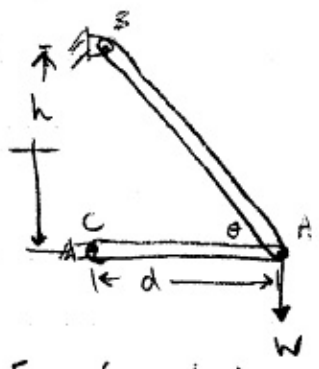


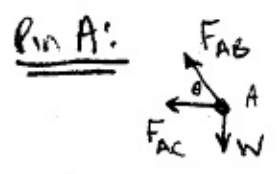
①

SOLUTIONS FOR PROBLEM SET 2

PROBLEM 1



Let us consider equilibrium about the pins to solve this problem:



$$\sum F_x = 0: -F_{AB} \cos \theta - F_{AC} = 0 \quad \text{①}$$

$$\sum F_y = 0: F_{AB} \sin \theta - W = 0 \quad \text{②}$$

From ② \rightarrow $F_{AB} = \frac{W}{\sin \theta} = \frac{W(h^2 + d^2)^{1/2}}{h}$

From ① \rightarrow $F_{AC} = -F_{AB} \cos \theta$

Combining ①, ② \rightarrow $F_{AC} = -\frac{W}{\tan \theta}$

$$F_{AC} = -\frac{Wd}{h}$$

From geometry:

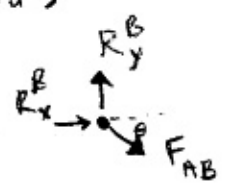
$$\tan \theta = \frac{h}{d}$$

$$\overline{AB}^2 = h^2 + d^2$$

$$\overline{AB} = (h^2 + d^2)^{1/2}$$

$$\sin \theta = \frac{h}{(h^2 + d^2)^{1/2}}$$

Pin B:



* Note: F_{AB} on Pin B acts equal and opposite than the direction shown on Pin A. This is the nature of internal forces in Two-Force Members

$$\sum F_x = 0: R_x^B - F_{AB} \cos \theta = 0 \quad \text{③}$$

$$\sum F_y = 0: R_y^B - F_{AB} \sin \theta = 0 \quad \text{④}$$

From ③ \rightarrow $R_x^B = -F_{AB} \cos \theta$

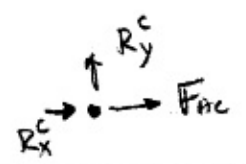
Combine ②, ③ \rightarrow $R_x^B = -\frac{W}{\tan \theta} = -\frac{Wd}{h}$

* NOTE: $R_y^B = W$, which would result if a Free Body Diagram was done of the entire truss structure

From ④ \rightarrow $R_y^B = F_{AB} \sin \theta$

Combine ②, ④ \rightarrow $R_y^B = W$

Pin C:



$$\sum F_x = 0: F_{AC} + R_x^C = 0 \quad \text{⑤}$$

$$\sum F_y = 0: R_y^C = 0 \quad \text{⑥}$$

From ⑤ \rightarrow $R_x^C = -F_{AC} = \frac{Wd}{h}$

What dimensions ($d : h$) would minimize these loads?

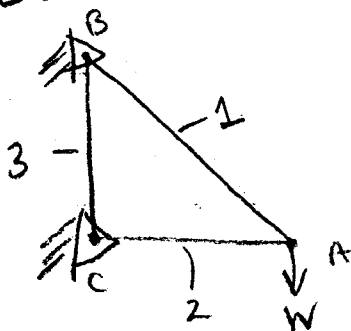
Considering that $\tan \theta = \frac{h}{d}$; $\sin \theta = \frac{h}{(h^2 + d^2)^{1/2}}$

AND that $R_x^B = \frac{-W}{\tan \theta}$; $F_{AB} = \frac{W}{\sin \theta}$

we see that As $d \gg h$, $\theta \rightarrow 0$ and $R_x^B \rightarrow -\infty$; $F_{AB} \rightarrow \infty$
 As $h \gg d$, $\theta \rightarrow 90^\circ$ and $R_x^B \rightarrow 0$; $F_{AB} \rightarrow W$

Therefore $\theta = 90^\circ$ is the most optimal position ;
 $h \gg d$.

