic control systems are modeled as two linear time-invariant 576 (LTI) filters. The transfer functions for the sympathetic s(s) and parasympathetic p(s) filters are:

$$s(s) = \frac{1}{42s^2}e^{-2s} + \frac{1}{75s^2}e^{-5s} + \frac{1}{300s^2}e^{-30s}$$
(12)

577

 $p(s) = 1 \tag{13}$

578

579 Transcapillary Flow and the Interstitial Fluid Volume

580 Orthostatic stress causes a decrease in intravascular volume due to an increase in transcapillary 581 fluid flow to the dependent vasculature. This phenomenon can be represented using additional RC 582 compartments (24, 25, 54). The transcapillary flow is solved analytically based on the orthostatic stress 583 profile using the equations described in the following section. The solution of the equations depends on 584 two parameters: the time constant $\tau = RC = 4.6 \min (24, 25)$, and the maximum interstitial volume 585 change $V_{max} = P_h C$, given in **Table 1**. The transcapillary flow is then subtracted from the venous return 586 at the selected compartments where this phenomenon is significant: splanchnic venous (compartment 587 11), leg venous (compartment 13), and abdominal venous (compartment 14). The fractions of interstitial 588 volume and interstitial flow assigned to each compartment are defined below:

$$V^{n}(t) = \frac{P_{h,max}^{n}}{\sum_{i} P_{h,max}^{i}} \cdot V(t)$$
(14)

589

$$q^{n}(t) = \frac{P_{h,max}^{n}}{\sum_{i} P_{h,max}^{i}} \cdot q(t)$$
(15)

590

591 where $P_{h,max}^n$ is the maximum hydrostatic pressure in the nth compartment; and $\sum_i P_{h,max}^i$ is the sum of 592 the maximum hydrostatic pressures of the three compartments (11, 13, and 14).

593

594 Analytical Solutions for the Transcapillary Flow and the Interstitial Fluid Volume

The following equations provide an analytical solution for the intercapillary flow and interstitialvolume change during gravitational stress.

- 597
- 598 <u>Region I:</u> Gradual increase in orthostatic stress over a period of length Δt .

$$q(t) = \frac{V_{max}}{\Delta t} \cdot (1 - e^{-\frac{t}{\tau}})$$
(16)

$$V(t) = V_{max} \cdot \left(\frac{t}{\Delta t} - \frac{\tau}{\Delta t} \left(1 - e^{-\frac{t}{\tau}}\right)\right)$$
(17)

599 <u>Region II</u>: Full gravitational stress during period of duration T_{tilt} .

$$q(t) = \frac{V_{max}}{\Delta t} \cdot (1 - e^{-\frac{\Delta t}{\tau}}) \cdot e^{-\frac{t - \Delta t}{\tau}}$$
(18)

$$V(t) = V_{max} \cdot \left(1 - \frac{\tau}{\Delta t} \left(1 - e^{-\frac{\Delta t}{\tau}}\right) e^{-\frac{t - \Delta t}{\tau}}\right)$$
(19)

600 <u>Region III</u>: Gradual decline in gravitational stress over a period of length Δt .

$$q(t) = \frac{V_{max}}{\Delta t} \cdot \left(1 + \left(1 - e^{-\frac{\Delta t}{\tau}}\right)e^{-\frac{T_{tilt}}{\tau}}\right) \cdot e^{-\frac{t - (\Delta t + T_{tilt})}{\tau}} - \frac{V_{max}}{\Delta t}$$
(20)

$$V(t) = V_{max} \cdot \left(1 - \frac{t - (\Delta t + T_{tilt})}{\Delta t}\right) - V_{max} \cdot \frac{\tau}{\Delta t} \cdot \left(1 - e^{-\frac{\Delta t}{\tau}}\right) \cdot e^{-\frac{T_{tilt}}{\tau}} + V_{max} \cdot \frac{\tau}{\Delta t} \cdot \left(1 + \left(1 - e^{-\frac{\Delta t}{\tau}}\right)e^{-\frac{T_{tilt}}{\tau}}\right) \cdot \left(1 - e^{-\frac{t - (\Delta t + T_{tilt})}{\Delta t}}\right)$$
(21)

601 <u>Region IV</u>: Post-orthostatic stress recovery of unspecified length.

