

OPTIMIZING THE ARRANGEMENT OF TRUSS MEMBERS OR THE STIFFENERS
OF PLATED PLANE PANELS UNDER INPLANE LOADS

BY

CONSTANTINOS RENGOS

B.S., MASSACHUSETTS INSTITUTE OF TECHNOLOGY
(1969)

SUBMITTED IN PARTIAL FULFILLMENT
OF THE REQUIREMENTS FOR THE DEGREE OF
MASTER OF SCIENCE IN NAVAL ARCHITECTURE
AND MARINE ENGINEERING

AT THE

MASSACHUSETTS INSTITUTE OF TECHNOLOGY
AUGUST, 1971

SIGNATURE OF AUTHOR: _____

Department of Ocean Engineering
August, 1971

CERTIFIED BY: _____

Thesis Supervisor |

ACCEPTED BY: _____



Chairman, Departmental Graduate
Committee

OPTIMIZING THE ARRANGEMENT OF TRUSS MEMBERS OR THE STIFFENERS
OF PLATED PLANE PANELS UNDER INPLANE LOADS

BY

CONSTANTINOS RENGOS

Submitted to the Department of Ocean Engineering on August 16, 1971 in partial fulfillment of the requirements for the degree of Master of Science in Naval Architecture and Marine Engineering, ~~and the Naval Architect Degree.~~

ABSTRACT

Clerk Maxwell's theorem for the least weight arrangement of filamentary trusses enabled A. G. M. Michell to come to the tentative conclusion that in certain cases the least weight arrangement of the truss members or the stiffeners of an isotropic elastic continuum is obtained by following the principal strain trajectories.

Using this as a basis, the Plane Stress Approximation incorporated with the Finite Element Displacement Method are employed to determine the general state of stress of a two-dimensional planar structure through which a technique is developed to obtain the principal stress trajectories for any plane stress with an isotropic material problem.

A computer program has been written through which the displacements, the stresses, and the stress trajectories can be obtained; the results for several planar problems are in agreement with those theoretically predicted.

A comparison among several stiffener arrangements suggests that the least weight arrangement that reduces the stress level by the required amount, throughout a cross-section of a plate, is the one which adds material at the location of maximum principal stress.

THESIS SUPERVISOR: J. Harvey Evans

TITLE: Professor of Naval Architecture

ACKNOWLEDGEMENTS

The author wishes to express his appreciation to his thesis supervisor, Professor J. Harvey Evans, for his constant guidance and motivation throughout this study.

Acknowledgement is made to the Department of Ocean Engineering for financially enabling me to conduct this investigation.

All calculations were performed by System 65/40 at the Information Processing Center at the Massachusetts Institute of Technology.

Thanks are also extended to Miss Artemis Georgantas for the preparation of the graphic artwork.

TABLE OF CONTENTS

	<u>Page</u>
Title Page	1
Abstract	2
Acknowledgements	3
Table of Contents	4
List of Figures	6
List of Tables and Plates	8
INTRODUCTION	9
I BACKGROUND	14
A. Maxwell Structures	14
B. Michell Structures	18
C. The Stress Trajectory Approach	22
II THE STRESS TRAJECTORY TECHNIQUE	26
A. The Finite Element Approach	26
1. Introduction	26
2. General	26
3. Geometry	28
4. Forces and Displacements	28
5. Strains and Stresses	32
6. The Stiffness Matrix	35
7. Equivalent Nodal Forces	42
B. Stresses and Stress Trajectories	47
1. General State of Stress for a Rectangular Element	47
2. Principal Stressés and Stress Trajectories	51

	<u>Page</u>
III STIFFENING ARRANGEMENTS	60
1. Introduction	60
2. A Comparison between Two Stiffener Arrangements--Case I	60
3. A Comparison between Two Stiffener Arrangements--Case II	69
4. Results from Comparing Arrangements A, B, and C	74
IV RESULTS	90
1. Energy Equivalent Boundary Loads	90
2. Nodal Displacements	97
3. Average Nodal Stresses	105
4. Principal Compressive Stress Trajectories	110
5. Computer "Stiffening" Procedure	114
6. Least Weight Stiffener Arrangements	118
CONCLUSIONS	134
Appendices	
I-A APPLICATION OF MAXWELL'S THEOREM AND LEMMA	137
I-B APPLICATION OF THE MICHELL STRUCTURES	142
II-A THE COMPUTATIONAL PROCEDURE	149
II-B LISTING OF COMPUTER PROGRAM'S PRINTOUT FOR THE CANTILEVER CASE	206
References	255

LIST OF FIGURES

<u>Figure</u>		<u>Page</u>
I-1	The Principal Stress Trajectories in a Warship in the Hogging Condition	25
II-1	The Nodal Displacements of an Element in Their Positive Directions	30
II-2	An Element under a Linearly Varying Boundary Load Distribution	45
II-3	Linear Extrapolation of the Directions of the Principal Stresses to Get the Stress Trajectories in a Six Element Structure	54
III-1	A Centrally Loaded Plate	61
III-2	A Comparison between Two Stiffener Arrangements--Case I	63
III-3	Graphical Proof That $g(H,c)$ and $f(H)$ of Inequality [3.6.1] Have no Common Point	67
III-4	A Comparison between Two Stiffener Arrangements--Case II	70
III-5 through III-10	$\bar{\tau}_A, \bar{\tau}_B, \bar{\tau}_C$ versus H	75,76 78,79 81,82
III-11 through III-16	$\bar{\sigma}_A, \bar{\sigma}_B, \bar{\sigma}_D$ versus H	83-88
IV-1	A Centrally Loaded Plate	92
IV-2	Modeling of the Left-Half Plate	92
IV-3	Setup of Origin for the τ vs y Distribution	92
IV-4	A Cantilever Plate Loaded at Its Free End with a Concentrated Load, P	102
IV-5	The Left Half of a Centrally Loaded Plate	102
IV-6	A Uniformly Loaded and Self-Equilibrating Plate with Shear Reactions at Its Free Ends	104
IV-7	The σ_x (in psi) Distribution along Half the Length of a Centrally Loaded (in its plane) Plate	106
IV-8	The σ_x (in psi) Distribution along the Length of a Cantilever	108
IV-9	The σ_x (in psi) Distribution along the Length of a Self-Equilibrating Plate	109

<u>Figure</u>		<u>Page</u>
IV-10	The Computer Program's "Stiffening" Arrangement (First Trial)	115
IV-11	The σ_x (in psi) Distribution along Half the Length of a Centrally Loaded Plate after It Has Been "Reinforced"	117
IV-12	The Computer Program's "Stiffening" Arrangement (Second Trial)	119
IV-13 through IV-18	$\bar{\tau}_A, \bar{\tau}_B, \bar{\tau}_C$ versus \bar{A}	122- 127
IV-19 through IV-24	$\bar{\sigma}_A, \bar{\sigma}_B, \bar{\sigma}_C$ versus \bar{A}	128- 133
I-A.1	Truss of Example 1	138
I-A.2	Maxwell's Equivalent Equilibrium	138
I-A.3	(a) Truss of Example 2 (b) Maxwell's Equivalent Equilibrium	140
I-B.1	Michell Field: Layout for a Cantilever	143
I-B.2	The Principal Stress Trajectories for a Cantilever Appearing in Crandall and Dahl	145
I-B.3	Michell Field: Layout for a Centrally Loaded Beam	145
I-B.4	Michell Field: Layout for a Centrally Loaded Beam, Whose Frame Lies Completely in the Semiplane of AB	148
I-B.5	Principal Stress Trajectories in an "I" Beam by A. W. Hendry	148
II-A.1	Flowchart	157

LIST OF TABLES AND PLATES

<u>Table</u>		<u>Page</u>
II-1	The [A] Matrix of Equation [2.15.2]	38
II-2	The Stiffness Matrix $[K] \times [1 - \nu^2/Et]$ for One Rectangular Element	41
IV-1	The Computer Input Required Values, (Column 4), of the Shear Intensities per Node of Action and per y-Coordinate	94
IV-2	The Analytical Calculations to Obtain the Energy Equivalent Nodal Forces of the Example of Figure IV-2	96
IV-3	Results Obtained for Examples No. 1 and No. 3	99
 <u>Plate</u>		
I	Principal Compressive Stress Trajectories for a Cantilever (Discrete Parabolic Load Distribution at Free End)	250
II	Principal Compressive Stress Trajectories for a Cantilever (Distributed Parabolic Load Distribution at Free End)	111
III	Principal Stress Trajectories for a Centrally Loaded Plate with Clamped Ends	112
IV	Principal Compressive Stress Trajectories for a Uniformly Loaded and Self Equili- brated Plate with Shear Reactions at Its Free Ends	113

INTRODUCTION

The present study formulates a technique which may assist in determining the minimum weight design of two-dimensional planar structures such as plated panels and trusses. Of particular interest is the determination of the minimum weight arrangement of (a) stiffeners for a plate, or (b) the members of a truss, both being loaded in their plane.

Rectangular plates or truss members of linearly elastic, isotropic and homogeneous material are examined in detail. Although instability is not considered, the present method of analysis may aid in the examination of such effects as instability and/or plasticity.

The first part of this study functions as background. The basic theorem for the design of truss-like structures established by Clerk Maxwell in 1869 is discussed and numerical applications of the theorem are made.

A. G. M. Michell in 1904 used Maxwell's theorem to arrive at the tentative conclusion that in certain cases we can find lower limits to the total material necessary to sustain given loads, and also assign the forms of frames which are most economical. The implications of his conclusion is the basis for the present study.

Michell has shown for a number of simple two-dimensional truss problems that the minimum weight arrangement of the truss members follows the lines of the "Michell Fields"

which are lines that meet orthogonally at any point in the Field.

These lines are analogous to the principal strain trajectories which are curves that follow the directions of the principal strains. Since only isotropic material is considered in this study, the search for a way to obtain the principal strain trajectories of a structure has been substituted by an efficient technique by which we obtain the principal stress trajectories.

The principal stress trajectories, similar to the principal strain trajectories are lines which follow the directions of the principal stresses.

The second part of this investigation, demonstrates how one can efficiently obtain the stress trajectories by incorporating the *plane stress approximation* through the Finite (or Discrete) Element Technique.

An introduction to the Finite Element (Displacement) Method as applied to the development of a rectangular element is given. This involves the definition of the displacement functions, the development of the Element's Stiffness Matrix, and the determination of the Energy Equivalent nodal forces.

From the assembled structure's stiffness matrix and the Energy Equivalent nodal forces, the nodal displacements are obtained. Therefore, the state of stress of the total structure can be determined from the stress-displacement relationships. The magnitude and direction of the principal stresses

at any nodal point (or control station) can be calculated. Profiting from the existence of the orthogonal grid provided by the Finite Elements' boundaries and from the fact that the stresses vary linearly along the interelement boundaries, a linear extrapolation method is described, through which the principal stress trajectories are obtained, (for our purposes only the compressive stress trajectories).

A computer program has been written in FORTRAN IV for the use of the G level compiler of the IBM 360 computer model.

The program enables one to adequately model any plane stress problem subject to the above discussed limitations. By reading in the geometric parameters, the boundary conditions and the applied forces, concentrated anywhere in the structure or distributed on the boundaries, one obtains as output the displacements and the average stresses at each nodal point, (or control station) of the structure.

From the calculation of the principal stresses derived from the average nodal stresses, a plotting of the principal compressive stress trajectories is obtained, (by the aid of the IBM Calcomp Plotter).

Furthermore, the program is capable of reinforcing the structure along the principal compressive trajectories with fictitious stiffeners; that is, by increasing the thickness of the elements which are traversed by the trajectories.

Once the first trial of "stiffening" has been performed, the new plot of stress trajectories is given together with

a listing of the elements to be reinforced for the second trial, and so on.

The complete description of the Program's capabilities and limitations is given in Appendix II-A.

The procedure followed by the program goes beyond the determination of the stress trajectories. However, it is not the purpose of this study to further develop the computer method of reinforcing a structure by true stiffener sizes.

It is of greater importance to demonstrate first that by adding material at the location(s) of the maximum principal stress, the required reduction of stress is achieved, resulting at the same time with the least weight addition of material for the specified stress reduction.

Part three of the present work compares four different stiffener arrangements for the optimum (least weight) reduction of the principal stresses.

Two cross-sections along the length of a centrally loaded plated plane panel (in its plane) and with fixed ends were conveniently chosen to be at the quarter length and at the midspan.

The Simple Beam Theory which is a good approximation when applied to plane panels was employed. By its aid, the maximum shear on the N.A. of the quarter length cross-section and the maximum bending stress at the edges of the midspan were calculated for the four different plate-stiffener combinations, to yield two sets of curves, one for each kind

of stress. These curves describe the behavior of the three shear stresses and the three bending stresses corresponding to the three best arrangements at each of the above specified cross-sections respectively.

Part four includes all the significant results of this study. Three plane stress problems are examined in detail and their results for the nodal displacements, the average nodal stresses, and the stress trajectories are in agreement with the theoretically predicted or anticipated results.

The computer "stiffening" procedure results are included to demonstrate explicitly the maximum capability of the present computing technique.

At the end of Part four two sets of graphs illustrate that the stiffening of a plate is of least weight when the reinforcing material is added at the location of the maximum principal stress.

I BACKGROUND

A. Maxwell Structures

The first to establish the theorem that governs the design of "single purpose structures" as those structures were described by H. L. Cox⁽¹⁾ was Clerk Maxwell in 1869.⁽²⁾

The theorem as it is stated by Maxwell is:

THEOREM--"If every one of a system of points in a plane is in equilibrium under the action of tensions and pressures acting along the lines joining the points, then if we substitute for each point a small smooth ring through which smooth thin rods of indefinite length corresponding to the lines are compelled to pass, then if to each rod be applied a couple in the plane, whose moment is equal to the product of the length of the rod between the points multiplied by the tension or pressure in the former case, and tends to turn the rod in the positive or the negative direction, according as the force was a tension or a pressure, then every one of the system of rings will be in equilibrium. For each ring is acted on by a system of forces equal to the tensions and pressures in the former case, each to each, the whole system being turned round a right angle, and therefore the equilibrium of each point is undisturbed."

LEMMA--"In any system of points in equilibrium in a plane under the action of repulsions and attractions, the sum of the products of each attraction multiplied by the distance of the points between which it acts, is equal to the sum of the products of the repulsions multiplied each by the distance of the points between which it acts."

Maxwell's Lemma takes the algebraic form:

$$\sum F_T L_T + \sum Ph = \sum F_C L_C + \sum Rh \quad [1.1]$$

where:

F_T, F_C are the internal tensile and compressive forces, respectively.

L_T, L_C are the lengths of the truss members (ties and struts, respectively).

P, R are the external loads (applied and reactions, respectively)

h is the height of the point on which the external loads are applied.

If the reactions of the truss are not vertical, their horizontal components must be considered to create tensile or compressive moments.

Two examples of planar trusses are used to illustrate the application of both the Theorem and the Lemma. These are described in Appendix I-A.

According to Michell⁽⁴⁾ Maxwell's Lemma takes the form:

$$\sum F_T L_T - \sum F_C L_C = C \quad [1.2]$$

where:

$$C = \sum Ph + \sum Rh \quad [1.2.1]$$

C is a function of applied forces and the coordinates of their points of application, and is independent of the form of the frame.

As it was mentioned in the beginning, Maxwell's Theorem and Lemma apply to "single purpose structures" only. By that it is meant that the structure will be able to support a given set of loads. However, it may or may not support another set of loads. Furthermore, the structure is:

- (1) Filamentary (that is, a structure consisting entirely of normal stress carrying elements).
- (2) Constructed from uniform linearly-elastic material. (5)

This Theorem is significant in that it relates the total quantity of material of any truss member with a given allowable stress, to the external pressure or tension on that member. For any truss member with a known allowable stress $+\sigma_{all.}$ or $-\sigma_{all.}$, depending on whether the member is in tension or in compression, the strength of the member will be proportional to the cross-section A of the member.

That is,

$$|F| \leq \sigma_{all.} A \quad (6) \quad [1.3]$$

The weight of the member is

$$W = \rho g A \ell \quad [1.4]$$

where ρg is the density of the material and ℓ , the length of the bar. Therefore,

$$W = \rho g \frac{F}{\sigma_{all.}} \ell \quad [1.5]$$

or

$$V \cdot \sigma_{all.} = F \ell \quad [1.6]$$

where V is the volume of the bar. Therefore Maxwell's Lemma becomes:

$$V_t f_t - V_c f_c = \sum_i \bar{F}_i \cdot \bar{r}_i \quad [1.7]^*$$

which is the algebraic form in which H. L. Cox introduces Maxwell's Lemma. In equation [1.7]:

V_t, V_c are the total volumes of the material in tension and compression, respectively.

f_t, f_c are the maximum allowable tensile and compressive stresses.

\bar{F}_i is the planar external vector force applied to the i^{th} node of the structure.

\bar{r}_i is the vector distance of the i^{th} point from an assigned origin on the plane of the structure.

We obtain the total volume of material needed by adding the total material being in tension (all the ties) to the total material being in compression (all the struts).

Using equation [1.6] and solving for V , we obtain the following relationship which gives the minimum total volume of a truss which will adequately support a given set of external loads: (4)

$$V = \sum l_T \frac{F_T}{\sigma_{\text{all}.T}} + \sum l_C \frac{F_C}{\sigma_{\text{all}.C}} \quad [1.8]$$

* Note: In equation [1.7] the volume of the end fittings is not included.

In general, $\sigma_{all.T}$ for tension is not the same as $\sigma_{all.C}$ for compression in the same structure and this is why the notation $\pm\sigma_{all.}$ is not used above. l_T , l_C , F_T , and F_C are as defined before.

To summarize, Maxwell's Theorem is the cornerstone in the theory of optimization of weight in structural design because it gives the relationship of the minimum weight necessary to equilibrate a given set of applied loads. However, it conveys strict limitations:

- (a) In that it applies only to a given structure with a given set of loads (single purpose structure).
- (b) In that it applies only to filamentary truss structures of uniform elastic material.

B. Michell Structures

A. G. M. Michell's contribution to the field of optimization of weight in structural design is made in the expansion of Maxwell's Theorem. He also deals with filamentary type structures of uniform elastic material but which are restricted in that they consist of two types of filaments or bars which meet orthogonally. This orthogonality is due to the fact that each type of the filaments, depending on whether it is a tie or a strut, follows the paths of the principal tensile or compressive strain trajectories.

Michell shows that in *certain cases* we can find (a) the global minimum or the optimum of the optima of weight

solutions which equilibrate a given set of forces and (b) the configuration of the frames which gives the least weight of all the minimum weight solutions.

Starting with equation [1.8] which gives the minimum weight for a given frame and a given set of loads, he seeks to find the least weight frame out of a set of acceptable frames.

First he indicates that in order for the total volume of the structure V to be the least,

$$\sum \ell |F| \quad \text{must also be the least,}^{(4)} \quad [1.9]$$

where ℓ is the length of any tie or strut and $|F|$ is the absolute value of any tension or compression.

Consider a region of space R , and a set of frames within R such that every frame in R equilibrates the applied loads and satisfies the given boundary conditions.

If the imposed virtual deformation on the boundary of the structure due to the external loads is being shared by every member in such a way that the corresponding elongation or contraction is

$$|\Delta \ell| \leq \epsilon \ell \quad [1.10]$$

where ϵ is an infinitesimal positive ratio, then, the virtual work done on the structure will be

$$\delta W = \sum F \Delta \ell \quad [1.11]$$

or
$$|\delta W| = |\sum F \Delta \ell| \quad [1.12]$$

But, mathematically, it is also true that:

$$|\Sigma F \Delta l| \leq \Sigma |F| |\Delta l| \quad [1.13]$$

Notice, however, that the inequality sign has no physical significance here since the products of tension \times elongation or compression \times contraction are always positive. Therefore, equations [1.3], [1.10], and [1.13] yield

$$\Sigma |F| |\Delta l| \leq \sigma_{all.} \epsilon \Sigma A l \quad [1.14]$$

$$\text{or} \quad \leq \sigma_{all.} \epsilon V \quad [1.14.1]$$

where V is the total volume of the material of the structure.

From equations [1.12] and [1.14.1] we obtain

$$\frac{|\delta W|}{\sigma_{all.} \epsilon} \leq V \quad [1.15]$$

Since we want the least volume of the structure for the maximum use of the frame,

$$\frac{|\delta W|_{max}}{\sigma_{all.} \epsilon} = V_{least} \quad [1.16]$$

which is in complete agreement with equation [1.9].

This is easy to check. Note that if we substitute V_{least} by $\Sigma A l$, equation [1.16] becomes

$$\frac{|\delta W|_{max}}{\epsilon} = \Sigma l \sigma_{all.} A \quad [1.16.2]$$

Since $\sigma_{all.}$ stands for the numerical value of the allowable stress and it is positive

$$\sigma_{all.} A = |F| \quad [1.16.3]$$

where $|F|$ is as defined in equation [1.9]. For a particular frame M which satisfies the condition of equation [1.16], equation [1.16.4] becomes

$$\frac{|\delta W|_{\max}}{\epsilon} = \Sigma \rho_M |F|_M \quad [1.16.5]$$

For any other frame of the admissible frames that we compare with frame M , say frame A ,

$$\frac{|\delta W|_{\max}}{\epsilon} < \Sigma \rho_A |F|_A \quad [1.16.6]$$

will hold true. Therefore, frame M , M representing Michell, is the least weight frame.

To conclude, Michell has shown that there is always a least volume material that could be used in a structure to equilibrate a given set of loads. However, whether or not a structure that uses the least volume material exists for all cases is not known. ⁽⁶⁾ Michell has demonstrated the existence of such structures in a number of examples, some of which are described in Appendix I-B.

It is clear from the preceding material that the least weight structure, if it exists, must satisfy two conditions: ⁽⁷⁾

- (1) The stresses in all members are equal to the allowable stress σ_{all} . (Equation [1.16.3])
- (2) The virtual strains in each of the members of the structure are equal to $\pm\epsilon$, where the sign is in agreement with the sign of the end loads for each

member and in no case exceed the numerical value of ϵ .

These conditions imply that the members of the optimum structure M must lie along the principal strain trajectories. If they do not, and they simultaneously satisfy condition (2), then points can exist on any of these members at which the directions of the corresponding principal strains will be different than the directions of the members, and their magnitude would be greater than ϵ .

Since the principal strain trajectories as defined by Mohr's circle form an orthogonal mesh of lines, it follows that at any node of a Michell structure, a tie comes vertical to a strut.

4. The Stress Trajectory Approach

The approach followed in this study for the optimum arrangement of two-dimensional planar structures is basically the same as the one described in the previous Sections. However, instead of obtaining the principal strain trajectories, the technique to follow obtains the principal stress trajectories.

The principal stress trajectories are continuous curves, divided into two families, each corresponding to the principal compressive and tensile stresses, and at any point in a continuous medium are tangent to the directions of the principal compressive and tensile stresses which meet at

right angles; the magnitude of the principal stress varies along the paths of the trajectories, and it can be indicated in a pictorial representation either by varying their thickness or by assigning values of the principal stresses along their paths.

As recently as 1966, they were known as curves laborious to obtain, not easy to represent on paper and therefore not often used in practical stress analysis work. (12)

Today, however, the aid of the computer and the applicability of the Finite Element Technique to linear elastic problems provide the means by which one can easily and economically obtain the stress trajectories. Also, the representation on paper is done by the computer.

Two examples of stress trajectories have already been introduced in association with the Michell Field lines in Appendix I-B.

The stress trajectories have been introduced to ship structural design by Hovgaard. (13) He particularly demonstrates their importance in that they are curves indicative of the way to stiffen a plate against "wrinkling" which is a particular case of buckling.

Specifically, for high stress levels, the principal compressive stresses in a thin webbed plate like that of Figure I-B.5 can cause wrinkling. The regions of the plate where those principal stresses are totally, or to the greater percentage of their value, depended on the shear

stress are more likely to wrinkle. The directions of the principal compressive stresses are at 45° to the Neutral Axis (N.A.) of the plate at the N.A. and at a distance of $L/4$ from either end of the plate.

Therefore, the buckling wave formed when the critical stress value is reached runs along the direction of the principal compressive stresses. Its effect however is amplified due to the principal tensile stresses which in stretching the wave in a 90° direction from that in which the wave runs, create the wrinkling waves.

It is of extreme importance to note that in the longitudinally-framed ship, such as the warship of Figure I-1, the girders run approximately along the pathways of the stress trajectories. The plating of Section FFFF according to the previous discussion will be the most vulnerable to compressive stress due to shearing. Therefore, proper stiffening along the compressive stress trajectories will strengthen it.

This author has explained how one can obtain the stress trajectories applying Simple Beam Theory to rectangular plates; ⁽¹⁴⁾ however, the computational method is limited to one particular example, a centrally-loaded plate fixed at the ends. A more complete method which can treat any two-dimensional planar stress problem is described in detail in the next Section.

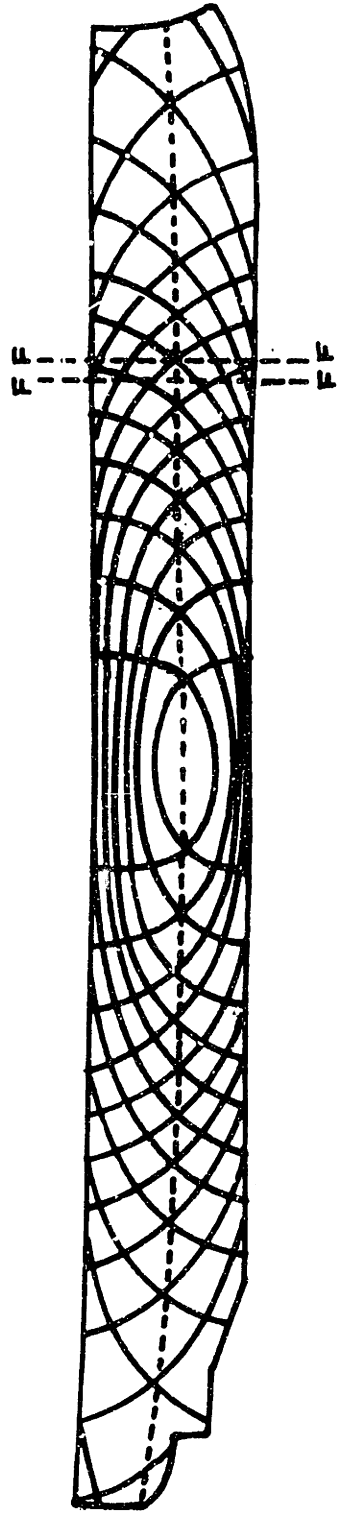


Figure I-1 (13)

The Principal Stress Trajectories in a Warship in the Hogging Condition

II THE STRESS TRAJECTORY TECHNIQUE

A. The Finite Element Approach

1. Introduction. The importance of the stress trajectories in determining the minimum weight arrangement of the truss members or the stiffeners of a plate under two dimensional loading has been explained in the previous section. However, the question still remains as to how one can easily obtain the principal stress trajectories.

The Finite Element Technique applied to the Plane Stress Approximation serves as one answer: one can arrive at the general state of stress of the structure and from Mohr's circle derive the principal stresses from which the stress trajectories will be obtained. The efficiency of this Technique is attributed to the fact that it is aided by the computer.

2. General. The Finite Element Technique is based on the fact that an elastic continuum, such as a plate or a shell, can be thought of as an assemblage of finite structural elements interconnected at a discrete number of finite nodal points, or control stations. Within each discrete or Finite Element, the behavior (displacements) is described in terms of a limited number of degrees of freedom, which are usually defined at interelement nodal stations (the nodal displacements in the present case).

In reality, however, an elastic continuum has an infinite number of degrees of freedom, but since it is impossible to treat them, the Finite Element Technique becomes an approximation to reality.

The approach to a planar stress structural problem using the Finite Element Displacement Method is similar to that used in simple Frame Structural Analysis as again the basic unknown parameters are the displacements of the nodal points. The difference between the two is that a two dimensional Finite Element can have three or more discrete number of nodal points situated on its boundaries, while the bars in Frame Analysis have only two nodes, one at each end.

The following is the general procedure for working with the Finite Element Technique:

- (1) Separate the continuum into a number of Finite Elements by imaginary lines.
- (2) Define a set of nodes on the boundaries of each element. The unknown displacements, q , will be defined there.
- (3) Choose a function (or functions) to define uniquely the displacements (u, v) of every point within the element, in terms of the nodal displacements, q .
- (4) Define the strains ($\epsilon_x, \epsilon_y, \gamma_{xy}$) of every point within the element in terms of the displacements,

u , v ; and thus, together with the elastic properties of the material, E , ν define the stresses $(\sigma_x, \sigma_y, \tau_{xy})$ within the element and therefore on its boundaries in terms of the strains.

- (5) Determine a system of nodal equivalent forces, Q , which balance the boundary stresses and any distributed boundary loads, so that from the stiffness relationship

$$\{Q\} = [K]\{q\} \quad [2.1]$$

We can solve for q having worked out the stiffness matrix $[K]$. (15)

3. Geometry. As mentioned in the Introduction, the present Technique examines only orthogonal geometry. Therefore, the simplest manner to represent a rectangular plate is to use a rectangular element, with dimensions which are multiples of the dimensions of the plate. To simplify the element further for our purposes, the element under consideration has only four nodes, one at each corner, and has no other nodes along its four edges.

4. Forces and Displacements. If the Force-Displacement relationships for the individual elements are known, we can derive the properties and study the behavior of the assembled structure.

The Finite Element Technique assumes that the internal stresses which actually act along the boundaries of an

element are substituted by equivalent fictitious forces on the nodes of the element. These equivalent forces, Q , will relate to the nodal displacements which are the basic unknown quantities, q .

Since the three kinds of possible inplane loads acting on a two-dimensional planar structure--namely, the forces in the x-direction, the forces in the y-direction, and the moments about the z-direction in a cartesian coordinate system--can be adequately modeled by a two-dimensional orthogonal system of forces acting on each node of the structure, each nodal point will have two degrees of freedom. Therefore, the displacements u , in the x-direction, and v , in the y-direction, within an element will have to be uniquely defined by the nodal displacements, q , as defined in Figure II-1. They are functions of the local coordinates x and y and their simplest representation for a rectangular element is the following:

$$u = \alpha_1 + \alpha_2 \frac{x}{L_x} + \alpha_3 \frac{y}{L_y} + \alpha_4 \frac{xy}{L_x L_y} \quad [2.1.1]$$

$$v = \alpha_5 + \alpha_6 \frac{x}{L_x} + \alpha_7 \frac{y}{L_y} + \alpha_8 \frac{xy}{L_x L_y} \quad [2.1.2]$$

where the constants $\alpha_1, \alpha_2, \alpha_3, \alpha_4$ can be expressed in terms of the nodal displacements, q . (15)

For each horizontal nodal displacement, we can write

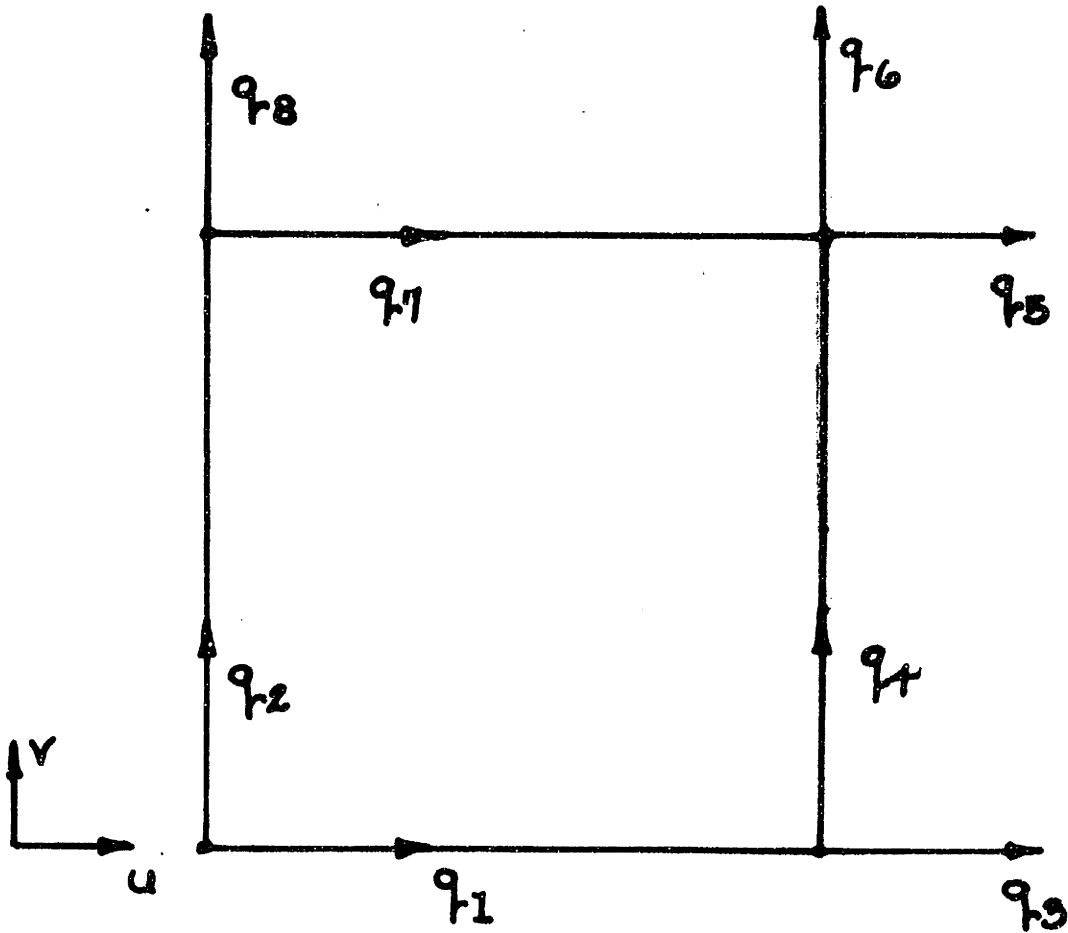


Figure II-1
The Nodal Displacements of
An Element in Their Positive Directions

$$q_1 = \alpha_1 \quad [2.2.1]$$

$$q_3 = \alpha_1 + \alpha_2 \quad [2.2.2]$$

$$q_5 = \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 \quad [2.2.3]$$

$$q_7 = \alpha_1 + \alpha_3 \quad [2.2.4]$$

Solving for α_1 , α_2 , α_3 , and α_4 , we obtain

$$\alpha_1 = q_1 \quad [2.3.1]$$

$$\alpha_2 = q_3 - q_1 \quad [2.3.2]$$

$$\alpha_3 = q_7 - q_1 \quad [2.3.3]$$

$$\alpha_4 = q_1 - q_3 + q_5 - q_7 \quad [2.3.4]$$

Substitution for α_1 , α_2 , α_3 , and α_4 in equation [2.1.1] yields

$$\begin{aligned} u = & q_1 + (q_3 - q_1) \frac{x}{L_x} + (q_7 - q_1) \frac{y}{L_y} \\ & + (q_1 - q_3 + q_5 - q_7) \frac{xy}{L_x L_y} \end{aligned} \quad [2.4.1]$$

or, rewriting equation [2.4.1] one has

$$\begin{aligned} u = & q_1 \left(1 - \frac{x}{L_x} - \frac{y}{L_y} + \frac{xy}{L_x L_y} \right) + q_3 \left(\frac{x}{L_x} - \frac{xy}{L_x L_y} \right) \\ & + q_5 \frac{xy}{L_x L_y} + q_7 \left(\frac{y}{L_y} - \frac{xy}{L_x L_y} \right) \end{aligned} \quad [2.4.2]$$

Note that the above expression for u , checks with the horizontal nodal displacements of Figure II-1, if we substitute for $(x = 0, y = 0)$, $(x = L_x, y = 0)$, $(x = L_x, y = L_y)$, and $(x = 0, y = L_y)$.

Similarly, we obtain the expression for the vertical displacement:

$$\begin{aligned}
 v = & q_2 \left(1 - \frac{x}{L_x} - \frac{y}{L_y} + \frac{xy}{L_x L_y} \right) + q_4 \left(\frac{x}{L_x} - \frac{xy}{L_x L_y} \right) \\
 & + q_6 \left(\frac{xy}{L_x L_y} \right) + q_8 \left(\frac{y}{L_y} - \frac{xy}{L_x L_y} \right) \quad [2.5]
 \end{aligned}$$

Clearly, the two expressions for the horizontal and vertical displacements are similar because of the symmetry of the element. Note that the displacements along the interelement boundaries are compatible.

Thus, the third step of the general procedure of the Finite Element Technique has been completed, that is, that a function must be chosen to uniquely define the state of displacement within each element in terms of its nodal displacements, q .

5. Strains and Stresses. From Timoshenko and Goodier⁽¹⁶⁾ it is clear that the strains at any point on a two-dimensional planar elastic continuum are given by

$$\{\epsilon\} = \begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \gamma_{xy} \end{Bmatrix} = \begin{Bmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial v}{\partial y} \\ \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \end{Bmatrix} \quad [2.6]$$

Also, the stresses will be given from

$$\{\sigma\} = [D] \{\epsilon\} \quad [2.7]$$

where

$$\{\sigma\} = \begin{Bmatrix} \sigma_x \\ \sigma_y \\ \tau_{xy} \end{Bmatrix} \quad [2.8]$$

and

$$[D] = \frac{E}{1 - \nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{(1-\nu)}{2} \end{bmatrix} \quad [2.9]$$

where $[D]$ is the *elasticity matrix* for the *Plane Stress--Isotropic Material* Approximation. E is Young's Modulus, and ν is Poisson's ratio.

The relationship of strain and stress in equation [2.7] is the matrix notation of the following set of simultaneous equations:

$$\epsilon_x = \frac{\sigma_x}{E} - \frac{\nu\sigma_y}{E} \quad [2.10.1]$$

$$\epsilon_y = -\frac{\nu\sigma_x}{E} + \frac{\sigma_y}{E} \quad [2.10.2]$$

$$\gamma_{xy} = 2(1 + \nu) \frac{\tau_{xy}}{E} \quad [2.10.3]$$

which explicitly explain the origin of $[D]$.

From equation [2.6] one can obtain the total strain at any point within the element in terms of the unknown nodal displacements, q , and the x , y coordinates.

$$\{\epsilon\} = \begin{Bmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial v}{\partial y} \\ \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \end{Bmatrix}$$

$$= \begin{bmatrix} \left[\frac{-1}{L_x} + \frac{y}{L_x L_y} \right] & 0 & \left[\frac{1}{L_x} - \frac{y}{L_x L_y} \right] & 0 & \left[\frac{y}{L_x L_y} \right] & 0 & \left[\frac{-y}{L_x L_y} \right] & 0 \\ 0 & \left[\frac{-1}{L_x} + \frac{x}{L_x L_y} \right] & 0 & \left[\frac{-x}{L_x L_y} \right] & 0 & \left[\frac{x}{L_x L_y} \right] & 0 & \left[\frac{1}{L_y} - \frac{x}{L_x L_y} \right] \\ \left[\frac{-1}{L_y} + \frac{x}{L_x L_y} \right] & \left[\frac{-1}{L_x} + \frac{y}{L_x L_y} \right] & \left[\frac{-x}{L_x L_y} \right] & \left[\frac{1}{L_x} - \frac{y}{L_x L_y} \right] & \left[\frac{x}{L_x L_y} \right] & \left[\frac{y}{L_x L_y} \right] & \left[\frac{1}{L_y} - \frac{x}{L_x L_y} \right] & \left[\frac{-y}{L_x L_y} \right] \end{bmatrix} \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \\ q_5 \\ q_6 \\ q_7 \\ q_8 \end{Bmatrix}$$

or

$$\{\epsilon\} = [B]\{q\}$$

[2.11]

Noticing the similarities in the terms of [B], one defines

$$A_1 = \frac{-1}{L_x} + \frac{y}{L_x L_y} \quad [2.12.1]$$

$$B_1 = \frac{y}{L_x L_y} \quad [2.12.2]$$

$$\Gamma_1 = \frac{-1}{L_y} + \frac{x}{L_x L_y} \quad [2.12.3]$$

$$\Delta_1 = \frac{-x}{L_x L_y} \quad [2.12.4]$$

Therefore [B] becomes:

$$[B] = \begin{bmatrix} A_1 & 0 & -A_1 & 0 & B_1 & 0 & -B_1 & 0 \\ 0 & \Gamma_1 & 0 & \Delta_1 & 0 & -\Delta_1 & 0 & -\Gamma_1 \\ \Gamma_1 & A_1 & \Delta_1 & -A_1 & -\Delta_1 & B_1 & -\Gamma_1 & -B_1 \end{bmatrix} \quad [2.13]$$

Equation [2.11] shows the linear relationship between the strains and the nodal displacements and therefore, the [B] matrix contains linear components.

6. The Stiffness Matrix. The stiffness matrix is defined as follows:

$$[K] = \int_V [B]^T [D] [B] dV \quad (15) \quad [2.14.1]$$

$$= \int_V [B]^T [D] [B] t dx dy \quad [2.14.2]$$

where t is the thickness of the plate and the integral is taken over an elemental volume $dV = t dx dy$.

Knowing [D] and [B], one can write

$$\begin{aligned}
 [B]^T [D] [B] t &= \begin{bmatrix} A_1 & 0 & \Gamma_1 \\ 0 & \Gamma_1 & A_1 \\ -A_1 & 0 & \Delta_1 \\ 0 & \Delta_1 & -A_1 \\ B_1 & 0 & -\Delta_1 \\ 0 & -\Delta_1 & B_1 \\ -B_1 & 0 & -\Gamma_1 \\ 0 & -\Gamma_1 & -B_1 \end{bmatrix} \\
 &= \frac{Et}{1 - \nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{(1-\nu)}{2} \end{bmatrix} \begin{bmatrix} A_1 & 0 & -A_1 & 0 & B_1 & 0 & -B_1 & 0 \\ 0 & \Gamma_1 & 0 & \Delta_1 & 0 & -\Delta_1 & 0 & -\Gamma_1 \\ \Gamma_1 & A_1 & \Delta_1 & -A_1 & -\Delta_1 & B_1 & -\Gamma_1 & -B_1 \end{bmatrix} =
 \end{aligned}$$

[2.15.1]

$$= \frac{Et}{1 - \nu^2}$$

$$\begin{bmatrix} A_1 & A_1 \nu & 0 & 0 & 0 & 0 \\ \Gamma_1 \nu & A_1 \nu & 0 & 0 & 0 & 0 \\ -A_1 & \Gamma_1 & 0 & 0 & 0 & 0 \\ \Delta_1 \nu & -A_1 \nu & \Delta_1 & 0 & 0 & 0 \\ B_1 & \Gamma_1 \nu & B_1 & 0 & 0 & 0 \\ -\Delta_1 \nu & -A_1 & -\Delta_1 & 0 & 0 & 0 \\ -B_1 & \Gamma_1 & -B_1 & 0 & 0 & 0 \\ -\Gamma_1 \nu & -A_1 \nu & -\Gamma_1 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} A_1 & 0 & -A_1 & 0 & B_1 & 0 & -B_1 & 0 \\ 0 & \Gamma_1 & 0 & \Delta_1 & 0 & -\Delta_1 & 0 & -\Gamma_1 \\ \Gamma_1 & A_1 & \Delta_1 & -A_1 & -\Delta_1 & B_1 & -\Gamma_1 & -B_1 \end{bmatrix}$$

$$= \frac{Et}{1 - \nu^2} [A]$$

[2.15.2]

$A_1^2 + \frac{\Gamma_1^2 (1-\nu)}{2}$	$A_1 \Gamma_1 \nu + A_1 \Gamma_1 \frac{(1-\nu)}{2}$	$-A_1^2 + \Gamma_1 \Delta_1 \frac{(1-\nu)}{2}$	$A_1 \Delta_1 \nu - A_1 \Gamma_1 \frac{(1-\nu)}{2}$	$A_1 B_1 - \Gamma_1 \Delta_1 \frac{(1-\nu)}{2}$	$-A_1 \Delta_1 \nu + B_1 \Gamma_1 \frac{(1-\nu)}{2}$	$-B_1 A_1 - \Gamma_1^2 \frac{(1-\nu)}{2}$	$-A_1 \Gamma_1 \nu - B_1 \Gamma_1 \frac{(1-\nu)}{2}$
$\Gamma_1^2 + A_1^2 \frac{(1-\nu)}{2}$	$\Gamma_1 \Delta_1 - A_1^2 \frac{(1-\nu)}{2}$	$-A_1 \Gamma_1 + \Delta_1 A_1 \frac{(1-\nu)}{2}$	$\Gamma_1 \Delta_1 - A_1^2 \frac{(1-\nu)}{2}$	$B_1 \Gamma_1 \nu - A_1 \Delta_1 \frac{(1-\nu)}{2}$	$-\Gamma_1 \Delta_1 + B_1 A_1 \frac{(1-\nu)}{2}$	$-B_1 \Gamma_1 \nu - \Gamma_1 A_1 \frac{(1-\nu)}{2}$	$\Gamma_1^2 - B_1 A_1 \frac{(1-\nu)}{2}$
$A^2 + \Delta_1^2 \frac{(1-\nu)}{2}$	$-A_1 \Delta_1 \nu - A_1 \Delta_1 \frac{(1-\nu)}{2}$	$A^2 + \Delta_1^2 \frac{(1-\nu)}{2}$	$-A_1 \Delta_1 \nu - A_1 \Delta_1 \frac{(1-\nu)}{2}$	$-A_1 B_1 - \Delta_1^2 \frac{(1-\nu)}{2}$	$\Delta_1 A_1 \nu + B_1 \Delta_1 \frac{(1-\nu)}{2}$	$A_1 B_1 - \Gamma_1 \Delta_1 \frac{(1-\nu)}{2}$	$\Gamma_1 A_1 \nu - B_1 \Delta_1 \frac{(1-\nu)}{2}$
	$\Delta_1^2 + A_1^2 \frac{(1-\nu)}{2}$		$\Delta_1^2 + A_1^2 \frac{(1-\nu)}{2}$	$B_1 \Delta_1 \nu + A_1 \Delta_1 \frac{(1-\nu)}{2}$	$-\Delta_1^2 - A_1 B_1 \frac{(1-\nu)}{2}$	$-B_1 \Delta_1 \nu + B_1 \Gamma_1 \frac{(1-\nu)}{2}$	$-\Gamma_1 \Delta_1 + A_1 B_1 \frac{(1-\nu)}{2}$
				$B_1^2 + \Delta_1^2 \frac{(1-\nu)}{2}$	$-\Delta_1 B_1 \nu - B_1 \Delta_1 \frac{(1-\nu)}{2}$	$-B_1^2 + \Gamma_1 \Delta_1 \frac{(1-\nu)}{2}$	$-\Gamma_1 B_1 \nu + B_1 \Delta_1 \frac{(1-\nu)}{2}$
					$\Delta_1^2 + B_1^2 \frac{(1-\nu)}{2}$	$+B_1 \Delta_1 \nu - \Gamma_1 B_1 \frac{(1-\nu)}{2}$	$\Gamma_1 \Delta_1 - B_1^2 \frac{(1-\nu)}{2}$
	(symmetric)					$B_1^2 + \Gamma_1^2 \frac{(1-\nu)}{2}$	$B_1 \Gamma_1 \nu + B_1 \Gamma_1 \frac{(1-\nu)}{2}$
							$\Gamma_1^2 + B_1^2 \frac{(1-\nu)}{2}$

Table II-1 The [A] Matrix of Equation [2.15.2]

where [A] is the symmetric matrix shown in Table II-1.

Taking the integral of the right-hand-side of equation [2.15.2] over an elemental volume, $t dx dy$, essentially means to take the following integrals where t has already been taken out of the integral:

From equations [2.12.1] through [2.12.4], one has

$$\int_v A_1^2 dx dy = \int_0^{L_y} \int_0^{L_x} \left(\frac{1}{L_x} + \frac{y}{L_x L_y} \right)^2 dx dy = \frac{L_y}{3L_x} \quad [2.16.1]$$

$$\int_v B_1^2 dx dy = \int_0^{L_y} \int_0^{L_x} \left(\frac{y}{L_x L_y} \right)^2 dx dy = \frac{L_y}{3L_x} \quad [2.16.2]$$

$$\int_v \Gamma_1^2 dx dy = \int_0^{L_y} \int_0^{L_x} \left(-\frac{1}{L_y} + \frac{x}{L_x L_y} \right)^2 dx dy = \frac{L_x}{3L_y} \quad [2.16.3]$$

$$\int_v \Delta_1^2 dx dy = \int_0^{L_x} \int_0^{L_x} \left(\frac{x}{L_x L_y} \right)^2 dx dy = \frac{L_x}{3L_y} \quad [2.16.4]$$

$$\int_v A_1 B_1 dx dy = \int_0^{L_y} \int_0^{L_x} \left(-\frac{1}{L_x} + \frac{y}{L_x L_y} \right) \left(\frac{y}{L_x L_y} \right) dx dy = \frac{-L_y}{6L_x} \quad [2.16.5]$$

$$\int_v A_1 \Gamma_1 dx dy = \int_0^{L_y} \int_0^{L_x} \left(-\frac{1}{L_x} + \frac{y}{L_x L_y} \right) \left(-\frac{1}{L_y} + \frac{x}{L_x L_y} \right) dx dy = \frac{1}{4} \quad [2.16.6]$$

$$\int_v A_1 \Delta_1 dx dy = \int_0^{L_y} \int_0^{L_x} \left(-\frac{1}{L_x} + \frac{y}{L_x L_y} \right) \left(\frac{-x}{L_x L_y} \right) dx dy = \frac{1}{4} \quad [2.16.7]$$

$$\int_v B_1 \Gamma_1 dx dy = \int_0^{L_y} \int_0^{L_x} \left(\frac{y}{L_x L_y} \right) \left(-\frac{1}{L_y} + \frac{x}{L_x L_y} \right) dx dy = -\frac{1}{4} \quad [2.16.8]$$

$$\int_v B_1 \Delta_1 dx dy = \int_0^{L_y} \int_0^{L_x} \left(\frac{y}{L_x L_y} \right) \left(\frac{-x}{L_x L_y} \right) dx dy = -\frac{1}{4} \quad [2.16.9]$$

$$\int_v \Gamma_1 \Delta_1 dx dy = \int_0^{L_y} \int_0^{L_x} \left(-\frac{1}{L_y} + \frac{x}{L_x L_y} \right) \left(\frac{-x}{L_x L_y} \right) dx dy = \frac{L_x}{6L_y} \quad [2.16.10]$$

$\frac{L_y}{3L_x} + \frac{L_x(1-\nu)}{3L_y}$	$\frac{\nu}{4} + \frac{1}{4} \frac{(1-\nu)}{2}$	$-\frac{L_y}{3L_x} + \frac{L_x(1-\nu)}{6L_y}$	$\frac{\nu}{4} - \frac{1}{4} \frac{(1-\nu)}{2}$	$-\frac{L_y}{6L_x} + \frac{L_x(1-\nu)}{6L_y}$	$-\frac{\nu}{4} - \frac{1}{4} \frac{(1-\nu)}{2}$	$\frac{L_y}{6L_x} - \frac{L_x(1-\nu)}{3L_y}$	$-\frac{\nu}{4} + \frac{1}{4} \frac{(1-\nu)}{2}$
$\frac{L_x}{3L_y} + \frac{L_y(1-\nu)}{3L_x}$	$\frac{\nu}{4} - \frac{1}{4} \frac{(1-\nu)}{2}$	$-\frac{L_x}{6L_y} + \frac{L_y(1-\nu)}{6L_x}$	$\frac{\nu}{4} + \frac{1}{4} \frac{(1-\nu)}{2}$	$-\frac{L_x}{6L_y} + \frac{L_y(1-\nu)}{6L_x}$	$-\frac{\nu}{4} - \frac{1}{4} \frac{(1-\nu)}{2}$	$\frac{L_x}{6L_y} - \frac{L_y(1-\nu)}{3L_x}$	$-\frac{\nu}{4} + \frac{1}{4} \frac{(1-\nu)}{2}$
$\frac{L_y}{3L_x} + \frac{L_x(1-\nu)}{3L_y}$	$\frac{\nu}{4} - \frac{1}{4} \frac{(1-\nu)}{2}$	$-\frac{L_y}{6L_x} + \frac{L_x(1-\nu)}{6L_y}$	$\frac{\nu}{4} + \frac{1}{4} \frac{(1-\nu)}{2}$	$-\frac{L_y}{6L_x} + \frac{L_x(1-\nu)}{6L_y}$	$-\frac{\nu}{4} - \frac{1}{4} \frac{(1-\nu)}{2}$	$\frac{L_y}{6L_x} - \frac{L_x(1-\nu)}{3L_y}$	$-\frac{\nu}{4} + \frac{1}{4} \frac{(1-\nu)}{2}$
$\frac{L_x}{3L_y} + \frac{L_y(1-\nu)}{3L_x}$	$\frac{\nu}{4} + \frac{1}{4} \frac{(1-\nu)}{2}$	$-\frac{L_x}{6L_y} + \frac{L_y(1-\nu)}{6L_x}$	$\frac{\nu}{4} - \frac{1}{4} \frac{(1-\nu)}{2}$	$-\frac{L_x}{6L_y} + \frac{L_y(1-\nu)}{6L_x}$	$-\frac{\nu}{4} + \frac{1}{4} \frac{(1-\nu)}{2}$	$\frac{L_x}{6L_y} - \frac{L_y(1-\nu)}{3L_x}$	$-\frac{\nu}{4} - \frac{1}{4} \frac{(1-\nu)}{2}$
(symmetric)							

Table II-2 The Stiffness Matrix $[K] \times [1-\nu^2/Et]$ for One Rectangular Element

Therefore,

$$[K] = \frac{Et}{1 - \nu^2} [A'] \quad [2.17]$$

where $[A']$ is shown in Table II-2.

Here ends the development of one element's stiffness matrix. The stiffness matrix for the entire structure is obtained by assembling all of the individual stiffness matrices. The inverse of the assembled stiffness matrix is used to solve for all the nodal displacements, that is, from equation [2.1].

$$\{q\} = [K]_{\text{total}}^{-1} \{Q\} \quad [2.18]$$

where $\{Q\}$ is the matrix of the equivalent nodal forces for the entire structure.

7. Equivalent Nodal Forces. As mentioned in Part 3 of this section, the Finite Element Technique deals with fictitious forces, at the nodes of each element, which are energy equivalent⁽¹⁵⁾ to the internal stresses acting on its boundaries. These nodal forces, Q , have a one-to-one correspondence with the nodal displacements of the element, q .

Presently, since each node will have two degrees of freedom, two equivalent nodal forces are required. That is, for every element which has a stiffness matrix $[K]$ as defined on Table II-2,

$$\begin{Bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ Q_4 \\ Q_5 \\ Q_6 \\ Q_7 \\ Q_8 \end{Bmatrix} = [K] \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \\ q_5 \\ q_6 \\ q_7 \\ q_8 \end{Bmatrix} \quad [2.19]$$

When distributed loads act on an edge of an element, as the case is for an element on the boundary of a plate, the nodal forces of the element must be energy equivalent to the distributed external loads or the internal interelement boundary stresses.

Example. Let us assume the rectangular element of Figure II-2 loaded on one of its edges with a linearly distributed force of intensity $f(x)$.

The total external work done on that element, if one allows a virtual displacement $\{\delta\}$ will be:

$$W_{\text{ext.}} = \int_0^{L_x} (\vec{F} \cdot \vec{\delta}) dx \quad [2.19]$$

where \vec{F} is the vector force resultant formed by integrating the applied load $f(x)$ over the thickness of the element.

When together with the normal intensity $f(x)$, there is a shear distribution acting along the boundary of the element, \vec{F} will no longer be normal to the edge of the element.

Therefore, in general

$$\vec{F} = F_x \vec{i} + F_y \vec{j} \quad [2.20]$$

where the \vec{i} and \vec{j} directions are shown in Figure II-2, and $\vec{\delta}$ is the total virtual displacement due to \vec{F} and for the general case, it will be:

$$\vec{\delta} = \delta_x \vec{i} + \delta_y \vec{j} \quad [2.21]$$

Therefore, applying equation [2.19] to the example of Figure II-2, we obtain:

$$W_{\text{ext.}} = \int_0^{L_x} F_y \delta_y dx \quad [2.22]$$

Since F_y will equal to the intensity of the load over the elemental side dx ,

$$F_y = - \left\{ \frac{[f(l) - f(k)]}{L_x} x + f(k) \right\} \quad [2.23]$$

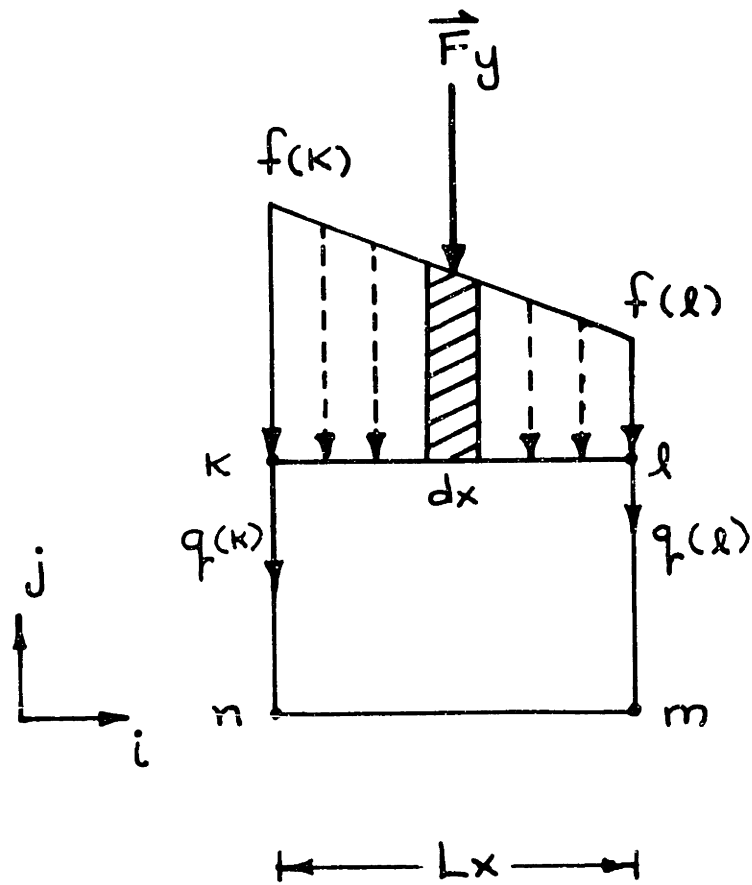
Similarly,

$$\delta_y = - \left\{ \frac{[q(l) - q(k)]}{L_x} x + q(k) \right\} \quad [2.24]$$

where $q(l)$ and $q(k)$ are the nodal displacements.

Integrating to get $W_{\text{ext.}}$ in equation [2.22] we have:

$$\begin{aligned} W_{\text{ext.}} &= \\ &= \int_0^{L_x} \left\{ \frac{[f(l) - f(k)]}{L_x} x + f(k) \right\} \left\{ \frac{[q(l) - q(k)]}{L_x} x + q(k) \right\} dx = \end{aligned}$$



NOTE: THE POSITIVE FORCES AND DISPLACEMENTS ARE POINTING AWAY FROM THE ELEMENT.

