STEADY STATE ANALYSIS OF PIPING NETWORKS

by

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ABSTRACT

The author has developed a computer program to solve for the steady state response of arbitrary piping networks consisting of pipes, control valves and ideal pressure and flow sources. Recommendations are given for extension of the program to accommodate a greater variety of network elements. It is believed this program can easily be incorporated into a model of the energy interactions in the MIT Chilled Water Distribution System.

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I. INTRODUCTION

A project is under way at the Massachusetts Institute of Technology to implement centralized computer control of the environmental parameters in the academic and administrative buildings. Set points on thermostats, air vent openings, etc., will be modified according to the demands of building usage. The purpose of such control is, of course, to attempt to save energy. Achievement of this goal is threatened, however, by the following consideration.

The air conditioning systems in several buildings require chilled water as coolant. Water is chilled at a central plant where it is pumped through a three loop primary system. Each building has its own circulating pump to tap off the primary and is thus a secondary circulating system. The central plant is designed to operate at specified inlet and outlet temperatures and, naturally, runs at reduced efficiency when these temperatures vary from the ideal.

The proposed computer control system will <u>not</u>
directly control the primary chilled water system. It
will, however, indirectly control flow in the building
secondary systems and thus tend to greatly vary the plant

inlet temperature. This implies the plant will be running at lower efficiency and will, therefore, be wasting energy.

The next logical step is, therefore, to implement some form of control to maintain the desired plant inlet and outlet temperatures. The design of an effective control scheme requires a mathematical model of the energy interactions within the distribution system. As a first step in the development of such a model, this paper presents a FORTRAN computer program which allows the user to solve for the steady state pressures and flows in arbitrary piping networks. Section II explains the theory required to understand the program implementation described in Section III. At present, the only permissible network elements are pipes, control valves, and ideal constant pressure and flow sources. However, extension of the program to handle a larger variety of elements is straightforward and is discussed in Section IV. The FORTRAN source code and a sample network analysis are included in the Appendix.

II. THEORETICAL BACKGROUND

2.1 Pipes and Valves.

Mathematical approximations to the pressure-flow characteristics of pipes and control valves are well known. Assuming turbulent flow, the following equation has been used for pipes:

$$P = a_{+} Q|Q|^{3/4}$$
 (1)

where P is the pressure drop across the pipe, Q is the volume flow rate and a_t is a constant "whose value dependens on the flow rate at which transition to turbulent flow occurs, the dimensions of the pipe (diameter and length), the properties of the fluid (density and viscosity) and the roughness of the inner walls of the pipe."

Since a control valve is nothing more than a variable orifice, the following equation for the pressure drop across an orifice has been used:

$$P = a_{Q} Q |Q| \qquad (2)$$

where a is a function of the fluid density and the valve geometry. 2

At present, the program requires the user to input both a and a explicitly. A simple modification

could cause these constants to be calculated from parameters which might be more readily available.

2.2 Linear Graph Theory

The theory which follows attempts to define a procedure for deriving the network governing equations.

Piping networks lend themselves quite readily to representation as linear graphs. The following definitions and relationships apply to linear graphs in general.

Definition 1: Graph Edges and Vertices

"A linear graph is a set of line segments referred to as edges. End-point intersections of these edges are called vertices. All line segments are interconnected in such a way that the edges are only incident with the vertices." The terms edge, branch, and element will be used interchangeably as will the terms vertex and node. Definition 2: Circuit Loop

"If one begins at an initial vertex point of a graph and traverses through edges and vertices... until reaching the initial vertex without crossing any vertex more than once, the closed path traversed is called a circuit loop." The terms circuit loop, circuit and loop will be used interchangeably.

Definition 3: Tree and Branch

"A tree T of some graph G consists of a subpart of the original graph. It contains all vertices of G but no circuits. The edges forming this subpart...are referred to as tree branches." A given graph can have many possible trees.

Definition 4: Link

For a particular choice of tree, a link is an edge which is not one of the tree branches.

Definition 5: Fundamental Circuit

A fundamental circuit is defined with respect to a particular tree of a given graph. It is a circuit which contains one and only one link. For a given link there is a unique fundamental circuit.

It is easily shown that the number of links, L , and therefore the number of fundamental circuits, is given by

$$L = E - V + 1 \tag{3}$$

where E is the number of edges in the graph and V is the number of vertices.

It is well known that an analogy may be drawn between piping networks and electrical networks where pressure corresponds to voltage and volume flow rate corresponds to current. Pursuing this analogy, Kirchhoff's Voltage

Law (KVL) and Kirchhoff's Current Law (KCL) may be applied.

If one were to write the KVL equations for all possible loops in a given network, it would soon be apparent that some of the equations are not independent. In fact, there are exactly L independent KVL equations. One set of such equations may be obtained by choosing any tree of the network and writing KVL for each of the resulting fundamental circuits. Obviously, only L of the variables in these equations are independent. Since the link pressures each appear only once in the set and since they all appear in different equations, they must be the L independent variables.

For non-linear networks, such as piping networks, it is not convenient to express the remaining tree pressures directly in terms of the link pressures. Rather, it is easier to calculate the tree pressures from the tree flows (by means of the elements' constitutive relations, assumed known), and to express the tree flows as linear combinations of the flows through the links. The link flows are therefore the independent variables in this set of L equations. These equations may be written in matrix form as follows:

$$Q = Kx \tag{4}$$

$$P = G(Q) (5)$$

$$CP = 0 (6)$$

where Q is an E x l vector containing the flows in all the elements, x is the L x l vector of link flows, and K is an E x L matrix of constants. Equation (4) expresses the tree flows as linear combinations of the link flows. In Equation (5), P is an E x l vector containing the pressure drops across all the elements and G is a vector function containing the constitutive relations for all elements. Matrix C is an L x E matrix of constants. Equation (6) is the explicit statement of KVL.