$$q(t) = -\frac{V_{max}}{\Delta t} \cdot \left(1 - e^{-\frac{\Delta t}{\tau}}\right) \cdot \left(1 - e^{-\frac{T_{tilt} + \Delta t}{\tau}}\right) \cdot e^{-\frac{t - (2\Delta t + T_{tilt})}{\tau}}$$
(22)

$$V(t) = V_{max} \cdot \frac{\tau}{\Delta t} \cdot \left(1 - e^{-\frac{\Delta t}{\tau}}\right) \cdot \left(1 - e^{-\frac{T_{tilt} + \Delta t}{\tau}}\right) \cdot e^{-\frac{t - (2\Delta t + T_{tilt})}{\tau}}$$
(23)

602

603 Initial Conditions

The following 23 non-linear algebraic equations are used to find the initial conditions, and they describe the blood flow in the compartments assuming that the system is in steady state (54). The first equation equates the right ventricular stroke volume and the left ventricular stroke volume, and the last equation is based on the conservation of volume equating the difference between the total volume and the unstressed volume, and the distending volume in each compartment.

$$C_{ld}(P_{lvd} - P_{th}) - C_{ls}(P_{lvs} - P_{th}) = C_{rd}(P_{rvd} - P_{th}) - C_{rs}(P_{rvs} - P_{th})$$
(24)

$$C_{ld}(P_{lvd} - P_{th}) - C_{ls}(P_{lvs} - P_{th}) = T_s^{v} \cdot \frac{P_{lvd}}{R_1}$$
(25)

$$T_s^{\nu} \cdot \frac{P_{l\nu d}}{R_1} = I_0 \cdot \left(\frac{P_1 - P_2}{R_2} + \frac{P_1 - P_6}{R_6}\right)$$
(26)

$$I_0 \cdot \frac{P_1 - P_2}{R_2} = I_0 \cdot \frac{P_2 - P_3}{R_3}$$
(27)

$$I_0 \cdot \frac{P_2 - P_3}{R_3} = I_0 \cdot \frac{P_3 - P_4}{R_{ub}}$$
(28)

$$I_0 \cdot \frac{P_3 - P_4}{R_{\mu b}} = I_0 \cdot \frac{P_4 - P_5}{R_4}$$
(29)

$$I_0 \cdot \frac{P_4 - P_5}{R_4} = I_0 \cdot \frac{P_5 - P_{ra}}{R_5}$$
(30)

$$I_0 \cdot \frac{P_1 - P_6}{R_6} = I_0 \cdot \frac{P_6 - P_7}{R_7} \tag{31}$$

$$I_0 \cdot \frac{P_6 - P_7}{R_7} = I_0 \cdot \left(\frac{P_7 - P_8}{R_8} + \frac{P_7 - P_{10}}{R_{10}} + \frac{P_7 - P_{12}}{R_{12}}\right)$$
(32)

$$I_0 \cdot \frac{P_7 - P_8}{R_8} = I_0 \cdot \frac{P_8 - P_9}{R_{rc}}$$
(33)

$$I_0 \cdot \frac{P_8 - P_9}{R_{rc}} = I_0 \cdot \frac{P_9 - P_{14}}{R_9}$$
(34)

$$I_0 \cdot \frac{P_7 - P_{10}}{R_{10}} = I_0 \cdot \frac{P_{10} - P_{11}}{R_{sc}}$$
(35)

$$I_0 \cdot \frac{P_{10} - P_{11}}{R_{sc}} = I_0 \cdot \frac{P_{11} - P_{14}}{R_{11}}$$
(36)

$$I_0 \cdot \frac{P_7 - P_{12}}{R_{12}} = I_0 \cdot \frac{P_{12} - P_{13}}{R_{lc}}$$
(37)

$$I_0 \cdot \frac{P_{12} - P_{13}}{R_{lc}} = I_0 \cdot \frac{P_{13} - P_{14}}{R_{13}}$$
(38)

$$I_0 \cdot \frac{P_{14} - P_{15}}{R_{14}} = I_0 \cdot \left(\frac{P_9 - P_{14}}{R_9} + \frac{P_{11} - P_{14}}{R_{11}} + \frac{P_{13} - P_{14}}{R_{13}}\right)$$
(39)

$$I_0 \cdot \frac{P_{14} - P_{15}}{R_{14}} = I_0 \cdot \frac{P_{15} - P_{ra}}{R_{15}}$$
(40)

$$I_0 \cdot \left(\frac{P_5 - P_{ra}}{R_5} + \frac{P_{15} - P_{ra}}{R_{15}}\right) = T_d^v \cdot \frac{P_{ra} - P_{rvd}}{R_{tri}}$$
(41)

$$T_d^{\nu} \cdot \frac{P_{ra} - P_{rvd}}{R_{tri}} = T_s^{\nu} \cdot \frac{P_{rvd} - P_{pa}}{R_{ro}}$$
(42)