Part B:



1) Each Joint allows 2 degrees of Freedom :

$$2 \times 3 = 6 \text{ DOF}$$

↑
of Joints

2) B & C are constrained in 2 directions each :

$$2 \times 2 = 4$$

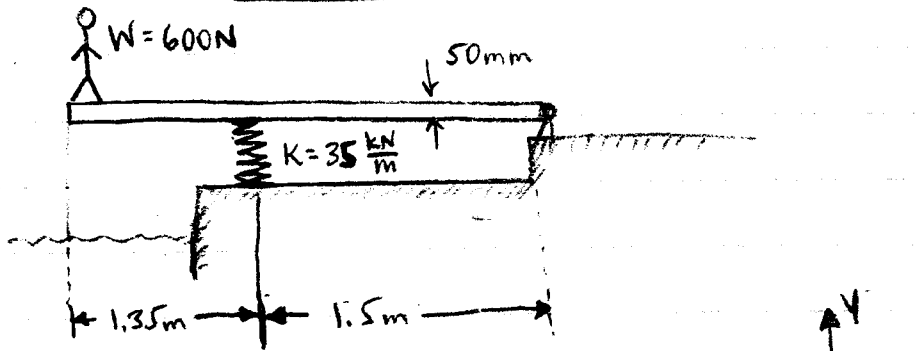
↑ # of constraints
 ↗ # of directions

3) Members provide additional constraints each

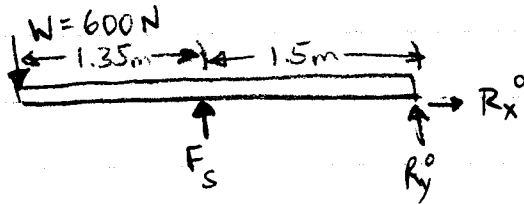
$$\text{Total Members} = 3$$

$$\underbrace{6 \text{ DOF}}_{\text{Motion allowed}} - \underbrace{7 \text{ constraints}}_{\text{Motion Prohibited}} = -1 \Rightarrow \text{STATICALLY INDETERMINATE}$$

Problem 2: CDL 2.1



FBD:



$$\sum \circlearrowleft M = 0 \quad : \quad -F_s(1.5\text{m}) + (600\text{N})(2.85\text{m}) = 0$$

$$F_s = 1140\text{ N}$$

$$F_s = k \delta$$

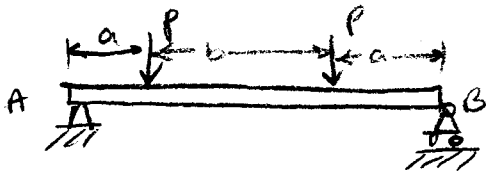
$$1140\text{ N} = 35 \frac{\text{kN}}{\text{m}} \cdot \delta$$

$$1.14\text{ kN} = 35 \frac{\text{kN}}{\text{m}} \cdot \delta$$

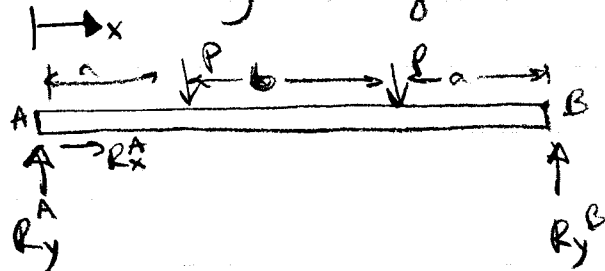
$$\delta = 0.0326\text{ m} = \underline{\underline{32.6\text{ mm}}}$$

The deflection would be slightly less if the board was extremely rigid.

