

THE PLASTIC BENDING
OF CURVED BARS

by

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12 September 1947

Professor Joseph S. Newell
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Dear Professor Newell:

I hereby submit this thesis entitled, "THE PLASTIC BENDING OF CURVED BARS," in partial fulfillment of the requirements for the degree of Master of Science in Mechanical Engineering from the Massachusetts Institute of Technology.

Respectfully submitted,

Charles O. Smith

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N O M E N C L A T U R E

- a - a constant, see Case I
- A - cross-sectional area of bar, square inches
- b - width of bar, inches
- c - a constant, see Case I
- C_1, C_2 - constants of integration
- E - modulus of elasticity, pounds per square inch
- h - depth of bar, inches
- I - moment of inertia of cross-section, (inches)⁴
- k - a constant, used for integrating, Cases II and III
- M - bending moment at any point, inch pounds, considered positive when decreasing the curvature of the bar
- M_c - bending moment for complete yielding, inch pounds
- M_i - bending moment for initial yielding, inch pounds
- M_s - bending moment for secondary yielding, inch pounds
- P - applied load, pounds
- R_i - inner radius of curved bar, inches
- R_o - outer radius of curved bar, inches
- S - stress at any point, pounds per square inch
- S_o - yield stress, pounds per square inch
- w - deflection, inches

Nomenclature

- y - distance of a point from the neutral axis,
inches, measured positive upward
- y_1 - distance from neutral axis to bottom of bar,
inches
- y_2 - distance from neutral axis to top of bar,
inches
- y^{\perp} - distance from neutral axis to edge of plastic
region, measured downward, inches
- y'' - distance from neutral axis to edge of plastic
region, measured upward, inches
- \bar{y} - vertical distance between neutral axis and
horizontal axis through the centroid, inches
- z - width of bar at any point, inches
- ϵ - unit strain at any point, inches per inch
- ϵ_1 - unit strain on bottom of bar, inches per inch
- ϵ_2 - unit strain on top of bar, inches per inch
- ϵ_0 - unit strain at yield stress, inches per inch
- e - radius of curvature at any point, inches
- e_0 - initial radius of curvature, inches
- θ - angle of position, measured from fixed end,
degrees or radians
- θ_1 - angle to which plastic region extends on
bottom of bar - degrees or radians
- θ_2 - same to top of bar

Nomenclature

Numbers in parentheses refer to bibliography.

A S S U M P T I O N S

1. Transverse cross-sections of the bar originally plane and normal to the center line of the bar remain so after bending.
2. The material of which the bar is composed is homogeneous and isotropic.

I N T R O D U C T I O N

The general field of the plastic behavior of materials is of great importance since many common fabricating processes are entirely dependent upon the plastic properties of materials. The bending of curved bars, in the plastic as well as in the elastic range, is of great importance since many such elements are used in structural engineering and electrical machinery, while others serve as essential machine parts. Consequently, it is desired to know of the behavior of such elements and to be able to predict the stress conditions and the deflection of such curved bars under various loading conditions.

P U R P O S E

It is the purpose of this thesis to develop analytical expressions for stress distribution and for deflection of a curved bar, which is built in at one end, of a length sufficient to form an arc of 90° , and loaded by a single load at the free end, this load being applied in the plane of curvature. (See Figure 1 for the geometry of the curved bar.)

PREVIOUS CONTRIBUTIONS TO THE SUBJECT

Several contributions have been made to knowledge of the general field of plastic behavior of materials by various individuals. A great deal of the work of formulating the laws of plastic behavior has been done by NADAI (2, 5, 6, 7).

Murphy and Timoshenko (4, 11) have written textbooks on the advanced theory of the mechanics of materials. Both of these texts contain expressions for stress distribution and deflection of a curved bar loaded in the plane of curvature, but these expressions apply only within the elastic range and for a stress-strain curve in which stress is directly proportional to strain. WINSLOW and EDMONDS (12) did considerable work on comparison of experimental results with theoretical predictions but, again, this work was only within the elastic range. HOGAN (3) developed expressions for design purposes for stress distribution, deflection angle of slope, and angle of twist in circular cantilever beams loaded normal to the plane of curvature under various load conditions; but these expressions also hold only for the elastic region.

NADAI (7) has developed expressions for determining the extent of the plastic region, the stress distribution, and deflection of a bar subjected to plastic bending using an idealized stress-strain curve and a curve accounting for the effect of work hardening (somewhat idealized), but these expressions apply only to a straight beam, not to an

PREVIOUS CONTRIBUTIONS TO THE SUBJECT

initially curved bar.

So far as the author could determine, there have been no publications of work on the plastic bending of a curved bar.

P R O C E D U R E

Three separate cases were considered. The case of a bar with rectangular cross-section and an idealized stress-strain curve, the case of a bar with rectangular cross-section and an arbitrary stress-strain curve of the form $S = S_0 \left(\frac{\epsilon}{\epsilon_0} \right)^{\frac{1}{2}}$, and the case of the bar with triangular cross-section and an arbitrary stress-strain curve of the form $S = S_0 \left(\frac{\epsilon}{\epsilon_0} \right)^{\frac{1}{2}}$; these being hereafter referred to as Case I, Case II, and Case III, respectively.

The first consideration was to determine a general method and then apply it to each of these cases separately. This is necessary since both the cross-section of the bar and the stress-strain curve will affect the results obtained. In fact, the results and their form are entirely dependent on these two factors.

The method developed is simple in idea but very likely to be unwieldy in execution. The method followed is:

(1) The use of the equilibrium condition, $\int S dA = 0$, to determine the position of the neutral axis.

(2) The use of the equilibrium condition, $M = \int S y dA$, to determine the bending moment in terms of the geometry of the cross-section and the stress-strain curve.

(3) The combination of the bending moment expression just derived and the stress-strain expression to obtain an expression for stress distribution in terms of the bending moment and the geometry of the cross-section.

PROCEDURE

(4) The determination of the expression, $\frac{c_0 - l}{e}$, from the bending moment expression derived in Step 2, and the substitution of this term in the differential equation

$$\frac{d^2 w}{d\theta^2} + w = c_0 \left(\frac{c_0 - l}{e} \right) \quad (10)$$

This will give expressions for the stress distribution and deflection in general terms of M for the particular cross-section and stress-strain curve being considered. These expressions must then be used to determine the stress distribution equation and the deflection equation for the geometry of the bar and the particular type of loading.

For the geometry and the loading considered in this work, the steps to be followed are:

(5) The substitution of $-P c_0 \cos\theta$ for M in the stress distribution relation derived in Step 3.

(6) The substitution of $-P c_0 \cos\theta$ for M in the differential equation derived in Step 4, and the solution of the differential equation for the deflection in terms of P and $\cos\theta$.

For each of the three cases, the extent of the plastic region, the stress distribution on the plane of maximum stress, and the deflection curve was determined for five different loads, varying from that required for initial yielding to that required for complete yielding (Case I) or for extensive yielding (Cases I and II). The maximum deflection versus load relation was determined for each of the three cases.

S U M M A R Y A N D D I S C U S S I O N

Case I

For the geometry of the curved bar and the type of loading considered (Figure 1), the stress distribution is given by:

For the completely elastic beam,

$$S = \frac{M}{A \bar{y}} \left(\frac{y}{e_0 + y} \right)$$

For the partially plastic-partially elastic beam,

$$S = -S_0 \left(\frac{e_0 - y'}{y'} \right) \left(\frac{y}{e_0 + y} \right) \quad \text{for } y' < y < y'' \quad (\text{elastic portion})$$

$$S = -S_0 \quad \text{for } y'' < y < y_2$$

$$S = S_0 \quad \text{for } y' < y < y_1$$

$$M = \frac{S_0 b e_0 y_1^2}{3(e_0 - 2y_1)} - \frac{S_0 b h^2}{4} = -P e_0 \cos \theta$$

It is possible to combine the expression for stress distribution and bending moment to eliminate y' and obtain a new expression for stress distribution in the elastic portion. This expression is:

$$S = -S_0 \left(\sqrt{1 + \frac{4e_0^2/3h^2}{1 - \frac{4Pe_0 \cos \theta}{S_0 b h^2}}} \right) \left(\frac{y}{e_0 + y} \right)$$

For the geometry of the curved bar and the type of loading considered (Figure 1), the deflection equation is:

Summary and Discussion - Case I

For the completely elastic beam,

$$w = \frac{-P e_0^3 \theta \sin \theta}{2EI}$$

For the partially plastic-partially elastic beam,
for the partially plastic portion

$$\frac{d^2 w}{d\theta^2} + w = -e_0 \epsilon_0 \sqrt{1 + \frac{4 e_0^2 / 3h^2}{1 - \frac{4 P e_0 \cos \theta}{5_0 b h^2}}}$$

for the completely elastic portion

$$w' = C_1 \sin \theta + C_2 \cos \theta - \frac{P e_0^3 \theta \sin \theta}{2EI}$$

Several attempts were made to find an analytical solution to the differential equation given above. Unfortunately all attempts met with no success. A solution may be made by numerical integration by the method of successive approximations (1, 8, 9). This was done making use of the boundary conditions that

$$\theta = 0, \quad w = 0, \quad \frac{dw}{d\theta} = 0$$

At the point where the partially plastic-partially elastic and the completely elastic portions of the beam meet, the constants of integration, C_1 and C_2 , may be evaluated from the boundary conditions that

$$w = w', \quad \frac{dw}{d\theta} = \frac{dw'}{d\theta}$$

Summary and Discussion - Case I

A question might well be raised as to the validity of the expressions derived for this case since the position of the neutral axis does not remain fixed but shifts from its position at initial yielding to coincide with the horizontal axis through the centroid at complete yielding. In this particular case, with the depth of the beam small in comparison with the radius of curvature, this neutral axis shift is very small and therefore its effect is negligible. For example, in the numerical case for which results were calculated, this neutral axis shift was 0.002" in an original radius of curvature of 10.248".

Case II

For the geometry of the curved bar and the type of loading considered (Figure 1), the stress distribution is given by:

$$S = \frac{P e_o \cos \theta \left(\frac{\pm y}{e_o + y} \right)^{\frac{1}{2}}}{b \left[\frac{3e_o^2}{4} \left(\sin^{-1} \sqrt{\frac{y_1}{e_o}} + \sinh^{-1} \sqrt{\frac{y_2}{e_o}} \right) + \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{R_o} - \sqrt{y_1^3} \sqrt{R_i} \right) - \frac{3e_o}{4} \left(\sqrt{y_2} \sqrt{R_o} + \sqrt{y_1} \sqrt{R_i} \right) \right]}$$

For the geometry of the curved bar and the type of loading considered (Figure 1), the deflection equation is:

Summary and Discussion - Case II

$$W = \frac{P^2 e_0^3 \epsilon_0 \left(\frac{2 \cos \theta}{3} + \frac{\cos 2\theta}{3} - 1 \right)}{4 S_0^2 b^3 \left[\frac{3 e_0^2}{4} \left(\sin^{-1} \sqrt{\frac{y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) + \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_i} \right) - \frac{3 e_0}{4} \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right]^2}$$

These expressions for stress distribution and deflection apply to both the completely elastic and the partially plastic-partially elastic cases. The reason for this is that the stress-strain curve applies to both the elastic and plastic regions.

Case III

For the geometry of the curved bar and the type of loading considered (Figure 1), the stress distribution is given by:

$$S = \frac{\mp P e_0 \cos \theta h \left(\frac{\pm y}{e_0 + y} \right)^{\frac{1}{2}}}{b \left[\left(\frac{3 e_0^2 y_2}{4} + \frac{5 e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) - \frac{1}{3} \left(\sqrt{y_2^5} \sqrt{R_0} + \sqrt{y_1^5} \sqrt{R_i} \right) + \left(\frac{y_2}{2} + \frac{5 e_0}{12} \right) \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_i} \right) - \left(\frac{3 e_0 y_2}{4} + \frac{5 e_0^2}{8} \right) \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right]}$$

Summary and Discussion - Case III

For the geometry of the curved bar and the type of loading considered (Figure 1), the deflection equation is:

$$\begin{aligned}
 W = & \frac{P^2 e_0^3 h^2 \epsilon_0 \left(\frac{2 \cos \theta}{3} + \frac{\cos 2\theta}{3} - 1 \right)}{4 S_0^2 b^2 \left[\left(\frac{3 e_0^2 y_2^2}{4} + \frac{5 e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{y_2}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) \right.} \\
 & + \left(\frac{y_2}{2} + \frac{5 e_0}{12} \right) \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_i} \right) - \frac{1}{3} \left(\sqrt{y_2^5} \sqrt{R_0} + \sqrt{y_1^5} \sqrt{R_i} \right) \\
 & \left. - \left(\frac{3 e_0 y_2^2}{4} + \frac{5 e_0^2}{8} \right) \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right]^2
 \end{aligned}$$

These expressions for stress distribution and deflection apply to both the completely elastic and the partially plastic-partially elastic cases. The reason for this is that the stress-strain curve applies to both the elastic and plastic regions.

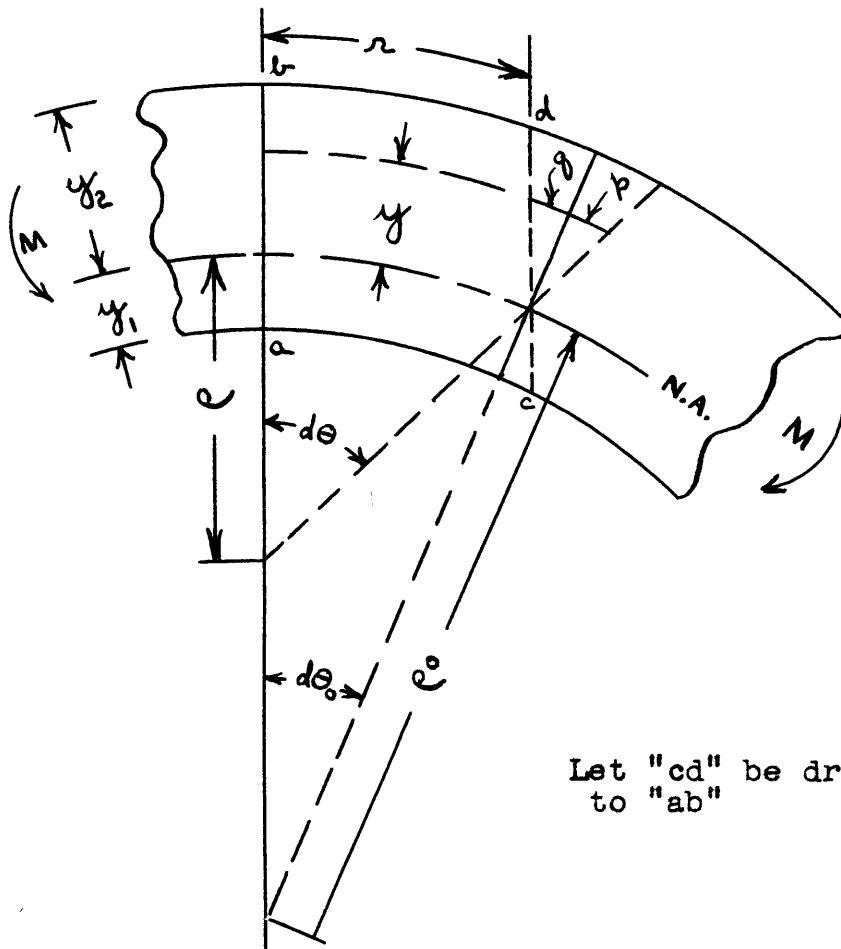
SUGGESTIONS FOR FUTURE INVESTIGATION

Since this thesis covers only a very narrow range of possibilities, future investigation could well be done in this field by using different cross-sections (circular, trapezoidal), various other stress-strain relations, other boundary conditions (arcs greater or smaller than 90° , bars built in at both ends, bars simply supported), and other conditions of loading (constant moment, uniformly distributed load, uniformly varying load, more than one concentrated load, loading normal to the plane of curvature).

An investigation which should prove interesting would be to determine the analytical expression for stress as a function of strain for a particular material, derive the stress distribution and deflection equations as was done in this thesis, and compare the predicted results with those obtained experimentally for a curved bar of the same material having the same boundary and loading conditions. This could be done with a number of materials and for a variety of combinations of cross-sections, boundary conditions and loading conditions.

GENERAL PRELIMINARY
INVESTIGATION

Consider the general case
of a curved bar in bending
(elastic or plastic)



Let "cd" be drawn parallel to "ab"

From the similarity of triangles,

$$\frac{g}{r} = \frac{y}{e_0} \quad \text{AND} \quad \frac{p+g}{r} = \frac{y}{e}$$

$$\frac{p}{r} + \frac{g}{r} = \frac{y}{e}$$

$$\frac{p}{r} = \frac{y}{e} - \frac{g}{r} = \frac{y}{e} - \frac{y}{e_0} = y \left(\frac{1}{e} - \frac{1}{e_0} \right)$$

$$\frac{p+r}{r} = \frac{y}{e_0} + 1 = y \left(\frac{1}{e_0} + \frac{1}{y} \right)$$

$$\varepsilon = \frac{p}{f+r} = \frac{\frac{p}{r}}{\frac{f+r}{r}} = \frac{y \left(\frac{1}{e} - \frac{1}{e_0} \right)}{y \left(\frac{1}{e_0} + \frac{1}{y} \right)}$$

$$\varepsilon = \frac{\frac{1}{e} - \frac{1}{e_0}}{\frac{1}{e_0} + \frac{1}{y}}$$

$$\varepsilon = \left(\frac{e_0 - e}{e} \right) \left(\frac{y}{e_0 + y} \right) \quad \text{EQUATION 1}$$

It should be noted that for $e_0 = \infty$, $\varepsilon = \frac{y}{e}$, which is the case of a straight beam.