$$T_s^{\nu} \cdot \frac{P_{r\nu d} - P_{pa}}{R_{ro}} = I_0 \cdot \frac{P_{pa} - P_{p\nu}}{R_{p\nu}}$$

$$\tag{43}$$

$$I_{0} \cdot \frac{P_{pa} - P_{pv}}{R_{pv}} = I_{0} \cdot \frac{P_{pv} - P_{la}}{R_{li}}$$
(44)

$$I_0 \cdot \frac{P_{pv} - P_{la}}{R_{li}} = T_d^v \cdot \frac{P_{la} - P_{lvd}}{R_{mit}}$$

$$\tag{45}$$

$$V_{total} - V_{total}^{0} = \sum_{\substack{j \in \left\{ \substack{1,2,\dots,10, \\ 12,15,ra,rv, \\ pa,pv,la,lv \right\}}}} C_{j} \cdot \Delta P_{j} + \sum_{\substack{k \in \{11,13,14\}}} \left[\frac{2V_{maxk}}{\pi} \cdot \arctan\left(\frac{\pi C_{0k}}{2V_{maxk}} \cdot \Delta P_{k} \right) \right]$$
(46)

6	1	0
~	-	~

- **B.** Parameters of the Cardiovascular Model

C. Baseline Steady State Flows and Volume Distributions

- (Insert Table 5)

(Insert Table 4)

620	
621	
622	ACKNOWLEDEMENTS
623	We thank the subjects who kindly participated in the experimental study conducted at the
624	Massachusetts Institute of Technology.
625	
626	GRANTS
627	This project was supported by the MIT/Skolkovo development project (Seed Grant 6925991),
628	and the National Space Biomedical Research Institute through NASA NCC 9-58. In addition, the
629	Fulbright Commission has provided additional support.
630	
631	DISCLOSURES
632	No conflicts of interest, financial or otherwise, are declared by the authors.
633	
634	
635	

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775 FIGURE CAPTIONS

776

777 Figure 1. Circuit representation of the 21-compartment cardiovascular model, composed of 4 sections: 778 head and arms, thorax, abdomen, and legs. Systemic compartments include proximal aorta (1), 779 brachiocephalic arteries (2), upper body precapillary (3) and postcapillary (4) compartments, superior 780 vena cava (5), thoracic aorta (6), abdominal aorta (7), renal precapillary (8) and postcapillary (9) 781 compartments, splanchnic precapillary (10) and postcapillary (11) compartments, leg precapillary (12) 782 and postcapillary (13) compartments, abdominal veins (14), and thoracic inferior vena cava (15). Four 783 microvascular resistances are also included: upper body R_{ub} , kidneys R_{rc} , splanchnic R_{sc} , and legs R_{lc} . 784 The right heart and left heart include variable capacitors and diodes representing the heart valves that 785 prevent reversal flow. The pulmonary circulation is represented by two compartments (pre and post 786 capillary components) connected by a microvascular resistor. Two vein compartments (Compartments 787 4-upper body and 13-leg) also include diodes to capture the unidirectional nature of the venous flow 788 due to the presence of venous valves.

Figure 2. Single representation of the nth compartment, where R_n is the resistance, C_n is the (incremental) vascular compliance (C_n is defined as $dV_n/d\Delta P_n$), P_n is the compartment pressure, q_n is the flow rate; $P_{h,n}$ is the hydrostatic pressure; and $P_{ext,n}$ is the external pressure (e.g. intra-thoracic pressure, intra-abdominal pressure, muscle pump pressure). The arrows over the compliance (represented by the electric symbol of a capacitor) and pressure sources (represented by open circles) indicate the variable nature of these elements, either as a function of filling status (capacitors) or as a function of time (pressure sources).

Figure 3. Exercise protocol conducted by twelve subjects on the MIT short-radius centrifuge. The protocol consisted of the following phases: baseline (3 min), spin-up phase to the desired G-level (~100 sec), AG phase with only centrifugation (~2min), AG & Exercise phase (15 min), AG phase with no exercise for subjects to partially recover (2 min), and spin-down phase (1 min). We simulated an identical profile with our computational model and used the experimental data for validation purposes. Figure adapted from (10).

Figure 4. Simulated (black line) and experimental (grey line, mean ± SD including 12 subjects)
cardiovascular responses to centrifugation at 1G (measured at the feet) and ergometer exercise in a
short-radius centrifuge.