Problem 3: CDL 3.5



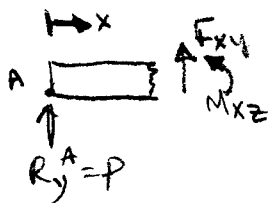
Draw the Free Body Diagram:



$$\begin{aligned} \Sigma F_x = 0: & \quad R_x^A = 0 & \text{Ⓐ} \\ \Sigma F_y = 0: & \quad R_y^A + R_y^B - 2P = 0 & \text{Ⓑ} \\ \Sigma M^A = 0: & \quad Pa + P(a+b) - (2a+b)R_y^B = 0 & \text{Ⓒ} \\ & \quad P(2a+b) - (2a+b)R_y^B = 0 & \text{Ⓓ} \\ & \quad \text{Ⓒ} \quad \underline{P = R_y^B} & \text{(Can be determined using the symmetry argument)} \end{aligned}$$

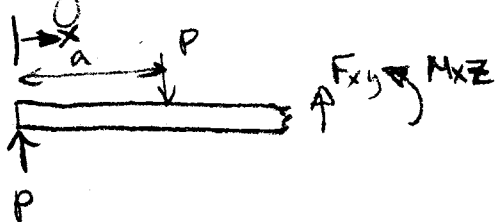
From Ⓑ; Ⓒ, we find that $R_y^A = P$ Ⓔ

In the region where $0 < x < a$:



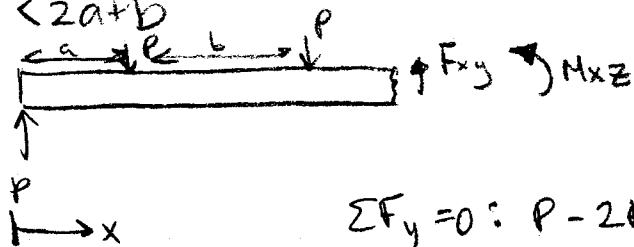
$$\begin{aligned} \Sigma F_y = 0: & \quad \underline{F_{xy} = -P} & \text{Ⓚ} \\ \Sigma M^A = 0: & \quad F_{xy} \cdot x + M_{xz} = 0 & \quad \underline{M_{xz} = Px} & \text{Ⓛ} \end{aligned}$$

In the region where $a < x < a+b$:



$$\begin{aligned} \Sigma F_y = 0: & \quad F_{xy} - P + P = 0 & \quad \underline{F_{xy} = 0} & \text{Ⓜ} \\ \Sigma M_{xz} = 0: & \quad -Pa + F_{xy} \cdot x + M_{xz} = 0 & & \\ & \quad \underline{M_{xz} = Pa} & \text{Ⓨ} \end{aligned}$$