Figure II-2

An Element under a Linearly Varying Boundary Load Distribution

$$\begin{aligned}
&= \frac{1}{3} [f(l)q(l) - f(k)q(l) - f(l)q(k) + f(k)q(k)]L_x \\
&+ f(k)q(k)L_x + \frac{1}{2}[f(l)q(k) - f(k)q(k)]L_x \\
&+ \frac{1}{2}[q(l)f(k) - q(k)f(k)]L_x
\end{aligned}$$

or

$$W_{\text{ext.}} = q(k) \left\{ L_x \left[\frac{f(k)}{3} + \frac{f(l)}{6} \right] \right\} + q(l) \left\{ L_x \left[\frac{f(k)}{6} + \frac{f(l)}{3} \right] \right\} \quad [2.25]$$

Clearly, the expressions in the brackets have units of Force and represent the equivalent nodal forces, Q , since

$$\int_x (\vec{F} \cdot \vec{\delta}) dx = \sum_i q_i Q_i \quad [2.26]$$

Therefore, the equivalent nodal forces are:

$$Q(k) = L_x \frac{f(k)}{3} + \frac{f(l)}{6}$$

$$\text{and } Q(l) = L_x \frac{f(k)}{6} + \frac{f(l)}{3} \quad [2.27]$$

When external concentrated forces \bar{Q} are applied on the nodes of the assembled structure, their effects must be added to the equilibrium equation, that is,

$$[K]\{q\} = \{Q\} = \underbrace{\{\bar{Q}\}}_{\text{nodal concentrated}} + \underbrace{\{Q\}}_{\text{nodal equivalent}} \quad [2.28]$$

However, the computer program which is explained in Appendix II-2 is equipped to handle either linearly

distributed forces or external concentrated loads but not both at the same time.

B. Stresses and Stress Trajectories

1. General State of Stress for a Rectangular Element.

In the previous section, it is shown explicitly how one can obtain the nodal displacements for the total structure. That is:

- (1) By developing the stiffness matrix for the assembled structure
- (2) By defining the "force entries" (that is, the magnitude and direction of every applied force at the control point of application)
- (3) By solving for the q 's in equation [2.18].

According to the fourth step of the Finite Element general procedure, the strains ϵ_x , ϵ_y , and γ_{xy} of one element are defined in terms of the displacement functions $u(x, y)$ and $v(x, y)$ which are expressed in terms of the nodal displacements, q (equations [2.4.2], [2.5], and [2.6]).

Therefore, using the strain-displacement relationship of equation [2.11] and the stress-strain relationship of equation [2.7], one obtains

$$\{\sigma\}^e = [D][B]\{q\}^e \quad [2.29]$$

where the superscript e refers to the stresses and nodal displacements of one element.

Multiplying the elasticity matrix [D] with [B], and substituting from equations [2.9] and [2.13] for their equals

$$\begin{aligned}
 & \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{(1-\nu)}{2} \end{bmatrix} \begin{bmatrix} A_1 & 0 & -A_1 & 0 & B_1 & 0 & -B_1 & 0 \\ 0 & \Gamma_1 & 0 & \Delta_1 & 0 & -\Delta_1 & 0 & -\Gamma_1 \\ \Gamma_1 & A_1 & \Delta_1 & -A_1 & -\Delta_1 & B_1 & -\Gamma_1 & -B_1 \end{bmatrix} \\
 & = \frac{E}{1-\nu^2} \begin{bmatrix} A_1 & \Gamma_1 \nu & -A_1 & \Delta_1 \nu & B_1 & -\Delta_1 \nu & -\Gamma_1 \nu & \\ A_1 \nu & \Gamma_1 & -A_1 \nu & \Delta_1 & B_1 \nu & -\Delta_1 & -\Gamma_1 & \\ \Gamma_1 \frac{(1-\nu)}{2} & A_1 \frac{(1-\nu)}{2} & \Delta_1 \frac{(1-\nu)}{2} & -A_1 \frac{(1-\nu)}{2} & -\Delta_1 \frac{(1-\nu)}{2} & B_1 \frac{(1-\nu)}{2} & -\Gamma_1 \frac{(1-\nu)}{2} & -B_1 \frac{(1-\nu)}{2} \end{bmatrix} \\
 & = [S]^e \quad [2.29.1]
 \end{aligned}$$

where $[S]^e$ is the element stress matrix.

Therefore, substituting for the values of A_1 , B_1 , Γ_1 and Δ_1 from equations [2.12.1] through [2.12.4] and multiplying $[S]^e$ by $\{q\}^e$, we obtain the stresses σ_x , σ_y , and τ_{xy} where

$$\begin{aligned} \sigma_x = & \left(\frac{E}{1 - \nu^2} \right) \left\{ \left(\frac{-1}{L_x} + \frac{y}{L_x L_y} \right) q_1 + \nu \left(\frac{-1}{L_y} + \frac{x}{L_x L_y} \right) q_2 \right. \\ & - \left(\frac{-1}{L_x} + \frac{y}{L_x L_y} \right) q_3 + \nu \left(\frac{-x}{L_x L_y} \right) q_4 + \left(\frac{y}{L_x L_y} \right) q_5 - \nu \left(\frac{-x}{L_x L_y} \right) q_6 \\ & \left. - \left(\frac{y}{L_x L_y} \right) q_7 - \nu \left(\frac{-1}{L_y} + \frac{x}{L_x L_y} \right) q_8 \right\} \quad [2.30.1] \end{aligned}$$

$$\begin{aligned} \sigma_y = & \left(\frac{E}{1 - \nu^2} \right) \left\{ \nu \left(\frac{-1}{L_x} + \frac{y}{L_x L_y} \right) q_1 + \left(\frac{-1}{L_y} + \frac{x}{L_x L_y} \right) q_2 \right. \\ & - \nu \left(\frac{-1}{L_x} + \frac{y}{L_x L_y} \right) q_3 + \left(\frac{-x}{L_x L_y} \right) q_4 + \nu \left(\frac{y}{L_x L_y} \right) q_5 - \left(\frac{-x}{L_x L_y} \right) q_6 \\ & \left. - \nu \left(\frac{y}{L_x L_y} \right) q_7 - \left(\frac{-1}{L_y} + \frac{x}{L_x L_y} \right) q_8 \right\} \quad [2.30.2] \end{aligned}$$

$$\begin{aligned} \tau_{xy} = & \left(\frac{E}{2(1 + \nu)} \right) \left(\frac{-1}{L_y} + \frac{x}{L_x L_y} \right) q_1 + \left(\frac{-1}{L_x} + \frac{y}{L_x L_y} \right) q_2 \\ & + \left(\frac{-x}{L_x L_y} \right) q_3 - \left(\frac{-1}{L_x} + \frac{y}{L_x L_y} \right) q_4 - \left(\frac{-x}{L_x L_y} \right) q_5 + \left(\frac{y}{L_x L_y} \right) q_6 \end{aligned}$$

$$\left[\frac{-1}{L_y} + \frac{x}{L_x L_y} \right] q_7 = \left[\frac{y}{L_x L_y} \right] q_8 \quad [2.30.3]$$

Thus, one arrives at the general expressions for the state of stress at any point within the element.

Rearranging and redefining, equations [2.30] become

$$\sigma_x = \sigma_{x_1} + \sigma_{x_2} x + \sigma_{x_3} y \quad [2.31.1]$$

$$\sigma_y = \sigma_{y_1} + \sigma_{y_2} x + \sigma_{y_3} y \quad [2.31.2]$$

$$\tau_{xy} = \tau_{xy_1} + \tau_{xy_2} x + \tau_{xy_3} y \quad [2.31.3]$$

where

$$\sigma_{x_1} = \frac{E}{1 - \nu^2} \left[\frac{1}{L_x} (q_3 - q_1) + \frac{\nu}{L_y} (q_8 - q_2) \right] \quad [2.32.1]$$

$$\sigma_{x_2} = \frac{E}{1 - \nu^2} \left[\frac{\nu}{L_x L_y} (q_2 - q_4 + q_6 - q_8) \right] \quad [2.32.2]$$

$$\sigma_{x_3} = \frac{E}{1 - \nu^2} \left[\frac{1}{L_x L_y} (q_1 - q_3 + q_5 - q_7) \right] \quad [2.32.3]$$

$$\sigma_{y_1} = \frac{E}{1 - \nu^2} \left[\frac{\nu}{L_x} (q_3 - q_1) + \frac{1}{L_y} (q_8 - q_2) \right] \quad [2.32.4]$$

$$\sigma_{y_2} = \frac{E}{1 - \nu^2} \left[\frac{1}{L_x L_y} (q_2 - q_4 + q_6 - q_8) \right] \quad [2.32.5]$$

$$\sigma_{y_3} = \frac{E}{1 - \nu^2} \left[\frac{\nu}{L_x L_y} (q_1 - q_3 + q_5 - q_7) \right] \quad [2.32.6]$$

$$\tau_{xy_1} = \frac{E}{2(1 + \nu)} \left[\frac{1}{L_y} (q_7 - q_1) + \frac{1}{L_x} (q_4 - q_2) \right] \quad [2.32.7]$$

$$\tau_{xy_2} = \frac{E}{2(1 + \nu)} \left[\frac{1}{L_x L_y} (q_1 - q_3 + q_5 - q_7) \right] \quad [2.32.8]$$

$$\tau_{xy_3} = \frac{E}{2(1 + \nu)} \left[\frac{1}{L_x L_y} (q_2 - q_4 + q_6 - q_8) \right] \quad [2.32.9]$$

To assure the linearity of stress throughout a uniform elastic planar structure, such as a rectangular plate which is the subject of the present study, the stresses $\{\sigma\}$ at each nodal point of the structure must represent the average stress value of those stresses calculated there separately for each element common to the nodal point. The way to calculate the average stress at a nodal point due to two or four common to the nodal point elements is explained in Appendix II-A.

2. Principal Stresses and Stress Trajectories. Once the average stresses σ_x , σ_y , and τ_{xy} at all control points of the structure have been calculated, the principal stresses there can be obtained using the well-known Mohr's circle equations:

$$\sigma_1 = \frac{\sigma_x + \sigma_y}{2} + \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \quad [2.33.1]$$

$$\sigma_2 = \frac{\sigma_x + \sigma_y}{2} - \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \quad [2.33.2]$$

where σ_1 is the principal tensile stress and σ_2 is the principal compressive stress.

Their directions with respect to the horizontal x-axis are given by

$$\theta = \frac{1}{2} \tan^{-1} \left[\frac{2\tau_{xy}}{\sigma_x - \sigma_y} \right] \quad [2.33.3]$$

where 2θ is defined to be in the range of

$$0 \leq 2\theta \leq \pi/2 \quad [2.33.4]$$

$$\text{for } 0 \leq \frac{2\tau_{xy}}{\sigma_x - \sigma_y} < +\infty \quad [2.33.5]$$

$$\text{and } -\pi/2 \leq 2\theta < 0 \quad [2.33.6]$$

$$\text{for } -\infty < \frac{2\tau_{xy}}{\sigma_x - \sigma_y} < 0 \quad [2.33.7]$$

Since the magnitudes and the directions of the principal stresses with the +x-axis can be calculated at any nodal point of the structure, the stress trajectories can easily be obtained.

According to the definition of the stress trajectories given in section C of part I, the directions of the

principal tensile and compressive stresses are perpendicular to each other at any point in an elastic continuum such as a plate subjected to inplane loading. These directions are tangent to the stress trajectories that pass from that point.

As long as the stress trajectories maintain a smooth curvature and have no sharp discontinuities, they can be approximated in a satisfactory manner by straight line segments between the interelement boundaries of the structure which form an equidistant orthogonal grid of lines.

Example. Let us assume the simple orthogonal grid of the structure of Figure II-3, which is a plate divided into six rectangular finite elements.

Let us assume that the geometry of the structure has been previously defined and that the average stresses σ_x , σ_y , and τ_{xy} at each control point have been already calculated.

The first questions to be asked would be:

- (a) Where to start?
- (b) Which family of trajectories (compressive and/or tensile) to represent?
- (c) How many trajectories would sufficiently define the state of stress of the entire structure?

Since the average stresses at each nodal point are known, the most natural place to start is at a corner of the structure nodal point because to start at some point on an element boundary, or anywhere else in the structure (even at points within elements), would be a very involved problem

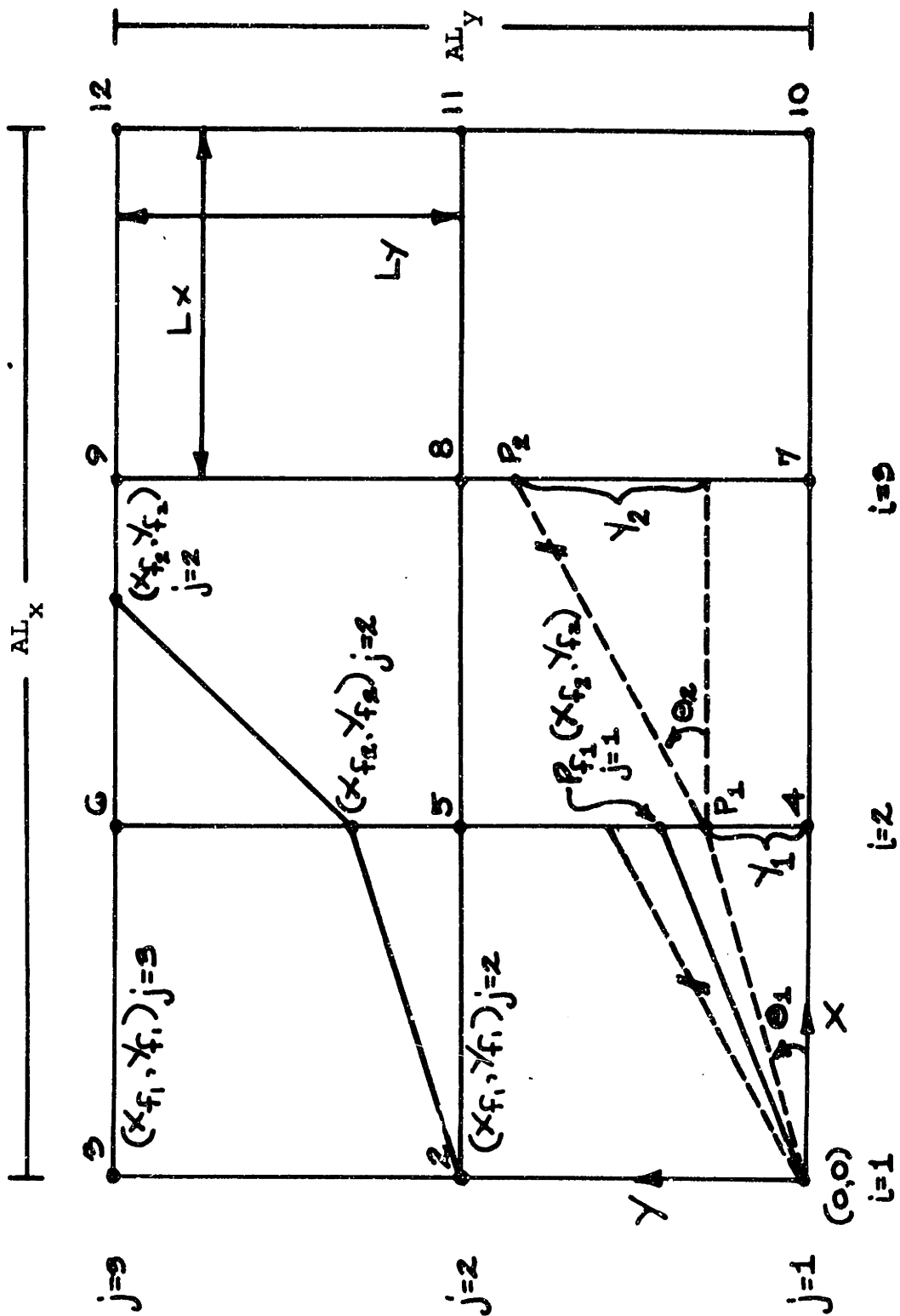


Figure II-3

Linear Extrapolation of the Directions of the Principal Stresses to Get the Stress Trajectories in a Six Element Structure

and beyond the scope of the present study. Nevertheless, this can almost be achieved if we assign a large number of elements to the geometry of the structure, creating thus a very fine orthogonal grid, with more nodal points.

Furthermore, to assure that the extrapolated direction of principal stress will meet an element boundary or another control station, the structure must be "properly" oriented.

In other words, if it is decided that the starting point is the first node of the structure and that it is desired to obtain the principal compressive stress trajectories, we should not anticipate a negatively sloped principal compressive stress at the starting point because then the extrapolated slope would be out of the structure.

If, however, we do get a negative slope at the starting point, the structure should be turned at 90° so that in the present example, the new node No. 1 will be that which at the present is node No. 10.

It appears that the number of the stress trajectories to define the state of stress could be limited sufficiently to the number of control points in the y-direction. This is really a decision that depends on the designer. For our purposes, however, which is to show how one can efficiently obtain the stress trajectories, we will allow the number of trajectories to be determined by the number of control points in the y-direction, that is, in the example of Figure II-3, the number of trajectories is "three".

To summarize, the answers given to the three questions above define the following limitations to the problem of determining the stress trajectories.

- (a) The calculation of the first trajectory starts at the first node of the structure which is "properly" oriented.
- (b) Only the principal compressive stress trajectories are obtained in this study. The principal tensile stress trajectories can be obtained in a similar manner.
- (c) The number of control points in the y-direction and on the left edge of a rectangular structure will correspond to the number of trajectories to determine the state of compressive stress of the structure.

The analytic procedure is partly explained by means of Comment cards in Subroutine TRAJEC (see Appendix II-A) but for purposes of clarification and continuity it is explained in detail below, and it is shown how it applies to the example of Figure II-3.

- (1) Start at the first node of the structure where the x, y coordinates are (0, 0).
- (2) Define the number of trajectories to be calculated. (that is, the number of trajectories is equal to the number of stations in the y-direction which is equal to 3).

Note that the last trajectory is actually one point, (that is, the control station No. 3 in the present example). However, its magnitude evaluated there completes the picture.

(3) Knowing the average stresses σ_x , σ_y , and τ_{xy} evaluate σ_2 (the principal compressive stress) at node No. 1.

(4) Define the number of stations along the x-direction at which the extrapolated direction of principal compressive stress will start. (Here, we have three stations, namely the interelement boundaries vertical to nodes No. 1, No. 4, and No. 7.

(5) Calculate the angle θ_1 between the positive x-axis and the direction of the principal stress at node No. 1. Knowing the element's side L_x and θ_1 , we can calculate y_1 which is the difference in y between point P_1 and the ordinate of the starting point.

(6) Check if $y_1 > AL_y$. If so, specify that the trajectory in question is off the plate and in that case define its final coordinates x_f , y_f and its final σ_x , σ_y and σ_{xy} stresses. Then go to trajectory No. 2 which starts at control station No. 2. If not, continue.

(7) Calculate the stresses at the first extrapolation point P_1 which is in general between two nodes N_1 and N_2 (in our case P_1 is between nodes No. 4 and No. 5).

(8) Calculate the difference Δy_1 between the ordinates of P_1 and N_1 .

(9) Interpolate between the stress values at nodes N_1 and N_2 to obtain the stresses at P_1 . (No need to calculate the σ_2 at P_1 because P_1 is a temporary point).

(10) Calculate the angle θ_2 between the direction of the principal compressive stress and the +x-axis (similarly to step No. 5) and obtain y_2 .

(11) Take the average between y_1 and y_2 and add it to the final y_{f_i} coordinate of the current station i to get the final y_f of the $i + 1$ station. (Here the final y_f of the current station is zero).

(12) Similarly to step No. 6, check if $y_{f_{i+1}} > AL_y$. If so, define the new $y_{f_{i+1}}$ final coordinate to be $y_{f_{i+1}} = AL_y$. But its $x_{f_{i+1}}$ coordinate will be at some point between x_{f_i} and $(x_{f_i} + L_x)$ which can be easily obtained by comparing similar triangles. Then go to trajectory No. 2 and start from control point No. 2. If not, continue.

(13) Evaluate the stresses at the final point $P_{f_1}(x_{f_{i+1}}, y_{f_{i+1}})$ by interpolation between the stresses at N_1 and N_2 . (Here P_{f_1} is again between nodes No. 4 and No. 5).

(14) Go back to step No. 5 and repeat all the steps up to here until the trajectory is off the plate or until the trajectory passes through all stations along the x-direction.

(15) In any case continue the procedure by going to the second control point where the second trajectory commences and repeat the above steps until all the trajectories have been properly defined in terms of the x and y coordinates.

Thus, from the present example we anticipate three trajectories (subscripted j) of which trajectory $j=3$ is just the magnitude of the compressive stress σ_2 at control station No. 3.

Since the final coordinates x_f , y_f of each trajectory have been properly calculated, we can easily plot them by the aid of the computer (see Appendix II-A).

To conclude, this part has shown how through applying the Plane Stress Approximation to the Finite Element Technique one can obtain the general state of stress for two-dimensional planar problems. Furthermore, this part has explicitly described and analyzed the procedure through which a good approximation of the stress trajectories can be obtained.

Appendix II-A includes a discussion of the capability as well as the complete listing of the computer program through which we obtain the displacements $\{q\}$, the stresses $\{\sigma\}$ and the principal compressive stress trajectories. (Subroutine STIFEN which was lately added to the main program is related to the next section.

III STIFFENER ARRANGEMENTS

1. Introduction

The Stress Trajectory Technique explained in detail in Part II together with its associated computer program described in Appendix II-A may give the designer the means of properly reinforcing a plate or arranging the truss members in a two-dimensional truss problem. For the latter case one has to imagine that the initial thickness, t , of the plate is infinitesimal.

In this part different stiffener arrangements of the same cross-sectional area of reinforcing material are being compared in two distinct cross-sections of a planar structure. The results of this comparison may lead one to determine the least weight arrangement for the maximum stress reduction.

2. A Comparison between Two Stiffener Arrangements--Case I

Let us consider the panel of Figure III-1 (that is, a centrally loaded fixed ends plate) for which the Simple Beam Theory is a very good approximation.

Observing a small element at $x = L/4$ and $y = B/2$ (location A), one expects it to have a principal compressive stress σ_2 due to the shear stress τ_{xy} . At $x = L/2$, $y = B$ (location B) the principal compressive stress σ_2 will be due only to the bending stress, σ_x .

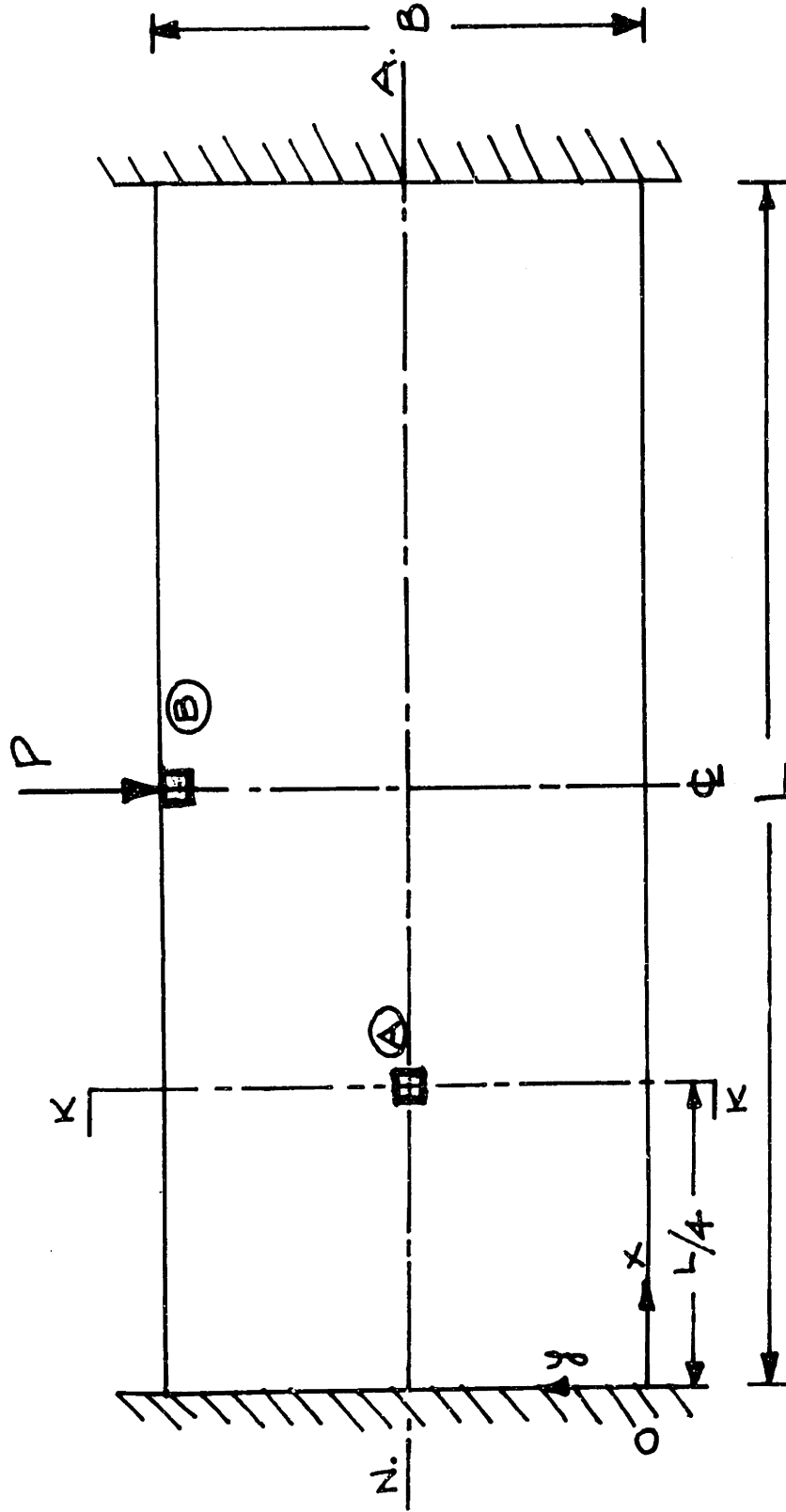


Figure III-1
A Centrally Loaded Plate

Consider the cross-section KK and question where would the best location or locations be to add reinforcing material in order to reduce the maximum shear stress $\tau_{\max.}$.

The shear stress τ_{xy} is given by

$$\tau_{\max.} = \frac{VQ}{It} \quad [3.1]$$

where

V is the shear force constant throughout the cross-section at $x = L/4$.

Q is the first moment of all the material above or below the N.A. and taken about the N.A.

I is the moment of inertia of the cross-section.

t is the thickness of the panel.

Since V is independent of the x cross-section of the panel it must be investigated how the other three variables would be arranged to minimize $\tau_{\max.}$.

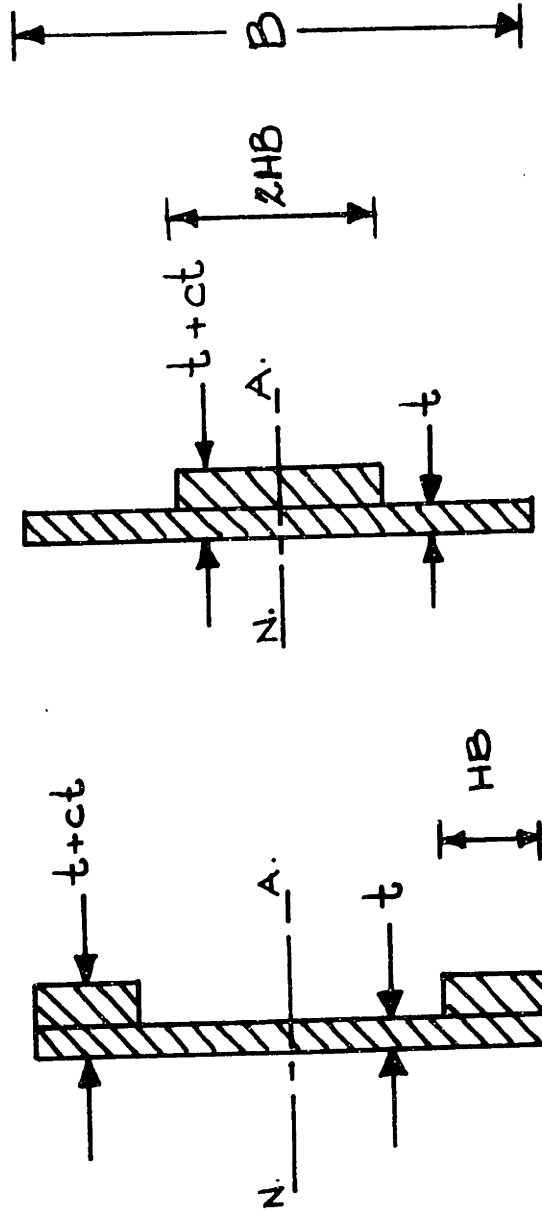
Let us consider the same cross-sectional material added as shown in Figure III-2 to two panels of the same thickness, t. The first moments, Q, of half the cross-sectional area about the N.A. for A and B are given by:

$$Q_A = \frac{B^2 t}{8} [1 + 4Hc(1 - H)] \quad [3.2.1]$$

$$Q_B = \frac{B^2 t}{8} (1 + 4H^2 c) \quad [3.2.2]$$

The moments of inertia, I, are:

$$I_A = \frac{B^3 t}{12} [1 + c + (1 - 2H)^3 c] \quad [3.3.1]$$



(A) (LATER D) (B) (LATER C)

Figure III-2

Comparison between Two Stiffener Arrangements (Case I)

$$I_B = \frac{B^3 t}{12} (1 + 8cH^3) \quad [3.3.2]$$

Therefore, the expressions for the maximum τ are

$$\tau_A = \frac{3}{2} \frac{V}{Bt} \frac{[1 + 4Hc(1 - H)]}{\{1 + c[1 - (1 - 2H)^3]\}} \quad [3.4.1]$$

$$\tau_B = \frac{3}{2} \frac{V}{Bt} \frac{(1 + 4cH^2)}{(1 + c)(1 + 8cH^3)} \quad [3.4.2]$$

To check the validity of equations [3.4.1] and [3.4.2] one can substitute for $c = 1$ and $H = 1/2$.

From equation [3.4.1]

$$\tau_A = \frac{3}{2} \left(\frac{V}{Bt} \right) \quad [3.5.1]$$

and from equation [3.4.2]

$$\tau_B = \frac{3}{4} \left(\frac{V}{Bt} \right) \quad [3.5.2]$$

The factor of two between equations [3.5.1] and [3.5.2] is due to the fact that adding material from the N.A. towards the edges of the panel the thickness of the panel is essentially doubled, while adding material from the edges towards the N.A., a cut is left.

Comparing τ_A and τ_B for $0 < c < \infty$ and $0 < H < 1/2$

$$\tau_A > \tau_B \quad [3.6]$$

Proof

Substituting from equations [3.4.1] and [3.4.2]

$$\frac{1 + 4Hc(1 - H)}{1 + c[1 - (1 - 2H)^3]} \stackrel{?}{>} \frac{1 + 4cH^2}{(1 + c)(1 + 8cH^3)}$$

Multiplying out and rearranging, one obtains

$$\begin{aligned} & c(-64H^5 + 80H^4 - 16H^3 - 4H^2 + 4H) \\ & + c^2(-32H^5 + 32H^4) \stackrel{?}{>} 2H - 4H^2 - 1 \end{aligned} \quad [3.6.1]$$

where the left-hand-side of the inequality is defined

$$\begin{aligned} g(H, c) &= c[-64H^5 + 64H^4 + 16H^3 - 4H^2 + 4H] \\ &+ c^2[32H^4(1 - H)] \end{aligned} \quad [3.6.2]$$

Since the second term of [3.6.2] will always be positive for the specified range of H , the first term is being examined.

Factoring out and rearranging

$$c[(64H^4 - 16H^3 + 4H)(1 - H)] \stackrel{?}{>} 0$$

where $c > 0$

$$(1 - H) > 0$$

Therefore,

$$4H(16H^3 - 4H^2 + 1) \stackrel{?}{>} 0$$

where $4H > 0$ and $4H^2(4H - 1) > -1$

where $4H^2 > 0$,

leaving $(4H - 1) \geq 0$ for $1/4 \leq H \leq 1/2$

and $(4H - 1) < 0$ for $0 < H < 1/4$

As H becomes smaller than $1/4$ and tends to 0 , $4H - 1$ will tend to -1 but it will never become -1 . In fact, multiplied with $4H^2$, its absolute value will become even smaller than unity but algebraically it will always be greater than -1 .

Therefore,

$$4H^2(4H - 1) > -1 \quad [3.6.3]$$

is satisfied for $0 < H \leq 1/2$ and implies that the first term of the left-hand-side of inequality [3.6.1] is always positive.

Examining the second side of inequality [3.6.1] one notices that it has a maximum at $H = 1/4$. That is, if

$$f(H) = 2H - 4H^2 - 1$$

$$f'(H) = 2 - 8H$$

and for $f'(H) = 0$, $H = 1/4$

where

$$f(1/4) = -3/4$$

See also Figure III-3 for a graphical proof by which it is shown that $g(H, c)$ does not cross $f(H)$ for any value of H within the specified range $0 < H \leq 1/2$ and for $c > 0$.

$$g'(H, c) = 4[c(-80H^4 + 80H^3 - 12H^2 - 2H + 1) + c^2(-40H^4 + 32H^3)]$$

As H goes to 0 and $c > 0$

$$\lim_{H \rightarrow 0} g'(H, c) \rightarrow 4c \quad [3.6.4]$$

which implies a positive slope there.

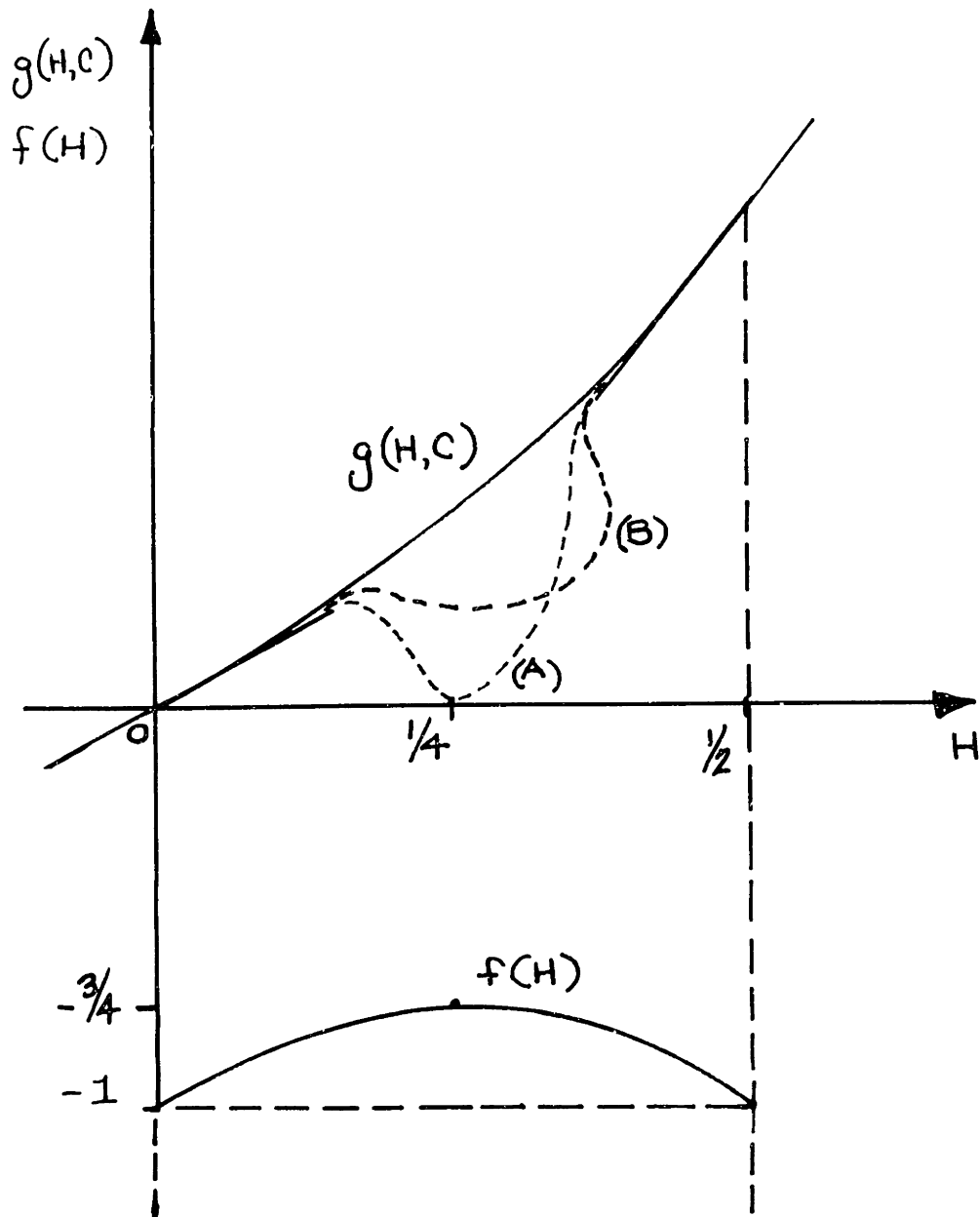


Figure III-3

A Graphical Proof That $g(H, c)$ and $f(H)$ of Inequality [3.6.1] have no common point.

At $H = 1/2$

$$g'(1/2, c) = 4(2c + 3/2c^2) \quad [3.6.5]$$

which implies a more positive slope than that at $H = 0$. Thus the slopes drawn in Figure III-3 are consistent with equations [3.6.4] and [3.6.5]. The dotted lines (A) and (B) between $H = 0$ and $H = 1/2$ show two possible deviations of $g(H, c)$ from its expected smooth course of direction. However, as shown before $g(H, c)$ will always be positive. Therefore, it never meets $f(H)$ at its maximum value at $H = 1/4$

Q.E.D.

Therefore, according to [3.6] it can be concluded that arrangement B will yield a lower value of τ .

The bending stress σ_x in element B of Figure III-1 will depend on I_A , and I_B , because

$$\sigma_x = \frac{M(B/2)}{I} \quad [3.7]$$

where M is the bending moment at $x = L/2$ which is constant throughout the cross-section there.

Comparing I_A with I_B one has

$$I_A > I_B \quad [3.7.1]$$

substituting for their values from equations [3.3.1] and [3.3.2] one obtains

$$-12H^2 + 6H > 0 \quad [3.7.2]$$

which is true for all values of H . When $H = 1/2$, the inequality yields

$$I_A = I_B \quad [3.7.3]$$

which implies that the correct relationship between I_A and I_B is

$$I_A > I_B \quad [3.8]$$

from equation [3.7] and [3.8] it is clear that

$$\sigma_B - \sigma_A \quad [3.9]$$

which indicates that arrangement (A) will decrease the maximum principal compressive value of σ_2 which depends only on σ_x (in element B in Figure III-1) more rapidly than arrangement (B).

3. A Comparison between Two Stiffener Arrangements--Case II

As a second possible arrangement of stiffeners for cross-section KK at $x = L/4$ and the center line cross-section, for the reduction of τ_{\max} in the former and σ_x in the latter, consider the arrangements (A) and (B) of Figure III-4.

Following the same procedure as for Case I, the first moments, Q , are calculated to be

$$Q_A = \frac{Bt}{8} [B + 4cH(B - ct)] \quad [3.10.1]$$

$$Q_B = \frac{B^2t}{8} (1 + 2H^2c) \quad [3.10.2]$$

and the moments of inertia I

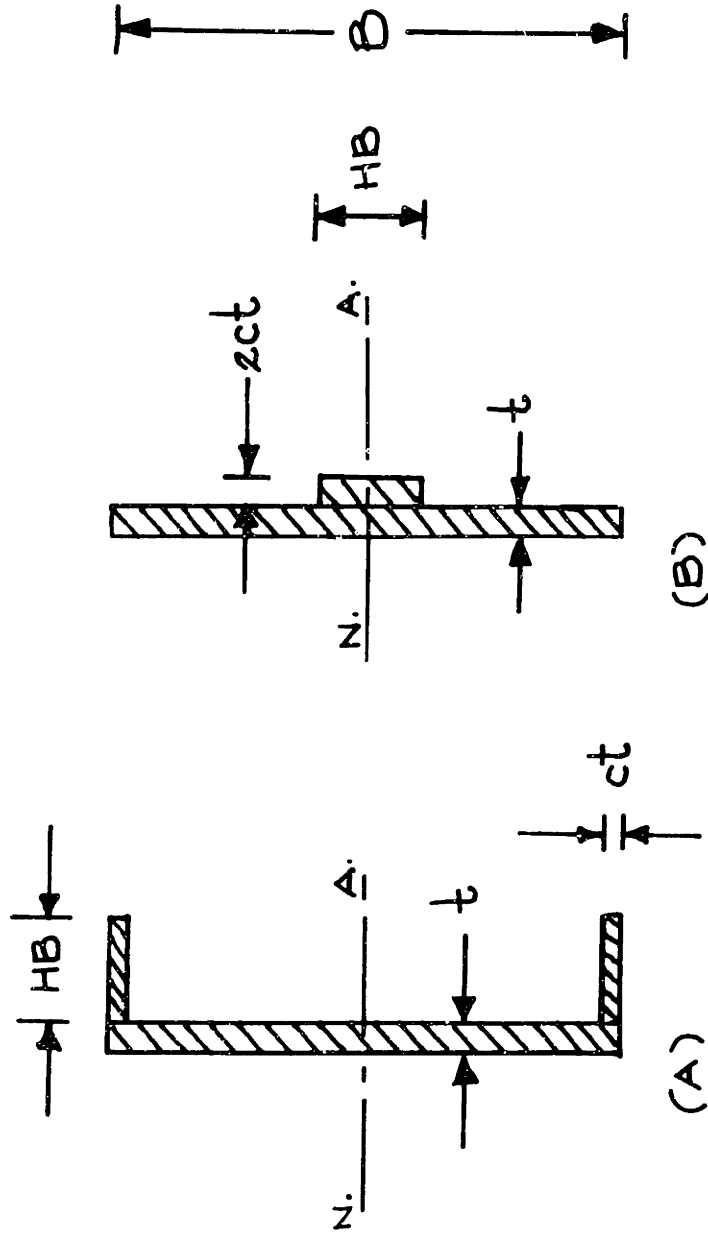


Figure III-4

Comparison between Two Stiffener Arrangements--Case II

$$I_A = \frac{B}{12} [tB^2 + HB^3 - H(B - 2ct)^3] \quad [3.11.1]$$

$$I_B = \frac{B^3 t}{12} (1 + 2cH^3) \quad [3.11.2]$$

From equations [3.10] and [3.11] and from the expression for τ , equation [3.1], one obtains

$$\tau_A = \frac{3}{2} \frac{V}{t^2} \frac{[\alpha + 4cH(\alpha - c)]}{\{\alpha^2 + \alpha^3 H [1 - [1 - 2c/\alpha]^3]\}} \quad [3.12.1]$$

and

$$\tau_B = \frac{3}{2} \frac{V}{t^2} \frac{(1 + 2H^2 c)}{\alpha(1 + 2cH^3)(1 + 2c)} \quad [3.12.2]$$

where $\alpha = B/t$.

To compare τ_A and τ_B , one must define reasonable ranges for c , H , and α .

According to the "Design Data for Tee Stiffeners" by the U. S. Navy Bureau of Ships,⁽¹⁹⁾ the following ranges of stiffener sizes have been used in the past:

$$10 \leq \alpha \leq 60 \quad [3.13.1]$$

$$10 \leq \frac{HB}{ct} \leq 30 \quad [3.13.2]$$

$$\text{where} \quad 0 < H \leq 1 \quad [3.13.3]$$

$$\text{and} \quad c = 1, 2, 3. \quad [3.13.4]$$

Non dimensionalizing τ_A and τ_B for a constant plate height B , one obtains (from equations [3.12]),

$$\bar{\tau}_A = \frac{\tau_A}{\frac{3}{2} \frac{V}{B^2}} = \frac{\alpha(1 + 4cH) - 4c^2H}{1 + H\alpha[1 - (1 - 2c/\alpha)^3]} \quad [3.14.1]$$

and

$$\bar{\tau}_B = \frac{\tau_B}{\frac{3}{2} \frac{V}{B^2}} = \frac{\alpha(1 + 2H^2c)}{(1 + 2cH^3)(1 + 2c)} \quad [3.14.2]$$

The most efficient way to compare $\bar{\tau}_A$ and $\bar{\tau}_B$ for the values of α , HB/ct , H , and c specified in the ranges of equations [3.13] is to write a small computer program. In doing so, it is more efficient if at the same time one compares $\bar{\tau}_A$ and $\bar{\tau}_B$ of Case II he also compares the shear stress τ_B of the best arrangement of Case I, which when non dimensionalized becomes

$$\bar{\tau}_C = \bar{\tau}_{B_I} = \frac{\alpha(1 + 4cH^2)}{(1 + c)(1 + 8cH^3)} \quad [3.14.3]$$

where $\bar{\tau}_{B_I}$ is the $\bar{\tau}_B$ of the first case and is renamed here for purposes of clarification. The results of comparison among $\bar{\tau}_A$, $\bar{\tau}_B$, $\bar{\tau}_C$ is shown in Figures III-5 through Figure III-10 for $\alpha = 10, 20, 30, 40, 50, 60$, $H = 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 1.0$, and $c = 1, 2, 3$.

From these it can be observed that

$$\bar{\tau}_B < \bar{\tau}_C < \bar{\tau}_A \quad [3.15]$$

for all c 's and for the same α and H . (see section 4)

From Case I arrangement (A) was proven to be more desirable than (B) for the center line cross-section. (see Figure III-1)

Presently, in Case II, due to the results of Case I, one may anticipate that arrangement A is the most appropriate because the material is added at the upper and lower edges of the plate where the maximum principal stresses exist. This anticipated result implies that $I_A > I_B$.

Therefore, substituting for I_A and I_B from equation [3.11] into the above inequality, simplifying,

$$tB^2 + HB^3 - H(B - 2ct)^3 > B^2t(1 + 2cH^3) \quad [3.16]$$

which by rearranging and substituting for $\alpha = B/t$ becomes

$$\alpha^2(3 - H^2) - 6\alpha c + 4c^2 > 0 \quad [3.16.1]$$

For $H = 1$, inequality [3.16.1] becomes

$$\alpha^2 - 3\alpha c + 2c^2 > 0 \quad [3.16.2]$$

or

$$(\alpha - 2c)(\alpha - c) > 0 \quad [3.16.3]$$

Since $10 \leq \alpha \leq 50$, for $\alpha = 10$, [3.16.3] yields

$$144 > 0 \text{ for } c = 1$$

$$96 > 0 \text{ for } c = 2$$

$$\text{and } 56 > 0 \text{ for } c = 3.$$

Clearly, for any other value of $H < 1$, the first term of the left-hand side will be more positive.

Therefore, it has been shown that $I_A > I_B$ is true for all values of α , H , and c that satisfy conditions [3.13]

from which

$$\sigma_A < \sigma_B \quad [3.17]$$

implying that arrangement (A) is better than (B) at the center line cross-section of the centrally loaded plate of Figure III-1.

To compare σ_A and σ_B of the present Case with the lowest σ_A of Case I, the small computer program which calculated $\bar{\tau}_A$, $\bar{\tau}_B$, and $\bar{\tau}_C$ is employed again, which gives the results of Figures III-11 through III-16 as discussed in the next section.

For the purpose of clarification, σ_A of Case I has been renamed σ_D , while σ_C is not being compared because $\sigma_C < \sigma_D$.

The expression for σ_A , σ_B , and σ_D are

$$\bar{\sigma}_A = \frac{A}{6M/B^3} = \frac{1}{1/\alpha + H[1 - (1 - 2c/\alpha)^3]} \quad [3.18.1]$$

$$\bar{\sigma}_B = \frac{B}{6M/B^3} = \frac{\alpha}{(1 + 2cH^3)} \quad [3.18.2]$$

$$\bar{\sigma}_D = \frac{D}{6M/B^3} = \frac{\alpha}{1 + c[1 - (1 - 2H)^3]} \quad [3.18.3]$$

4. Results from Comparing Arrangements A, B, and C

Figures III-5 and III-6 apply to a stiffener the thickness of which is equal to that of the plate (that is, $c = 1$). As the α ratio increases, the difference among

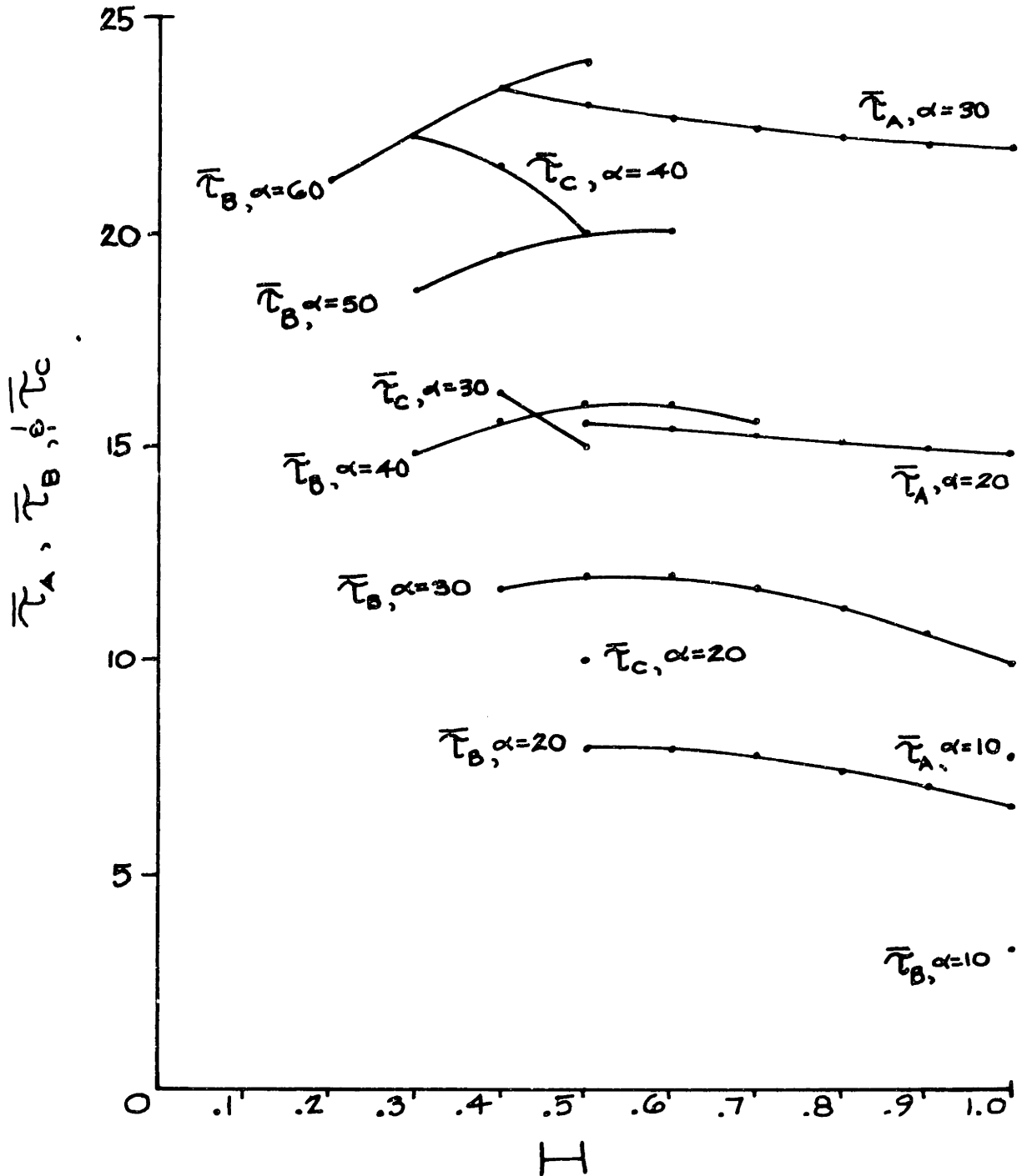
C=1

Figure III-5

C=1

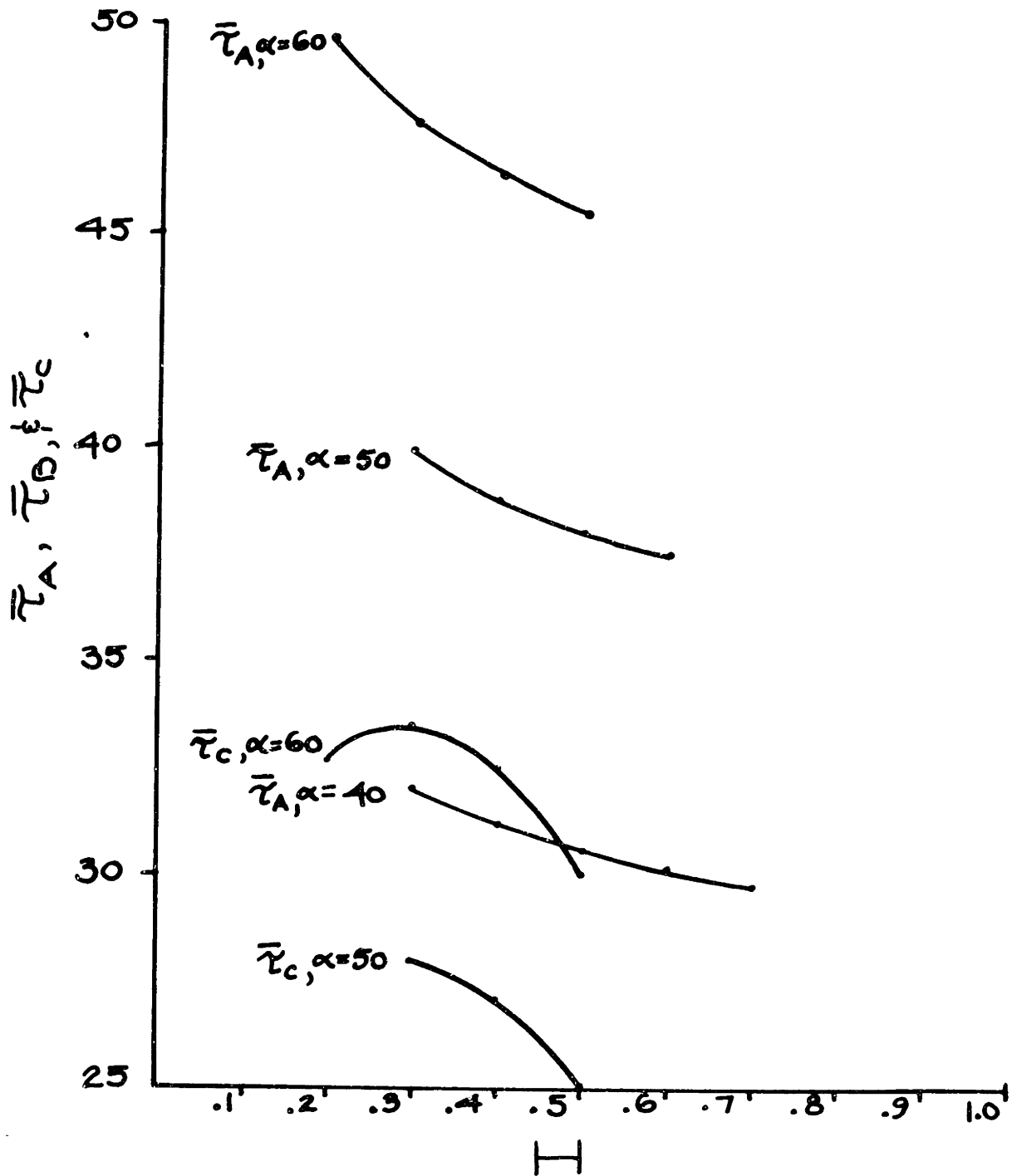


Figure III-6

$\bar{\tau}_A$, $\bar{\tau}_B$, and $\bar{\tau}_C$ increases, while at the same time, the acceptable values of H decrease.

This can be interpreted as follows: The ratio α is proportional to the initial weight of the plate so that if one compares $\bar{\tau}_A$, $\bar{\tau}_B$, and $\bar{\tau}_C$ for the same α and the same H , he compares the maximum nondimensional shear stresses (at the N.A. of the cross-section KK, Figure III-1) for three different stiffener arrangements of the same weight. Clearly, for any comparison among A, B, and C with a common α and H , the result is always that of the simultaneous inequalities [3.15]. Furthermore, one can see the variation of any $\bar{\tau}_A$, $\bar{\tau}_B$, and $\bar{\tau}_C$ with respect to H for each α .

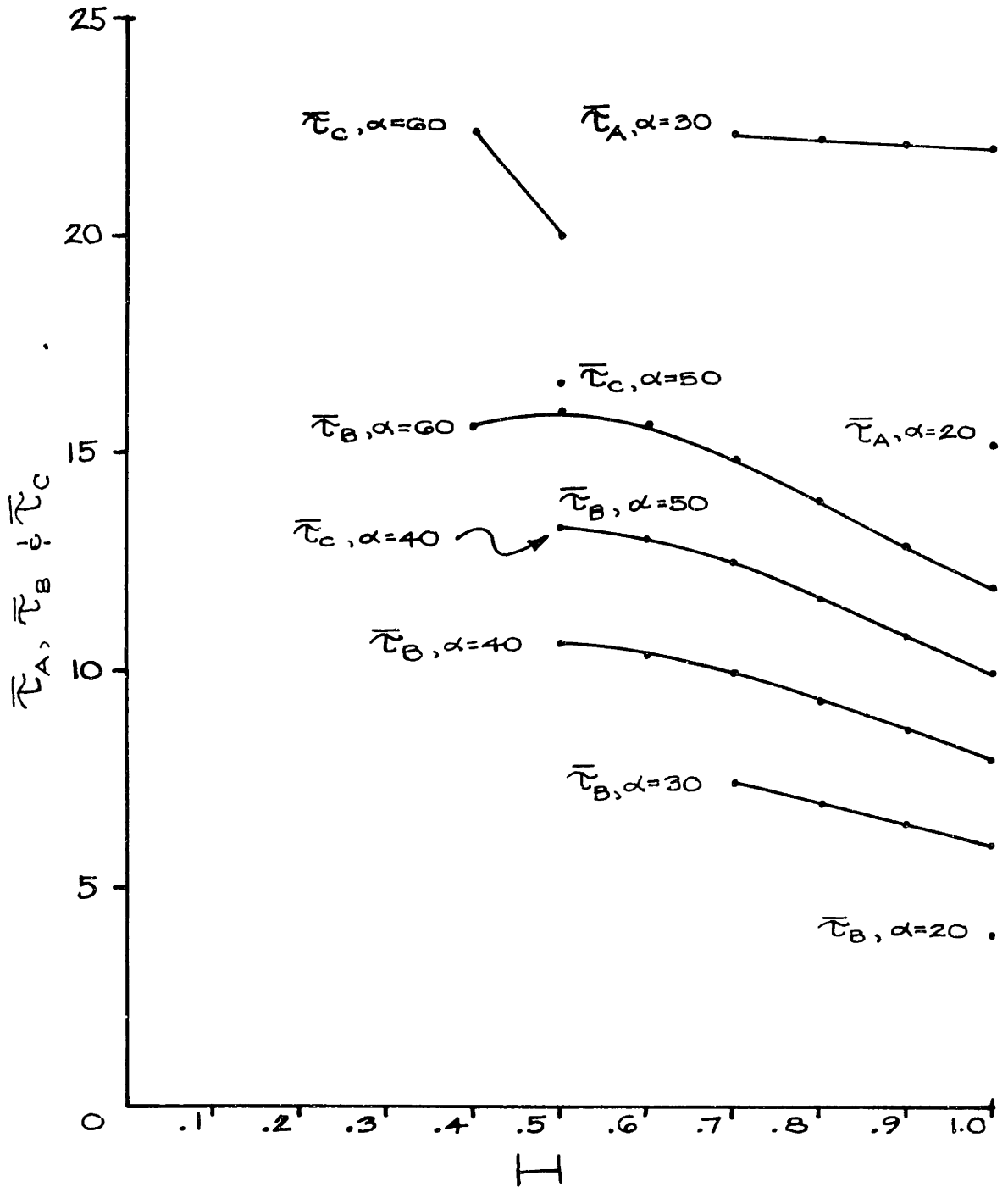
For the (A) arrangement, $\bar{\tau}_A$ drops with the increase of H , and the rate of dropping increases as α increases.