- Figure 5. Simulated (black line) and experimental (grey line, mean ± SD including 12 subjects)
 cardiovascular responses to centrifugation at 1.4G (measured at the feet) and ergometer exercise in a
 short-radius centrifuge.
- 808 Figure 6. Simulated cardiovascular responses to centrifugation at 1G (measured at the feet) and
- 809 ergometer exercise varying blood volume conditions. Data are reported for all protocol phases: baseline
- 810 (BL), centrifugation alone (AG), and centrifugation combined with exercise (25W, 50W, and 100W).
- 811 Blood volume levels include baseline blood volume ($V_{total} = 5175 \text{ ml}$) and blood volume reductions
- 812 of 5%, 10%, and 15%.

814 TABLES

815

816 Table 1: Mathematical expressions capturing orthostatic stress during short-radius centrifugation 817 through three mechanisms: 1) changes in hydrostatic pressure (term included in all systemic 818 compartments), 2) changes in intrathoracic pressure (due to the weight of the liver being pulled down in 819 the thoracic compartment; term included in compartments within the thorax region), and 3) changes in

total blood volume (due to the increase in transcapillary fluid flow into the dependent vasculature)

Gravitational Effect	Short-radius Centrifugation
Hydrostatic pressure	$P_{h,n} = \frac{1}{2}\rho\omega^{2}(t) \left(R_{0,n}^{2} - R_{i,n}^{2}\right)$
Intrathoracic pressure	$P_{th}(t) = P_{th_0} - 3.5 \frac{(r+d)^2 \cdot \omega_{max}^2}{g^2} \cdot \omega^2(t)$
Maximum Interstitial Volume Change	$V_{max} = 300ml \cdot \frac{(r+d) \cdot \omega_{max}^2}{g \cdot \sin(85^\circ)}$

821

822 where $P_{h,n}(t)$ is the hydrostatic pressure, ρ is the density of the blood, $\omega(t)$ is the angular velocity of the 823 centrifuge, $P_{th}(t)$ is the intrathoracic pressure, P_{th_0} is the nominal intrathoracic pressure without orthostatic stress 824 (-4 mmHg), ω_{max} is the maximum and final angular velocity achieved, $r = 55 \ cm$ is the distance of the thoracic 825 compartment to the center of rotation of the centrifuge, d is the distance from the head of the subject to the center 826 of rotation of the centrifuge (d = 0 cm), V_{max} is the maximum interstitial volume change (from intravascular 827 volume to the interstitial space), $R_{i,n}$ is the inner radio of the compartment under consideration (the distance 828 between the superior end of the compartment and the center of rotation), and $R_{0,n}$ is the outer radius of the 829 compartment under consideration, which is defined as the sum of the effective length of the compartment and the 830 inner radius. Note: The effective length of each compartment is defined as one half of its anatomical vertical length $l_{v,n}$, except for the leg compartments, where the effective length is assumed to be one third of the 831 832 anatomical vertical length.

834	Table 2: Exercise parameters during the different phases of the "1G" and "1.4G" simulations.
835	Manipulated parameters include P_A^{sp} : set-point reference pressure for the arterial baroreceptor control
836	system (mmHg); R_{lc} : leg microvascular resistance (Peripheral Resistance Units (PRU) or
837	mmHg/ml/min.)); P_{max}^{pump} : maximal leg external pressure (mmHg); and P_{max}^{abd} : maximal intra-abdominal
838	pressure (mmHg). P_A^{sp} and P_{max}^{pump} were adjusted to match the experimental Mean Arterial Pressure
839	(MAP) data, and R_{lc} was adjusted to match the experimental total peripheral resistance (TPR) data.
840	<i>P</i> ^{<i>abd</i>} was adjusted based on the literature.

Simulation phase	poir	rial set- nt <i>P^{sp}</i> nHg)	Resista	rterial nce <i>R_{lc}</i> RU)	pressur due to	xternal re P ^{pump} muscle (mmHg)	Intra-abdominal pressure P ^{abd} (mmHg)		
AG level (measured at the feet)	1G	1.4G	1G	1.4G	1G	1.4G	1G	1.4G	
Baseline	93	93	3.9	3.9	0	0	2	2	
AG after Spin-up	93	93	3.9	3.9	20**	30**	2	2	
Exercise: 25W	120	125	1.15*	1*	40***	65***	2.5	2.5	
Exercise: 50W	135	140	0.75*	0.75^{*}	50***	75***	6	6	
Exercise: 100W	205	225	0.54*	0.54^{*}	60***	90***	10	10	
AG before Spin- down	105	105	2.4*	2.4*	20**	30**			
Rest	105	105			0	0			

- 843 844 *resistance disconnected from controls **constant **** periodic 1 sec

Table 3: Simulated (Sim) and experimental (Exp, values are mean \pm SD) average of cardiovascular variables during the different phases of the protocol at the two G-levels investigated: 1G and 1.4G (measured at the feet). For both simulated and experimental data, averages were calculated including the last 2 minutes of each period.

