

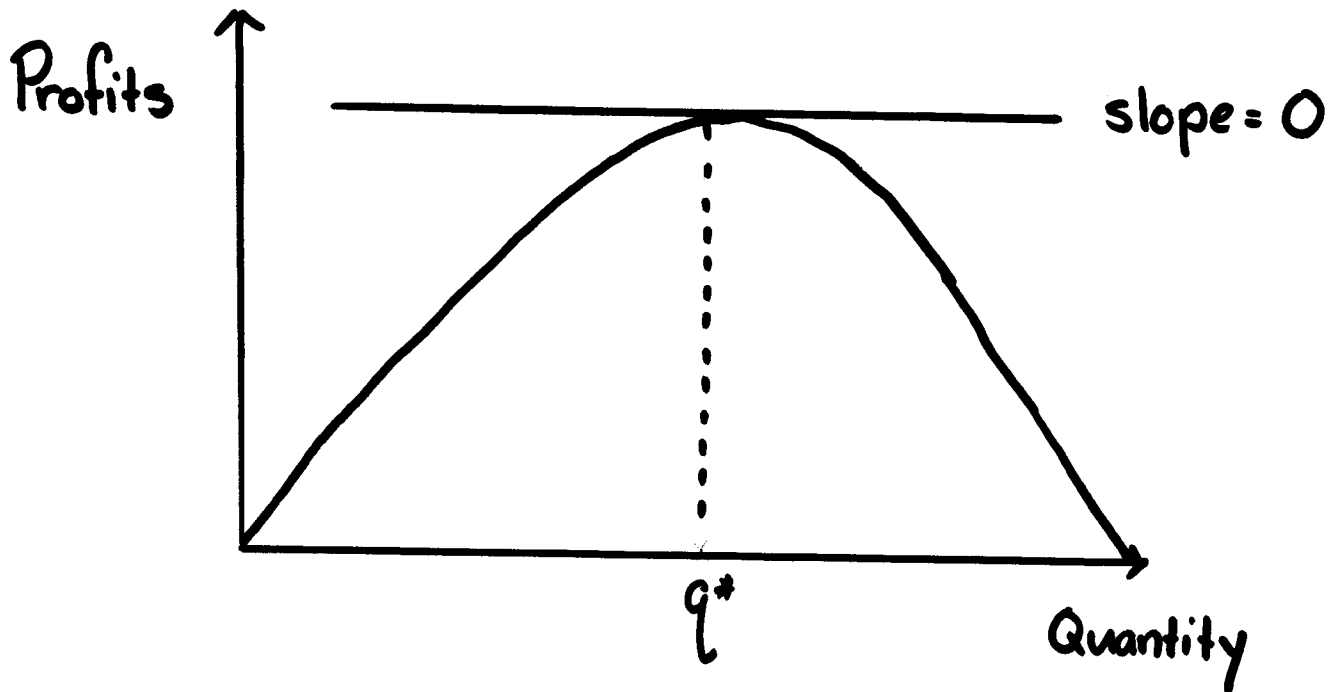
# 14.03 Fall 2000 - Lecture # 3

- Optimization
  - single variable
  - multi-variable
- Implicit Function Theorem & comparative statistics
- Envelope Theorem - constrained & unconstrained
- Constrained Optimization (Lagrangian Method)
- Duality

# Single Variable Optimization

$\Pi(q)$  is profit function

Choose  $q^*$  to maximize  $\Pi(q)$

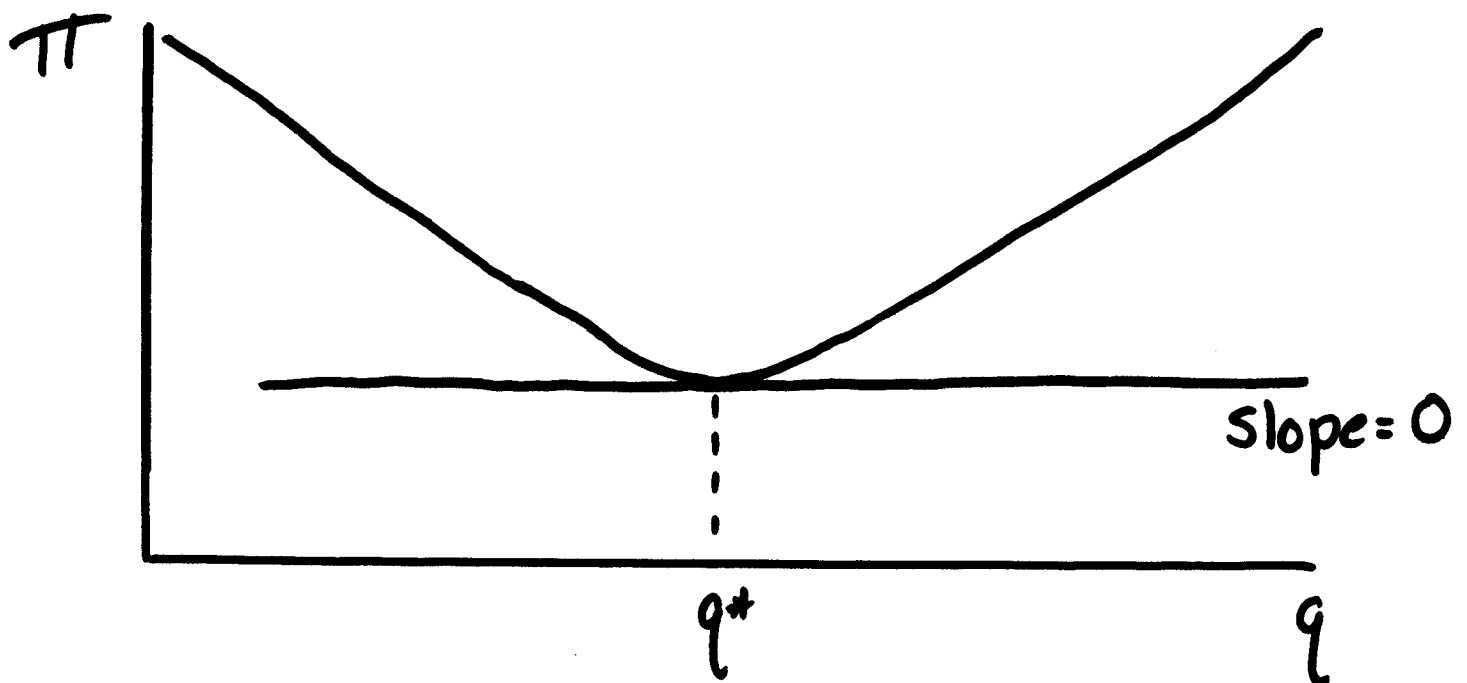


$$\frac{d\Pi}{dq} \Big|_{q^*} = 0 \quad \text{"First order condition" (FOC)}$$

Q: Is  $q^*$  necessarily the profit max?