It should be fairly obvious that the only constants C can contain must be 1,0 or -1. Similarly, K also contains only those constants. In fact, it can be shown that K is the transpose of C. The matrix K therefore contains all the topological information necessary to derive the network governing equations. The problem of deriving the network equations has been solved except for one detail. The K matrix representation of network topology is not a representation most people would find convenient to use. Another more intuitive representation is therefore proposed.

Let us construct a V x E matrix D according to the following procedure. Number the elements and the nodes of the matrix under consideration. Now, assign

arbitrary directions to the flows through all the elements. This defines a starting and ending node for each branch.

Label the columns of D with the edge numbers and the rows with the vertex numbers. Now, considering each column and its associated element in turn, place a l in the row corresponding to the starting node of the element and a -l in the ending node row.

This matrix is called the incidence matrix for the network and contains the same topological information as the K matrix. It follows then, that K may be derived from D. That derivation will now be described.

First, since every column of D has exactly one l and one -1 in it, one row of the matrix may be removed without losing any topological information. The resulting (V - 1) x E matrix is called the incidence sub-matrix, A.

Identify a set of tree branches for the network.

Any set of (V - 1) linearly independent columns of D

is one such set. 6 Now define

$$Q_f = A_f^{-1} A \tag{7}$$

where A_t is a (V-1) x (V-1) matrix containing the above mentioned tree columns. Rearrange the columns of Q_f so that the resulting matrix may be partitioned as follows:

$$Q_{f} = \left[Q_{f_{11}} \middle| U_{g}\right] \tag{8}$$

where U_g is a (V-1) x (V-1) identity matrix. Note, the resulting column order is different from the column order of the A matrix.

Now define:

$$B_{f_{12}} = -Q_{f_{11}}^{T} \tag{9}$$

Construct matrix B_f ,

$$B_{f} = \left[U_{b} \middle| B_{f_{12}}\right] \tag{10}$$

where $U_{\rm b}$ is an L x L identity matrix. Matrix $B_{\rm f}$ is called the fundamental circuit matrix and is the desired K matrix with the elements renumbered in the same order as $Q_{\rm f}^{-6}$.

2.3 Non-linear Equations.

This section presents an algorithm for the solution of a set of simultaneous non-linear equations.

Consider a vector of functions F whose argument is the vector x. We wish to find the value of x which satisfies the equation

$$F(x) = 0 (11)$$

Expanding (11) in a Taylor series about the desired solution vector \mathbf{x}_{O} and neglecting higher order terms yields

$$F(x_0) + H(x_0) (x - x_0) = 0$$
 (12)

where H is a square matrix such that

$$H_{ij} = \frac{\partial F_{i}}{\partial x_{j}}$$
 (13)

If we assume that \mathbf{x}_n is the nth iteration of an iterative algorithm, the following recursion relation may be deduced

$$x_{n+1} = -(H(x_n))^{-1}F(x_n) + x_n$$
 (14)

The derivative H_{ij} may be approximated by perturbing the jth variable an amount P to give the vector x^* and setting

$$H_{ij} = \frac{F_i (x^*_j) - F_i(x)}{P}$$
 (15)

Iteration stops when $F(x_n)$ is less than a prescribed tolerance.

III. IMPLEMENTATION

This section will explain the actual program structure and operation.

3.1 Structure.

The main program is responsible for the iterative solution of the L network governing equations. It uses the algorithm presented in Section 2.3 with x equal to the vector of link flows and F the function such that F_i is the sum of the pressure drops around the ith fundamental circuit. A subroutine named F is called each time evaluation of the function is required.

Before iteration of the solution algorithm can begin, the fundamental circuit matrix, here called B, must be constructed. The subroutine INIT is called which accepts user input and formulates the B matrix according to the procedure of Section 2.2.

When the solution has been found the subroutine OUTPUT is called which prints the results.

3.2 Operation.

A data card for the program looks like this:

cc 1-10 - User pipe number (integer)

array = USERP

```
cc 11-20 - User starting node number (integer) array = USER
```

1 = pipe

2 = pressure source

3 = flow source

4 = control valve

A card with a zero in cc l indicates the end of the data.

Subroutine INIT reads the data and stores it in appropriate arrays. Each time it reads a card it adds a column to the incidence matrix A. If the user node numbers are new numbers, it adds appropriate rows to the matrix and makes the correct entries. The element types are then examined for flow sources. The columns corresponding

to flow sources are shifted to the rightmost columns in the matrix. The other stored data is also sorted the same way to maintain internal pipe numbering consistency. The incidence matrix is then transposed and passed to the subroutine REDUCE.

The function of REDUCE is to identify the subscripts of (V-1) linearly independent columns of A. These columns are used to fill the matrix A_t . The product A_t^{-1} A is computed. The columns representing an identity sub-matrix are identified and rearranged to give $\left[Q_{fl1}\middle|U_g\right]$. The stored element data is sorted again according to this rearrangement.

The B_f matrix is constructed. The array of element types is searched again for flow sources. The last (V-1) elements of the rows corresponding to fundamental circuits containing flow sources are shifted to the bottom of B. The first L elements of stored edge data are sorted according to this last shifting.