$$a+b < x < 2a+b$$



Approach 1:
looking at beam
from left to
right

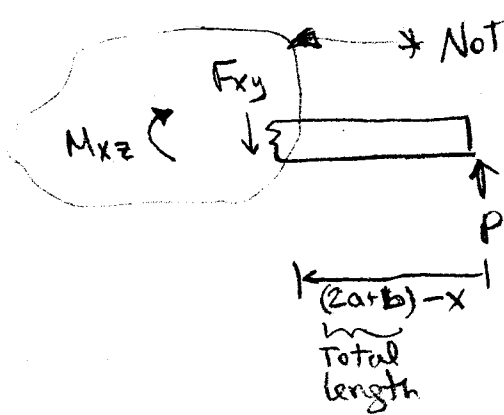
$$\sum F_y = 0: P - 2P + F_{xy} = 0$$

$$F_{xy} = P \quad \textcircled{IX}$$

$$\sum M_z = 0: -Pa - P(a+b) + F_{xy}x + M_{xz} = 0$$

$$M_{xz} = 2Pa + Pb - Px$$

$$M_{xz} = P(2a+b-x)$$



* NOTE: EQUAL & OPPOSITE
TO THE FORCES SHOWN
ABOVE

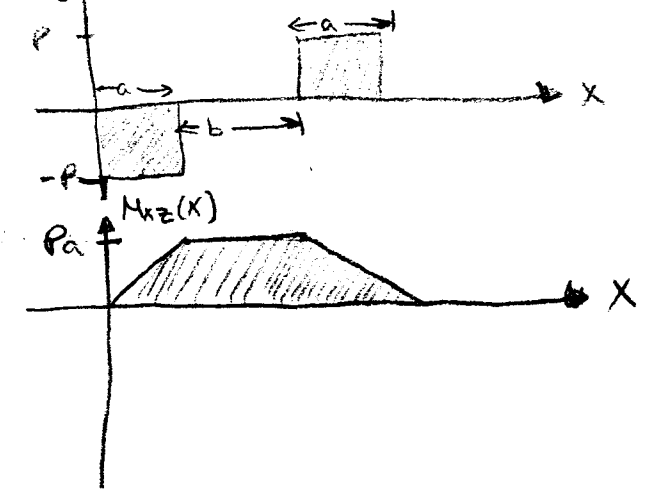
Approach 2:
looking at beam
from right to left

$$\sum F_y = 0: F_{xy} = P \quad \textcircled{XI}$$

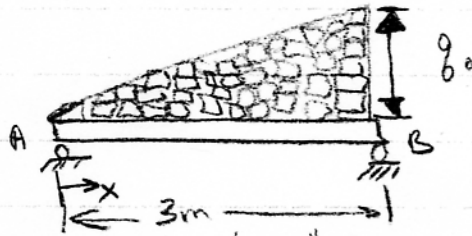
$$\sum M_z = 0: -M_{xz} + F_{xy}(2a+b-x) = 0$$

$$M_{xz} = P(2a+b-x) \quad \textcircled{XII}$$

Note: Approach 2 is simpler than Approach 1 and results are the same.



Problem 4: CDL 3.10



TOTAL LOAD = $400 \cdot 60 = 24 \text{ kN}$, however, this is a distributed load.

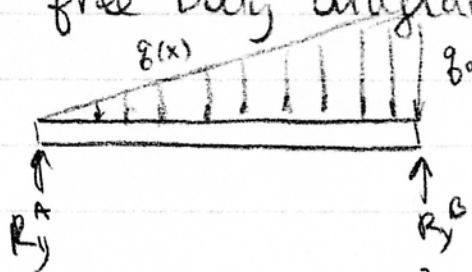
Let us determine the magnitude q_0 :

$$\text{Total Load} = \int_0^3 \frac{q_0 x}{3} dx = \int_0^3 \frac{q_0 x}{3} dx$$

$$24 \text{ kN} = \frac{q_0 x^2}{6} \Big|_0^3 = \frac{3}{2} q_0 \Rightarrow q_0 = 16 \text{ kN}$$

$$q(x) = \frac{16x}{3}$$

Now, do a free body diagram:



$$\Sigma F_y = 0 : R_y^A + R_y^B = \int_0^3 q(x) dx$$

$$R_y^A + R_y^B = \int_0^3 \frac{16x}{3} dx = \frac{8}{3} x^2 \Big|_0^3 = 24 \text{ kN}$$

$$\Sigma M = 0 : 3 \cdot R_y^B - \int_0^3 q(x) \cdot x dx = 0$$

$$3 \cdot R_y^B - \int_0^3 \frac{16x^2}{3} dx = 0$$

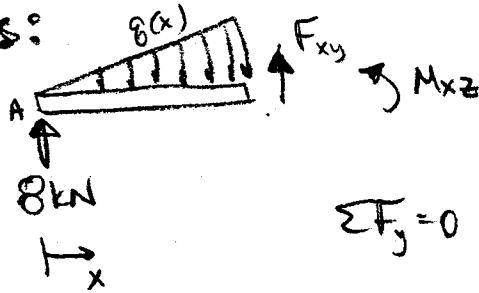
$$3 \cdot R_y^B = \frac{16}{9} x^3 \Big|_0^3 = 48 \Rightarrow R_y^B = 16 \text{ kN}$$

From $24 = R_y^A + R_y^B \rightarrow R_y^A = 8 \text{ kN}$

7

Problem 4 (cont'd)