From Eq. 1

$$\frac{1}{e_0} + \frac{1}{y} = \frac{\frac{1}{e} - \frac{1}{e_0}}{\varepsilon}$$

$$\frac{1}{y} = \frac{\frac{1}{e} - \frac{1}{e_0}}{\varepsilon} - \frac{1}{e_0}$$

$$\frac{1}{y} = \frac{e_0 - e}{e e_0 \varepsilon} - \frac{1}{e_0}$$

$$\frac{1}{y} = \frac{e_0 - e - e \varepsilon}{e e_0 \varepsilon}$$

$$y = \frac{e e_0 \varepsilon}{e_0 - e(1 + \varepsilon)}$$

EQUATION 2

$$dy = \frac{e e_0 (e_0 - e)}{[e_0 - e(1 + \epsilon)]^2} d\epsilon$$

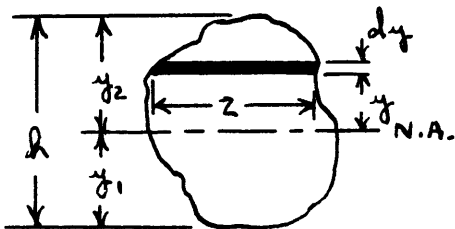
$$y_1 = \frac{e e_0 \epsilon_1}{e_0 - e(1 - \epsilon_1)} \quad \text{EQUATION 3}$$

$$y_2 = \frac{e e_0 \epsilon_2}{e_0 - e(1 + \epsilon_2)} \quad \text{EQUATION 4}$$

Where $-\epsilon_1$ & ϵ_2 are the unit strains at $-y_1$ & y_2 respectively.

$$y_1 + y_2 = h \quad \text{EQUATION 5}$$

Consider the cross-section



$$z = f(y)$$

$$dA = z dy$$

$$dA = f(y) dy$$

$$\text{LET } S = f_2(\epsilon)$$

For equilibrium $\int S dA = 0$ over the cross-section of the beam.

$$\int S dA = 0$$

$$\int_{-y_1}^{y_2} f_2(\epsilon) f(y) dy = 0$$

BUT FROM EQ. 2

$$y = \frac{e e_0 \epsilon}{e_0 - e(1+\epsilon)} \quad \therefore f(y) = f_1(\epsilon, e)$$

$$\int S dA = \int_{-\epsilon_1}^{\epsilon_2} f_2(\epsilon) f_1(\epsilon, e) \frac{e e_0 (e_0 - e)}{[e_0 - e(1+\epsilon)]^2} d\epsilon = 0 \quad \text{EQUATION 6}$$

$$M = \int S y dA$$

$$M = \int_{-y_1}^{y_2} f_2(\epsilon) y f(y) dy$$

$$M = \int_{-\epsilon_1}^{\epsilon_2} f_2(\epsilon) \frac{e e_0 \epsilon}{[e_0 - e(1+\epsilon)]} f_1(\epsilon, e) \frac{e e_0 (e_0 - e)}{[e_0 - e(1+\epsilon)]^2} d\epsilon$$

$$M = \int_{-\epsilon_1}^{\epsilon_2} e^2 e_0^2 (e_0 - e) \frac{f_2(\epsilon) f_1(\epsilon, e) \epsilon}{[e_0 - e(1+\epsilon)]^3} d\epsilon \quad \text{EQUATION 7}$$

BUT $M = f(\theta)$

$$\int_{-\epsilon_1}^{\epsilon_2} e^2 e_0^2 (e_0 - e) \frac{f_2(\epsilon) f_1(\epsilon, e) \epsilon}{[e_0 - e(1+\epsilon)]^3} d\epsilon = f(\theta) \quad \text{EQUATION 8}$$

There are six variables:

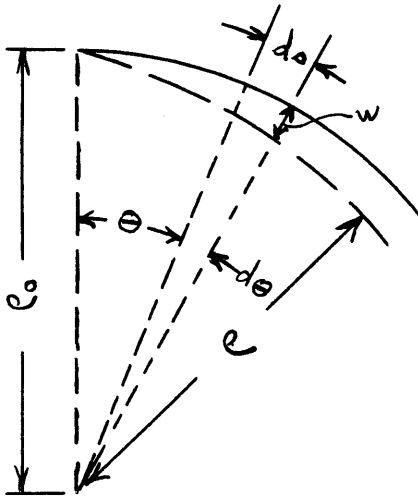
$$y_1, y_2, \epsilon_1, \epsilon_2, e, \theta$$

There are five equations:

$$3, 4, 5, 6, 8$$

Therefore, $e = f_2(\theta)$ can be found. EQUATION 9

Deflection Equation



It has been shown (10) that the solution of the following differential equation will yield the deflection equation.

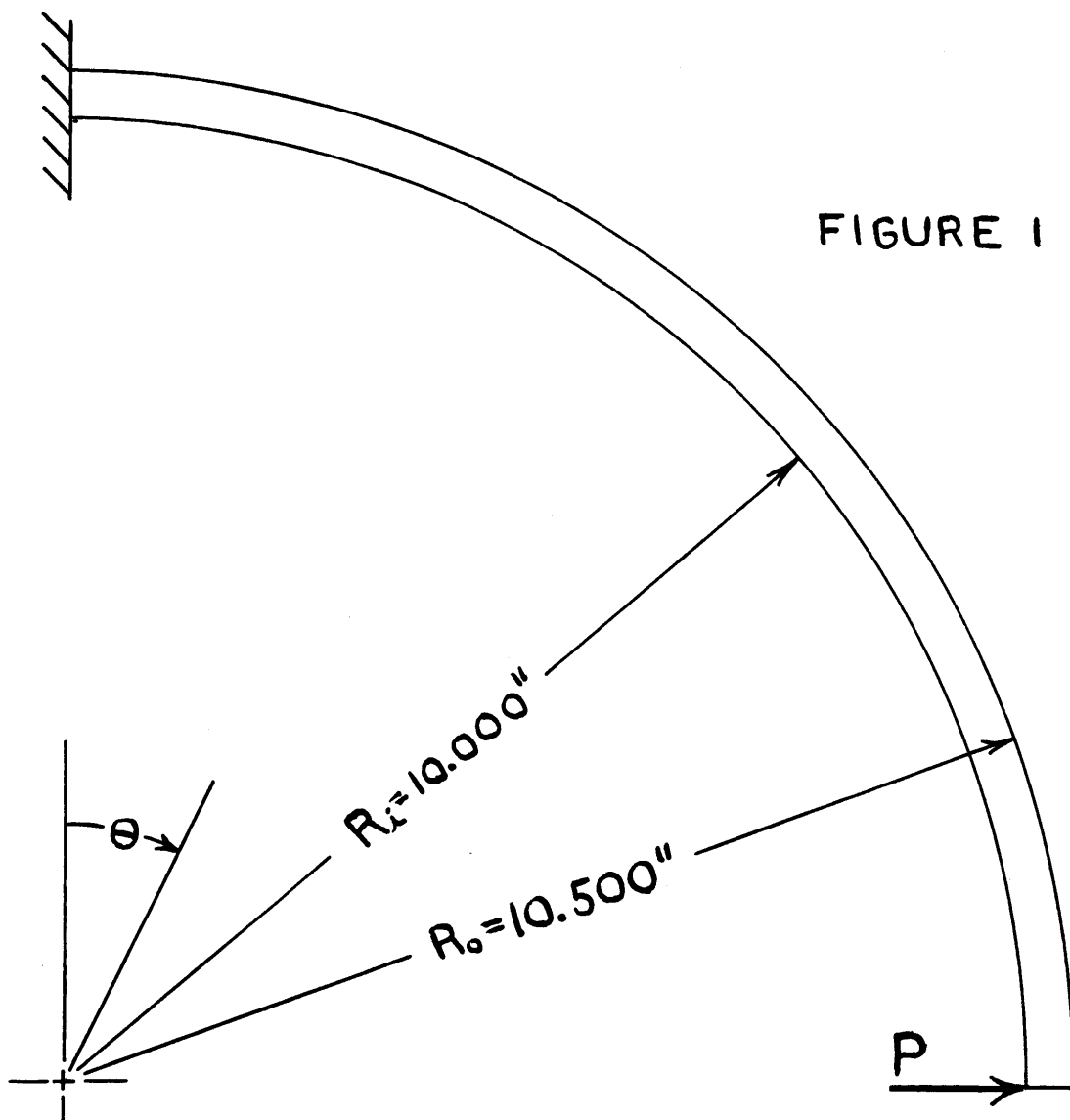
$$\frac{d^2 w}{ds^2} + \frac{w}{e_0^2} = \frac{1}{e} - \frac{1}{e_0}$$

$$ds = e_0 d\theta$$

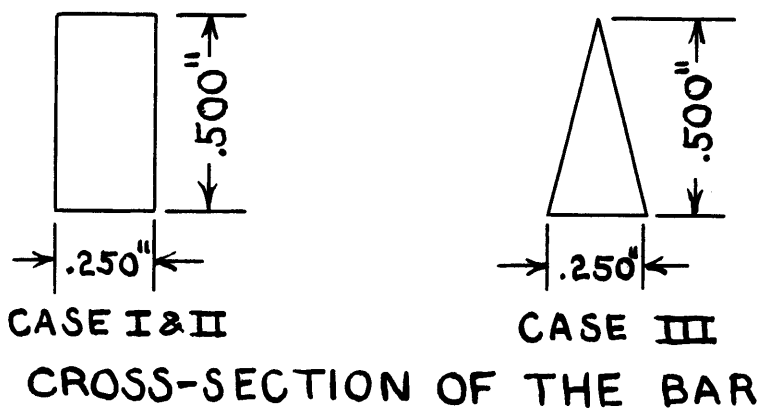
$$ds^2 = e_0^2 d\theta^2$$

$$\frac{d^2 w}{d\theta^2} + w = e_0^2 \left(\frac{1}{e} - \frac{1}{e_0} \right) = e_0 \left(\frac{e_0 - e}{e} \right) \quad \text{EQUATION 10}$$

Substituting Equation 9 in Equation 10, and solving for $w = f_3(\theta)$ will yield deflection equation of the bar.

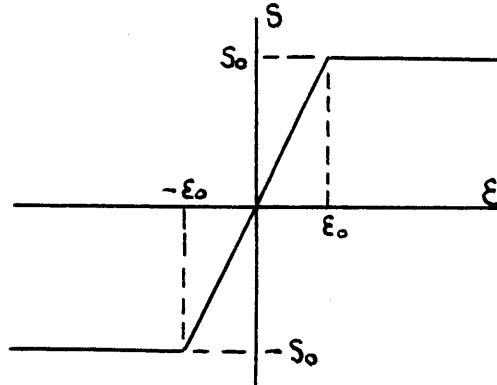


GEOMETRY OF THE CURVED BAR



Case I

Consider a curved bar of rectangular cross-section
with depth of beam small
in comparison with the radius of curvature
and an idealized stress-strain curve such as



For the Completely Elastic Condition (4)

$$e_0 = \frac{h}{\ln \frac{R_o}{R_i}} \quad \text{EQUATION 11}$$

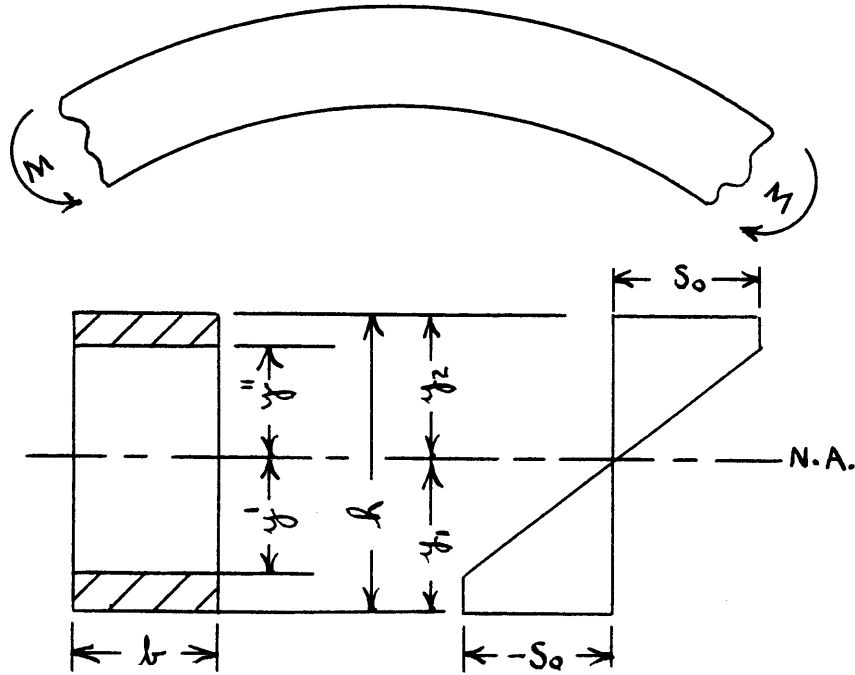
$$S = \frac{M}{A \bar{y}} \left(\frac{y}{e_0 + y} \right) \quad \text{EQUATION 12}$$

$$\frac{1}{e} - \frac{1}{e_0} = \frac{M}{EI}$$

$$\frac{d^2 w}{d\theta^2} + w = e_0^2 \frac{M}{EI} \quad \text{EQUATION 13}$$

If the idealized stress-strain curve is assumed, it is obvious that beyond the yield point the neutral axis will shift toward the centroid of the cross-section until at the point of complete yielding, the neutral axis will coincide with the horizontal axis passing through the centroid.

Partial Plastic Yielding



Considering the elastic stress equation (Equation 12) assume $S = \frac{ay}{c+y}$ in the elastic portion of the bar, in which "a" and "c" are constants for the particular section.

For the plastic portion, $S = \pm S_0$

$$S_0 = \frac{ay''}{c+y''} \quad -S_0 = \frac{a(-y')}{c-y'}$$

DIVIDING

$$-\frac{S_0}{S_0} = \frac{\frac{ay''}{c+y''}}{\frac{-ay'}{c-y'}} = \frac{y''(c-y')}{y'(c+y'')}$$

$$y'(c+y'') = y''(c-y')$$

$$cy' + y'y'' = cy'' - y'y''$$

$$cy' - cy'' = -2y'y''$$

$$c(y' - y'') = -2y'y''$$

$$c = \frac{-2y'y''}{y' - y''} = \frac{2y'y''}{y'' - y'}$$

$$c + y'' = \frac{2y'y''}{y'' - y'} + y'' = \frac{y''(y'' + y')}{y'' - y'}$$

$$\frac{y''}{c + y''} = \frac{y'' - y'}{y'' + y'}$$

$$S_0 = \frac{ay''}{c + y''} = a \left(\frac{y'' - y'}{y'' + y'} \right)$$

$$a = S_0 \left(\frac{y'' + y'}{y'' - y'} \right)$$

$$\varepsilon = \left(\frac{e_0 - e}{e} \right) \left(\frac{y''}{e_0 + y''} \right)$$

$$\varepsilon_0 = \left(\frac{e_0 - e}{e} \right) \left(\frac{y''}{e_0 + y''} \right)$$

$$-\varepsilon_0 = \left(\frac{e_0 - e}{e} \right) \left(\frac{-y'}{e_0 - y'} \right)$$