The MAIN program now treats the problem as if the number of independent variables is L minus the number of flow sources. Subroutine F calculates pressure drops across flow sources in such a way as to guarantee satisfaction of KVL.

IV. RECOMMENDATIONS

Several dummy subroutines are called which, when replaced with actual subroutines, allow the extension of this program to accept a larger variety of network elements.

The function ASSIGN can be used to retrieve the number of a data set in which tabulated pressure-flow data may be stored. Subroutine F can then call PRESS to evaluate the necessary constitutive relations.

The COMPUTED GO TO statement in subroutine F can be altered to accommodate elements having a known closed form constitutive relation.

V. CONCLUSIONS

This program makes the calculation of steady state,
DC response of piping networks an easy matter. It should
be a straightforward task to incorporate this program
in the proposed energy interaction model. Minor additions
allow the extension of the program to a greater variety
of network elements. The accuracy of the assumed
constitutive relations is, of course, still a question
to be experimentally verified.

REFERENCES

- 1. Shearer, Murphy, Richardson, Introduction to System Dynamics, Addison-Wesley, 1967.
- 2. Davis, Palmer, Computer Aided Analysis of Electrical Networks, Charles E. Merrill, 1973.

FOOTNOTES

- 1. Shearer, Murphy, Richardson, <u>Introduction to System</u>
 Dynamics, p. 67.
- 2. Ibid., pp. 67-68.
- 3. Davis, Palmer, Computer Aided Analysis of Electrical Networks, p. 124.
- 4. Ibid., pp. 124-125.
- 5. Ibid., p. 126.
- 6. Ibid., pp. 285-286.
- 7. Ibid., pp. 123-172.

APPENDIX I. FORTRAN CODE & SAMPLE OUTPUT

JOINT COMPUTER FACILITY, MIT USER=GOODMAN 274 84255 PROGRAM: MAIN C ARGUMENTS: NONE INIT, OUTPUT, INVERS, EXIT C CALLS: C DESCRIPTION: THIS IS A PROGRAM TO PERFORM STEADY STATE ANALYSIS OF PIPING C IT CALLS INIT TO INITIAL-NETWORKS. C IZE THE NECESSARY MATRICES, THEN С USES AN ITERATIVE TECHNIQUE TO C SOLVE THE RESULTING NON-LINEAR C THE SOLUTION IS CON-EQUATIONS. SIDERED COMPLETE WHEN THE FRROR C IS LESS THAN THE VALUE OF THE C TOLERANCE, TOL. C C C C IMPLICIT INTEGER*2 (I-N) INTEGER*2 E,NTYPE(30) REAL P(30),Q(30),B(30,30),PIPE(30) INTEGER*2 USERP(30) REAL FO(30), DELTA(30), FXP(30), DFDX(30,30), L1(30), M1(30), DX(30) REAL X(30) REAL TEMP(900) COMMON E, L, P, Q, B, NTYPE, PIPE, NSRCE COMMON/BLK1/USERP

READ THE DATA AND INITIALIZE THE REQUIRED MATRICES

CALL INIT

C

COMMON/BLK2/X

```
JOINT COMPUTER FACILITY, MIT
USER=GOODMAN 274 84255
      LL=L-NSRCE
      PERT=.1
      TOL=.001
      IDIM=30
      CONTINUE
50
      0 = MUM = 0
                 FO=F(X)
C
      CALL F(FO,X)
                 COUNT THE DELTAS LESS THAN TOL
C
      DO 100 I=1,LL
      DELTA(I) = -FO(I)
       IF(A9S(DELTA(I)).LE.TOL)NUM=NUM+1
       CONTINUE
100
                  ARE WE FINISHED?
C
       IF (NUM. EQ. LL) CALL OUTPUT
                 CALCULATE DEDX, THE MATRIX OF
C
                  PARTIAL DERIVATIVES
C
       DO 200 J=1,LL
       X(J)=X(J)+PERT
       CALL F(FXP,X)
       DO 150 I=1,LL
       DFDX(I,J) = (FXP(I) - FO(I))/PERT
       CONTINUE
150
       X(J)=X(J)-PERT
       CONTINUE
200
                  DFDX=INVERSE OF DFDX
\mathbf{C}
       CALL INVERS (DFDX, LL, IDIM, TEMP, L1, H1)
                  INCREMENT THE LINK FLOW VECTOR BY
C
                  DX WHICH IS THE PRODUCT OF THE
C
```

C

DO 300 I=1,LL

DO 250 J=1,LL

DX(I)=0.

MATRIX DFDX AND THE VECTOR DELTA.

USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT

250 DX(I)=DX(I)+DFDX(I,J)*DELTA(J)

X(I)=X(I)+DX(I)

300 CONTINUE

C GO BACK FOR ANOTHER ITERATION

GO TO 50 CALL EXIT

END

PROGRAM *MAIN* HAS NO ERRORS

```
USER=GOODMAN 274 84255
                            JOINT COMPUTER FACILITY, MIT
C
   PROGRAM:
                 INIT
C
C
                 NONE
   ARGUMENTS:
C
C
   CALLS:
                 ICSORT, ISORT, SORT, REDUCE, ASSIGN
C
                 INVERS, ERROR1, ERROR3
C
   DESCRIPTION: THIS PROGRAM READS THE INPUT DATA
C
C
                 AND FROM THAT DATA CONSTRUCTS THE
C
                 FUNDAMENTAL CIRCUIT MATRIX FOR THE
C
                 NETWORK UNDER ANALYSIS.
C
C
C
      SUBROUTINE INIT
      IMPLICIT INTEGER*2 (I-N)
      INTEGER*2 E, NTYPE(30)
      REAL P(30),Q(30),B(30,30),PIPE(30)
      INTEGER*2 USERP(30)
      REAL X(30)
      INTEGER*2 V,A(30,30),SUB1(30),USER(30)
      REAL M1(30),M2(30)
      INTEGER *2 V1
      INTEGER*2 QF(30,30)
      REAL TEMP(900)
      REAL PRMTR(30)
      REAL COORDS (30,2)
      INTEGER*2 SUB(30)
      COMMON E, L, P, Q, B, NTYPE, PIPE, NSRCE
      COMMON/BLK1/USERP
      COMMON/BLK2/X
```