A: No,  $q^*$  is necessary but not sufficient for profit max.

# Single Variable Optimization

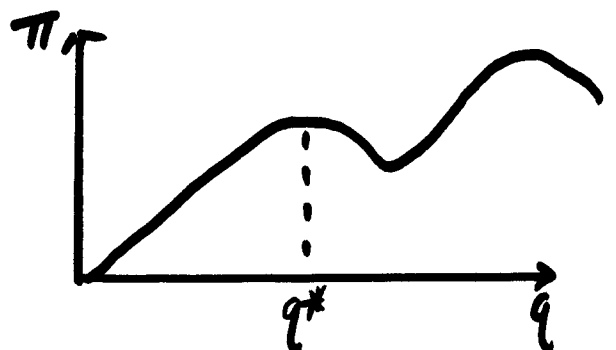
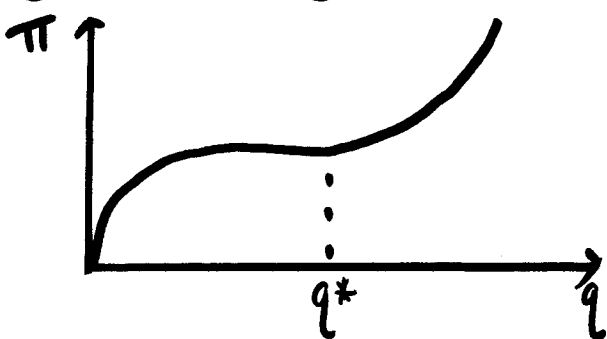


$\frac{d\pi}{dq} |_{q^*} = 0$  but  $q^*$  is a profit minimum

Second order condition:

$\frac{d^2\pi}{dq^2} |_{q^*} < 0$ , guarantees that  $q^*$  is a (local) maximum

Does not solve:



## Optimization

We'll generally work with "well-behaved" functions: continuous, differentiable, concave. Hence, we won't focus on Second Order Conditions (read about them in Chapter 2, however).

### Multi-Variate Case

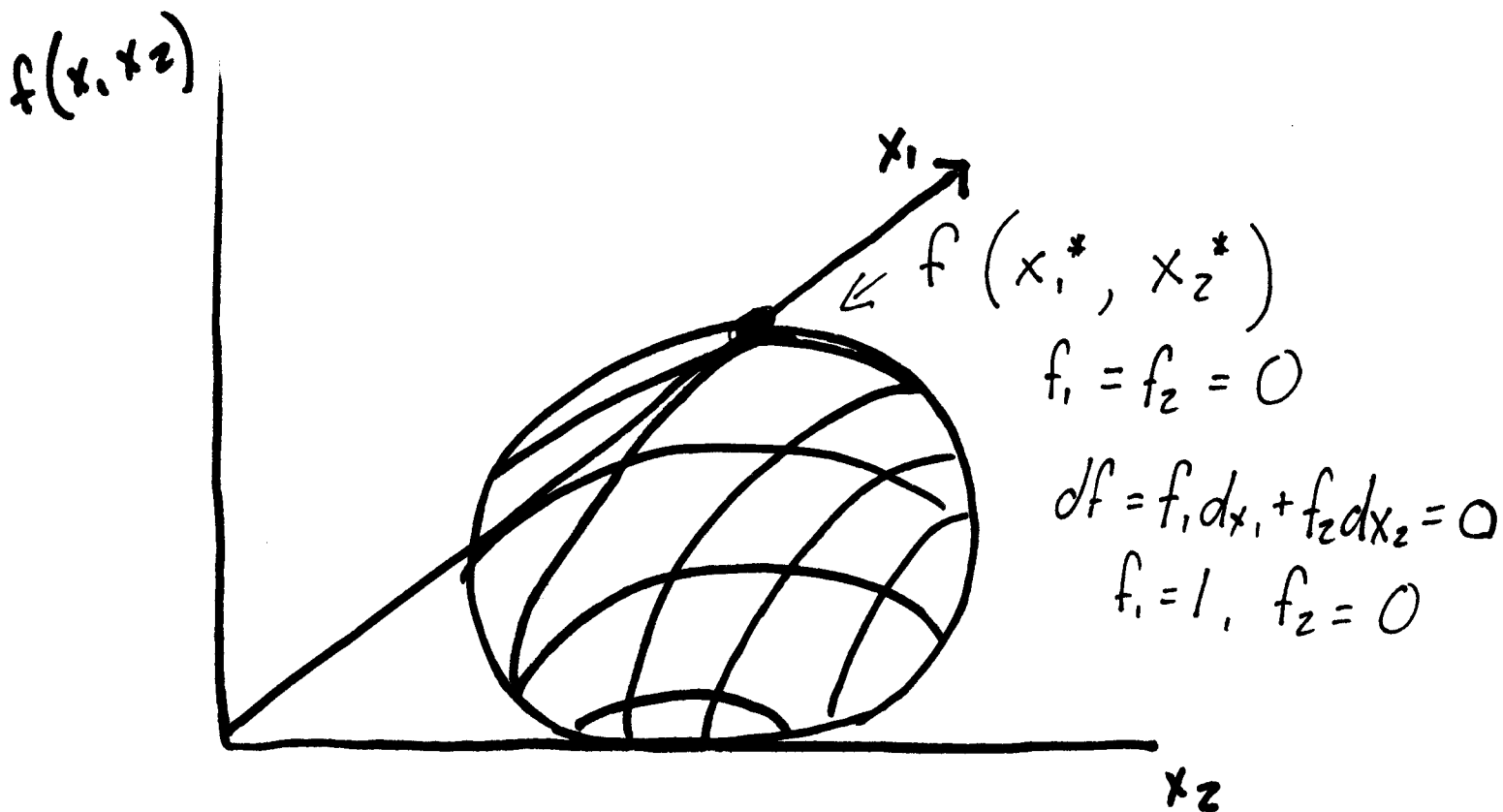
$$y = f(x_1, x_2, \dots, x_n)$$

$$\frac{\partial f(\cdot)}{\partial x_1} \equiv f_1 \quad \frac{\partial f(\cdot)}{\partial x_2} \equiv f_2 \quad \dots$$

