

8.07 Homework 2

Problem 1. Griffiths 1.48 (p.52).

Problem 2. Exercises with δ -functions

(i) A charge Q is spread uniformly over a spherical shell of radius R . Express the volume charge density using a delta function in spherical coordinates. Repeat for a ring of radius R with charge Q lying in the xy plane.

(ii) Express a three dimensional delta function in cylindrical coordinates (ρ, ϕ and z).

(iii) A charge λ per unit length is distributed uniformly over a cylindrical surface of radius b . Give the volume charge density using a delta function in cylindrical coordinates

(iv) What is $\nabla^2 \ln r$ in two dimensions ?

Problem 3. This problem is closely related to problem 1.60, p.56 of Griffiths. You will find useful hints there– but try without hints first!. Show that:

(i) $\int_V \nabla \psi d^3x = \int_S \psi d\vec{a}$, where S is the surface bounding the volume V . Show that as a consequence of this, $\int_S d\vec{a} = 0$ for a closed surface S .

(ii) $\int_V \nabla \times \vec{A} d^3x = \int_S d\vec{a} \times \vec{A}$, where S is the surface bounding the volume V .

(iii) $\int_S \nabla \psi \times d\vec{a} = - \oint_{\Gamma} \psi d\vec{l}$, where Γ is the boundary of the surface S .

(iv) For a closed surface S , one has $\int_S (\nabla \times \vec{A}) \cdot d\vec{a} = 0$.

Problem 4. Griffiths 1.61, p.57, parts (c), (d) and (e), only. In part (d) Griffiths is a bit unclear: take an arbitrary loop and draw the cone subtended by the loop and with apex at the origin.

Problem 5. Exercises: (i) Griffiths 2.2 (p. 61), (ii) Griffiths 2.5 (p.64)

Problem 6. (Challenging!) A direct calculation of $\vec{A}(\vec{x})$ given $\vec{B} = \vec{\nabla} \times \vec{A}$.

Prove that

$$\vec{A}(\vec{x}) = - \int_0^1 t dt \vec{x} \times \vec{B}(t\vec{x}),$$

by showing by explicit computation that the proposed \vec{A} satisfies $\vec{\nabla} \times \vec{A} = \vec{B}$ provided that $\nabla \cdot \vec{B} = 0$. In order to solve this problem, it is useful to define $\vec{y} = t\vec{x}$, and then to prove that

$$\nabla_{\vec{x}} = t \nabla_{\vec{y}}, \quad \text{and} \quad \frac{d}{dt} \vec{B}(t\vec{x}) = \frac{1}{t} (\vec{x} \cdot \nabla_{\vec{x}}) \vec{B}(t\vec{x}).$$

Final hint: try to turn the integrand into a total derivative.

Problem 7. Griffiths 2.12 (p.75). Do not compare with 2.8.

Problem 8. Griffiths 2.18 (p.75).