C

IDIM=30

USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, HIT

```
E = 0
      V = 0
                 INITIALIZE THE SUBSCRIPT VECTORS
C
                 SUB AND SUB1.
C
                 INITIALIZE B AND A TO ZERO.
C
      DO 7 I=1,IDIM
      SUB(I)=I
      SUB1(I)=I
      DO 7 J=1.IDIM
      B(I,J)=0.0
       A(I_nJ)=0
7
      CONTINUE
5
                 READ THE DATA
       READ(8,1001) IPIPE, NSTART, NEND, ITYPE, DATUM, PARAM, XCOORD, YCC
       FORMAT (4110,4F10.4)
1001
                 IS THIS THE LAST DATA CARD?
C
       IF(IPIPE.EQ.O)GO TO 50
       E = E + 1
                  STORE THE ELEMENT DATA
C
       PIPE(E)=DATUM
                  ELEMENT TYPES GREATER THAN 4 ARE
C
                  SPECIAL CASES AND MAY REQUIRE DIF-
C
                  FERENT VALUES TO BE STORED IN PIPE.
C
       IF(ITYPE.GT.4)PIPE(E)=ASSIGN(ITYPE)
       NTYPE(E)=ITYPE
       USERP(E)=IPIPE
       COORDS(E, 1) = XCOORD
       COORDS (E, 2) = YCOORD
       PRMTR(E)=PARAM
C
                  CONSTRUCT THE INCIDENCE MATRIX
C
       DO 10 I=1.V
       IF(USER(I).NE.NSTART)GO TO 10
```

```
USER=GOODMAN 274 84255
                            JOINT COMPUTER FACILITY, MIT
      A(I_nE)=1
      GO TO 20
10
      CONTINUE
C
      V=V+1
      USER(V)=NSTART
      A(V,E)=1
20
      CONTINUE
C
      DO 30 I=1,V
      IF(USER(I).NE.NEND)GO TO 30
      A(I_{\nu}E)=-1
      GO TO 5
30
      CONTINUE
C
      V=V+1
      USER(V)=NEND
      A(V_cE)=-1
      GO TO 5
50
      CONTINUE
      IF(E.EQ.O)CALL ERROR1
      V1=V-1
      NSRCE=0
      NON = 0
C
С
                 REARRANGE THE SUBSCRIPT VECTOR SO
C
                 THAT SOURCES APPEAR AS THE RIGHTMOST
C
                 ELEMENTS
      DO 60 I=1,E
      IF(NTYPE(I).EQ.3)GO TO 53
      NON=NON+1
```

SUB1(NOM)=I

```
USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT
       GO TO 60
53
       CONTINUE
       ISUB=E-NSRCE
       SUB1(ISUB)=I
       NSRCE=NSRCE+1
50
       CONTINUE
C
C
                 SORT THE COLUMNS OF THE A MATRIX
C
                 AND ALL THE DATA VECTORS ACCORDING
С
                 TO THE ORDER OF THE SUBSCRIPTS IN
C
                 SUB1.
      CALL ICSORT(A,V,E,SUB1)
      CALL SORT(PIPE, E, 1, SUB1)
      CALL ISORT (NTYPE, E, 1, SUB1)
      CALL ISORT (USERP, E, 1, SUB1)
      CALL SORT (COORDS, E, 2, SUB1)
      CALL SORT (PRMTR, E, 1, SUB1)
C
                 SET B=TRANSPOSE OF A
      DO 70 I=1,E
      DO 70 J=1, V
70
      B(I,J)=\lambda(J,I)
C
C
                 ROW REDUCE B TO FIND THE INDEPEN-
C
                 DENT COLUMNS OF A.
      CALL REDUCE (P.E.V, SUB1)
C
C
                 FILL B WITH THE INDEPENDENT COLUMNS
C
                 OF A. THESE REPRESENT THE TREE
C
                 BRANCHES FOR THE NETWORK.
      DO 80 J=1,V1
      ISUB=SUB1(J)
      DO 80 I=1, V1
08
      B(I,J)=A(I,ISUB)
```

```
USER=G00DMAN 274 84255
                            JOINT COMPUTER FACILITY, MIT
C
C
                 B=INVERSE OF B
      CALL INVERS(B, V1, IDIM, TEMP, M1, M2)
C
C
                 OF=PRODUCT OF MATRICES B AND A
      DO 90 I=1,V1
      DO 90 J=1,E
      QF(I_{\bullet}J)=0
      DO 90 K=1,V1
      QF(I,J)=QF(I,J)+IFIX(B(I,K))*A(K,J)
90
      CONTINUE
C
C
                 FIND THE IDENTITY SUBMATRIX IN QF.
      L=E-V1
      IV2=V-2
C
      DO 91 J=1,E
91
      SUB1(J)=J
C
      DO 100 I=1,V1
C
      DO 95 JJ=1,E
      J=SUB1(JJ)
      IF(QF(I,J).NE.1)GO TO 95
      ICOUNT=0
C
      DO 93 II=1,V1
      IF(QF(II,J).EQ.O)ICOUNT=ICOUNT+1
93
      CONTINUE
      IF(ICOUNT.NE.IV2)GO TO 95
      ISUB=L+I
      ISAVE=SUB1(ISUB)
```

```
USER=GOODMAN 274 84255
                             JOINT COMPUTER FACILITY, MIT
       SUB1(ISUB)=J
       SUB1(JJ)=ISAVE
       GO TO 100
95
       CONTINUE
\mathbb{C}
       CALL ERROR3
       CONTINUE
100
C
C
                  CONSTRUCT THE FUNDAMENTAL CIRCUIT
                  MATRIX. B.
       DO 110 T=1,L
       00 110 J=1,L
       B(T,J)=0
       IF(I,EQ,J)B(I,J)=1
       CONTINUE
110
\mathbf{C}
       L1=L+1
\mathsf{C}
       DO 120 I=1,L
       ISUB=SUB1(I)
       DO 120 J=L1.E
       KSUB=J-L
120
       B(I,J) = -QF(KSUB,ISUB)
C
C
                  SORT THE ELEMENT DATA, CONSISTENT
C
                  WITH THE ORDERING OF THE COLUMNS
C
                  OF OF.
       CALL SORT (PIPE, E, 1, SUB1)
       CALL ISORT (NTYPE, E, 1, SUB1)
      CALL ISORT (USERF, E, 1, SUB1)
      CALL SORT (COORDS, E, 2, SUB1)
      CALL SORT(PRMTR, E, 1, SUB1)
```