$$\frac{\partial f(\cdot)}{\partial x_n} = f_n$$

First Order Condition (FOC) for maximum (or minimum):

$$f_1 = f_2 = \dots = f_n = 0$$



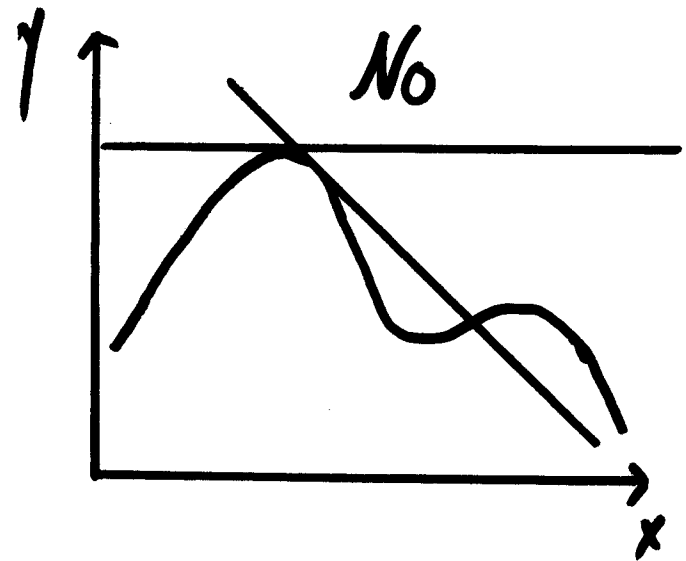
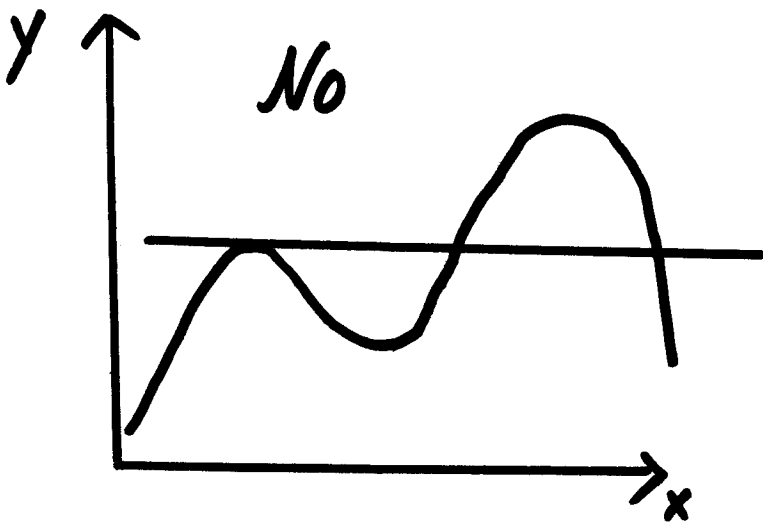
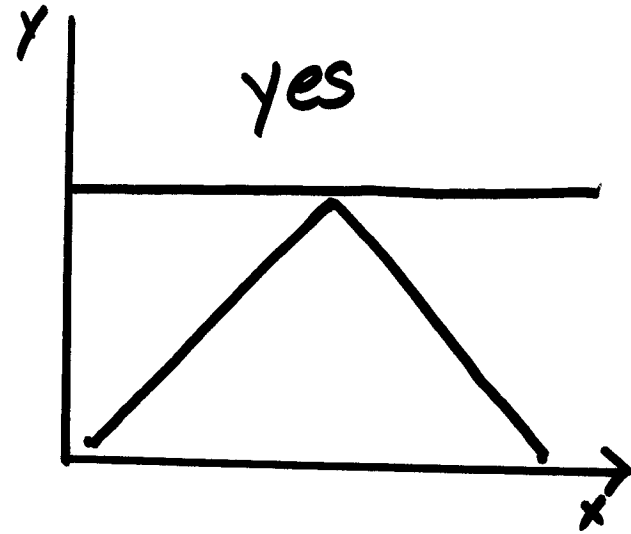
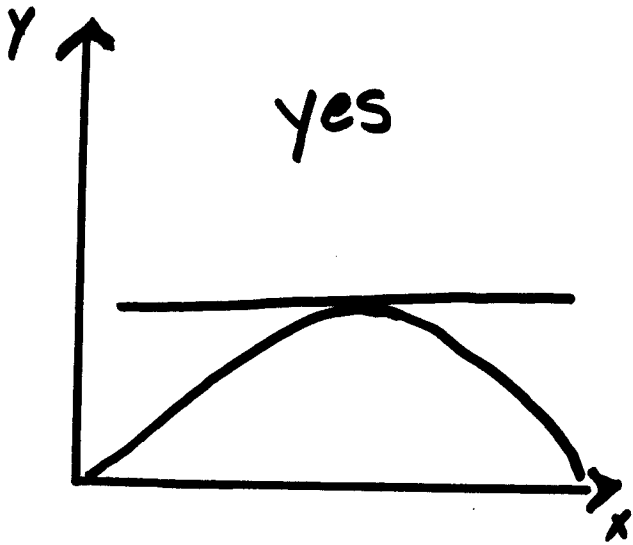
Optimization of a function with 2 variables

Any concave function will be maximized at its "flat spot" or "saddle point".  
 $(f_1 = f_2 = \dots = f_n = 0)$

A concave function is a function that always lies below any equ-dimensional surface that is tangent to it:  
 (1 dimension  $\rightarrow$  line, 2 dimensions  $\rightarrow$  plane, 3 dimensions  $\rightarrow$  hyper-plane)

$$S.O.C. = d^2f = f_{11} (dx_1)^2 + 2f_{12} dx_1 dx_2 + f_{22} (dx_2)^2 < 0 \quad 5$$

# Concave Functions



## Two Dimensional

- Inverted Teacup? yes
- Non-Inverted Teacup? No

# Implicit Functions

endogenous      exogenous

1)  $y = mx + b$       Explicit

2)  $y - mx - b = 0$       Implicit

3)  $f(y, x; m, b) = 0$       Implicit

2 & 3 are called implicit because the relationship between the variables is implicitly present rather than explicitly shown as  $y = f(x)$ .

