

**Problem 1 - Palm 2.24**

All of these problems are second order, thus the roots of the characteristic equations can be found using the quadratic formula;

$$s_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

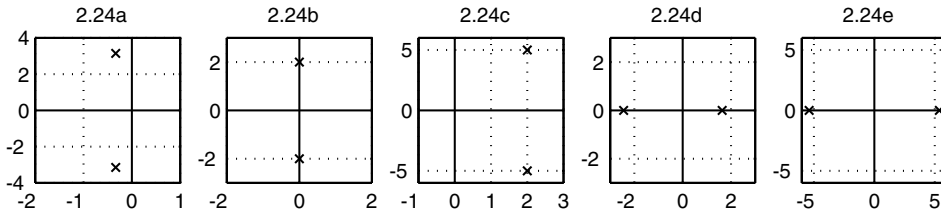


Figure 1: Pole plot for 2.24

- a)  $s_{1,2} = -0.3333 \pm 3.1447i$ , Stable
- b)  $s_{1,2} = \pm 3.1447i$ , marginally stable
- c)  $s_{1,2} = 2 \pm 5i$ , unstable
- d)  $s_{1,2} = -2.4396, 1.6396$ , unstable
- e)  $s_{1,2} = \pm 5.3853$ , unstable

**Problem 2 - Palm 2.22**

- a)  $s_{1,2} = -5, -2$ , no oscillation, response dominated by  $-2$  pole thus  $\tau_d = 0.5, t_{settle} = 4\tau = 2$  s.
- b)  $s_{1,2} = -2, -2$ , repeated root, no oscillation,  $\tau_d = 0.5, t_{settle} = 4\tau = 2$  s.
- c)  $s_{1,2} = -2 \pm 5i$ , oscillates,  $\tau = 0.5, t_{settle} = 4\tau = 2$  s,  $\omega = 5 \frac{rad}{s}$ .

**Problem 3 - Palm 2.15**

While it is possible to solve this question using just the formulas in Table 2.3-1, I think it is valuable to see where those solutions were derived. In general the solution to any unforced 2nd order system  $m\ddot{x} + c\dot{x} + kx = 0$  is:

$$x(t) = Ae^{s_1 t} + Be^{s_2 t}$$

where

$$s_{1,2} = \text{the roots of the characteristic equation}$$

$A$  and  $B$  can be expressed in terms of the initial conditions of the system as follows:

$$\begin{aligned}x(0) &= x_0 = A + B \\ \dot{x}(0) &= \dot{x}_0 = As_1 + Bs_2 \\ A &= \frac{\dot{x}_0 - s_2x_0}{s_1 - s_2} \\ B &= \frac{\dot{x}_0 - s_1x_0}{s_2 - s_1}\end{aligned}$$

Without doing any additional work, the solution so far matches that for Case 1 (real distinct roots) in Table 2.3-1. The solution for Case 2 (real repeated roots) can be found in any differential equation textbook. The solution to Case 3 (complex conjugate pairs) is presented here since it is the most difficult and interesting. In the case of complex conjugate pairs, the solution to the characteristic equation is:

$$s_1 = a + bj \text{ and } s_2 = a - bj$$

Substituting these values into the general homogenous solution yields:

$$\begin{aligned}x(t) &= Ae^{(a+bj)t} + Be^{(a-bj)t} \\ &= e^{at}(Ae^{bjt} + Be^{-bjt}) \\ \text{Note: } e^{(a+bj)t} &= e^{at}e^{bjt}\end{aligned}$$

Substituting into our general expressions for  $A$  and  $B$ , we get:

$$\begin{aligned}A &= \frac{\dot{x}_0 - (a - bj)x_0}{a + bj - a + bj} = \frac{\dot{x}_0 - x_0(a - bj)}{2bj} \\ B &= \frac{\dot{x}_0 - (a + bj)x_0}{a - bj - a - bj} = -\frac{\dot{x}_0 - x_0(a + bj)}{2bj}\end{aligned}$$

Using Euler's Identity for complex exponentials, we get

$$\begin{aligned}e^{bjt} &= \cos bt + j \sin bt \\ e^{-bjt} &= \cos -bt + j \sin -bt = \cos bt - j \sin bt \\ \text{Note: } \cos -bt &= \cos bt \\ \sin -bt &= -\sin bt\end{aligned}$$

Combining the equations above yields:

$$\begin{aligned}
 x(t) &= e^{at} \left( \frac{\dot{x}_0 - x_0(a - bj)}{2bj} (\cos bt + j \sin bt) - \frac{\dot{x}_0 - x_0(a + bj)}{2bj} (\cos bt - j \sin bt) \right) \\
 &= e^{at} \left( \frac{\dot{x}_0 - x_0(a - bj) - \dot{x}_0 - x_0(a + bj)}{2bj} \cos bt + \frac{\dot{x}_0 - x_0(a - bj) + \dot{x}_0 - x_0(a + bj)}{2b} \sin bt \right) \\
 &= e^{at} \left( x_0 \cos bt + \frac{\dot{x}_0 - x_0 a}{b} \sin bt \right)
 \end{aligned}$$