C

```
USER=GOODNAN 274 84255
                            JOINT COMPUTER FACILITY, MIT
\mathbb{C}
                 SEARCH THE ELEMENT TYPES FOR THE
C
                 FLOW SOURCES
      NSRCE=0
      0 = MCM
      DO 130 I=1.L
      IF(NTYPE(I).EQ.3)GO TO 125
      1+NCN=NON
      SUB1(NON)=I
      GO TO 130
125
      CONTINUE
      ISUB=L-NSRCE
       SUB1(ISUB)=I
      NSRCE=NSRCE+1
130
      CONTINUE
C
                 RENUMBER THE LINK FLOWS SO THAT
C
                 THE FLOW SOURCES HAVE THE HIGHEST
C
                 SUBSCRIPTS. INTERCHANGE THE APPRO-
C
                 PRIATE ROWS OF B AND SORT THE ELEMENT
C
                 DATA VECTORS.
      DO 135 I=1,L
      DO 135 J=L1,E
      K=J-L
      QF(I,K)=B(I,J)
135
      CALL ISORT(QF,L,V1,SUB1)
      DO 137 I=1,L
      DO 137 J=L1.E
      K=J-L
      B(I_J)=QF(I_K)
137
      CALL SORT(PIPE, L, 1, SUB1)
      CALL ISORT(NTYPE, L, 1, SUB1)
      CALL ISORT (USERP, L, 1, SUB1)
```

USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT

CALL SORT (COORDS, L, 2, SUB1)

CALL SORT(PRMTR, L, 1, SUB1)

DO 140 I=1,L

X(I)=1.0

IF(NTYPE(I).EQ.3)X(I)=PIPE(I)

140 CONTINUE

RETURN

END

PROGRAM

INIT HAS NO ERRORS

USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT PROGRAM: C C ARGUMENTS: A - THE VECTOR EQUAL TO F(Y) C X - THE VECTOR OF LINK FLOWS C CALLS: PRESS. ABS C DESCRIPTION: SUBROUTINE F EVALUATES THE VECTOR C FUNCTION F(X) WHICH IS THE SUM OF C THE PRESSURES AROUND THE FUNDAMENTAL C CIRCUITS C SUBROUTINE F(A,X) IMPLICIT INTEGER*2 (T-N) INTEGER*2 E,NTYPE(30) REAL P(30),Q(30),B(30,30),PIPE(30) REAL X(30), A(30) INTEGER*2 SUB(30) COMMON E, L, P, Q, B, NTYPE, PIPE, NSRCE C Q=PRODUCT OF MATRICES B TRANSPOSE С AND X. Q IS THE VECTOR OF FLOWS C THROUGH ALL THE ELEMENTS OF THE C NETWORK. LL = LDO 10 I=1,EQ(I)=0.DO 10 K=1,LL Q(I)=Q(I)+B(K,I)*X(K)10 C CALCULATE THE PRESSURE DROP ACROSS C ALL THE ELEMENTS FROM THE VECTOR C OF FLOWS. THE PROCEDURE IS DIFFER-ENT FOR EACH TYPE OF ELEMENT.

```
USER=GOODMAN 274 84255
                           JOINT COMPUTER FACILITY, HIT
      PEXP=.75
      NSRCE=0
      DO 100 I=1,E
      00=0(1)
      ITYPE=NTYPE(I)
      IF(ITYPE.GT.4)GO TO 30
      GO TO (40,50,60,70), ITYPE
30
      CALL PRESS(I)
      GO TO 100
40
      P(I)=PIPE(I)*QQ*ABS(QQ)**PEXP
      GO TO 100
50
      P(I)=PIPE(I)
      GO TO 100
60
      NSRCE=NSRCE+1
      SUB (NSRCE) = I
      P(I)=0.
      GO TO 100
70
      P(I)=PIPE(I)*QQ*ABS(QQ)
100
      CONTINUE
C
                 CALCULATE PRESSURE DROP AROUND
C
                 FUNDAMENTAL CIRCUIT LOOPS
      DO 105 I=1,LL
      A(I)=0.
      DO 105 K=1.E
105
      A(I)=A(I)+B(I,K)*P(K)
      IF (NSRCE.EQ.O) RETURN
C
                 SET THE PRESSURE DROP ACROSS ALL
C
                FLOW SOURCES SO THAT KVL IS SATIS-
C
                 FIED.
      DO 110 I=1, NSRCE
```