For the (B) arrangement and for high values of α ($\alpha = 60$, $\alpha = 50$), $\bar{\tau}_B$ increases as H increases, while for medium values of α ($\alpha = 40$, $\alpha = 30$), it exhibits a convex behavior with H increasing.

For the (C) arrangement (that is, arrangement B of Case I), $\bar{\tau}_C$ decreases with increasing H , except for $\alpha = 60$ where it exhibits convex behavior.

Figures III-7 and III-8 apply to the case where the thickness of the stiffener is double the thickness of the plate, (that is, $c = 2$). The values of $\bar{\tau}_A$, $\bar{\tau}_B$, and $\bar{\tau}_C$, for the same H , are far more spread apart than those obtained when $c = 1$.

C=2



NOTE:  ARROW INDICATES THAT ONE POINT OF τ_B COINCIDES WITH τ_C .

Figure III-7

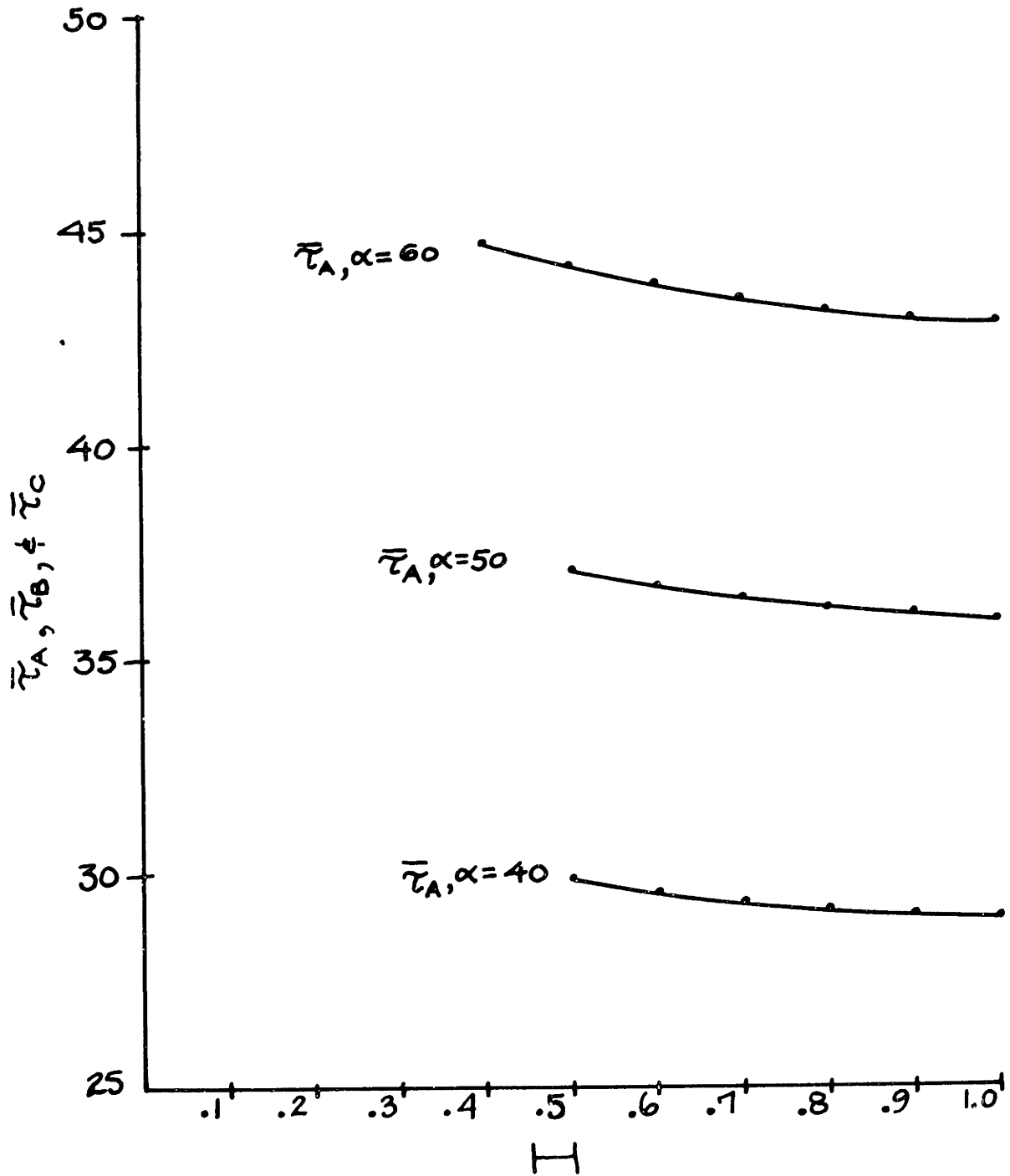
C=2

Figure III-8

In fact, $\bar{\tau}_A$ for $\alpha = 20$ and $H = 1$ equals $\bar{\tau}_B$ for $\alpha = 60$ and $H = 0.67$. This implies that the same stress level can be attained if one uses arrangement B for $\alpha = 60$, which is lighter than arrangement A for $\alpha = 20$ by a factor of 4.07.

Furthermore, from Figures III-7 and III-8 one notices that the condition of inequality [3.13.2] is not satisfied for small α . Notice that $\bar{\tau}_C$ exists only for $\alpha = 50, 60$ and that there are no $\alpha = 10$ ratios for $\bar{\tau}_A, \bar{\tau}_B$.

Aside from the above differences, the behavior of stress with respect to H for each arrangement and at a particular α is the same as that for $c = 1$.

Finally, from Figures III-9 and III-10, one observes an even greater discrepancy between $\bar{\tau}_A$ and $\bar{\tau}_B$ in favor of arrangement B. Arrangement C has only one value of $\bar{\tau}_C$ for $\alpha = 60$ and is the second most favorable.

Figures III-11 through III-16 show that for any H value and for the same α , for the same weight,

$$\sigma_A < \sigma_D < \sigma_B \quad [3.19]$$

It may be seen that for $c = 1, 2, 3$, $\bar{\sigma}_A, \bar{\sigma}_B$, and $\bar{\sigma}_D$ exhibit the same behavior as expected. However, as c increases, $\bar{\sigma}_A, \bar{\sigma}_B$, and $\bar{\sigma}_D$ come more closely together and towards $H = 1$, and smaller values of stress.

The behavior of the bending stresses $\bar{\sigma}_A, \bar{\sigma}_B$, and $\bar{\sigma}_D$ resembles that of the shear stresses $\bar{\tau}_A, \bar{\tau}_B$, and $\bar{\tau}_C$.

C=3

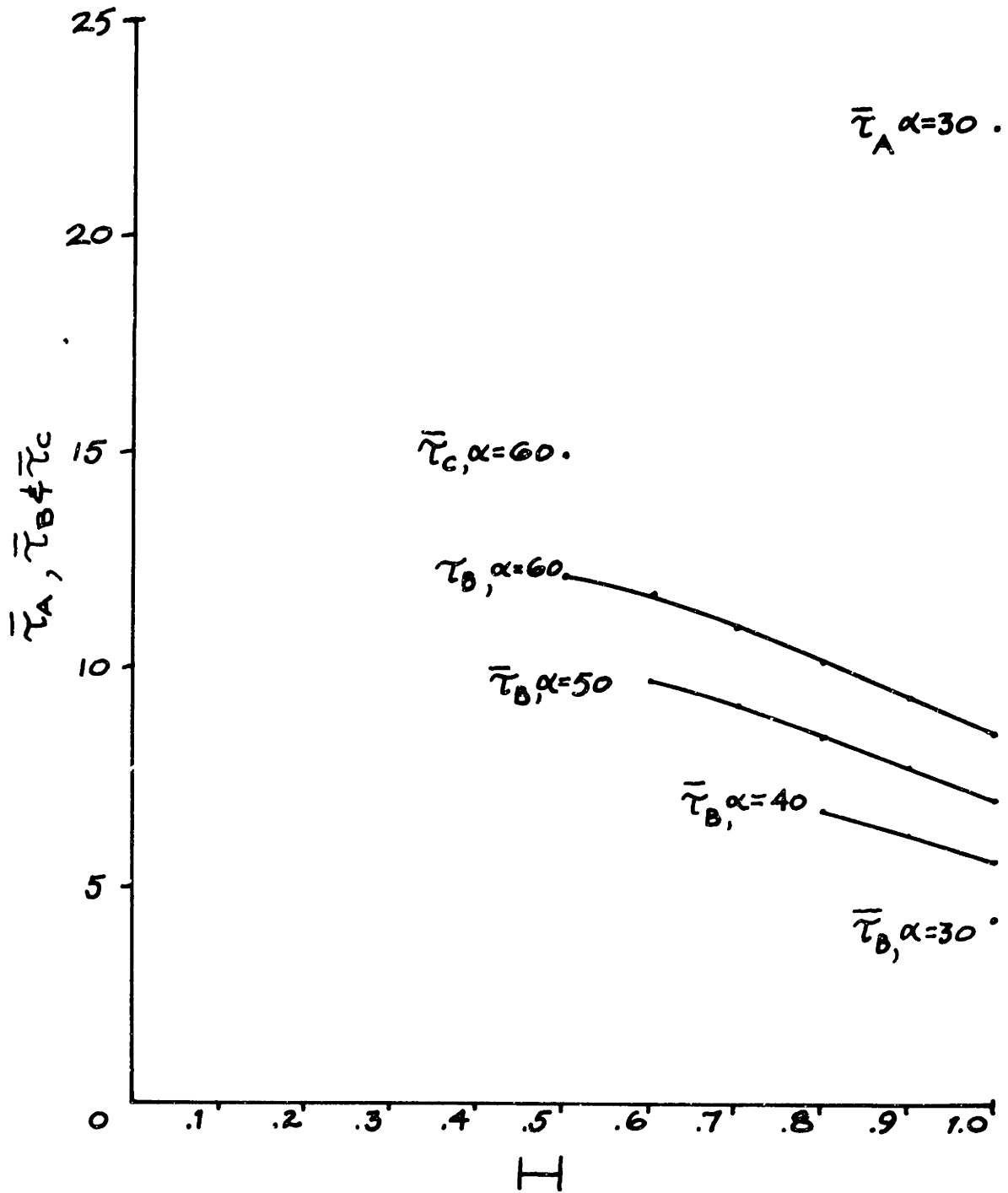


Figure III-9

C=3

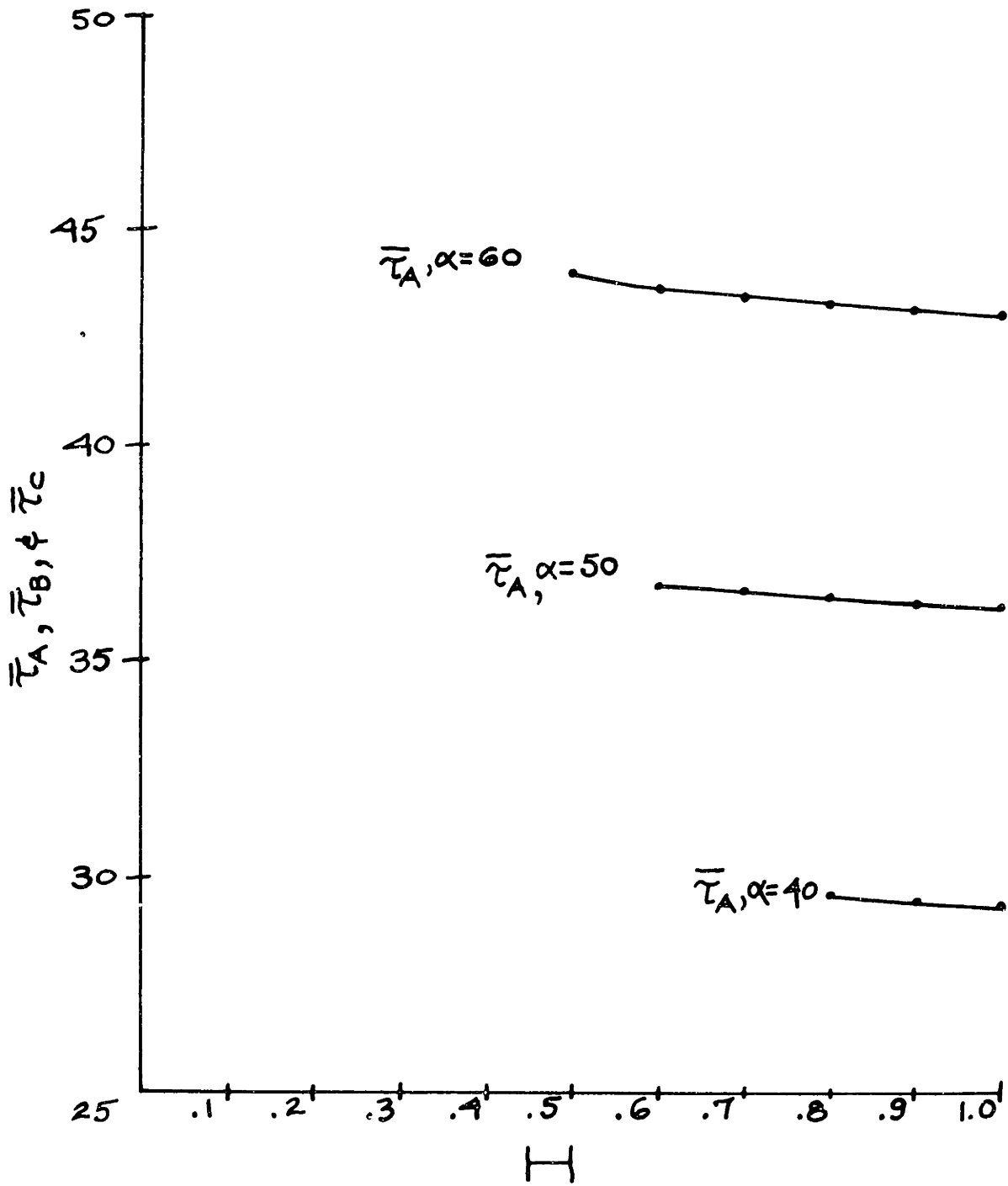


Figure III-10

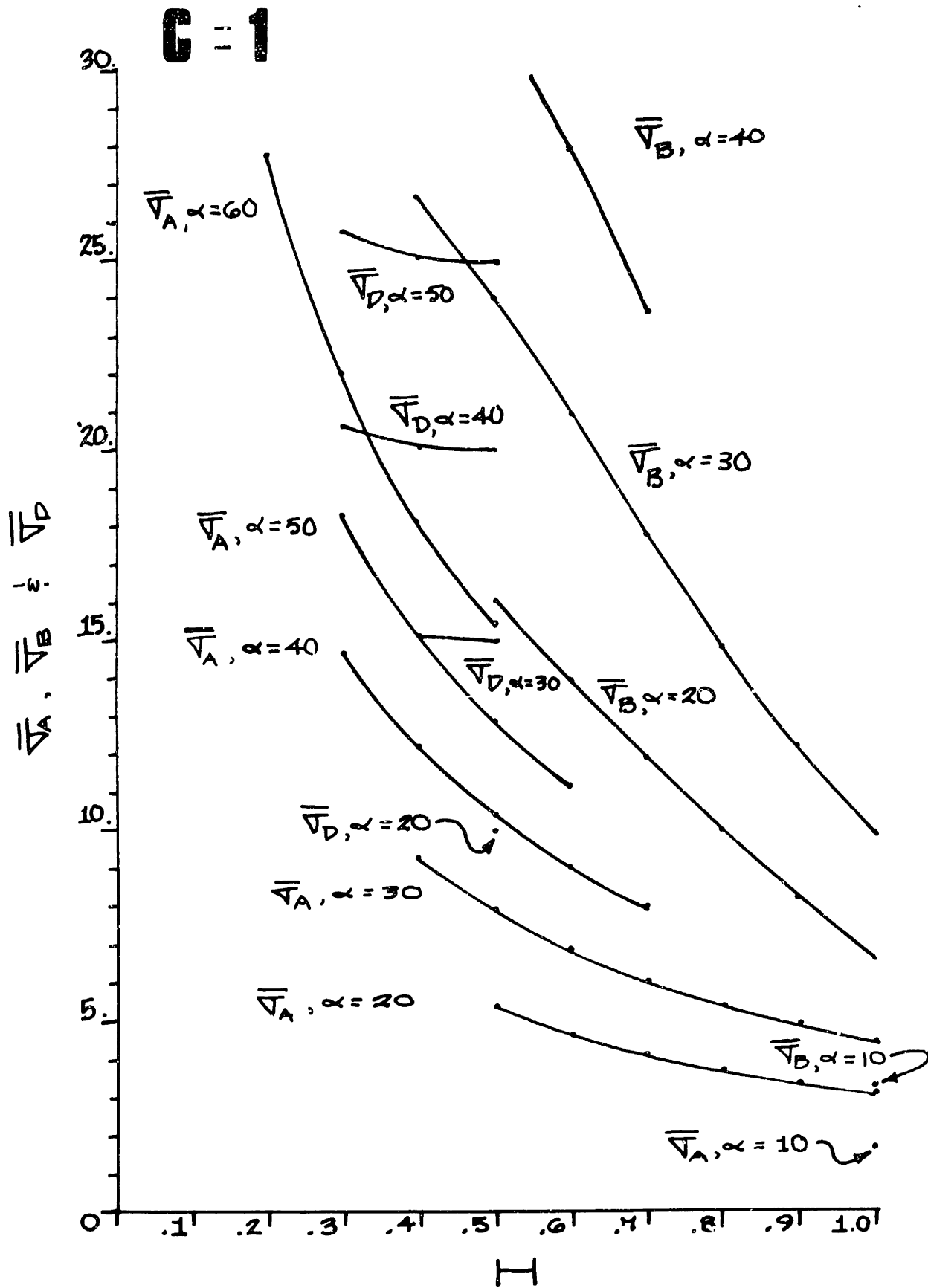


Figure III-11

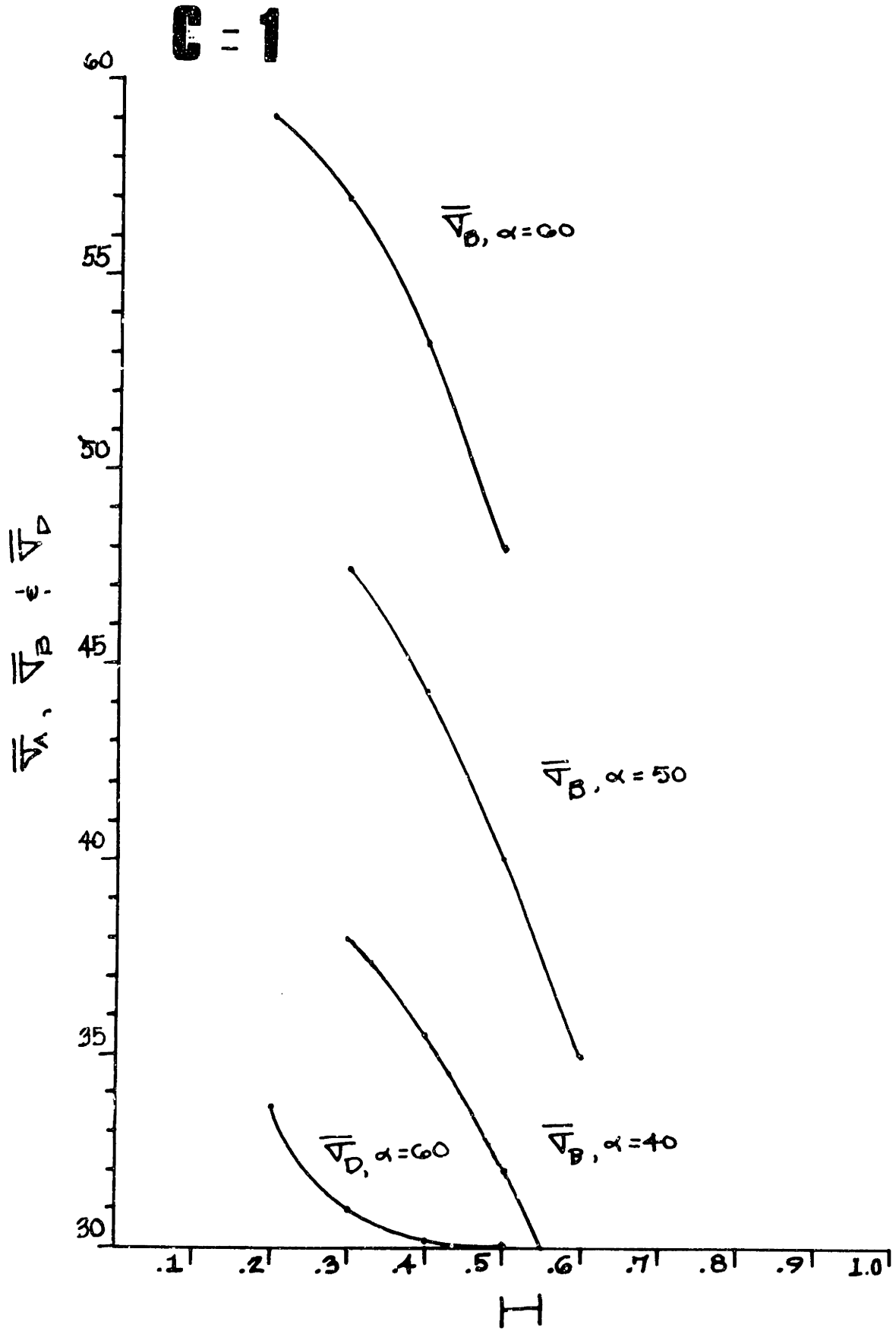


Figure III-12

C = 2

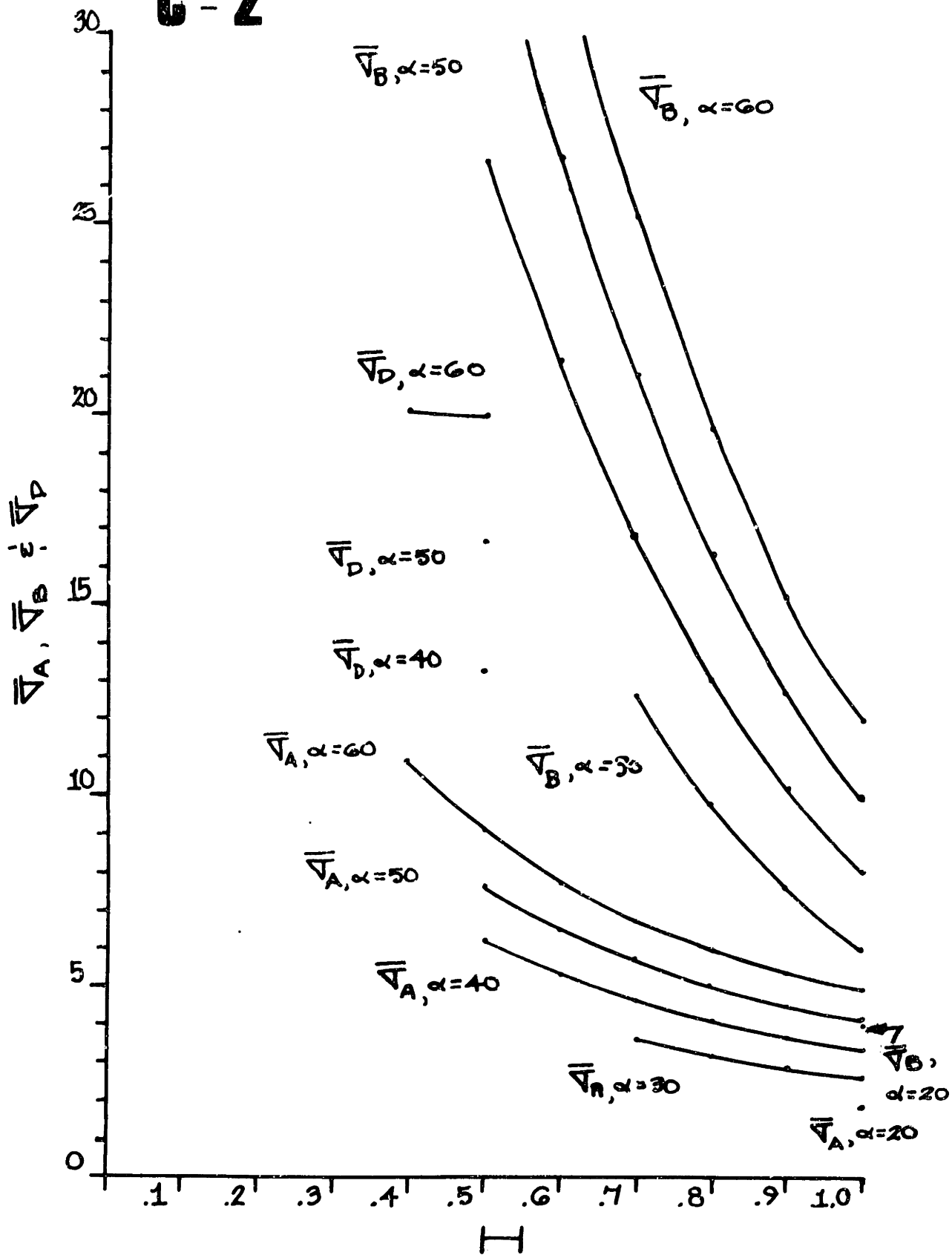


Figure III-13

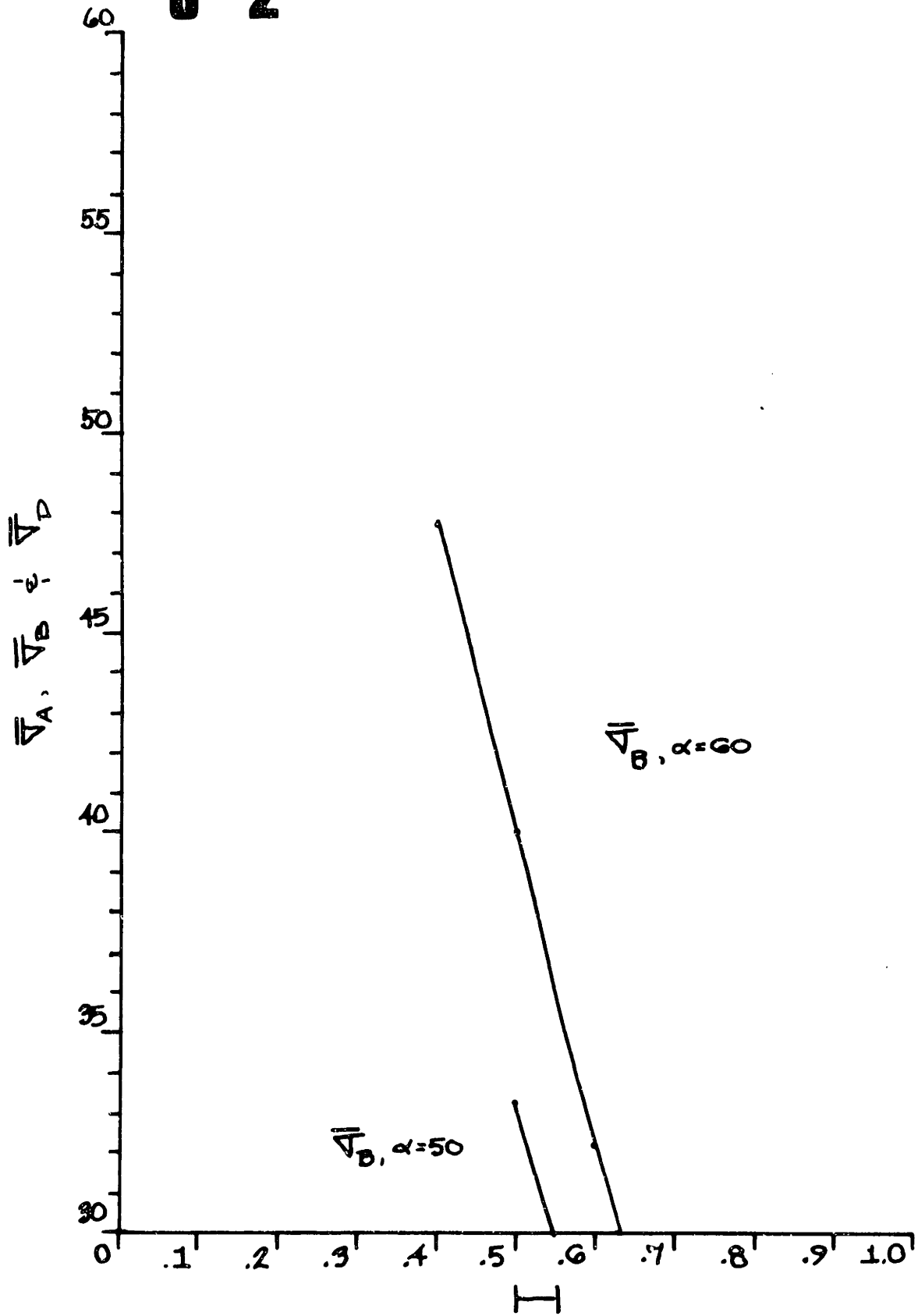
C = 2

Figure III-14

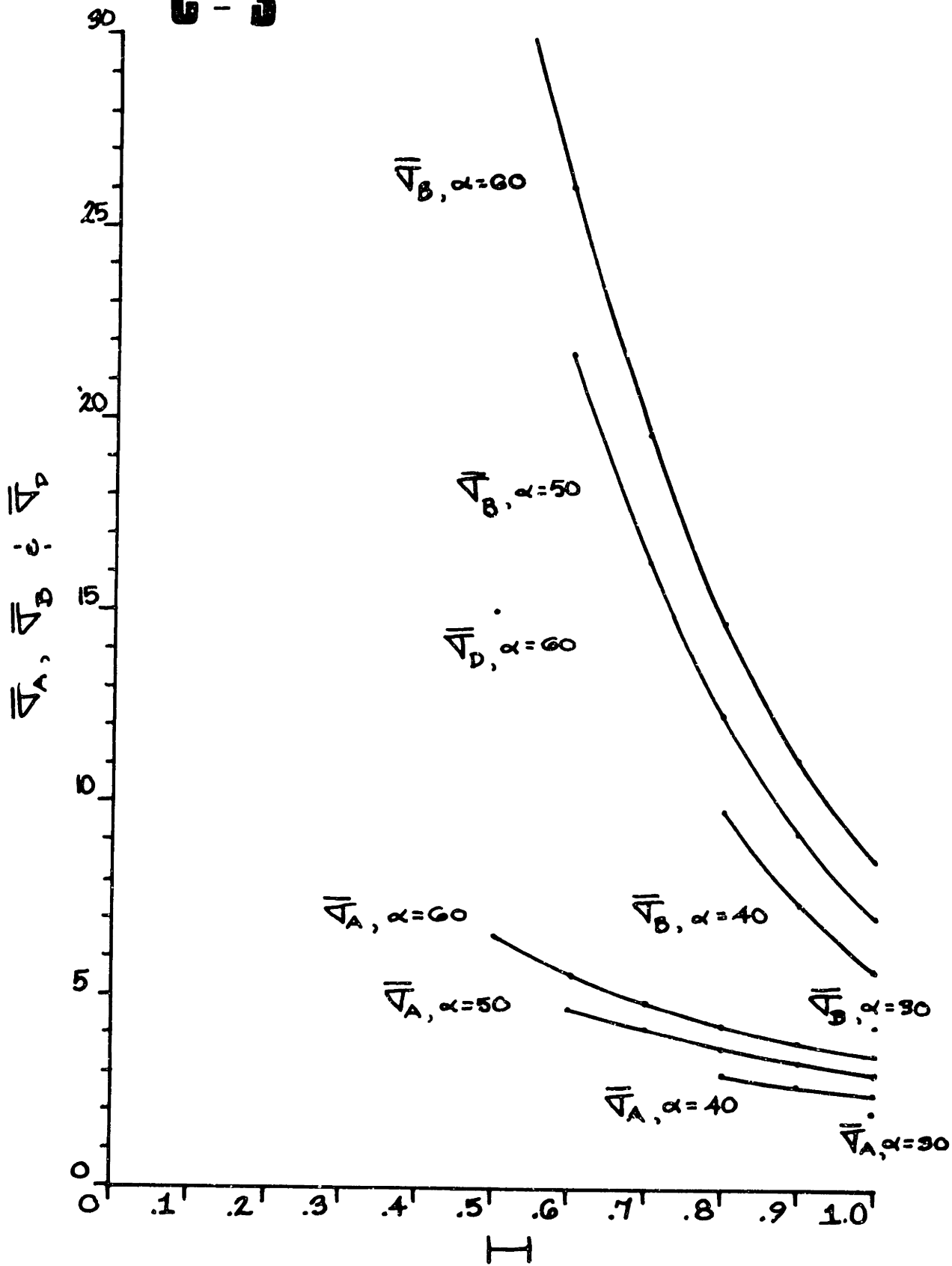
C = 3

Figure III-15

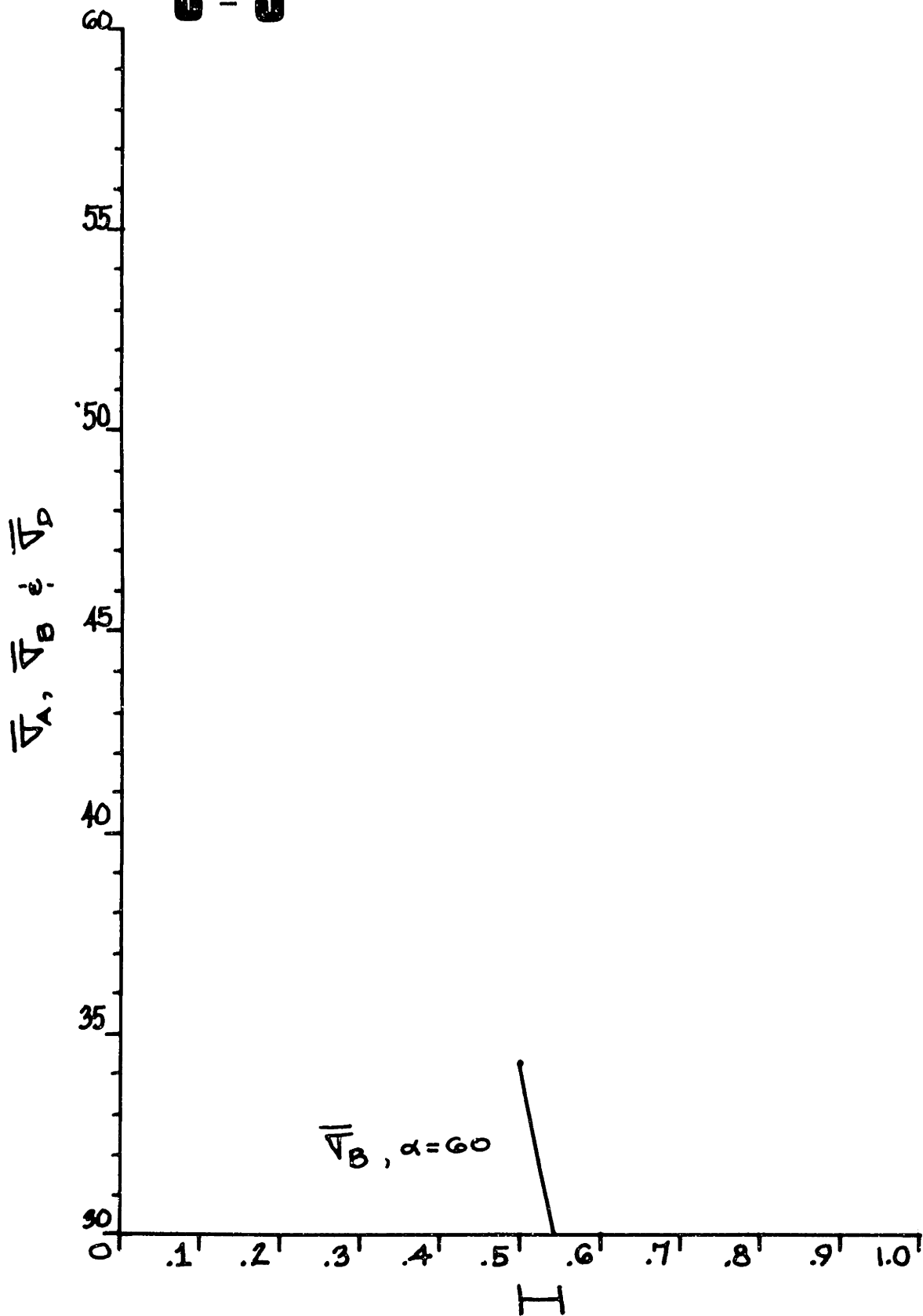
C = 3

Figure III-16

Notice that for a particular α , all the $\bar{\sigma}$'s decrease with increasing H .

To summarize, in this part four different stiffener arrangements have been compared in two's. For the best three arrangements, the expressions of the bending and shear stresses for a reasonable range of values of plate height over thickness, α , and flange width over flange thickness, HB/ct , where $0 < HB \leq B$ and $ct = t, 2t, 3t$ have been plotted against H , α , and c .

The results suggest that the maximum stress reduction for the least weight of reinforcing material is achieved when the stiffeners are added (a) vertical to the plate at the location of maximum principal compressive stress due to bending stress and (b) horizontal to the plate at the location of the maximum principal compressive stress due to shear stress.

Two more sets of curves are used in Part IV to explicitly show the behavior of all the shear stresses $\bar{\tau}_A$, $\bar{\tau}_B$, and $\bar{\tau}_C$ and the bending stresses $\bar{\sigma}_A$, $\bar{\sigma}_B$, and $\bar{\sigma}_D$ as a function of a nondimensionalized weight expression.

IV RESULTS

1. Energy Equivalent Boundary Loads

Example. Let us consider the centrally loaded plate of Figure IV-1 for which

$$t = 0.4 \text{ in.}$$

$$E = 30 \times 10^6 \text{ in.}$$

$$\nu = .25$$

Taking advantage of the existing symmetry of the load and of the boundary conditions, one needs to consider only half the plate to calculate (a) the displacements $\{q\}$, (b) the average stresses $\{\sigma\}_{\text{average}}^S$ and (c) the principal compressive stress trajectories.

Since the aspect ratio of the half plate is 2.5:1, "250" is an appropriate number of elements to be used for the modeling of the plate. These "250" elements correspond to "286" nodal points (or control stations), of which the four at the corners of the total structure as well as the two transversed by the horizontal N.A. of the plate on its vertical sides are shown in Figure IV-2.

Since the nodes for the entire structure have thus been properly numbered, the next step is to restrain nodes No. 1 through No. 11 and No. 276 through No. 286, in the x-direction due to symmetry, and node No. 6 in the y-direction, also. It must be mentioned that the restraining in the x-direction of all nodal points of the left and right-hand-sides of the

left half plate as shown in Figure IV-2 contradicts with the anticipated elongation of the plate along the x-axis. This anticipated elongation on the x-axis, however, can be neglected since the deflection in the y-direction will be infinitesimal (Infinitesimal Theory).

Having thus properly defined the boundary conditions of the problem, the next step is to simulate the parabolically distributed shear load equal to $P/2$, as shown in Figure IV-2.

Knowing that the total applied load on that edge will be 60 lbs., all one needs to do is to find the equation of the parabola as a function of the height of the plate.

For this purpose, define (a) the τ , y axes, as shown in Figure IV-3, and (b) the equation of the parabola in its general form,

$$\tau = ay^2 + by + c \quad [4.1]$$

for which,

$$(1) \text{ at } y = 0, \tau = 0 \text{ gives } c = 0 \quad [4.1.1]$$

$$(2) \text{ at } y = 144, \tau = 0 \text{ gives } b/a = -144 \quad [4.1.2]$$

Clearly, the area under the curve in Figure IV-3, the total force $F = P/2 = 60$ lbs.

Therefore,

$$F = t \int_{y_1=0}^{y_2=144} \tau dy$$

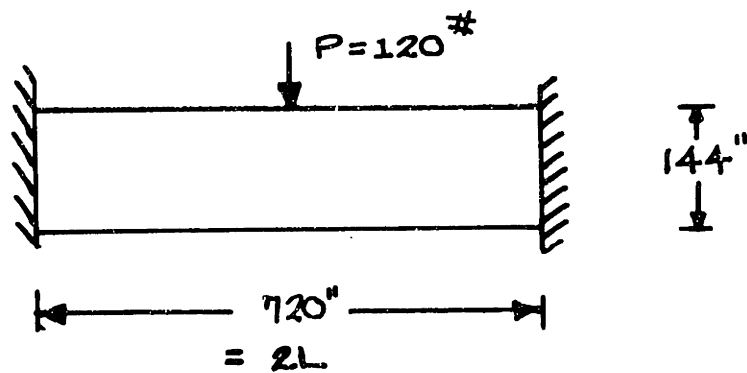


Figure IV-1
A Centrally-Loaded Plate

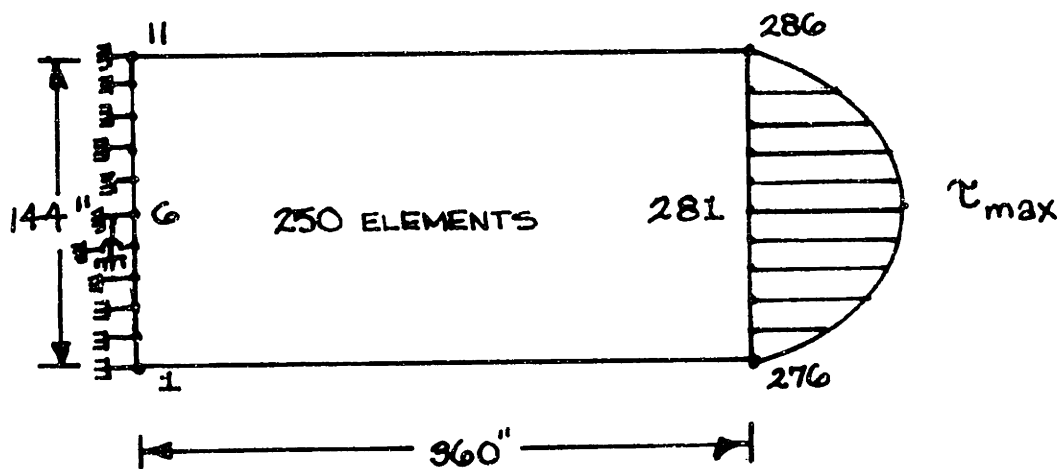


Figure IV-2
Modeling of the Left-Half Plate

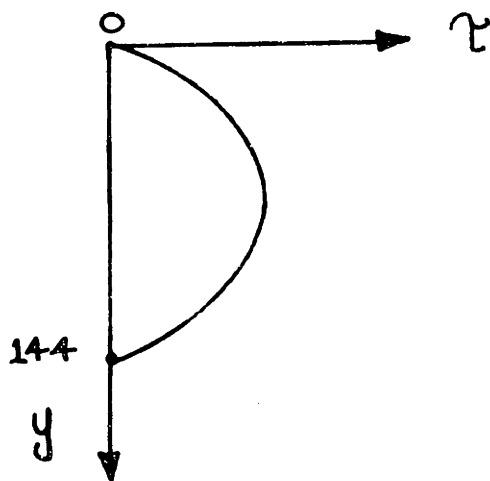


Figure IV-3
Set up of Origin for the τ vs y Distribution

or

$$\int_0^{144} (ay^2 + by)dy = \frac{60}{0.4} = 150 \text{ lbs/in} \quad [4.2.1]$$

Integrating, one gets:

$$\frac{ay^3}{3} + \frac{by^2}{2} \Big|_0^{144} = \frac{(144)^3 a}{6} = 150 \quad [4.2.2]$$

Therefore,

$$a = - \frac{900}{(144)^3} \quad [4.3.1]$$

and

$$b = -144a = \frac{900}{(144)^2} \quad [4.3.2]$$

Therefore equation [4.1] becomes

$$\tau = \frac{6P}{tB^2} \left[y \left(1 - \frac{y}{B} \right) \right] \quad [4.4]$$

Solving for the y values corresponding to the nodal points of the structure at the edge of interest, one obtains the shear stress τ values in lbs/in^2 , which are tabulated in Table IV-1.

Since, however, the computer program accepts the values of τ in units of (lbs/in), one must multiply column No. 3 by $t = 0.4$ in. to obtain the shear stress τ in column No. 4.

Note that the values of column No. 4 are read as described in Section 3 of Appendix II-A.

COLUMN # 1. 2. 3. 4.

NODE	y in.	τ #/in. ²	τ #/in.
286	0	0.0	0.0
285	14.4	-.5625	-.225
284	28.8	-1.0000	-.400
283	43.2	-1.3125	-.525
282	57.6	-1.5000	-.600
281	72.0	-1.5500	-.625
280	86.4	-1.5000	-.600
279	100.8	-1.3125	-.525
278	115.2	-1.0000	-.400
277	129.6	-.5625	-.225
276	144.0	0.0	0.0

TABLE IV - 1

The Computer Input Required Values, (Column 4), of the Shear Intensities per Node of Action and per y-Coordinate

That is,

$$\begin{array}{r}
 \text{TS (276, 2)} = 0.0 \\
 \text{TS (277, 2)} = -0.225 \\
 \text{TS (278, 2)} = -0.400 \\
 \text{' } \quad \quad \quad \text{' } \\
 \text{' } \quad \quad \quad \text{' } \\
 \text{' } \quad \quad \quad \text{' } \\
 \cdot \text{ TS (285, 2)} = -0.225 \\
 \text{TS (286, 2)} = 0.0
 \end{array}
 \quad \left. \vphantom{\begin{array}{r} \text{TS (276, 2)} \\ \text{TS (277, 2)} \\ \text{TS (278, 2)} \\ \text{' } \\ \text{' } \\ \text{' } \\ \text{TS (285, 2)} \\ \text{TS (286, 2)} \end{array}} \right\} [4.5]$$

where the first dimension for every TS is the node number at which the shear intensity acts; the second dimension is defined to be 1, if the intensity acts on a horizontal side, or 2 when the shear intensity acts on a vertical side, as is the case here.

The energy equivalent nodal forces Q are obtained by using equations [2.27] as shown in Table IV-2. As noticed, nodes 282 and 280 accept the same loads due to symmetry.

The total load obtained from the above calculated energy equivalent loads is:

$$\begin{aligned}
 F_T &= 2[(-54) + (-3.12) + (-5.64) + (-7.44) \\
 &\quad + (-8.52) + (8.88)] = 60.24 \qquad [4.6]
 \end{aligned}$$

which deviates by 0.4%, from F of equation [4.2], and which is to be expected since the integration according to the computer program is approximated by straight line segments.

line	250	$Q_1 = -(\frac{0}{3} + \frac{.225}{6})(14.4)$	$= -5A$	
	285	$Q_2 = -(\frac{0}{6} + \frac{.225}{3})(14.4)$	$=$	$= -3.12$
	259	$Q_1 = -(\frac{.225}{3} + \frac{.400}{6})(14.4)$	$=$	
	284	$Q_2 = -(\frac{.225}{6} + \frac{.400}{3})(14.4)$	$=$	$= -5.64$
	258	$Q_1 = -(\frac{.400}{3} + \frac{.525}{6})(14.4)$	$=$	
	283	$Q_2 = -(\frac{.400}{6} + \frac{.525}{3})(14.4)$	$=$	$= -7.44$
	257	$Q_1 = -(\frac{.525}{3} + \frac{.600}{6})(14.4)$	$=$	
	282	$Q_2 = -(\frac{.525}{6} + \frac{.600}{3})(14.4)$	$=$	$= -8.52$
	256	$Q_1 = -(\frac{.600}{3} + \frac{.625}{6})(14.4)$	$=$	
	281	$Q_2 = -(\frac{.600}{6} + \frac{.625}{3})(14.4)$	$=$	$= -8.88$
	255	$Q_1 = -(\frac{.625}{3} + \frac{.600}{6})(14.4)$	$=$	
	280	$Q_2 = -(\frac{.625}{6} + \frac{.600}{3})(14.4)$	$=$	$= -8.52$
	254	$Q_1 = -(\frac{.600}{3} + \frac{.525}{6})(14.4)$	$=$	\cdot
	279	$Q_2 = -(\frac{.600}{6} + \frac{.525}{3})(14.4)$	$=$	\cdot
	\cdot	\cdot	\cdot	\cdot
	\cdot	\cdot	\cdot	\cdot
	\cdot	\cdot	\cdot	\cdot

TABLE IX - 2

The Analytical Calculations to Obtain the Energy Equivalent Nodal Forces of the Example of Figure IV-2

Notice that the above energy equivalent loads tabulated in Table IV-2 are identical to those obtained for the cantilever printout (see end of Appendix II-B) where exactly the same parabolic distribution is used on the free edge of the cantilever.

Also, notice the similarity between the approximately estimated discrete nodal forces and the computed energy equivalent nodal forces in Appendix II-B.

2. Nodal Displacements

Example 1. The boundary conditions imposed on the left half plate of Figure IV are compatible with those boundary conditions required to simulate Kirchoff's Simple Beam Theory which does not include the effects of the transverse shear deformation.

According to the Theory, in order to obtain the total deflection, δ_T , at half the length of the plate, $L = 360$ in. from the wall, for the centrally loaded plate, one has to apply superposition. That is,

$$\delta_T = \delta_{P_0} - \delta_{M_0} \quad [4.7]$$

where δ_{P_0} is the deflection due to the pointing downwards load P_0 , and δ_{M_0} is the upwards deflection due to the existing moment at L (see Figure IV-1).

Substituting in the well-known general expressions for the deflections, equation [4.7] becomes

$$\delta_T = \frac{P_0 L^3}{3EI} - \frac{P_0 L^3}{4EI} = \frac{P_0 L^3}{12EI} \quad [4.8]$$

Therefore, substituting for

$$P_0 = 60 \text{ lbs}$$

$$L = 360 \text{ in}$$

$$E = 30 \times 10^6 \text{ psi}$$

$$I = 0.4 \times 12^5 \text{ in}^4$$

in equation [4.8] one obtains

$$\delta_T = 78.1 \times 10^{-6} \text{ in} \quad [4.9]$$

For the centrally loaded case, the computer program gives the displacements of each node along the edge of the plate at the midspan, to be as described in column 1 of Table IV-3.

The average displacement of these center line nodal displacements is -118.7×10^{-6} in. which of course is way off from the predicted value calculated from the Simple Beam Theory.

However, for an aspect ratio of 5:1 (overall aspect ratio for the present plate), the shear deformation is considerably significant. Therefore, one must calculate the deflection due to the shear deformation and add it to the δ_T obtained from Kirchoff's Simple Beam Theory to obtain the true total deflection which we want to compare with the results of the computer program.

Accordingly, from Timoshenko's Theory of Elasticity⁽¹⁶⁾ the deflection of a cantilever beam due to shear is

COLUMN 1		COLUMN 2	
NODE NUMBER	DISPLACEMENTS $\times 10^{-6}$	NODE NUMBER	DISPLACEMENTS $\times 10^{-6}$
286	-116.9	11	205.4
285	-118.0	10	205.6
284	-118.9	9	205.7
283	-119.5	8	206.0
282	-119.9	7	206.2
281	-120.1	6	206.3
280	-119.9	5	206.4
279	-119.5	4	206.4
278	-118.9	3	206.4
277	-118.0	2	206.4
276	-116.0	1	206.4

TABLE IV - 3

Results Obtained for Examples No. 1 and No. 3

$$\delta_{s_{\text{cantilever}}} = \frac{3P}{4cG} (\ell - x) \quad [4.10]$$

where

P is the applied load at the free end of the beam

c is half the width

ℓ is the length as shown in Figure IV-4

and G is $E/2(1 + \nu)$

If we imagine the half centrally-loaded plate as two cantilever beams together as shown in Figure IV-5, the total deflection for the centrally-loaded plate at its center line would be

$$\delta_{s_{\text{C.L.P.}}} = 2\delta_{s_{\text{cantilever}}} = 2 \frac{3(P/2)}{4cG} (L/2) \quad [4.11]$$

where

$$P = 120 \text{ lbs.}$$

$$c = 72 \text{ in}$$

$$L = 360$$

$$\nu = .25$$

Therefore, substitution of these values in [4.11] would yield

$$\delta_{s_{\text{C.L.P.}}} = 18.750 \times 10^{-6} \quad [4.12]$$

However, since Timoshenko's formula has been derived for unity thickness one must divide δ_s of [4.12] by $t = 0.4$ which is the thickness of our plate.

Therefore,

$$\delta_s = 1/t \delta_{s_{C.L.P.}} = 46.875 \times 10^{-6} \quad [4.13]$$

Adding the above deformation due to the effect of shear to the deformation calculated from the Simple Beam Theory,

$$\begin{aligned} \delta_{\text{overall}} &= \delta_T + \delta_s \quad [4.14] \\ &= 78.1 \times 10^{-6} + 46.875 \times 10^{-6} \\ &= 124.975 \times 10^{-6} \end{aligned}$$

which when compared with the average displacement of the center line nodal displacements gives an error of 5.2% which is acceptable.

Example 2. Let us compare the displacement results as obtained for the cantilever case. The average displacement (in the y-direction) of nodes 276 through 286 (see Appendix II-B, results listed under MAIN0320 through MAIN0334) which is $\delta = -353.6 \times 10^{-6}$ with the analytical result from

$$(v)_{y=0} = \frac{Px^3}{6EI} - \frac{Pl^2x}{2EI} + \frac{Pl^3}{3EI} + \frac{Pc^2}{2IG} (l - x) \quad [4.15]$$

which is the general expression for the vertical deflections applied to Figure IV-4. (16)

Substitution for $x = 0$ gives

$$(v)_{y=0} = \frac{Pl}{I} \left[\frac{l^2}{3E} + \frac{c^2}{2G} \right] \quad [4.15.1]$$

Substituting for the known quantities ($t = 0.4$ in., $v = 0.25$, $c = 72$ in., $l = 360$ in., $E = 30 \times 10^6$ psi, $P = 60$ lbs.), we

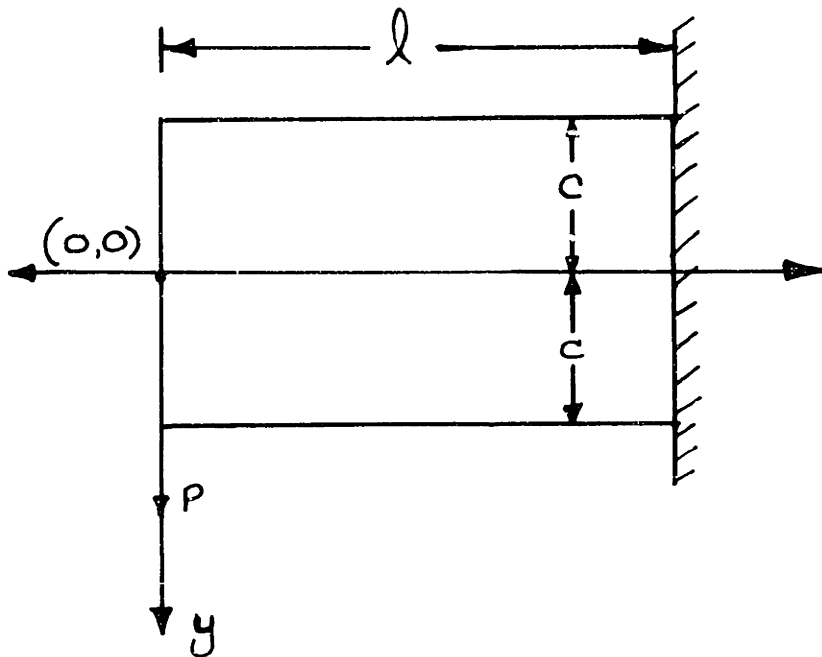


Figure IV-4

A Cantilever Plate Loaded at Its Free End
with a Concentrated Load, P

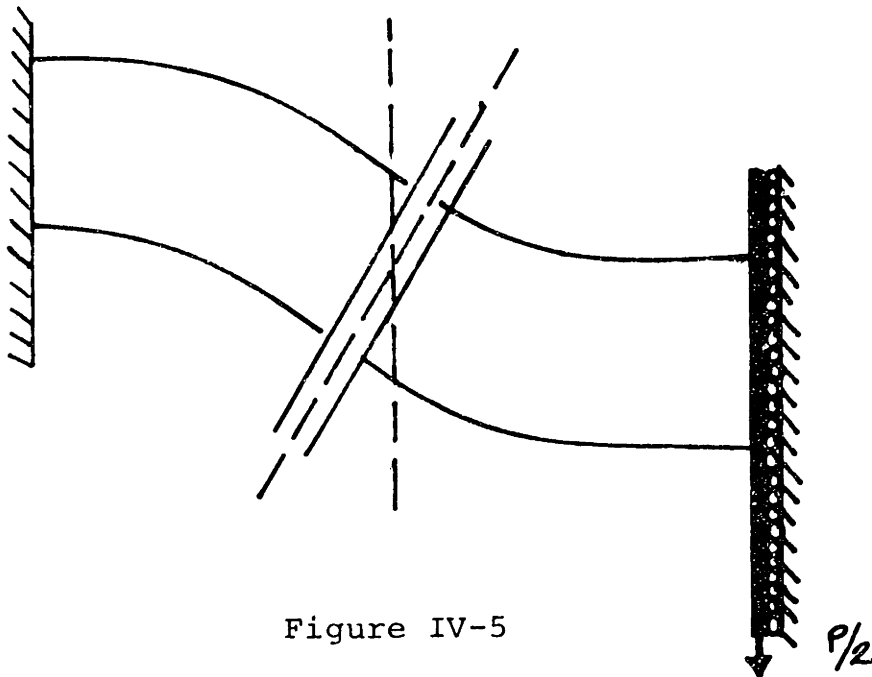


Figure IV-5

The Left Half of a Centrally Loaded
Plate

obtain

$$(v)_{y=0} = 359.3 \times 10^{-6} \quad [4.15.2]$$

Therefore, the average nodal displacement at the free edge of the cantilever case as obtained by the computer program compared with the analytic solution's result gives only a 1.6% error!

• Example 3. Consider the self-equilibrated plate of Figure IV-6.