Using the trigonometric identity:

$$\begin{aligned}
 A \cos bt + B \sin bt &= \sqrt{A^2 + B^2} \sin(bt + \phi) \\
 \text{where } \phi &= \tan^{-1} \frac{A}{B}
 \end{aligned}$$

We can show that

$$\begin{aligned}
 x(t) &= e^{at} \sqrt{x_0^2 + \frac{(\dot{x}_0 - x_0 a)^2}{b^2}} \sin(bt + \phi) \\
 \phi &= \tan^{-1} \frac{x_0 b}{\dot{x}_0 - ax_0}
 \end{aligned}$$

This expression is equivalent to that given in Table 2.3-1. The slightly different expression due to fact that I do not assume that  $a$  is a negative number.

For all sections  $x_0 = 0$  and  $\dot{x}_0 = 1$

**a)**  $s_{1,2} = -2 \pm 2i$ , complex conjugate pair

$$x(t) = e^{-2t} \sin 2t$$

**b)**  $s_{1,2} = -6, -2$ , Real distinct roots

$$x(t) = 0.25e^{-2t} - 0.25e^{-6t}$$

**c)**  $s_{1,2} = -2, -2$ , Repeated roots

$$x(t) = te^{-2t}$$

**Problem 4 - Palm 4.29**

This is a bit of a trick question since you need more information to determine  $k$  and  $c$ . Specifically, you need to know the period of the oscillation. Nonetheless, we can determine  $\zeta$  using the Logarithmic decrement:

$$\begin{aligned}\delta &= \frac{1}{n} \ln \frac{B_i}{B_{i+n}} \\ \zeta &= \frac{\delta}{\sqrt{(2\pi)^2 + \delta^2}} \\ \delta &= \frac{1}{30} \ln \frac{1}{0.5} = 0.0536 \\ \zeta &= \frac{0.0536}{\sqrt{(2\pi)^2 + 0.0536^2}} = 0.0085\end{aligned}$$

If we had the period  $P$ , we could calculate  $k$  and  $c$  using the following relationships:

$$\begin{aligned}k &= m\omega_n^2 = \frac{m\omega_d^2}{1 - \zeta^2} = \frac{m(2\pi/P)^2}{1 - \zeta^2} \\ \zeta &= \frac{c}{2\sqrt{mk}}\end{aligned}$$

**Problem 5 - Palm example4.3-3**

The characteristic equation for this problem is:

$$I_e \ddot{\theta} + c_e \dot{\theta} + k_e \theta = 0$$

where

$$\begin{aligned}I_e &= I_m + I_s + \frac{m_p R^2}{2} + m_r R^2 \\ k_e &= kR^2\end{aligned}$$

This means that:

$$\omega_n^2 = \frac{k_e}{I_e} = \frac{kR^2}{I_m + I_s + \frac{m_p R^2}{2} + m_r R^2}$$

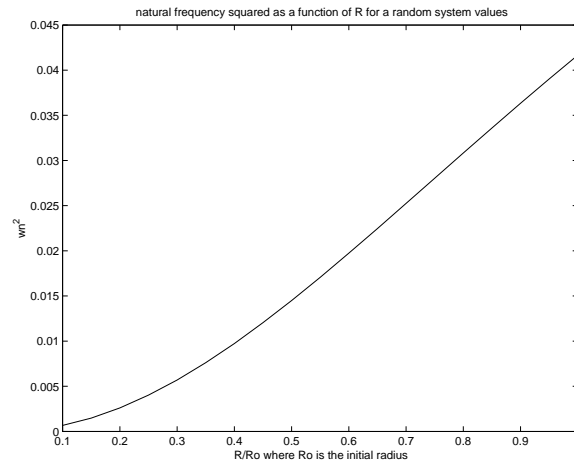


Figure 2: Natural frequency vs R

It is a little difficult to see since both the numerator and denominator contain R, but we can see that as R drops the denominator converges to a positive real value, while the numerator converges to zero. This that the system natural frequency drops as R drops. Figure illustrates how the natural frequency drops as R gets smaller for this system with some set of values for I, R, m, and k.

**Problem 6 - Palm 1.21**

a)  $\gg (-3+5i)*(-6+7i)$

ans=-17-51i

b)  $\gg (-3+5i)/(-6+7i)$

ans=0.625-0.1059i

c)  $\gg 3*i/2$

ans=0+1.5i

d)  $\gg 3/(2i)$

ans=0-1.5i

**Problem 7 - Palm 1.22**

a)  $\gg x=-5-7i; y=6+2i$

$\gg x+y$

ans=1-5i

b)  $\gg x*y$

ans=-16-52i

c)  $\gg x/y$

ans=-1.1-0.8i