ISUB=SUB(I)

USER=GOODMAN 274 84255

JOINT COMPUTER FACILITY, MIT

110 P(ISUB) = -A(ISUB)

RETURN

END

PROGRAM F

HAS NO ERRORS

USEB=GOODNAN 274 84255 JOINT COMPUTER FACILITY, MIT C PROGRAM: PRESS C C ARGUMENTS: I - THE SUBSCRIPT IDENTIFYING AN C ELEMENT WHOSE PRESSURE DROP IS TO C BE CALCULATED. C CALLS: NOTHING CCDESCRIPTION: PRESS IS A DUMMY SUBROUTINE TO CAL-CULATE THE PRESSURE DROP ACROSS C EXOTIC NETWORK ELEMENTS. C, C SUBROUTINE PRESS(I) IMPLICIT INTEGER*2 (I-N) INTEGER*2 E,NTYPE(30) REAL P(30),Q(30),B(30,30),PIPE(30) COMMON E, L, P, Q, B, NTYPE, PIPE P(I) = 20.RETURN END

NO ERRORS

PROGRAM

PRESS HAS

```
USER=GOODMAN 274 84255
                                 JOINT COMPUTER FACILITY, MIT
       C
          PROGRAM:
                       OUTPUT
       C
          ARGUMENTS:
                        NONE
       C
          CALLS:
                        EXIT
          DESCRIPTION: OUTPUT PRINTS OUT THE DESIRED
       C
                        RESULTS, THEN CALLS EXIT.
       C
       C
             SUBROUTINE OUTPUT
             IMPLICIT INTEGER*2 (I-N)
             INTEGER*2 E, NTYPE(30)
             REAL P(30),Q(30),B(30,30),PIPE(30)
             INTEGER*2 USERP(30)
             COMMON E, L, P, Q, B, NTYPE, PIPE
             COMMON/BLK1/USERP
             WRITE(5,1000)
             FORMAT(//,6X, PIPE NO.',15X, PRESSURE',15X, FLOW RATE',/)
       1000
             DO 100 I=1,E
            WRITE(5,1010)USERP(I),P(I),Q(I)
       1010
             FORMAT(1X, I10, 15X, F10.4, 15X, F10.4)
             CALL EXIT
             END
PROGRAM
         OUTPUT HAS
                       NO ERRORS
```

USER = GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT C PROGRAM: REDUCE C A - A MATRIX TO BE ROW REDUCED ARGUMENTS: H - NUMBER OF ROWS IN A N - NUMBER OF COLUMNS IN A Ċ SUB - VECTOR OF SUBSCRIPTS INDICAT-ING THE REARRANGEMENT OF A C DURING REDUCTION. C C CALLS: NOTHING C C DESCRIPTION: REDUCE PERFORMS ROW REDUCTION ON C ARGUMENT MATRIX A. THE VECTOR SUB C CONTAINS THE ORIGINAL A MATRIX SUB-C SCRIPTS IN THE FINAL ORDER. CONLY REDUCES THE MATRIX BELOW THE DIAGONAL. SUBROUTINE REDUCE (A, M, N, SUB) IMPLICIT INTEGER*2 (I-N) INTEGER*2 SUB(M) REAL A(30,30) DO 10 I=1,M10 SUB(I)=IC N1=N-1DO 100 K=1,N1 C DO 20 I=K,M

IF(A(I,K).EQ.0.0)GO TO 20

 $PIVOT=\lambda(I,K)$

USER=GOODMAN 274 84255

```
JOINT COMPUTER FACILITY, MIT
              ISUB=I
              GO TO 30
       20
              CONTINUE
       C
              CALL ERROR4
       30
              CONTINUE
       C
              DO 40 J=1,N
              HOLD=A (ISUB,J)
              A(ISUB,J)=A(K,J)
       40
              A(K_{r}J) = HOLD
       С
              ISAVE=SUB(ISUB)
              SUB(ISUB)=SUB(K)
              SUB(K)=ISAVE
              IF(K.EQ.N1)RETURN
              IF(PIVOT.EQ.1.0)GO TO 50
       C
              DO 45 J=1.N
       45
              A(K,J) = A(K,J)/PIVOT
       С
       50
              CONTINUE
              K1 = K + 1
       C
              DO 60 I=K1,H
              UMULT=A(I,K)
              DO 60 J=K,N
       60
              A(I,J)=A(I,J)-UMULT*A(K,J)
       C
       100
              CONTINUE
              END
PROGRAM REDUCE HAS
                         NO ERRORS
```

USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT

PROGRAM: INVERS C ARGUMENTS: A - MATRIX TO BE INVERTED N - NUMBER OF ROWS USED IN A K - NUMBER OF ROWS AND COLUMNS TO WHICH A IS DIMENSIONED IN THE CALLING PROGRAM. B - A WORKING VECTOR OF DIMENSION K SOUARED OR LARGER. M1 - WORKING VECTOR OF LENGTH K M2 - WORKING VECTOR OF LENGTH K C MINV, ABS, ERROR2 CALLS: DESCRIPTION: INVERS FINDS THE INVERSE OF THE MATRIX A. IT IS USEFUL WHEN THE MATRIX TO BE INVERTED ONLY CONTAINS USEFUL DATA IN THE UPPER N BY N SUB-MATRIX. INVERS PACKS THE MATRIX THEN CALLS THE SSP ROUTINE MINV TO DO THE ACTUAL INVERSION. THE RESULT IS STORED IN A, THEREFORE THE CCC ORIGINAL IS DESTROYED. SUBROUTINE INVERS(A,N,K,B,M1,M2) IMPLICIT INTEGER*2 (I-N) REAL A(K,K),B(N,N)

REAL M1(N)_M2(N) DO 10 I=1,NDO 10 J=1,N 10 $B(I,J)=\lambda(I,J)$

USER=GOODMAN 274 84255

JOINT COMPUTER FACILITY, MIT

CALL MINV(B,N,DET,M1,M2)

IF(ABS(DET).LT..0001)CALL ERROR2

DO 20 I=1,N DO 20 J=1,N

20 A(I,J)=B(I,J)

RETURN

END

PROGRAM INVERS HAS NO ERRORS

USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT PROGRAM: ASSIGN ARGUMENTS: N - NUMBER OF ELEMENT FOR WHICH A VALUE OF PIPE MUST BE ASSIGNED. C CALLS: NOTHING DESCRIPTION: ASSIGN IS A DUMMY FUNCTION. FUNCTIONAL VERSION HOULD RETURN A NUMBER, USUALLY A DATA SET NUMBER, TO BE STORED IN THE DATA VECTOR, C C C C CPIPE. ASSIGN WOULD BE RESPONSIBLE FOR INTERPRETING EXOTIC USER ELEMENT TYPES. FUNCTION ASSIGN(N)

ASSIGN = 75 RETURN END

PROGRAM ASSIGN HAS NO ERRORS

USER=GOODMAN 274 84255

JOINT COMPUTER FACILITY, MIT

SUBROUTINE ERROR1

WRITE(5,1000)

FORMAT(//, NO PIPES HAVE BEEN ENTERED ,//) 1000

CALL EXIT

END

PROGRAM ERBOR1 HAS NO ERRORS

USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT

SUBROUTINE ERROR2

WRITE(5,1000)

1000 FORMAT(//, * INCIDENCE MATRIX TREE COLUMNS WERE DEPENDENT*

CALL EXIT

END

PROGRAM ERROR2 HAS NO ERRORS

USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT

SUBROUTINE ERROR3 WRITE(5,1000)

1000 FORMAT(//, UNABLE TO IDENTIFY IDENTITY SUBMATRIX ,//)

CALL EXIT

EN D

PROGRAM ERRORS HAS NO ERRORS

USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT

SUBROUTINE ERROR4 WRITE(5,1000)

FORMAT(//, NO NON-ZERO PIVOT FOUND .//) 1000

CALL EXIT

END

PROGRAM ERROR4 HAS NO ERRORS

```
USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIT
   PROGRAM:
                ISORT
C
   ARGUMENTS:
                A - MATRIX TO BE SORTED
C
                M - NUMBER OF ROWS IN A
C
                N - NUMBER OF COLUMNS IN A
C
                SUB - VECTOR CONTAINING SUPSCRIPTS
                       IN THE DESIRED ORDER FOR THE
                       ROWS OF A.
C
C
   CALLS:
                NOTHING
C
   DESCRIPTION: ISORT (INTEGER SORT) IS A PROGRAM
C
                TO SORT THE ROWS OF AN INTEGER
C
                MATRIX, A, IN THE ORDER DICTATED
C
                BY THE VECTOR OF SUBSCRIPTS. SUB.
C
C
      SUBROUTINE ISORT(A,M,N,SUB)
      IMPLICIT INTEGER*2 (I-N)
      INTEGER*2 A(30,30),B(30,30)
      INTEGER *2 SUB(M)
      DO 10 I=1.M
      ISUB=SUB(I)
      DO 10 J=1,N
10
      B(I,J)=A(ISUB,J)
      DO 20 I=1,M
      DO 20 J=1,N
20
      A(I,J)=B(I,J)
      RETURN
      END
```