The deflection at the center line is given by:

$$\delta = \frac{5}{24} \frac{q l^4}{EI} \left[1 + \frac{12}{5} \frac{c^2}{l^2} \left(\frac{4}{5} + \frac{\nu}{2} \right) \right] \quad (16) \quad [4.16]$$

For

$$q = 0.1667 \text{ lbs/in}$$

$$l = 360 \text{ in}$$

$$c = 72 \text{ in}$$

$$\nu = 0.25$$

$$E = 30 \times 10^6 \text{ psi}$$

$$\delta = 212.5 \times 10^{-6} \text{ in.} \quad [4.17]$$

The nodal displacement values obtained from the computer run for this case are tabulated in the second column of Table IV-3, for which the average value is $\delta = 206.12 \times 10^{-6}$ in. The difference between the two values gives a 3% error.

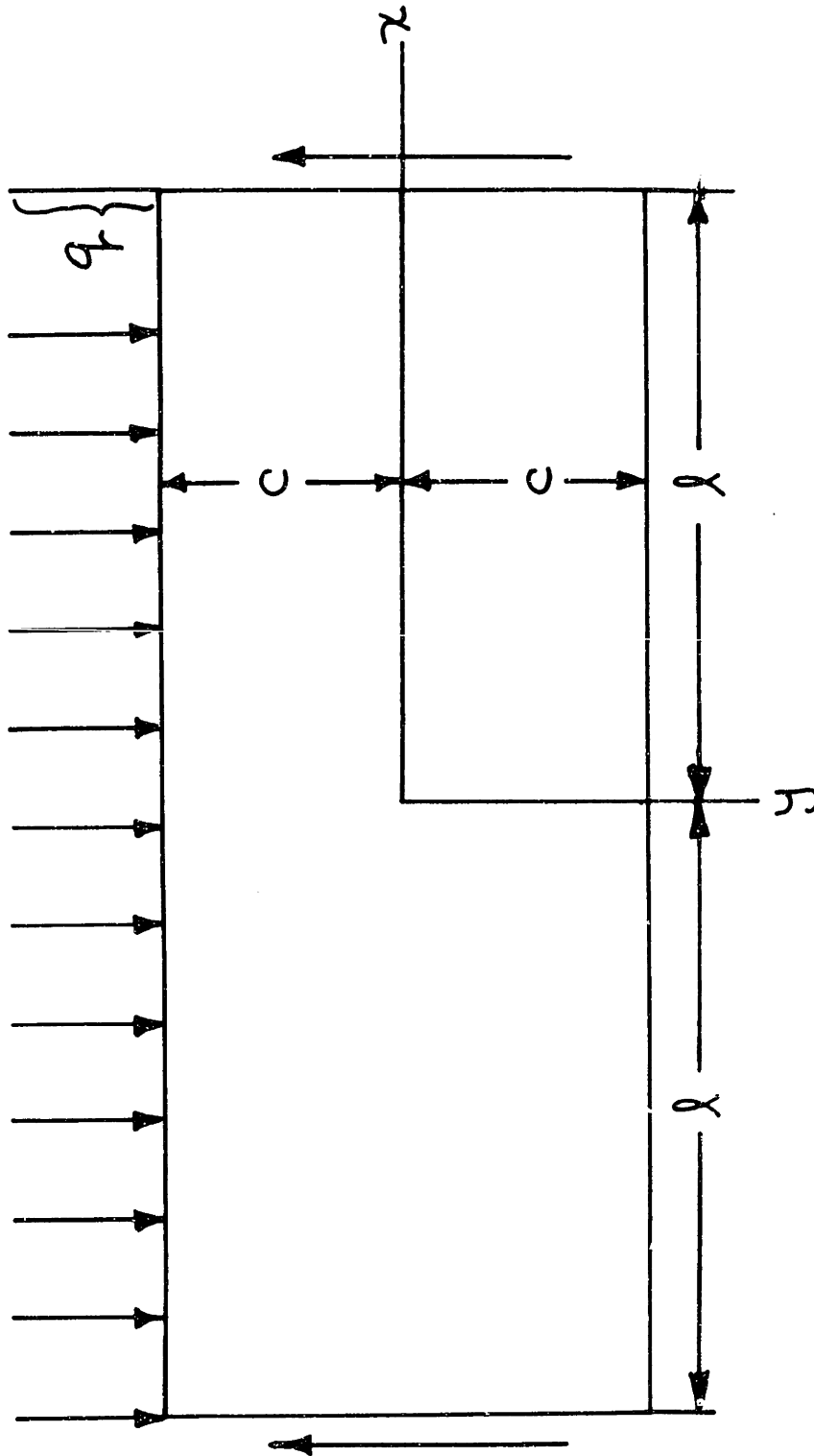


Figure IV-6
 A Uniformly Loaded and Self-Equilibrating Plate
 with Shear Reactions at its Free Ends

From the above discussion the conclusion is that the computer program gives excellent results for the calculated nodal displacements.

It should be noted that the percentage error between the analytic results and the computed results is an overall error in which the modeling error is included (that is, when simulating Simple Beam Theory, one should be careful of which nodes to restrain, etc.).

Now, that it has been shown that the nodal displacements are in agreement with the theoretically predicted results, we may expect that the average nodal stresses are also agreeable to the theoretical expected results.

3. Average Nodal Stresses

The results for the σ_x bending stress obtained from example one of the previous section have been plotted in Figure IV-7. These results reveal that the overall behavior of the bending stress σ_x is in agreement with that expected from the Simple Beam Theory.

The small discrepancy between the maximum σ_x at the center line and the σ_x at the wall is indicative of the boundary effects. That is, the small percentage error associated with the displacements is also reflected in the stress results as it should be expected.

Aside from the fact that there is a slight assymetry about the quarter length axis of the plate, all the σ_x values

E = 30×10^6 PSI
 $\nu = .25$
 LOADS: 60 LB. PARABOLICALLY DISTRIBUTED
 ON THE ϕ EDGE.
 TOTAL NUMBER OF ELEMENTS: (10X25)

THICKNESS OF PLATE = .4 IN.
 BOUNDARY CONDITIONS: NODES 1-11, 276-286 RESTRAINED IN X
 NODE 0 RESTRAINED IN Y

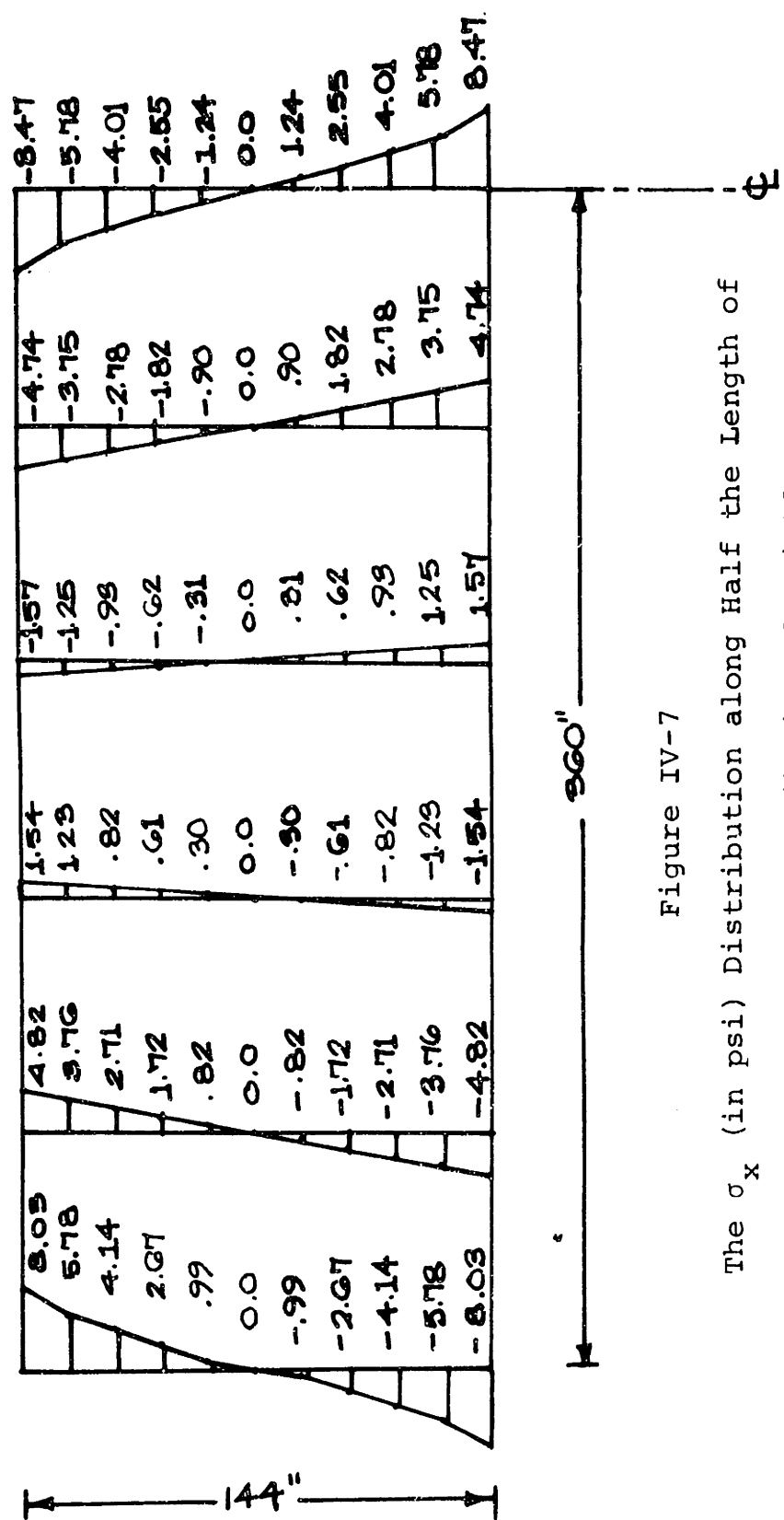


Figure IV-7
 The σ_x (in psi) Distribution along Half the Length of
 a Centrally Loaded (in its Plane) Plate

are completely symmetrical about the horizontal N.A. as it is expected from Beam Theory.

The σ_x results for the cantilever case are shown in Figure IV-8. The stress decreases with x increasing; starting from the maximum values of stress at the upper and lower edges of the plate and falling off to zero at the free edge.

The maximum value for the bending stress on the upper and lower edges of the plate at the edge of the wall is ± 15.82 psi.

From Simple Beam Theory,

$$\sigma_x = \pm \frac{My}{I} = \pm \frac{PLc}{I} = \pm 15.62 \text{ psi} \quad [4.18]$$

Therefore, it is clear that the desired values for σ_x are close to those obtained from the Simple Beam Theory which is simulated here.

From the third example of the previous section, the σ_x results are shown in Figure IV-9.

Note that the upper half plate of Figure IV-6 is in compression, and the lower half is in tension. This is confirmed by the variation of σ_x in Figure IV-9 (that is, there are no alternating stresses about the quarter length axis). The asymmetry of σ_x about the horizontal N.A. at the last two sections where it is plotted, is due to the fact that the upper and lower nodes of the plate at the center line were left unrestrained in y .

E = 30×10^6 PSI
 $\nu = .25$
 LOADS: 60 LB. PARABOLICALLY DISTRIBUTED
 ON THE FREE EDGE.
 TOTAL NUMBER OF ELEMENTS: (10 x 25)

THICKNESS OF PLATE = .4 IN.
 BOUNDARY CONDITIONS: NODES 1-11 RESTRAINED IN X
 NODE 6 RESTRAINED IN Y

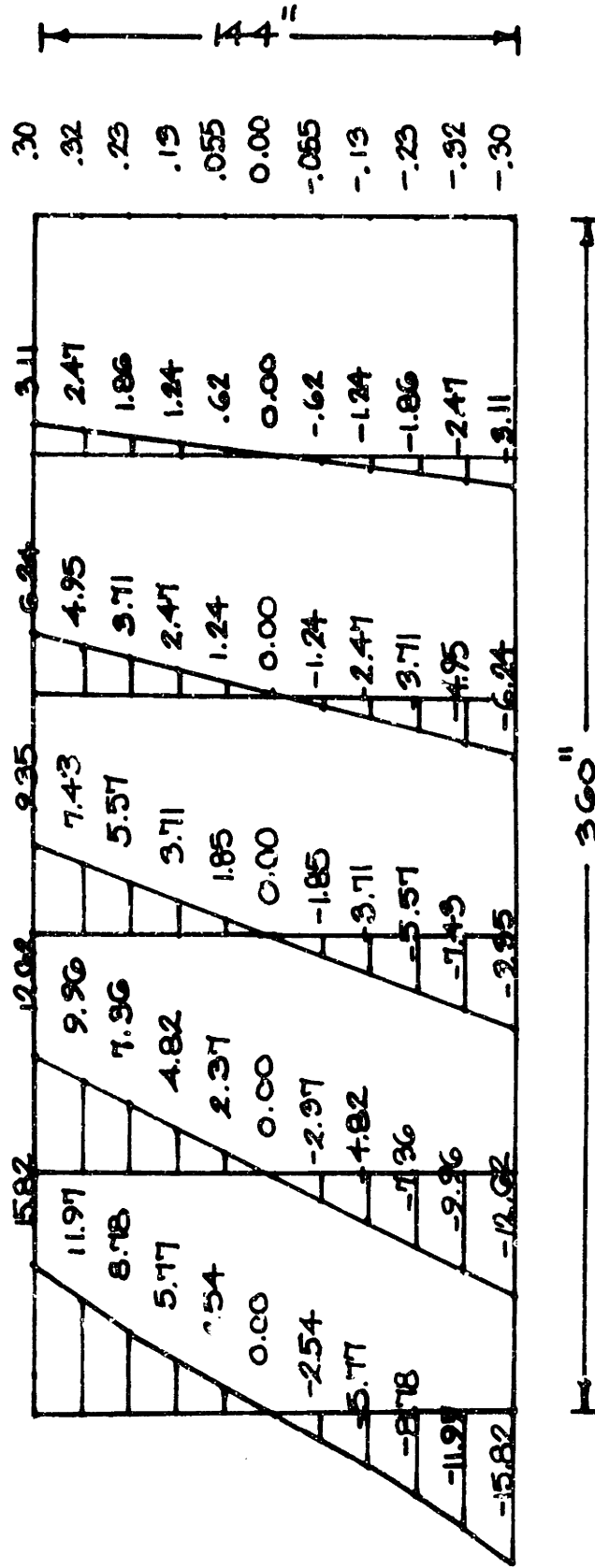


Figure IV-8
 The σ_x (in psi) Distribution along the Length of a Cantilever

$E = 30 \times 10^6$ PSI LOADS: A UNIFORMLY DISTRIBUTED LOAD OF INTENSITY $q = 0.1667$ #/in ON THE UPPER EDGE.
 $\nu = .25$
 THICKNESS OF PLATE = .4 in.
 BOUNDARY CONDITIONS: A PARABOLIC SHEAR LOAD DISTRIBUTION OF AN OVERALL 60 # LOAD, ON THE LEFT EDGE, ON THE
 NODES 276-286 RESTRAINED LEFT EDGE.
 IN X
 NODES 275-285 RESTRAINED
 IN Y

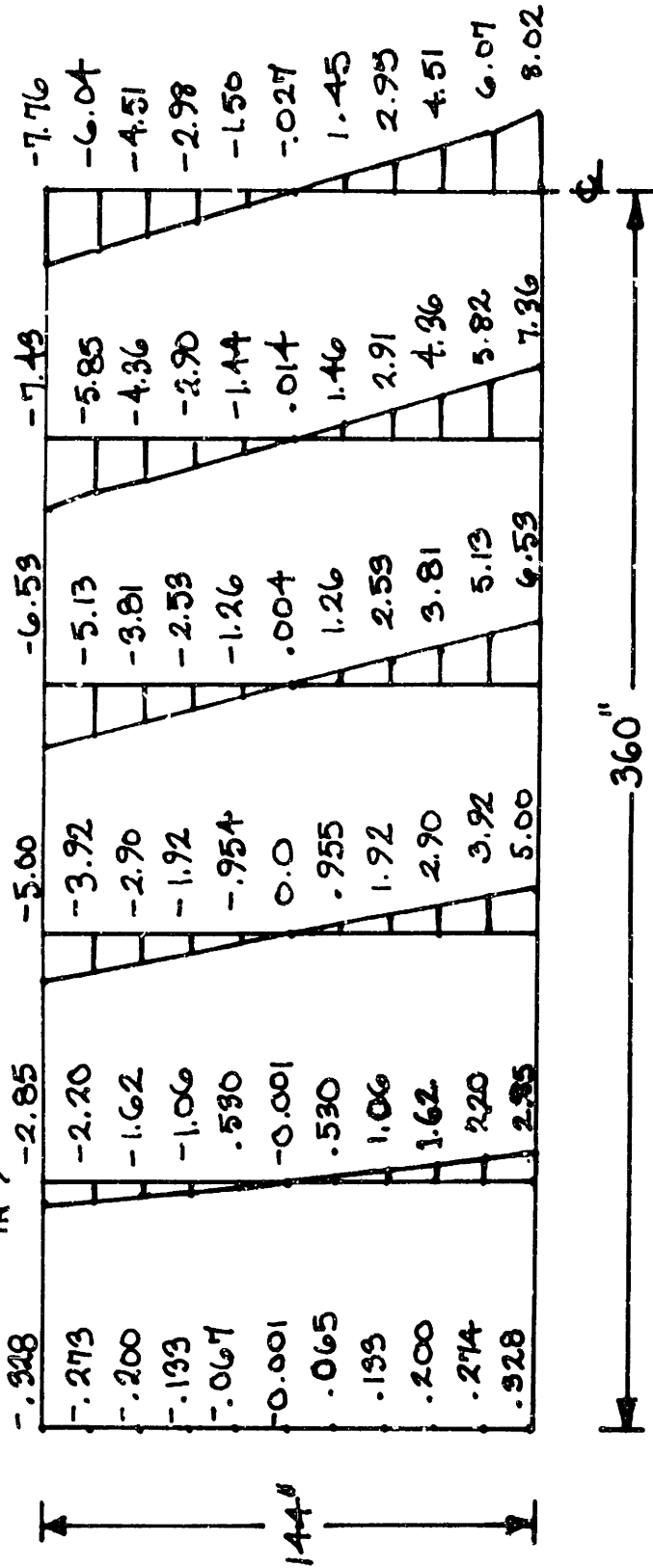


Figure IV-9

The σ_x (in psi) Distribution along the Length of a Self-Equilibrated Plate

4. Principal Compressive Stress Trajectories

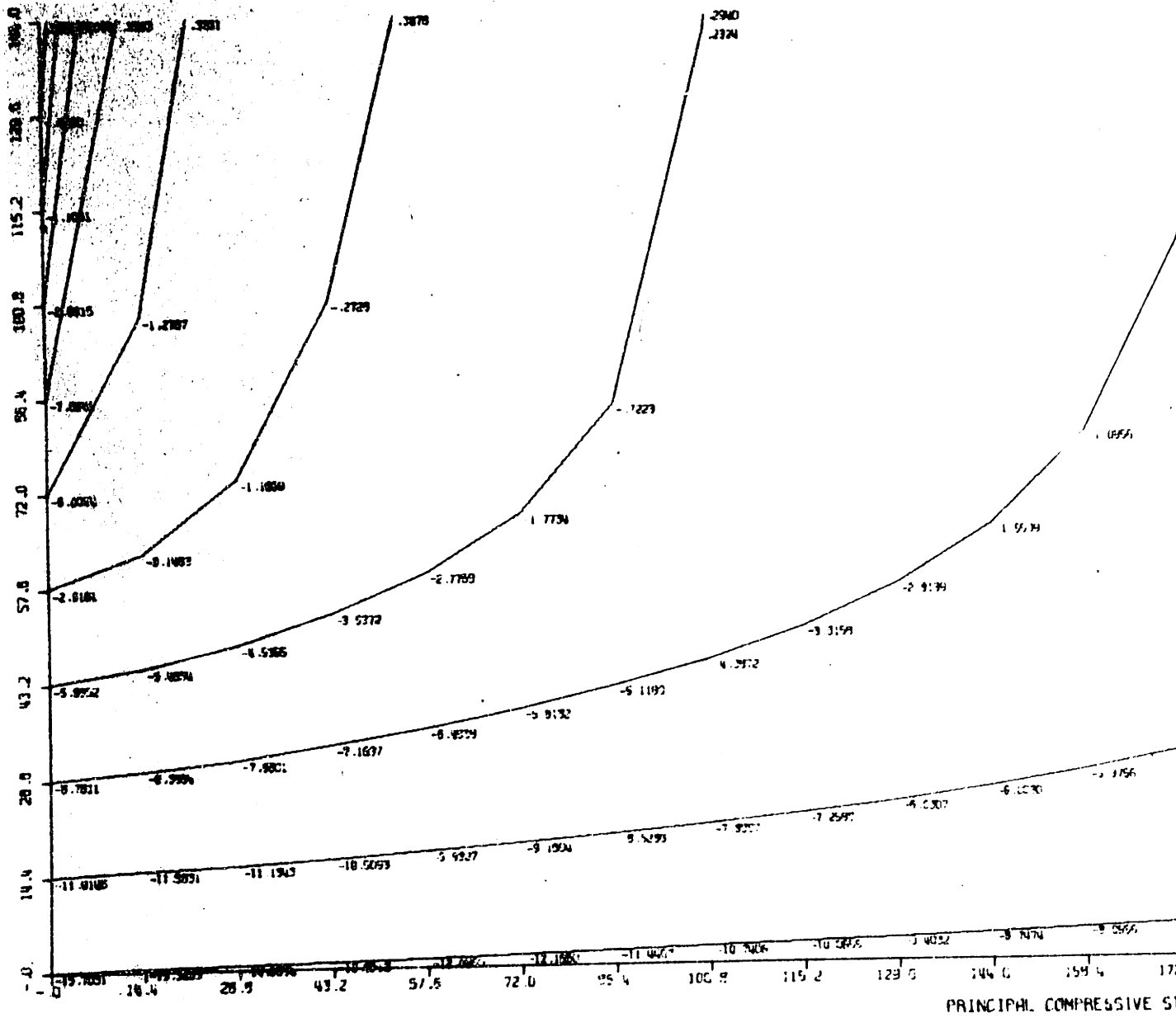
The results for the principal compressive stress trajectories of the above three examples are shown in PLATE I (see Appendix II-A) and in PLATES II, III, and IV.

PLATE I and II are almost identical; the small differences in the principal compressive stresses, σ_2 , reveal that for the case of PLATE I, the parabolic shear distribution is simulated by discrete nodal loads, while for the case of PLATE II, it is simulated by distributed boundary loads. In both cases, however, the stress trajectories are agreeable to the expectation of Figure I-B-2, in Appendix I-B.

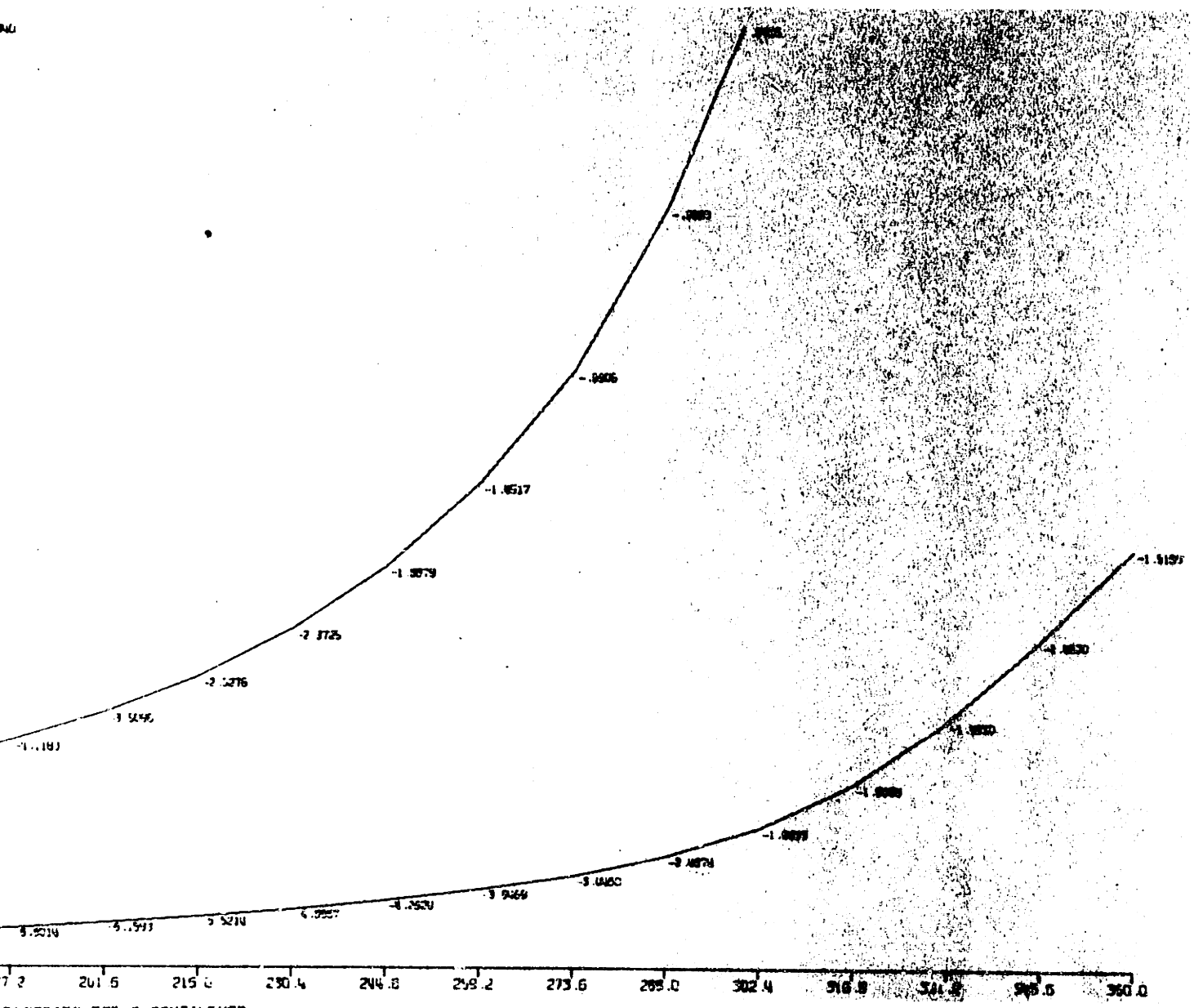
The stress trajectories appearing in PLATE III correspond to the centrally loaded plate (left-half) and are in agreement with theoretical expectations. (14)

Notice that the directions of the trajectories along the N.A. are at 45° to the horizontal, revealing that the principal stress there is due to shear. Also, notice that at the center line and at the wall sections the principal stress direction becomes horizontal, due to the bending stress, σ_x . (There is no shear stress component there). The trajectories that start from nodal points on the left edge of the plate and above the N.A. are directed upwards, implying that they are at right angles with the principal tensile stress trajectories (which are not indicated here).

Notice also that for the maximum compressive stress trajectory that commences at nodal point 1, the magnitude

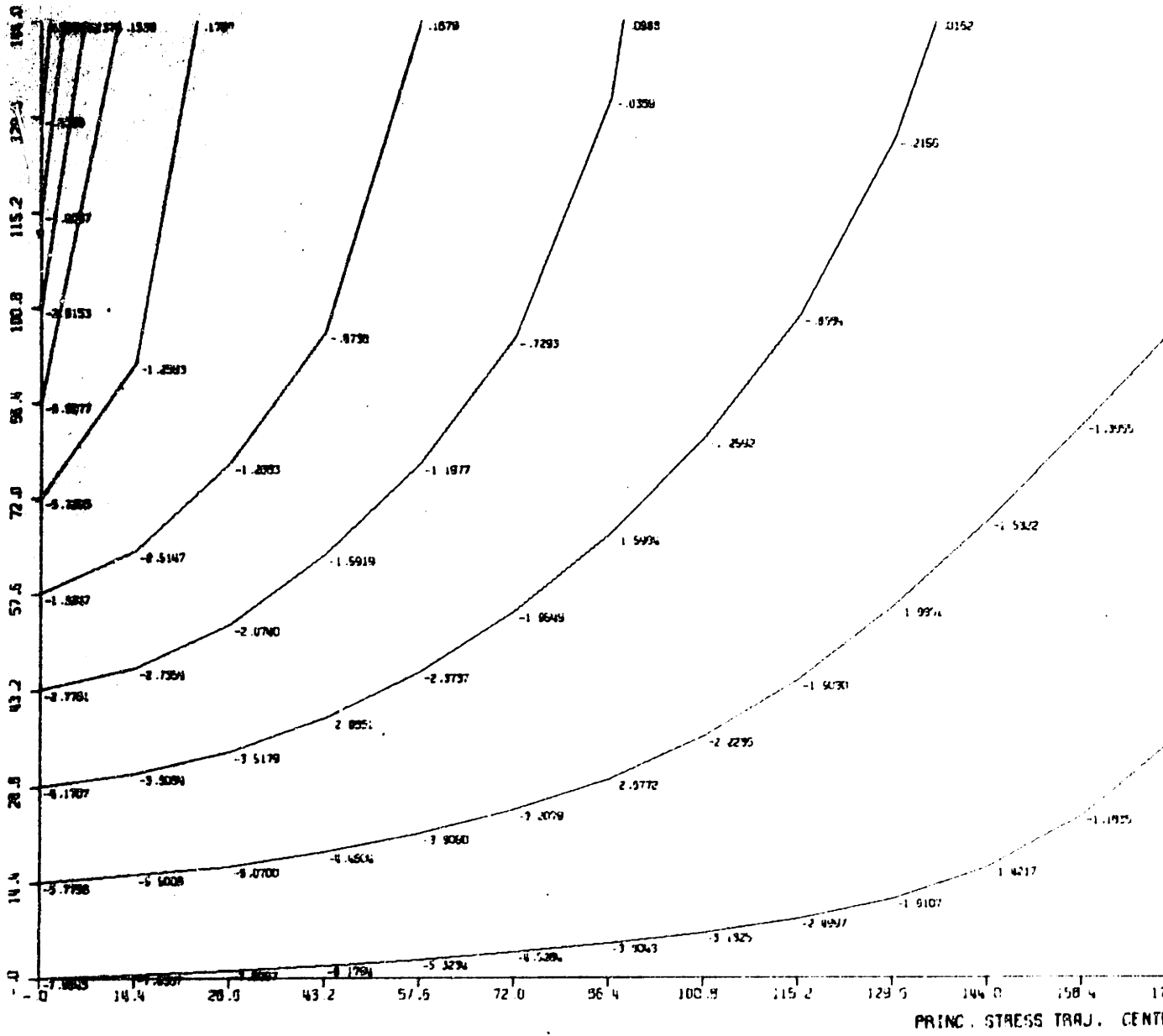


PRINCIPAL COMPRESSIVE S

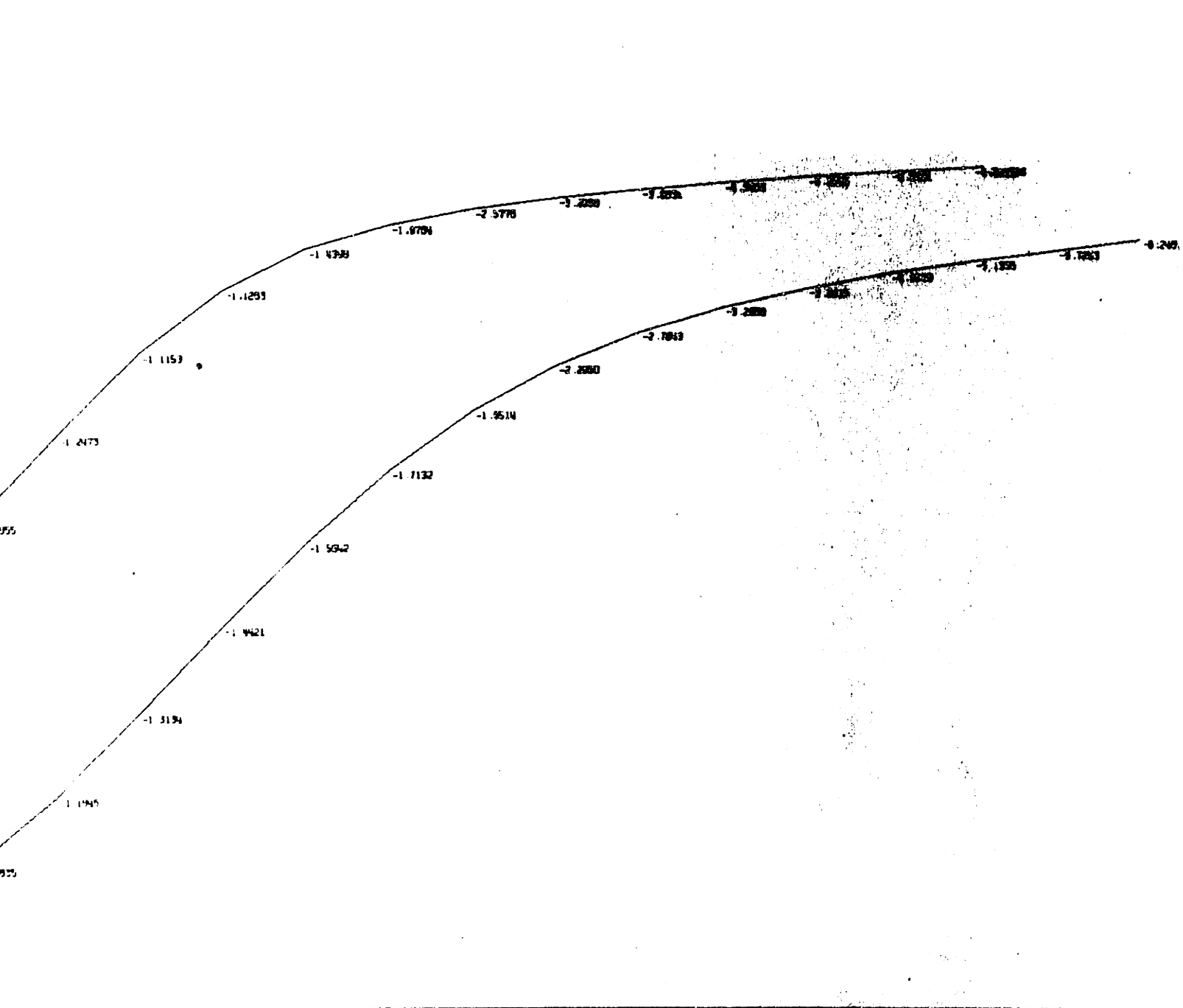


TRAJECTORIES FOR A CANTILEVER

PLATE II

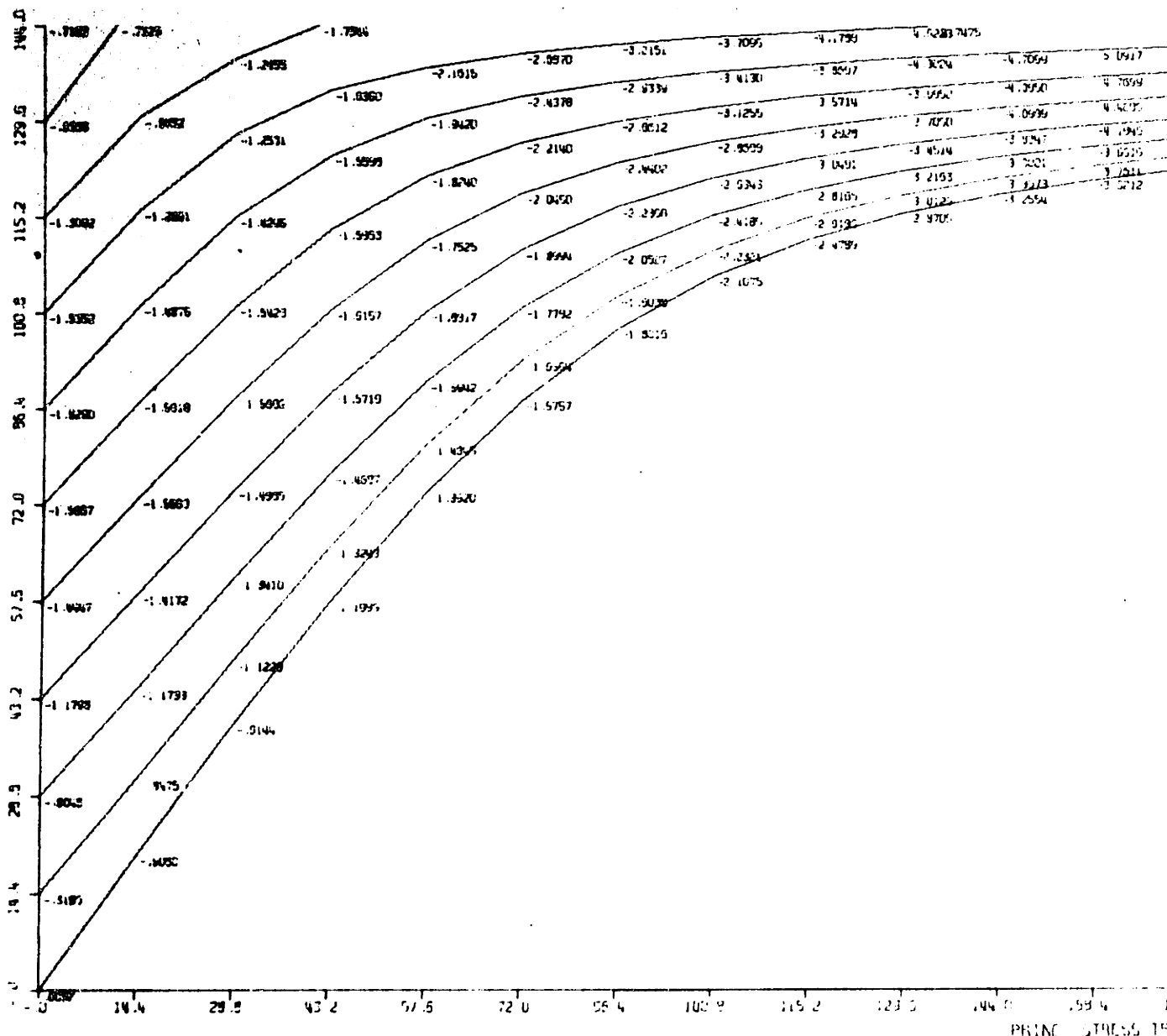


PRINC. STRESS TRAJ. CENT



CENTRALLY LOADED PLATE, CLAMPED ENDS

PLATE III



PRINCIPAL STRESS 19

465	5.7378	5.7415	5.7451	5.7487	-6.9374	-7.0381	-7.2015	-7.3339	-7.4229	-7.4800	-7.5078	-7.5311	-7.5579
466	5.7425	5.7465	5.7503	5.7541	-6.9367	-7.0350	-7.1959	-7.3255	-7.4129	-7.4697	-7.4971	-7.5202	-7.5470
467	5.7472	5.7515	5.7557	5.7600	-6.9360	-7.0324	-7.1905	-7.3175	-7.4035	-7.4600	-7.4871	-7.5100	-7.5367
468	5.7519	5.7565	5.7610	5.7655	-6.9353	-7.0297	-7.1859	-7.3105	-7.3949	-7.4510	-7.4778	-7.4995	-7.5261
469	5.7566	5.7615	5.7663	5.7710	-6.9346	-7.0270	-7.1815	-7.2935	-7.3765	-7.4320	-7.4585	-7.4800	-7.5065
470	5.7613	5.7665	5.7715	5.7765	-6.9339	-7.0243	-7.1775	-7.2875	-7.3690	-7.4240	-7.4500	-7.4715	-7.4980
471	5.7660	5.7715	5.7768	5.7820	-6.9332	-7.0217	-7.1735	-7.2815	-7.3615	-7.4160	-7.4415	-7.4630	-7.4895
472	5.7707	5.7765	5.7820	5.7875	-6.9325	-7.0190	-7.1695	-7.2755	-7.3540	-7.4080	-7.4330	-7.4545	-7.4810
473	5.7754	5.7815	5.7875	5.7935	-6.9318	-7.0155	-7.1645	-7.2685	-7.3460	-7.4000	-7.4250	-7.4465	-7.4730
474	5.7801	5.7865	5.7928	5.7990	-6.9311	-7.0110	-7.1585	-7.2605	-7.3370	-7.3900	-7.4150	-7.4365	-7.4630

210 215 220 225 230 235 240 245 250 255 260 265 270 275 280 285 290 295 300 305 310 315 320 325 330 335 340 345 350

PLATE IV

of the principal stress decreases with x increasing, until it reaches the N.A. at quarter lengths and increases again in a symmetrical manner.

In PLATE IV the compressive stress trajectories are in agreement with Figure IV-9 where the compressive stresses are all above the N.A. Since a shear reaction acts along the left edge of the plate, all the trajectories are expected to be at 45° angles to the horizontal.

Notice that as the σ_x stress increases while moving towards the center line, the compressive stress trajectories also increase and tend to become more horizontal.

5. Computer Stiffening Procedure

The results in this section demonstrate the computer program's "stiffening" capabilities.

Let us divide the left-half of the centrally-loaded plate into 250 finite elements. By assigning numbers to each one of the elements starting from the lower left hand side element of the structure and counting always from bottom to top, subroutine STIFEN identifies all elements which are transversed by every stress trajectory.

The stress trajectories for this case cross all the elements which have been darkened in Figure IV-10. By setting NUM = 2 (See Appendix II-A) the computer program procedure is repeated after the identification of the elements need to be "stiffened"; the new average nodal stresses are calculated.



Figure IV-10
The Computer Program's "Stiffening" Arrangement (First Trial)

For the case where the "stiffening" is made by doubling the thickness of the elements, traversed by trajectories, the σ_x average nodal stresses obtained are shown in Figure IV-11.

By comparing Figures IV-7 and IV-11, one observes that the stresses for the thus "stiffened" case are lower than those of the unstiffened as it is expected.

Furthermore, the symmetric distribution of the σ_x about the horizontal N.A. of the plate is disturbed in a similar manner to that of the pathways of the stress trajectories.

Notice that the compressive $-\sigma_x$ stresses at the extreme lower left portion of the plate (first section) are decreased more than what the corresponding tensile $+\sigma_x$ stresses are in that same section. The same behavior is observed in the next two sections; when passed the quarter length of the plate, the lower stress values in a section appear on the above of the N.A. portion of the plate.

Thus, it has been explicitly shown that by assigning a new thickness value to the elements which are traversed by stress trajectories, the overall stress in the structure is reduced; in particular, it is reduced in a manner proportional to the magnitude of the compressive stress and along the principal compressive stress trajectories.

Before the repeated procedure ends, the new stress trajectories for the thus "stiffened" plate will yield a new set of elements for further "reinforcement" of the

$E = 30 \times 10^6$ PSI
 $\nu = .25$

LOADS: 60 LB. PARABOLICALLY DISTRIBUTED ON THE Φ EDGE.

TOTAL NUMBER OF ELEMENTS: (10 X 25).

THICKNESS OF PLATE = .4 IN.

THICKNESS OF 'STIFFENERS' = .4 IN.

BOUNDARY CONDITIONS:

NODES 1-11, 276-286 RESTRAINED IN X;
NODE 6 RESTRAINED IN Y.

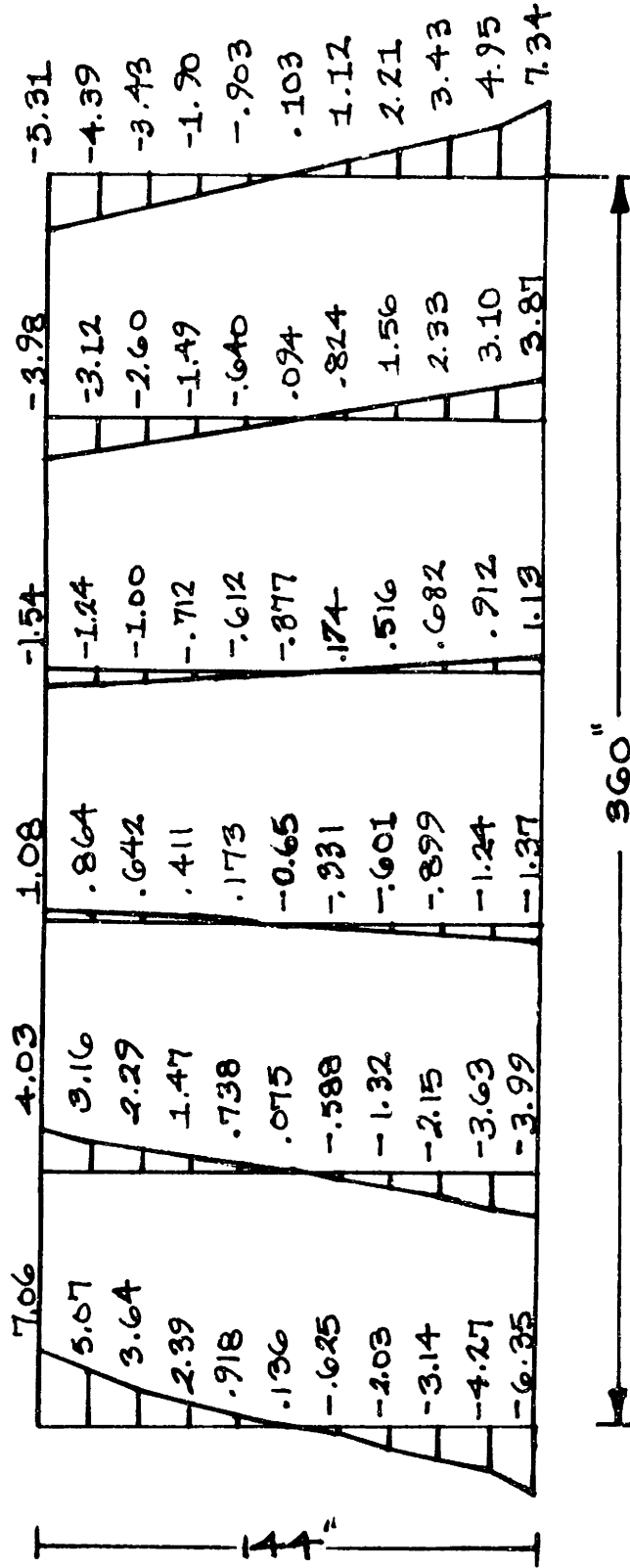


Figure IV-11

The σ_x (in psi) Distribution along Half the Length of a Centrally-Loaded Plate after It Has Been "Reinforced"

structure.

Figure IV-12 illustrates the new darkened elements. If one compares the darkened elements of the first trial with those identified for a second trial in Figure IV-12, one may notice that the darkened elements to be "stiffened" the second time maintain the same pattern with those darkened elements which were "stiffened" the first time.

The difference between the two however is that the second pattern shifts slightly to the left, creating this way a steeper slope of ascent for the maximum principal stress trajectory; this is to be expected since the values of the compressive $-\sigma_x$ stresses have been lowered from the "stiffening" of the first trial.

6. Least Weight Stiffener Arrangements

In Part III, the results for $\bar{\tau}_A$, $\bar{\tau}_B$, and $\bar{\tau}_C$ vs H as well as the results for $\bar{\sigma}_A$, $\bar{\sigma}_B$, and $\bar{\sigma}_D$ vs H are discussed and it is mentioned that $\bar{\tau}_B < \bar{\tau}_C < \bar{\tau}_A$ is always true for the same H, α , and c which essentially implies the same weight. The conclusion that $\bar{\sigma}_A < \bar{\sigma}_D < \bar{\sigma}_B$ was the similar relation for the case where the principal stress σ_2 depends completely on the σ_x bending stress.

However, the Figures in the corresponding section there do not explicitly show the variation of stress with weight.

The results to follow in this section show the variation of the non dimensional shear and bending stresses with

respect to a common non-dimensional weight parameter, A , to all arrangements A, B, C, and D where

$$A = Bt + 2cHt \quad [4.19]$$

where B , t , c , and H are as defined, in Part III.

Since B is constant for all the arrangements, it is appropriate to non-dimensionalize A with respect to B as it was done for the non-dimensional expression for the shear stresses and the bending stresses for all cases.

Multiplying both numerator and denominator of the right hand side of equation [4.19] by B one obtains

$$A = \frac{B^2}{\alpha} [1 + 2cH] \quad [4.20]$$

or

$$\bar{A} = \frac{A}{B^2} = \frac{1}{\alpha} (1 + 2cH) \quad [4.21]$$

which is the non-dimensional weight.

Therefore, plotting $\bar{\tau}_A$, $\bar{\tau}_B$, $\bar{\tau}_C$, and $\bar{\sigma}_A$, $\bar{\sigma}_B$, $\bar{\sigma}_D$ vs \bar{A} one obtains the results of Figures IV-13 through IV-24 which verify the results of the Figures of Part III.

Furthermore, they show that the stress varies in a hyperbolic manner with respect to weight.

Therefore, the closest family of curves to the axes corresponds to the best stiffener arrangement; that is, the B arrangement for the case of maximum shear and the A arrangement for the case of maximum bending stress.

The conclusion one may draw from the plotted results of the following Figures is: the least weight arrangement of stiffeners to reduce the stress level in any cross-section of any planar structure is that one which adds material at the location where the principal compressive stress is maximum.

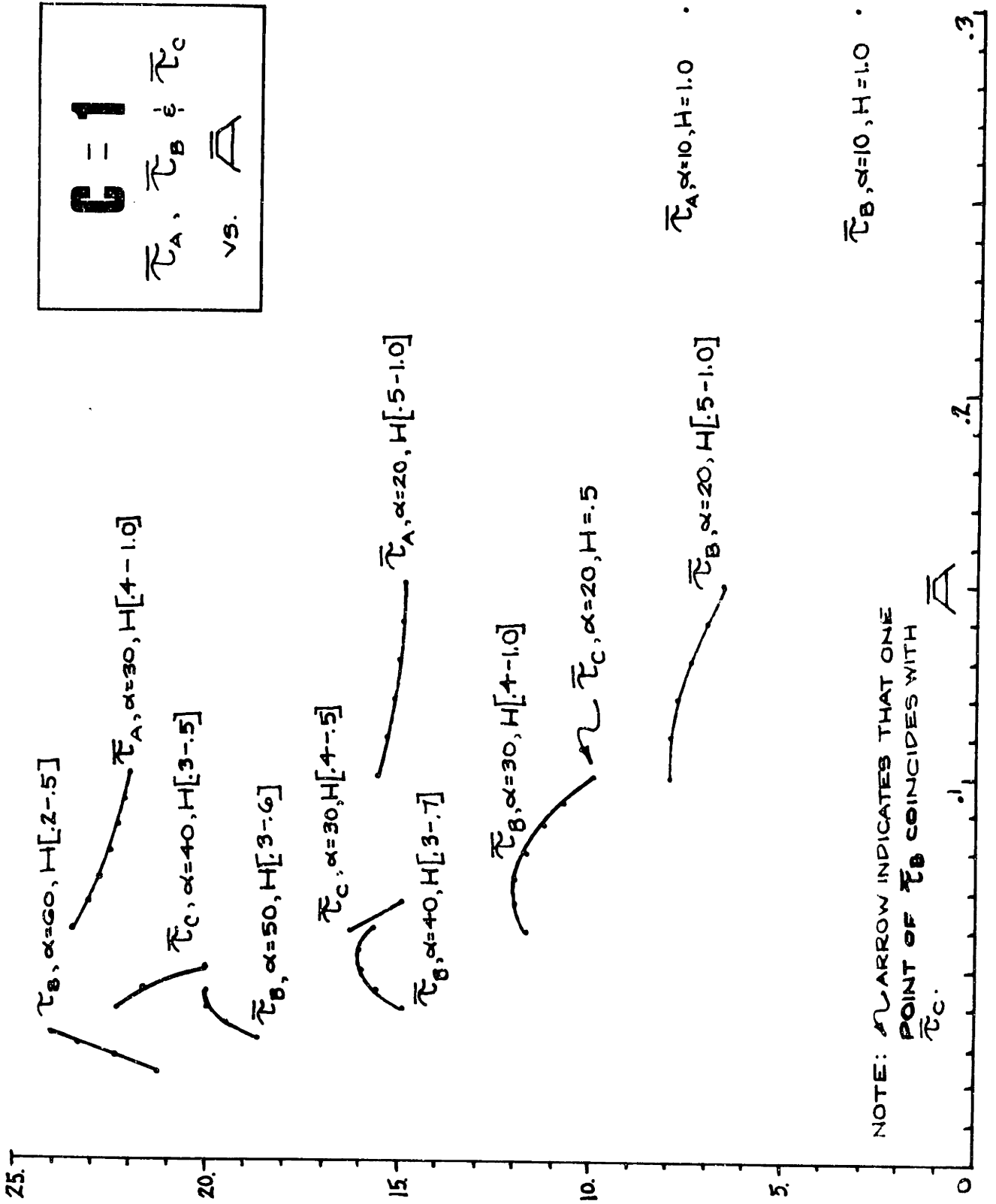


Figure IV-13

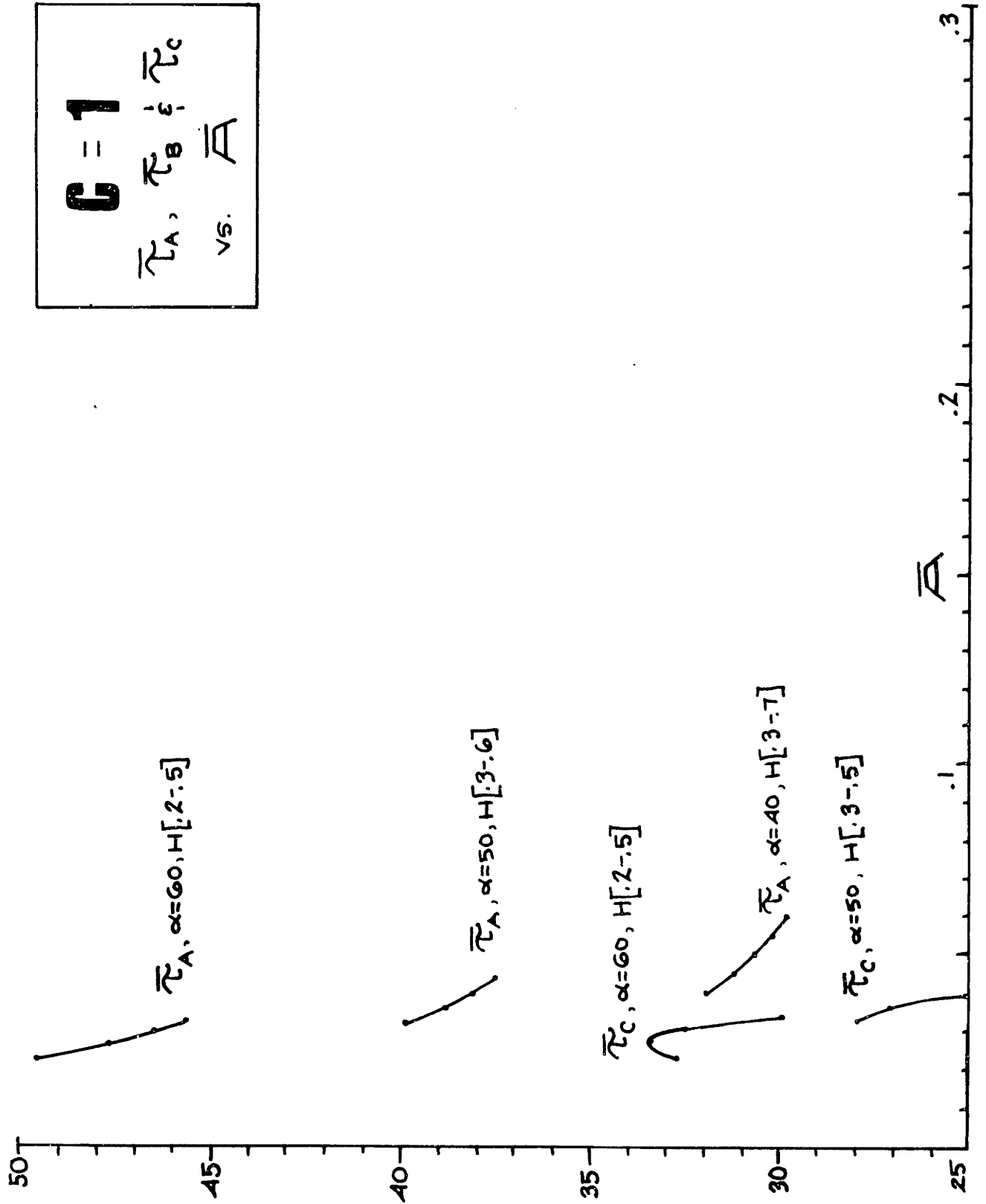
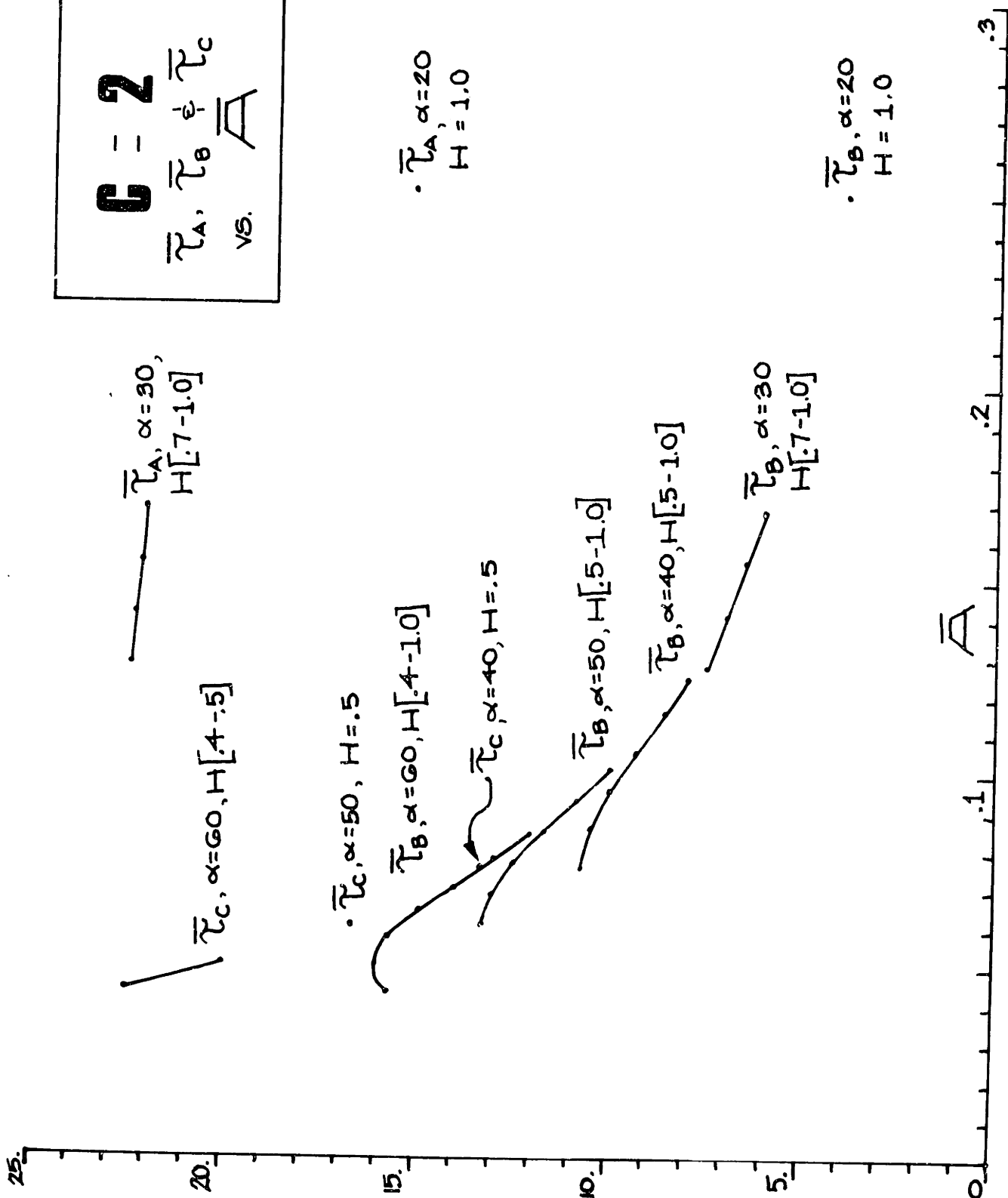