DIVIDING

$$-\frac{\varepsilon_0}{\varepsilon_0} = \frac{\left(\frac{e_0 - e}{e} \right) \left(\frac{y''}{e_0 + y''} \right)}{\left(\frac{e_0 - e}{e} \right) \left(\frac{-y'}{e_0 - y'} \right)} = - \left(\frac{y'}{e_0 - y'} \right) \left(\frac{e_0 + y''}{y''} \right)$$

$$\frac{h_2 - c_2}{2h_2} = h - \frac{h_2 - c_2}{h_2} = h - h$$

$$\frac{h_2 - c_2}{(h - c_2)h_2} = h + \frac{h_2 - c_2}{h_2} = h + h$$

$$\frac{h_2 + c_2}{2h_2} = h$$

$$2h_2 = (c_2 + h_2)h$$

$$2h_2 = h_2h + c_2h$$

$$\frac{h_2 - c_2}{2h_2} = h$$

$$h_2 - c_2 = (2h_2 - c_2)h$$

$$h_2 - c_2 = c_2h - h_2h$$

$$c_2 = 0$$

$$\frac{h - h}{2h_2} = 0 \quad \text{But}$$

$$\frac{h - h}{2h_2} = c_2$$

$$c_2(h - h) = (h - h)h_2$$

$$c_2h - h_2c_2 = h_2h - h_2h$$

$$h_2(c_2 - h) = (h - h_2)h$$

$$a = S_0 \left(\frac{y'' + y'}{y'' - y'} \right)$$

$$a = S_0 \left(\frac{\frac{2y'(e_0 - y')}{e_0 - 2y'}}{\frac{2y'^2}{e_0 - 2y'}} \right)$$

$$a = \frac{S_0 (e_0 - y')}{y'} = \frac{S_0 (e_0 + y'')}{y''}$$

$$S = S_0 \left(\frac{e_0 - y'}{y'} \right) \left(\frac{y}{e_0 + y} \right) \quad \text{EQUATION 14}$$

$$\int S dA = 0$$

$$\int_{-y_1}^{-y_2} S_0 b dy + \int_{-y_1}^{y''} \frac{a y}{c+y} b dy + \int_{y''}^{y_2} S_0 b dy = 0$$

$$-y_0 b \left[-y \right]_{-y_1}^{-y_2} + a b \left[c+y - c \ln c+y \right]_{-y_1}^{y''} + S_0 b y \left[y \right]_{y''}^{y_2} = 0$$

$$-S_0 (-y_2 + y_1) + a \left[c+y'' - c+y_1 - c \ln \frac{c+y''}{c-y_1} \right] + S_0 (y_2 - y'') = 0$$

$$a \left[y'' + y_1 - c \ln \frac{c+y''}{c-y_1} \right] = S_0 [y_1 - y_2 - (y_2 - y'')]]$$

$$c - y_1 = \frac{y_1 (y'' + y_1)}{y'' - y_1}$$

$$c + y'' = \frac{y'' (y'' + y_1)}{y'' - y_1}$$

OR

$$\frac{c+y''}{c-y_1} = \frac{y''}{y_1} = \frac{e_0 y_1}{e_0 - 2y_1} = \frac{e_0}{e_0 - 2y_1}$$

$$a \left[y'' + y_1 - c \ln \frac{e_0}{e_0 - 2y_1} \right] = S_0 [y_1 - y_2 - y_1 + y'']]$$

$$y_2 = h - y_1$$

$$y'' = \frac{e_0 y_1}{e_0 - 2y_1}$$

$$c = e_0$$

$$a = S_0 \left(\frac{e_0 - y_1}{y_1} \right)$$

$$S_o \left(\frac{e_o - y_1'}{y_1'} \right) \left[y_1' + \frac{e_o y_1'}{e_o - 2y_1'} - e_o \ln \frac{e_o}{e_o - 2y_1'} \right] = S_o \left[y_1' - (h - y_1') - y_1' + \frac{e_o y_1'}{e_o - 2y_1'} \right]$$

$$\left(\frac{e_o - y_1'}{y_1'} \right) \left[\frac{y_1' (e_o - 2y_1') + e_o y_1'}{e_o - 2y_1'} - e_o \ln \frac{e_o}{e_o - 2y_1'} \right] = 2y_1' - h + \frac{(y_1') (e_o - 2y_1') + e_o y_1'}{e_o - 2y_1'}$$

$$\frac{e_o (e_o - y_1')}{y_1'} \ln \frac{e_o}{e_o - 2y_1'} = h - 2y_1' - \frac{2y_1'^2}{e_o - 2y_1'} + \frac{2(e_o - y_1')^2}{e_o - 2y_1'}$$

$$\frac{e_o (e_o - y_1')}{y_1'} \ln \frac{e_o}{e_o - 2y_1'} = h - 2y_1' + 2e_o$$

$$h - 2y_1' = \frac{e_o (e_o - y_1')}{y_1'} \ln \frac{e_o}{e_o - 2y_1'} - 2e_o$$

$$y_1' = -\frac{1}{2} \left[\frac{e_o (e_o - y_1')}{y_1'} \ln \frac{e_o}{e_o - 2y_1'} - (2e_o + h) \right] \text{ EQUATION 15}$$

This expression is used to determine the position of the neutral axis. A trial and error solution is recommended since the expression is not readily solvable by algebraic means. Care should be taken to insure accuracy since the solution involves the small difference of two comparatively large numbers.

$$M = \int S_y dA$$

$$M = \int_{-y_1}^{-y_2} -S_0 b y dy + \int_{-y_1}^{-y_2} \frac{a y}{c+y} y b dy + \int_{y_1}^{y_2} S_0 y b dy$$

$$M = -S_0 b \int_{-y_1}^{-y_2} y dy + a b \int_{-y_1}^{-y_2} \frac{y^2 dy}{c+y} + S_0 b \int_{y_1}^{y_2} y dy$$

$$M = -\frac{S_0 b y^2}{2} \Big|_{-y_1}^{-y_2} + a b \left[\frac{1}{2} (c+y)^2 - 2c(c+y) + c^2 \ln(c+y) \right] \Big|_{-y_1}^{-y_2} + \frac{S_0 b y^2}{2} \Big|_{y_1}^{y_2}$$

$$M = a b \left[\frac{y_2^2 - y_1^2}{2} - c(y_2 + y_1) + c^2 \ln \frac{c+y_2}{c-y_1} \right] + \frac{S_0 b}{2} [y_2^2 + y_1^2 - (y_1^2 + y_2^2)]$$

$$a = \frac{S_0 (e_0 + y_2'')}{y_2''}$$

$$c = e_0$$

$$y_2 = h - y_1$$

$$\frac{c+y_2''}{c-y_1'} = \frac{e_0 + 2y_2''}{e_0}$$

$$M = \frac{S_0 (e_0 + y_2'')}{y_2''} b \left[\frac{y_2''^2 - y_1'^2}{2} - e_0 (y_2'' + y_1') + e_0^2 \ln \frac{e_0 + 2y_2''}{e_0} \right] + \frac{S_0 b}{2} [y_1'^2 + (h - y_1')^2 - (y_1'^2 + y_2''^2)]$$

$$M = \frac{S_0 b (e_0 + y_2'')}{2 y_2''} (y_2''^2 - y_1'^2) - S_0 b e_0 \left(\frac{e_0 + y_2''}{y_2''} (y_2'' + y_1') \right) + \frac{S_0 b h}{2} (h - 2y_1') + S_0 b e_0^2 \left(\frac{e_0 + y_2''}{y_2''} \right) \ln \frac{e_0 + 2y_2''}{e_0} + S_0 b y_1'^2 - \frac{S_0 b}{2} (y_1'^2 + y_2''^2)$$

$$\begin{aligned}
 M &= \frac{2 S_0 b y''^2 (e_0 + y'')^2}{(e_0 + 2y'')^2} - \frac{2 S_0 b e_0 (e_0 + y'')^2}{e_0 + 2y''} - \frac{S_0 b y''^4}{(e_0 + 2y'')^2} \\
 &+ S_0 b e_0^2 \left(\frac{e_0 + y''}{y''}\right) \ln \frac{e_0 + 2y''}{e_0} + \frac{S_0 b h e_0}{2} \left(\frac{e_0 + y''}{y''}\right) \ln \frac{e_0 + 2y''}{e_0} \\
 &- S_0 b h e_0 + \frac{S_0 b}{4} (2e_0 + h)^2 - \frac{S_0 b}{2} (2e_0 + h) e_0 \left(\frac{e_0 + y''}{y''}\right) \ln \frac{e_0 + 2y''}{e_0} \\
 &+ \frac{S_0 b e_0^2}{4} \left(\frac{e_0 + y''}{y''}\right)^2 \left[\ln \left(\frac{e_0 + 2y''}{e_0}\right) \right]^2 - \frac{S_0 b y''^2 (e_0 + y'')^2}{(e_0 + 2y'')^2}
 \end{aligned}$$

$$\begin{aligned}
 M &= -\frac{S_0 b y''^2}{(e_0 + 2y'')^2} \left[-(e_0 + y'')^2 + y''^2 \right] + \frac{S_0 b e_0^2}{4} \left(\frac{e_0 + y''}{y''}\right)^2 \left[\ln \left(\frac{e_0 + 2y''}{e_0}\right) \right]^2 \\
 &- \frac{2 S_0 b e_0 (e_0 + y'')^2}{e_0 + 2y''} - \frac{S_0 b}{4} \left[4 h e_0 - (2e_0 + h)^2 \right]
 \end{aligned}$$

$$M = -S_0 b e_0^2 + \frac{S_0 b h^2}{4} - \frac{S_0 b e_0 y''^2}{e_0 + 2y''} + \frac{S_0 b e_0^2}{4} \left(\frac{e_0 + y''}{y''}\right)^2 \left[\ln \left(\frac{e_0 + 2y''}{e_0}\right) \right]^2$$

$$\text{LET } \frac{e_0 + 2y''}{e_0} = x$$

EXPANSION

$$\ln x = 2 \left[\frac{x-1}{x+1} + \frac{1}{3} \left(\frac{x-1}{x+1}\right)^3 + \frac{1}{5} \left(\frac{x-1}{x+1}\right)^5 + \dots \right]$$

$$\frac{x-1}{x+1} = \frac{y''}{e_0 + y''} \ll 1$$

$$\frac{S_0 b e_0^2}{4} \left(\frac{e_0 + y''}{y''}\right)^2 \left[\ln \left(\frac{e_0 + 2y''}{e_0}\right) \right]^2 \approx \frac{S_0 b e_0^2}{4} \left(\frac{e_0 + y''}{y''}\right)^2 \left[\left(\frac{y''}{e_0 + y''}\right)^2 + \frac{2}{3} \left(\frac{y''}{e_0 + y''}\right)^4 \right]$$

NEGLECTING FURTHER TERMS

$$= S_0 b e_0^2 + \frac{2}{3} S_0 b e_0^2 \left(\frac{y''}{e_0 + y''} \right)^2$$

$$= S_0 b e_0^2 + \frac{2}{3} \frac{S_0 b e_0^2 y''^2}{e_0^2 + 2e_0 y'' + \underbrace{y''^2}_{\text{NEGLECT}}}$$

$y''^2 \ll e_0^2 + 2e_0 y''$

$$M = \frac{S_0 b h^2}{4} - \frac{S_0 b e_0 y''^2}{3(e_0 + 2y'')} \quad \text{EQUATION 16a}$$

OR

$$M = \frac{S_0 b h^2}{4} - \frac{S_0 b e_0 y''^2}{3(e_0 - 2y'')} \quad \text{EQUATION 16b}$$

$$M = \frac{S_0 b h^2}{4} - \frac{S_0 b e_0 y'^2}{3(e_0 - 2y')}$$

FOR COMPLETE YIELDING $y' = 0$

$$M_c = \frac{S_0 b h^2}{4}$$

LET $g = \frac{1}{y'}$

$$M = \frac{S_0 b h^2}{4} - \frac{S_0 b e_0}{3(e_0 g^2 - 2g)}$$

$$\frac{4M}{S_0 b h^2} - 1 = \frac{-4 S_0 b e_0}{3 S_0 b h^2 (e_0 g^2 - 2g)}$$

$$\left(\frac{M}{M_c} - 1\right) = -\frac{4 e_0}{3 h^2 (e_0 g^2 - 2g)}$$

$$\left(\frac{M}{M_c} - 1\right) e_0 g^2 - 2g \left(\frac{M}{M_c} - 1\right) + \frac{4 e_0}{3 h^2} = 0$$

$$g = \frac{2 \left(\frac{M}{M_c} - 1\right) \pm \sqrt{4 \left(\frac{M}{M_c} - 1\right)^2 - 4 \left(\frac{M_c - 1}{M_c}\right) e_0 \left(\frac{4 e_0}{3 h^2}\right)}}{2 e_0 \left(\frac{M}{M_c} - 1\right)}$$

$$g = \frac{1}{y'} = \frac{1}{e_0} + \frac{1}{e_0} \sqrt{1 - \frac{4 e_0^2 / 3 h^2}{\frac{M}{M_c} - 1}}$$

$$\frac{1}{y'} - \frac{1}{e_0} = \frac{1}{e_0} \sqrt{1 - \frac{4 e_0^2 / 3 h^2}{\frac{M}{M_c} - 1}}$$

$$\frac{e_0 - y'}{e_0 y'} = \frac{1}{e_0} \sqrt{1 - \frac{4 e_0^2 / 3 h^2}{\frac{M}{M_c} - 1}}$$

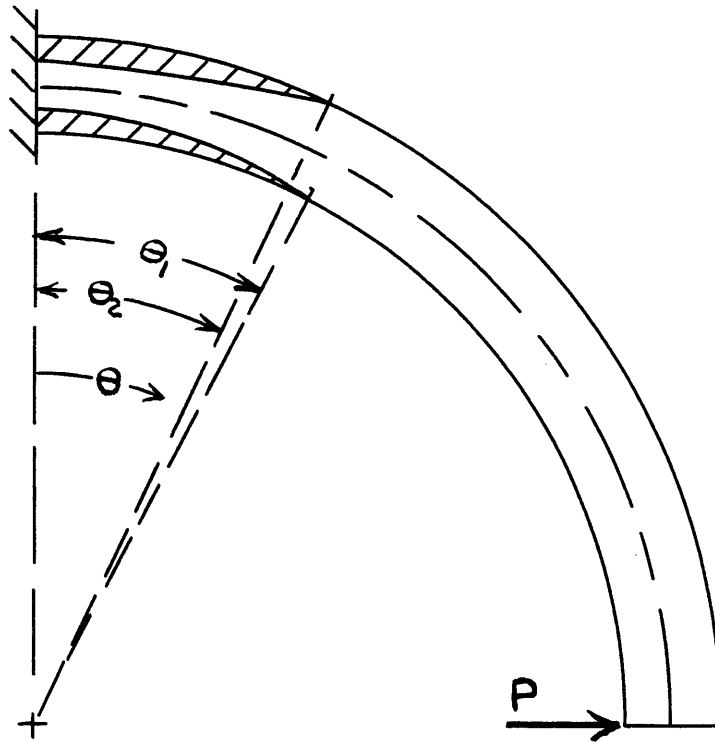
$$\frac{e_0 - y'}{y'} = \frac{1}{\epsilon_0} \left(\frac{e_0 - e}{e} \right)$$

$$\frac{e_0 - e}{e} = \epsilon_0 \sqrt{1 - \frac{4e_0^2/3h^2}{\frac{M}{Mc} - 1}}$$

SUBSTITUTING IN EQUATION 10

$$\frac{d^2w}{d\theta^2} + w = e_0 \epsilon_0 \sqrt{1 + \frac{4e_0^2/3h^2}{1 - \frac{M}{Mc}}} \quad \text{EQUATION 17}$$

Calculations for the Specific Case (Figure 1)



$$M = -P e_o \cos \theta$$

$$b = 0.250''$$

$$h = 0.500''$$

$$R_o = 10.500''$$

$$R_i = 10.000''$$

Initial Yielding

From Equation 11

$$e_o = \frac{.500}{\ln \frac{10.500}{10.000}} = 10.248''$$

From Equation 12 and using $y = y' = y_1$

$$S_o = \frac{M_i}{.250 \times .500 \times .002} \left(\frac{-.248}{10.000} \right)$$

$$M_i = -0.001008 S_o \text{ IN-LB.}$$

$$P = 0.000984 S_o \text{ LB}$$

Secondary Yielding

From Equation 15

$$y_1 = -0.248" \quad \text{or} \quad e_0 = 10.248"$$

From Equation 16a using $y'' = y_2 = 0.252"$

$$M_s = -0.01058 \text{ So inlb}$$

$$P = 0.001032 \text{ So lb}$$

Complete Yielding

From inspection of the equilibrium condition,

$$e_0 = 10.250"$$

From Equation 16a or 16b using $y' = y'' = 0$

$$M_c = -0.01562 \text{ So inlb}$$

$$P = 0.001524 \text{ So lb}$$

Stress Distribution

For any value of applied load up to that required for initial yielding ($P = 0.000984 \text{ So}$) and for the elastic portion (completely so) of the curved bar, the stress distribution is given by Equation 12.

$$S = \frac{M}{A\bar{y}} \left(\frac{y}{e_0 r y} \right)$$

For larger values of applied load up to that required for complete yielding, in any section which has partially yielded, the stress is given in the elastic portion by Equation 14, $S = -S_0 \left(\frac{e_0 - y'}{y} \right) \left(\frac{y}{e_0 r y} \right)$, and in the plastic portion by S_0 for $-y$ and by $-S_0$ for $+y$.

Deflection Equations

$$0 < M < M_L$$

EQUATION 13 APPLIES

$$\frac{d^2 w}{d\theta^2} + w = e_0^2 \frac{M}{EI}$$

$$\text{BUT } M = -P e_0 \cos \theta$$

$$\frac{d^2 w}{d\theta^2} + w = -\frac{P e_0^3 \cos \theta}{EI}$$

COMPLEMENTARY SOLUTION

$$w = C_1 \sin \theta + C_2 \cos \theta$$

PARTICULAR SOLUTION

$$w = -\frac{P e_0^3}{2EI} \theta \sin \theta$$

GENERAL SOLUTION

$$w = C_1 \sin \theta + C_2 \cos \theta - \frac{P e_0^3}{2EI} \theta \sin \theta$$

$$\theta = 0, \quad w = 0, \quad \frac{dw}{d\theta} = 0$$

EVALUATING C_1 & C_2

$$C_1 = C_2 = 0$$

$$w = -\frac{P e_0^3}{2EI} \theta \sin \theta \quad \text{EQUATION 18}$$

$$M_i < M < M_c$$

$$0 < \theta < \theta_1 \quad \text{EQUATION 17 APPLIES}$$

$$\frac{d^2 w}{d\theta^2} + w = -e_0 \epsilon_0 \sqrt{1 + \frac{4e_0^2/3\Delta^2}{1 - \frac{4Pe_0 \cos \theta}{S_0 b h^2}}} \quad \text{EQUATION 17a}$$

$$\theta_1 < \theta < \frac{\pi}{2} \quad \text{EQUATION 13 APPLIES}$$

$$\frac{d^2 w'}{d\theta^2} + w' = -\frac{Pe_0^3 \cos \theta}{EI} \quad \text{EQUATION 13a}$$

Strictly, Equation 17 applies only $0 < \theta < \theta_2$, and Equation 13 applies only $\theta_1 < \theta < \frac{\pi}{2}$, leaving the small range $\theta_2 < \theta < \theta_1$. For this range there would be a new expression. However, since for the case under consideration, i.e., a thin bar with large curvature, the difference between M_i and M_s is very small and consequently the difference between θ_1 and θ_2 is very small. This small difference can be neglected for Equation 17 will extend over this region with sufficient accuracy.