PROGRAM ISORT HAS NO ERRORS

USER=GOODMAN 274 84255 JOINT COMPUTER FACILITY, MIN

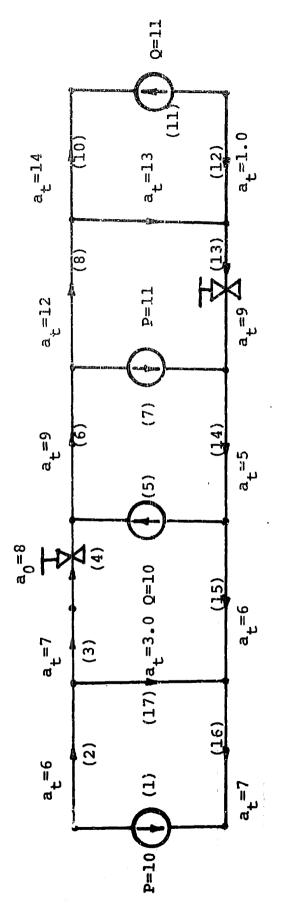
```
SORT
       \mathbb{C}
           PROGRAM:
       C
       C
                         A - MATRIX TO BE SORTED
           ARGUMENTS:
       C
                         M - NUMBER OF ROWS IN A
                         N - NUMBER OF COLUMNS IN A
       C
       C
                         SUB - VECTOR OF SUBSCRIPTS
       C
       C
          CALLS:
                         HOTHING
       \mathsf{C}
       C
           DESCRIPTION: SORT SORTS THE ROWS OF THE MATRIX
       C
                         A IN THE ORDER DICTATED BY THE
       C
C
                         VECTOR SUB.
       Ĉ
       C.
              SUBROUTINE SORT (A, M, N, SUB)
              IMPLICIT INTEGER*2 (I-N)
              REAL A(30,30),B(30,30)
              INTEGER*2 SUB(M)
              DO 10 I=1.M
              ISUB=SUB(I)
              DO 10 J=1, N
       10
              B(I,J)=\lambda(ISUB,J)
              DO 20 I=1.M
              DO 20 J=1,N
              A(I,J)=B(I,J)
       20
              RETURN
              END
                         NO ERRGRS
PROGRAM
         SORT
                 HAS
```

```
USER=GOODMAN 274 84255
                                   JOINT COMPUTER FACILITY, MIT
       \mathbf{C}
          PROGRAM:
                        ICSORT
       C
       C
                        A - MATRIX TO BE SORTED
          ARGUMENTS:
       C
       С
                        M - NUMBER OF ROWS OF A
       C
                        N - NUMBER OF COLUMNS OF A
       C
                        SUB - VECTOR OF SUBSCRIPTS
       C
       C
          DESCRIPTION: ICSORT (INTEGER COLUMN SORT) SORTS
       C
                        THE COLUMNS OF AN INTEGER MATRIX,
       C
                        A, ACCORDING TO THE ORDER DICTATED
       C
                        BY THE VECTOR SUB.
       C
       C
       \mathbf{C}
              SUBROUTINE ICSORT(A,M,N,SUB)
              IMPLICIT INTEGER*2 (I-N)
              INTEGER*2 A(30,30),B(30,30)
              INTEGER*2 SUB(N)
              DO 10 J=1,N
              JSUB=SUB(J)
              DO 10 I=1,M
              B(I,J)=A(I,JSUB)
       10
              DO 20 I=1.M
              DO 20 J=1.N
       20
              A(I,J)=B(I,J)
              RETURN
              END
PROGRAM ICSORT HAS NO ERRORS
```

TO OPERATING SYSTEM VERSION 2 REVISION 222 6/13/76 GENERATED 12/17/76 03:26.

```
HANDLING CHARGE
                    S
                       .35 / JOB
                                         .35
LINES PRINTED PR1 $ 1.25 / K LN
                                         .89
CARDS READ
                    $ 1.50 / K CD
                                        1.03
                    $ .25 / 1000
$25.00 / HOUR
PLOTTER VECTORS
                                         .00
                                         .34
MODEL 70 SECONDS
MODEL 80 SECONDS
                    $35.00 / HOUR
                                         .00
                                        2.61
                     TOTAL CHARGE $
```

274 84255 LOGGED OUT 05/19/17 23:45. \$ 6.54 LEFT AFTER 16 LOGINS.



The network above is solved in the program run which follows.

// JOE ANY 00080 // DUP XB > *PN CHLDWAT *EL SSPNAT *EL BINARY *BC OFBA *LC OOB4 *LAST			GOODMAN	0425 5
CHLDWAT SSPMAT EOF EOF EOF	BINARY7	RTL		
THURSDAY 05/19/	17 23:37:05	d)		
PROGRAM LARELS:				
1C00 *MAIN*	3DC6 INIT	69 7 2 F	6D80 PRESS	6DE4 OUTPUT
7508 ASSIGN	755C ERROR1	75DC ERROR2	766E ERROR3	76F8 ERRORA
8F5C ICSORT	97CC MINV	B26C ALOG	B364 AEXP	B364 EXP
B5DC ABS	B834 EXIT	B8 DA		
COMMON-BLCCKS: F044 //	EF90 BLK1	EFCC BLK2		

UNDEFINED SUBROUTINES: NONE

TRANSFER ADDRESS 1000
PROGRAM ENDS AT: X'BA7A' AND REQUIRED 006A DISK READS;0068 DISK WRITES@FIND REFS=0663 RECALL BUFS= 0066@EXECUTION REGINS: @

PIPE NO.	PRESSURE	FLOW RATE
8	-162.4736	-4.4323
7	11.0000	10.2744
2	-5.8342	-0.9841
11	-1346.8977	11.0000
5	-318.3394	10.0000
9	350.2810	6.5677
1 0	-930.1758	-11.0000
12	-66.4411	-11.0000
13	-176.8076	-4.4323
14	109.7641	5.8421
15	-72.6421	-4.1579
16	-6.8066	-0.9841
17	22.6407	3.1738
1	10.0000	0.9841
3	-84.7491	-4.1579
4	-138.3076	-4.1579

// END

JCF	AIO	OPERATING	SYSTEM	VERSION	2	REVISION	222	6/13/76	GENERATED	12/17
-----	-----	-----------	--------	---------	---	----------	-----	---------	-----------	-------

	HANDLING CHARGE	\$.35	/ JOB	•35
		\$ 1.25	/ K LN	•06
	CAPES READ	\$ 1.50	/ K CD	.04
	PLOTTER VECTORS	\$.25	/ 1000	.00
	MODEL 70 SECONDS	\$25.00	/ HOUR	. 20
0.0	MODEL 80 SECONDS	\$35.00	/ HOUR	•00
		TOTAI.	CHARGE '	\$.60

GOODMAN 274 84255 LOGGED OUT 05/19/17 23:37. \$ 9.15 LEFT AFTER 15 LO