Figure IV-14

$$G = 2$$

$$\bar{\tau}_A, \bar{\tau}_B \text{ vs. } \bar{A}$$



• $\bar{\tau}_A, \alpha=20$
 $H = 1.0$

• $\bar{\tau}_B, \alpha=20$
 $H = 1.0$

Figure IV-15

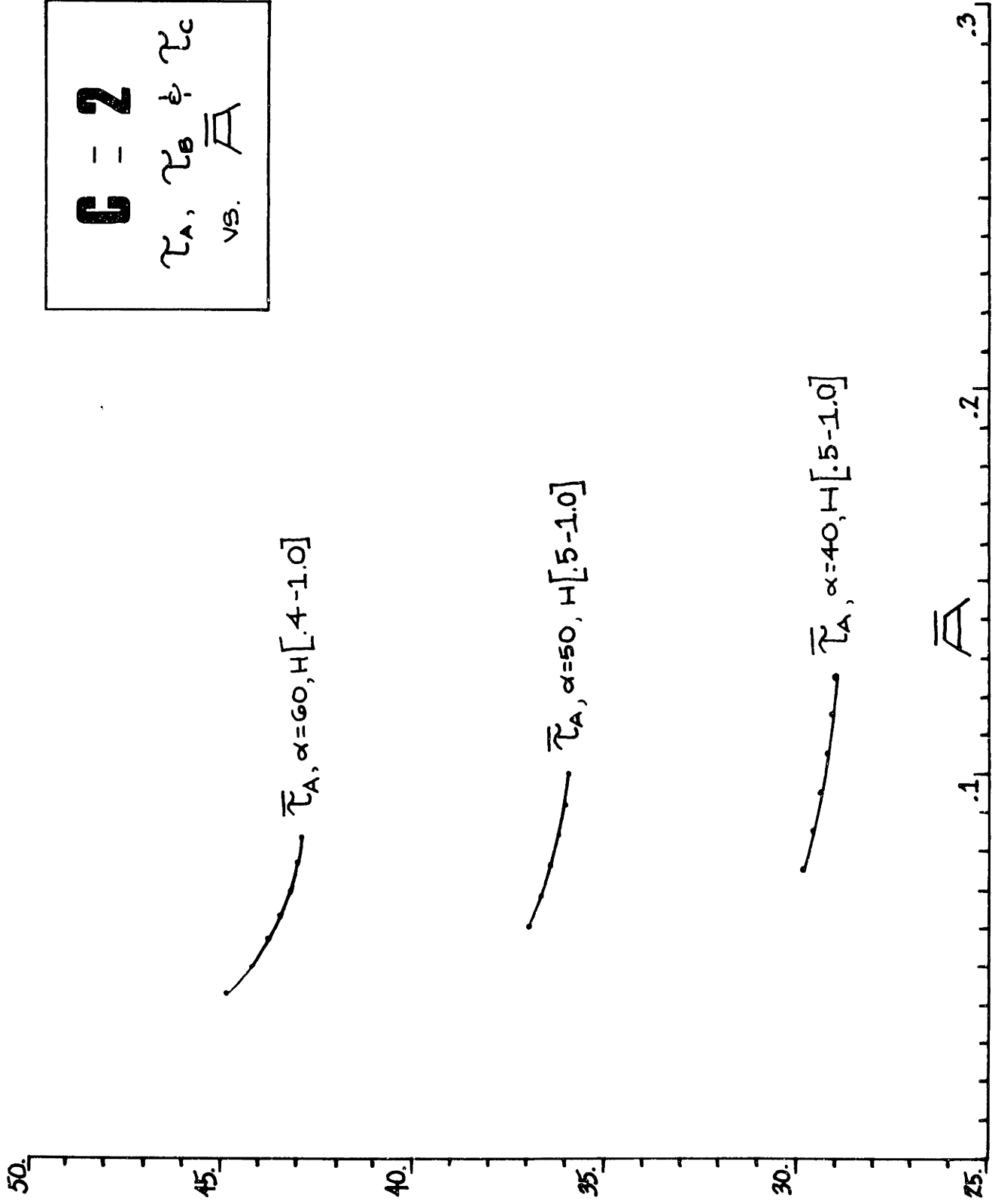


Figure IV-16

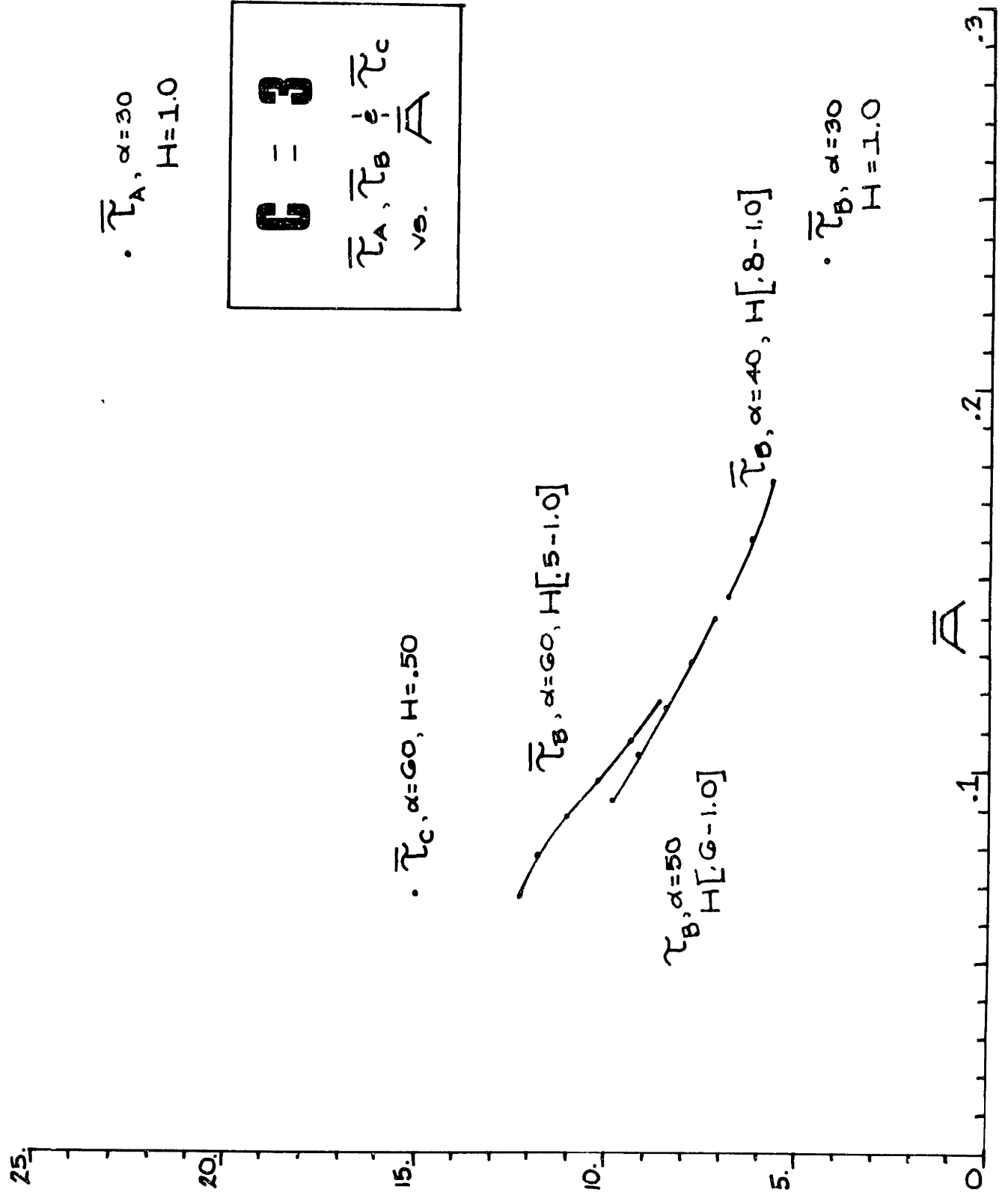


Figure IV-17

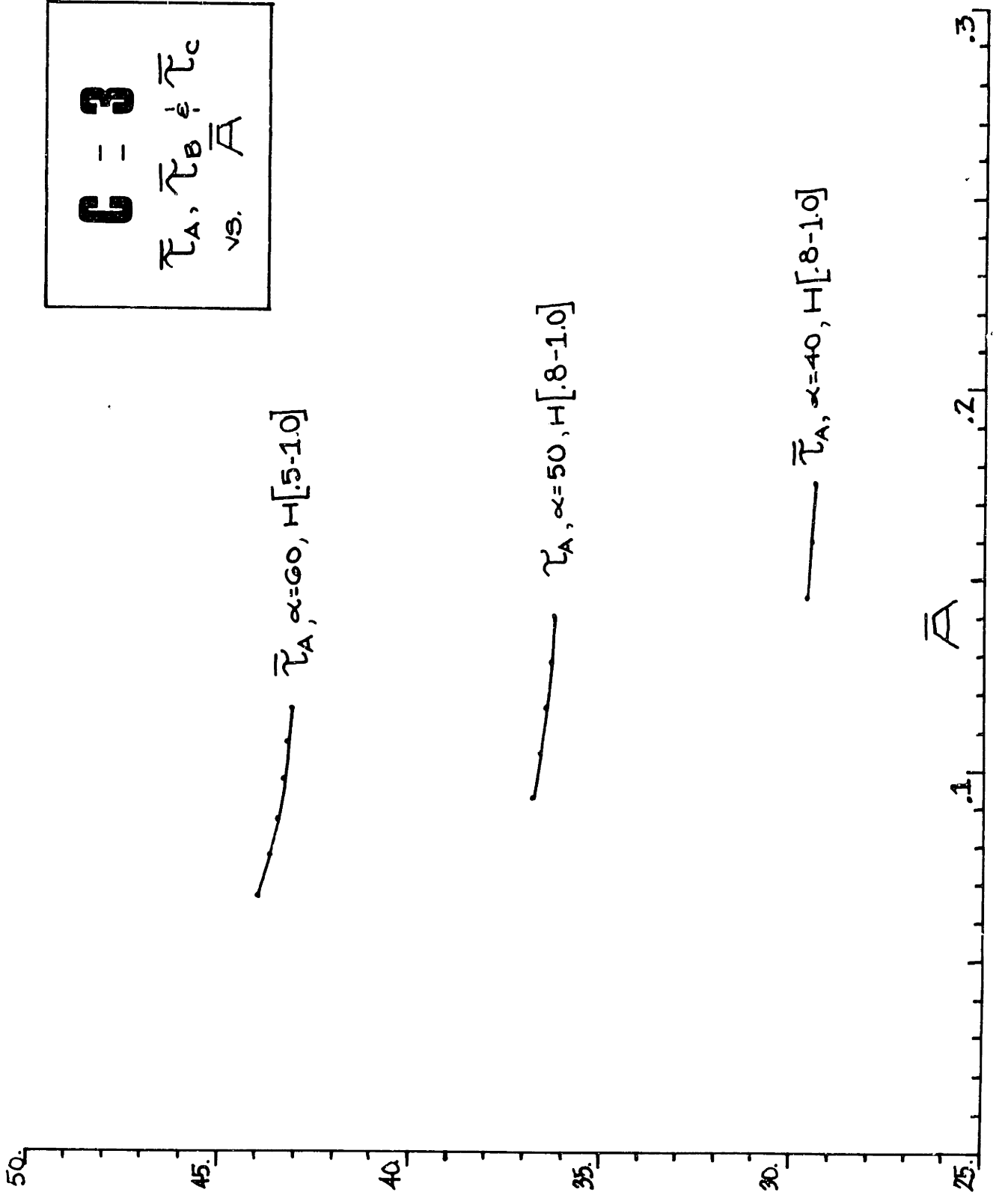


Figure IV-18

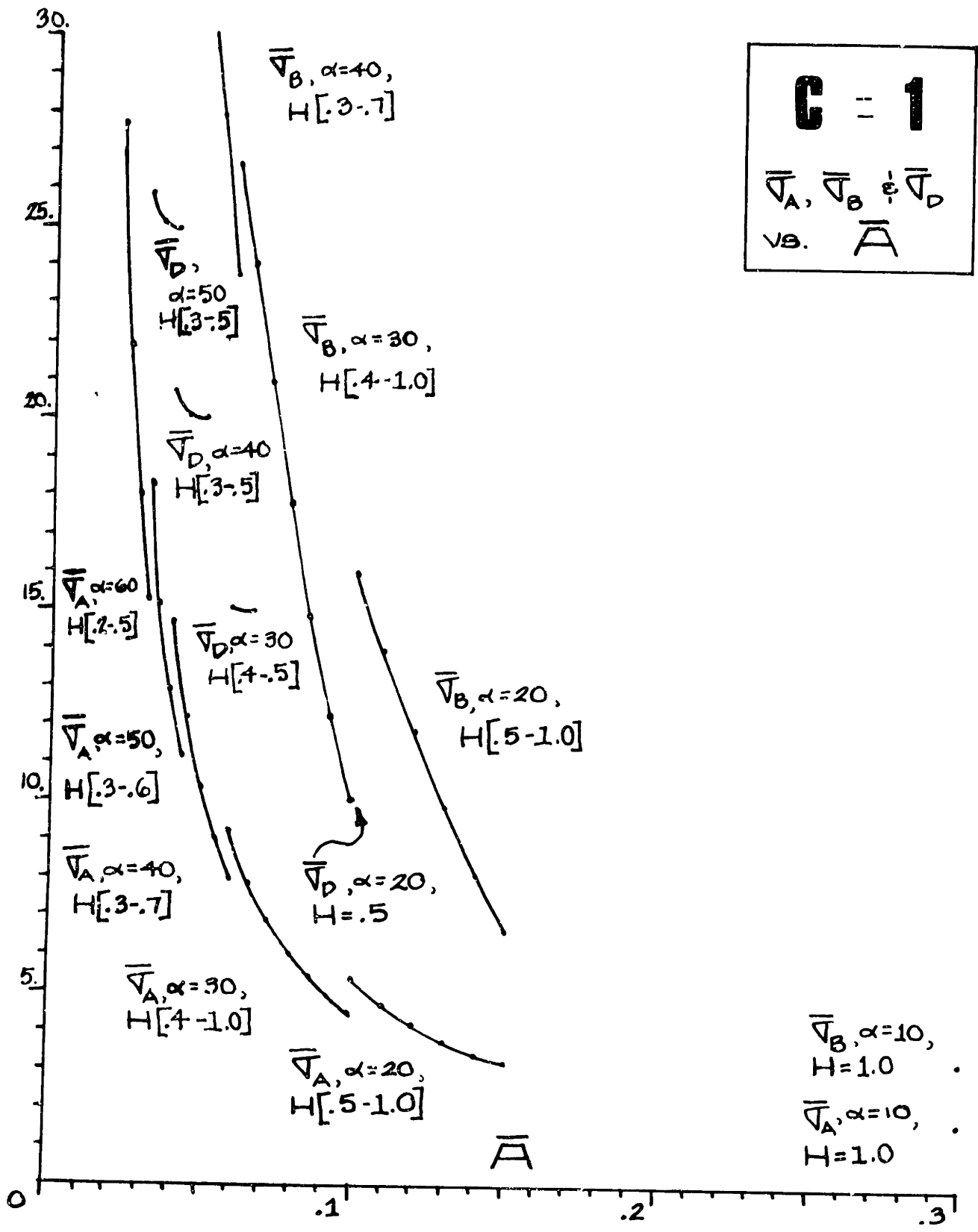


Figure IV-19

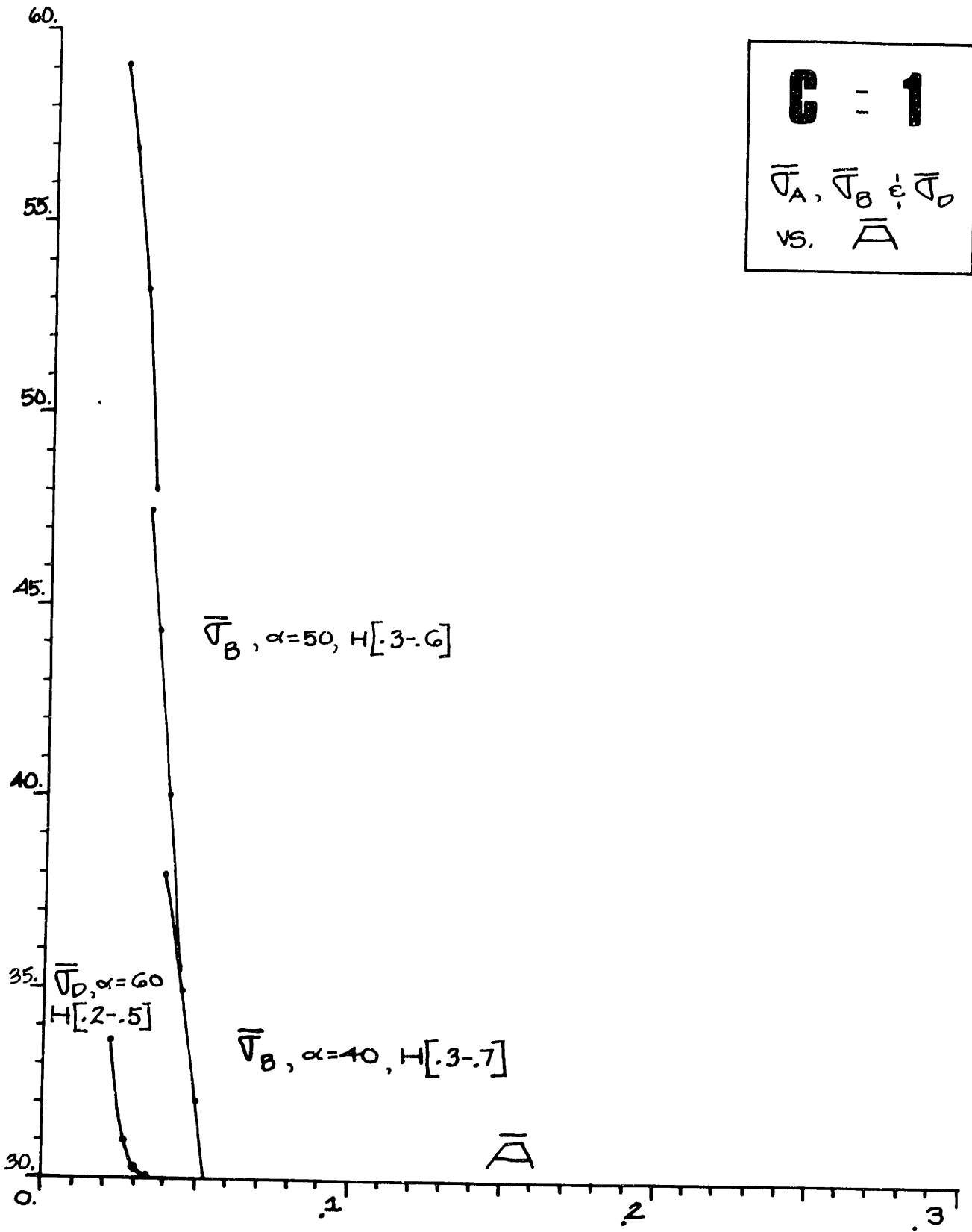


Figure IV-20

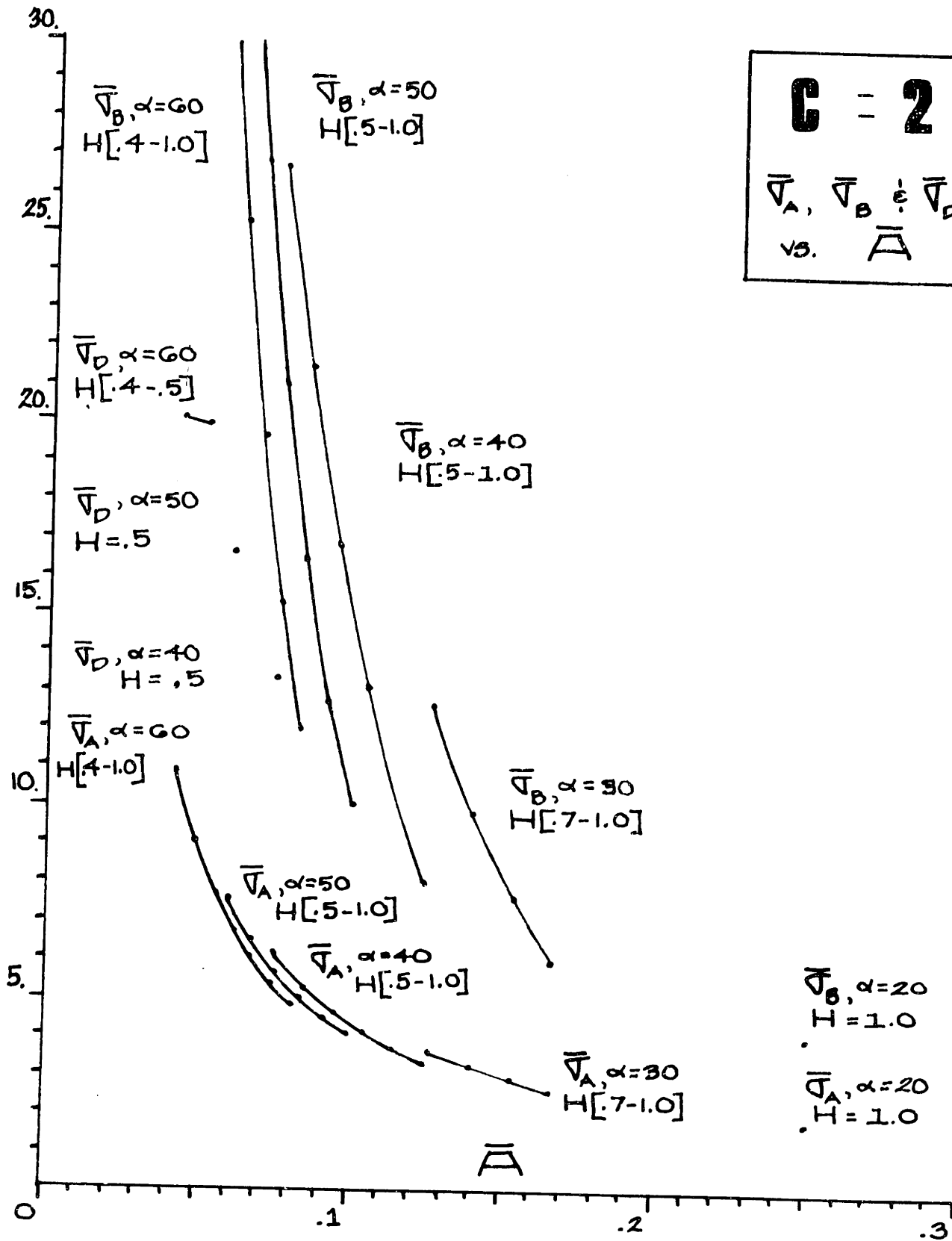


Figure IV-21

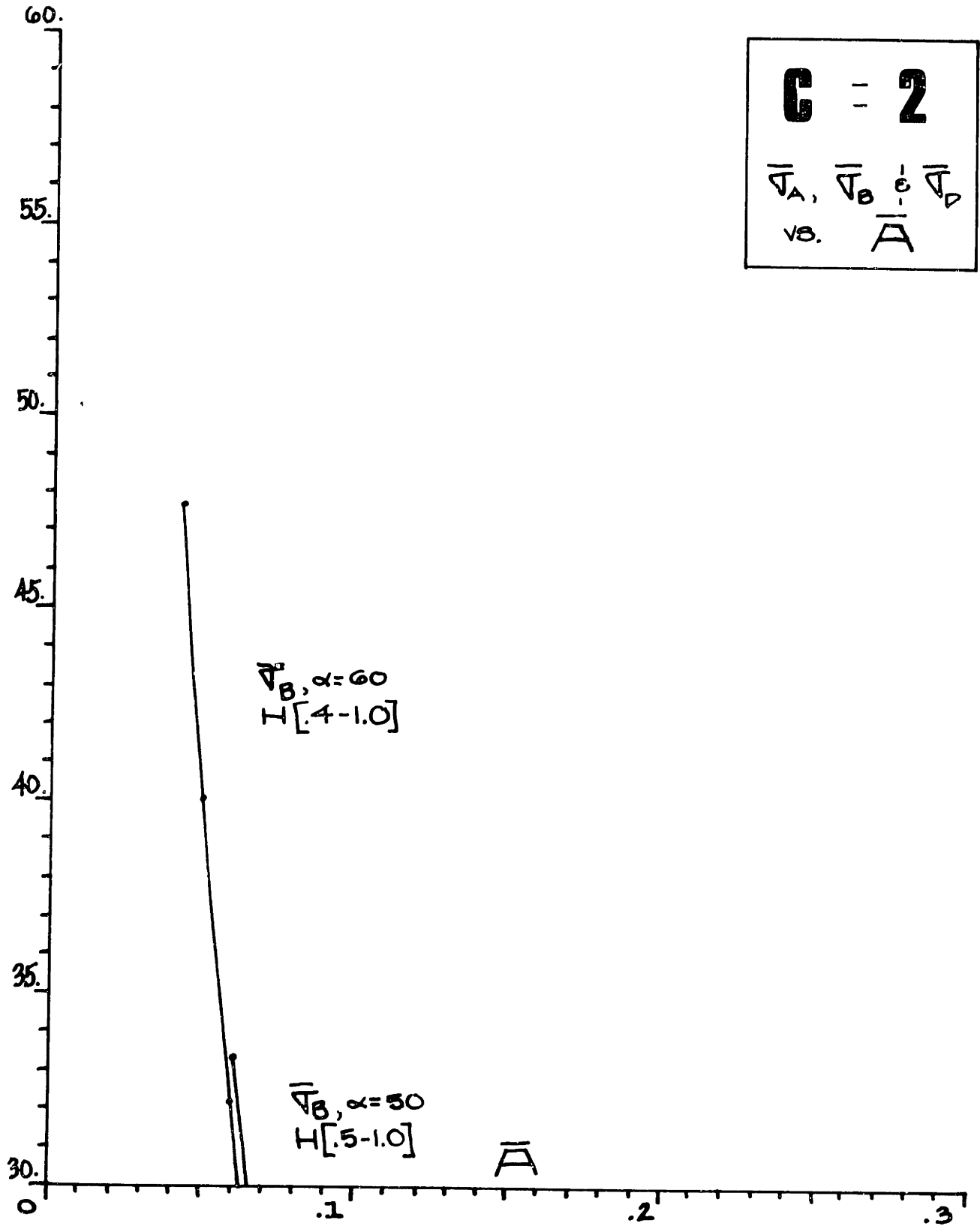


Figure IV-22

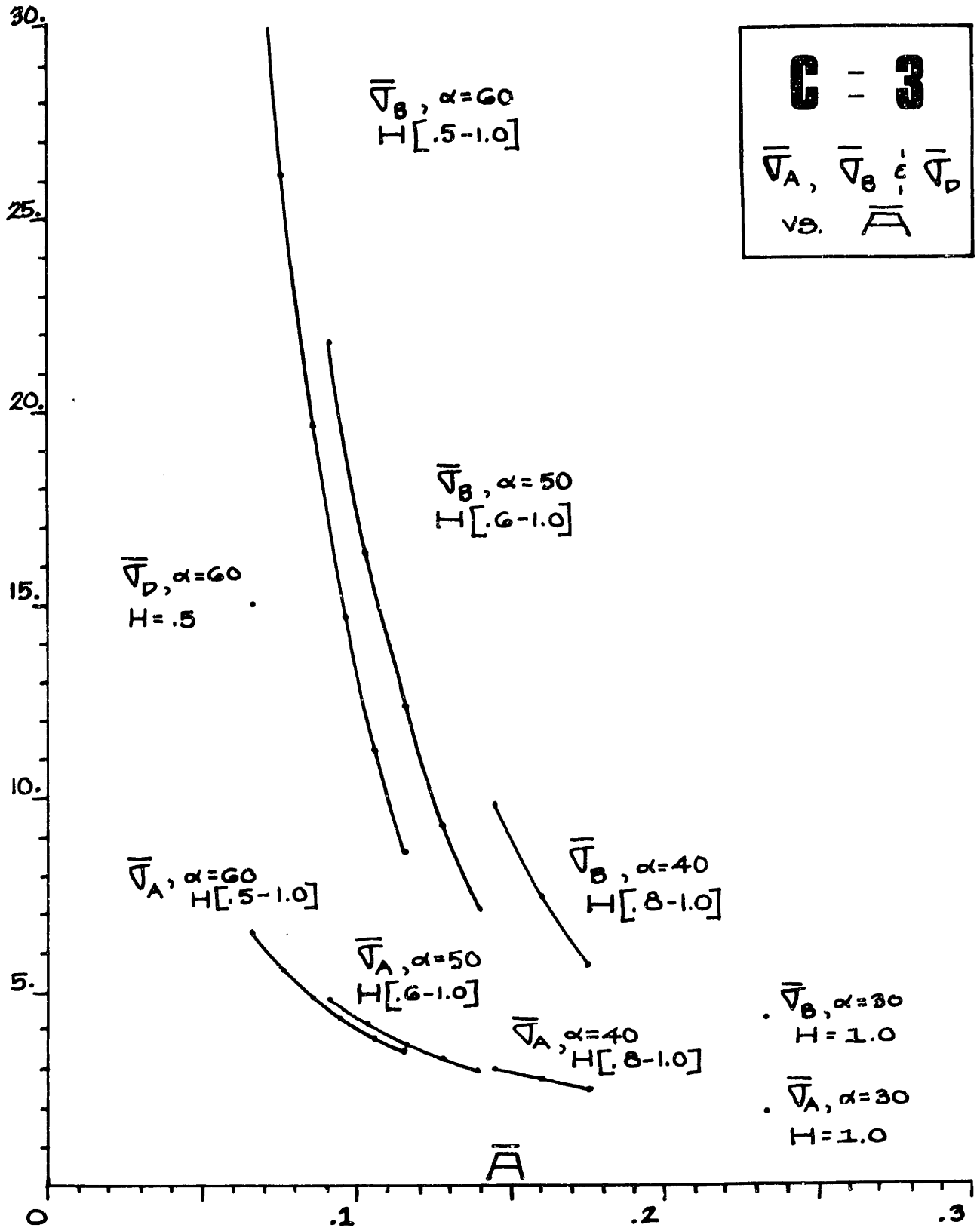


Figure IV-23

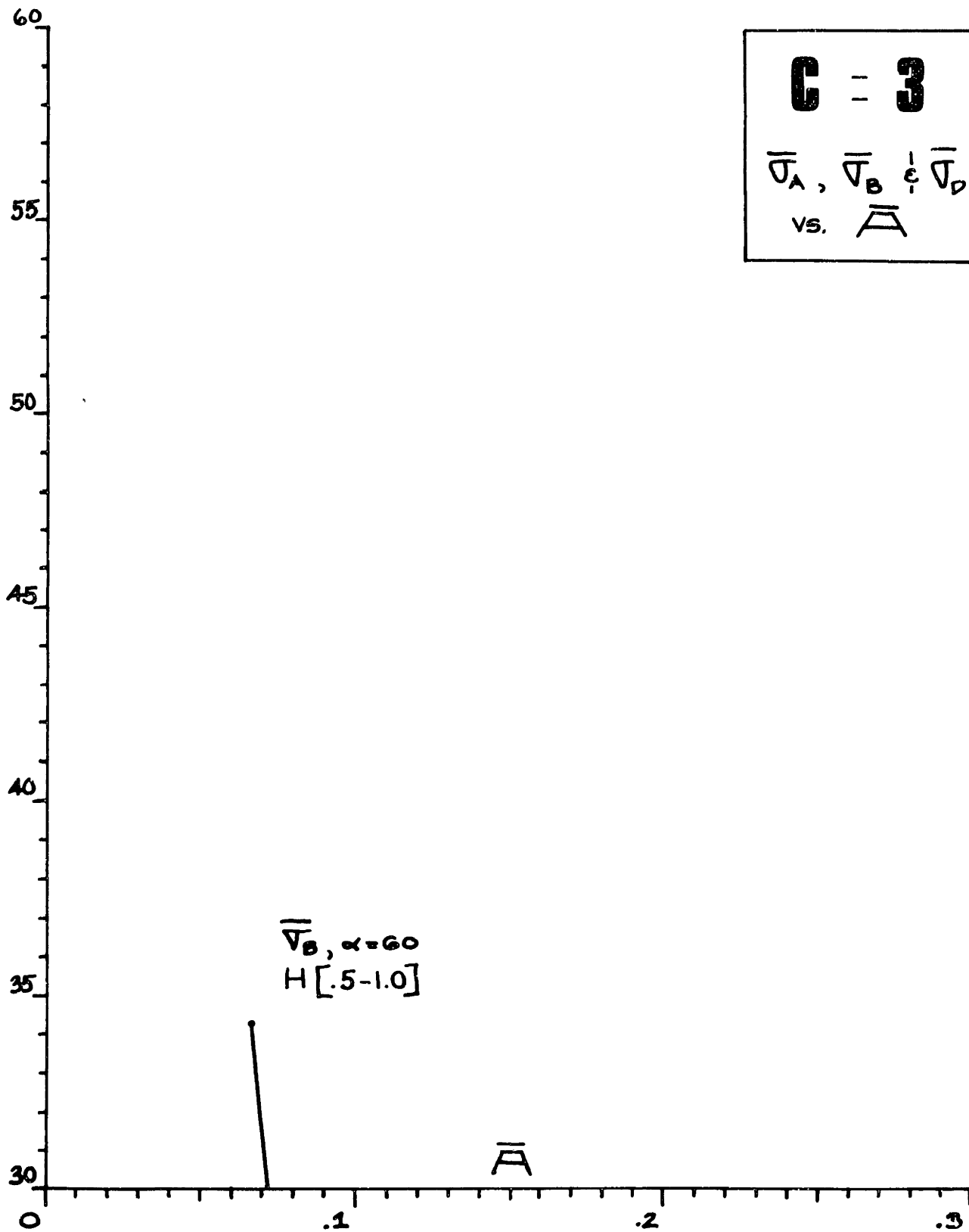


Figure IV-24

CONCLUSIONS

It may be concluded from the results obtained for the three classical cases used to illustrate the Stress Trajectory Technique that the present study has fulfilled its purpose within the limitations originally defined.

Specifically, for any two-dimensional isotropic material plane stress problem, the general state of stress can be described in detail by determining the state of stress, first. From the general state of stress it has been shown how the principal stress trajectories can be efficiently obtained.

The fact that only compressive stress trajectories are obtained at the present, implies that although no mention is made of instability, eventually the investigator of optimum arrangement structures aims to arrive at the stage that he can handle problems in which instability is a factor.

This would involve an optimum sizing of the particular truss members or plate stiffeners, in order to resist buckling, as well as a particular spacing of the individual frames.

In this work, however, although instability is ignored, implicitly it is being considered. When one refers to a tie for example, only the maximum allowable tensile stress σ_T is of importance. In the case of a strut, however, the designer has to take into account the σ_{cr} stress as well as the maximum allowable compressive stress σ_c .

In reducing σ_c by adding material on the location where the principal compressive stress is a maximum, we efficiently increase σ_{cr} .

It has been tentatively shown that the arrangement which adds the reinforcing material on the location of the principal stress in every cross section throughout the planar structure is the least weight arrangement.

If one observes the texture of a sea shell he can justify its light structure by noticing that its "ribs" are in alignment with the compressive "Michell lines" (or the stress trajectories) of the lower arc of the structure of Figure I-B.3; where the radially spaced spokes could be carrying the hydrostatic pressure that the shell carries when the animal in it is alive and the shell stands in the upright position on the bottom of the sea.

The optimization (least weight) of structural framework is a relatively new field ever since men left the caves and started building houses and boats.

The study of the weight minimization in structural design assisted by the Finite Element Technique will efficiently arrive at revolutionary results for structural design; especially, with the increasing demand for composite materials, which are being used in nuclear submarine structural design, and where the particular matrices of the structure can be analyzed only by filamentary-type structures such as those of Maxwell's or Michell's.

APPENDICES

Appendix I-A

APPLICATION OF MAXWELL'S THEOREM AND LEMMA

Example 1.

Let us consider a truss problem, ⁽³⁾ the solution of which is given in Figure I-A.1. The external loads are 10^K , 12^K , 12^K , and 8^K , as shown. The reactions can be easily obtained either by a graphical solution or algebraically; their magnitudes are 6^K , 21.9^K and 18.1^K , and their directions are as shown.

Using either Bow's notation ⁽³⁾ or applying equilibrium of forces at each node, the tensions and the compressions acting along the rods have been found and written--the + sign indicating tension and the - sign compression.

(a) Applying Maxwell's Theorem, the equilibrium of the "small smooth rings", as the nodes are described, is undisturbed and the forces are as shown in Figure I-A.2. The internal tensile forces and the external applied loads have turned 90° counterclockwise, while all the internal compressive forces and the reactions have turned 90° clockwise.

(b) If we now apply Maxwell's Lemma to Figure I-A.2, we should have:

$$\begin{aligned} & \Sigma[\text{external and internal loads creating moments clockwise}] \\ & = \Sigma[\text{external and internal loads creating moments counterclockwise}] \end{aligned} \quad \text{[I-A.1]}$$

which is another way of interpreting equation [1.1].

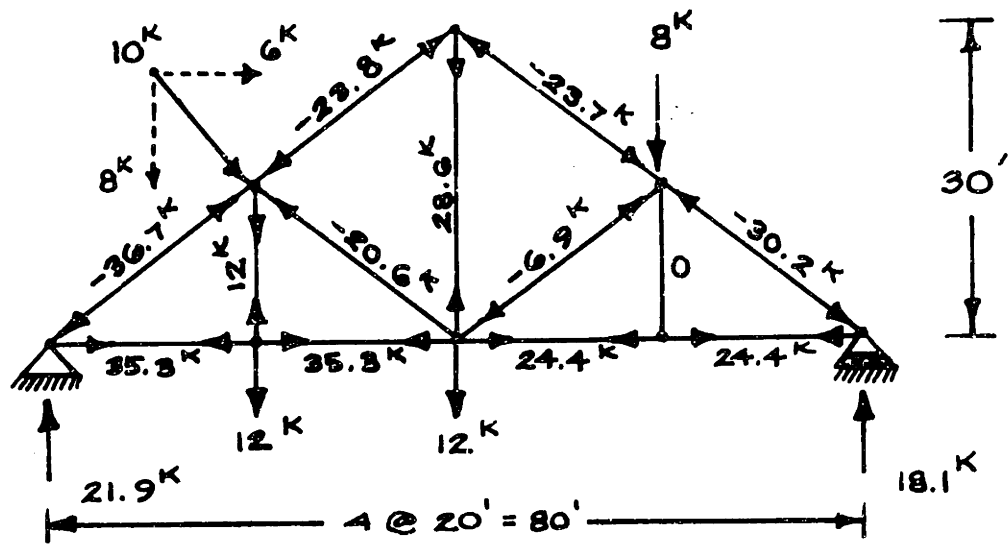


Figure I-A.1

Truss of Example 1

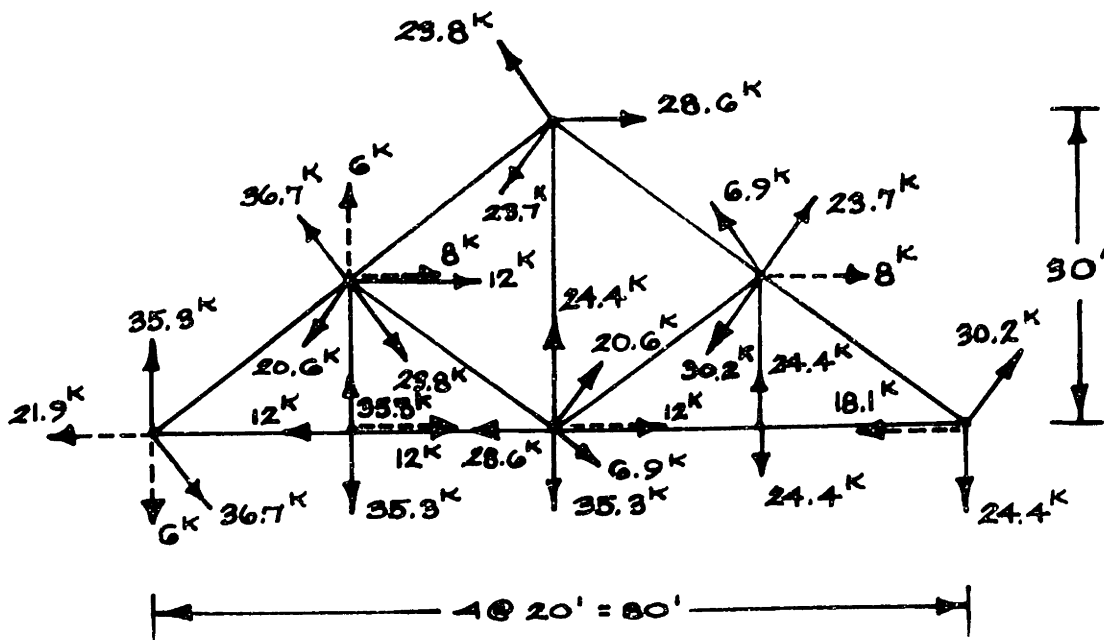


Figure I-A.2

Maxwell's Equivalent Equilibrium

Therefore:

$$\begin{aligned} \text{Left-hand-side of equation [1.1]} &= \overbrace{8^{\text{K}} \times 15' + 8^{\text{K}} \times 15'}^{\text{applied vertical forces}} \\ &\quad \underbrace{+ 35.3^{\text{K}} \times 20' + 35.3^{\text{K}} \times 20' + 24.4^{\text{K}} \times 20' + 24.4^{\text{K}} \times 20'}_{\text{internal tensile forces}} \\ &\quad \underbrace{+ 28.6^{\text{K}} \times 30'} = 240^{\text{K}\cdot\text{FT}} + 3426^{\text{K}\cdot\text{FT}} = 3,666^{\text{K}\cdot\text{FT}} \end{aligned}$$

Note that only the vertical component of the 10^{K} external applied force is considered part of the summation of the clockwise moments.

$$\begin{aligned} \text{Right-hand-side of equation [1.1]} &= \overbrace{6^{\text{K}} \times 20'}^{\text{horizontal reactions}} \\ &\quad \underbrace{+ 36.7^{\text{K}} \times 25' + 23.8^{\text{K}} \times 25' + 30.2^{\text{K}} \times 25'}_{\text{internal compressive forces}} \\ &\quad \underbrace{+ 20.6^{\text{K}} \times 25' + 6.9^{\text{K}} \times 25'} = 120^{\text{K}\cdot\text{FT}} + 3,547.5^{\text{K}\cdot\text{FT}} \\ &= 3,667.5^{\text{K}\cdot\text{FT}} \end{aligned}$$

Therefore, the two sides of equation [I-A.1] are equal as they should be according to Maxwell's Lemma. Their small discrepancy in the fourth significant digit is due to the round-off error in the calculation of the internal loads and the reactions.

Example 2.

Consider the truss of Figure I-A.3a with the applied external load vertical to the direction of bar CB.

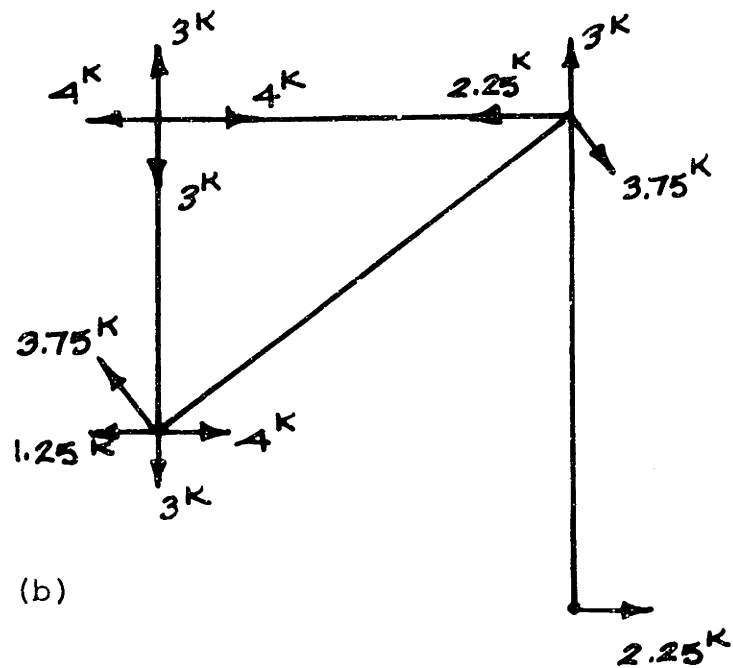
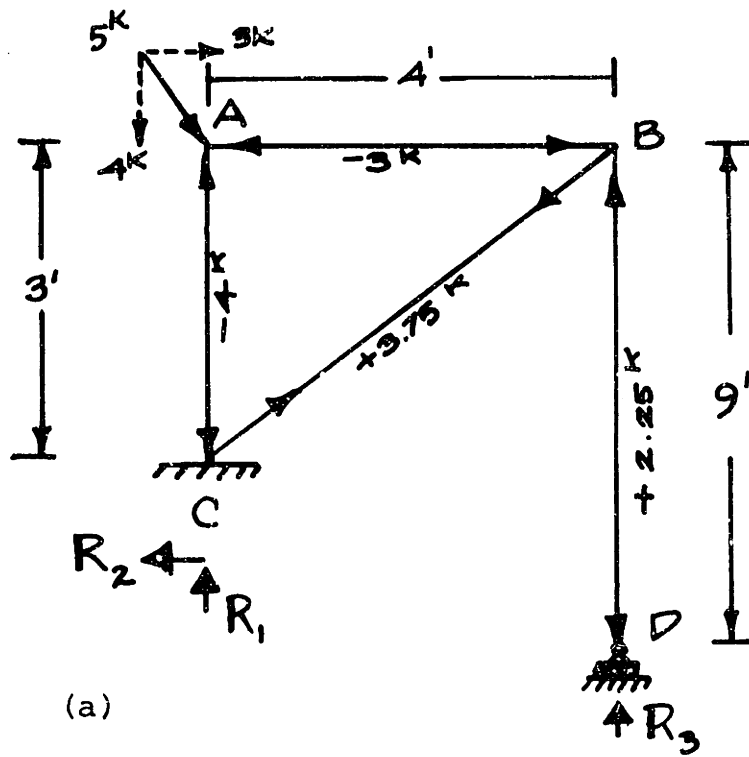


Figure I-A.3

- (a) Truss of Example 2
 (b) Maxwell's Equivalent Equilibrium

Applying equilibrium of forces and moments, we find the force reactions to be:

$$R_1 = 1.25^k$$

$$R_2 = 3^K$$

$$R_3 = 2.25^K$$

Equilibrium at each of the nodes yields the internal tensile and compressive forces as shown.

(a) Applying Maxwell's Theorem, all the forces turn 90° and create moments in the clockwise or counterclockwise direction depending on whether they are tensile or compressive, respectively, and applied or reactions, respectively (Figure I-A.3b).

(b) According to Maxwell's Lemma or equation [1.1]:

$$\begin{aligned} \text{Left-hand-side of equation [1.1]} &= \overbrace{4^K \times 3'}^{\text{applied vertical forces}} \\ &+ \overbrace{3.75^K \times 5'}^{\text{internal tensile forces}} = 12^{K \cdot FT} + 18.75^{K \cdot FT} = 30.75^{K \cdot FT} \\ \text{Right-hand-side of equation [1.1]} &= \\ &= \overbrace{-2.25^K \times 6'}^{\text{horizontal reactions}} + \overbrace{4^K \times 3' + 3^K \times 4' + 2.25^K \times 9'}^{\text{internal compressive forces}} \\ &= -13.50^{K \cdot FT} + 24^{K \cdot FT} + 20.25^{K \cdot FT} = 30.75^{K \cdot FT} \end{aligned}$$

Therefore, the left-hand-side = the right-hand-side in equation [1.1].

Notice that the first term has a negative sign to account for the height since 0 height is considered at point C.

Appendix I-B

APPLICATIONS OF THE MICHELL STRUCTURES

Example 1.

Let us assume that we have two points a distance, AB , apart and a load, P , vertical to AB and pointed at, A , which must be equilibrated by a reaction R , and a moment, M , at the other end, B .

We now want to build the optimum (least weight) structure that would equilibrate these loads. Michell provides the solution that appears in Figure I-B.1. The minimum frame is formed by two symmetric equiangular spirals about AB , which have their origin at B and intersect orthogonally at A , together with all the smaller spirals enveloped inside these two.

The circle of radius, r , about point B justifies the fact that there cannot be an infinite amount of material at B . We can imagine according to the interpretation given by R. L. Barnett⁽⁷⁾ that the cantilever is supported on a shaft of radius, r .

The least necessary volume is given by

$$V_{\text{least}} = PL \cdot \log \frac{L}{r} \left(\frac{1}{\sigma_{\text{all.T}}} + \frac{1}{\sigma_{\text{all.C}}} \right) \quad [\text{I-B.1}]$$

where $L = (AB)$.

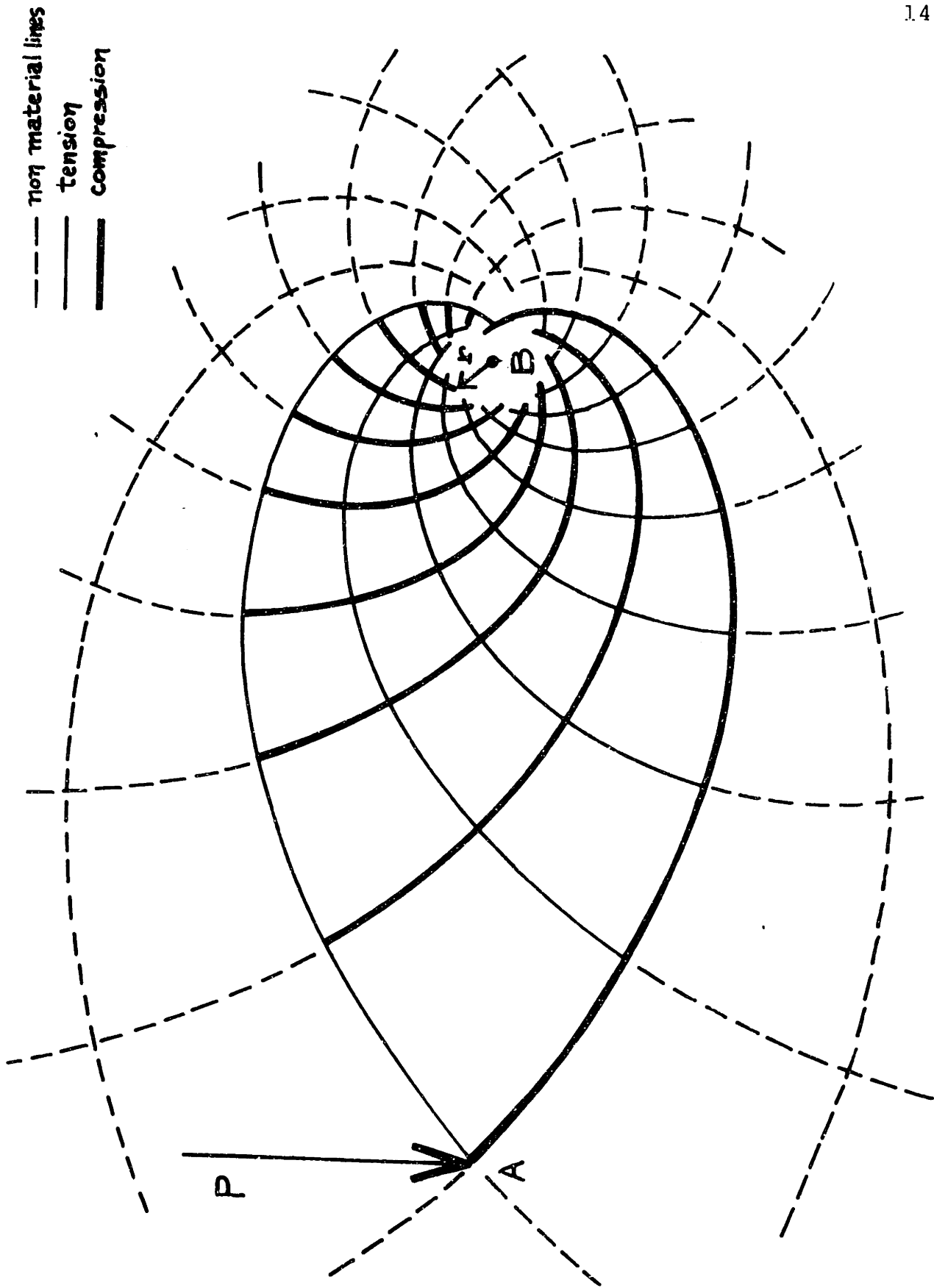


Figure I-B.1 Michell Field: Layout for a Cantilever

A comparison between the Michell Field of Figure I-B.1 and the principal stress trajectories of Figure I-B.2 reveals their similarity. Figure I-B.2 has been reproduced here for convenience from the accompanying figure of Problem 7.55 of Crandall and Dahl.⁽⁸⁾

An expansion of the first example of the Michell Field is given in detail by D. M. Richards and H. S. Y. Chan.⁽⁹⁾

Example 2.

Another least-weight structure arrangement given by Michell and expanded by H. L. Cox,⁽¹⁰⁾ and W. S. Hemp⁽⁶⁾ is the following:

Consider that we want to build a structure to support three point loads, their points lying in a straight line so that point C is at the midspan of AB. In seeking the optimum structural arrangement, Michell provides the solution shown in Figure I-B.3.

The least volume of material for the centrally loaded beam is

$$V_{\text{least}} = P \frac{L}{2} (1/2 + \pi/4) \left(\frac{1}{\sigma_{\text{all. T}}} + \frac{1}{\sigma_{\text{all. C}}} \right) \quad [\text{I-B.2}]$$

where $L/2 = AC = CB$.

Maxwell could have solved for the least volume if he knew the arrangement *a priori*. Applying equation [1.8] in Figure I-B.3, we have

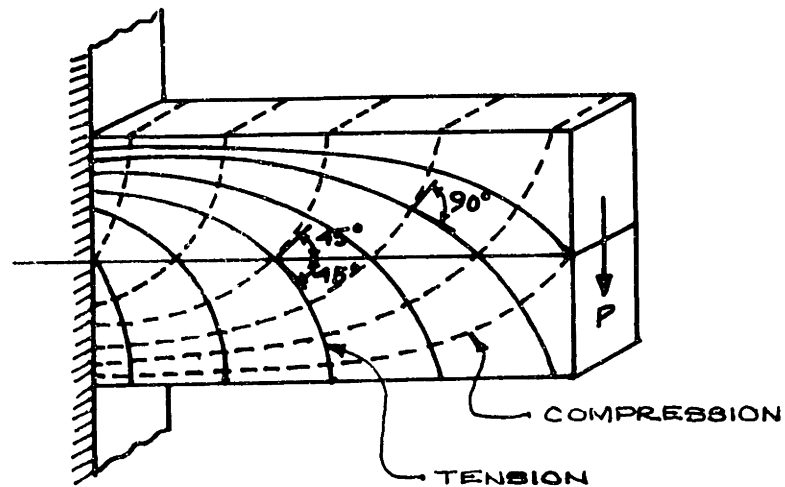


Figure I-B.2 The Principal Stress Trajectories for a Cantilever Appearing in Crandall and Dahl. (8)

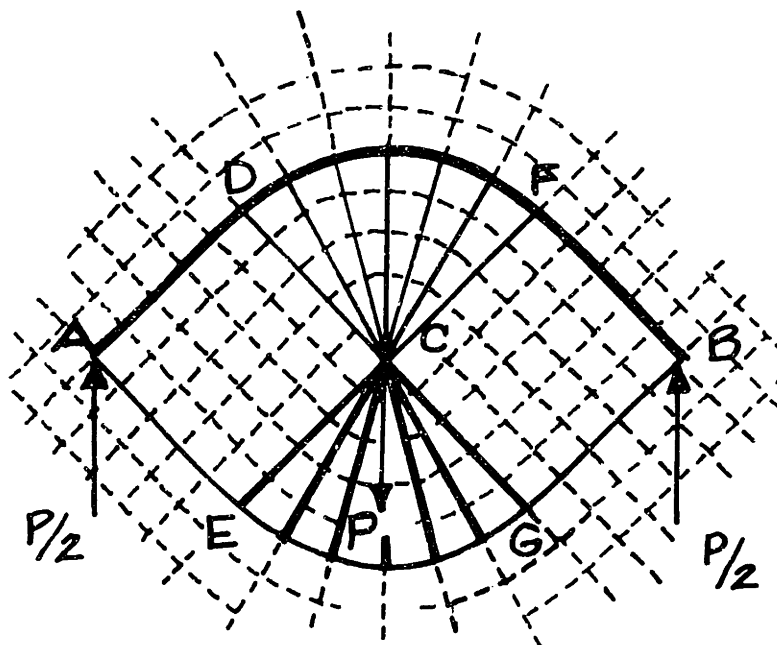


Figure I-B.3 Michell Field: Layout for a Centrally Loaded Beam

$$\begin{aligned}
V_{\text{least}} &= [(AE + EG + GB) \frac{P}{2} \cos 45^\circ + (DF) \frac{P}{2} \cos 45^\circ] \frac{1}{\sigma_{\text{all.T}}} \\
&\quad + [(AD + DE + FB) \frac{P}{2} \cos 45^\circ + (EG) \frac{P}{2} \cos 45^\circ] \frac{1}{\sigma_{\text{all.C}}} \\
&= \left[\left(\frac{L}{2\sqrt{2}} + \frac{\pi L}{4\sqrt{2}} + \frac{L}{2\sqrt{2}} \right) \frac{P}{2} \cdot \frac{\sqrt{2}}{2} + \frac{\pi L}{4\sqrt{2}} \cdot \frac{P}{2} \cdot \frac{\sqrt{2}}{2} \right] \\
&\quad \cdot \left(\frac{1}{\sigma_{\text{all.T}}} + \frac{1}{\sigma_{\text{all.C}}} \right) \\
&= \frac{LP}{2} \left(\frac{1}{2} + \frac{\pi}{4} \right) \left(\frac{1}{\sigma_{\text{all.T}}} + \frac{1}{\sigma_{\text{all.C}}} \right)
\end{aligned}$$

Q.E.D.