Several attempts were made to find an analytical solution to Equation 17a. Unfortunately, no success was met with. Accordingly, the equation was solved by numerical integration using the method of successive approximations (1, 8, 9).

The general solution for Equation 13a is

$$w' = C_1 \sin \theta + C_2 \cos \theta - \frac{P e_0^3 \theta \sin \theta}{2EI}$$

$$\theta = 0, \quad w = 0, \quad \frac{dw}{d\theta} = 0$$

$$\theta = \theta_1, \quad w = w', \quad \frac{dw}{d\theta} = \frac{dw'}{d\theta}$$

The four constants of integration may be determined from the boundary conditions as stated above. Thus the complete deflection curve may be determined; by numerical integration from 0 to θ_1 and by substitution in Equation 13a (after evaluation of the integration constants) from θ_1 to $\frac{\pi}{2}$.

CASE IINITIAL YIELDING

$$(y' = -0.248")$$

$$M = -0.01008 \text{ So in lbs}$$

$$P = 0.000984 \text{ So lbs}$$

$$e_0 = 10.248 \text{ in}$$

Extent of Plastic Region

There is no plastic region.

Case I - Initial YieldingStress Distributionon Plane ofDeflection CurveMaximum Stress

Y	S	θ	w
inches	psi	radians	inches
0.252	-0.968 So	0	0
0.200	-0.772 So	0.100	0.203 ϵ .
0.150	-0.582 So	0.200	0.808 ϵ .
0.100	-0.390 So	0.300	1.802 ϵ .
0.050	-0.196 So	0.400	3.166 ϵ .
0	0	0.500	4.873 ϵ .
-0.050	0.198 So	0.600	6.886 ϵ .
-0.100	0.397 So	0.700	9.166 ϵ .
-0.150	0.599 So	0.800	11.66 ϵ .
-0.200	0.803 So	0.900	14.33 ϵ .
-0.248	1.000 So	1.000	17.10 ϵ .
		1.100	19.93 ϵ .
		1.200	22.74 ϵ .
		1.300	25.46 ϵ .
		1.400	28.04 ϵ .
		1.500	30.41 ϵ .
		1.5708	31.93 ϵ .

CASE IYIELDING TO ONE QUARTER OF DEPTH OF BEAM

$$(y' = -0.186")$$

$$M = -0.01267 \text{ So in lbs}$$

$$P = 0.001236 \text{ So lbs}$$

$$e_0 = 10.248 \text{ in}$$

Extent of Plastic Region

y'	y''	θ
inches	inches	degrees
-0.186	0.191	0
-0.190	0.197	9°24'
-0.200	0.208	16°28'
-0.220	0.230	25°46'
-0.230	0.241	29°45'
	0.252	33°23'
-0.248		37°17'

Case I - Yielding to One-quarter of Depth of Beam

Stress Distribution

on Plane of

Deflection Curve

Maximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.252	-1.000 S_o	0	0
0.200	-1.000 S_o	0.100	4.818 ϵ .
0.191	-1.000 S_o	0.200	19.13 ϵ .
0.150	-0.780 S_o	0.300	42.50 ϵ .
0.100	-0.523 S_o	0.400	74.29 ϵ .
0.050	-0.263 S_o	0.500	113.7 ϵ .
0	0	0.600	159.7 ϵ .
-0.050	0.265 S_o	0.700	210.7 ϵ .
-0.100	0.533 S_o	0.800	260.8 ϵ .
-0.150	0.804 S_o	0.900	308.6 ϵ .
-0.186	1.000 S_o	1.000	353.6 ϵ .
-0.200	1.000 S_o	1.100	395.4 ϵ .
-0.248	1.000 S_o	1.200	433.5 ϵ .
		1.300	467.4 ϵ .
		1.400	496.8 ϵ .
		1.500	521.3 ϵ .
		1.5708	535.6 ϵ .

CASE IYIELDING TO ONE-HALF OF DEPTH OF BEAM

$$(y' = -0.124")$$

$$M = -0.01431 \text{ So in lbs}$$

$$P = 0.001396 \text{ So lbs}$$

$$e_o = 10.249 \text{ in}$$

Extent of Plastic Region

y'	y''	θ
inches	inches	degrees
-0.124	0.127	0
-0.132	0.136	9°6'
-0.150	0.154	16°56'
-0.175	0.181	24°54'
-0.200	0.208	31°53'
-0.225	0.235	38°26'
	0.251	42°19'
-0.249		45°13'

Case I - Yielding to One-half of Depth of BeamStress Distributionon Plane ofDeflection CurveMaximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.251	-1.000 So	0	0
0.200	-1.000 So	0.100	7.206 ε.
0.150	-1.000 So	0.200	28.39 ε.
0.127	-1.000 So	0.300	62.35 ε.
0.100	-0.789 So	0.400	107.6 ε.
0.075	-0.593 So	0.500	162.4 ε.
0.050	-0.396 So	0.600	225.0 ε.
0.025	-0.199 So	0.700	293.9 ε.
0	0	0.800	367.6 ε.
-0.025	0.200 So	0.900	440.7 ε.
-0.050	0.400 So	1.000	509.7 ε.
-0.075	0.602 So	1.100	574.0 ε.
-0.100	0.805 So	1.200	632.8 ε.
-0.124	1.000 So	1.300	685.5 ε.
-0.150	1.000 So	1.400	731.5 ε.
-0.200	1.000 So	1.500	765.4 ε.
-0.249	1.000 So	1.5708	793.2 ε.

CASE IYEILDING TO THREE-QUARTERS OF DEPTH OF BEAM

$$(y = -0.062")$$

$$M = -0.01530 S_0 \text{ in lbs}$$

$$P = 0.001493 S_0 \text{ lbs}$$

$$c_0 = 10.250 \text{ in}$$

Extent of Plastic Region

y'	y''	θ
inches	inches	degrees
-0.062	0.063	0
-0.100	0.102	14°59'
-0.150	0.154	26°31'
-0.200	0.208	37°22'
	0.250	46°15'
-0.250		48°47'

Case I - Yielding to Three-quarters of Depth of BeamStress Distributionon Plane ofDeflection CurveMaximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.250	-1.000 So	0	0
0.200	-1.000 So	0.100	14.26 ε.
0.150	-1.000 So	0.200	54.32 ε.
0.100	-1.000 So	0.300	114.8 ε.
0.063	-1.000 So	0.400	190.8 ε.
0.050	-0.797 So	0.500	278.4 ε.
0.025	-0.400 So	0.600	374.4 ε.
0	0	0.700	476.3 ε.
-0.025	0.401 So	0.800	581.8 ε.
-0.050	0.805 So	0.900	688.2 ε.
-0.062	1.000 So	1.000	788.9 ε.
-0.100	1.000 So	1.100	882.0 ε.
-0.150	1.000 So	1.200	966.7 ε.
-0.200	1.000 So	1.300	1042 ε.
-0.250	1.000 So	1.400	1107 ε.
		1.500	1161 ε.
		1.5708	1192 ε.

CASE ICOMPLETE YIELDING

$$(y' = y'' = 0)$$

$$M = -0.01562 \text{ So in lb}$$

$$P = 0.001524 \text{ So lb}$$

$$e_0 = 10.250 \text{ in}$$

Extent of Plastic Region

y'	y''	θ
inches	inches	degrees
0	0	0
-0.050	0.051	9°14'
-0.100	0.102	18°54'
-0.150	0.154	28°48'
-0.200	0.208	38°53'
	0.250	47°22'
-0.250		49°49'

Case I - Complete YieldingStress Distributionon Plane ofDeflection CurveMaximum Stress

<u>y</u>	<u>S</u>	<u>e</u>	<u>w</u>
inches	psi	radians	inches
0.250	-1.000 So	0	0
0.200	-1.000 So	any other	∞
0.150	-1.000 So	value	
0.100	-1.000 So		
0.050	-1.000 So		
0	-1.000 So		
0	1.000 So		
-0.050	1.000 So		
-0.100	1.000 So		
-0.150	1.000 So		
-0.200	1.000 So		
-0.250	1.000 So		

Case IMaximum Deflection

P	Wmax
lbs	inches
0	0
0.000492 So	15.96 ε.
0.000984 So	31.93 ε.
0.001236 So	535.6 ε.
0.001396 So	793.2 ε.
0.001493 So	1192 ε.
0.001524 So	∞

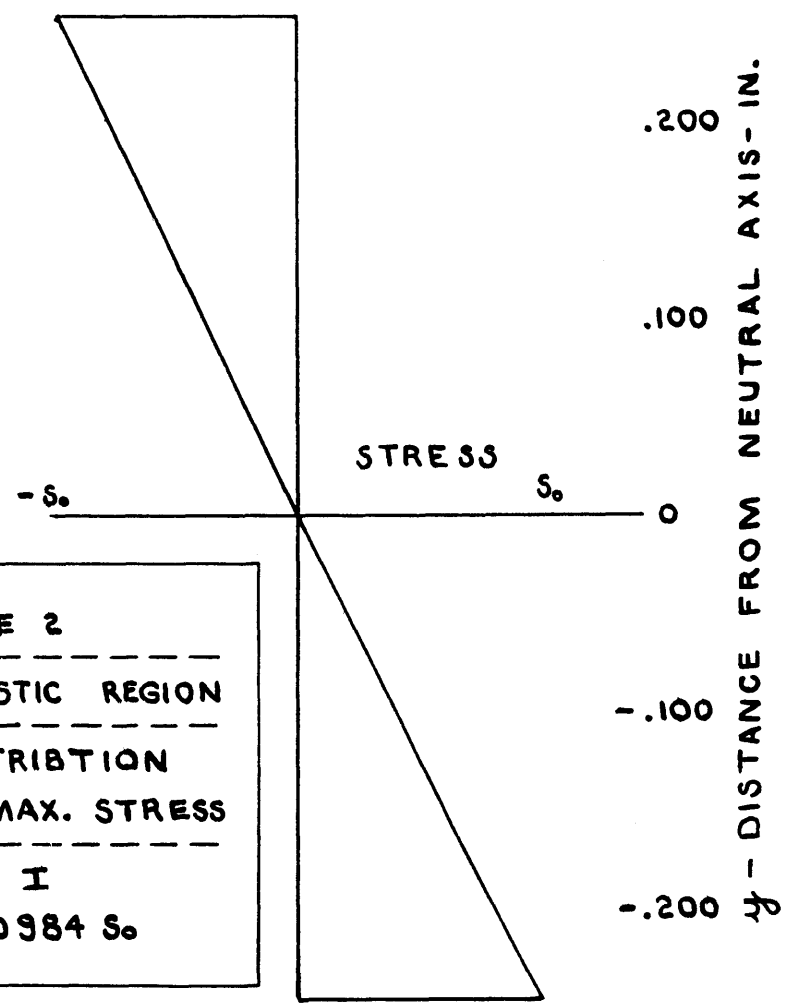
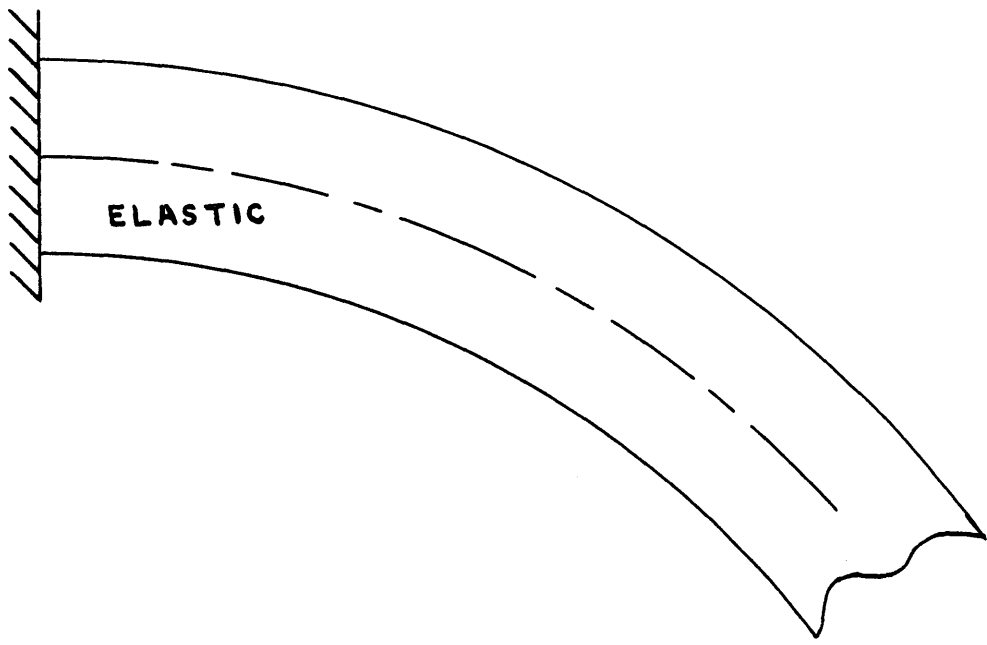


FIGURE 2

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

 CASE I
 $P = 0.000984 s_0$

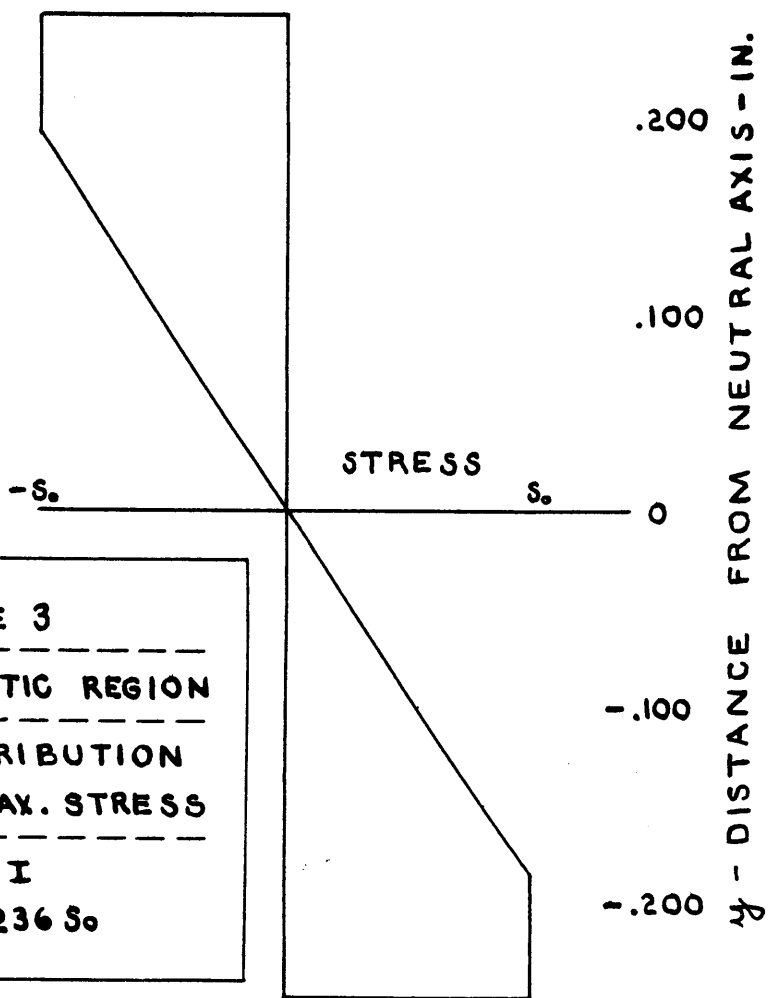
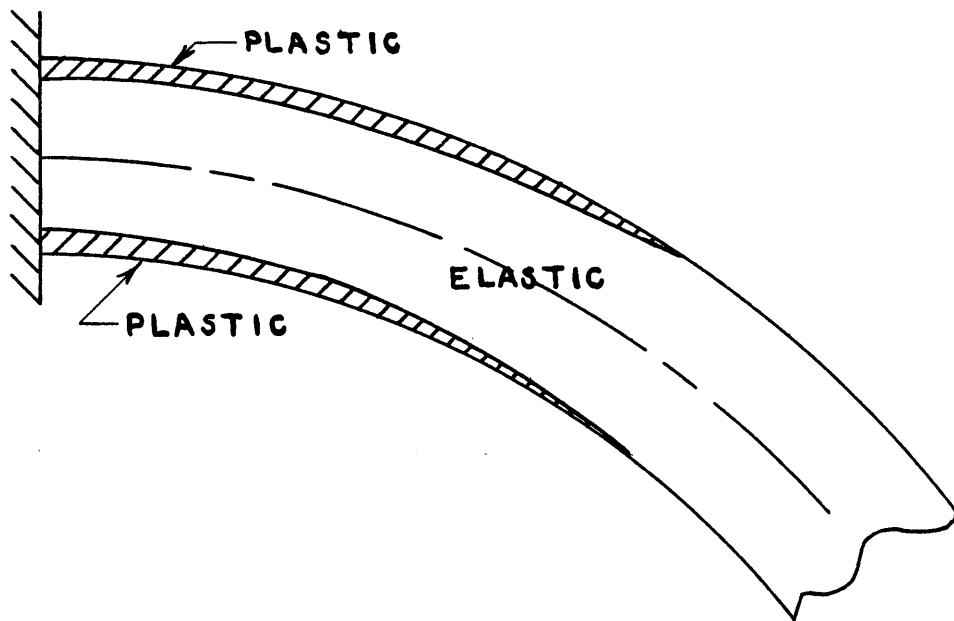