Determine Shear force : Bending Moment Expressions:



$$\Sigma F_y = 0: F_{xy} - \int_0^x g(x') dx' + 8 = 0$$

$$F_{xy} = 8 - \int_0^x \frac{16x'}{3} dx' = \boxed{8 - \frac{8}{3}x^2}$$

$$\Sigma M = 0: F_{xy} \cdot x + M_{xz} - \int_0^x g(x') \cdot x' dx' = 0$$

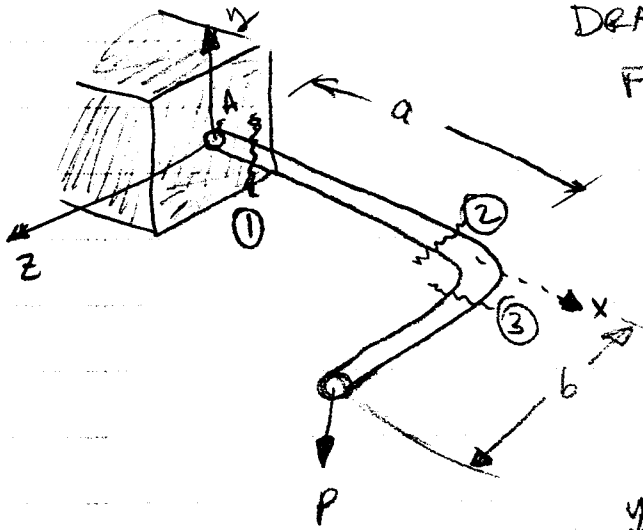
$$(8 - \frac{8}{3}x^2)x + M_{xz} - \int_0^x \frac{16(x')^2}{3} dx'$$

$$M_{xz} = \frac{16}{9}x^3 + \frac{8}{3}x^3 - 8x$$

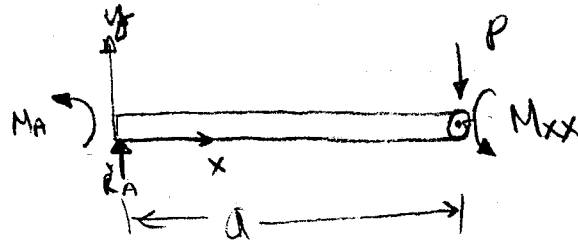
$$\boxed{M_{xz}(x) = \frac{40}{9}x^3 - 8x}$$

Problem 5: 3.13

DRAW SKETCHES SHOWING INTERNAL FORCES & MOMENTS ACTING AT SECTIONS 1, 2, & 3 :

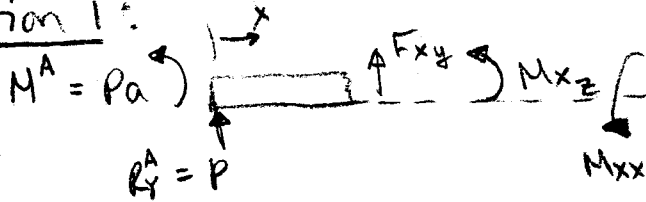


FBD of Systems:

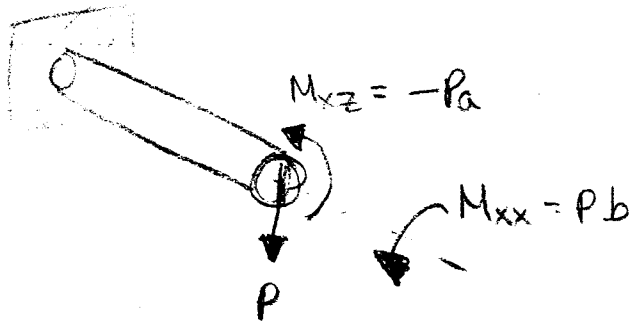


$$\left. \begin{aligned} \sum F_y = 0 & \quad R_y^A = P \\ \sum M = 0 & \quad M^A = Pa \end{aligned} \right\} \text{Reactions}$$

Section 1:

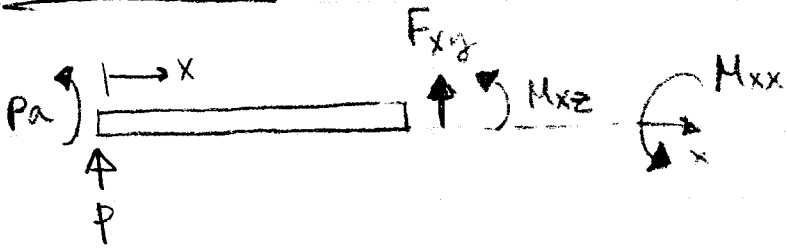


$$\begin{aligned} F_{xy} &= -P : \sum F_y \\ M_{xz} + F_{xy} \cdot x + Pa &= 0 \\ M_{xz} &= -Pa + Px \\ &= P(x-a) \\ x \sim 0 &\rightarrow = -Pa \end{aligned}$$



CDL 3.13 (cont'd)

Section 2

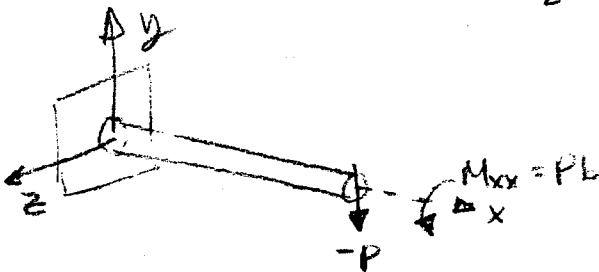


$$\sum F_y = 0 : P + F_{xy} = 0 \quad F_{xy} = -P$$

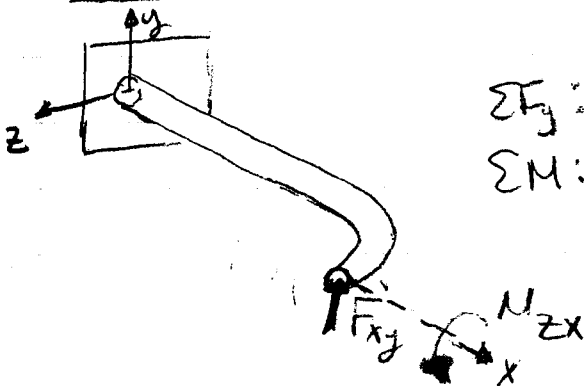
$$\sum M_z = 0 : Pa + F_{xy}x + M_{xz} = 0$$

$$M_{xz} = P(x-a)$$

$$x \rightarrow a \Rightarrow M_{xz} = 0$$



Section 3

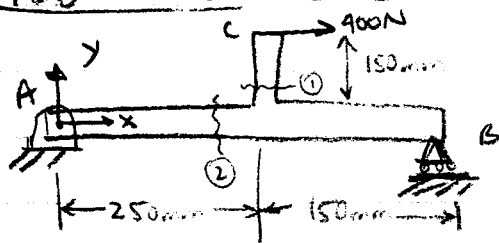


$$\sum F_y : F_{xy} = -P$$

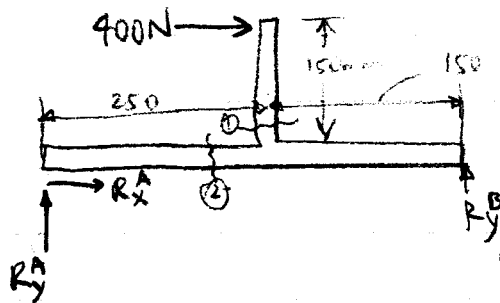
$$\sum M : -M_{xz} + Pb = 0$$

$$\underline{M_{xz} = Pb}$$

Problem 6: CDL 3-14



Calculate Internal Forces & Moments @ Sections 1 & 2:



$$\sum F_x = 0: R_x^A + 400N = 0$$

$$R_x^A = -400N$$

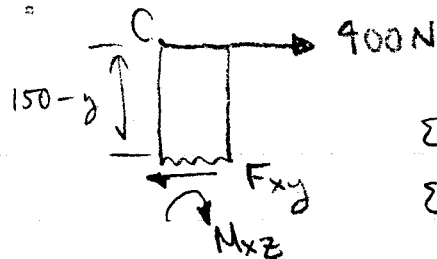
$$\sum F_y = 0: R_y^A + R_y^B = 0$$

$$\sum M^A = 0: (400)(150) - R_y^B(400) = 0$$

$$R_y^B = 150N$$

$$R_y^A = -150N$$

Section ①:



$$\sum F_x = 0: F_{xy} = 400N$$

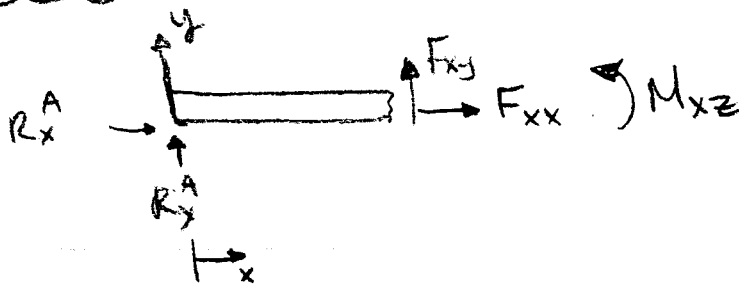
$$\sum M = 0: F_{xy}(150-y) + M_{xz} = 0$$

$$M_{xz} = -F_{xy}(150-y)$$

$$= -400(150-y)$$

$$y \sim 0 \Rightarrow \underline{M_{xz} = -60N \cdot m}$$

Section ②:



$$\sum F_x = 0: R_x^A + F_{xx} = 0 \Rightarrow F_{xx} = 400N$$

$$\sum F_y = 0: R_y^A + F_{xy} = 0 \Rightarrow F_{xy} = 150N$$

$$\sum M^A = 0: F_{xy} \cdot x + M_{xz} = 0 \Rightarrow M_{xz} = -150x$$

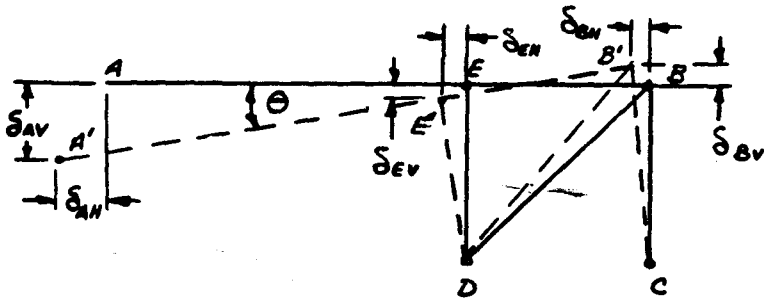
$$x \sim 250mm \Rightarrow \underline{M_{xz} = 37.5Nm}$$

EXTRA CREDIT

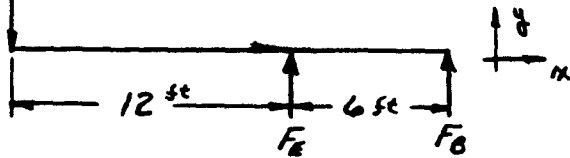
2-6

(11)

GEOMETRY OF DEFORMATION



5000 lb



$$\sum F_y = 0$$

$$F_E + F_B - 5000 = 0$$

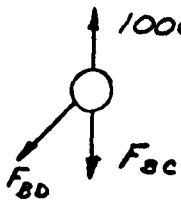
$$\sum M_E = 0$$

$$(5 \times 10^3)(12 \text{ ft}) + F_B(6 \text{ ft}) = 0$$

$$F_B = -10000 \text{ lb}$$

$$F_E = 15000 \text{ lb}$$

FOR THE PIN B:



$$\sum F_x = 0$$

$$F_{BD} = 0$$

$$\sum F_y = 0$$

$$F_{BC} = 10000 \text{ lb TENSION}$$

BY A SIMILAR ANALYSIS $F_{DE} = 15000 \text{ COMP.}$

ROD BD DOES NOT DEFORM. IT ONLY ROTATES ABOUT D. THUS $\delta_{BH} = \delta_{BV}$ (FROM GEOMETRY)

$$\delta_{BV} = \left(\frac{FL}{AE} \right)_{BC} = \frac{(10^4 \text{ lb})(6 \text{ ft})(12 \frac{\text{in}}{\text{ft}})}{(1 \text{ in}^2)(30 \times 10^6 \frac{\text{lb}}{\text{in}^2})} = .024 \text{ in}$$

$$\delta_{EV} = \left(\frac{FL}{AE} \right)_{ED} = \frac{(1.5 \times 10^4 \text{ lb})(6 \text{ ft})(12 \frac{\text{in}}{\text{ft}})}{(2 \text{ in}^2)(30 \times 10^6 \frac{\text{lb}}{\text{in}^2})} = .018 \text{ in}$$