Notice that the terms $(DF) \frac{P}{2} \cos 45^\circ$, $(EG) \frac{P}{2} \cos 45^\circ$ represent the volume of all the radial members of the arcs \widehat{DF} and \widehat{EG} respectively. Since buckling is not considered here, the necessary material is independent of the number of spokes. Therefore, instead of taking the summation of the products of each of the spokes in quadrants DCF and ECG times their associated tensile and compressive loads which are not known, we consider the statically equivalent case: \widehat{DF} and \widehat{EG} are in tension and in compression respectively, from which we obtain $(DF) \frac{P}{2} \cos 45^\circ$ and $(EG) \frac{P}{2} \cos 45^\circ$.

If any design constraint is imposed on the second Michell example, the necessary volume will be greater than that of equation [I-B.2].

Example 2.1. Let us consider the second example again but with the constraint that all of the necessary material to equilibrate the three point loads must lie on either side of AB. Michell's solution to that problem is directly applicable to the problem of the optimum stiffening arrangement of a bicycle wheel. (See Figure I-B.4)

The least volume structure for half the wheel is easily obtained by applying equation [1.8] as before:

$$V_{\text{least}} = P \cdot \frac{L}{2} \cdot \frac{\pi}{2} \left(\frac{1}{\sigma_{\text{all. T}}} + \frac{1}{\sigma_{\text{all. C}}} \right) \quad [\text{I-B.3}]$$

Comparing the unconstrained V_{least} with that of the constrained one we see that

$$\frac{[V_{\text{least}}] \text{ constrained}}{[V_{\text{least}}] \text{ unconstrained}} = \frac{2\pi}{2 + \pi} \quad [\text{I-B.4}]$$

which implies that any imposed constraint on the arrangement of the truss members or the stiffeners for a Michell type structure increases the least possible weight of the unconstrained structure.

Furthermore, this last example illustrates well the similarity of the Michell fields with the principal stress trajectories. Although Figure I-B.5 shows reverse loading from that of Figure I-B.4, the similarity is clear. The difference being that load P is radially transmitted by the principal compressive trajectories, and the reactions are being carried by the concentric semicircular principal tensile trajectories.

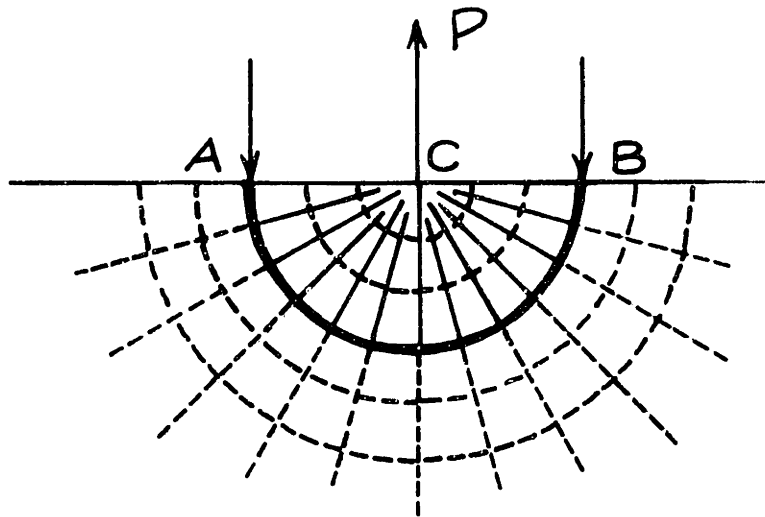


Figure I-B.4

Michell Field: Layout of a Centrally Loaded Beam,
Whose Frame Lies Completely in the
Semiplane of AB

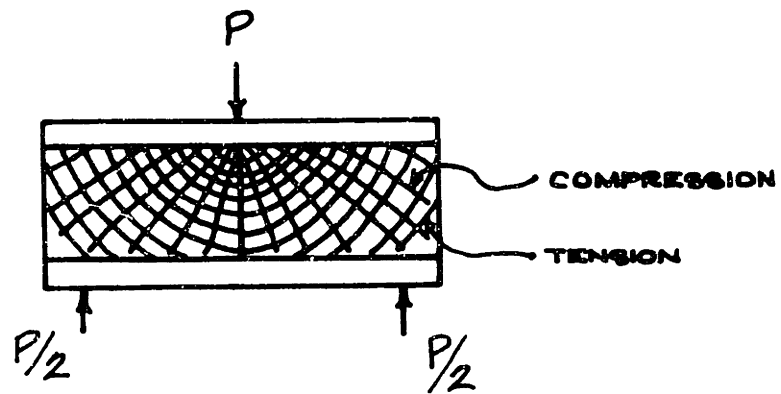


Figure I-B.5

Principal Stress Trajectories in an "I"
Beam by A. W. Hendry⁽¹¹⁾

Appendix II-A
THE COMPUTATIONAL PROCEDURE

1. Introduction

The computer program listed and explained here is written in FORTRAN IV, for the G level compiler of the IBM 360 computer model.

Its objectives, some of which have been already introduced in Part II are:

- (1) To calculate the nodal displacements $\{q\}$ from the stiffness relationship of equation [2.1].

For this calculation:

- (a) The element stiffness matrix $[K]$, as defined in Table II-2, must be assembled to give the stiffness matrix $[K]_{\text{total}}$ for the total structure.
- (b) The "force entries" $\{Q\}$ must be defined
 - (i) either from the applied concentrated forces $\{\bar{Q}\}$ or
 - (ii) from the distributed boundary loads which are converted to energy equivalent nodal forces.

- (2) To calculate the average stresses at each node.

This calculation involves:

- (a) The use of equations [2.31] and [2.32] in which the stress σ_x , σ_y , and τ_{xy} are functions

of the nodal displacements, q .

- (b) The calculation of the average stresses at each control point which is the common point of two or four elements.
- (3) To determine the points in terms of the x , y coordinates as well as the principal compressive stress at each point and for each compressive stress trajectory according to the analytical and detailed explanation given in the last section of Part II.
- (4) To plot the principal compressive stress trajectories. That is, to connect the points of each stress trajectory by straight lines and print the value of σ_2 at each point.
- (5) To reduce the stress level in the structure of a plane stress problem by increasing the thickness of each Finite Element which lies on any principal compressive stress trajectory.

Furthermore, for this purpose the program should provide the option of using one or more trajectories and not necessarily all of them. The reason is that a closely spaced number of trajectories can result in a doubling of the thickness of the original unreinforced structure. It must, for example, be capable of increasing the thickness of the elements associated with three out of nine stress trajectories, every three trajectories, that is, $j = 3$, $j = 6$,

$j = 9$ (where j is the trajectory number as defined in Figure II-3) without increasing the thickness of the elements associated with the other stress trajectories.

2. General Description--Macro Flowchart

The complete program consists of the following Main Program (MAIN) and subprograms:

a. MAIN:

(1) The geometry of the structure is defined. This involves the total number of elements to be used as well as the overall dimensions of the entire structure, the initial thickness of the structure, Young's Modulus of Elasticity and Poisson's Ratio.

Each nodal point of the structure is assigned a number starting from the lower left corner up and counting always from bottom to top.

Each element is thus defined in terms of the four nodal points (see computer printout in the Results Section). Also, each element's side may be thus defined in terms of the adjacent nodal points.

(2) The Boundary Conditions of the structure must be defined. That involves the reading in of the total number of restrained nodes in each direction as well as the particular node numbers which are restrained in the corresponding direction. (Look at the printout results for the example of a cantilever in the Results section.)

The variable NODEN, (see Nomenclature and Computer printout) is also defined in MAIN to be used later in subroutine STRESS for the calculation of the average stresses per node.

Once the Geometry and the Boundary Conditions for the entire structure have been defined, the procedure commences.

An option is given as to how many times it is desired to go through the entire procedure. That is, if NUM = 1, the procedure stops, at the most after it has accomplished the determination of all the elements which are transversed by all the stress trajectories. If NUM = 2, 3, 4, the entire procedure is repeated until a new plot of stress trajectories is obtained, corresponding to the trajectories of the reinforced structure. At this point, the program may either stop or continue until it has accomplished the determination of all the elements which are crossed through by all the new stress trajectories (see Results Section).

b. STFMTX:

In subroutine STFMTX the element's stiffness matrix is defined. Actually, all the components of BIGK(I,J) must be multiplied by the thickness THIC to give the exact components of the stiffness matrix [K] as defined by equation [2.17] and Table II-2.

c. INIT:

Subroutine INIT is a complete codified package of subroutines for the solution of a general set of linear algebraic equations of the form

$$[A]\{U\} = \{Q\} \quad [II-A,1]$$

where [A] corresponds to the assembled stiffness matrix [K]_{total}, {U} is the column matrix which contains the

unknown displacements, $\{q\}$, and $\{Q\}$ is the column matrix which contains the "force entries" per degrees of freedom as they are stored in subroutine FØRCER.

INIT is the name of the complete package of the following subroutines: INIT, SETUP, LØADER, RSTRN, and SØLVER, each of which is a step to obtain the solution of the simultaneous equations. (17)

Thus, INIT satisfies the first objective of the program which is to calculate the two displacements, q , per node for the entire structure.

d. FORCER:

In FØRCER, the applied concentrated forces or the distributed load intensities per node of action on the boundaries of the structure are read in. In the first case they are directly stored in the one-dimensional array FØRCE. Before they are destroyed, since the calculated q 's are also stored in FØRCE, they are stored in two dummy dimensional arrays FSTØRX and FSTØRY. Before the Main program calls SØLVER, where the nodal displacements q are obtained, the two forces per node column matrix $\{Q\}$, or FØRCE in this case, are printed out under the title "Force Entries Two Per Node in Order," (see computer printout for the cantilever case which is loaded on its free end by a parabolic distribution of discrete nodal forces).

In the second case, the load intensities of a distributed load per node of action are converted to energy

equivalent concentrated forces and then stored in FØRCE. Similarly to the first case, before the energy equivalent nodal forces are destroyed, they are stored in QDUMMY which is a dummy one-dimensional array. Before the displacements q are calculated for this case the equivalent forces of the one-dimensional array FØRCE are printed out under the same title as that of the first case, (see computer printout for the cantilever case which is loaded on its free end by a parabolic distribution of load).

e. STRESS

Subroutine STRESS uses the displacements $\{q\}$ to solve for the stresses $\{\sigma\}^e$, (equation [2.31] and [2.32]) at the four nodes of each element.

Starting thus with the first element, STRESS calculates the average stresses $\{\sigma\}_{\text{average}}^s$ at each node of the entire structure, (see the listing of STRESS for details).

f. TRAJEC

Subroutine TRAJEC uses the average stresses $\{\sigma\}_{\text{average}}^s$ to obtain the x, y coordinates of the principal compressive stress trajectories as well as the magnitude of the principal compressive stresses at each point (x, y) of all the trajectories.

g. PLTTRJ:

It uses the results of TRAJEC to plot the stress trajectories and includes instructions for the IBM 360 CALCØMP Plotter. (18)

h. STIFEN:

This subroutine identifies the element numbers transversed by each trajectory. These elements may be used in the Main to reduce the stress level of the entire structure if their thickness is properly increased. Thus, the structure may be stiffened along the paths of the stress trajectories.

The following Figure II-A.1 is a Macro-Flowchart which lends better understanding to the program's architecture.

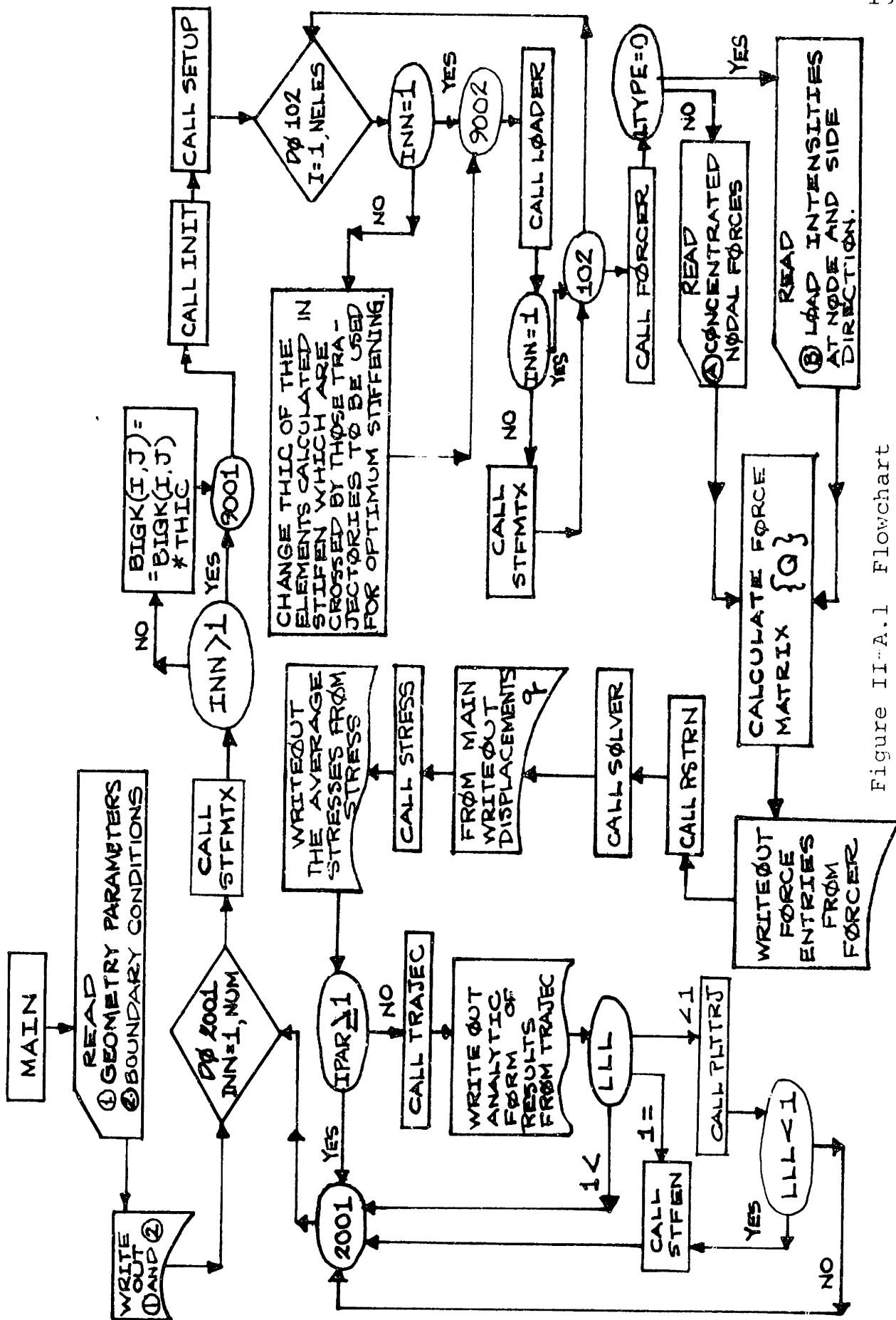


Figure II-A.1 Flowchart

3. Nomenclature and Program's Specifications

ALENX(1):

A single dimension variable indicating the length of the (rectangular) element in the x-direction. If there are more than one size of rectangular elements, then the dimension of ALENX will correspond to that number of sizes.

ALENY(1):

The same as above, but corresponding to the y-direction.

ALX:

The total length of the structure in the x-direction.

ALXX:

The length of one element in the x-direction.

ALY:

The total length of the structure in the y-direction.

ALYY:

The length of one element in the y-direction.

BIGK (IØCT, IØCT):

A doubled-dimensioned variable in which all the components of the one element stiffness matrix [K] (over the thickness t of the structure) are stored.

BIGL():

A single array defined in subroutines INIT and SETUP which is used for the storage of the lower triangle of the coefficient matrix. BIGL includes the diagonal terms. (17)

BIGU():

A single array in subroutine SETUP that is used for storage of the upper triangle of the coefficient matrix, and which does not include the diagonal terms. (17)

DET:

The determinant of the constrained stiffness matrix of the assembled structure calculated in SØLVER (see also ITEST). (17)

DX:

An argument of AXIS1⁽¹⁸⁾ called from PLTRJ indicating the number of length units in the x-direction per actual inch of plot paper to be printed out for the number labeling along the x-axis.

DY:

The same applies as in DX, but corresponds instead to the y-direction.

E:

Young's Modulus.

FØRCE(IFØRCE):

A single array corresponding to the column matrix {q} where the displacements for the entire structure are stored after they have been calculated in SØLVER and printed out from the Main program. The array must be at least the number of degrees of freedom of the total structure in length. Before the solution {q} is stored in FØRCE. FØRCE contains the "force entries" of

the entire structure, (that is, for programming economy purposes, the same memory space is used twice to store the known "force entries" and after solving for the q's to store them there). This can be achieved by means of the JORDAN Reduction Method for the solution of linear algebraic simultaneous equations.

FØRVAL(IDSTR):

- . A work vector in FØRCER dimensioned at least equal to the number of nodes of the entire structure. (see also FSTØRX, FSTØRY).

FS(IXF1):

A single array, argument of SCLGPH⁽¹⁸⁾ called by PLTTRJ and used for storage for the y-coordinates of the number of points per trajectory to be plotted.

FSTØRX(IDSTR):

The same definition applies as in FØRVAL above.

FSTØRY(IDSTR):

The same definition applies as in FØRVAL above.

FT(IT):

A work vector used in PLTTRJ which stores the maximum number of the y-coordinates of all the stress trajectories to be plotted.

HEADNG(15):

A variable of subroutine PLTTRJ in which the heading title for the plot of the principal compressive stress trajectories, is stored in an alpha-numeric field in

15 groups of four letters per group giving a 60-character range for the title.

I1KELE:

A dummy dimension variable corresponding to a maximum anticipated number of elements through which one stress trajectory passes. (see KELEM)

I2KELE:

A dummy dimension variable corresponding to the number of stress trajectories which are to be used for the reinforcing of the structure. (see KELEM)

IDIR:

A dummy dimension variable, equal to "2" in the present study, but may correspond to the number of sides in different directions that define the boundaries of a structure.

IDNØDE:

A dummy dimension variable corresponding to the number of elements in a structure. (see also NØDE)

IDST1:

A dummy dimension variable corresponding to the maximum number of stations along the x-direction on which the stresses $\{\sigma\}$ are defined for the determination of the stress trajectories.

IDST2:

A dummy dimension variable corresponding to the number of stress trajectories and is used as a second index

to distinct the stresses $\{\sigma\}$ at the same station among the different trajectories that pass through that station.

IDSTR:

A dummy dimension variable corresponding to the number of nodes of the entire structure and used in many subscripted variables.

IFØRCE:

A dummy dimension variable equal to the number of degrees of freedom of the entire structure. (see also FØRCE)

IIPØIN:

A dummy dimension variable which is equal to at least the number of trajectories of the structure. (see also IPØINT)

ILINUM:

A dummy dimension variable corresponding to twice the number of the total line segments on the boundaries of the structure.

IMPØIN:

A dummy dimension variable corresponding to the number of stress trajectories. (see also MPØINT)

INN:

The index of the big DØ loop which goes from 1 to the number of times it is desired to go through the entire procedure.

INØDEN:

A dummy dimension variable corresponding to the number of nodes of the entire structure. (see also NØDEN)

IØCT:

A dummy dimension variable corresponding to the number of vertical or horizontal components of the stiffness matrix for one element.

IPAR:

A code variable which, if zero, the program goes through the calculation of the stress trajectories; if one, the program stops with the calculation of the average stresses at each node of the structure.

IPØINT (IIPØIN):

A single dimension variable which stores the number of y-coordinates per trajectory.

IT:

A dummy dimension variable equal to the total number of the x, y-coordinates of all the stress trajectories which at the most will equal the number of nodes of the structure.

ITEST:

A code which is defined to be zero for no calculation of the determinant in subroutine SØLVER. (17)

IVCT(4):

A single array used in the Main program and subroutines INIT, LOADER as an array of master node numbers for the

element and is number of nodes/element in length. (17)

IWORK():

A work vector at least equal to the number of degrees of freedom of the total structure and is used in sub-routines INIT and SETUP. (17)

IXF1:

A dummy dimension variable corresponding to the number of stations along the x-direction on which the y-final coordinates of the stress trajectories are calculated.

IXF2:

A dummy dimension variable equal to the number of stress trajectories.

JSTFN:

The number of trajectories associated with the stiffening of the structure. There can be used less trajectories than these plotted for the best stiffening of the structure.

JTEST:

A code variable which equals zero for no dumping of pointer data in SETUP. (17)

JWORK():

A work vector equal at least to the number of degrees of freedom of the total structure used in INIT and SETUP.

KELEM(I1KELE, I2KELE):

A two-dimensional array which defines the element number associated with each stress trajectory.

KKWØRK(4):

A single array used in INIT and LØADER as a vector which contains the number of degrees of freedom at each node of the element. It must be dimensioned according to the number of nodes per element.

KWØRK(4):

A work vector in LØADER at least the number of nodes per element long.

KEXPX:

An argument of AXIS1 called from PLTTRJ which specifies the exponent to be printed on the label of the x-scale, (that is, if the label is desired in the form $N \times 10$ KEXPX where N is the number to be printed out.)

KEXPY:

Same as KEXPX, but defines the exponent of the y-scale.

LIL:

A code variable which, if equal to zero, the program goes through STIFFEN after having plotted the stress trajectories. If equal to 1, it skips the subroutine.

LINUM(ILINUM):

A one-dimension array variable corresponding to the number of line segments which are subjected to boundary loads; that is, if both normal and shear distributed loads are exerted only on one line segment on the boundary of the structure LINUM could be dimensioned "2". The dimension ILINUM corresponds to twice the

maximum possible number of boundary line segments under distributed loads.

LLL:

A code variable which, if equal to zero, the program plots the stress trajectories; if equal to one, skips plotting and goes through STIFEN; if greater than one, the program stops.

LTYPE:

A code variable in FØRCER which, if zero, the distributed boundary loads are converted to the *energy equivalent* nodal forces and stored in FØRCE, that is, in matrix {Q}; if it is equal to one, the *concentrated* nodal forces are stored in FØRCE.

MARCH:

The number equal to the j^{th} trajectory from which the stiffening of the structure, by increasing the thicknesses of the element associated with each trajectory, commences. (see Main and subroutine STIFEN)

MPØINT (IMPØIN):

A single dimension variable which stores the number of elements associated with each trajectory, the thickness of which must be increased for the stiffening of the structure.

MTAP:

Is a READ input code variable and should equal "five" if the program runs in the IBM 360 computer.

NBD1:

Total number of restrained nodes in the x-direction.

NBC2:

Total number of restrained nodes in the y-direction.

NCØL:

A single array variable used in INIT; a vector of column numbers of the first non zero entry in each row of the assembled matrix. It must be dimensioned at least the number of degrees of freedom of the entire structure. (17)

NCR:

Total number of restrained nodes in both x and y directions.

NCRT():

A single dummy dimension array (used in MAIN) in which the nodes constrained in the x-direction and the y-direction are stored beginning with these in the x-direction. (17)

NDIGX:

An argument of AXIS1 called from PLTTRJ and representing the number of digits after the decimal point to be printed on the label of the x-scale.

NDIGY:

The same definition as for NDIGX, applying instead to the y-scale.

NDØF:

The number of degrees of freedom of the entire structure.

NELEM:

The current number of elements used to assign the node numbers associated with each element.

NELES:

The total number of elements of the entire structure.

NFØRX:

Total number of concentrated forces acting on the nodes of the structure in the x-direction.

NFØRY:

Same definition as for NFØRX, but applying to the y-direction.

NLIN:

Total number of line segments between nodes in the structure.

NLINE(NLIN, IDIR):

A double dimension array which gives the two nodal points for each line segment of the structure. (that is, if for line segment 1, NLINE(1, 1) is 1; and NLINE(1, 2) is 2.

NNØDEN:

Total number of nodal points associated with the boundary line segments of the structure on which the intensity of a normal distributed load on the boundary

is specified.

NNØDES:

The same as NNØDEN, but referring to a shear distributed load.

NØ:

(In subroutine FØRCER) indicates whether the load intensity (in the case of distributed loads) is on a horizontal side of the structure, in which case it is equal to one; or on a vertical side, where it is equal to two.

NØDAT:

Specifies the node at which the intensity of a distributed load is applied.

NØDE (, 4):

A two-dimensional array whose first dimension corresponds to the number of elements of a structure, and the second to the number of nodes per element. Notice that in the example printout for a cantilever, the two-dimensional array has a heading: "NØDE(4)".

NØDEN ():

A one-dimensional array which specifies the number of elements which are common to every nodal point of the structure per nodal point.

NØDES:

Total number of nodes or control points of the structure.

NØDLS(, 4):

A double array variable that identifies numerically the sides of each element. (That is, for element No. 1 of a 250-element structure, the left vertical side is No. 1; the lower horizontal is No. 261; the right vertical is No. 11; and the upper horizontal is No. 262. The second dimension refers to the four sides of each rectangular element.

NØDST():

A work vector in INIT equal to at least the number of degrees of freedom of the total structure in length.

NØDX(IDSTR):

A one-dimension variable that stores the node number of the structure on which the concentrated load acts in the x-direction. IDSTR represents the maximum possible dimension.

NPAGES:

The first READ input variable of PLTRRJ and refers to the number of "pages" on which the trajectories will be plotted. In the present case, since we request one plot of the total number of stress trajectories, NPAGES = 1. However, if in the future the principal tensile stress trajectories need to be plotted on a different "page" or graph, NPAGES will be "2", etc.

NSS:

The total number of line segments in the y-direction.

NSTAS:

The number of stations or control points in the y-direction.

NSTAT:

The number of stations in the x-direction.

NSTRN():

An output code which, when defined to be "6", the results of the program are printed out; when "7", the results are punched in computer cards.

NU:

Poisson's ratio.

NUM:

The upper limit of IIN. If defined to be greater than "1", the program will go through the entire procedure twice or more times; it is expected that each time it must pass through subroutine STIFEN.

NUMLNN:

An integer read as INPUT in subroutine FØRCER which corresponds to the line segments on the boundaries of the structure which are subjected to normal distributed loads.

NUMLNS:

Read as input in the same card with NUMLNN, and which corresponds to the number of line segments on the boundaries of the structure which are subjected to shear distributed loads.

QDUMMY (IFORCE) :

A dummy column vector where the "force entries" are stored from FØRCE so that when the solution for the displacements, q , will be stored in FØRCE, the "force entries" will not be destroyed.

RHO:

The ratio by which the thickness of the elements to be used for the reinforcement of the structure will increase. The elements are identified in STIFEN, but the reinforcement involves computations in the Main.

S (IXF1) :

A single array argument of SCLGPH⁽¹⁸⁾ called by PLTRJ and used for storage for the x-coordinates of the number of points per trajectory to be plotted.

SIGMA2 (IDST1, IDST2) :

Represents the principal compressive stress calculated at each point of the stress trajectories along the x-direction.

STRX (IDSTR) :

Indicates the average σ_x stress at each node of the structure.

STRY (IDSTR) :

The average σ_y as above.

STRXY (IDSTR) :

The average σ_{xy} as above.

STRX1:

- (1) As defined in STRESS corresponds to equation [2.32.1].
- (2) As defined in TRAJEC corresponds to the interpolated value of stress for point P_1 (see Figure II-3).

STRX2:

The σ_{x_2} according to equation [2.32.2].

STRX3:

The σ_{x_3} according to equation [2.32.3].

STRY1:

- (1) In STRESS it is defined according to equation [2.32.4].
- (2) In TRAJEC it represents the corresponding σ_{y_1} for point 1.

STRY2:

Defined according to equation [2.32.5].

STRY3:

Defined according to equation [2.32.6].

STRXY1:

- (1) In STRESS it is defined according to equation [2.32.7].
- (2) In TRAJEC it represents the associated σ_{xy_1} for the intermediate extrapolation point P_1 .

STRXY2:

Defined according to equation [2.32.8].

STRXY3:

Defined according to equation [2.32.9].

STX(IDST1, IDST2):

Corresponds to the σ_x stress at each (x, y) point for each trajectory.

STY(IDST1, IDST2):

Same as STX but corresponds to σ_y .

STXY(IDST1, IDST2):

Same as STY but corresponds to σ_{xy} .

T(IT):

A dummy one-dimension array used in PLTTRJ which stores the maximum number of the x-coordinates of all the stress trajectories.

THIC:

The thickness of the plate t.

TIT(IT):

A single dimension dummy array used for the storage of all the σ_2 (SIGMA2) principal stresses from which their values are printed out adjacent to the y-coordinates of all plotted stress trajectories in PLTTRJ.

TN(IDSTR, IDIR):

A two-dimension array which stores the intensities of a normal distribution of load; the first dimension refers to the node number at which the intensity is

applied and the second to the direction number of the boundary side of the structure. (see NØDAT, NØ)

TS(IDSTR, IDIR):

The same definition applies as in TN except that the array stores the intensities of a shear distribution of load.

X:

- (1) In STRESS it represents the length of an element in the x-direction.
- (2) In PLTTRJ it represents the number of inches the origin is set away from the left side of the page.

XF(IXF1, IXF2):

Two-dimensional array which stores the final x-coordinates for each trajectory.

Y:

- (1) In STRESS it represents the length of an element in the y-direction.
- (2) In PLTTRJ it represents the number of inches the origin is set from the bottom of the page.

YF(IXF1, IXF2):

The same as in XF, but storing the y-coordinates for each trajectory.

YY:

Equal to $E/(1 - \nu^2)$.

YXZERØ:

Used as an argument in subroutine SCLGPH which is called

from PLTTRJ, it represents the value on the y-axis at the origin.

ZZ:

Equal to $(1 - v)/2$.

4. Computer Program Listing

MAIN0001
MAIN0002
MAIN0003
MAIN0004
MAIN0005
MAIN0006
MAIN0007
MAIN0008
MAIN0009
MAIN0010
MAIN0011
MAIN0012
MAIN0013
MAIN0014
MAIN0015
MAIN0016
MAIN0017
MAIN0018
MAIN0019
MAIN0020
MAIN0021
MAIN0022
MAIN0023
MAIN0024
MAIN0025
MAIN0026
MAIN0027
MAIN0028
MAIN0029
MAIN0030
MAIN0031
MAIN0032
MAIN0033
MAIN0034
MAIN0035
MAIN0036

C *****
C *****
C *****

MAIN PROGRAM

C *****
C *****
C *****
C *****

LIST EXPLICIT STATEMENTS

REAL NU

LIST COMMON STATEMENTS

COMMON/A/ I DNODE, INDDEN, IFORCE, IMPOIN, I1KELE, I2KELE, IDSTR, IDST1,
1 IDST2, IXF1, IXF2, IT, I IPOIN, I LINUM, NLIN, I DIR, IOCT, NTAP, MTAP

LIST DIMENSION STATEMENTS

DIMENSION NODLS(250,4), NODST(572), KWK(4), BIGU(23500), BIGL(23500)
1, IWORK(572), JWORK(572), FORCE(572), NODE(250,4), IVCT(4), NSTRN(100),
2NCOL(572), NCRT(100), KWK(4), ALENX(1), ALENY(1), BIGK(8,8),
3NDDEN(300), MPOINT(11), KELEM(50,11), STRX(286), STRY(286), STRXY(286),
4STX(26,11), STY(26,11), STXY(26,11), XF(26,11), YF(26,11), T(286),
5FT(286), IPOINT(26), S(26), FS(26), NODX(286), FJVAL(286), FSTORX(286),
6NODY(286), FSTORY(286), SIGMA2(26,11), TIT(286), NLINE(535,2),
7 LINUM(140), TN(286,2), TS(286,2)

LIST FORMAT STATEMENTS

2 FORMAT(10I5)
4 FORMAT(8F10.4)
22 FORMAT(, I5, /, , NUMBER OF SEQUENCE = , I5, /, , NUMBER OF ELEMENTS
2 = , I5, /, , NUMBER OF NODES = , I5, /, , NSS = , I5, /,
3 , NUMBER OF LINES = , I5)
80 FORMAT(50I1)

C
C
C


```

C      READ(MTAP,4848) IDNJDE, INODEN, IFORCE, IMPOIN, I1KELE, I2KELE, IDSTR,
C      1 IDST1, IDST2, IXF1, IXF2, IT, IIPAIN, ILINUM, NLIN, IDIR, IDCT
C      READ(MTAP,4444) IPAR, MARCH, JSTFN, LOC, LLL, LIL, RHD
C      READ (MTAP,2) NUM, NSTAS, NSTAT
C      READ(MTAP,4) THIC,E,NU
C      READ (MTAP,4) ALX,ALY
C
C      CALCULATE NUMBER OF ELEMENTS IN T (X-DIRECTION)
C      CALCULATE NUMBER OF ELEMENTS IN S (Y-DIRECTION)
C
C      NSTAT1=NSTAT-1
C      NSTAS1=NSTAS-1
C
C      NSS IS THE MAXIMUM NUMBER OF LINES OF ELEMENTS IN S
C
C      NSS=NSTAS1*NSTAT
C
C      NODES IS THE TOTAL NUMBER OF NODES OF THE STRUCTURE
C
C      NODES=NSTAS*NSTAT
C
C      CALCULATE THE TOTAL NUMBER OF DEGREES OF FREEDOM OF THE STRUCTURE
C
C      NDOF=NODES*2
C
C      CALCULATE THE TOTAL NUMBER OF LINES OF THE STRUCTURE
C
C      NLIN=NSS+NSTAT1*NSTAS
C
C      TOTAL NUMBER OF FINITE ELEMENTS
C
C      NELES=NSTAT1*NSTAS1
C
C      LENGTH OF EACH ELEMENT IN X AND Y DIRECTIONS
C
C      ALY=ALY/NSTAS1

```

```

MAIN0073
MAIN0074
MAIN0075
MAIN0076
MAIN0077
MAIN0078
MAIN0079
MAIN0080
MAIN0081
MAIN0082
MAIN0083
MAIN0084
MAIN0085
MAIN0086
MAIN0087
MAIN0088
MAIN0089
MAIN0090
MAIN0091
MAIN0092
MAIN0093
MAIN0094
MAIN0095
MAIN0096
MAIN0097
MAIN0098
MAIN0099
MAIN0100
MAIN0101
MAIN0102
MAIN0103
MAIN0104
MAIN0105
MAIN0106
MAIN0107
MAIN0108

```

```

C
C
C
ALXX=ALX/NSTAT1
ALENX(1)=ALXX
ALENY(1)=ALYY
OUTPUT
WRITE (NTAP, 22) NUM, NELES, NNODES, NSS, NLIN
WRITE (NTAP, 6050) THIC, E, NU
WRITE(NTAP, 6799)
WRITE(NTAP, 105) ALENX(1), ALENY(1)
DO 50 NTN=1, NSTAT1
DO 50 NSN=1, NSTAS1
NTN1=NTN-1
NSN1=NSN-1
NELEM=NSTAS1*NTN1+NSN
C
C
C
C
CALCULATE THE FOUR NODE NUMBERS OF EACH ELEMENT CORRESPONDING TO
THE STRUCTURE NODE NUMBERS
NODE(NELEM, 1)=NSTAS*NTN1+NSN
NODE(NELEM, 2)=NSTAS*NTN +NSN
NODE(NELEM, 3)=NSTAS*NTN +NSN+1
NODE(NELEM, 4)=NSTAS*NTN1+NSN+1
C
C
C
C
CALCULATE THE FOUR EDGE NUMBERS OF EACH ELEMENT CORRESPONDING
TO THE LINE NUMBERS OF THE STRUCTURE
NODLS(NELEM, 1)=NSS+NSTAS*NTN1+NSN
NODLS(NELEM, 3)=NODLS(NELEM, 1)+1
NODLS(NELEM, 2)=NSTASI*NTN+NSN
NODLS(NELEM, 4)=NSTASI*NTN1+NSN
C
C
C
C
CALCULATE THE TWO NODE NUMBERS OF EACH LINE CORRESPONDING
TO THE NODE NUMBERS OF THE STRUCTURE
NLINE(NODLS(NELEM, 1), 1)=NODE(NELEM, 1)

```

```

MAIN0109
MAIN0110
MAIN0111
MAIN0112
MAIN0113
MAIN0114
MAIN0115
MAIN0116
MAIN0117
MAIN0118
MAIN0119
MAIN0120
MAIN0121
MAIN0122
MAIN0123
MAIN0124
MAIN0125
MAIN0126
MAIN0127
MAIN0128
MAIN0129
MAIN0130
MAIN0131
MAIN0132
MAIN0133
MAIN0134
MAIN0135
MAIN0136
MAIN0137
MAIN0138
MAIN0139
MAIN0140
MAIN0141
MAIN0142
MAIN0143
MAIN0144

```



```

C      ALXX=ALX/NSTAT1
C      ALENX(1)=ALXX
C      ALENY(1)=ALYY
C      OUTPUT
C      WRITE (NTAP, 22) NUM, NELES, NNODES, NSS, NLIN
C      WRITE (NTAP, 6050) THIC, E, NU
C      WRITE(NTAP, 6799)
C      WRITE(NTAP, 105) ALENX(1), ALENY(1)
C      DO 50 NTN=1, NSTAT1
C      DO 50 NSN=1, NSTASI
C      NTN1=NTN-1
C      NSN1=NSN-1
C      NELEM=NSTASI*NTN1+NSN
C      CALCULATE THE FOUR NODE NUMBERS OF EACH ELEMENT CORRESPONDING TO
C      THE STRUCTURE NODE NUMBERS
C      NODE(NELEM, 1)=NSTAS*NTN1+NSN
C      NODE(NELEM, 2)=NSTAS*NTN +NSN
C      NODE(NELEM, 3)=NSTAS*NTN +NSN+1
C      NODE(NELEM, 4)=NSTAS*NTN1+NSN+1
C      CALCULATE THE FOUR EDGE NUMBERS OF EACH ELEMENT CORRESPONDING
C      TO THE LINE NUMBERS OF THE STRUCTURE
C      NODLS(NELEM, 1)=NSS+NSTAS*NTN1+NSN
C      NODLS(NELEM, 3)=NODLS(NELEM, 1)+1
C      NODLS(NELEM, 2)=NSTASI*NTN+NSN
C      NODLS(NELEM, 4)=NSTASI*NTN1+NSN
C      CALCULATE THE TWO NODE NUMBERS OF EACH LINE CORRESPONDING
C      TO THE NODE NUMBERS OF THE STRUCTURE
C      NLINE(NODLS(NELEM, 1), 1)=NODLS(NELEM, 1)

```

```

MAIN0109
MAIN0110
MAIN0111
MAIN0112
MAIN0113
MAIN0114
MAIN0115
MAIN0116
MAIN0117
MAIN0118
MAIN0119
MAIN0120
MAIN0121
MAIN0122
MAIN0123
MAIN0124
MAIN0125
MAIN0126
MAIN0127
MAIN0128
MAIN0129
MAIN0130
MAIN0131
MAIN0132
MAIN0133
MAIN0134
MAIN0135
MAIN0136
MAIN0137
MAIN0138
MAIN0139
MAIN0140
MAIN0141
MAIN0142
MAIN0143
MAIN0144

```

MAIN0145
 MAIN0146
 MAIN0147
 MAIN0148
 MAIN0149
 MAIN0150
 MAIN0151
 MAIN0152
 MAIN0153
 MAIN0154
 MAIN0155
 MAIN0156
 MAIN0157
 MAIN0158
 MAIN0159
 MAIN0160
 MAIN0161
 MAIN0162
 MAIN0163
 MAIN0164
 MAIN0165
 MAIN0166
 MAIN0167
 MAIN0168
 MAIN0169
 MAIN0170
 MAIN0171
 MAIN0172
 MAIN0173
 MAIN0174
 MAIN0175
 MAIN0176
 MAIN0177
 MAIN0178
 MAIN0179
 MAIN0180

```

    NL INE(NODLS (NELEM, 1), 2) = NODE (NELEM, 2)
    NL INE(NODLS (NELEM, 2), 1) = NODE (NELEM, 2)
    NL INE(NODLS (NELEM, 2), 2) = NODE (NELEM, 3)
    NL INE(NODLS (NELEM, 3), 1) = NODE (NELEM, 4)
    NL INE(NODLS (NELEM, 3), 2) = NODE (NELEM, 3)
    NL INE(NODLS (NELEM, 4), 1) = NODE (NELEM, 1)
    NL INE(NODLS (NELEM, 4), 2) = NODE (NELEM, 4)
  50 CONTINUE
C
C BOUNDARY CONDITIONS
C
    WRITE (NTAP, 1352)
    READ (MTAP, 1102) NBC1
    IF ( NBC1 .EQ. 0 ) GO TO 701
    READ (MTAP, 1102) (NCRT(IX), IX=1, NBC1)
    WRITE (NTAP, 1150) NBC1, (NCRT(IX), IX=1, NBC1)
  701 READ (MTAP, 1102) NBC2
    IF ( NBC2 .EQ. 0 ) GO TO 702
    READ (MTAP, 1102) (NCRT(IX+NBC1), IX=1, NBC2)
    WRITE (NTAP, 1150) NBC2, (NCRT(IX+NBC1), IX=1, NBC2)
  702 NX12 = NBC1 + NBC2
    NCR = NBC1 + NBC2
    WRITE (NTAP, 1150) (NCRT(IX), IX=1, NCR)
    IF ( NBC1 .EQ. 0 ) GO TO 801
    DO 1780 IX=1, NBC1
    NSTRN(IX) = (NCRT(IX) - 1) * 2 + 1
  1780 CONTINUE
  801 CONTINUE
    IF ( NBC2 .EQ. 0 ) GO TO 802
    DO 1781 IX=1, NBC2
    NSTRN(IX+NBC1) = (NCRT(IX+NBC1) - 1) * 2 + 2
  1781 CONTINUE
  802 CONTINUE
C
C NODEN
C
    DO 60 NSN=1, NSTAS
    DO 60 NTN=1, NSTAT
  
```

```

MAIN0181
MAIN0182
MAIN0183
MAIN0184
MAIN0185
MAIN0186
MAIN0187
MAIN0188
MAIN0189
MAIN0190
MAIN0191
MAIN0192
MAIN0193
MAIN0194
MAIN0195
MAIN0196
MAIN0197
MAIN0198
MAIN0199
MAIN0200
MAIN0201
MAIN0202
MAIN0203
MAIN0204
MAIN0205
MAIN0206
MAIN0207
MAIN0208
MAIN0209
MAIN0210
MAIN0211
MAIN0212
MAIN0213
MAIN0214
MAIN0215
MAIN0216

```

```

NTN1=NTN-1
NSN1=NSN-1
NN=NSTAS*NTN1+NSN
60 NODEN(NN)=4
DO 61 I=1,NSTAS
  NODEN(I)=2
  J=I+NSTAT1*NSTAS
61 NODEN(J)=2
DO 11 J=1,NSTAT
  K=NSTAS*(J-1)+1
  NODEN(K)=2
  K=NSTAS*(J-1)+NSTAS
11 NODEN(K)=2
  NODEN(I)=1
  NODEN(NSTAS)=1
  NODEN(NODES)=1
  NODEN(NSTAS*NSTAT1+1)=1
C
C DO 2001 GOES THROUGH THE WHOLE PROGRAM ONCE OR MORE THAN ONCE
C DEPENDING ON WHETHER IT IS DESIRED TO SEE THE EFFECTS OF
C THE REINFORCING STIFFENERS OR NOT
C
C DO 2001 INN=1,NUM
C
C IM=1 SINCE ALL ELEMENTS HAVE THE SAME GEOMETRY AND HENCE STIFFENES.
C
C IM=1
C
C YY AND ZZ ARE CONSTANTS USED IN OBTAINING THE ELEMENTS OF
C THE STIFFNESS MATRIX
C
C YY=E/(1.-NU**2)
C ZZ=(1.-NU)/2.
C CALL STFM TX(BIGK,YY,ZZ,IM,NU,ALENX,ALENY)
C IF(INN.NE.1) GO TO 9001
C DO 9000 I=1,8

```

MAIN0217
 MAIN0218
 MAIN0219
 MAIN0220
 MAIN0221
 MAIN0222
 MAIN0223
 MAIN0224
 MAIN0225
 MAIN0226
 MAIN0227
 MAIN0228
 MAIN0229
 MAIN0230
 MAIN0231
 MAIN0232
 MAIN0233
 MAIN0234
 MAIN0235
 MAIN0236
 MAIN0237
 MAIN0238
 MAIN0239
 MAIN0240
 MAIN0241
 MAIN0242
 MAIN0243
 MAIN0244
 MAIN0245
 MAIN0246
 MAIN0247
 MAIN0248
 MAIN0249
 MAIN0250
 MAIN0251
 MAIN0252

```

DO 9000 J=I,8
BIGK(I,J)=BIGK(I,J)*THIC
9000 BIGK(J,I)=BIGK(I,J)
9001 KKWRK(1)=2
KKWRK(2)=2
KKWRK(3)=2
KKWRK(4)=2
DO 101 I=1,NELES
IVCT(1)=NODE(I,1)
IVCT(2)=NODE(I,2)
IVCT(3)=NODE(I,3)
IVCT(4)=NODE(I,4)
CALL INIT ( NDOF,NCOL,IVCT,KKWRK,IWORK,4,NODST,I,NELES,BIGL)
101 CONTINUE
CALL SETUP (BIGU,BIGL,FORCE,IWORK,JWORK,JTEST,6)
DO 102 I=1,NELES
IF(INN.EQ.1) GO TO 9002
ATHIC=THIC
DO 899 JTRAJ=MARCH,JSTFN,LOC
MELEM=MPOINT(JTRAJ)
DO 898 IELEM=1,MELEM
IF(I-KELEM(IELEM,JTRAJ))898,821,898
898 CONTINUE
899 CONTINUE
GO TO 820
821 ATHIC=RHO*THIC
820 DO 9020 K=1,8
DO 9020 J=K,8
BIGK(K,J)=BIGK(K,J)*ATHIC
9020 BIGK(J,K)=BIGK(K,J)
9002 KKWRK(1)=2
KKWRK(2)=2
KKWRK(3)=2
KKWRK(4)=2
IVCT(1)=NODE(I,1)
IVCT(2)=NODE(I,2)

```

```

IVCT(3)=NDECE(I,3)
IVCT(4)=NDECE(I,4)
CALL LCADER ( 8,4,BIGK,KKWRK,IVCT,KKCRK)
IF(INN.EQ.1) GO TO 102
CALL STFMTX(BIGK,YY,ZZ,IM,NU,ALENX,ALENY)
102 CONTINUE
CALL FRCRER(FORCE,INN,NDOF,NODX,FORVAL,FSTORX,NODY,FSTCRY,
1 ALENX,ALENY,NLINE,NSS,ODUMMY,NCEDES,NSTAS,NSTAT,NSTASI,NSTAT1,
2 LINUM,TN,TS)
CALL RSTRN (NSTRN,NCR)
CALL SCLVER (DET,ITEST)
WRITE(NTAP,859) DET
WRITE (NTAP,5866)
DO 7777 KK=1,NODES
K2=(KK-1)*2+1
K3=KK*2
7777 WRITE(NTAP,8888) KK,FORCE(K2),FRCRCE(K3)
C FORCE CALCULATION FROM THE DISPLACEMENTS GOES HERE
CALL STRESS(NELES,NODE,FORCE,ALXX,ALYY,NODES,NU,ZZ,YY,NODEN,STRX,
1 STRY,STRXY)
IF(IPAR-1) 13,2001,2001
13 CALL TRAJEC(STRX,STRY,STRXY,ALXX,ALYY,ALY,STX,STY,STXY,XF,YF,
2NSTAS,NSTAT1,T,FT,IPOINT,MPTS,TIT,SIGMA2)
IF(LL-1) 7,8,2001
7 CALL PLTRJ(T,FT,IPOINT,NSTAS,MPTS,S,F,S,TIT)
IF(LIL-1) 8,2001,2001
8 CALL STIFEN(XF,YF,NSTAS,NSTASI,ALXX,ALYY,IPOINT,MPOINT,KELEM)
2001 CONTINUE
CALL EXIT
END

```

```

MAIN0253
MAIN0254
MAIN0255
MAIN0256
MAIN0257
MAIN0258
MAIN0259
MAIN0260
MAIN0261
MAIN0262
MAIN0263
MAIN0264
MAIN0265
MAIN0266
MAIN0267
MAIN0268
MAIN0269
MAIN0270
MAIN0271
MAIN0272
MAIN0273
MAIN0274
MAIN0275
MAIN0276
MAIN0277
MAIN0278
MAIN0279
MAIN0280
MAIN0281
MAIN0282

```

```

STFM0001
STFM0002
STFM0003
STFM0004
STFM0005
STFM0006
STFM0007
STFM0008
STFM0009
STFM0010
STFM0011
STFM0012
STFM0013
STFM0014
STFM0015
STFM0016
STFM0017
STFM0018
STFM0019
STFM0020
STFM0021
STFM0022
STFM0023
STFM0024
STFM0025
STFM0026
STFM0027
STFM0028
STFM0029
STFM0030
STFM0031
STFM0032
STFM0033
STFM0034
STFM0035
STFM0036

SUBROUTINE STFM TX(BIGK,YY,ZZ,IM,NU,ALENX,ALENY)
COMMON/A/ I DNODE,INODEN,IFORCE,I MPOIN,I I KELE,I 2KELE, IDSTR, IDST1,
1 IDST2, I XF1, IXF2, IT, I IPOIN, I L INUM, N L IN, I DIR, IOCT, NTAP, MTAP
REAL NU
DIMENSION BIGK(IOCT, IOCT), ALENX(1), ALENY(1)
BIGK(1,1)=YY*(ALENY(IM))/(3.*ALENX(IM))+ (ALENX(IM))/(3.*ALENY(IM))
1*ZZ)
BIGK(1,2)=YY*((NU+1.)/8.)
BIGK(1,3)=YY*(-ALENY(IM))/(ALENX(IM)*3.)+(ALENX(IM))/(ALENY(IM)*6.)
1*ZZ)
BIGK(1,4)=YY*((3.*NU-1.)/8.)
BIGK(1,5)=YY*(-ALENY(IM))/(6.*ALENX(IM))- (ALENX(IM))/(ALENY(IM)*6.)
1*ZZ)
BIGK(1,6)=YY*(-(NU+1.)/8.)
BIGK(1,7)=YY*(ALENY(IM))/(6.*ALENX(IM))- (ALENX(IM))/(3.*ALENY(IM))
1*ZZ)
BIGK(1,8)=YY*((-3.*NU+1.)/8.)
BIGK(2,2)=YY*(ALENX(IM))/(ALENY(IM)*3.0)+(ALENY(IM))/(ALENX(IM)*3.0)
1)*ZZ)
BIGK(2,3)=YY*((-3.*NU+1.)/8.)
BIGK(2,4)=YY*(ALENX(IM))/(ALENY(IM)*6.0)- (ALENY(IM))/(ALENX(IM)*3.0)
1)*ZZ)
BIGK(2,5)=YY*(-(NU+1.0)/8.)
BIGK(2,6)=YY*(-ALENX(IM))/(ALENY(IM)*6.0)- (ALENY(IM))/(ALENX(IM)*6.0)
1)*ZZ)
BIGK(2,7)=YY*(3.*NU-1.0)/8.
BIGK(2,8)=YY*(-ALENX(IM))/(ALENY(IM)*3.0)+( ALENY(IM)/(ALENX(IM)*
1 6.0))*ZZ)
BIGK(3,3)=YY*(ALENY(IM))/(ALENX(IM)*3.)+(ALENX(IM))/(ALENY(IM)*3.)
1ZZ)
BIGK(3,4)=YY*(-(NU+1.0)/8.)
BIGK(3,5)=YY*(ALENY(IM))/(ALENX(IM)*6.)-(ALENX(IM)/(3.*ALENY(IM))*
2ZZ)
BIGK(3,6)=YY*(3.*NU-1.0)/8.
BIGK(3,7)=YY*(-ALENY(IM))/(ALENX(IM)*6.)-(ALENX(IM))/(ALENY(IM)*6.)
3)*ZZ)

```

```

BIGK(3,8)=YY*(NU+1.0)/8.
BIGK(4,4)=YY*(ALENX(IM)/(3.*ALENY(IM))+(ALENY(IM)/(ALENX(IM)*3.0)
1)*ZZ)
BIGK(4,5)=YY*(-3.*NU+1.0)/8.
BIGK(4,6)=YY*(-ALENX(IM)/(ALENY(IM)*3.0)+(ALENY(IM)/(ALENX(IM)*6.0
1))*ZZ)
BIGK(4,7)=YY*(NU+1.0)/8.
BIGK(4,8)=YY*(-ALENX(IM)/(ALENY(IM)*6.0)-(ALENY(IM)/(ALENX(IM)*6.0
1))*ZZ)
BIGK(5,5)=YY*(ALENY(IM)/(ALENX(IM)*3.0)+(ALENY(IM)/(ALENY(IM)*3.0)
4)*ZZ)
BIGK(5,6)=YY*(NU+1.0)/8.
BIGK(5,7)=YY*(-ALENX(IM)/(ALENX(IM)*3.0)+(ALENX(IM)/(ALENY(IM)*6.0
5))*ZZ)
BIGK(5,8)=YY*(3.0*NU-1.0)/8.
BIGK(6,6)=YY*(ALENX(IM)/(ALENY(IM)*3.0)+(ALENY(IM)/(ALENX(IM)*3.0
1))*ZZ)
BIGK(6,7)=YY*(-3.0*NU+1.0)/8.
BIGK(6,8)=YY*(ALENX(IM)/(ALENY(IM)*6.0)-(ALENY(IM)/(ALENX(IM)*3.0)
1))*ZZ)
BIGK(7,7)=YY*(ALENY(IM)/(ALENX(IM)*3.0)+(ALENX(IM)/(ALENY(IM)*3.0)
1))*ZZ)
BIGK(7,8)=YY*(-(NU+1.0)/8.)
BIGK(8,8)=YY*(ALENX(IM)/(ALENY(IM)*3.0)+(ALENY(IM)/(ALENX(IM)*3.0
1))*ZZ)
RETURN
END
STFM0037
STFM0038
STFM0039
STFM0040
STFM0041
STFM0042
STFM0043
STFM0044
STFM0045
STFM0046
STFM0047
STFM0048
STFM0049
STFM0050
STFM0051
STFM0052
STFM0053
STFM0054
STFM0055
STFM0056
STFM0057
STFM0058
STFM0059
STFM0060
STFM0061
STFM0062
STFM0063

```

```

SUBROUTINE FORCER(FORCE, INN, NDOF, NODX, FORVAL, FSTORX, VODY, FSTORY,
1 ALENX, ALENY, NLINE, NSS, QDUMMY, NODES, NSTAS, NSTAT, NSTASI,
2 NSTATI, LINUM, TN, TS)
COMMON/A/ IDNODE, INODEN, IFORCE, I MPOIN, I1KELE, I2KELE, IDSTR, IDSTI,
1 IDST2, IXF1, IXF2, IT, I IPOIN, I LINUM, NLINE, IDIR, IOCT, NTAP, MTAP
DIMENSION FORCE(IFORCE), NODX(IDSTR), FORVAL(IDSTR), FSTORX(IDSTR),
1 NODY(IDSTR), FSTORY(IDSTR), ALENX(1), ALENY(1), QDUMMY(IFORCE),
2 LINUM(I LINUM), TN(IDSTR, IDIR), TS(IDSTR, IDIR), NLINE(NLINE, IDIR)
1 FORMAT(I5)
2 FORMAT(I5, F10.4)
11 FORMAT(I6, 3X, F10.4)
101 FORMAT(1X, 6F10.4)
10 FORMAT(0 FORCXNODE VALUE 0)
21 FORMAT(0 FORCYNODE VALUE 0)
100 FORMAT(/, 8X, 0 FORCE ENTRIES TWO PER NODE IN ORDER 0, //)
15 FORMAT(10I5)
19 FORMAT(2I5, F10.4)
C
C IDENTIFY CODE FOR THE TYPE OF LOADING
C
READ(5, 1) LTYPE
IF(LTYPE.EQ.0) GO TO 1001
C
C LTYPE DIFFERENT THAN ZERO : DISCRETE NODAL LOADS
C
IFOR2=IFORCE
CALL ERASE(FORCE, IFOR2)
IF(INN.GT.1) GO TO 5
READ(5, 1) NFORX
READ(5, 1) NFORY
NFOR=NFORX+NFORY
IF(NFORX.EQ.0) GO TO 20
DO 3 I=1, NFORX
READ(5, 2) NODX(I), FORVAL(I)
FSTORX(NODX(I))=FORVAL(I)
3 CONTINUE

```

```

FORC0001
FORC0002
FORC0003
FORC0004
FORC0005
FORC0006
FORC0007
FORC0008
FORC0009
FORC0010
FORC0011
FORC0012
FORC0013
FORC0014
FORC0015
FORC0016
FORC0017
FORC0018
FORC0019
FORC0020
FORC0021
FORC0022
FORC0023
FORC0024
FORC0025
FORC0026
FORC0027
FORC0028
FORC0029
FORC0030
FORC0031
FORC0032
FORC0033
FORC0034
FORC0035
FORC0036

```



```

WRITE(NTAP,10)
WRITE(NTAP,11)(NODX(I),FSTORX(NODX(I)),I=1,NFORX)
20 CONTINUE
IF(NFORX.EQ.0) GO TO 5
DO 7 I=1,NFORX
READ(5,2)NDDY(I),FORVAL(I)
FSTORY(NDDY(I))=FORVAL(I)
7 CONTINUE
WRITE(NTAP,21)
WRITE(NTAP,11)(NDDY(I),FSTORY(NDDY(I)),I=1,NFORX)
5 CONTINUE
IF(NFORX.EQ.0)GO TO 110
DO 4 I=1,NFORX
J=(NODX(I)-1)*2+1
4 FORCE(J)=FSTORX(NODX(I))
110 CONTINUE
IF(NFORX.EQ.0) GO TO 111
DO 60 I=1,NFORX
J=(NDDY(I)-1)*2+2
60 FORCE(J)=FSTORY(NDDY(I))
111 CONTINUE
IF(INN.GT.1) RETURN
WRITE(NTAP,100)
WRITE(NTAP,101)(FORCE(I),I=1,NDOF)
RETURN
C
C LTYPE EQUALS 0 : BOUNDARY LINE LOADS
C
1001 NSTAS2=NSTAS-2
NSTAT2=NSTAT-2
NDD250=NSTAT1*NSTAS1
NDD276=NODES-NSTAS1
NDD277=NODES-NSTAS1+1
NDD284=NODES-2
NDD285=NODES-1
IFOR2=IFORCE
FORC0037
FORC0038
FORC0039
FORC0040
FORC0041
FORC0042
FORC0043
FORC0044
FORC0045
FORC0046
FORC0047
FORC0048
FORC0049
FORC0050
FORC0051
FORC0052
FORC0053
FORC0054
FORC0055
FORC0056
FORC0057
FORC0058
FORC0059
FORC0060
FORC0061
FORC0062
FORC0063
FORC0064
FORC0065
FORC0066
FORC0067
FORC0068
FORC0069
FORC0070
FORC0071
FORC0072