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854	

	Baseline				AG			AG +Exercise 25W			AG + Exercise 50W				AG + Exercise 100W					
	1	G	1.	4G	1	G	1.	4G	1	G	1.4	4G	1	G	1.4	4G	1	G	1.	4G
CV Variable	Sim	Exp	Sim	Exp	Sim	Exp	Sim	Exp	Sim	Exp	Sim	Exp	Sim	Exp	Sim	Exp	Sim	Exp	Sim	Exp
CO (l/min)	5.9	6.1±1 .2	5.9	6.5±1 .1	5.8	5.8±1 .3	6.0	6.7±1 .3	8.7	9.5±2 .2	9.8	10.9± 1.5	10.6	12.1± 2.3	11.6	13.2± 2.3	13.2	15.8± 2.8	14.5	16.7± 2.5
SV (ml)	87.9	96.2± 14.0	87.9	101.0 ±11.9	83.2	91.0± 15.4	84.5	98.2± 14.3	90.0	98.8± 20.8	97.7	107.9 ±14.1	96.7	110.5 ±19.2	104.6	115.5 ±17.8	98.5	114.8 ±17.4	106.4	120.3 ±20.3
HR (bpm)	67.3	64.1± 9.0	67.3	64.9± 10.0	67.7	64.5± 9.2	67.7	69.3± 11.9	96.2	97.0± 10.5	100.0	101.6 ±12.8	109.3	110.3 ±12.4	110.6	114.4 ±14.2	133.7	138.1 ±17.6	136.3	140.2 ±17.4
SBP (mmHg)	116.9	116.6 ±6.5	116.9	123.4 ±9.7	115.4	116.5 ±11.6	116.4	121.7 ±11.9	124.3	128.1 ±13.6	128.6	136.6 ±11.5	129.3	138.1 ±14.2	135.3	151.0 ±16.7	140.4	151.0 ±17.5	147.5	158.7 ±19.9
MBP (mmHg)	92.9	90.4± 4.9	92.9	94.4± 7.4	92.8	90.5± 8.3	93.5	92.8± 9.7	100.8	98.6± 10.3	103.2	103.2 ±11.1	104.1	101.8 ±10.6	108.3	108.1 ±10.4	115.0	110.7 ±12.9	120.3	113.8 ±14.7
DBP (mmHg)	67.8	73.2± 4.3	67.8	75.8± 6.7	68.9	74.2± 6.9	69.2	74.5± 8.8	74.9	80.0± 8.6	75.1	81.7± 9.2	76.4	80.7± 7.4	78.4	84.7± 7.7	86.6	86.0± 9.8	89.7	87.2± 11.2
PP (mmHg)	49.1	43.4± 6.8	49.1	47.6± 5.8	46.5	42.4± 9.1	47.2	47.2± 7.6	49.5	48.2± 10.6	53.5	54.9± 6.3	52.8	57.4± 9.7	57.0	66.3± 11.1	53.7	65.0± 10.2	57.8	71.5± 10.3
TPR (PRU)	0.86	0.93± 0.2	0.86	0.90± 0.2	0.86	0.98± 0.3	0.86	0.86± 0.2	0.62	0.66± 0.2	0.58	0.59± 0.1	0.49	0.53± 0.1	0.49	0.52± 0.1	0.40	0.44± 0.1	0.40	0.44± 0.1