Many times in economics, we end up with implicit functions where exogenous and endogenous variables are all mixed together.

We may have no closed form expression for  $y(x)$ , but the derivative  $\frac{dy}{dx}$  may still exist, and this is often exactly what we need.

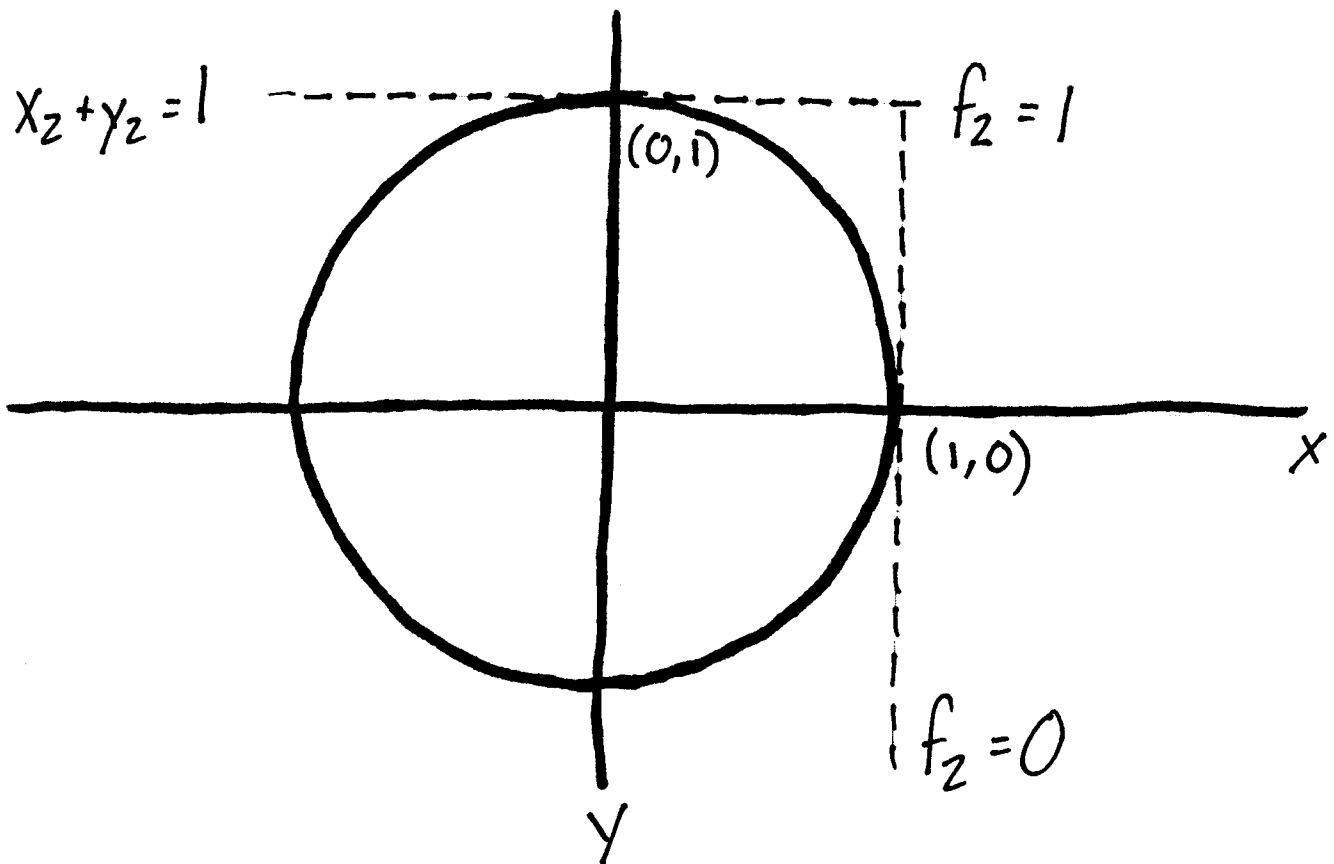
## Easy to Work With Implicit Functions

$$f(x, y) = 0 \Rightarrow f(x, y(x)) = 0$$
$$f_x dx + f_y dy = 0$$
$$\frac{dy}{dx} = -\frac{f_x}{f_y}$$

Caveat:  $\frac{dy}{dx}$  may not exist ...



# Implicit Functions



When can we write:  $f(x^*, y(x^*)) = 0$ ?

Take implicit function:

$$x^2 + y^2 - 1 = 0 \quad 2x dx + 2y dy = 0$$

$$\frac{dy}{dx} = -\frac{f_1}{f_2} = -\frac{x}{y} = 0 \quad \left. \vphantom{\frac{dy}{dx}} \right\} \text{Undefined when } f_2 = y = 0$$

Q: What is the intuition for the non-existence of  $f(x^*, y(x^*)) = 0$  at  $(x, y) = (1, 0)$ ?

A:  $\frac{dy}{dx}$  could be  $\oplus$  or  $\ominus$  here. Undefined.

## Implicit Function Example

Long Way:

$$2x^2 + y^2 = 225, \quad \text{what's } \frac{dy}{dx} ?$$

$$y = \sqrt{225 - 2x^2}$$

$$\begin{aligned} \frac{dy}{dx} &= \frac{1}{2} (225 - 2x^2)^{-1/2} (-4x) = \frac{-4x}{2\sqrt{225 - 2x^2}} \\ &= -\frac{4x}{2y} = -\frac{2x}{y} \end{aligned}$$

Implicit Function Method:

- ① Write:  $2x^2 + y^2 - 225 = 0$
- ② Totally differentiate:  $4x dx + 2y dy = 0$
- ③ Rearrange:  $\frac{dy}{dx} = \frac{4x}{2y} = -\frac{2x}{y}$

You can see how this works formally:

Suppose there is a continuous solution to  $y = y(x)$   
for the equation  $F(x, y) = C \Rightarrow F(x, y(x)) = C$

We want to know  $\frac{dy}{dx}$  for sum  $x_0, y(x_0)$

Use the chain rule to differentiate.

$$\frac{\partial F}{\partial x}(x_0, y(x_0)) = \frac{\partial F}{\partial x}(x_0, y(x_0)) \frac{dx}{dx} + \frac{\partial F}{\partial y}(x_0, y(x_0)) \cdot \frac{dy}{dx}(x_0) = C$$

$$\text{Simplify: } = \frac{\partial F}{\partial x}(x_0, y(x_0)) + \frac{\partial F}{\partial y}(x_0, y(x_0)) \cdot y'(x_0) = 0$$

$$y'(x_0) = - \frac{\partial F}{\partial x}(x_0, y(x_0))$$

---

$$\frac{\partial F}{\partial y}(x_0, y(x_0))$$

Necessary condition for  $y'(x_0)$  to exist is that

$\frac{\partial F}{\partial y}(x_0, y(x_0)) \neq 0 \Rightarrow$  Turns out this is sufficient also.