```

```

CALL ERASE(FORCE,IFOR2)
IF(INN.LE.1) GO TO 1040
DO 37 IRIS=1,NDOF
37 FORCE(IRIS)=QDUMMY(IRIS)
IF(INN.GT.1) RETURN
1040 READ(5,15)NUMLNN,NUMLNS,NNODEN,NNODES
IF(NUMLNN.EQ.0) GO TO 210
DO 81 I=1,NNODEN
81 READ(5,19)NODAT,NO,TN(NODAT,NO)
READ(5,15)(LNUM(I),I=1,NUMLNN)
210 IF(NUMLNS.EQ.0)GO TO 23
DO 82 I=1,NNODES
82 READ(5,19)NODAT,NO,TS(NODAT,NO)
READ(5,15)(LNUM(I+NUMLNN),I=1,NUMLNS)
23 CONTINUE
LINTOT=NUMLNN+NUMLNS
DO 1010 I=1,LINTOT
LIN=LINUM(I)
J1=NLIN(LIN,1)
J2=NLIN(LIN,2)
IF(LIN.GT.NSS)GO TO 26
SIDE 2 VARYING
IF(LIN.GE.1.AND.LIN.LE.NSTAS1)ISIGN=-1
IF(LIN.GT.NOD250.AND.LIN.LE.NSS)ISIGN=1
K2=(J1-1)*2+1
K1=K2+1
K4=(J2-1)*2+1
K3=K4+1
ALEN=ALENY(I)
GO TO 25
26 CONTINUE
C SIDE 1 VARYING
DO 800 KA=1,NSTAT1
800 IF(LIN.EQ.(NSS+NSTAS*KA))ISIGN=1
DO 802 KB=1,NSTAT2
802 IF(LIN.EQ.(NSS+NSTAS*(KB-1)+1))ISIGN=-1
FORC0073
FORC0074
FORC0075
FORC0076
FORC0077
FORC0078
FORC0079
FORC0080
FORC0081
FORC0082
FORC0083
FORC0084
FORC0085
FORC0086
FORC0087
FORC0088
FORC0089
FORC0090
FORC0091
FORC0092
FORC0093
FORC0094
FORC0095
FORC0096
FORC0097
FORC0098
FORC0099
FORC0100
FORC0101
FORC0102
FORC0103
FORC0104
FORC0105
FORC0106
FORC0107
FORC0108

```

FORC0109
 FORC0110
 FORC0111
 FORC0112
 FORC0113
 FORC0114
 FORC0115
 FORC0116
 FORC0117
 FORC0118
 FORC0119
 FORC0120
 FORC0121
 FORC0122
 FORC0123
 FORC0124
 FORC0125
 FORC0126
 FORC0127
 FORC0128
 FORC0129
 FORC0130
 FORC0131
 FORC0132
 FORC0133
 FORC0134
 FORC0135
 FORC0136
 FORC0137
 FORC0138
 FORC0139
 FORC0140
 FORC0141
 FORC0142
 FORC0143
 FORC0144

```

K1=(J1-1)*2+1
K2=K1+1
K3=(J2-1)*2+1
K4=K3+1
ALEN=ALENX(1)
25 CONTINUE
C
C NORMAL FORCES PER BOUNDARY LINE
C ALONG VERTICAL OR HORIZONTAL EDGES
C
IF(I.GT.NUMLN)GO TO 1000
C
CHECK THE VERTICAL SIDE ( ALL THE IFS BELLOW )
C
DO 50 KK=2,NSTAS2
IF(J1.EQ.KK) GO TO 400
50 CONTINUE
DO 61 KK=NDD277,NDD284
IF(J1.EQ.KK) GO TO 400
61 CONTINUE
IF(J1.EQ.1.AND.J2.EQ.2)GO TO 400
IF(J1.EQ.NSTAS1.AND.J2.EQ.NSTAS)GO TO 400
IF(J1.EQ.NDD276.AND.J2.EQ.NDD277)GO TO 400
IF(J1.EQ.NDD285.AND.J2.EQ.NDD284)GO TO 400
QDUMMY(K2)=(TN(J1,1)/3.+TN(J2,1)/6.)*ALEN*ISIGN
QDUMMY(K4)=(TN(J1,1)/6.+TN(J2,1)/3.)*ALEN*ISIGN
GO TO 40
400 QDUMMY(K2)=(TN(J1,2)/3.+TN(J2,2)/6.)*ALEN*ISIGN
QDUMMY(K4)=(TN(J1,2)/6.+TN(J2,2)/3.)*ALEN*ISIGN
40 FORCE(K2)=FORCE(K2)+QDUMMY(K2)
FORCE(K4)=FORCE(K4)+QDUMMY(K4)
GO TO 1010
1000 CONTINUE
C
C SHEAR FORCES PER BOUNDARY LINE
C ALONG VERTICAL OR HORIZONTAL EDGES
C

```

FORC0145
 FORC0146
 FORC0147
 FORC0148
 FORC0149
 FORC0150
 FORC0151
 FORC0152
 FORC0153
 FORC0154
 FORC0155
 FORC0156
 FORC0157
 FORC0158
 FORC0159
 FORC0160
 FORC0161
 FORC0162
 FORC0163
 FORC0164
 FORC0165
 FORC0166
 FORC0167
 FORC0168
 FORC0169
 FORC0170
 FORC0171
 FORC0172

```

C
C
C
C
      CHECK THE VERTICAL SIDE ( ALL THE IFS BELOW )
      DO 500 LL=2, NSTAS2
      IF(J1.EQ.LL) GO TO 4000
500  CONTINUE
      DO 600 LL=NDD277,NDD284
      IF(J1.EQ.LL) GO TO 4000
600  CONTINUE
      IF(J1.EQ.1.AND.J2.EQ.2) GO TO 4000
      IF(J1.EQ.NSTAS1.AND.J2.EQ.NSTAS) GO TO 4000
      IF(J1.EQ.NDD276.AND.J2.EQ.NDD277) GO TO 4000
      IF(J1.EQ.NDD285.AND.J2.EQ.NDD284) GO TO 4000
      QDUMMY(K1)=(TS(J1,1)/3.+TS(J2,1)/6.)*ALEN*ISIGN
      QDUMMY(K3)=(TS(J1,1)/6.+TS(J2,1)/3.)*ALEN*ISIGN
      GO TO 14
4000 QDUMMY(K1)=(TS(J1,2)/3.+TS(J2,2)/6.)*ALEN*ISIGN
      QDUMMY(K3)=(TS(J1,2)/6.+TS(J2,2)/3.)*ALEN*ISIGN
      14  FORCE(K1)=FORCE(K1)+QDUMMY(K1)
      FORCE(K3)=FORCE(K3)+QDUMMY(K3)
1010 CONTINUE
      DO 17 LIA=1, NDOF
      QDUMMY(LIA)=FORCE(LIA)
      17  WRITE(NTAP,100)
      WRITE(NTAP,101)(FORCE(I),I=1,NDOF)
      RETURN
      END

```

```

SUBROUTINE STRESS(NELES,NODE,FORCE,ALXX,ALYY,NODES,NU,ZZ,YY,NODEN,
2STRX,STRY,STRXY)
REAL NU
COMMON/A/ ICNODE,INODEN,IFORCE,IMPOIN,I1KELE,I2KELE,IDSTR,IDST1,
1 IDST2,IXF1,IXF2,IT,I1POIN,I1INUM,NLIN,IDIR,IOCT,NTAP,MTAP
DIMENSION NCDE( ICNODE,4),FKCE(IFORCE),NODEN(INODEN),STRX(ICSTR),
1STRY(IDSTR),STRXY(IDSTR)
X=ALXX
Y=ALYY
IDSTR2=IDSTR
CALL ERASE(STRX,IDSTR2,STRY,IDSTR2,STRXY,IDSTR2)
WRITE(NTAP,1457)
1457 FORMAT(//,' NODE(4) ',//)
1200 FORMAT(4I5)
WRITE(NTAP,780)X,Y
780 FORMAT(//,' X=',E12.4,' Y=',E12.4,//)
WRITE(NTAP,777)
777 FORMAT(//,' NODEN',//)
WRITE(NTAP,778)(NOCEN(II),II=1,300)
778 FORMAT(1X,20I3)
WRITE(NTAP,779)NU,ZZ,YY
779 FORMAT(//,' NU=',E12.4,' ZZ=',E12.4,' YY=',E12.4)
DO 7 IM=1,NELES
N1=NODE(IM,1)
N2=NODE(IM,2)
N3=NODE(IM,3)
N4=NODE(IM,4)
I1=(N1-1)*2+1
I2=(N1-1)*2+2
I3=(N2-1)*2+1
I4=(N2-1)*2+2
I5=(N3-1)*2+1
I6=(N3-1)*2+2
I7=(N4-1)*2+1
I8=(N4-1)*2+2

```

```

STRE0001
STRE0002
STRE0003
STRE0004
STRE0005
STRE0006
STRE0007
STRE0008
STRE0009
STRE0010
STRE0011
STRE0012
STRE0013
STRE0014
STRE0015
STRE0016
STRE0017
STRE0018
STRE0019
STRE0020
STRE0021
STRE0022
STRE0023
STRE0024
STRE0025
STRE0026
STRE0027
STRE0028
STRE0029
STRE0030
STRE0031
STRE0032
STRE0033
STRE0034
STRE0035
STRE0036

```

STRE0037
 STRE0038
 STRE0039
 STRE0040
 STRE0041
 STRE0042
 STRE0043
 STRE0044
 STRE0045
 STRE0046
 STRE0047
 STRE0048
 STRE0049
 STRE0050
 STRE0051
 STRE0052
 STRE0053
 STRE0054
 STRE0055
 STRE0056
 STRE0057
 STRE0058
 STRE0059
 STRE0060
 STRE0061
 STRE0062
 STRE0063
 STRE0064
 STRE0065
 STRE0066
 STRE0067
 STRE0068
 STRE0069
 STRE0070
 STRE0071
 STRE0072

```

01=FORCE(I1)
02=FORCE(I2)
03=FORCE(I3)
04=FORCE(I4)
05=FORCE(I5)
06=FORCE(I6)
07=FORCE(I7)
08=FORCE(I8)
STRX1=(I1./X)*(Q3-Q1)+(I./Y)*(Q8-Q2)*NU)*YY
STRX2=(NU/X*Y)*(Q2-Q4+Q6-Q8)*YY
STRX3=(I1./X*Y)*(Q1-Q3+Q5-Q7)*YY
STRY1=(NU/X)*(Q3-Q1)+(I./Y)*(Q8-Q2)*YY
STRY2=(I1./X*Y)*(Q2-Q4+Q6-Q8)*YY
STRY3=(NU/X*Y)*(Q1-Q3+Q5-Q7)*YY
STRXY1=(ZZ*(I1./Y)*(Q7-Q1)+(I./X)*(Q4-Q2))*YY
STRXY2=(ZZ/(X*Y))*(Q1-Q3+Q5-Q7)*YY
STRXY3=(ZZ/(X*Y))*(Q2-Q4+Q6-Q8)*YY
STRX(N1)=STRX(N1)+(I./NODEN(N1))*STRX1
STRX(N2)=STRX(N2)+(I./NODEN(N2))*STRX1+STRX2*X
STRX(N3)=STRX(N3)+(I./NODEN(N3))*STRX1+STRX2*X+STRX3*Y
STRX(N4)=STRX(N4)+(I./NODEN(N4))*STRX1
STRY(N1)=STRY(N1)+(I./NODEN(N1))*STRY1
STRY(N2)=STRY(N2)+(I./NODEN(N2))*STRY1+STRY2*X
STRY(N3)=STRY(N3)+(I./NODEN(N3))*STRY1+STRY2*X+STRY3*Y
STRY(N4)=STRY(N4)+(I./NODEN(N4))*STRY1
STRXY(N1)=STRXY(N1)+(I./NODEN(N1))*STRXY1
STRXY(N2)=STRXY(N2)+(I./NODEN(N2))*STRXY1+STRXY2*X
STRXY(N3)=STRXY(N3)+(I./NODEN(N3))*STRXY1+STRXY2*X+STRXY3*Y
STRXY(N4)=STRXY(N4)+(I./NODEN(N4))*STRXY1
7 CONTINUE
WRITE(NTAP,8)
8 FORMAT(//,' AVERAGE STRESSES PER NODE',//)
WRITE(NTAP,9)
9 FORMAT(//,' NODE STRESS-X STRESS-Y STRESS-X
1Y',//)
WRITE(NTAP,10)(I,STRX(I),STRY(I),STRXY(I),I=1,NODES)
  
```

10 FORMAT (1X, I5, 3E16.5)
RETURN
END

STRE0073
STRE0074
STRE0075

```

SUBROUTINE TRAJEC(STRX,STRY,STRXY,ALXX,ALYY,ALY,STX,STY,STXY,
2XF,YF,NSTAS,NSTAT1,T,FT,IPOINT,MPTS,TIT,SIGMA2)
COMMON/A/ I DNODE,INODEN,IFORCE,IMPOIN,IIKELE,I2KELE,IDSJR,IDST1,
1 IDST2,IXF1,IXF2,IT,IIPOIN,ILINUM,NLIN,IDIR,IOCT,NTAP,MTAP
DIMENSION STRX(IDSTR),STRY(IDSTR),STRXY(IDSTR),XF(IXF1,IXF2),
1YF(IXF1,IXF2),STX(IDST1,IDST2),STY(IDST1,IDST2),STXY(IDST1,IDST2),
2T(IT),FT(IT),IPOINT(IIPOIN),SIGMA2(IDST1,IDST2),TIT(IT)

C
WRITE( 6,1051)
1051 FORMAT('1 ANALYTIC PROCEDURE FOR OBTAINING THE STRESS TRAJECTORIES
1',/////)
C
C
C START AT THE FIRST NODE OF THE STRUCTURE
C
C DO LOOP FOR THE TRAJECTORY NUMBER
C
C J=0
C DO 10 II=1,NSTAS
C
C DEFINE INITIAL COORDINATES XF, YF, AND INITIAL STRESSES
C
XF(1,II)=0.0
YF(1,II)=(II-1)*ALY
STX(1,II)=STRX(II)
STY(1,II)=STRY(II)
STXY(1,II)=STRXY(II)
C
C CALCULATE THE INITIAL PRINCIPAL COMPRESSIVE STRESS SIGMA2
C
SIGMA2(1,II)=(STX(1,II)+STY(1,II))/2.-SQRT((STXY(1,II))**2+
1 (STX(1,II)-STY(1,II))**2/4.)
C
C WRITE THE INITIAL STRESSES OUT
C
C WRITE( 6,40)II,XF(1,II),II,YF(1,II),II,STX(1,II),II,STY(1,II),

```

```

TRAJ0001
TRAJ0002
TRAJ0003
TRAJ0004
TRAJ0005
TRAJ0006
TRAJ0007
TRAJ0008
TRAJ0009
TRAJ0010
TRAJ0011
TRAJ0012
TRAJ0013
TRAJ0014
TRAJ0015
TRAJ0016
TRAJ0017
TRAJ0018
TRAJ0019
TRAJ0020
TRAJ0021
TRAJ0022
TRAJ0023
TRAJ0024
TRAJ0025
TRAJ0026
TRAJ0027
TRAJ0028
TRAJ0029
TRAJ0030
TRAJ0031
TRAJ0032
TRAJ0033
TRAJ0034
TRAJ0035
TRAJ0036

```


TRAJ0037
 TRAJ0038
 TRAJ0039
 TRAJ0040
 TRAJ0041
 TRAJ0042
 TRAJ0043
 TRAJ0044
 TRAJ0045
 TRAJ0046
 TRAJ0047
 TRAJ0048
 TRAJ0049
 TRAJ0050
 TRAJ0051
 TRAJ0052
 TRAJ0053
 TRAJ0054
 TRAJ0055
 TRAJ0056
 TRAJ0057
 TRAJ0058
 TRAJ0059
 TRAJ0060
 TRAJ0061
 TRAJ0062
 TRAJ0063
 TRAJ0064
 TRAJ0065
 TRAJ0066
 TRAJ0067
 TRAJ0068
 TRAJ0069
 TRAJ0070
 TRAJ0071
 TRAJ0072

```

1 II,STXY(1,II),II,SIGMA2(1,II)
40 FORMAT(/,IX, XF(1,,I3,')=,F8.3, YF(1,,I3,')=,
1 F8.3,/,IX, STX(1,,I3,')=,E12.4, STY(1,,I3,')=,F12.4,
2 STXY(1,,I3,')=,E12.4, SIGMA2(1,,I3,')=,E12.4)
C
C DO LOOP FOR THE NUMBER OF STATIONS ALONG THE X-DIRECTION
C
C DO 11 I=1,NSTAT1
C
C DEFINE NS TO BE THE INDEX OF THE NEXT ADJACENT
C STATION ALONG THE X-DIRECTION
C
C NS=I+1
C
C CALCULATE THETA1,Y1
C
C IF(I .GT. 1) GO TO 5
C X1=STRX(II)-STRY(II)
C THETA1=0.5*ATAN(2.*STRXY(II)/X1)
200 IF(THETA1)151,152,152
152 IF(X1)160,112,112
160 THETA1=THETA1+3.1416
C GO TO 112
151 IF(X1)170,112,171
170 THETA1=THETA1+3.1416
C GO TO 112
171 THETA1=THETA1+1.5708
112 Y1=ALXX*ABS(TAN(THETA1))
C GO TO 6
5 X1=STX(I,II)-STY(I,II)
C THETA1=0.5*ATAN(2.*STXY(I,II)/X1)
C GO TO 200
C
C CHECK IF Y1 IS GREATER THAN THE LENGTH OF THE
C STRUCTURE IN THE Y DIRECTION, I.E. Y1 GREATER THAN ALY
C
C

```

```

6 IF((Y1+YF(I,II))-ALY)12,12,14
14 WRITE( 6,15)II
15 FORMAT(/,1X,' TRAJECTORY(',I3,') IS OFF THE PLATE')
C
C IN THAT CASE DEFINE XF,YF,STX,STY,SIXY
C
XX=ALX*(ALY-YF(I,II))/Y1
XF(NS,II)=XF(I,II)+X*
YF(NS,II)=ALY
WRITE( 6,4)NS,II,XF(NS,II),NS,II,YF(NS,II)
41 FORMAT(/,1X,' XF(',I3,',' ,I3,')=',F8.3,' YF(',I3,',' ,I3,')=',
1I3,')=',F8.3)
NODER=I*NSTAS+1
GO TO 87
12 CONTINUE
C
C CALCULATE STRESSES AT P1 WHICH IS THE FIRST EXTRAPOLATION POINT
C THIS POINT IS IN GENERAL BETWEEN TWO NODES, SAY N1 AND N2
C
C DEFINE NODER (NODE NUMBER ALONG X-AXIS ONLY)
C
NODER=I*NSTAS+1
DUMN=(YF(I,II)+Y1)/ALY
NNODE=DUMN
C
C CALCULATE N1 AND N2
C
N1=NODER+NNODE
N2=N1+1
C
C CALCULATE THE DIFFERENCE DIFY1 BETWEEN P1 AND N1
C
DIFY1=(Y1+YF(I,II))-ALY*NNODE
C
C EVALUATE THE TEMPORARY STRESSES AT P1 BY INTERPOLATION
C

```

```

TRAJ0073
TRAJ0074
TRAJ0075
TRAJ0076
TRAJ0077
TRAJ0078
TRAJ0079
TRAJ0080
TRAJ0081
TRAJ0082
TRAJ0083
TRAJ0084
TRAJ0085
TRAJ0086
TRAJ0087
TRAJ0088
TRAJ0089
TRAJ0090
TRAJ0091
TRAJ0092
TRAJ0093
TRAJ0094
TRAJ0095
TRAJ0096
TRAJ0097
TRAJ0098
TRAJ0099
TRAJ0100
TRAJ0101
TRAJ0102
TRAJ0103
TRAJ0104
TRAJ0105
TRAJ0106
TRAJ0107
TRAJ0108

```

```

C      STRX1=STRX(N1)+(STRX(N2)-STRX(N1))*DIFY1/ALYY
C      STRY1=STRY(N1)+(STRY(N2)-STRY(N1))*DIFY1/ALYY
C      STRXY1=STRXY(N1)+(STRXY(N2)-STRXY(N1))*DIFY1/ALYY
C
C      CALCULATE THETA2 AND Y2 AT P1
C
C      X2=STRX1-STRY1
C      THETA2=0.5*ATAN(2.*STRXY1/X2)
C      IF(THETA2)191,192,192
192  IF(X2)165,116,116
165  THETA2=THETA2+3.1416
C      GO TO 116
191  IF(X2)210,116,211
210  THETA2=THETA2+3.1416
C      GO TO 116
211  THETA2=THETA2+1.5708
116  Y2=ALXX*ABS(TAN(THETA2))
C
C      TAKE AVERAGE SLOPE
C
C      YF(NS,II)=(Y1+Y2)/2.+YF(I,II)
C
C      CHECK IF YF(NS,II) IS GREATER THAN ALY
C
C      IF(YF(NS,II)-ALY)22,22,24
22  XF(NS,II)=I*ALXX
C      WRITE( 6,16)NS,II,XF(NS,II),NS,II,YF(NS,II)
16  FORMAT(/,1X,' XF(',I3,',',I3,',')=',F8.3,' YF(',I3,',',I3,',')=',
1F8.3)
C
C      CALCULATE THE STRESSES AT THE FINAL POINT PF1
C      DUMN=YF(NS,II)/ALYY
C      NNODE=DUMN
C      N1=NODER+NNODE
C      N2=N1+1
C

```

```

TRAJ0109
TRAJ0110
TRAJ0111
TRAJ0112
TRAJ0113
TRAJ0114
TRAJ0115
TRAJ0116
TRAJ0117
TRAJ0118
TRAJ0119
TRAJ0120
TRAJ0121
TRAJ0122
TRAJ0123
TRAJ0124
TRAJ0125
TRAJ0126
TRAJ0127
TRAJ0128
TRAJ0129
TRAJ0130
TRAJ0131
TRAJ0132
TRAJ0133
TRAJ0134
TRAJ0135
TRAJ0136
TRAJ0137
TRAJ0138
TRAJ0139
TRAJ0140
TRAJ0141
TRAJ0142
TRAJ0143
TRAJ0144

```

TRAJ0145
 TRAJ0146
 TRAJ0147
 TRAJ0148
 TRAJ0149
 TRAJ0150
 TRAJ0151
 TRAJ0152
 TRAJ0153
 TRAJ0154
 TRAJ0155
 TRAJ0156
 TRAJ0157
 TRAJ0158
 TRAJ0159
 TRAJ0160
 TRAJ0161
 TRAJ0162
 TRAJ0163
 TRAJ0164
 TRAJ0165
 TRAJ0166
 TRAJ0167
 TRAJ0168
 TRAJ0169
 TRAJ0170
 TRAJ0171
 TRAJ0172
 TRAJ0173
 TRAJ0174
 TRAJ0175
 TRAJ0176
 TRAJ0177
 TRAJ0178
 TRAJ0179
 TRAJ0180

```

C          CALCULATE THE DIFFERENCE DIF2 BETWEEN
C          THE FINAL POINT AND NI
C          DIF2=YF(NS,II)-ALYY*NNODE
C          EVALUATE STRESSES AT FINAL POINT
C          STX(NS,II)=STRX(N1)+(STRX(N2)-STRX(N1))*DIF2/ALYY
C          STY(NS,II)=STRY(N1)+(STRY(N2)-STRY(N1))*DIF2/ALYY
C          STXY(NS,II)=STRXY(N1)+(STRXY(N2)-STRXY(N1))*DIF2/ALYY
C          SIGMA2(NS,II)=(STX(NS,II)+STY(NS,II))/2.-SQRT(STXY(NS,II)**2+
C          1 (STX(NS,II)-STY(NS,II))**2/4.)
C          WRITE THE STRESSES OUT
C          WRITE( 6,43)NS,II,STX(NS,II),NS,II,STY(NS,II),NS,II,STXY(NS,II),
C          INS,II,SIGMA2(NS,II)
C          43 FORMAT(/,1X,' STX(',I3,',',I3,',')=',E12.4,
C          1 ' STY(',I3,',',I3,',')=',E12.4,' STXY(',I3,',',I3,',')=',E12.4,
C          2 ' SIGMA2(',I3,',',I3,',')=',E12.4)
C          GO TO 11
C          24 XX=ALXX*(ALY-YF(I,II))/(YF(NS,II)-YF(I,II))
C          XF(NS,II)=(I-1)*ALXX+XX
C          YF(NS,II)=ALY
C          WRITE( 6,44) NS,II,XF(NS,II),NS,II,YF(NS,II)
C          44 FORMAT(/,1X,' XF(',I3,',',I3,',')=',F8.3,' YF(',I3,',',I3,',')=',
C          1 ,F8.3)
C          87 NN1=NNODE-1
C          NN2=NN1+NSTAS
C          STX(NS,II)=STRX(NN1)+(STRX(NN2)-STRX(NN1))*XX/ALXX
C          STY(NS,II)=STRY(NN1)+(STRY(NN2)-STRY(NN1))*XX/ALXX
C          STXY(NS,II)=STRXY(NN1)+(STRXY(NN2)-STRXY(NN1))*XX/ALXX
C          SIGMA2(NS,II)=(STX(NS,II)+STY(NS,II))/2.-SQRT(STXY(NS,II)**2+
C          1 (STX(NS,II)-STY(NS,II))**2/4.)
C          WRITE( 6,43)NS,II,STX(NS,II),NS,II,STY(NS,II),NS,II,STXY(NS,II),
C          1 NS,II,SIGMA2(NS,II)
    
```

TRAJ0181
TRAJ0182
TRAJ0183
TRAJ0184
TRAJ0185
TRAJ0186
TRAJ0187
TRAJ0188
TRAJ0189
TRAJ0190
TRAJ0191
TRAJ0192
TRAJ0193
TRAJ0194
TRAJ0195
TRAJ0196
TRAJ0197
TRAJ0198
TRAJ0199
TRAJ0200
TRAJ0201
TRAJ0202

```
GO TO 100
11 CONTINUE
100 J=J+1
    IPOINT(J)=NS
10 CONTINUE
    MPTS=0
    DO 85 L=1,NSTAS
85 MPTS=MPTS+IPOINT(L)
    NPOINS=0
    K=0
    DO 91 II=1,NSTAS
    NPOINS=IPOINT(II)
    DO 92 I=1,NPOINS
    JJ=I+K
    T(JJ)=XF(I,II)
    FT(JJ)=YF(I,II)
    TIT(JJ)=SIGMA2(I,II)
92 CONTINUE
    K=IPOINT(II)+K
91 CONTINUE
    RETURN
    END
```

```

SUBROUTINE PLTRJ(T, FT, IPOINT, NPLOTS, MPTS, S, FS, TIT)
COMMON/A/ IDNODE, INODEN, IFORCE, IMPOIN, I1KELE, I2KELE, IDSTR, IDST1,
1 IDST2, IXF1, IXF2, IT, IIPAIN, ILINUM, NLIN, IDIR, IOCT, NTAP, MJAP
DIMENSION HEADNG(15), T(IT), FT(IT), IPOINT (IIPAIN), S(IXF1), FS(IXF1)
1 , TIT(IT)
C INITIALIZE PLOTTER ROUTINES
C LABEL WITH USER IDENTIFICATION
C SPECIAL INSTRUCTIONS FOR CALCOMP OPERATOR
CALL NEWPLT('M8707', '8129', 'WHITE ', 'BLACK')
C DEFINE A NEW ORIGIN
CALL PLOT1(4.0, 0.0, -3)
READ(5, 900) NPAGES
FORMAT(13)
900 FOR EACH PAGE
C DO 500 KPAGE=1, NPAGES
C FORCE CORRECT POSITIONING OF PEN
CALL PLOT1(0.0, 10.5, 3)
CALL PLOT1(0.0, -5, 3)
CALL PLOT1(4.0, 0.0, -3)
C LABEL EACH PAGE
READ(5, 901)(HEADNG(J), J=1, 15)
FORMAT(15A4)
901 CALL SYMBL5(-2.0, -.12, HEADNG, 90., 60)
C READ IN SCALING INFORMATION FOR THIS PAGE
READ(5, 902) X, Y, YXZERO, DX, DY, NDIGX, KEXPX, NDIGY, KEXPY
C DEFINE AN ORIGIN FOR THIS PAGE
CALL PLOT1(X, Y, -3)
READ(5, 555) XXI, YY1, XA, YA
555 FORMAT(4F10.2)
DDX=DX/XA
DDY=DY/YA
XLNGTH=XX1-X
YLNPTH=YY1-Y
DRAW AXES
C CALL AXIS1(-X, 0., ' ', 4, XLNGTH, 0., 0.0, DX, NDIGX, KEXPX, XA)
902 FORMAT(3X, 5E12.6, 4I3)

```

PLTT0001
 PLTT0002
 PLTT0003
 PLTT0004
 PLTT0005
 PLTT0006
 PLTT0007
 PLTT0008
 PLTT0009
 PLTT0010
 PLTT0011
 PLTT0012
 PLTT0013
 PLTT0014
 PLTT0015
 PLTT0016
 PLTT0017
 PLTT0018
 PLTT0019
 PLTT0020
 PLTT0021
 PLTT0022
 PLTT0023
 PLTT0024
 PLTT0025
 PLTT0026
 PLTT0027
 PLTT0028
 PLTT0029
 PLTT0030
 PLTT0031
 PLTT0032
 PLTT0033
 PLTT0034
 PLTT0035
 PLTT0036

```

C      CALL AXISI(0.,-Y.,      ,4,YLNGTH,90.,YXZERO,DY,NDIGY,KEXPY,YA)
FOR EACH PLOT
KSYMBL=0
LL=0
DO 400 KPLOT=1,NPLOTS
K=IPOINT(KPLOT)
DO 20 JJ=1,K
NPTS=K
LL=LL+1
S(JJ)=T(LL)
20 FS(JJ)=FT(LL)
PLOT ONE SET OF POINTS
CALL SCLGPH(S,FS,NPTS,.000,KSYMBL,0.,DDX,YXZERO,DDY)
LK=LL-K
DO 300 JJ=1,K
LK=LK+1
PRINTX=S(JJ)/DX+.05
PRINTY=FS(JJ)/DY-.1
CALL NUMBRI(PRINTX,PRINTY,.08,TIT(LK),0.,4)
300 CONTINUE
400 IF(LL-MPTS)400,400,401
CONTINUE
C      SET ORIGIN BACK TO PREVIOUS POSITION
401 CALL PLOT1(-X,-Y,-3)
SPACE AHEAD FOR THE NEXT PAGE
CALL PLOT1(27.0,0.0,-3)
500 CONTINUE
CALL ENDPLT
WRITE(NTAP,910)
910 FORMAT(///16H PLOTS COMPLETED)
RETURN
END
PLTT0037
PLTT0038
PLTT0039
PLTT0040
PLTT0041
PLTT0042
PLTT0043
PLTT0044
PLTT0045
PLTT0046
PLTT0047
PLTT0048
PLTT0049
PLTT0050
PLTT0051
PLTT0052
PLTT0053
PLTT0054
PLTT0055
PLTT0056
PLTT0057
PLTT0058
PLTT0059
PLTT0060
PLTT0061
PLTT0062
PLTT0063
PLTT0064
PLTT0065
PLTT0066
PLTT0067
PLTT0068

```

```

SUBROUTINE STIFEN(XF,YF,NSTAS,NSTAS1,ALX,ALY,IPOINT,MPOINT,
1 KELEM)
COMMON/A/ IDNODE,INODEN,IFORCE,IMPOIN,I1KELE,I2KELE,IDSIR,IDST1,
1 IDST2,IXF1,IXF2,IT,IIP0IN,I1LNUM,NLIN,IDIR,IOCT,NTAP,MTAP
DIMENSION XF(IXF1,IXF2),YF(IXF1,IXF2),IPOINT(IIP0IN),
1 KELEM(I1KELE,I2KELE),MPOINT(IMPOIN)
M=0
DO 10 J=1,NSTAS
KK=0
NPOINS=IPOINT(J)
NPOIN1=NPOINS-1
DO 11 I=1,NPOIN1
NS=I+1
IF(I-1)45,45,46
45 NYINC=J-1
GO TO 500
46 NYINC=YF(I,J)/ALY
500 NARCH=(I-1)*NSTAS1+1+NYINC
12 IF(XF(NS,J)-(I*ALX))12,13,13
12 NFINAL=(I-1)*NSTAS1+NSTAS1
DO 20 K=NARCH,NFINAL
KK=I+KK
20 KELEM(KK,J)=K
GO TO 100
13 NN=YF(NS,J)/ALY
NFINAL=(I-1)*NSTAS1+1+NN
DO 30 K=NARCH,NFINAL
KK=I+KK
30 KELEM(KK,J)=K
11 CONTINUE
100 M=M+1
MPOINT(M)=KK
10 CONTINUE
DO 40 JJ=1,NSTAS
WRITE(NTAP,199)JJ
199 FORMAT(' FJR THE ',I2,' TRAJECTORY')

```

```

STIF0001
STIF0002
STIF0003
STIF0004
STIF0005
STIF0006
STIF0007
STIF0008
STIF0009
STIF0010
STIF0011
STIF0012
STIF0013
STIF0014
STIF0015
STIF0016
STIF0017
STIF0018
STIF0019
STIF0020
STIF0021
STIF0022
STIF0023
STIF0024
STIF0025
STIF0026
STIF0027
STIF0028
STIF0029
STIF0030
STIF0031
STIF0032
STIF0033
STIF0034
STIF0035
STIF0036

```



```
MELEM=MPOINT(JJ)  
DO 50 II=1, MELEM  
  WRITE(NTAP,200)II,JJ,KELEM(II,JJ)  
  200 FORMAT( ' KELEM( ,I2, , ,I2, )= ',I3)  
50 CONTINUE  
40 CONTINUE  
  RETURN  
  END
```

```
STIF0037  
STIF0038  
STIF0039  
STIF0040  
STIF0041  
STIF0042  
STIF0043  
STIF0044
```

Appendix II-B
LISTING OF COMPUTER PROGRAM'S
PRINTOUT FOR THE CANTILEVER CASE

ANALYTIC TABULATION OF RESULTS FOR THE CASE OF A PLATE WHICH IS LOADED
IN ITS PLANE SIMILARLY TO A CANTILEVER BEAM.

EACH ONE OF THE DISCRETE LOADS IS APPLIED AT EACH OF THE NODES OF THE
FREE EDGE.

THE MAGNITUDE OF THE DISCRETE LOADS HAS A PARABOLIC PROFILE ALONG THE
EDGE OF THE PLATE.

NUMBER OF SEQUENCE = 1
NUMBER OF ELEMENTS = 250
NUMBER OF NCDES = 286
NSS = 260
NUMBER OF LINES = 535
THICKNESS = 0.400000E 00
MODULUS = 0.300000E 08
POISSON RATIO = 0.250000E 00

ALENX ALENY
0.1440E 020.1440E 02

MAIN0001
MAIN0002
MAIN0003
MAIN0004
MAIN0005
MAIN0006
MAIN0007
MAIN0008
MAIN0009
MAIN0010
MAIN0011
MAIN0012
MAIN0013
MAIN0014
MAIN0015
MAIN0016
MAIN0017
MAIN0018
MAIN0019
MAIN0020
MAIN0021
MAIN0022
MAIN0023
MAIN0024
MAIN0025
MAIN0026
MAIN0027
MAIN0028
MAIN0029
MAIN0030
MAIN0031
MAIN0032
MAIN0033
MAIN0034
MAIN0035
MAIN0036

```

MAIN0037
MAIN0038
MAIN0039
MAIN0040
MAIN0041
MAIN0042
MAIN0043
MAIN0044
MAIN0045
MAIN0046
MAIN0047
MAIN0048
MAIN0049
MAIN0050
MAIN0051
MAIN0052
MAIN0053
MAIN0054
MAIN0055
MAIN0056
MAIN0057
MAIN0058
MAIN0059
MAIN0060
MAIN0061
MAIN0062
MAIN0063
MAIN0064
MAIN0065
MAIN0066
MAIN0067
MAIN0068
MAIN0069
MAIN0070
MAIN0071
MAIN0072

```

*****BOUNDARY CONDITIONS *****

```

11 1 2 3 4 5 6 7 8 9 10 11
1 6
1 2 3 4 5 6 7 8 9 10 11 6

```

THE FIRST NUMBER IN THE FIRST TWO LINES INDICATES THE NUMBER OF NODES
FIXED IN THE X AND Y DIRECTIONS RESPECTIVELY. THE NUMBERS FOLLOWING IN
THESE FIRST TWO LINES CORRESPOND TO THE INDIVIDUAL NODES WHICH ARE FIXED
IN THE X AND THE Y DIRECTIONS. THE THIRD LINE LISTS THE NODES WHICH ARE
FIXED IN BOTH DIRECTIONS IN ORDER.

THE DETERMINANT IS THAT OF THE CCNSTRAINED STIFFNESS MATRIX CF THE
 ASSEMBLED STRUCTURE.
 IF THE DETERMINANT IS POSITIVE THE STRUCTURE IS PROPERLY CONSTRAINED.
 IF THE DETERMINANT IS NEGATIVE OR ZERO THE STRUCTURE IS A MECHANISM.

DETERMINANT = C.9148679E 03

THE FOLLOWING IS A LISTING OF THE DISPLACEMENTS PER NODE IN CRDR

NODE	DISP. X	DISP. Y
1	0.0	-0.1187E-04
2	0.0	-0.1014E-04
3	0.0	-0.8616E-05
4	0.0	-0.7040E-05
5	0.0	-0.4823E-05
6	0.0	0.0
7	0.0	-0.4823E-05
8	0.0	-0.7040E-05

MAIN0001
 MAIN0002
 MAIN0003
 MAIN0004
 MAIN0005
 MAIN0006
 MAIN0007
 MAIN0008
 MAIN0009
 MAIN0010
 MAIN0011
 MAIN0012
 MAIN0013
 MAIN0014
 MAIN0015
 MAIN0016
 MAIN0017
 MAIN0018
 MAIN0019
 MAIN0020
 MAIN0021
 MAIN0022
 MAIN0023
 MAIN0024
 MAIN0025
 MAIN0026
 MAIN0027
 MAIN0028
 MAIN0029
 MAIN0030
 MAIN0031
 MAIN0032
 MAIN0033
 MAIN0034
 MAIN0035
 MAIN0036

CONTINUED

NODE	DISP. X	DISP. Y	CONTINUED
9	0.0	-0.8616E-05	MAIN0037
10	0.0	-0.1014E-04	MAIN0038
11	0.0	-0.1187E-04	MAIN0039
12	-0.7550E-05	-0.1286E-04	MAIN0040
13	-0.5795E-05	-0.1117E-04	MAIN0041
14	-0.4339E-05	-0.9730E-05	MAIN0042
15	-0.3072E-05	-0.8391E-05	MAIN0043
16	-0.2026E-05	-0.7175E-05	MAIN0044
17	-0.6639E-10	-0.7284E-05	MAIN0045
18	0.2026E-05	-0.7175E-05	MAIN0046
19	0.3072E-05	-0.8391E-05	MAIN0047
20	0.4339E-05	-0.9730E-05	MAIN0048
21	0.5795E-05	-0.1117E-04	MAIN0049
22	0.7550E-05	-0.1286E-04	MAIN0050
23	-0.1488E-04	-0.1576E-04	MAIN0051
24	-0.1145E-04	-0.1416E-04	MAIN0052
25	-0.8496E-05	-0.1289E-04	MAIN0053
26	-0.5816E-05	-0.1194E-04	MAIN0054
27	-0.3032E-05	-0.1147E-04	MAIN0055
28	-0.1310E-09	-0.1127E-04	MAIN0056
29	0.3032E-05	-0.1147E-04	MAIN0057
30	0.5795E-05	-0.1194E-04	MAIN0058
31	0.8496E-05	-0.1289E-04	MAIN0059
32	0.1144E-04	-0.1416E-04	MAIN0060
33	0.1488E-04	-0.1576E-04	MAIN0061
34	-0.2186E-04	-0.2038E-04	MAIN0062
35	-0.1686E-04	-0.1887E-04	MAIN0063
36	-0.1243E-04	-0.1774E-04	MAIN0064
37	-0.8275E-05	-0.1698E-04	MAIN0065
38	-0.4166E-05	-0.1655E-04	MAIN0066
39	-0.1846E-09	-0.1644E-04	MAIN0067
40	0.4166E-05	-0.1655E-04	MAIN0068
41	0.8275E-05	-0.1698E-04	MAIN0069
42	0.1243E-04	-0.1774E-04	MAIN0070
			MAIN0071
			MAIN0072

CONTINUED

MAIN	DISP.	X	DISP.	Y	CONTINUED
MAIN0073					
MAIN0074					
MAIN0075					
MAIN0076					
MAIN0077					
MAIN0078					
MAIN0079					
MAIN0080					
MAIN0081					
MAIN0082					
MAIN0083					
MAIN0084					
MAIN0085					
MAIN0086					
MAIN0087					
MAIN0088					
MAIN0089					
MAIN0090					
MAIN0091					
MAIN0092					
MAIN0093					
MAIN0094					
MAIN0095					
MAIN0096					
MAIN0097					
MAIN0098					
MAIN0099					
MAIN0100					
MAIN0101					
MAIN0102					
MAIN0103					
MAIN0104					
MAIN0105					
MAIN0106					
MAIN0107					
MAIN0108					
43	0.1686E-04	-0.1887E-04			
44	0.2186E-04	-0.2038E-04			
45	-0.2843E-04	-0.2649E-04			
46	-0.2202E-04	-0.2507E-04			
47	-0.1619E-04	-0.2401E-04			
48	-0.1068E-04	-0.2330E-04			
49	-0.5322E-05	-0.2290E-04			
50	-0.2392E-09	-0.2277E-04			
51	0.5321E-05	-0.2290E-04			
52	0.1068E-04	-0.2330E-04			
53	0.1619E-04	-0.2401E-04			
54	0.2202E-04	-0.2507E-04			
55	0.2843E-04	-0.2649E-04			
56	-0.3462E-04	-0.3393E-04			
57	-0.2692E-04	-0.3259E-04			
58	-0.1979E-04	-0.3157E-04			
59	-0.1303E-04	-0.3088E-04			
60	-0.6472E-05	-0.3047E-04			
61	-0.2901E-09	-0.3035E-04			
62	0.6471E-05	-0.3047E-04			
63	0.1303E-04	-0.3088E-04			
64	0.1979E-04	-0.3157E-04			
65	0.2692E-04	-0.3259E-04			
66	0.3462E-04	-0.3393E-04			
67	-0.4046E-04	-0.4258E-04			
68	-0.3157E-04	-0.4131E-04			
69	-0.2324E-04	-0.4033E-04			
70	-0.1530E-04	-0.3965E-04			
71	-0.7595E-05	-0.3926E-04			
72	-0.3201E-09	-0.3913E-04			
73	0.7594E-05	-0.3926E-04			
74	0.1530E-04	-0.3965E-04			
75	0.2324E-04	-0.4033E-04			
76	0.3157E-04	-0.4131E-04			

CONTINUED

NODE	DISP. X	DISP. Y	CONTINUED
77	0.4046E-04	-0.4258E-04	MAIN0109
78	-0.4598E-04	-0.5236E-04	MAIN0110
79	-0.3598E-04	-0.5116E-04	MAIN0111
80	-0.2653E-04	-0.5023E-04	MAIN0112
81	-0.1748E-04	-0.4957E-04	MAIN0113
82	-0.8677E-05	-0.4918E-04	MAIN0114
83	-0.3483E-09	-0.4906E-04	MAIN0115
84	0.8676E-05	-0.4918E-04	MAIN0116
85	0.1748E-04	-0.4957E-04	MAIN0117
86	0.2653E-04	-0.5023E-04	MAIN0118
87	0.3598E-04	-0.5116E-04	MAIN0119
88	0.4598E-04	-0.5236E-04	MAIN0120
89	-0.5119E-04	-0.6321E-04	MAIN0121
90	-0.4015E-04	-0.6207E-04	MAIN0122
91	-0.2965E-04	-0.6119E-04	MAIN0123
92	-0.1955E-04	-0.6056E-04	MAIN0124
93	-0.9709E-05	-0.6019E-04	MAIN0125
94	-0.3756E-09	-0.6007E-04	MAIN0126
95	0.9708E-05	-0.6019E-04	MAIN0127
96	0.1955E-04	-0.6056E-04	MAIN0128
97	0.2965E-04	-0.6119E-04	MAIN0129
98	0.4015E-04	-0.6207E-04	MAIN0130
99	0.5119E-04	-0.6321E-04	MAIN0131
100	-0.5610E-04	-0.7506E-04	MAIN0132
101	-0.4408E-04	-0.7399E-04	MAIN0133
102	-0.3259E-04	-0.7316E-04	MAIN0134
103	-0.2151E-04	-0.7257E-04	MAIN0135
104	-0.1069E-04	-0.7221E-04	MAIN0136
105	-0.3920E-09	-0.7210E-04	MAIN0137
106	0.1069E-04	-0.7221E-04	MAIN0138
107	0.2150E-04	-0.7257E-04	MAIN0139
108	0.3259E-04	-0.7316E-04	MAIN0140
109	0.4407E-04	-0.7399E-04	MAIN0141
110	0.5610E-04	-0.7506E-04	MAIN0142
			MAIN0143
			MAIN0144

CONTINUED

NODE	DISP. X	DISP. Y
111	-0.6071E-04	-0.8786E-04
112	-0.4776E-04	-0.8686E-04
113	-0.3535E-04	-0.8608E-04
114	-0.2335E-04	-0.8552E-04
115	-0.1161E-04	-0.8519E-04
116	-0.4284E-09	-0.8508E-04
117	0.1161E-04	-0.8519E-04
118	0.2335E-04	-0.8553E-04
119	0.3535E-04	-0.8608E-04
120	0.4776E-04	-0.8686E-04
121	0.6071E-04	-0.8787E-04
122	-0.6502E-04	-0.1016E-03
123	-0.5121E-04	-0.1006E-03
124	-0.3794E-04	-0.9989E-04
125	-0.2507E-04	-0.9937E-04
126	-0.1247E-04	-0.9906E-04
127	-0.4429E-09	-0.9896E-04
128	0.1247E-04	-0.9906E-04
129	0.2507E-04	-0.9938E-04
130	0.3794E-04	-0.9990E-04
131	0.5121E-04	-0.1006E-03
132	0.6502E-04	-0.1016E-03
133	-0.6904E-04	-0.1161E-03
134	-0.5443E-04	-0.1152E-03
135	-0.4035E-04	-0.1145E-03
136	-0.2668E-04	-0.1141E-03
137	-0.1327E-04	-0.1138E-03
138	-0.4638E-09	-0.1137E-03
139	0.1327E-04	-0.1138E-03
140	0.2668E-04	-0.1141E-03
141	0.4035E-04	-0.1145E-03
142	0.5443E-04	-0.1152E-03
143	0.6904E-04	-0.1161E-03
144	-0.7275E-04	-0.1314E-03

MAIN0145
 MAIN0146
 MAIN0147
 MAIN0148
 MAIN0149
 MAIN0150
 MAIN0151
 MAIN0152
 MAIN0153
 MAIN0154
 MAIN0155
 MAIN0156
 MAIN0157
 MAIN0158
 MAIN0159
 MAIN0160
 MAIN0161
 MAIN0162
 MAIN0163
 MAIN0164
 MAIN0165
 MAIN0166
 MAIN0167
 MAIN0168
 MAIN0169
 MAIN0170
 MAIN0171
 MAIN0172
 MAIN0173
 MAIN0174
 MAIN0175
 MAIN0176
 MAIN0177
 MAIN0178
 MAIN0179
 MAIN0180

CONTINUED

NODE	DISP. X	DISP. Y	DISP. Z	MAIN
145	-0.5740E-04	-0.1306E-03		MAIN0181
146	-0.4258E-04	-0.1300E-03		MAIN0182
147	-0.2817E-04	-0.1295E-03		MAIN0183
148	-0.1402E-04	-0.1292E-03		MAIN0184
149	-0.4738E-09	-0.1292E-03		MAIN0185
150	0.1402E-04	-0.1292E-03		MAIN0186
151	0.2816E-04	-0.1295E-03		MAIN0187
152	0.4258E-04	-0.1300E-03		MAIN0188
153	0.5740E-04	-0.1306E-03		MAIN0189
154	0.7275E-04	-0.1314E-03		MAIN0190
155	-0.7618E-04	-0.1474E-03		MAIN0191
156	-0.6014E-04	-0.1467E-03		MAIN0192
157	-0.4464E-04	-0.1461E-03		MAIN0193
158	-0.2953E-04	-0.1457E-03		MAIN0194
159	-0.1470E-04	-0.1454E-03		MAIN0195
160	-0.5093E-09	-0.1454E-03		MAIN0196
161	0.1470E-04	-0.1454E-03		MAIN0197
162	0.2953E-04	-0.1457E-03		MAIN0198
163	0.4463E-04	-0.1461E-03		MAIN0199
164	0.6014E-04	-0.1467E-03		MAIN0200
165	0.7618E-04	-0.1474E-03		MAIN0201
166	-0.7930E-04	-0.1641E-03		MAIN0202
167	-0.6264E-04	-0.1634E-03		MAIN0203
168	-0.4651E-04	-0.1629E-03		MAIN0204
169	-0.3078E-04	-0.1625E-03		MAIN0205
170	-0.1533E-04	-0.1623E-03		MAIN0206
171	-0.5239E-09	-0.1622E-03		MAIN0207
172	0.1532E-04	-0.1623E-03		MAIN0208
173	0.3078E-04	-0.1625E-03		MAIN0209
174	0.4651E-04	-0.1629E-03		MAIN0210
175	0.6264E-04	-0.1634E-03		MAIN0211
176	0.7930E-04	-0.1641E-03		MAIN0212
177	-0.8213E-04	-0.1813E-03		MAIN0213
178	-0.6490E-04	-0.1807E-03		MAIN0214

CONTINUED

NODE	DISP. X	DISP. Y	DISP. Z
179	-0.4821E-04	-C.1803E-03	
180	-0.3191E-04	-0.1799E-03	
181	-0.1589E-04	-0.1797E-03	
182	-0.5384E-09	-0.1797E-03	
183	0.1589E-04	-0.1797E-03	
184	0.3191E-04	-0.1799E-03	
185	0.4821E-04	-0.1803E-03	
186	0.6490E-04	-0.1807E-03	
187	0.8213E-04	-0.1813E-03	
188	-0.8466E-04	-0.1991E-03	
189	-0.6692E-04	-0.1986E-03	
190	-0.4972E-04	-0.1982E-03	
191	-0.3293E-04	-0.1979E-03	
192	-0.1640E-04	-0.1977E-03	
193	-0.5821E-09	-0.1977E-03	
194	0.1640E-04	-0.1977E-03	
195	0.3293E-04	-0.1979E-03	
196	0.4972E-04	-0.1982E-03	
197	0.6692E-04	-0.1986E-03	
198	0.8466E-04	-0.1991E-03	
199	-0.8689E-04	-0.2174E-03	
200	-0.6871E-04	-0.2169E-03	
201	-0.5106E-04	-0.2166E-03	
202	-0.3382E-04	-0.2163E-03	
203	-0.1684E-04	-0.2162E-03	
204	-0.6257E-09	-0.2161E-03	
205	0.1684E-04	-0.2162E-03	
206	0.3382E-04	-0.2163E-03	
207	0.5106E-04	-0.2166E-03	
208	0.6871E-04	-0.2169E-03	
209	0.8689E-04	-0.2174E-03	
210	-0.8683E-04	-0.2361E-03	
211	-0.7026E-04	-0.2357E-03	
212	-0.5223E-04	-0.2354E-03	

MAIN0217
 MAIN0218
 MAIN0219
 MAIN0220
 MAIN0221
 MAIN0222
 MAIN0223
 MAIN0224
 MAIN0225
 MAIN0226
 MAIN0227
 MAIN0228
 MAIN0229
 MAIN0230
 MAIN0231
 MAIN0232
 MAIN0233
 MAIN0234
 MAIN0235
 MAIN0236
 MAIN0237
 MAIN0238
 MAIN0239
 MAIN0240
 MAIN0241
 MAIN0242
 MAIN0243
 MAIN0244
 MAIN0245
 MAIN0246
 MAIN0247
 MAIN0248
 MAIN0249
 MAIN0250
 MAIN0251
 MAIN0252

CONTINUED

NODE	DISP. X	DISP. Y	MAIN0253
213	-0.3459E-04	-0.2352E-03	MAIN0254
214	-0.1723E-04	-0.2350E-03	MAIN0255
215	-0.7858E-09	-0.2350E-03	MAIN0256
216	0.1723E-04	-0.2350E-03	MAIN0257
217	0.3459E-04	-0.2352E-03	MAIN0258
218	0.5222E-04	-0.2354E-03	MAIN0259
219	0.7026E-04	-0.2357E-03	MAIN0260
220	0.8883E-04	-0.2361E-03	MAIN0261
221	-0.9046E-04	-0.2552E-03	MAIN0262
222	-0.7157E-04	-0.2548E-03	MAIN0263
223	-0.5321E-04	-0.2546E-03	MAIN0264
224	-0.3525E-04	-0.2544E-03	MAIN0265
225	-0.1756E-04	-0.2543E-03	MAIN0266
226	-0.9168E-09	-0.2542E-03	MAIN0267
227	0.1756E-04	-0.2543E-03	MAIN0268
228	0.3525E-04	-0.2544E-03	MAIN0269
229	0.5321E-04	-0.2546E-03	MAIN0270
230	0.7157E-04	-0.2548E-03	MAIN0271
231	0.9046E-04	-0.2552E-03	MAIN0272
232	-0.9180E-04	-0.2745E-03	MAIN0273
233	-0.7264E-04	-0.2743E-03	MAIN0274
234	-0.5402E-04	-0.2740E-03	MAIN0275
235	-0.3579E-04	-0.2739E-03	MAIN0276
236	-0.1783E-04	-0.2738E-03	MAIN0277
237	-0.9750E-09	-0.2738E-03	MAIN0278
238	0.1783E-04	-0.2738E-03	MAIN0279
239	0.3579E-04	-0.2739E-03	MAIN0280
240	0.5401E-04	-0.2740E-03	MAIN0281
241	0.7264E-04	-0.2743E-03	MAIN0282
242	0.9180E-04	-0.2745E-03	MAIN0283
243	-0.9283E-04	-0.2941E-03	MAIN0284
244	-0.7347E-04	-0.2939E-03	MAIN0285
245	-0.5465E-04	-0.2937E-03	MAIN0286
246	-0.3621E-04	-0.2936E-03	MAIN0287
			MAIN0288

CONTINUED

MAIN0289
 MAIN0290
 MAIN0291
 MAIN0292
 MAIN0293
 MAIN0294
 MAIN0295
 MAIN0296
 MAIN0297
 MAIN0298
 MAIN0299
 MAIN0300
 MAIN0301
 MAIN0302
 MAIN0303
 MAIN0304
 MAIN0305
 MAIN0306
 MAIN0307
 MAIN0308
 MAIN0309
 MAIN0310
 MAIN0311
 MAIN0312
 MAIN0313
 MAIN0314
 MAIN0315
 MAIN0316
 MAIN0317
 MAIN0318
 MAIN0319
 MAIN0320
 MAIN0321
 MAIN0322
 MAIN0323
 MAIN0324

NODE	DISP. X	DISP. Y
247	-0.1804E-04	-0.2936E-03
248	-0.9459E-09	-0.2935E-03
249	0.1804E-04	-0.2936E-03
250	0.3621E-04	-0.2936E-03
251	0.5465E-04	-0.2937E-03
252	0.7347E-04	-0.2939E-03
253	0.9283E-04	-0.2941E-03
254	-0.9356E-04	-0.3139E-03
255	-0.7407E-04	-0.3137E-03
256	-0.5510E-04	-0.3136E-03
257	-0.3652E-04	-0.3136E-03
258	-0.1819E-04	-0.3135E-03
259	-0.8586E-09	-0.3135E-03
260	0.1819E-04	-0.3135E-03
261	0.3652E-04	-0.3136E-03
262	0.5510E-04	-0.3136E-03
263	0.7407E-04	-0.3137E-03
264	0.9356E-04	-0.3139E-03
265	-0.9396E-04	-0.3337E-03
266	-0.7444E-04	-0.3336E-03
267	-0.5539E-04	-0.3336E-03
268	-0.3669E-04	-0.3336E-03
269	-0.1827E-04	-0.3336E-03
270	-0.7567E-09	-0.3336E-03
271	0.1827E-04	-0.3336E-03
272	0.3669E-04	-0.3336E-03
273	0.5538E-04	-0.3336E-03
274	0.7444E-04	-0.3337E-03
275	0.9396E-04	-0.3337E-03
276	-0.9406E-04	-0.3534E-03
277	-0.7455E-04	-0.3536E-03
278	-0.5547E-04	-0.3537E-03
279	-0.3675E-04	-0.3538E-03
280	-0.1830E-04	-0.3537E-03

CONTINUED

NODE	DISP. X	DISP. Y
281	-0.6092E-09	-0.3537E-03
282	0.1830E-04	-0.3537E-03
283	0.3675E-04	-0.3538E-03
284	0.5547E-04	-0.3537E-03
285	0.7455E-04	-0.3536E-03
286	0.9406E-04	-0.3534E-03

MAIN0325
MAIN0326
MAIN0327
MAIN0328
MAIN0329
MAIN0330
MAIN0331
MAIN0332
MAIN0333
MAIN0334

NODE(4) (I. E. THE NODE NUMBERS PER ELEMENT, COUNTERCLOCKWISE)

1	12	13	14	15	16	17	18	19	20	21	22	24	25	26	27	28	29	30	31	32	33	35	36	37
2	13	14	15	16	17	18	19	20	21	22	24	25	26	27	28	29	30	31	32	33	35	36	37	
3	14	15	16	17	18	19	20	21	22	24	25	26	27	28	29	30	31	32	33	35	36	37		
4	15	16	17	18	19	20	21	22	24	25	26	27	28	29	30	31	32	33	35	36	37			
5	16	17	18	19	20	21	22	24	25	26	27	28	29	30	31	32	33	35	36	37				
6	17	18	19	20	21	22	24	25	26	27	28	29	30	31	32	33	35	36	37					
7	18	19	20	21	22	24	25	26	27	28	29	30	31	32	33	35	36	37						
8	19	20	21	22	24	25	26	27	28	29	30	31	32	33	35	36	37							
9	20	21	22	24	25	26	27	28	29	30	31	32	33	35	36	37								
10	21	22	24	25	26	27	28	29	30	31	32	33	35	36	37									
11	22	24	25	26	27	28	29	30	31	32	33	35	36	37										
12	23	24	25	26	27	28	29	30	31	32	33	35	36	37										
13	24	25	26	27	28	29	30	31	32	33	35	36	37											
14	25	26	27	28	29	30	31	32	33	35	36	37												
15	26	27	28	29	30	31	32	33	35	36	37													
16	27	28	29	30	31	32	33	35	36	37														
17	28	29	30	31	32	33	35	36	37															
18	29	30	31	32	33	35	36	37																
19	30	31	32	33	35	36	37																	
20	31	32	33	35	36	37																		
21	32	33	35	36	37																			
22	33	35	36	37																				
23	34	35	36	37																				
24	35	36	37																					
25	36	37																						
26	37																							
27	38																							
28	39																							
29	40																							
30	41																							
31	42																							
32	43																							
33	44																							
34	45																							
35	46																							
36	47																							
37	48																							

