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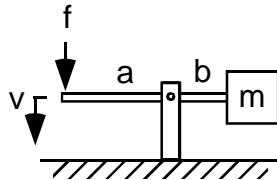
**2.003 Modeling, Dynamics and Control I  
Homework 5**

Assigned: Wednesday March 13, 2002

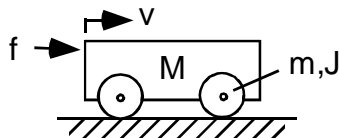
Due: Wednesday March 20, 2002

**Problem 1**

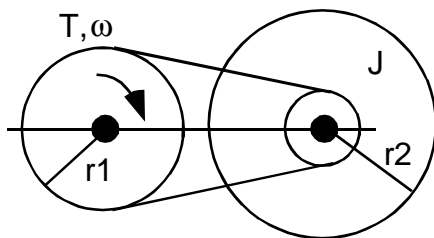
- (a) Derive an expression for the equivalent mass at the point of application of the force.



- (b) Derive an expression for the equivalent mass at the point of application of the force. Assume that each wheel has a mass,  $m$ , and a rotational inertia of  $J$ . Assume there is no energy loss due to bearings and that the wheels do not slip.

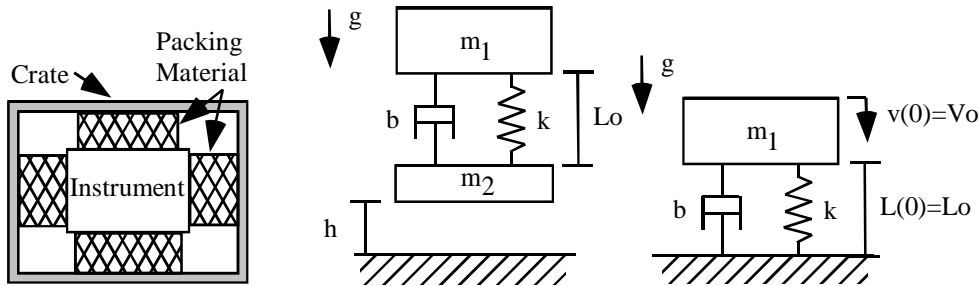


- (c) Derive an expression for the equivalent rotational inertia. Assume that the two pulleys have negligible inertia, there are no losses due to bearings and that the flywheel has inertia,  $J$ .



### Problem 2

A packing crate was designed to protect a fragile instrument during shipment. Assuming that the packing material can be modeled as an ideal linear spring of stiffness,  $k$ , in parallel with an ideal linear damper,  $b$ , and that the instrument and crate are of mass,  $m_1$  and  $m_2$ , respectively, the system can be modeled as shown in the middle figure below



The packing crate (with instrument inside) is dropped from a height,  $h$ , as shown in the middle figure. The height is sufficiently large that by the time the crate hits the ground, the spring is fully extended to its unloaded length,  $L_0$ , as shown in the figure on the right. Note that the crate hits the ground with velocity,  $V_0$ , and in the presence of gravity.

- Derive the differential equation for the system. Clearly indicate the initial conditions, and any inputs present.
- For what values of,  $b$ , will the instrument oscillate?
- Assuming that the instrument does oscillate, derive an analytical expression for the complete solution.

### Problem 3

Palm 3.4

### Problem 4

Palm 3.5

### Problem 5

Palm 3.6