[multivariate:  $\frac{\partial F}{\partial y}(x^*, \dots, x_n^*, y^*) \neq 0$ ]

Take a more complicated example:

$$x^2 - 3xy + y^3 - 7 = 0$$

What is  $\left. \frac{dy}{dx} \right|_{\substack{x=4 \\ y=3}}$  note: A Valid Solution

Use implicit function theorem:

① Totally differentiate

$$2x dx - 3y dx + 3x dy + 3y^2 dy = 0$$

$$3y^2 dy - 3x dy = 2x dx + 3y dx$$

$$\frac{dy}{dx} = \frac{-2x + 3y}{3y^2 - 3x}$$

② Plug In (Substitute)

$$\left. \frac{dy}{dx} \right|_{(4,3)} = \frac{-8 + 9}{27 - 12} = \frac{1}{15}$$

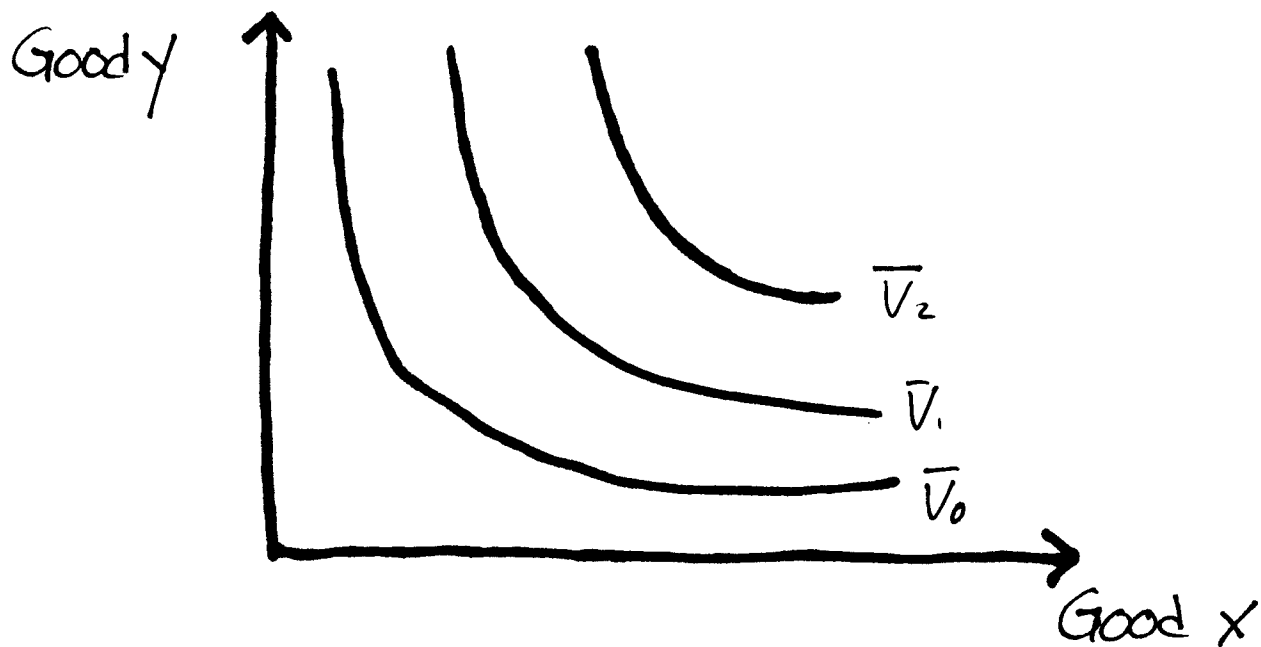
Q: What is  $y_1(x=4.3)$ ?  $\approx y(4) + \left. \frac{dy}{dx} \right|_{x=4} (.3)$

③ Take  $\Delta x = .3$

$$y_1 \approx 3 + .3\left(\frac{1}{15}\right) = 3.02$$

To solve for  $y$  at  $x=4.3$  could only be computed numerically and equals 3.01475

# Applications of Implicit Functions



- Along an indifference curve, we have  $V(x, y) = \bar{V}$
- Implicit function  $V(x^*, y^*(x^*)) = \bar{V}$  tells how much  $y$  we'd give up for a little more  $x$  (at the margin) while holding total utility constant.

$$V(x^*, y^*(x^*)) = \bar{V} \Rightarrow \frac{\partial V}{\partial x} dx + \frac{\partial V}{\partial y} dy = 0$$

$$\frac{dy}{dx} = \frac{V'(x)}{V'(y)}$$

## Envelope Theorems

A shortcut for taking derivatives of optimized functions with respect to their parameters.

Definition (unconstrained case). Let  $f(x, a)$  be a  $C^1$  function of  $x \in \mathbb{R}^n$  and the scalar  $a$ . For each  $a$ , consider the unconstrained maximization:

$$\max f(x, a) \underbrace{\text{w.r.t. } x}_{\text{"with respect to"}}$$

Let  $x^*(a)$  be a solution of this problem. Suppose that  $x^*(a)$  is a  $C^1$  function of  $a$ . Then,

$$\frac{d}{da} \underbrace{f(x^*(a), a)}_{\text{total derivative}} = \frac{d}{da} \underbrace{f(x^*(a), a)}_{\text{partial derivative}}$$

## Proof of the Envelope Theorem

$$\frac{d}{da} f(x^*(a), a) = \underbrace{\sum \frac{df}{dx_i}(x^*(a), a) \cdot \frac{dx_i^*(a)}{da}}_{= 0} + \frac{df}{da}(x^*(a), a) = \frac{df}{da}(x^*(a), a)$$

$$\text{b/c } \frac{df}{dx_i}(x^*(a), a) = 0 \quad \forall i$$

These are the first order conditions of the maximization problem to obtain  $x^*$  [that maximizes  $f(x, a)$ ]

(much more intuitive - and useful - than it looks.)