STRE0001
 STRE0002
 STRE0003
 STRE0004
 STRE0005
 STRE0006
 STRE0007
 STRE0008
 STRE0009
 STRF001C
 STRE0011
 STRE0012
 STRE0013
 STRE0014
 STRE0015
 STRE0016
 STRE0017
 STRE0018
 STRE0019
 STRE002C
 STRE0021
 STRE0022
 STRE0023
 STRE0024
 STRE0025
 STRE0026
 STRE0027
 STRE0028
 STRE0029
 STRE003C
 STRE0031
 STRE0032
 STRE0033
 STRE0034
 STRE0035
 STRE0036

CCNT INUED

STRE0037
 STRE0038
 STRE0039
 STRE0040
 STRE0041
 STRE0042
 STRE0043
 STRE0044
 STRE0045
 STRE0046
 STRE0047
 STRE0048
 STRE0049
 STRE0050
 STRE0051
 STRE0052
 STRE0053
 STRE0054
 STRE0055
 STRE0056
 STRE0057
 STRE0058
 STRE0059
 STRE0060
 STRE0061
 STRE0062
 STRE0063
 STRE0064
 STRE0065
 STRE0066
 STRE0067
 STRE0068
 STRE0069
 STRE0070
 STRE0071
 STRE0072

NODE(4)

37	48	49	38
38	49	50	39
39	50	51	40
40	51	52	41
41	52	53	42
42	53	54	43
43	54	55	44
44	55	56	45
45	56	57	46
46	57	58	47
47	58	59	48
48	59	60	49
49	60	61	50
50	61	62	51
51	62	63	52
52	63	64	53
53	64	65	54
54	65	66	55
55	66	67	56
56	67	68	57
57	68	69	58
58	69	70	59
59	70	71	60
60	71	72	61
61	72	73	62
62	73	74	63
63	74	75	64
64	75	76	65
65	76	77	66
66	77	78	67
67	78	79	68
68	79	80	69
69	80	81	70
70	81	82	71
71	82	83	72
72	83	84	73
73	84	85	74

CCNT INUED

STREC073
 STREC074
 STREC075
 STREC076
 STREC077
 STREC078
 STREC079
 STREC080
 STREC081
 STREC082
 STREC083
 STREC084
 STREC085
 STREC086
 STREC087
 STREC088
 STREC089
 STREC090
 STREC091
 STREC092
 STREC093
 STREC094
 STREC095
 STREC096
 STREC097
 STREC098
 STREC099
 STREC100
 STREC101
 STREC102
 STREC103
 STREC104
 STREC105
 STREC106
 STREC107
 STREC108

NODE(4)

74 85 86 75
 75 86 87 76
 76 87 88 77
 78 89 90 79
 79 90 91 80
 80 91 92 81
 81 92 93 82
 82 93 94 83
 83 94 95 84
 84 95 96 85
 85 96 97 86
 86 97 98 87
 87 98 99 88
 89 100 101 90
 90 101 102 91
 91 102 103 92
 92 103 104 93
 93 104 105 94
 94 105 106 95
 95 106 107 96
 96 107 108 97
 97 108 109 98
 98 109 110 99
 100 111 112 101
 101 112 113 102
 102 113 114 103
 103 114 115 104
 104 115 116 105
 105 116 117 106
 106 117 118 107
 107 118 119 108
 108 119 120 109
 109 120 121 110
 111 122 123 112

CCNT INUED

STREC109
 STREC11C
 STRE0111
 STRE0112
 STRE0113
 STRE0114
 STRE0115
 STRE0116
 STRE0117
 STRE0118
 STRE0119
 STREC12C
 STRE0121
 STRE0122
 STRE0123
 STRE0124
 STRE0125
 STRE0126
 STRE0127
 STRE0128
 STRE0129
 STRE0130
 STRE0131
 STRE0132
 STRE0133
 STRE0134
 STRE0135
 STRE0136
 STRE0137
 STRE0138
 STRE0139
 STRE014C
 STRE0141
 STRE0142
 STRE0143
 STRE0144

NODE (4)

112	123	124	113
113	124	125	114
114	125	126	115
115	126	127	116
116	127	128	117
117	128	129	118
118	129	130	119
119	130	131	120
120	131	132	121
122	133	134	123
123	134	135	124
124	135	136	125
125	136	137	126
126	137	138	127
127	138	139	128
128	139	140	129
129	140	141	130
130	141	142	131
131	142	143	132
133	144	145	134
134	145	146	135
135	146	147	136
136	147	148	137
137	148	149	138
138	149	150	139
139	150	151	140
140	151	152	141
141	152	153	142
142	153	154	143
144	155	156	145
145	156	157	146
146	157	158	147
147	158	159	148
148	159	160	149

CCNT INUED

STREC145
 STREC146
 STREC147
 STREC148
 STREC149
 STREC150
 STREC151
 STREC152
 STREC153
 STREC154
 STREC155
 STREC156
 STREC157
 STREC158
 STREC159
 STREC160
 STREC161
 STREC162
 STREC163
 STREC164
 STREC165
 STREC166
 STREC167
 STREC168
 STREC169
 STREC170
 STREC171
 STREC172
 STREC173
 STREC174
 STREC175
 STREC176
 STREC177
 STREC178
 STREC179
 STREC180

NODE (4)

149 160
 150 161
 151 162
 152 163
 153 164
 155 166
 156 167
 157 168
 158 169
 159 170
 160 171
 161 172
 162 173
 163 174
 164 175
 166 177
 167 178
 168 179
 169 180
 170 181
 171 182
 172 183
 173 184
 174 185
 175 186
 177 188
 178 189
 179 190
 180 191
 181 192
 182 193
 183 194
 184 195
 185 196
 186 197

150
 151
 152
 153
 154
 156
 157
 158
 159
 160
 161
 162
 163
 164
 165
 167
 168
 169
 170
 171
 172
 173
 174
 175
 176
 177
 178
 179
 180
 181
 182
 183
 184
 185
 186
 187
 188
 189
 190
 191
 192
 193
 194
 195
 196
 197

CONTINUED

STREC181
 STREC182
 STREC183
 STREC184
 STREC185
 STREC186
 STREC187
 STREC188
 STREC189
 STREC190
 STREC191
 STREC192
 STREC193
 STREC194
 STREC195
 STREC196
 STREC197
 STREC198
 STREC199
 STREC200
 STREC201
 STREC202
 STREC203
 STREC204
 STREC205
 STREC206
 STREC207
 STREC208
 STREC209
 STREC210
 STREC211
 STREC212
 STREC213
 STREC214
 STREC215
 STREC216

NODE(4)

186	197	198	187
188	199	200	189
189	200	201	190
190	201	202	191
191	202	203	192
192	203	204	193
193	204	205	194
194	205	206	195
195	206	207	196
196	207	208	197
197	208	209	198
198	209	210	199
199	210	211	200
200	211	212	201
201	212	213	202
202	213	214	203
203	214	215	204
204	215	216	205
205	216	217	206
206	217	218	207
207	218	219	208
208	219	220	209
210	221	222	211
211	222	223	212
212	223	224	213
213	224	225	214
214	225	226	215
215	226	227	216
216	227	228	217
217	228	229	218
218	229	230	219
219	230	231	220
221	232	233	222
222	233	234	223
223	234	235	224

CCNT INUED

NODE(4)

224	235	236	225	STREC217
225	236	237	226	STREC218
226	237	238	227	STREC219
227	238	239	228	STRE0220
228	239	240	229	STRE0221
229	240	241	230	STRE0222
230	241	242	231	STRE0223
232	243	244	233	STRE0224
233	244	245	234	STRE0225
234	245	246	235	STRE0226
235	246	247	236	STRE0227
236	247	248	237	STRE0228
237	248	249	238	STRE0229
238	249	250	239	STRE0230
239	250	251	240	STRE0231
240	251	252	241	STRE0232
241	252	253	242	STRE0233
243	254	255	244	STRE0234
244	255	256	245	STRE0235
245	256	257	246	STRE0236
246	257	258	247	STRE0237
247	258	259	248	STRE0238
248	259	260	249	STRE0239
249	260	261	250	STRE0240
250	261	262	251	STRE0241
251	262	263	252	STRE0242
252	263	264	253	STRE0243
254	265	266	255	STRE0244
255	266	267	256	STRE0245
256	267	268	257	STRE0246
257	268	269	258	STRE0247
258	269	270	259	STRE0248
259	270	271	260	STRE0249
260	271	272	261	STRE0250

CONT INUED

STREC253
 STREC254
 STREC255
 STREC256
 STREC257
 STREC258
 STREC259
 STREC260
 STREC261
 STREC262
 STREC263
 STREC264
 STREC265
 STREC266
 STREC267
 STREC268
 STREC269
 STREC270
 STREC271
 STREC272
 STREC273
 STREC274
 STREC275
 STREC276
 STREC277
 STREC278
 STREC279
 STREC280
 STREC281
 STREC282
 STREC283
 STREC284
 STREC285
 STREC286
 STREC287
 STREC288

NODE(4)

261	272	273	262
262	273	274	263
263	274	275	264
265	276	277	266
266	277	278	267
267	278	279	268
268	279	280	269
269	280	281	270
270	281	282	271
271	282	283	272
272	283	284	273
273	284	285	274
274	285	286	275

REWRITE THE DIMENSIONS OF THE ELEMENT FOR CHECKING PURPOSES

X= 0.1440E 02 Y= 0.1440E 02

STRE0325
STRE0326
STRE0327
STRE0328
STRE0329
STRE0330
STRE0331
STRE0332
STRE0333
STRE0334
STRE0335
STRE0336
STRE0337
STRE0338
STRE0339
STRE0340
STRE0341
STRE0342
STRE0343
STRE0344
STRE0345
STRE0346
STRE0347
STRE0348
STRE0349
STRE0350
STRE0351
STRE0352
STRE0353
STRE0354
STRE0355
STRE0356
STRE0357
STRE0358
STRE0359
STRE0360

AVERAGE STRESSES PER NODE

NODE	STRESS-X	STRESS-Y	STRESS-XY
1	-0.15817E 02	-0.35259E 00	-0.82947E 00
2	-0.11975E 02	0.39103E 00	-0.85944E 00
3	-0.87827E 01	0.10301E 01	-0.92883E 00
4	-0.57741E 01	0.25077E 01	-0.11261E 01
5	-0.25470E 01	0.66964E 01	-0.19605E 01
6	-0.14305E-03	-0.21935E-04	-0.60700E 01
7	0.25467E 01	-0.66964E 01	-0.19605E 01
8	0.57738E 01	-0.25077E 01	-0.11261E 01
9	0.87824E 01	-0.10301E 01	-0.92884E 00
10	0.11975E 02	-0.39104E 00	-0.85947E 00
11	0.15817E 02	0.35258E 00	-0.32950E 00
12	-0.15555E 02	-0.37191E 00	-0.16243E 00
13	-0.11847E 02	0.29887E 00	-0.33833E 00
14	-0.86652E 01	0.72518E 00	-0.64555E 00
15	-0.57526E 01	0.12235E 01	-0.10760E 01
16	-0.30611E 01	0.38750E 00	-0.1492E 01
17	-0.14243E-03	-0.26688E-04	-0.30060E 01
18	0.30608E 01	-0.38755E 00	-0.14892E 01
19	0.57524E 01	-0.12235E 01	-0.10760E 01
20	0.86689E 01	-0.72521E 00	-0.64557E 00
21	0.11847E 02	-0.29889E 00	-0.33834E 00
22	0.15555E 02	0.37191E 00	-0.16243E 00
23	-0.15004E 02	-0.40571E 00	-0.26958E 00
24	-0.11497E 02	0.12273E 00	-0.55039E 00
25	-0.83754E 01	0.22270E 00	-0.99062E 00
26	-0.53866E 01	0.13113E 00	-0.13009E 01
27	-0.21920E 01	0.14870E 00	-0.14842E 01
28	-0.13453E-03	-0.47982E-04	-0.12868E 01
29	0.21918E 01	-0.14879E 00	-0.14843E 01

NODE	STRESS-X	STRESS-Y	STRESS-XY	CC	CONTINUED
30	0.53864E 01	-0.13119E 00	-0.13009E 01	01	STREC361
31	0.83751E 01	-0.22275E CC	-0.59064E C0	C0	STREC362
32	0.11497E 02	-0.12277E C0	-0.55041E 00	00	STREC363
33	0.150C4E 02	0.40569E 00	-0.26957E 00	00	STREC364
34	-0.14216E 02	-0.41456E C0	-0.30799E 00	00	STREC365
35	-0.11015E 02	0.69582E-03	-0.62179E C0	C0	STREC366
36	-0.80168E 01	-0.28738E-01	-0.10574E 01	01	STREC367
37	-0.50776E 01	-0.366C7E-01	-0.12889E 01	01	STREC368
38	-0.23936E 01	-0.336C0E-01	-0.13133E 01	01	STREC369
39	-0.128C5E-03	-0.624C6E-04	-0.13203E C1	C1	STREC370
40	0.23934E 01	0.33488E-01	-0.13133E C1	C1	STREC371
41	0.50773E 01	0.36518E-01	-0.12889E 01	01	STREC372
42	0.80165E 01	0.286C4E-01	-0.10575E C1	C1	STREC373
43	0.11015E 02	-0.76789E-03	-0.62180E C0	C0	STREC374
44	0.14216E 02	0.41459E C0	-0.30803E C0	C0	STREC375
45	-0.13395E 02	-0.39332E 00	-0.30397E 00	00	STREC376
46	-0.10488E 02	-0.37617E-01	-0.61269E 00	00	STREC377
47	-0.768C9E 01	-0.67026E-01	-0.10404E 01	01	STREC378
48	-0.49720E 01	-0.80078E-01	-0.12639E 01	01	STREC379
49	-0.24150E 01	-0.53128E-01	-0.13499E 01	01	STREC380
50	-0.12498E-03	-0.61512E-04	-0.13613E 01	01	STREC381
51	0.24148E 01	0.52977E-01	-0.13499E 01	01	STREC382
52	0.49718E 01	0.79913E-01	-0.12639E C1	C1	STREC383
53	0.768C7E 01	0.66880E-01	-0.10405E 01	01	STREC384
54	0.10488E 02	0.37342E-01	-0.61273E 00	00	STREC385
55	0.13394E C2	0.39291E 00	-0.30406E 00	00	STREC386
56	-0.12623E 02	-0.35956E 00	-0.28636E 00	00	STREC387
57	-0.996C2E 01	-0.32366E-01	-0.58458E C0	C0	STREC388
58	-0.73644E 01	-0.55976E-01	-0.10120E 01	01	STREC389
59	-0.48255E 01	-0.63652E-01	-0.12666E 01	01	STREC390
60	-0.23784E 01	-0.42585E-01	-0.13887E C1	C1	STREC391
61	-0.10589E-03	-0.86963E-04	-0.14239E 01	01	STREC392
62	0.23782E 01	0.42444E-01	-0.13887E 01	01	STREC393
63	0.48257E 01	0.63457E-01	-0.12666E 01	01	STREC394

NODE	STRESS-X	STRESS-Y	STRESS-XY	CCONTINUED	STRE
64	0.73641E 01	0.556C6E-01	-0.10120E C1		STRE0397
65	0.99599E 01	0.31954E-01	-0.58459E C0		STRE0398
66	0.12623E 02	0.35921E 00	-0.28638E 00		STRE0400
67	-0.11915E 02	-0.32844E 00	-0.27147E 00		STRE0401
68	-0.94433E 01	-0.20434E-01	-0.56096E C0		STRE0402
69	-0.70288E 01	-0.34812E-01	-0.99161E 00		STRE0403
70	-0.46422E 01	-0.40087E-01	-0.12702E 01		STRE0404
71	-0.23034E 01	-0.26962E-01	-0.14209E 01		STRE0405
72	-0.1052E-03	-0.17774E-03	-0.14675E 01		STRE0406
73	0.23031E 01	0.26650E-01	-0.14209E C1		STRE0407
74	0.46420E 01	0.39849E-01	-0.12703E 01		STRE0408
75	0.70285E 01	0.34552E-01	-0.99164E 00		STRE0409
76	0.94430E 01	0.19981E-01	-0.56092E 00		STRE0410
77	0.11915E 02	0.32783E C0	-0.27142E 00		STRE0411
78	-0.11251E 02	-0.30384E C0	-0.26218E C0		STRE0412
79	-0.89345E 01	-0.11016E-01	-0.54625E 00		STRE0413
80	-0.66767E 01	-0.18934E-01	-0.97872E 00		STRE0414
81	-0.44257E 01	-0.21958E-01	-0.12729E 01		STRE0415
82	-0.22061E 01	-0.14900E-01	-0.14406E 01		STRE0416
83	-0.93520E-04	-0.14472E-03	-0.14947E 01		STRE0417
84	0.22059E 01	0.14590E-01	-0.14406E 01		STRE0418
85	0.44255E 01	0.21657E-01	-0.12729E 01		STRE0419
86	0.66765E 01	0.18619E-01	-0.97871E C0		STRE0420
87	0.89343E 01	0.10640E-01	-0.54622E 00		STRE0421
88	0.1125CE 02	0.30336E 00	-0.26207E 00		STRE0422
89	-0.1061CE 02	-0.28339E C0	-0.25729E 00		STRE0423
90	-0.84318E 01	-0.54373E-02	-0.53840E C0		STRE0424
91	-0.63141E 01	-0.94026E-02	-0.97160E 00		STRE0425
92	-0.41958E 01	-0.10979E-01	-0.12742E 01		STRE0426
93	-0.20958E 01	-0.75713E-02	-0.14514E 01		STRE0427
94	-0.886C2E-04	-0.17375E-03	-0.15095E 01		STRE0428
95	0.20956E 01	0.72640E-02	-0.14514E 01		STRE0429
96	0.41956E 01	0.10629E-01	-0.12742E 01		STRE0430
97	0.63140E 01	0.89660E-02	-0.97153E C0		STRE0431
					STRE0432

NODE	STRESS-X	STRESS-Y	STRESS-XY	CONTINUED	STRESS-XY
98	0.84317E 01	0.50815E-02	-0.53834E 00		STRE0433
99	0.10610E 02	0.28310E 00	-0.25724E 00		STRE0434
100	-0.99809E 01	-0.26548E 00	-0.25502E 00		STRE0435
101	-0.79321E 01	-0.25954E-02	-0.53465E 00		STRE0436
102	-0.59464E 01	-0.43536E-02	-0.96805E 00		STRE0437
103	-0.39603E 01	-0.50570E-02	-0.12747E 01		STRE0438
104	-0.19784E 01	-0.34746E-02	-0.14568E 01		STRE0439
105	-0.82329E-04	-0.11158E-03	-0.15170E 01		STRE0440
106	0.19782E 01	0.31582E-02	-0.14567E 01		STRE0441
107	0.39602E 01	0.47038E-02	-0.12747E 01		STRE0442
108	0.59463E 01	0.40184E-02	-0.96794E 00		STRE0443
109	0.79320E 01	0.21513E-02	-0.53455E 00		STRE0444
110	0.99808E 01	0.26456E 00	-0.25497E 00		STRE0445
111	-0.93561E 01	-0.24835E 00	-0.25412E 00		STRE0446
112	-0.74364E 01	-0.12654E-02	-0.53303E 00		STRE0447
113	-0.55764E 01	-0.20210E-02	-0.96647E 00		STRE0448
114	-0.37161E 01	-0.22719E-02	-0.12750E 01		STRE0449
115	-0.18574E 01	-0.16333E-02	-0.14593E 01		STRE0450
116	-0.72081E-04	-0.78753E-04	-0.15205E 01		STRE0451
117	0.18573E 01	0.13674E-02	-0.14593E 01		STRE0452
118	0.37160E 01	0.18824E-02	-0.12749E 01		STRE0453
119	0.55763E 01	0.16212E-02	-0.96635E 00		STRE0454
120	0.74363E 01	0.89389E-03	-0.53255E 00		STRE0455
121	0.93561E 01	0.24800E 00	-0.25403E 00		STRE0456
122	-0.87325E 01	-0.23173E 00	-0.25382E 00		STRE0457
123	-0.69407E 01	-0.77638E-03	-0.53246E 00		STRE0458
124	-0.52054E 01	-0.99838E-03	-0.96589E 00		STRE0459
125	-0.34658E 01	-0.98239E-03	-0.12751E 01		STRE0460
126	-0.17347E 01	-0.71450E-03	-0.14603E 01		STRE0461
127	-0.79941E-04	-0.17148E-03	-0.15220E 01		STRE0462
128	0.17345E 01	0.38518E-03	-0.14604E 01		STRE0463
129	0.34657E 01	0.72634E-03	-0.12750E 01		STRE0464
130	0.52053E 01	0.63850E-03	-0.96575E 00		STRE0465
131	0.69406E 01	0.31966E-03	-0.53237E 00		STRE0466
					STRE0467
					STRE0468

NODE	STRESS-X	STRESS-Y	STRESS-XY	CCNTINUED	STREO
132	0.87329E 01	0.23136E 00	-0.25371E 00		STREO469
133	-0.81101E 01	-0.21510E 00	-0.25374E 00		STREO470
134	-0.64454E 01	-0.54605E-03	-0.53229E 00		STREO471
135	-0.48341E 01	-0.64297E-03	-0.96571E 00		STREO472
136	-0.32227E 01	-0.42865E-03	-0.12752E 01		STREO473
137	-0.16113E 01	-0.35426E-03	-0.14609E 01		STREO474
138	-0.86948E-04	-0.21867E-03	-0.15227E 01		STREO475
139	0.16112E 01	0.57772E-04	-0.14609E 01		STREO476
140	0.32225E 01	0.26144E-03	-0.12752E 01		STREO477
141	0.48340E 01	0.29129E-03	-0.96566E 00		STREO478
142	0.64453E 01	0.12177E-03	-0.53222E 00		STREO479
143	0.81102E 01	0.21484E 00	-0.25364E 00		STREO480
144	-0.74875E 01	-0.19875E 00	-0.25367E 00		STREO481
145	-0.59502E 01	-0.53382E-03	-0.53234E 00		STREO482
146	-0.44627E 01	-0.53383E-03	-0.96578E 00		STREO483
147	-0.29751E 01	-0.37608E-03	-0.12755E 01		STREO484
148	-0.14876E 01	-0.36742E-03	-0.14612E 01		STREO485
149	-0.11082E-03	-0.25509E-03	-0.15231E 01		STREO486
150	0.14874E 01	-0.13600E-03	-0.14612E 01		STREO487
151	0.29750E 01	0.27090E-04	-0.12754E 01		STREO488
152	0.44626E 01	0.23869E-03	-0.96574E 00		STREO489
153	0.59501E 01	0.18221E-03	-0.53223E 00		STREO490
154	0.74875E 01	0.19843E 00	-0.25356E 00		STREO491
155	-0.68647E 01	-0.18249E 00	-0.25376E 00		STREO492
156	-0.54550E 01	-0.57830E-03	-0.53247E 00		STREO493
157	-0.40913E 01	-0.60654E-03	-0.96604E 00		STREO494
158	-0.27275E 01	-0.43264E-03	-0.12757E 01		STREO495
159	-0.13638E 01	-0.27847E-03	-0.14615E 01		STREO496
160	-0.95555E-04	-0.17551E-03	-0.15234E 01		STREO497
161	0.13636E 01	-0.10492E-03	-0.14615E 01		STREO498
162	0.27274E 01	0.24438E-04	-0.12756E 01		STREO499
163	0.40911E 01	0.17807E-03	-0.96592E 00		STREO500
164	0.54549E 01	0.10940E-03	-0.53236E 00		STREO501
165	0.68644E 01	0.18190E 00	-0.25367E 00		STREO502

NODE	STRESS-X	STRESS-Y	STRESS-XY	CCNT	INUED
166	-0.62416E 01	-0.16587E 00	-0.25381E 00		STREC505
167	-0.49597E 01	-0.61464E-03	-0.53257E 00		STREC506
168	-0.37197E 01	-0.61055E-03	-0.96628E 00		STREC507
169	-0.24798E 01	-0.31137E-03	-0.12760E 01		STREC508
170	-0.12400E 01	-0.26077E-03	-0.14618E 01		STREC509
171	-0.10496E-03	-0.29904E-03	-0.15237E 01		STREC510
172	0.12398E 01	-0.12112E-03	-0.14617E 01		STREC511
173	0.24797E 01	-0.28148E-04	-0.12759E 01		STREC512
174	0.37196E 01	0.68903E-04	-0.96617E 00		STREC513
175	0.49596E 01	0.16196E-03	-0.53249E 00		STREC514
176	0.62412E 01	0.16551E 00	-0.25370E 00		STREC515
177	-0.56182E 01	-0.14934E 00	-0.25382E 00		STREC516
178	-0.44644E 01	-0.62275E-03	-0.53275E 00		STREC517
179	-0.33482E 01	-0.67526E-03	-0.96654E 00		STREC518
180	-0.22322E 01	-0.46055E-03	-0.12763E 01		STREC519
181	-0.11162E 01	-0.22641E-03	-0.14620E 01		STREC520
182	-0.68862E-04	-0.32246E-04	-0.15239E 01		STREC521
183	0.11160E 01	-0.14944E-03	-0.14619E 01		STREC522
184	0.22320E 01	-0.14137E-03	-0.12761E 01		STREC523
185	0.33481E 01	0.10931E-03	-0.96637E 00		STREC524
186	0.44642E 01	0.19422E-03	-0.53263E 00		STREC525
187	0.56181E 01	0.14915E 00	-0.25376E 00		STREC526
188	-0.49944E 01	-0.13287E 00	-0.25406E 00		STREC527
189	-0.39688E 01	-0.52164E-03	-0.53312E 00		STREC528
190	-0.29768E 01	-0.43666E-03	-0.96700E 00		STREC529
191	-0.19847E 01	-0.11733E-03	-0.12766E 01		STREC530
192	-0.99260E 00	-0.16178E-03	-0.14622E 01		STREC531
193	-0.14950E-03	-0.23443E-03	-0.15240E 01		STREC532
194	0.99229E 00	-0.25050E-03	-0.14620E 01		STREC533
195	0.19845E 01	-0.18986E-03	-0.12763E 01		STREC534
196	0.29765E 01	0.10931E-03	-0.96667E 00		STREC535
197	0.39688E 01	0.19823E-03	-0.53282E 00		STREC536
198	0.49947E 01	0.13257E 00	-0.25380E 00		STREC537
199	-0.43702E 01	-0.11623E 00	-0.25422E 00		STREC538

NODE	STRESS-X	STRESS-Y	STRESS-XY	CONTINUED	STRESS-X	STRESS-Y	STRESS-XY	CONTINUED
200	-0.34727E 01	-0.37206E-03	-0.53348E 00		-0.34727E 01	-0.37206E-03	-0.53348E 00	
201	-0.26053E 01	-0.20224E-03	-0.96753E 00		-0.26053E 01	-0.20224E-03	-0.96753E 00	
202	-0.17376E 01	0.23432E-03	-0.12769E 01		-0.17376E 01	0.23432E-03	-0.12769E 01	
203	-0.86911E 00	0.48497E-03	-0.14623E 01		-0.86911E 00	0.48497E-03	-0.14623E 01	
204	-0.16568E-03	0.18594E-03	-0.15239E 01		-0.16568E-03	0.18594E-03	-0.15239E 01	
205	0.86879E 00	-0.36778E-03	-0.14620E 01		0.86879E 00	-0.36778E-03	-0.14620E 01	
206	0.17372E 01	-0.57754E-03	-0.12765E 01		0.17372E 01	-0.57754E-03	-0.12765E 01	
207	0.26052E 01	-0.37178E-03	-0.96710E 00		0.26052E 01	-0.37178E-03	-0.96710E 00	
208	0.34730E 01	0.82254E-05	-0.53319E 00		0.34730E 01	0.82254E-05	-0.53319E 00	
209	0.43709E 01	0.11616E 00	-0.25410E 00		0.43709E 01	0.11616E 00	-0.25410E 00	
210	-0.37452E 01	-0.99713E-01	-0.25455E 00		-0.37452E 01	-0.99713E-01	-0.25455E 00	
211	-0.29764E 01	-0.27502E-03	-0.53411E 00		-0.29764E 01	-0.27502E-03	-0.53411E 00	
212	-0.22341E 01	0.24237E-03	-0.96818E 00		-0.22341E 01	0.24237E-03	-0.96818E 00	
213	-0.14909E 01	0.81234E-03	-0.12771E 01		-0.14909E 01	0.81234E-03	-0.12771E 01	
214	-0.74609E 00	0.72758E-03	-0.14618E 01		-0.74609E 00	0.72758E-03	-0.14618E 01	
215	-0.25055E-03	0.21023E-03	-0.15234E 01		-0.25055E-03	0.21023E-03	-0.15234E 01	
216	0.74565E 00	-0.63054E-03	-0.14618E 01		0.74565E 00	-0.63054E-03	-0.14618E 01	
217	0.14906E 01	-0.11155E-02	-0.12769E 01		0.14906E 01	-0.11155E-02	-0.12769E 01	
218	0.22342E 01	-0.85688E-03	-0.96798E 00		0.22342E 01	-0.85688E-03	-0.96798E 00	
219	0.29768E 01	-0.51327E-03	-0.53400E 00		0.29768E 01	-0.51327E-03	-0.53400E 00	
220	0.37459E 01	0.99062E-01	-0.25452E 00		0.37459E 01	0.99062E-01	-0.25452E 00	
221	-0.31178E 01	-0.82416E-01	-0.25555E 00		-0.31178E 01	-0.82416E-01	-0.25555E 00	
222	-0.24757E 01	0.48050E-03	-0.53553E 00		-0.24757E 01	0.48050E-03	-0.53553E 00	
223	-0.18640E 01	0.11074E-02	-0.96932E 00		-0.18640E 01	0.11074E-02	-0.96932E 00	
224	-0.12453E 01	0.17906E-02	-0.12771E 01		-0.12453E 01	0.17906E-02	-0.12771E 01	
225	-0.62340E 00	0.13057E-02	-0.14611E 01		-0.62340E 00	0.13057E-02	-0.14611E 01	
226	-0.21017E-03	-0.52482E-04	-0.15223E 01		-0.21017E-03	-0.52482E-04	-0.15223E 01	
227	0.62305E 00	-0.13986E-02	-0.14611E 01		0.62305E 00	-0.13986E-02	-0.14611E 01	
228	0.12450E 01	-0.23444E-02	-0.12771E 01		0.12450E 01	-0.23444E-02	-0.12771E 01	
229	0.18639E 01	-0.21221E-02	-0.96918E 00		0.18639E 01	-0.21221E-02	-0.96918E 00	
230	0.24800E 01	-0.11277E-02	-0.53546E 00		0.24800E 01	-0.11277E-02	-0.53546E 00	
231	0.31186E 01	0.82133E-01	-0.25553E 00		0.31186E 01	0.82133E-01	-0.25553E 00	
232	-0.24854E 01	-0.64012E-01	-0.25739E 00		-0.24854E 01	-0.64012E-01	-0.25739E 00	
233	-0.19820E 01	0.16936E-02	-0.53766E 00		-0.19820E 01	0.16936E-02	-0.53766E 00	

NODE	STRESS-X	STRESS-Y	STRESS-XY	CONTINUED	STRESS-X	STRESS-Y	STRESS-XY	CONTINUED
234	-0.14964E 01	0.25586E-02	-0.97044E 00		-0.14964E 01	0.25586E-02	-0.97044E 00	STREC577
235	-0.10008E 01	0.27567E-02	-0.12762E 01		-0.10008E 01	0.27567E-02	-0.12762E 01	STREC578
236	-0.50057E 00	0.14592E-02	-0.14598E 01		-0.50057E 00	0.14592E-02	-0.14598E 01	STREC579
237	-0.16166E-03	-0.52547E-03	-0.15212E 01		-0.16166E-03	-0.52547E-03	-0.15212E 01	STREC580
238	0.50021E 00	-0.22757E-02	-0.14598E 01		0.50021E 00	-0.22757E-02	-0.14598E 01	STREC581
239	0.10006E 01	-0.33065E-02	-0.12763E 01		0.10006E 01	-0.33065E-02	-0.12763E 01	STREC582
240	0.14962E 01	-0.33388E-02	-0.97030E 00		0.14962E 01	-0.33388E-02	-0.97030E 00	STREC583
241	0.19831E 01	-0.23929E-02	-0.53756E 00		0.19831E 01	-0.23929E-02	-0.53756E 00	STREC584
242	0.24864E 01	0.63786E-01	-0.25733E 00		0.24864E 01	0.63786E-01	-0.25733E 00	STREC585
243	-0.18416E 01	-0.42265E-01	-0.25983E 00		-0.18416E 01	-0.42265E-01	-0.25983E 00	STREC586
244	-0.14854E 01	0.28375E-02	-0.54028E 00		-0.14854E 01	0.28375E-02	-0.54028E 00	STREC587
245	-0.11333E 01	0.31043E-02	-0.96918E 00		-0.11333E 01	0.31043E-02	-0.96918E 00	STREC588
246	-0.75523E 00	0.20655E-02	-0.12741E 01		-0.75523E 00	0.20655E-02	-0.12741E 01	STREC589
247	-0.37523E 00	-0.43258E-03	-0.14594E 01		-0.37523E 00	-0.43258E-03	-0.14594E 01	STREC590
248	-0.64614E-04	-0.74380E-03	-0.15225E 01		-0.64614E-04	-0.74380E-03	-0.15225E 01	STREC591
249	0.37455E 00	-0.84884E-03	-0.14594E 01		0.37455E 00	-0.84884E-03	-0.14594E 01	STREC592
250	0.75457E 00	-0.31003E-02	-0.12742E 01		0.75457E 00	-0.31003E-02	-0.12742E 01	STREC593
251	0.11330E 01	-0.43858E-02	-0.96934E 00		0.11330E 01	-0.43858E-02	-0.96934E 00	STREC594
252	0.14855E 01	-0.37834E-02	-0.54042E 00		0.14855E 01	-0.37834E-02	-0.54042E 00	STREC595
253	0.18426E 01	0.42039E-01	-0.25989E 00		0.18426E 01	0.42039E-01	-0.25989E 00	STREC596
254	-0.11766E 01	-0.19124E-01	-0.26284E 00		-0.11766E 01	-0.19124E-01	-0.26284E 00	STREC597
255	-0.10054E 01	-0.11323E-03	-0.53751E 00		-0.10054E 01	-0.11323E-03	-0.53751E 00	STREC598
256	-0.77068E 00	-0.25264E-02	-0.96491E 00		-0.77068E 00	-0.25264E-02	-0.96491E 00	STREC599
257	-0.50325E 00	-0.91556E-02	-0.12721E 01		-0.50325E 00	-0.91556E-02	-0.12721E 01	STREC600
258	-0.24583E 00	-0.90707E-02	-0.14647E 01		-0.24583E 00	-0.90707E-02	-0.14647E 01	STREC601
259	-0.11314E-03	-0.12410E-02	-0.15285E 01		-0.11314E-03	-0.12410E-02	-0.15285E 01	STREC602
260	0.24567E 00	0.68475E-02	-0.14647E 01		0.24567E 00	0.68475E-02	-0.14647E 01	STREC603
261	0.50256E 00	0.71426E-02	-0.12724E 01		0.50256E 00	0.71426E-02	-0.12724E 01	STREC604
262	0.77026E 00	0.48100E-03	-0.96512E 00		0.77026E 00	0.48100E-03	-0.96512E 00	STREC605
263	0.10056E 01	-0.10429E-02	-0.53757E 00		0.10056E 01	-0.10429E-02	-0.53757E 00	STREC606
264	0.11779E 01	0.18950E-01	-0.26344E 00		0.11779E 01	0.18950E-01	-0.26344E 00	STREC607
265	-0.51954E 00	0.69040E-02	-0.21725E 00		-0.51954E 00	0.69040E-02	-0.21725E 00	STREC608
266	-0.51042E 00	-0.22830E-01	-0.52644E 00		-0.51042E 00	-0.22830E-01	-0.52644E 00	STREC609
267	-0.38930E 00	-0.43724E-01	-0.97207E 00		-0.38930E 00	-0.43724E-01	-0.97207E 00	STREC610

NODE	STRESS-X	STRESS-Y	STRESS-XY	CCNTI NUED	STRECE613
268	-0.253 C7E 00	-0.421 68E-01	-0.129 34E 01		STRECE614
269	-0.122 45E 00	-0.209 10E-01	-0.147 21E 01		STRECE615
270	-0.462 55E-04	-0.122 42E-02	-0.153 92E C1		STRECE616
271	0.122 46E 00	0.180 C2E-01	-0.147 22E 01		STRECE617
272	0.252 88E 00	0.392 C9E-01	-0.129 35E 01		STRECE618
273	0.389 15E 00	0.412 63E-01	-0.972 31E C0		STRECE619
274	0.510 12E 00	0.196 C5E-01	-0.526 59E 00		STRECE620
275	0.520 2CE 00	-0.106 19E-01	-0.217 86E C0		STRECE621
276	-0.301 57E 00	-0.380 11E C0	-0.170 64E 00		STRECE622
277	-0.328 74E 00	-0.372 25E C0	-0.521 69E 00		STRECE623
278	-0.236 29E 00	-0.263 C4E 00	-0.988 78E 00		STRECE624
279	-0.132 55E 00	-0.702 45E-01	-0.132 19E 01		STRECE625
280	-0.557 82E-01	0.982 25E-02	-0.147 50E C1		STRECE626
281	-0.124 52E-03	-0.172 89E-02	-0.154 40E 01		STRECE627
282	0.558 65E-01	-0.129 55E-C1	-0.147 52E C1		STRECE628
283	0.132 26E C0	0.660 49E-01	-0.132 18E 01		STRECE629
284	0.235 87E 00	0.258 C9E 00	-0.989 38E 00		STRECE630
285	0.328 C3E 00	0.367 55E C0	-0.522 26E 00		STRECE631
286	0.302 61E 00	0.376 39E 00	-0.170 66E 00		STRECE632
					STRECE633

STCC 1144 ID# 28436 STCC 1144 ID# 28437 STCC 1144 ID# 28438 ST1462C 1144 ID# 28439
 OCU 1144 ID# 199357 OCU 1144 ID# 28440
 STCC 1144 ID# 28442 STCC 1144 ID# 28443 STCC 1144 ID# 28444 STCC 1144 ID# 28445
 OCU 1144 ID# 199367 OCU 1144 ID# 28446
 STCC 1144 ID# 28448 STCC 1144 ID# 28449 STCC 1144 ID# 28450 ST1462C 1144 ID# 28451
 OCU 1144 ID# 199377 OCU 1144 ID# 28452
 STCC 1144 ID# 28454 STCC 1144 ID# 28455 STCC 1144 ID# 28456 ST1462C 1144 ID# 28457
 OCU 1144 ID# 199387 OCU 1144 ID# 28458
 STCC 1144 ID# 28460 STCC 1144 ID# 28461 STCC 1144 ID# 28462 ST1462C 1144 ID# 28463
 OCU 1144 ID# 199397 OCU 1144 ID# 28464
 STCC 1144 ID# 28466 STCC 1144 ID# 28467 STCC 1144 ID# 28468 ST1462C 1144 ID# 28469
 OCU 1144 ID# 199407 OCU 1144 ID# 28470
 STCC 1144 ID# 28472 STCC 1144 ID# 28473 STCC 1144 ID# 28474 ST1462C 1144 ID# 28475
 OCU 1144 ID# 199417 OCU 1144 ID# 28476
 STCC 1144 ID# 28478 STCC 1144 ID# 28479 STCC 1144 ID# 28480 ST1462C 1144 ID# 28481
 OCU 1144 ID# 199427 OCU 1144 ID# 28482
 STCC 1144 ID# 28484 STCC 1144 ID# 28485 STCC 1144 ID# 28486 ST1462C 1144 ID# 28487
 OCU 1144 ID# 199437 OCU 1144 ID# 28488
 STCC 1144 ID# 28490 STCC 1144 ID# 28491 STCC 1144 ID# 28492 ST1462C 1144 ID# 28493
 OCU 1144 ID# 199447 OCU 1144 ID# 28494
 STCC 1144 ID# 28496 STCC 1144 ID# 28497 STCC 1144 ID# 28498 ST1462C 1144 ID# 28499
 OCU 1144 ID# 199457 OCU 1144 ID# 28500

STAC 600 ZH = 4257.25 YC STAC 600 ZH = 4336.15 YC STAC 600 ZH = 4715.05 YC STAC 600 ZH = 4794.95 YC
 YC 600 ZH = 4628.00 YC 600 ZH = 4673.11
 STAC 700 ZH = 4338.00 YC STAC 700 ZH = 4397.00 YC STAC 700 ZH = 4715.50 YC STAC 700 ZH = 4794.125 YC
 YC 700 ZH = 4628.00 YC 700 ZH = 4673.11
 STAC 800 ZH = 4047.990 YC STAC 800 ZH = 4136.00 YC STAC 800 ZH = 4694.00 YC STAC 800 ZH = 4794.00 YC
 YC 800 ZH = 4154.20 YC 800 ZH = 4209.99
 STAC 900 ZH = 4242.990 YC STAC 900 ZH = 4331.00 YC STAC 900 ZH = 4715.50 YC STAC 900 ZH = 4794.00 YC
 YC 900 ZH = 4272.00 YC 900 ZH = 4327.38
 STAC 1000 ZH = 4248.990 YC STAC 1000 ZH = 4337.00 YC STAC 1000 ZH = 4715.50 YC STAC 1000 ZH = 4794.00 YC
 YC 1000 ZH = 4399.00 YC 1000 ZH = 4394.38
 STAC 1100 ZH = 4250.990 YC STAC 1100 ZH = 4403.00 YC STAC 1100 ZH = 4715.50 YC STAC 1100 ZH = 4794.00 YC
 YC 1100 ZH = 4545.00 YC 1100 ZH = 4540.21
 STAC 1200 ZH = 4252.990 YC STAC 1200 ZH = 4409.00 YC STAC 1200 ZH = 4715.50 YC STAC 1200 ZH = 4794.00 YC
 YC 1200 ZH = 4724.00 YC 1200 ZH = 4719.37
 STAC 1300 ZH = 4254.990 YC STAC 1300 ZH = 4415.00 YC STAC 1300 ZH = 4715.50 YC STAC 1300 ZH = 4794.00 YC
 YC 1300 ZH = 4872.00 YC 1300 ZH = 4867.37
 STAC 1400 ZH = 4256.990 YC STAC 1400 ZH = 4421.00 YC STAC 1400 ZH = 4715.50 YC STAC 1400 ZH = 4794.00 YC
 YC 1400 ZH = 4916.00 YC 1400 ZH = 4911.37
 STAC 1500 ZH = 4258.990 YC STAC 1500 ZH = 4427.00 YC STAC 1500 ZH = 4715.50 YC STAC 1500 ZH = 4794.00 YC
 YC 1500 ZH = 4960.00 YC 1500 ZH = 4955.37
 STAC 1600 ZH = 4260.990 YC STAC 1600 ZH = 4433.00 YC STAC 1600 ZH = 4715.50 YC STAC 1600 ZH = 4794.00 YC
 YC 1600 ZH = 5004.00 YC 1600 ZH = 4999.37
 STAC 1700 ZH = 4262.990 YC STAC 1700 ZH = 4439.00 YC STAC 1700 ZH = 4715.50 YC STAC 1700 ZH = 4794.00 YC
 YC 1700 ZH = 5048.00 YC 1700 ZH = 5043.37

STX(17,, ZI# -5.1600E-01 STY(17,, ZI# -5.3280E-03 STX(17,, ZI# -0.1381E-01 SIGMAZ(17,, ZI# -0.2396E-01
 X(18,, ZI# 269.80 Y(18,, ZI# 6.4923
 STX(18,, ZI# -0.7636E-03 STY(18,, ZI# -0.1739E-03 STX(18,, ZI# -0.1676E-01 SIGMAZ(18,, ZI# -0.1337E-01
 X(19,, ZI# 259.20 Y(19,, ZI# 73.724
 STX(19,, ZI# -0.1229E-03 STY(19,, ZI# -0.1239E-03 STX(19,, ZI# -0.1817E-01 SIGMAZ(19,, ZI# -0.1366E-01
 X(20,, ZI# 273.60 Y(20,, ZI# 66.436
 STX(20,, ZI# -0.5791E-03 STY(20,, ZI# -0.2790E-03 STX(20,, ZI# -0.1639E-01 SIGMAZ(20,, ZI# -0.1390E-01
 X(21,, ZI# 289.00 Y(21,, ZI# 115.922
 STX(21,, ZI# -0.1859E-03 STY(21,, ZI# -0.2379E-03 STX(21,, ZI# -0.2876E-01 SIGMAZ(21,, ZI# -0.1392E-01
 TRAJECTORY ZI 15 000 THE PLATE
 X(22,, ZI# 299.40 Y(22,, ZI# 18.00
 STX(22,, ZI# -0.2605E-03 STY(22,, ZI# -0.2739E-03 STX(22,, ZI# -0.2573E-01 SIGMAZ(22,, ZI# -0.4165E-01
 X(23,, ZI# 300.00 Y(23,, ZI# 39.00
 STX(23,, ZI# -0.8793E-03 STY(23,, ZI# -0.1793E-03 STX(23,, ZI# -0.2299E-01 SIGMAZ(23,, ZI# -0.8873E-01
 X(24,, ZI# 300.00 Y(24,, ZI# 50.00
 STX(24,, ZI# -0.4624E-03 STY(24,, ZI# -0.2707E-03 STX(24,, ZI# -0.2618E-01 SIGMAZ(24,, ZI# -0.4674E-01
 X(25,, ZI# 300.00 Y(25,, ZI# 61.891
 STX(25,, ZI# -0.2923E-03 STY(25,, ZI# -0.2250E-03 STX(25,, ZI# -0.1398E-01 SIGMAZ(25,, ZI# -0.2365E-01
 X(26,, ZI# 300.00 Y(26,, ZI# 73.893
 STX(26,, ZI# -0.7359E-03 STY(26,, ZI# -0.2310E-03 STX(26,, ZI# -0.1153E-01 SIGMAZ(26,, ZI# -0.2236E-01
 X(27,, ZI# 300.00 Y(27,, ZI# 85.927
 STX(27,, ZI# -0.6345E-03 STY(27,, ZI# -0.2366E-03 STX(27,, ZI# -0.1153E-01 SIGMAZ(27,, ZI# -0.2366E-01
 X(28,, ZI# 300.00 Y(28,, ZI# 97.979

001 300 50# 23,000 Y00 300 50# 86,623
 ST00 300 50# -291,600 01 STY0 300 50# 1,1377 01 ST000 300 50# -2197 01 ST09A20 300 50# -1,65810 01
 001 400 50# 43,200 Y00 400 50# 33,765
 ST00 400 50# -50,3700 01 STY0 400 50# -1,9030 01 ST000 400 50# -2197 01 ST09A20 400 50# -1,35790 01
 001 500 50# 57,600 Y00 500 50# 50,273
 ST00 500 50# -52,1650 01 STY0 500 50# -1,8150 01 ST000 500 50# -2197 01 ST09A20 500 50# -1,29050 01
 001 600 50# 72,000 Y00 600 50# 57,454
 ST00 600 50# -62,5570 01 STY0 600 50# -1,7130 01 ST000 600 50# -2197 01 ST09A20 600 50# -1,17910 01
 001 700 50# 86,400 Y00 700 50# 86,400
 ST00 700 50# -81,1770 01 STY0 700 50# -1,2230 01 ST000 700 50# -2197 01 ST09A20 700 50# -1,17910 01
 001 800 50# 100,800 Y00 800 50# 141,111
 ST00 800 50# -122,770 01 STY0 800 50# -1,2230 01 ST000 800 50# -2197 01 ST09A20 800 50# -1,23650 01
 ST000210,000 801 15 00 100 01 01#
 001 900 50# 115,200 Y00 900 50# 159,000
 ST00 900 50# -121,150 01 STY0 900 50# -1,1320 01 ST000 900 50# -2197 01 ST09A20 900 50# -1,29700 01
 001100 50# 000 001100 50# 57,600
 ST001100 50# -52,2590 01 STY01100 50# -1,2230 01 ST001100 50# -2197 01 ST09A201100 50# -1,29990 01
 001 200 50# 14,400 001 200 50# 62,623
 ST00 200 50# -50,1930 01 STY0 200 50# -1,2520 01 ST000 200 50# -2197 01 ST09A20 200 50# -1,3180 01
 001 300 50# 28,800 001 300 50# 75,654
 ST00 300 50# -52,2520 01 STY0 300 50# -1,1710 01 ST000 300 50# -2197 01 ST09A20 300 50# -1,1190 01
 001 400 50# 43,200 001 400 50# 100,253

XFC 200 90# 5.769 YFC 200 90# 199.000

STXC 200 90# 0.1573E 02 STYC 200 90# 0.3000E 01 STYZ 200 90# 0.2502E 01 SIGMAZ 20 90# 0.3398E 00

XFC100 90# 0.00 YFC100 90# 115.20

STXC100 90# 0.4878E 01 STYC100 90# 0.0110E 01 STYZ100 90# 0.0000E 00 SIGMAZ100 90# 0.1117E 01

TRAJECTORY 90 IS OFF THE PLATE

XFC 200 90# 2.702 YFC 200 90# 199.000

STXC 200 90# 0.1577E 02 STYC 200 90# 0.3000E 01 STYZ 200 90# 0.2700E 01 SIGMAZ 20 90# 0.3261E 00

XFC100 100# 0.00 YFC100 100# 100.00

STXC100 100# 0.1150E 02 STYC100 100# 0.0000E 01 STYZ100 100# 0.0000E 00 SIGMAZ100 100# 0.0000E 00

TRAJECTORY 100 IS OFF THE PLATE

XFC 200 100# 5.769 YFC 200 100# 199.000

STXC 200 100# 0.1567E 02 STYC 200 100# 0.3000E 01 STYZ 200 100# 0.2700E 01 SIGMAZ 20 100# 0.3193E 00

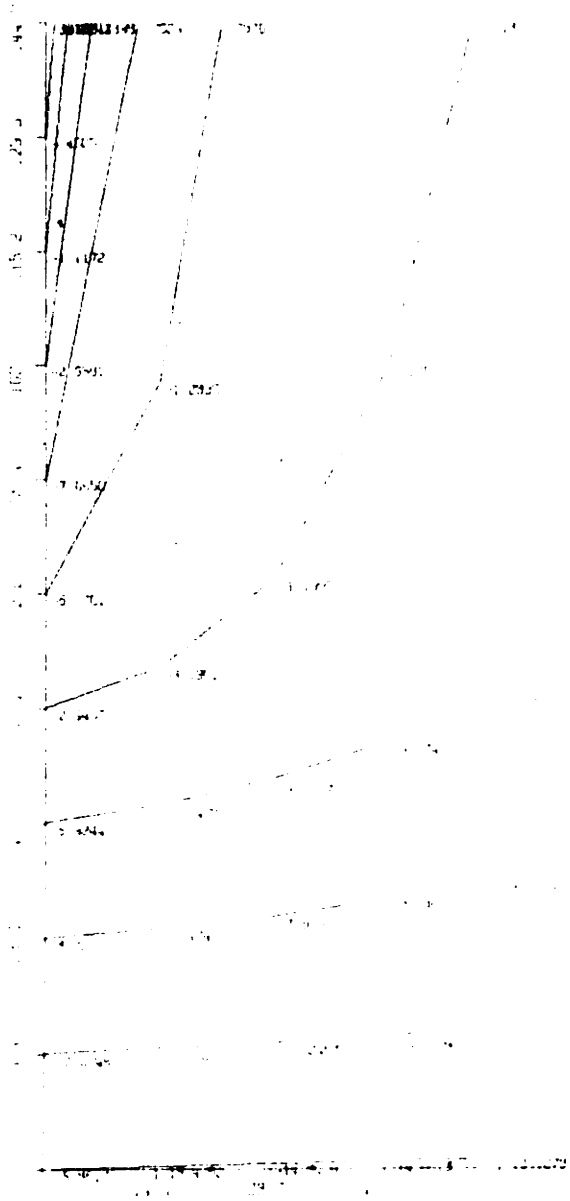
XFC100 100# 0.00 YFC100 100# 100.00

STXC100 100# 0.1570E 02 STYC100 100# 0.3000E 01 STYZ100 100# 0.2700E 01 SIGMAZ100 100# 0.3097E 00

TRAJECTORY 100 IS OFF THE PLATE

XFC 200 100# 7.200 YFC 200 100# 199.000

STXC 200 100# 0.1580E 02 STYC 200 100# 0.3000E 01 STYZ 200 100# 0.2700E 01 SIGMAZ 20 100# 0.3082E 00



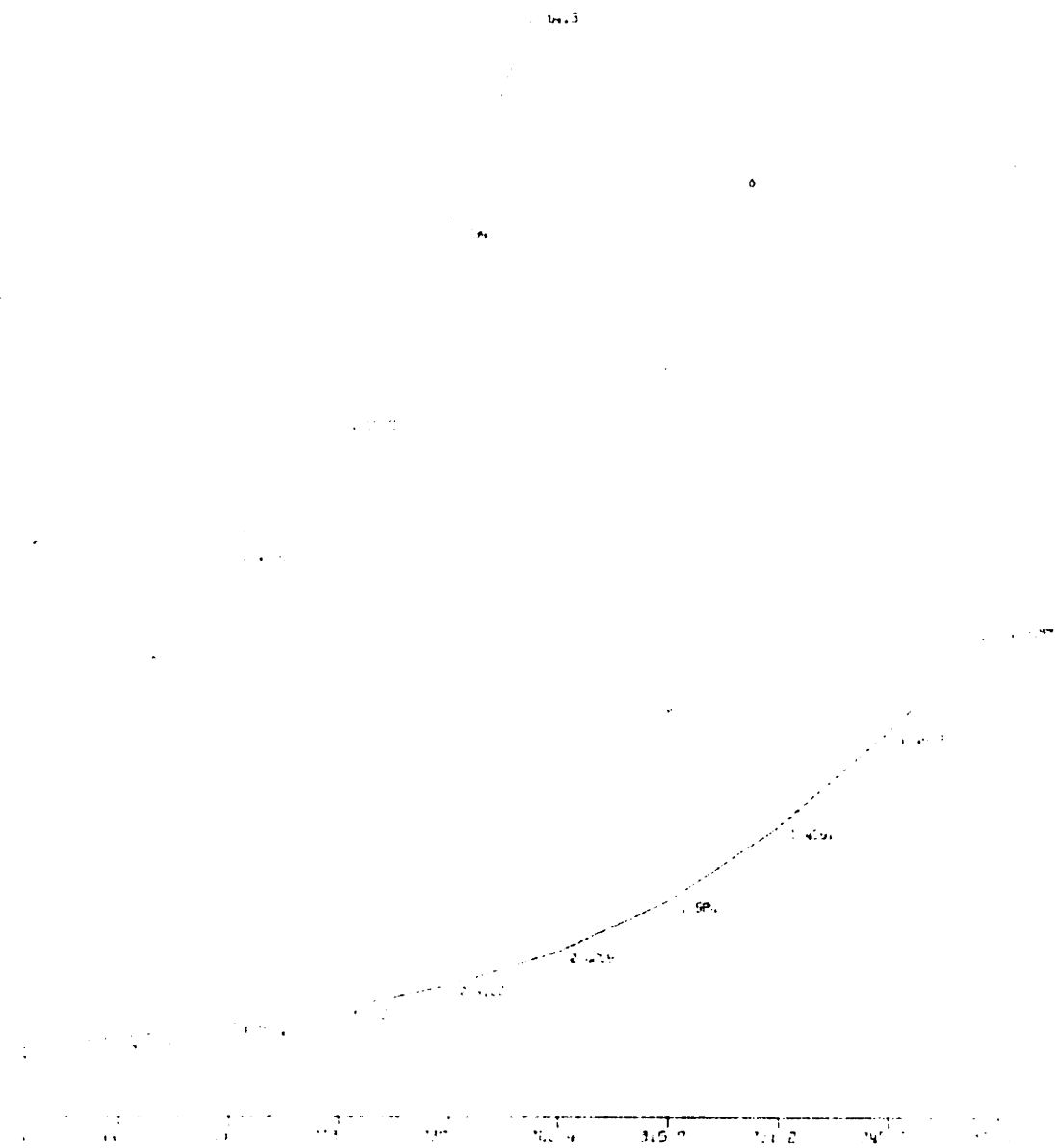


PLATE I

THE FOLLOWING IS A MESSAGE CODE THAT THE JCB HAS BEEN COMPLETED

PLOTS COMPLETED

PLTT0001
PLTT0002
PLTT0003
PLTT0004

REFERENCES

- (1) Cox, H. L., The Design of Structures of Least Weight, Pergamon Press Ltd., Oxford, 1965
- (2) Maxwell, James Clerk, Scientific Papers II, Cambridge University Press, Chapter XXXIX, pp. 175-177, 1890
- (3) Norris, C. H. and Wilbur, J. B., Elementary Structural Analysis, McGraw-Hill Book Company, New York, 1960
- (4) Michell, A. G. M., "The Limits of Economy of Material in Frame Structures," Philosophical Magazine, S. 6, Vol. 8, No. 47, 1904
- (5) Woods, W. J. and Sams, J. H., III, "Geometric Optimization in the Theory of Structural Synthesis," AJAA Paper No. 68-330, AIAA/ASME 9th Structures, Structural Dynamics and Materials Conference, Palm Springs, California, April 1-3, 1968
- (6) Hemp, W. S., "Studies in the Theory of Michell Structures," Proceedings of the Eleventh International Congress of Applied Mechanics, Munich, 1964, Springer-Verlag, Berlin, 1966, pp. 621-628
- (7) Barnett, Ralph L., "Survey of Optimum Structural Design," Experimental Mechanics, Vol. 6, No. 12, December, 1966, pp. 19A-26A
- (8) Crandall, S. H. and Dahl, N. C., An Introduction to the Mechanics of Solids, McGraw-Hill Book Company, Inc., New York, 1959
- (9) Richards, D. M. and Chan, H. S. Y., "Developments in the Theory of Michell Optimum Structures," AGARD Report 543, April, 1966
- (10) Cox, H. L., "The Theory of Design," Vol. 19, No. 791, Strut. 2037, Aeronautical Research Council (British), January 13, 1958
- (11) Hendry, A. W., "The Stress Distribution in a Simply Supported Beam," Proceedings of the Society for Experimental Stress Analysis, Vol. VII, No. 2
- (12) Flügge, Wilhelm, Stress in Shells, New York, 1966

- (13) Hovgaard, William, Structural Design of Warships, United States Naval Institute, Annapolis, Maryland, 1940, Plate I.
- (14) Rengos, Constantinos, "Optimum Stiffening of Plates under Two-Dimensional Loading by Means of Stress Trajectories," S.B. Thesis, Department of Naval Architecture, M.I.T., June, 1969
- (15) Zienkievich, O. C., The Finite Element Method in Structural and Continuum Mechanics, McGraw-Hill Publishing Company, Ltd., London, 1967
- (16) Timoshenko, S. and Goodier, J. N., Theory of Elasticity, McGraw-Hill Book Company, New York, 1951
- (17) Kotanchik, J. J., "Solution of a General Set of Linear Algebraic Equations of the Form $[A]\{U\} = \{Q\}$," Massachusetts Institute of Technology, Aeroelastic and Structures Research Laboratory, ASRL, Coded May 7, 1970, (updated June 23, 1970)
- (18) Calcomp Plotter Subroutines for the IBM 360, Massachusetts Institute of Technology Information Processing Services Center, August 9, 1968
- (19) Navy Department Bureau of Ships, "Design Data for Tee Stiffeners," No. 017969, DDS 1100-3, June 1, 1944