FIGURE 3

EXTENT OF PLASTIC REGION

STRESS DISTRIBUTION
ON PLANE OF MAX. STRESS

CASE I
 $P = 0.001236 s_0$

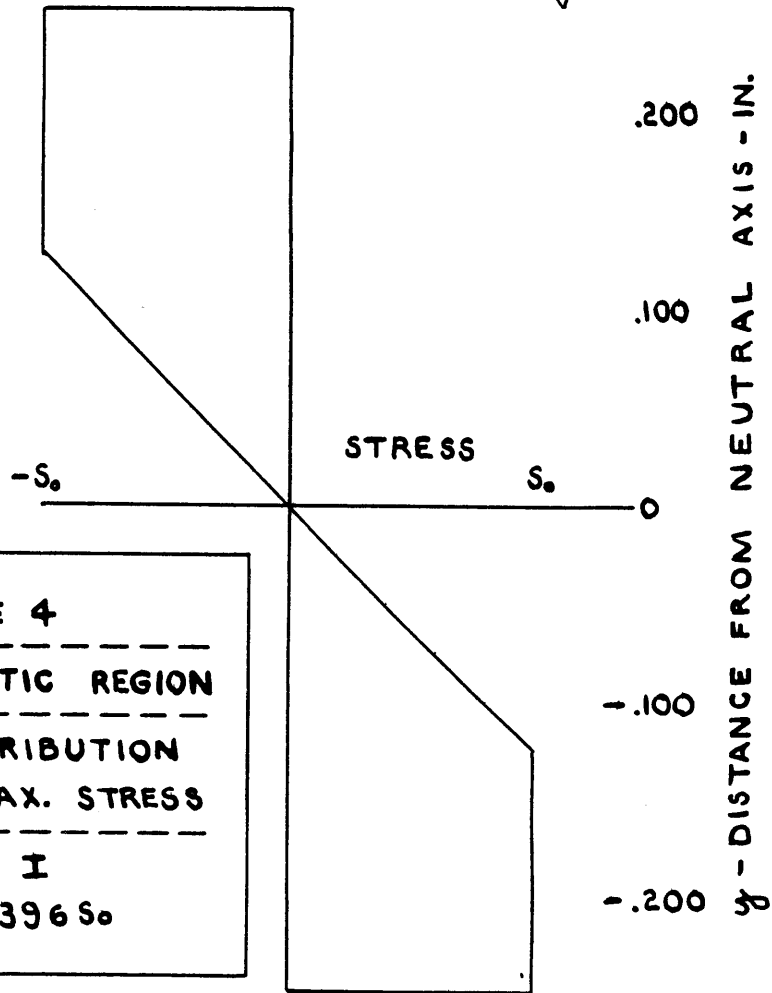
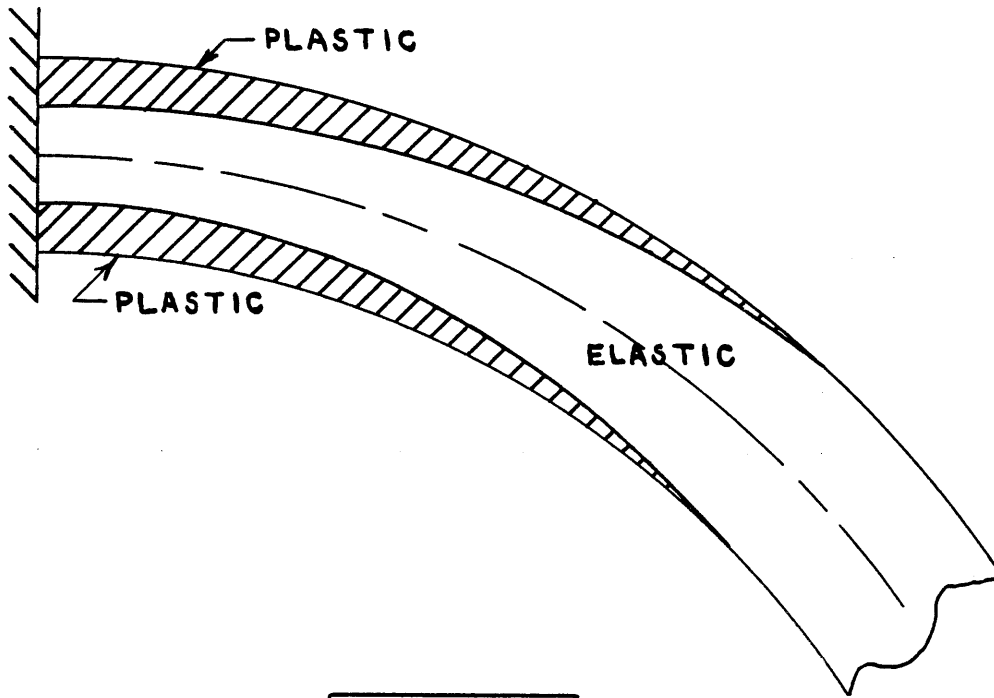


FIGURE 4

EXTENT OF PLASTIC REGION

STRESS DISTRIBUTION
ON PLANE OF MAX. STRESS

CASE I
 $P = 0.001396 S_0$

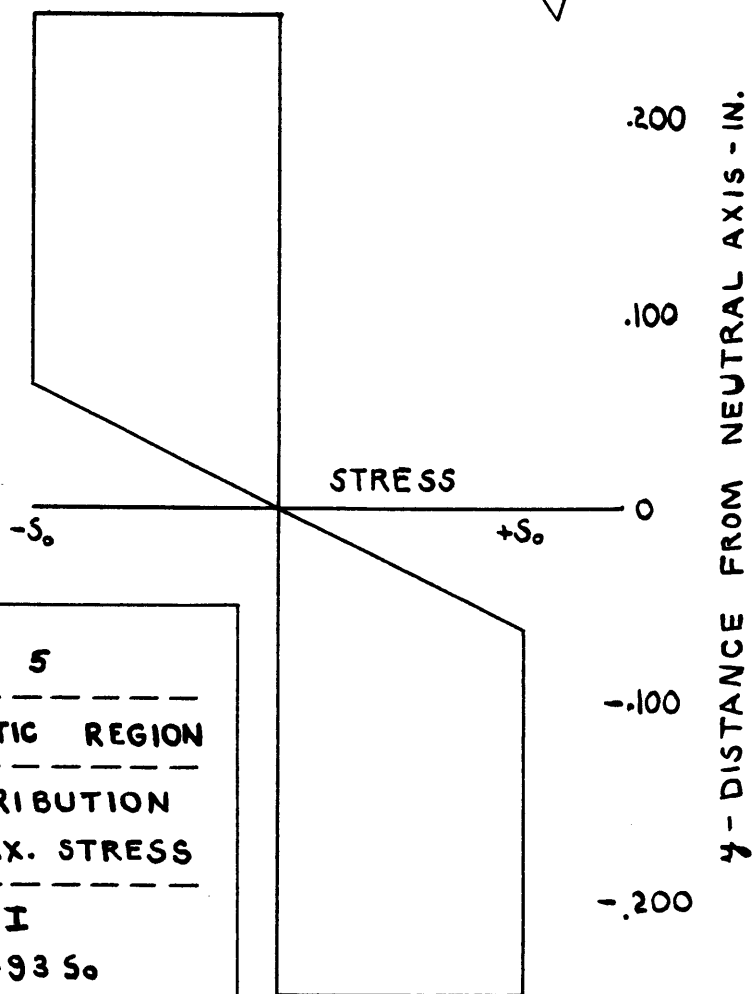
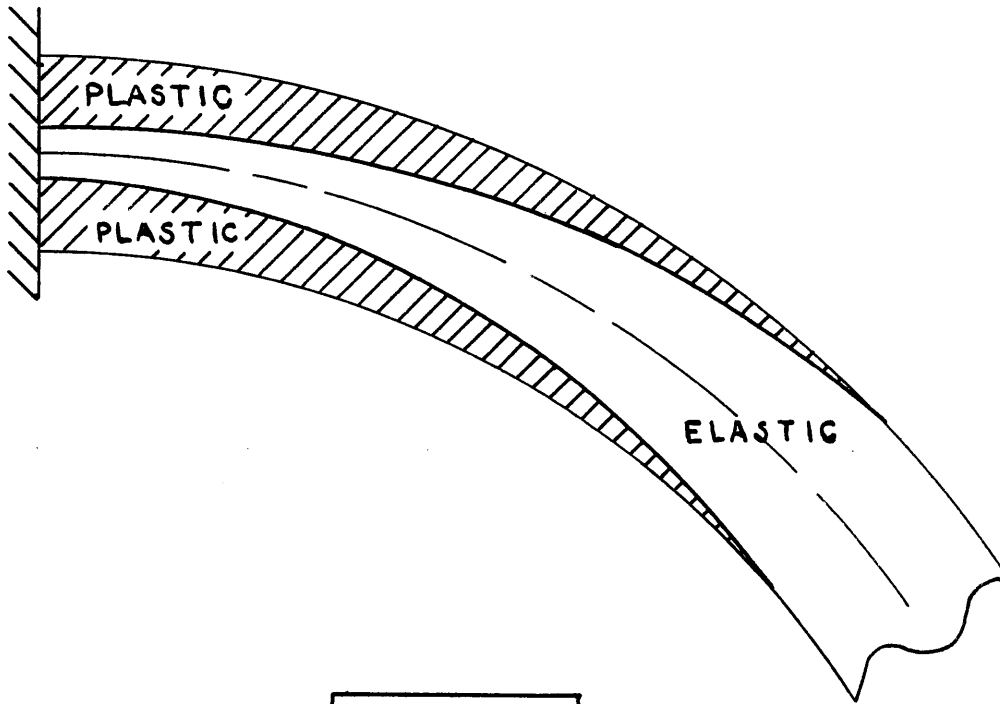


FIGURE 5

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

 CASE I
 $P = 0.001493 S_0$

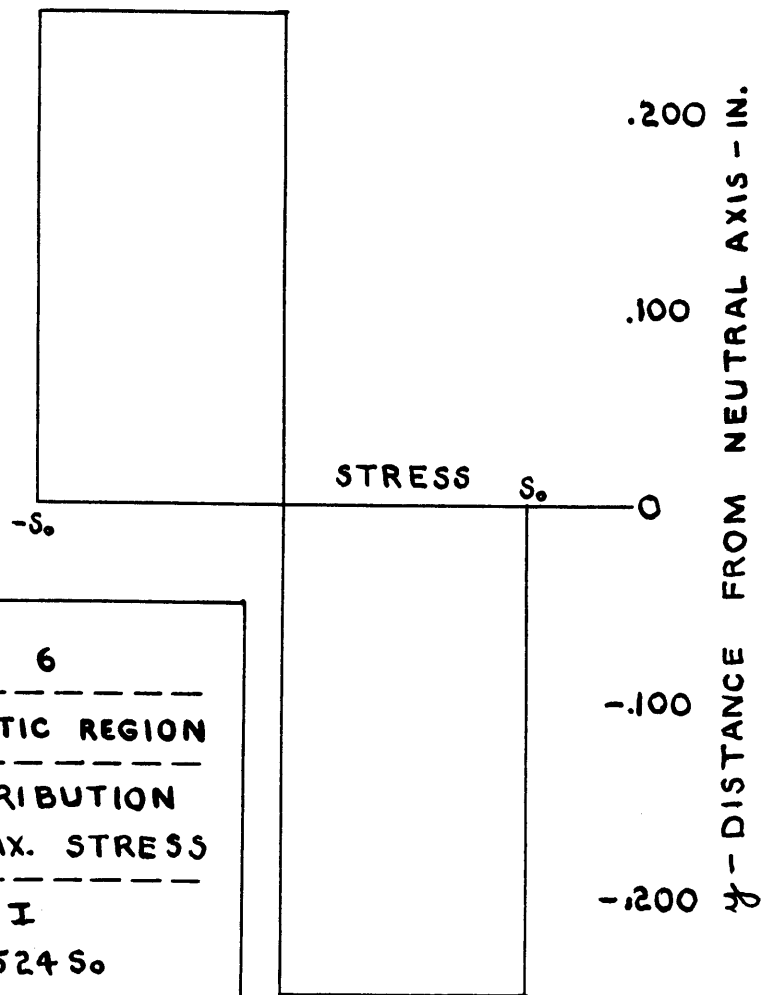
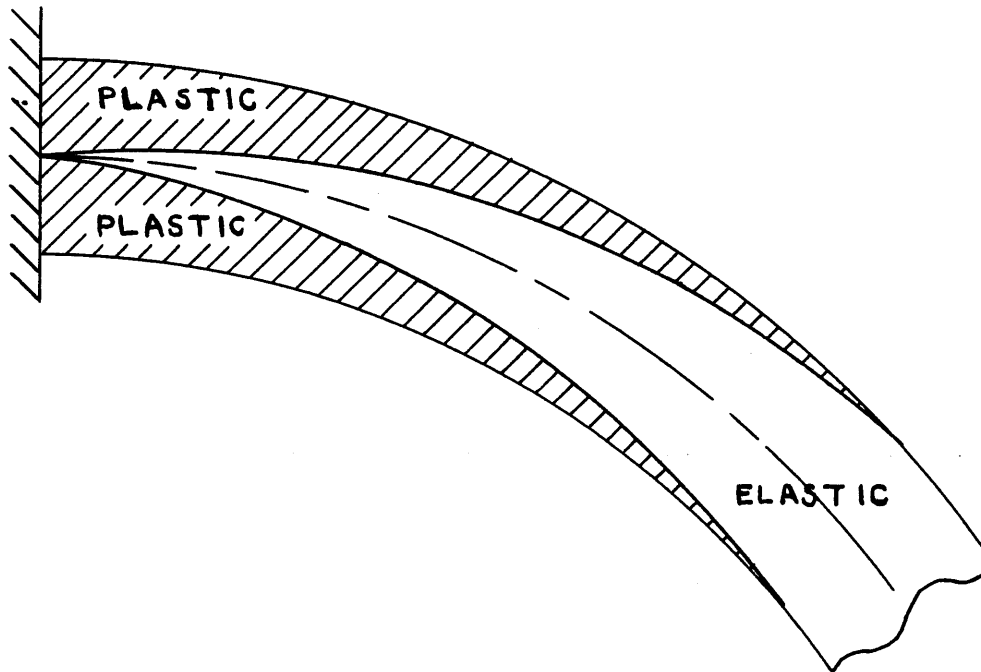
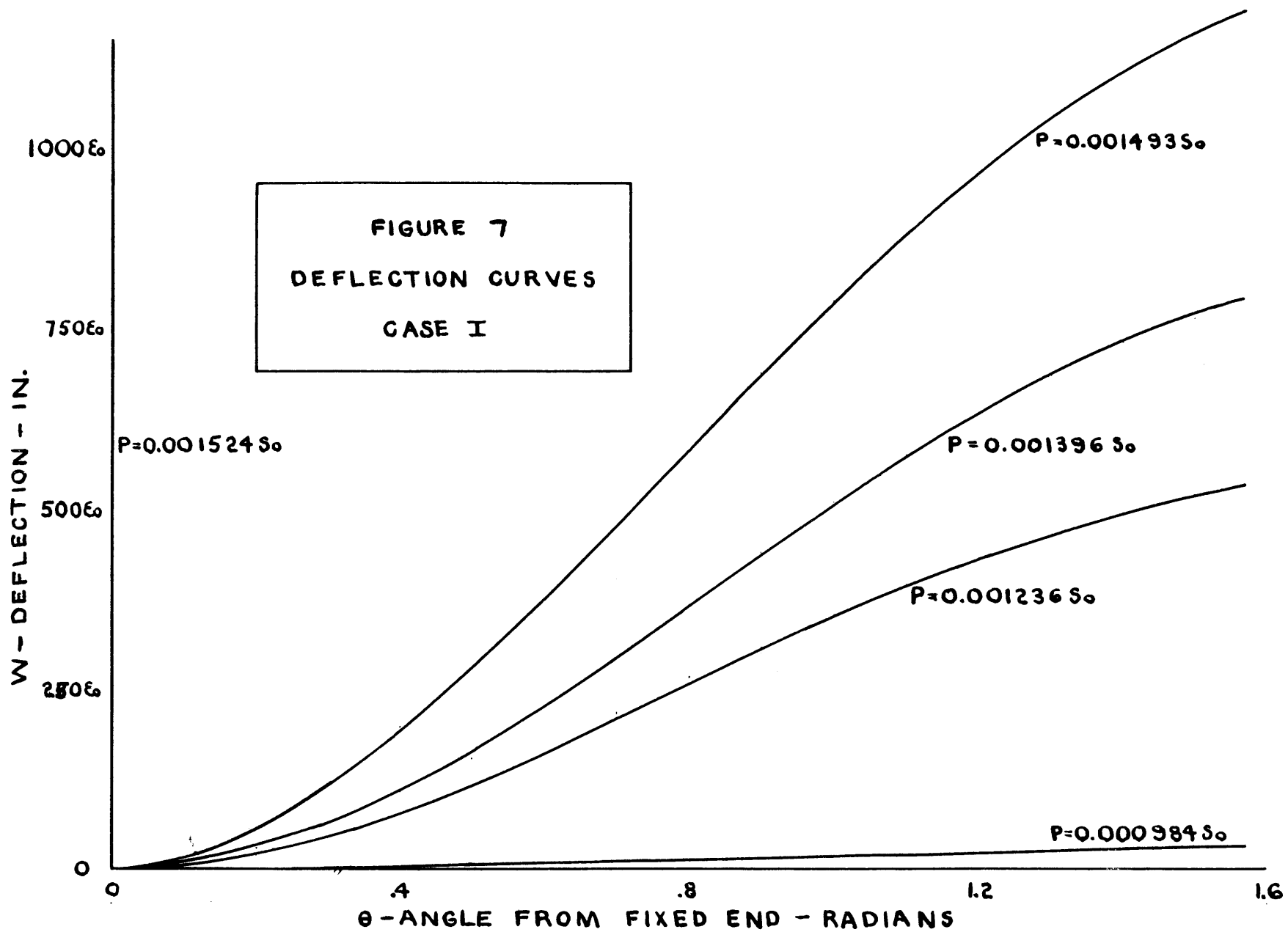