FOR E'B' TO EQUAL EB, $\delta_{EH} \approx \delta_{BH}$ BUT $\delta_{BH} = \delta_{BV} = .024 \text{ in}$
 $\delta_{EH} \approx .024 \text{ in}$

SIMILARLY $\delta_{AH} = .024 \text{ in}$

$$\theta \approx \frac{\delta_{BV} + \delta_{EV}}{72 \text{ in}} = \frac{.042}{72} \text{ RAD}$$

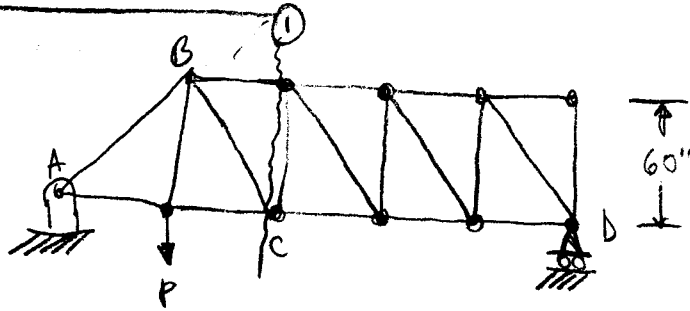
$$\delta_{AV} = -\delta_{BV} + \theta \times (18 \text{ ft}) \left(12 \frac{\text{in}}{\text{ft}} \right) = .126 \text{ in} - .024 \text{ in}$$

$$= .102 \text{ in}$$

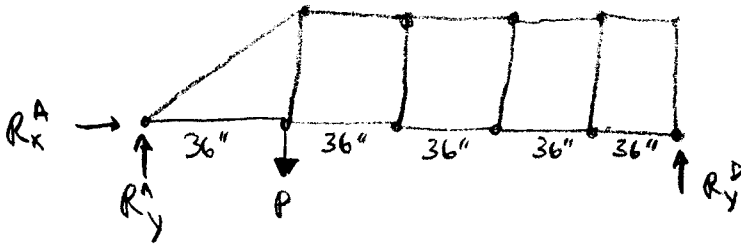
$$\delta_{AH} = .024 \text{ in}$$

EXTRA CREDIT

2.9



Determine Reactions from FBD:



$$\sum F_y = 0: R_y^A - P + R_y^D = 0$$

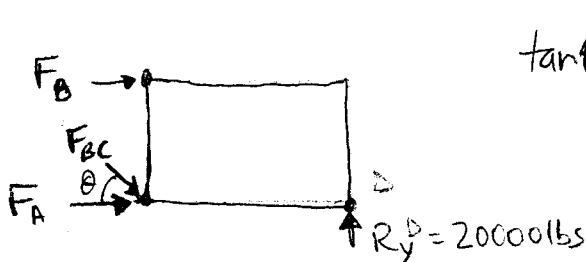
$$R_y^A + R_y^D = P = 100,000 \text{ lb}$$

$$\sum M^A = 0: -36P + R_y^D \cdot 180 = 0$$

$$R_y^D = \frac{P}{5} = \underline{20,000 \text{ lb}}$$

$$\underline{R_y^A = 80,000 \text{ lb}}$$

Consider the section to the Right of Cut ①:
(TREAT IT AS A BEAM)



$$\tan \theta = \frac{5}{3} \quad \theta \approx 59^\circ$$

$$\sum F_y = 0:$$

$$-F_{BC} \sin \theta + 20,000 \text{ lbs} = 0$$

$$F_{BC} = \frac{20,000}{\sin(59)} = 23,324 \text{ lbs}$$