858 **Table 4:** Values of the cardiovascular model parameters

Resistance (PRU) Unstressed volume (mL)		Compliance (mL/mm Hg)	Anatomical vertical length (cm)	Elastances Cardiac Model (mm Hg/mL)	Regulatory Control Systems	Additional Parameters		
$R_1 = 0.007$	V _{0,1} =21	<i>C</i> ₁ =0.28	$l_{v,1}$ =10.0	$E_{es,ra}$ =0.74	P_A^{sp} =93 mm Hg	P_{th_0} =-4 mm Hg		
$R_2 = 0.003$	$V_{0,2} = 5$	C ₂ =0.13	$l_{v,2}$ =4.5	$E_{d,ra}$ =0.3	$G_{R-R}^{A,S}=9$	V_{tot} =5175 mL		
$R_3 = 0.014$	$V_{0,3}=200$	<i>C</i> ₃ =0.2	$l_{v,3}$ =20.0	$E_{es,rv}$ =1.3	$G_{R-R}^{A,P}=9$	HR _{nom} =67 beats/min		
$R_4 = 0.11$	V _{0,4} =645	<i>C</i> ₄ =7.0	$l_{v,4}=20.0$	$E_{d,rv} = 0.05$	$G_{C_{lv}}^{A,S} = 0.007$	<i>BW</i> =69 <i>K</i> g		
R ₅ =0.028	$V_{0,5} = 16$	C ₅ =1.3	$l_{v,5}$ =14.5	$E_{es,la}$ =0.61	$G_{C_{rv}}^{A,S} = 0.022$			
$R_6 = 0.011$	$V_{0,6} = 16$	<i>C</i> ₆ =0.1	$l_{v,6}$ =16.0	$E_{d,la}$ =0.5	$G_{R_{ub}}^{A,S}$ =-0.05			
$R_7 = 0.010$	$V_{0,7} = 10$	<i>C</i> ₇ =0.1	$l_{v,7}$ =14.5	$E_{es,lv}$ =2.5	$G_{R_{rc}}^{A,S}$ =-0.05			
$R_8 = 0.10$	$V_{0,8} = 20$	C ₈ =0.21	$l_{v,8}=0$	$E_{d,lv}$ =0.11	$G_{R_{sc}}^{A,S}$ =-0.05			
$R_9 = 0.11$	$V_{0,9} = 30$	$C_9 = 5.0$	$l_{v,9}=0$		$G_{R_{lc}}^{A,S}$ =-0.05			
$R_{10} = 0.07$	$V_{0,10}$ =300	C ₁₀ =0.2	$l_{v,10}$ =10.0		$G_{V_{ub}}^{A,S}=5$			
$R_{11} = 0.07$	$V_{0,11}$ =1146	<i>C</i> ₁₁ =50	$l_{v,11}$ =10.0		$G_{V_{rc}}^{A,S}=2$			
R_{12} =0.09	$V_{0,12}$ =200	C ₁₂ =0.2	$l_{v,12}$ =85		$G_{V_{sc}}^{A,S}$ =13			
R_{13} =0.10	$V_{0,13} = 716$	C ₁₃ =20	$l_{v,13}$ =85		$G_{V_{lc}}^{A,S}=7$			
R_{14} =0.019	$V_{0,14} = 79$	$C_{14} = 1.3$	$l_{v,14}$ =14.5		P_{CP}^{sp} =6 mm Hg			
$R_{15} = 0.008$	$V_{0,15}=33$	<i>C</i> ₁₅ =0.5	$l_{v,15}=6$		$G_{R_{ub}}^{CP,S}$ =-0.05			
R_{tri} =0.006	$V_{0,ra} = 14$	<i>C</i> _{pa} =3.4			$G_{R_{rc}}^{CP,S}$ =-0.05			
R_{pa} =0.006	$V_{0,rv}$ =46	<i>C_{pv}</i> =9.0			$G_{R_{sc}}^{CP,S} = -0.05$			
$R_{pc} = 0.07$	$V_{0,pa} = 160$				$G_{R_{lc}}^{CP,S}$ =-0.05			
R_{pv} =0.006	$V_{0,pv}$ =430				$G_{V_{ub}}^{CP,S}$ =13			
R_{mit} =0.010	$V_{0,la}=24$				$G_{V_{rc}}^{CP,S}=3$			
R_{ub} =4.0	$V_{0,lv} = 55$				$G_{V_{sc}}^{CP,S}$ =64			
R_{rc} =4.2					$G_{V_{lc}}^{CP,S}$ =30			
R_{sc} =2.4								
R_{lc} =3.9								

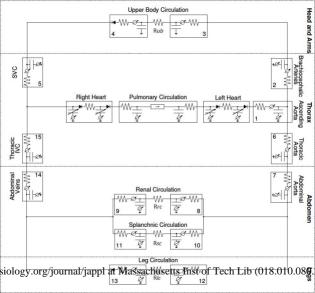
860 R: resistances; V_0 : unstressed volumes; C: compliances; l_v : anatomical vertical lengths; E: elastances; P: 861 pressures; G: gains factors; V: volumes; HR: heart rate; BW: body weight. Abbreviations: ra, right atrium; tri, 862 tricuspid valve; rv, right ventricle; pa, pulmonary arteries; pc, pulmonary circulation; pv, pulmonary veins; la, left 863 atrium; mit, mitral valve; lv, left ventricle; ub, upper body; rc, renal circulation, sc, splanchnic circulation; lc, leg 864 circulation; es, end-systolic elastance; d, diastolic elastance; A, arterial baroreflex; CP, cardiopulmonary reflex; sp, 865 set-point; S, sympathetic, P, parasympathetic; R-R, R-R interval; th₀, nominal intra-thoracic.