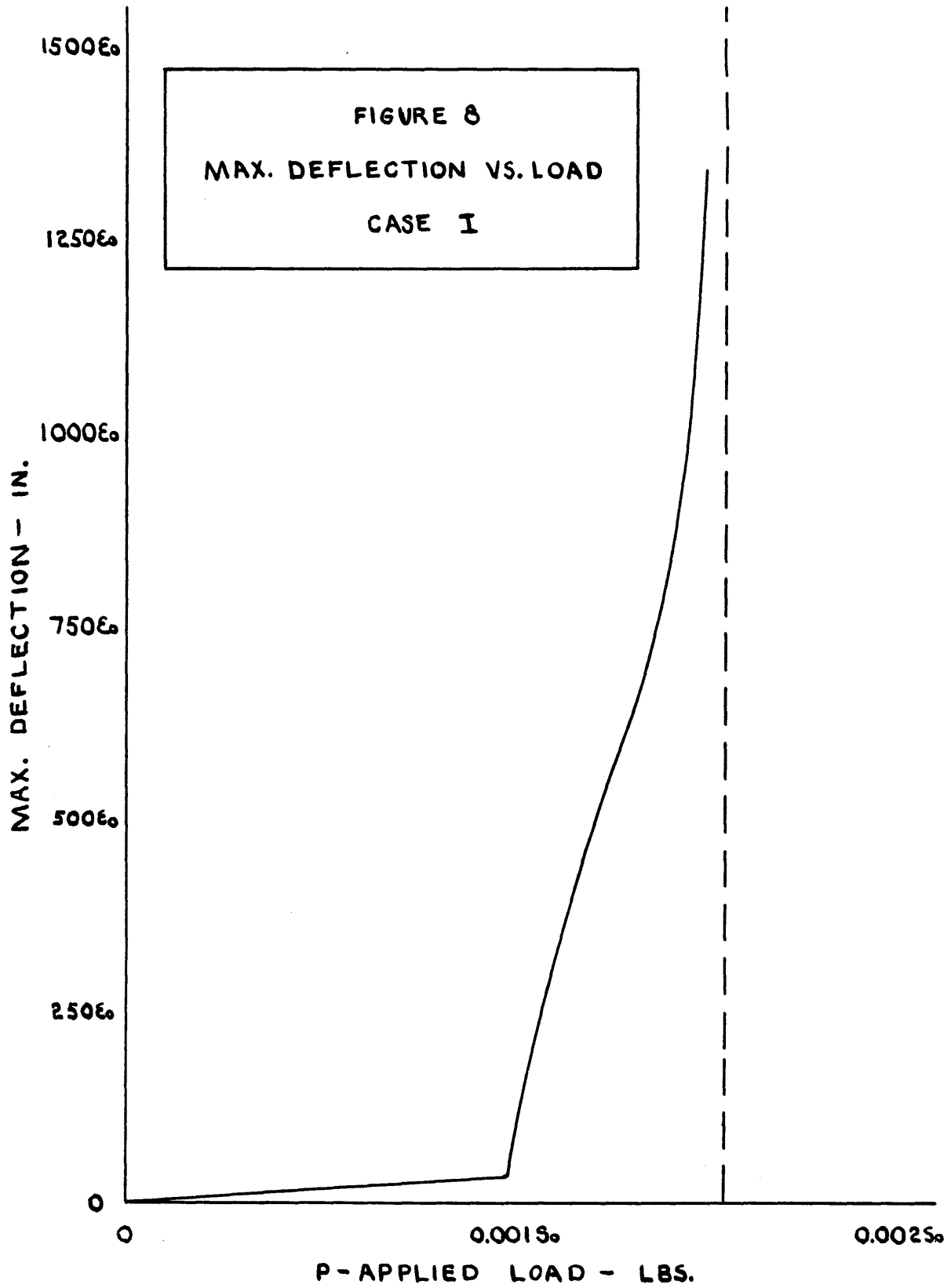
FIGURE 6

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

CASE I
 $P = 0.001524 S_0$

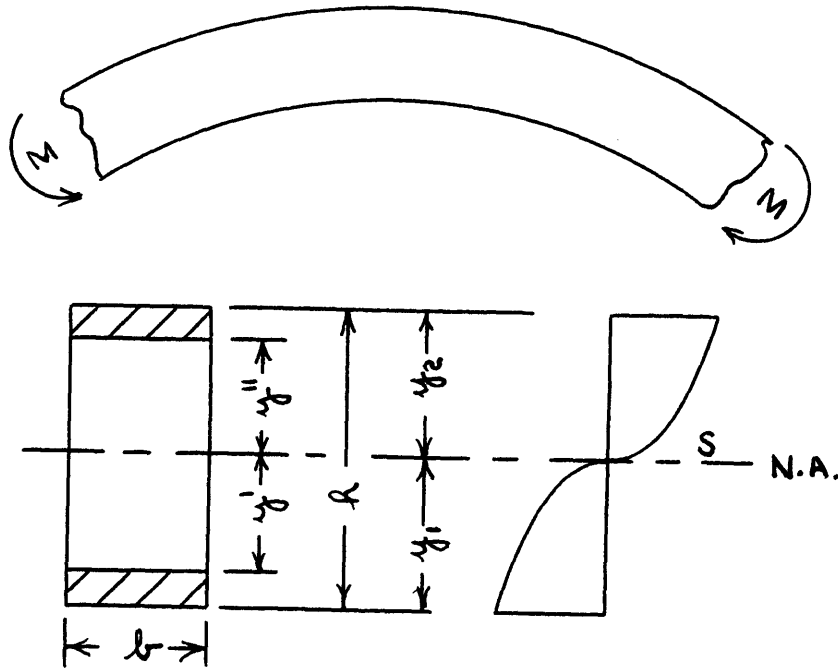




Case II

Consider a curved bar of rectangular cross-section
with depth of beam small
in comparison with the radius of curvature
and a stress-strain curve of the form

$$S = S_0 \left(\frac{2\varepsilon}{\varepsilon_0} \right)^{\frac{1}{2}}$$



$$S = S_0 \left(\frac{2y}{e_0} \right)^{\frac{1}{2}} \text{ FOR } +E$$

$$S = -S_0 \left(\frac{-2y}{e_0} \right)^{\frac{1}{2}} \text{ FOR } -E$$

$$E = \left(\frac{e_0 - e}{e} \right) \left(\frac{y}{e_0 + y} \right)$$

$$S = S_0 \left[\left(\frac{2}{e_0} \right) \left(\frac{e_0 - e}{e} \right) \left(\frac{y}{e_0 + y} \right) \right]^{\frac{1}{2}} \text{ FOR } +y$$

$$S = -S_0 \left[\left(\frac{2}{e_0} \right) \left(\frac{e_0 - e}{e} \right) \left(\frac{-y}{e_0 + y} \right) \right]^{\frac{1}{2}} \text{ FOR } -y$$

$$\text{LET } k = S_0 \left[\left(\frac{2}{e_0} \right) \left(\frac{e_0 - e}{e} \right) \right]^{\frac{1}{2}}$$

$$\int S dA = 0$$

$$\int_{y_1}^0 -k b \left(\frac{-y}{e_0 + y} \right)^{\frac{1}{2}} dy + \int_0^{y_2} k b \left(\frac{y}{e_0 + y} \right)^{\frac{1}{2}} dy = 0$$

$$- \int_{y_1}^0 \left(\frac{-y}{e_0 + y} \right)^{\frac{1}{2}} dy + \int_0^{y_2} \left(\frac{y}{e_0 + y} \right)^{\frac{1}{2}} dy = 0$$

$$- \left[(-y)^{\frac{1}{2}} (e_0 + y)^{\frac{1}{2}} - e_0 \sin^{-1} \left(\frac{-y}{(e_0)^{\frac{1}{2}}} \right) \right]_{y_1}^0 + \left[(y)^{\frac{1}{2}} (e_0 + y)^{\frac{1}{2}} - e_0 \sinh^{-1} \left(\frac{y}{(e_0)^{\frac{1}{2}}} \right) \right]_0^{y_2} = 0$$

$$\sqrt{-y_1} \sqrt{e_0 + y_1} - e_0 \sin^{-1} \sqrt{\frac{-y_1}{e_0}} + \sqrt{y_2} \sqrt{e_0 + y_2} - e_0 \sinh^{-1} \sqrt{\frac{y_2}{e_0}} = 0$$

$$\sqrt{-y_1} \sqrt{e_0 + y_1} + \sqrt{y_2} \sqrt{e_0 + y_2} = e_0 \left[\sin^{-1} \sqrt{\frac{-y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right]$$

$$e_0 = \frac{\sqrt{-y_1} \sqrt{e_0 + y_1} + \sqrt{y_2} \sqrt{e_0 + y_2}}{\sin^{-1} \sqrt{\frac{-y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}}} \quad \text{EQUATION 19}$$

Using absolute values, Equation 19 becomes

$$e_0 = \frac{\sqrt{-y_1} \sqrt{R_1} + \sqrt{y_2} \sqrt{R_0}}{\sin^{-1} \sqrt{\frac{-y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}}} \quad \text{EQUATION 19a}$$

This expression is used to determine the position of the neutral axis. A trial and error solution is recommended since the expression is not readily solvable by algebraic means.

$$M = \int S_y dA$$

$$M = \int_{y_1}^0 -k \left(\frac{-y}{e_0 + y} \right)^{\frac{1}{2}} y b dy + \int_0^{y_2} k \left(\frac{y}{e_0 + y} \right)^{\frac{1}{2}} y b dy$$

$$M = kb \left[- \int_{y_1}^0 y \left(\frac{-y}{e_0 + y} \right)^{\frac{1}{2}} dy + \int_0^{y_2} y \left(\frac{y}{e_0 + y} \right)^{\frac{1}{2}} dy \right]$$

$$M = kb \left(- \left[\frac{-(-y)^{\frac{3}{2}} (e_0 + y)^{\frac{1}{2}}}{2} - \frac{3e_0}{4} (-y)^{\frac{1}{2}} (e_0 + y)^{\frac{1}{2}} + \frac{3e_0^2}{4} \sin^{-1} \left(\frac{-y}{e_0} \right)^{\frac{1}{2}} \right]_0^{y_1} \right. \\ \left. + \left[\frac{(y)^{\frac{3}{2}} (e_0 + y)^{\frac{1}{2}}}{2} - \frac{3e_0}{4} (y)^{\frac{1}{2}} (e_0 + y)^{\frac{1}{2}} + \frac{3e_0^2}{4} \sinh^{-1} \left(\frac{y}{e_0} \right)^{\frac{1}{2}} \right]_0^{y_2} \right)$$

$$M = kb \left[- \frac{\sqrt{-y_1^3} \sqrt{e_0 + y_1}}{2} - \frac{3e_0}{4} \sqrt{-y_1} \sqrt{e_0 + y_1} + \frac{3e_0^2}{4} \sin^{-1} \sqrt{\frac{-y_1}{e_0}} \right. \\ \left. + \frac{\sqrt{y_2^3} \sqrt{e_0 + y_2}}{2} - \frac{3e_0}{4} \sqrt{y_2} \sqrt{e_0 + y_2} + \frac{3e_0^2}{4} \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right]$$

$$M = kb \left[\frac{3e_0^2}{4} \left(\sin^{-1} \sqrt{\frac{-y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) + \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{e_0 + y_2} - \sqrt{-y_1^3} \sqrt{e_0 + y_1} \right) \right. \\ \left. - \frac{3e_0}{4} \left(\sqrt{y_2} \sqrt{e_0 + y_2} + \sqrt{-y_1} \sqrt{e_0 + y_1} \right) \right]$$

$$M = S_0 b \left[\left(\frac{2}{e_0} \left(\frac{e_0 - e}{e} \right) \right)^{\frac{1}{2}} \left[\frac{3e_0^2}{4} \left(\sin^{-1} \sqrt{\frac{-y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) \right. \right. \\ \left. \left. + \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{e_0 + y_2} - \sqrt{-y_1^3} \sqrt{e_0 + y_1} \right) - \frac{3e_0}{4} \left(\sqrt{y_2} \sqrt{e_0 + y_2} + \sqrt{-y_1} \sqrt{e_0 + y_1} \right) \right] \right]$$

EQUATION 20

Using absolute values, Equation 20 becomes

$$M = S_0 \ln \left[\left(\frac{2}{\epsilon_0} \right) \left(\frac{e_0 - e}{e} \right) \right]^{\frac{1}{2}} \left[\frac{3e_0^2}{4} \left(\sin^{-1} \sqrt{\frac{y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) \right. \\ \left. + \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_i} \right) - \frac{3e_0}{4} \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right]$$

EQUATION 20a

Care must be taken to use a high degree of accuracy when evaluating the expression in Equation 20 (or 20a) contained in the brackets since it involves the very small difference of two comparatively large numbers.

$$S = \pm S_0 \left[\left(\frac{2}{\epsilon_0} \right) \left(\frac{e_0 - e}{e} \right) \left(\frac{\pm y}{e_0 + y} \right) \right]^{\frac{1}{2}}$$

$$S = \frac{\pm M \left(\frac{\pm y}{e_0 + y} \right)^{\frac{1}{2}}}{\ln \left[\frac{3e_0^2}{4} \left(\sin^{-1} \sqrt{\frac{y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) + \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_i} \right) - \frac{3e_0}{4} \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right]}$$

EQUATION 21

When using Equation 21, the + signs apply to + values of y, the - signs to - values of y.

FROM EQUATION 20a

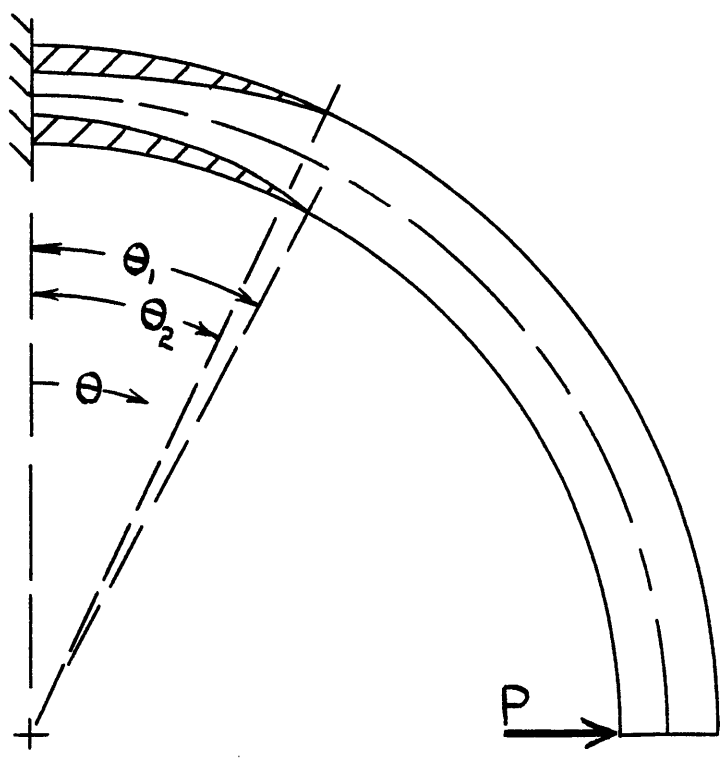
$$\frac{\rho_0 - \rho}{e} = \frac{M^2 \epsilon_0}{2S_0^2 \ln^2 \left[\frac{3\epsilon_0^2}{4} \left(\sin^{-1} \sqrt{\frac{21}{\epsilon_0}} + \sinh^{-1} \sqrt{\frac{21}{\epsilon_0}} \right) + \frac{1}{2} (\sqrt{y_2^2} \sqrt{R_0} - \sqrt{y_1^2} \sqrt{R_i}) - \frac{3\epsilon_0}{4} (\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i}) \right]^2}$$

SUBSTITUTING IN EQUATION 10

$$\frac{d^2 w}{d\theta^2} + w = \frac{\rho_0 M^2 \epsilon_0}{2S_0^2 \ln^2 \left[\frac{3\epsilon_0^2}{4} \left(\sin^{-1} \sqrt{\frac{21}{\epsilon_0}} + \sinh^{-1} \sqrt{\frac{21}{\epsilon_0}} \right) + \frac{1}{2} (\sqrt{y_2^2} \sqrt{R_0} - \sqrt{y_1^2} \sqrt{R_i}) - \frac{3\epsilon_0}{4} (\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i}) \right]^2}$$

EQUATION 22

Calculations for the Specific Case (Figure 1)



$$M = -P e_o \cos \theta$$

$$b = 0.250''$$

A trial and error solution of Equation 19a yields the result that

$$h = 0.500''$$

$$R_o = 10.500''$$

$$R_i = 10.000''$$

$$e_o = 10.249''$$

By the substitution of $M = -P e_o \cos \theta$ in Equation 21

$$S = \frac{-P e_o \cos \theta \left(\frac{\pm y}{e_o + y} \right)^{\frac{1}{2}}}{b \left[\frac{3e_o^2}{4} \left(\sin^{-1} \sqrt{\frac{y_1}{e_o}} + \sinh^{-1} \sqrt{\frac{y_2}{e_o}} \right) + \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{R_o} - \sqrt{y_1^3} \sqrt{R_i} \right) - \frac{3e_o}{4} \left(\sqrt{y_2} \sqrt{R_o} + \sqrt{y_1} \sqrt{R_i} \right) \right]}$$

Equation 21a

Evaluating

$$\left[\frac{3\epsilon_0^2}{4} \left(\sin^{-1} \sqrt{\frac{y_1}{\epsilon_0}} + \sin h^{-1} \sqrt{\frac{y_1}{\epsilon_0}} \right) + \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_i} \right) - \frac{3\epsilon_0}{4} \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right] = 0.00789$$

Initial Yielding

From Equation 21a, $S = S_0$, $y = y' = y_1$

$$M_1 = -0.01250 S_0 \text{ in-lb}$$

$$P = 0.001220 S_0 \text{ lb}$$

Secondary Yielding

From Equation 21a, $S = -S_0$, $y = y'' = y_2$

$$M_s = -0.01276 S_0 \text{ in-lb}$$

$$P = 0.001245 S_0 \text{ lb}$$

Complete Yielding

From Equation 21a, $S = S_0$, $y = y' = y'' = 0$

$$M_c = -\infty \text{ in-lb}$$

$$P = \infty \text{ lb}$$

Stress Distribution

The stress distribution at any angle θ from 0 to $\frac{\pi}{2}$ for any load P from 0 to ∞ is given by Equation 21a. This applies to both the elastic and plastic regions since the stress-strain curve also applies to both the elastic and plastic regions.