## Envelope Theorem Example

### Long Route:

$$\textcircled{1} \quad y = -x^2 + ax$$

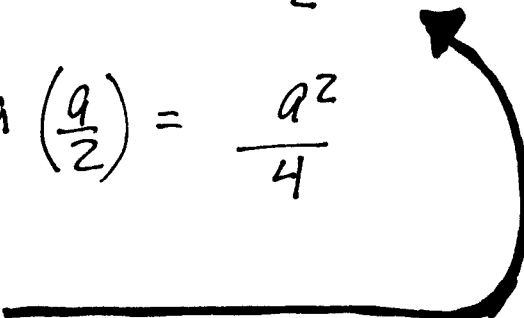
Want to know:

$$\frac{dy^*}{da} \quad \text{where } y^* \text{ is maximized value of } \textcircled{1}$$

Find  $x^*$  through single variable optimization

$$\frac{dy}{dx} = -2x + a = 0, \quad x^* = \frac{a}{2} \Rightarrow$$

$$y^* = -\left(\frac{a}{2}\right)^2 + a\left(\frac{a}{2}\right) = \frac{a^2}{4}$$

$$\frac{dy^*}{da} = \frac{a}{2} = x^*$$


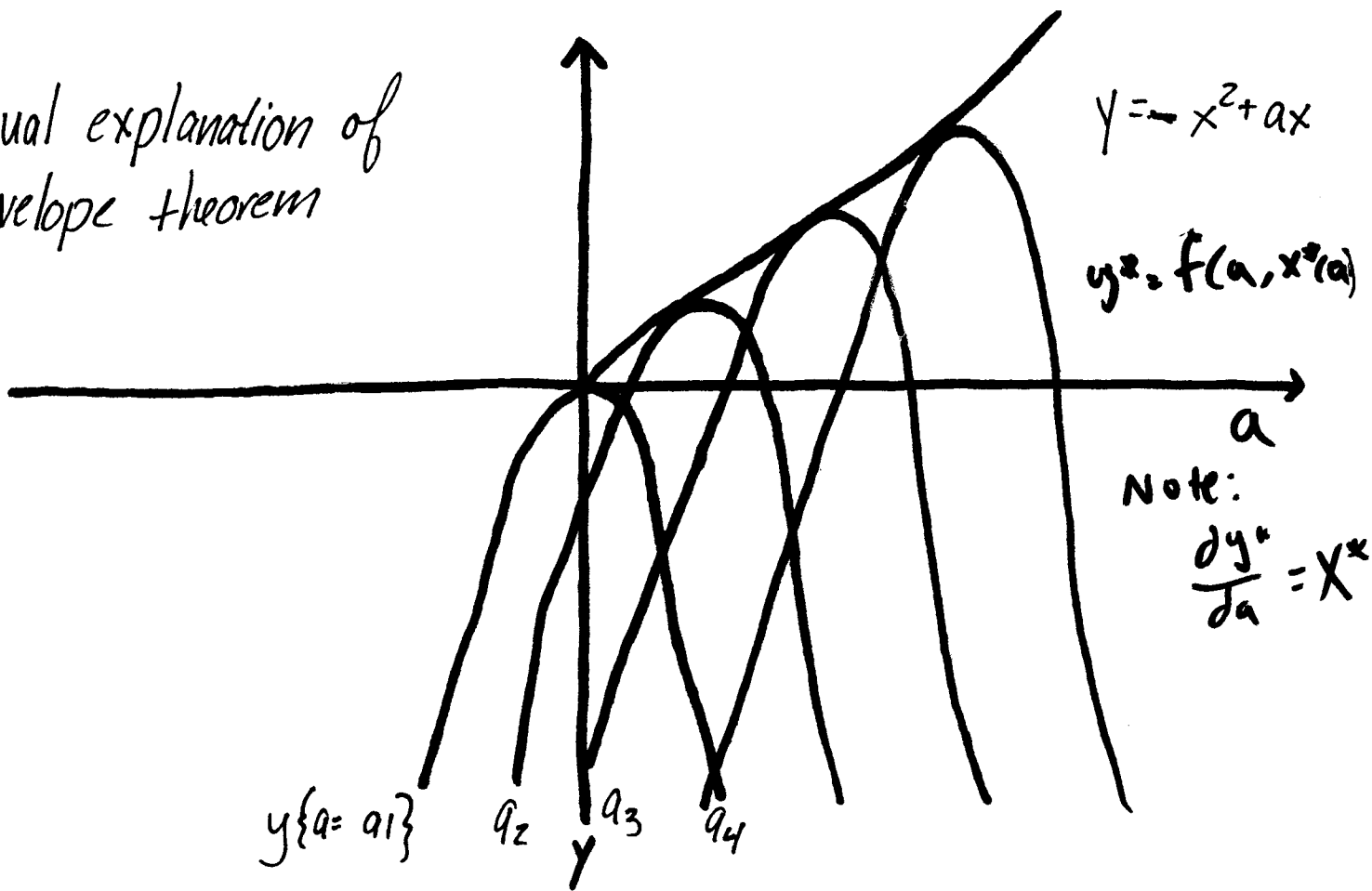
### Envelope shortcut

$$\text{Rewrite } \textcircled{1}: y^* = -(x^*)^2 + ax^*$$

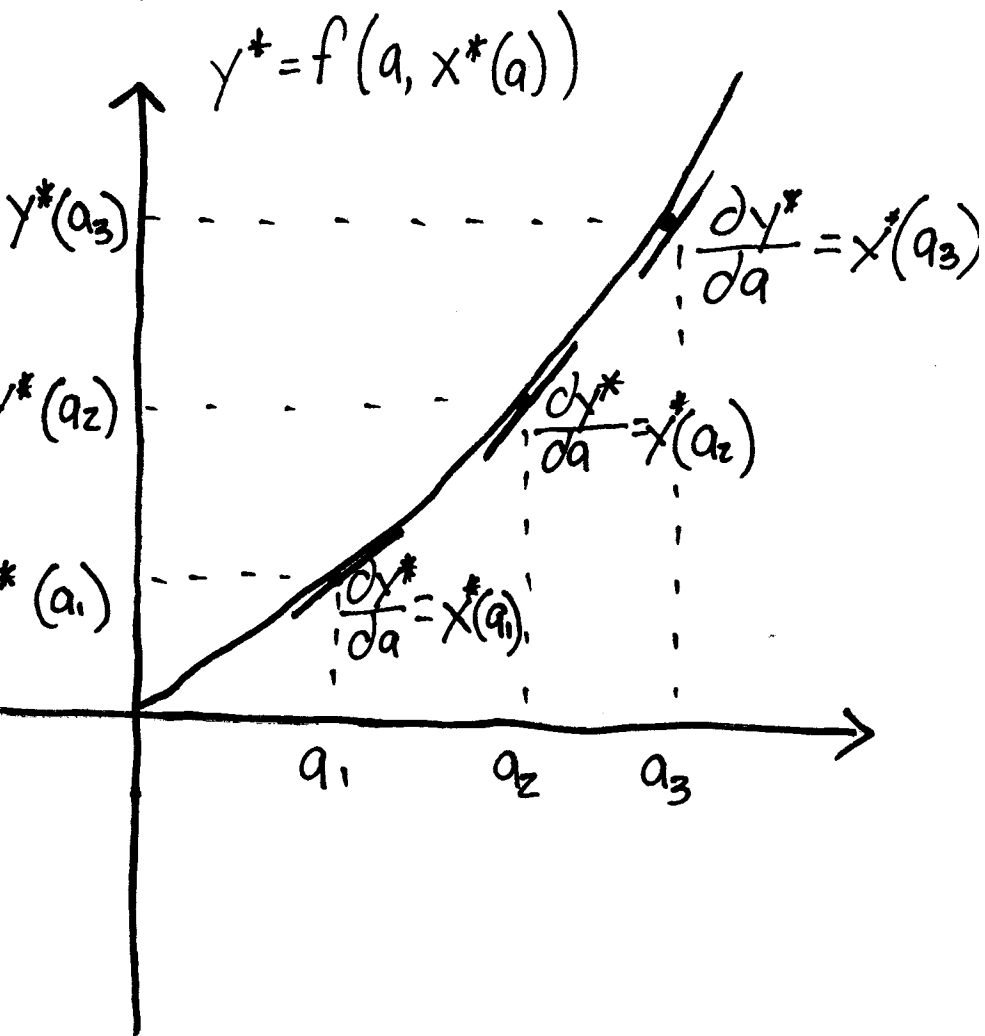
$$\frac{dy}{da} = x^* = \frac{dy^*}{da} \{x^* = x^*(a)\}$$



Visual explanation of envelope theorem



Note: Envelope Theorem is a linear approximation & hence only holds in an "envelope" surrounding  $x^*(a)$ .



Envelope Theorem is Multi-Variate

$$y^* = f [x_1^*(a), x_2^*(a), \dots, x_n^*(a); a]$$

$$\frac{dy^*}{da} = \frac{df}{dx_1} \cdot \frac{dx_1}{da} + \dots + \frac{df}{dx_n} \cdot \frac{dx_n}{da} + \frac{df}{da}$$

$$= 0$$

$$\Rightarrow \frac{dy^*}{da} = \frac{df}{da}$$

## Constrained Maximization

Most maximization problems in economics are subject to constraints:

- Maximize utility subject to budget constraint.
- Maximize social welfare subject to a resource constraint.
- Maximize profits subject to a technological constraint (e.g. can only produce so many lattes in one hour).

Tool for maximizing constrained functions:

Lagrangian Method.

A "trick" which turns out to have very useful economic content.

# Lagrangian Method

Problem:

$$\begin{aligned} \max \quad & y = f(x_1, x_2, \dots, x_n) \\ \text{s.t.} \quad & g(x_1, x_2, \dots, x_n) = 0 \\ \text{(subject to)} \end{aligned}$$

- Any function can be written in this implicit notation

$$x_1 + x_2 = 10 \Leftrightarrow x_1 + x_2 - 10 = 0$$

Setup:  $\mathcal{L}$  script  $\lambda$

$$\mathcal{L} = f(x_1, x_2, \dots, x_n) + \lambda g(x_1, x_2, \dots, x_n)$$

F. O. C. 's (First order conditions):

$$\frac{d\mathcal{L}}{dx_1} = f_1 + \lambda g_1 = 0$$

$$\vdots$$
$$\frac{d\mathcal{L}}{dx_n} = f_n + \lambda g_n = 0$$

$$* \frac{d\mathcal{L}}{d\lambda} = g(x_1, x_2, \dots, x_n) = 0$$

$\Rightarrow$  Get as many equations as unknowns.

Solve simultaneously for  $x_1^*, \dots, x_n^*$  and  $\lambda$ .

## Constrained Max Example

Optimal fence dimensions.

- Have fencing of perimeter length  $p$
- Maximize fenced area

Objective:

$$\max x \cdot y$$

Constraint:

$$2x + 2y = p \quad \Rightarrow \quad p - 2x - 2y = 0$$

Lagrangian:

$$L = x \cdot y + \lambda (p - 2x - 2y)$$

$$\frac{\partial L}{\partial x} = y - 2\lambda = 0$$

$$\frac{\partial L}{\partial y} = x - 2\lambda = 0$$

$$\frac{\partial L}{\partial \lambda} = p - 2x - 2y = 0$$

$$\Rightarrow y/2 = x/2 = \lambda, \quad x = y = \frac{p}{4}, \quad \lambda = \frac{p}{8}$$

## Optimal Fence (cont.)

$$x = y = P/4, \quad \lambda = P/8$$

- Optimal fence is square ( $x=y$ )
- (Q: what else do we assume about shape?)
- What is the interpretation of  $\lambda = P/8$ ?

$$\text{Observe that: } \frac{f_1}{-g_1} = \frac{f_2}{-g_2} = \lambda$$

§ (Lagrangian)

Where  $f_1$  is the marginal gain to  $Z$  from 1 more  $X$ ,  
and  $g_1$  is the marginal cost of 1 more  $X$  in terms of  
tightening the constraint & hence reducing feasible  $y$ .