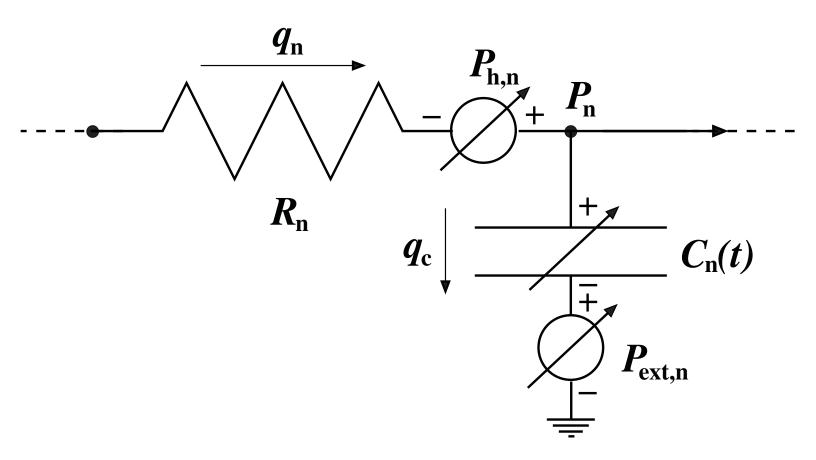
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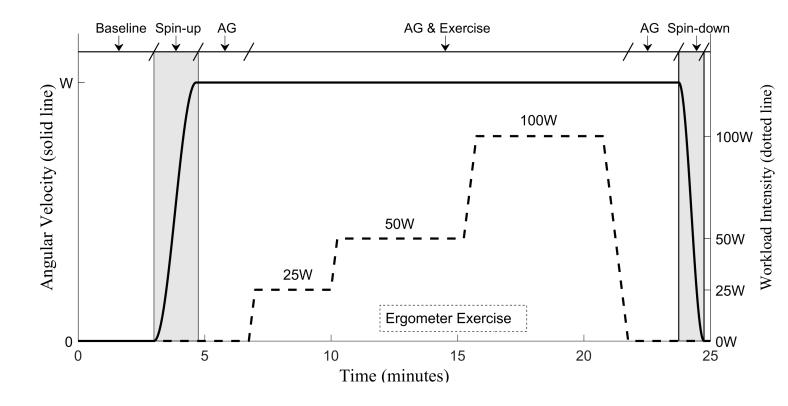
868	Table 5: Flow and Volume parameters in each of the compartments during steady-state simulation in
869	supine position.

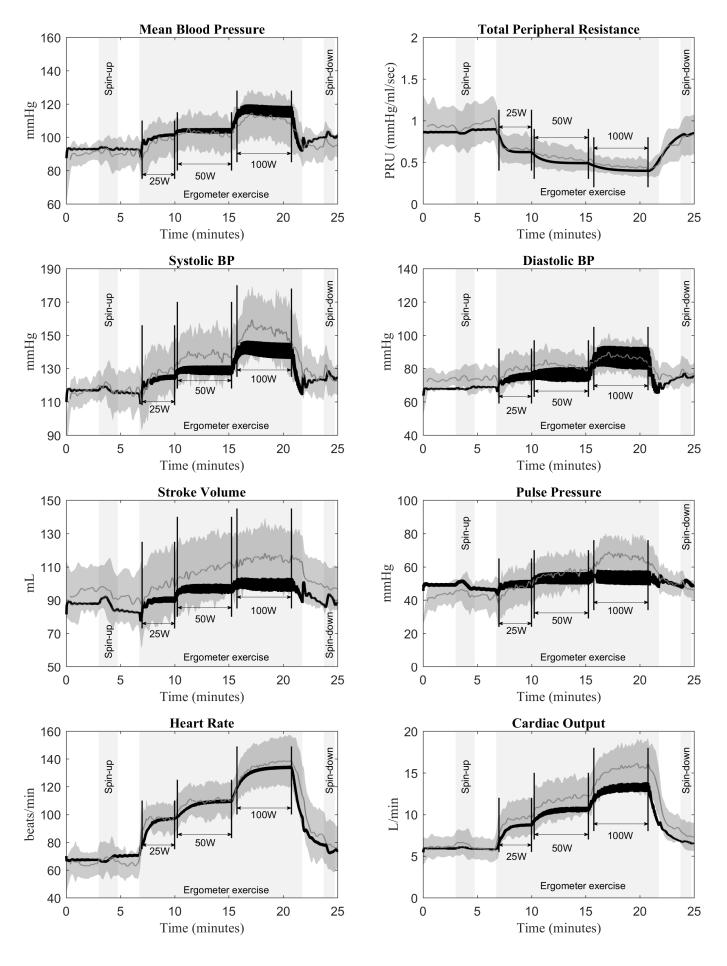
Upper Body Circulation		Heart Ci	rculation	Thoracic and Abdominal Circulation		Splanchnic	Circulation	Renal Cir	culation	Leg Circulation	
Flow (l/min)	Volume (ml)	Flow (l/min)	Volume (ml)	Flow (1/min)	Volume (ml)	Flow (l/min)	Volume (ml)	Flow (l/min)	Volume (ml)	Flow (l/min)	Volume (ml)
Q _{2i} = 1.34	V ₂ =17.6	Q _{rai} =5.85	V _{ra} =31.8	Q _{6i} =4.56	V ₆ =25.6	Q _{10i} =2.07	V ₁₀ =317.8	Q _{8i} = 1. 19	V ₈ =38.8	Q _{12i} = 1.29	V ₁₂ =217.9
Q _{3i} =1.33	V ₃ =218.5	Q _{rvi} =5.86	$V_{rv} = 110.5$	Q _{7i} =4.55	V ₇ =19.1	Q _{11i} =2.06	V ₁₁ =1382.7	Q _{9i} =1.18	V ₉ =52.2	Q _{13i} =1.28	V ₁₃ =845.9
Q _{4i} = 1.31	V ₄ =682.9	Q _{rvo} =5.88	$V_{la} = 54.5$	Q _{14i} =4.52	V ₁₄ =81.9	Q ₁₁₀ =2.06		Q ₉₀ =1.19		Q ₁₃₀ =1.28	
Q _{5i} =1.31	V ₅ =24.8	Q _{pc} =5.85	V _{lv} =153.8	$Q_{15i} = 4.53$	V ₁₅ =36.4						
Q ₅₀ =1.32		Q _{lai} =5.91	V ₁ =48.1	Q ₁₅₀ =4.53							
		Q _{lvi} =5.92									
070		Q _{lvo} =5.91									