Deflection Equation

Substitution of $M = -P e_0 \cos \theta$ and $\cos^2 \theta = \frac{\cos 2\theta + 1}{2}$
in Equation 22 yields

$$\frac{d^2 w}{d\theta^2} + w = \frac{P^2 e_0^3 \epsilon_0 (\cos 2\theta + 1)}{4 S_0^2 b^2 \left[\frac{3e_0^2}{4} \left(\sin^{-1} \sqrt{\frac{2z}{c_0}} + \sinh^{-1} \sqrt{\frac{2z}{c_0}} \right) + \frac{1}{2} (\sqrt{y_2^2} \sqrt{R_0} - \sqrt{y_1^2} \sqrt{R_i}) - \frac{3e_0}{4} (\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i}) \right]^2}$$

Complementary Solution

$$w = C_1 \sin \theta + C_2 \cos \theta$$

Particular Solution

$$w = \frac{-P^2 e_0^3 \epsilon_0 \left(\frac{\cos 2\theta}{3} - 1 \right)}{4 S_0^2 b^2 \left[\frac{3e_0^2}{4} \left(\sin^{-1} \sqrt{\frac{2z}{c_0}} + \sinh^{-1} \sqrt{\frac{2z}{c_0}} \right) + \frac{1}{2} (\sqrt{y_2^2} \sqrt{R_0} - \sqrt{y_1^2} \sqrt{R_i}) - \frac{3e_0}{4} (\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i}) \right]^2}$$

General Solution

$$w = C_1 \sin \theta + C_2 \cos \theta - \frac{P^2 e_0^3 \epsilon_0 \left(\frac{\cos 2\theta}{3} - 1 \right)}{4 S_0^2 b^2 \left[\frac{3e_0^2}{4} \left(\sin^{-1} \sqrt{\frac{2z}{c_0}} + \sinh^{-1} \sqrt{\frac{2z}{c_0}} \right) + \frac{1}{2} (\sqrt{y_2^2} \sqrt{R_0} - \sqrt{y_1^2} \sqrt{R_i}) - \frac{3e_0}{4} (\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i}) \right]^2}$$

Boundary Conditions

$$\theta = 0, \quad w = 0, \quad \frac{dw}{d\theta} = 0$$

Evaluation of C_1 and C_2

$$C_1 = 0$$

$$C_2 = \frac{-P^2 e_0^3 \epsilon_0}{6 S_0^2 b^2 \left[\frac{3e_0^2}{4} \left(\sin^{-1} \sqrt{\frac{2z}{c_0}} + \sinh^{-1} \sqrt{\frac{2z}{c_0}} \right) + \frac{1}{2} (\sqrt{y_2^2} \sqrt{R_0} - \sqrt{y_1^2} \sqrt{R_i}) - \frac{3e_0}{4} (\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i}) \right]^2}$$

$$w = \frac{-P^2 e_0^3 \epsilon_0 \left(\frac{2 \cos \theta}{3} + \frac{\cos 2\theta}{3} - 1 \right)}{4 S_0^2 b^2 \left[\frac{3e_0^2}{4} \left(\sin^{-1} \sqrt{\frac{2z}{c_0}} + \sinh^{-1} \sqrt{\frac{2z}{c_0}} \right) + \frac{1}{2} (\sqrt{y_2^2} \sqrt{R_0} - \sqrt{y_1^2} \sqrt{R_i}) - \frac{3e_0}{4} (\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i}) \right]^2}$$

Equation 23

This deflection equation (Equation 23) applies for all values of P from 0 to ∞ , ie, it applies over both the elastic and plastic regions. The sign of the deflection must be the same as that of the bending moment before the moment term is squared and substituted in Equation 22.

CASE IIINITIAL YIELDING

$$(y' = -0.249)$$

$$M = -0.01250 S_0 \text{ in lbs}$$

$$F = 0.001220 S_0 \text{ lbs}$$

$$e_0 = 10.249 \text{ in}$$

Extent of Plastic Region

There is no plastic region.

Case II - Initial YieldingStress Distributionon Plane ofDeflection CurveMaximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.251	-0.980 S_o	0	0
0.200	-0.877 S_o	0.100	1.027 ϵ_o
0.150	-0.761 S_o	0.200	4.075 ϵ_o
0.100	-0.623 S_o	0.300	9.055 ϵ_o
0.050	-0.442 S_o	0.400	15.85 ϵ_o
0.040	-0.395 S_o	0.500	25.84 ϵ_o
0.030	-0.342 S_o	0.600	33.85 ϵ_o
0.020	-0.280 S_o	0.700	44.60 ϵ_o
0.010	-0.198 S_o	0.800	56.11 ϵ_o
0	0	0.900	68.00 ϵ_o
-0.010	0.198 S_o	1.000	80.11 ϵ_o
-0.020	0.280 S_o	1.100	91.97 ϵ_o
-0.030	0.343 S_o	1.200	103.3 ϵ_o
-0.040	0.397 S_o	1.300	113.9 ϵ_o
-0.050	0.444 S_o	1.400	123.6 ϵ_o
-0.100	0.629 S_o	1.500	132.0 ϵ_o
-0.150	0.772 S_o	1.5708	137.2 ϵ_o
-0.200	0.894 S_o		
-0.249	1.000 S_o		

CASE IIYIELDING TO ONE-FIFTH OF DEPTH OF BEAM

$$(y' = -0.200)$$

$$M = -0.01398 \text{ So in lb}$$

$$P = 0.001364 \text{ So lb}$$

$$e_0 = 10.249 \text{ in}$$

Extent of Plastic Region

y'	y''	θ
inches	inches	degrees
-0.200	0.208	0
-0.209	0.218	12° 6'
-0.215	0.224	15° 28'
-0.230	0.241	21° 24'
	0.251	24° 9'
-0.249		26° 37'

Case II - Yielding to One-fifth of Depth of Beam

Stress Distribution

on Plane of

Deflection Curve

Maximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.251	-1.096 So	0	0
0.200	-0.981 So	0.100	1.285 ε.
0.150	-0.851 So	0.200	5.098 ε.
0.100	-0.697 So	0.300	11.33 ε.
0.050	-0.494 So	0.400	19.83 ε.
0.040	-0.442 So	0.500	32.33 ε.
0.030	-0.383 So	0.600	42.35 ε.
0.020	-0.313 So	0.700	55.80 ε.
0.010	-0.221 So	0.800	70.20 ε.
0	0	0.900	85.07 ε.
-0.010	0.222 So	1.000	100.2 ε.
-0.020	0.313 So	1.100	115.1 ε.
-0.030	0.384 So	1.200	129.3 ε.
-0.040	0.444 So	1.300	142.6 ε.
-0.050	0.496 So	1.400	154.6 ε.
-0.100	0.704 So	1.500	165.2 ε.
-0.150	0.864 So	1.5708	171.7 ε.
-0.200	1.000 So		
-0.249	1.118 So		

CASE IIYIELDING TO TWO-FIFTHS OF DEPTH OF BEAM

$$(y' = -0.150'')$$

$$M = -0.01618 \text{ So in lb}$$

$$P = 0.001579 \text{ So lb}$$

$$e_o = 10.249 \text{ in}$$

Extent of Plastic Region

y'	y''	θ
inches	inches	degrees
-0.150	0.154	0
-0.155	0.160	10°26'
-0.164	0.169	17° 7'
-0.180	0.187	24°17'
-0.209	0.218	32°22'
-0.230	0.241	36°27'
	0.251	37°59'
-0.249		39°26'

Case II - Yielding to Two-fifths of Depth of Beam

Stress Distribution

on Plane of

Deflection Curve

Maximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.251	-1.269 S_o	0	0
0.200	-1.135 S_o	0.100	1.722 ϵ_o
0.150	-0.985 S_o	0.200	6.832 ϵ_o
0.100	-0.807 S_o	0.300	15.18 ϵ_o
0.050	-0.572 S_o	0.400	26.57 ϵ_o
0.040	-0.512 S_o	0.500	43.32 ϵ_o
0.030	-0.443 S_o	0.600	56.75 ϵ_o
0.020	-0.362 S_o	0.700	74.78 ϵ_o
0.010	-0.256 S_o	0.800	94.07 ϵ_o
0	0	0.900	114.0 ϵ_o
-0.010	0.256 S_o	1.000	134.3 ϵ_o
-0.020	0.363 S_o	1.100	154.2 ϵ_o
-0.030	0.445 S_o	1.200	173.2 ϵ_o
-0.040	0.514 S_o	1.300	191.0 ϵ_o
-0.050	0.574 S_o	1.400	207.2 ϵ_o
-0.100	0.814 S_o	1.500	221.3 ϵ_o
-0.150	1.000 S_o	1.5708	230.0 ϵ_o
-0.200	1.158 S_o		
-0.249	1.295 S_o		

CASE IIYIELDING TO THREE-FIFTHS OF DEPTH OF BEAM

$$(y' = -0.100")$$

$$M = -0.01987 S_0 \text{ in lb}$$

$$P = 0.001939 S_0 \text{ lb}$$

$$e_0 = 10.249 \text{ in}$$

Extent of Plastic Region

y'	y''	θ
inches	inches	degrees
-0.100	0.102	0
-0.110	0.112	17°38'
-0.125	0.128	26°27'
-0.150	0.155	35°28'
-0.200	0.210	45°17'
	0.251	50° 4'
-0.249		51° 1'

Case II - Yielding to Three-fifths of Depth of Beam

Stress Distribution

on Plane of

Deflection Curve

Maximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.251	-1.558 So	0	0
0.200	-1.394 So	0.100	2.595 ε.
0.150	-1.210 So	0.200	10.28 ε.
0.100	-0.990 So	0.300	22.88 ε.
0.050	-0.702 So	0.400	40.06 ε.
0.040	-0.628 So	0.500	65.31 ε.
0.030	-0.544 So	0.600	85.55 ε.
0.020	-0.445 So	0.700	112.7 ε.
0.010	-0.314 So	0.800	141.8 ε.
0	0	0.900	171.8 ε.
-0.010	0.315 So	1.000	202.4 ε.
-0.020	0.445 So	1.100	232.4 ε.
-0.030	0.546 So	1.200	261.2 ε.
-0.040	0.631 So	1.300	288.0 ε.
-0.050	0.705 So	1.400	312.3 ε.
-0.100	1.000 So	1.500	325.0 ε.
-0.150	1.228 So	1.5708	346.7 ε.
-0.200	1.421 So		
-0.249	1.590 So		

CASE IIYIELDING TO FOUR-FIFTHS OF DEPTH OF BEAM

$$(y' = -0.050")$$

$$M = -0.02817 S_0 \text{ in lb}$$

$$P = 0.002749 S_0 \text{ lb}$$

$$e_0 = 10.249 \text{ in}$$

Extent of Plastic Region

y'	y''	θ
inches	inches	degrees
-0.050	0.051	0
-0.053	0.054	13°48'
-0.058	0.059	21°56'
-0.066	0.067	29°35'
-0.075	0.076	35°22'
-0.100	0.102	45° 8'
-0.150	0.155	54°56'
-0.200	0.210	60°15'
	0.251	63° 4'
-0.249		63°40'

Case II - Yielding to Four-fifths of Depth of Beam

Stress Distribution

on Plane of

Deflection Curve

Maximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.251	-2.208 So	0	0
0.200	-1.976 So	0.100	5.216 ε.
0.150	-1.715 So	0.200	20.70 ε.
0.100	-1.404 So	0.300	45.99 ε.
0.050	-0.995 So	0.400	80.51 ε.
0.040	-0.891 So	0.500	131.3 ε.
0.030	-0.772 So	0.600	172.0 ε.
0.020	-0.630 So	0.700	226.5 ε.
0.010	-0.446 So	0.800	285.0 ε.
0	0	0.900	345.4 ε.
-0.010	0.446 So	1.000	406.9 ε.
-0.020	0.632 So	1.100	467.1 ε.
-0.030	0.774 So	1.200	524.9 ε.
-0.040	0.894 So	1.300	578.8 ε.
-0.050	1.000 So	1.400	627.6 ε.
-0.100	1.418 So	1.500	670.5 ε.
-0.150	1.741 So	1.5708	696.9 ε.
-0.200	2.015 So		
-0.249	2.254 So		

Case IIMaximum Deflection

P	Wmax
lbs	inches
0	0
0.0002 So	3.689 ε.
0.0004 So	14.76 ε.
0.0006 So	33.20 ε.
0.0008 So	58.29 ε.
0.0010 So	92.23 ε.
0.0012 So	132.8 ε.
0.0014 So	180.4 ε.
0.0016 So	236.1 ε.
0.0018 So	298.8 ε.
0.0020 So	368.9 ε.
0.0022 So	446.4 ε.
0.0024 So	531.2 ε.
0.0026 So	623.5 ε.
0.0028 So	723.1 ε.
0.0030 So	830.1 ε.