This ratio,  $\lambda$ , is called the "shadow price" of the  
constraint,

✓ i.e. more area

## Interpretation of $\lambda$

$\lambda = \frac{P}{8}$  implies that relaxing the constraint that  $x + y = P$  by 1 unit would allow us to increase the maximand (area) by  $\frac{P}{8}$ .

Check this:

$$\text{Let } P = 40 \Rightarrow x = y = 10, A = 100$$

Compare to:

$$\text{Let } P = 41 \Rightarrow x = y = 10.25, A = 105.06$$

$$\Delta A = 5.06 \approx \frac{40}{8}$$

$\Rightarrow$  Multiplier  $\lambda$  is quite close to actual change in  $A$  for 1 unit change in constraint (and is exactly correct over an epsilon interval from  $(x^*, y^*, P = 40)$ )

- This multiplier is called the "shadow price" of the constraint.

## Another Constrained Max example

$$\max Z = x^{1/2} y^{1/2} \quad \text{s.t. } x + y = 4$$

$$Z = x^{1/2} \cdot y^{1/2} + \lambda (4 - x - y)$$

$$\frac{\partial Z}{\partial x} = \frac{1}{2} x^{-1/2} y^{1/2} - \lambda = 0$$

$$\frac{\partial Z}{\partial y} = \frac{1}{2} x^{1/2} y^{-1/2} - \lambda = 0$$

$$\frac{\partial Z}{\partial \lambda} = 4 - x - y = 0$$

$$\frac{1}{2} x^{-1/2} y^{1/2} = \frac{1}{2} x^{1/2} y^{-1/2} = \lambda \Rightarrow x = y = 2$$

and  $\lambda = \frac{1}{2}$  (after some algebra)

Check multiplier's implication:

$$f(x, y, 4) = 2^{1/2} \cdot 2^{1/2} = 2$$

$$f(x, y, 5) = 2.5^{1/2} \cdot 2.5^{1/2} = 2.5$$

$$\Delta Z = \frac{1}{2} \quad \text{exactly equal to } \lambda$$



# Envelope Theorem for Constrained Problems

Let  $x^*(a) = (x_1^*(a), \dots, x_n^*(a))$  denote a solution to  $\max f(x, a)$  s.t.  $\underbrace{g_1(x, a) = 0 \dots g_k(x, a) = 0}_{\text{constraints - could be many}}$

Let  $\lambda_1(a), \dots, \lambda_k(a)$  be the Lagrange multipliers of this problem. Then:

$$\underbrace{\frac{d}{da} f(x^*(a), a)}_{\text{Total derivative of original function } f(\cdot)} = \underbrace{\frac{dZ}{da}(x^*(a), \lambda(a), a)}_{\text{Partial derivative of Lagrangian}}$$

Why is this true?

- Because at  $x^*(a)$ , constrained function is already maximized w.r.t. each  $x_i$  so:

$$\sum_i \frac{df}{dx_i}(x^*(a), a) \cdot \frac{\partial x_i^*}{\partial a} = 0$$

• The only non-zero partial derivative is  $\frac{dZ}{da} = \lambda(a)$ .

# Envelope Theorem for Constrained Problems

This result is much more obvious than it looks....

Consider our previous problem:

$$\max x^{1/2} y^{1/2} \text{ s.t. } x + y = 4$$

$$Z = x^{1/2} + y^{1/2} + \lambda(4 - x - y)$$

$$\frac{\partial Z}{\partial x} = \frac{1}{2} x^{-1/2} y^{1/2} - \lambda = 0$$

$$\frac{\partial Z}{\partial y} = \frac{1}{2} x^{1/2} y^{-1/2} - \lambda = 0$$

$$\frac{\partial Z}{\partial \lambda} = 4 - x - y = 0$$

We found:  $x^* = y^* = 2$ ,  $\lambda = \frac{1}{2}$

What is:

$$1) \frac{\partial f(x^*(a), y^*(a), a)}{\partial x^*} ? \quad (0)$$

$$2) \frac{\partial f(x^*(a), y^*(a), a)}{\partial y^*} ? \quad (0)$$

$$3) \frac{\partial f(x^*(a), y^*(a), a)}{\partial a} ? \quad (\lambda)$$

# Duality

Every "primal" maximization problem subject to a constraint has a corresponding "dual" problem that minimizes the constraint function subject to the original objective function being equal to its optimal value in the original problem.

Primal:  $\max z = f(x, y)$  s.t.  $x + y = \bar{K}$   
yields  $z^* = f(x^*, y^*)$

Dual:  $\min K = x + y$  s.t.  $f(x, y) = z^*$   
will also obtain:

$$x_D^* = x_P^*$$

$$z_D^* = z_P^*$$

D = Dual

$$y_D^* = y_P^*$$

P = Primal

$$x_D^* + y_D^* = \bar{K}$$

## Duality Example

Primal Problem (familiar):

$$\max x^{1/2} y^{1/2} \quad \text{s.t.} \quad x+y=4$$

$$z = f(x, y) = x^{1/2} y^{1/2}$$

$$g(x, y) = 4 - x - y$$

$$Z = x^{1/2} y^{1/2} + \lambda (4 - x - y)$$

$$x^* = 2$$

$$z^* = 2$$

$$y^* = 2$$

$$\lambda = 1/2$$

Dual problem:

$$\min x + y$$

$$\text{s.t.} \quad x^{1/2} y^{1/2} = 2$$

$z^*$  from primal

$$f(x, y) = x + y$$

$$g(x, y) = 2 - x^{1/2} y^{1/2}$$

$$Z = x + y + \lambda_D (2 - x^{1/2} y^{1/2})$$

$$\text{Yields: } x_D^* = 2, \quad y_D^* = 2, \quad f(x+y) = 4$$

Q: Can you guess the value of  $\lambda_D$ ?

## Duality Example

Recall that:

$$\lambda_p = \frac{f_1}{-g_1} = \frac{f_n}{-g_n} \quad \text{eg.} = \frac{df/dx}{-dg/dx}$$

And for dual:

$$\begin{aligned} \text{we substituted } f_D &= g_P \\ g_D &= f_P \end{aligned}$$

Hence:

$$\lambda_D = \frac{dg/dx}{-df/dx} = \frac{1}{\lambda_P}$$

Why should we care about duality?

- Cost minimization is dual of profit maximization
- Expenditure minimization is dual of utility maximization

We'll be relying on these duality relationships all semester....