 Q_{ni} , flow going into the compartment *n*; Q_{no} , flow going out the compartment *n*; ra, right atrium; rv, right ventricle; la, left atrium; lv, left ventricle; 870 871

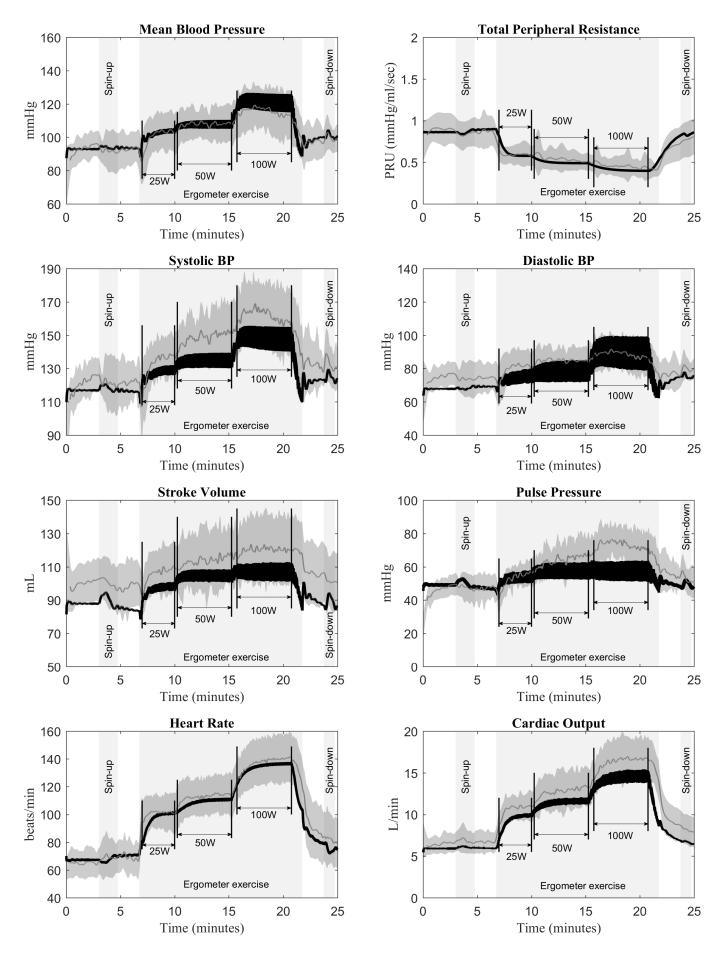








Computational model prediction at 1G — Experimental data (mean \pm SD) at 1G Downloaded from www.physiology.org/journal/jappl at Massachusetts Inst of Tech Lib (018.010.080.207) on September 30, 2019.



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