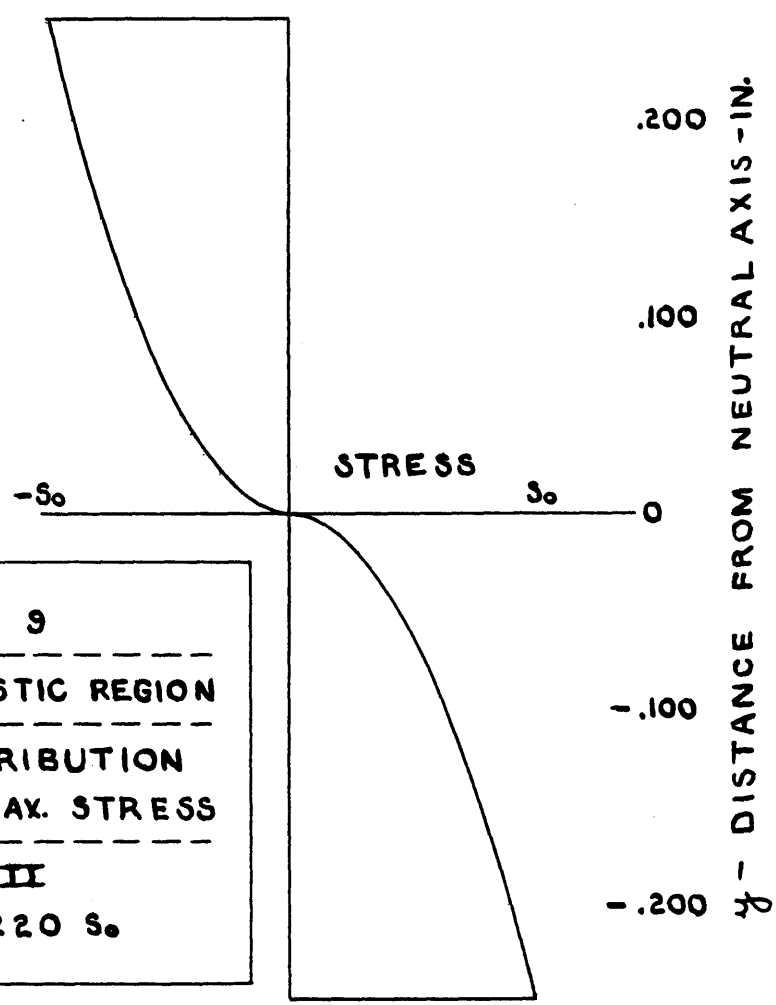
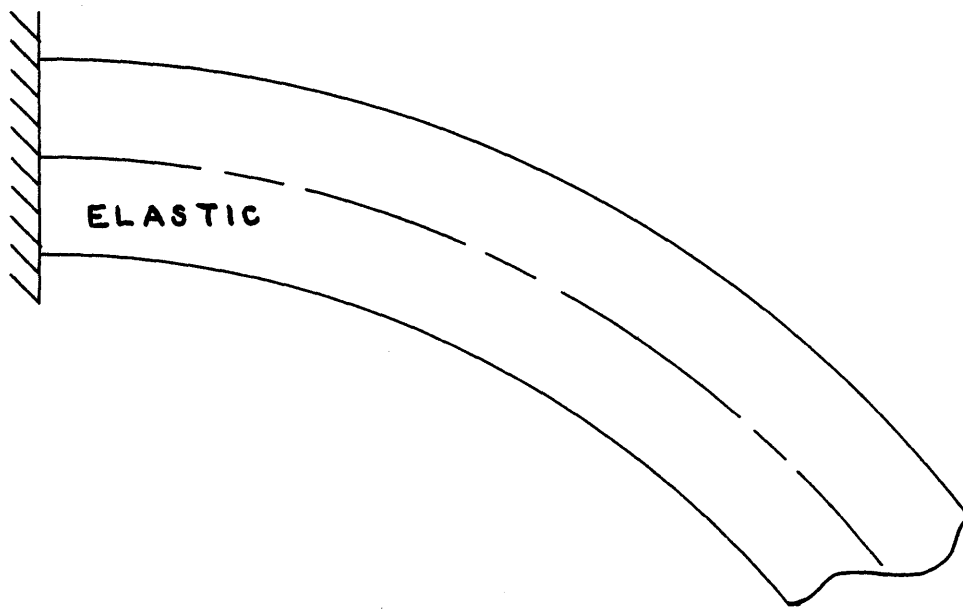


FIGURE 9

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

 CASE II
 $P = 0.001220 S_0$

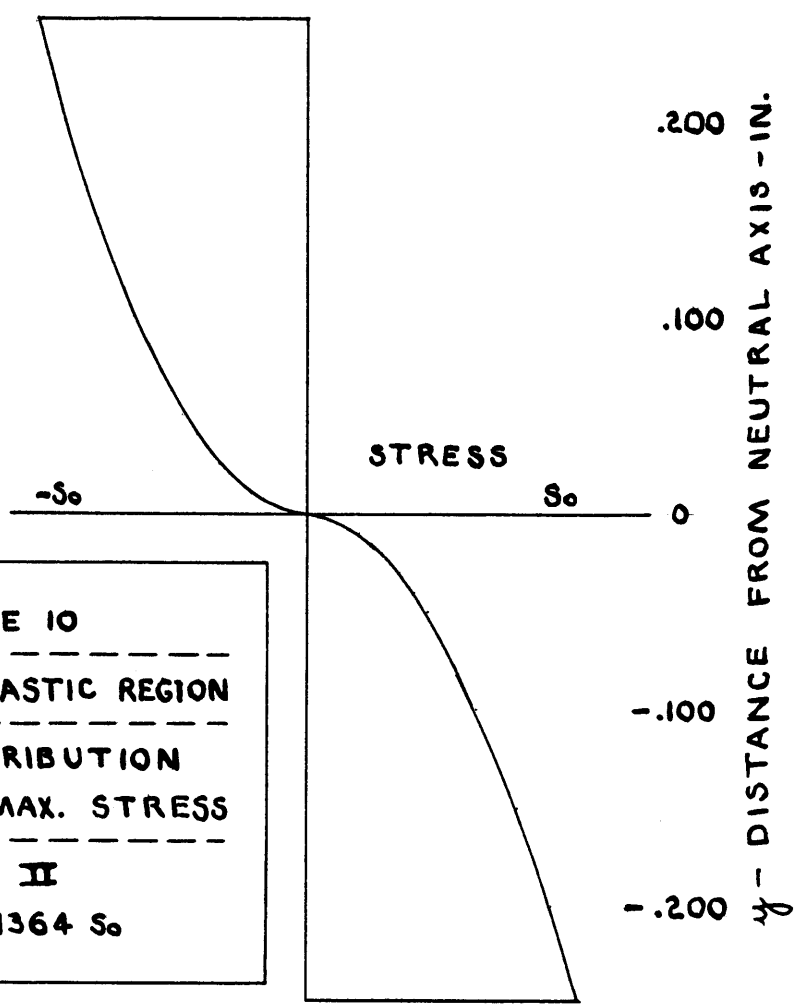
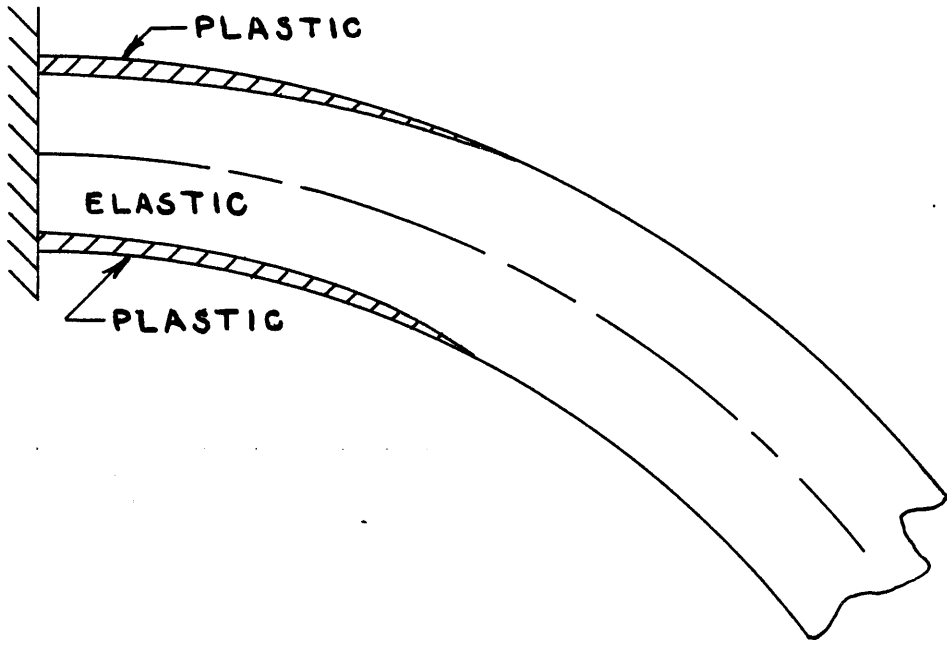


FIGURE 10

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

 CASE II
 $P = 0.001364 S_0$

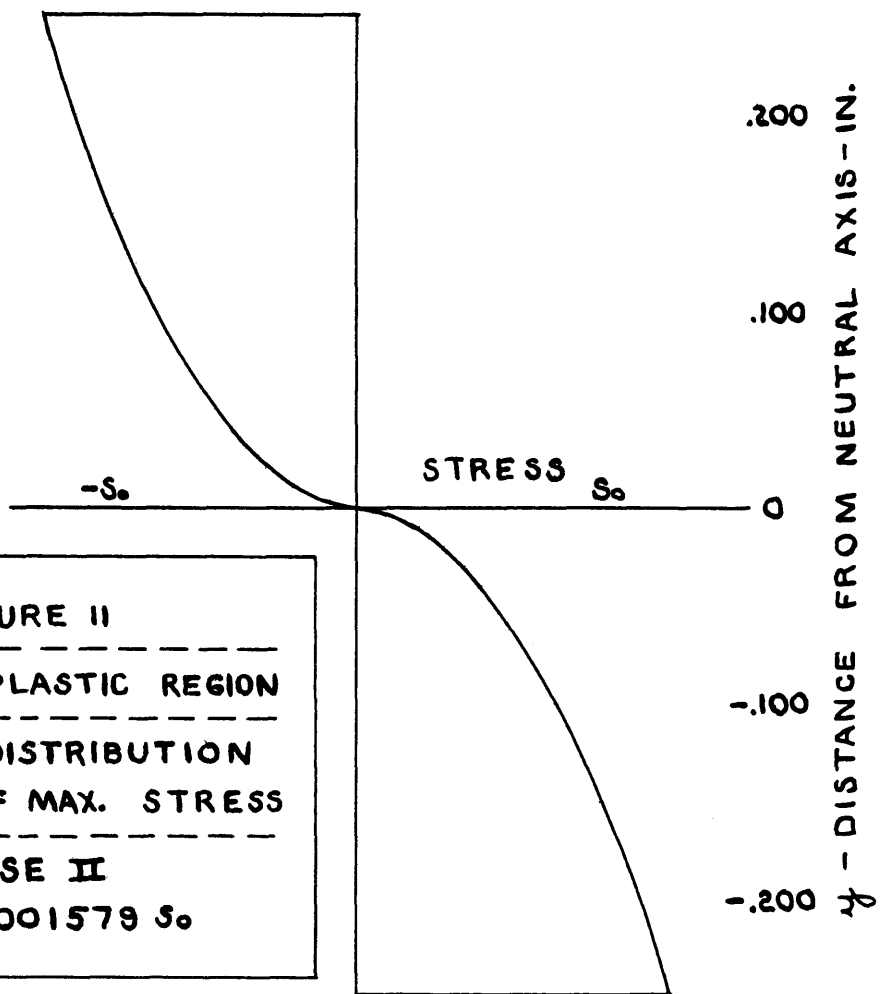
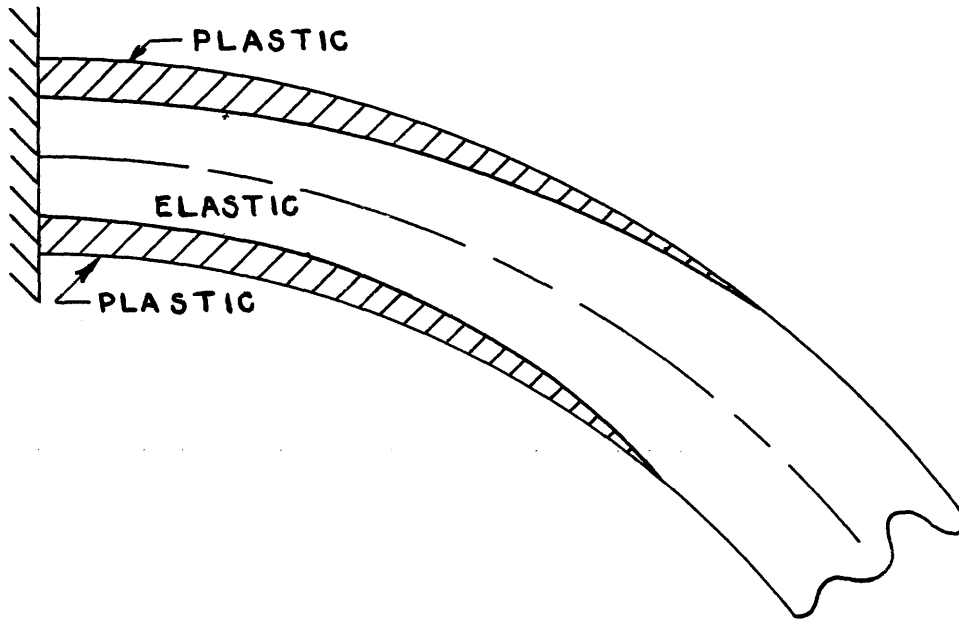


FIGURE II

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

 CASE II
 $P = 0.001579 S_0$

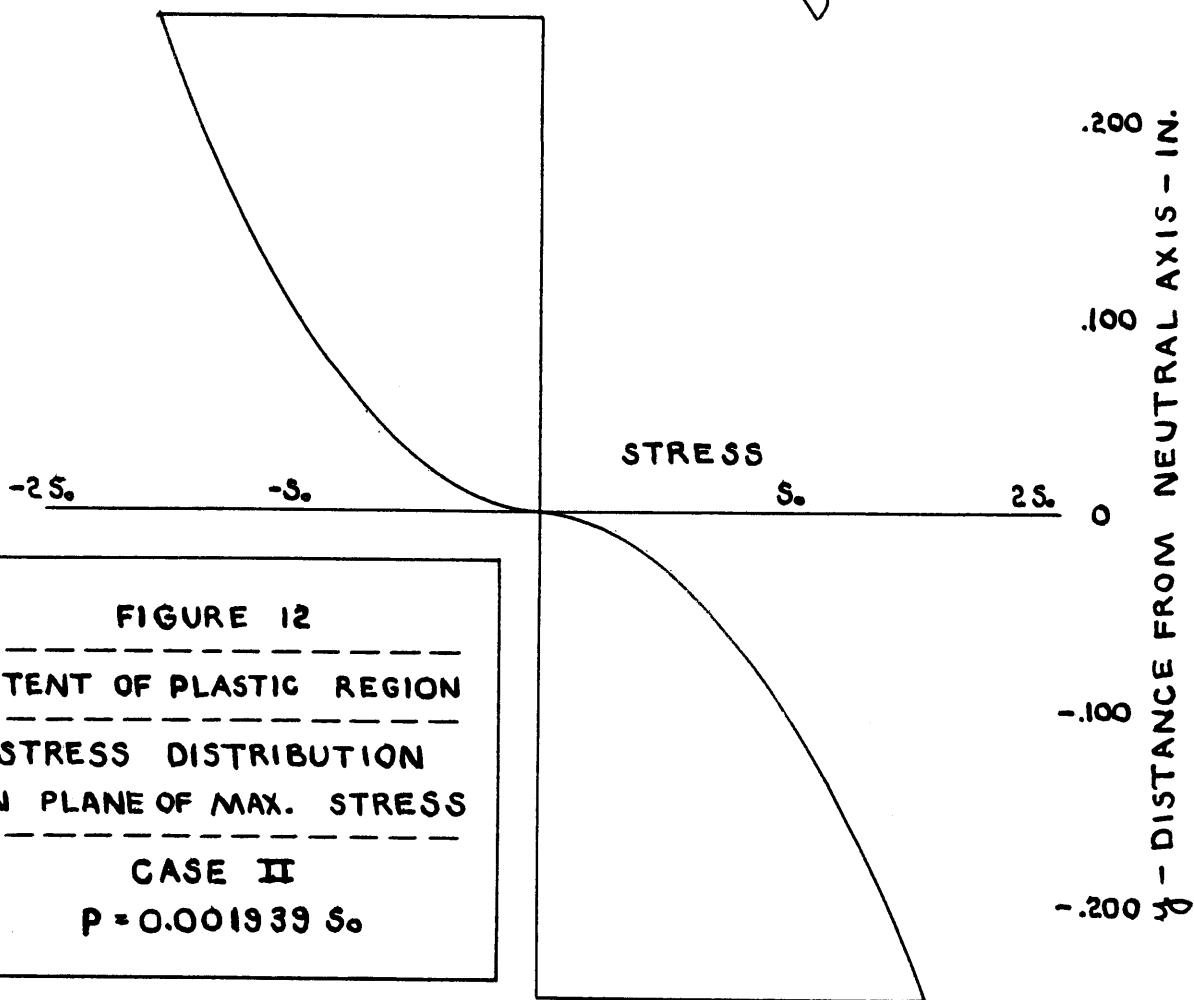
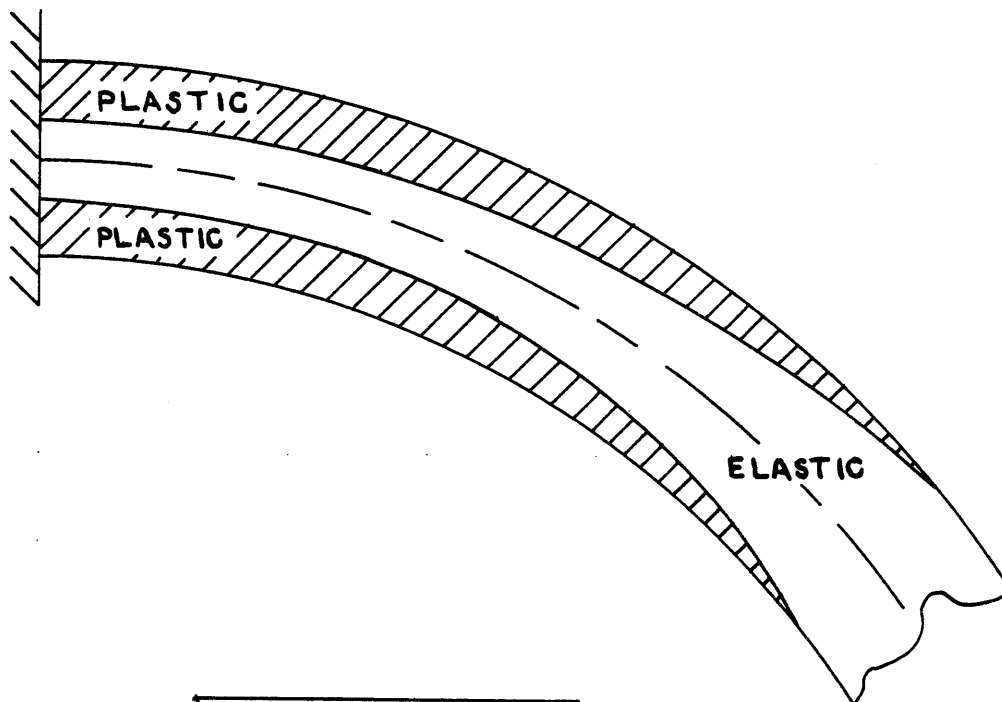
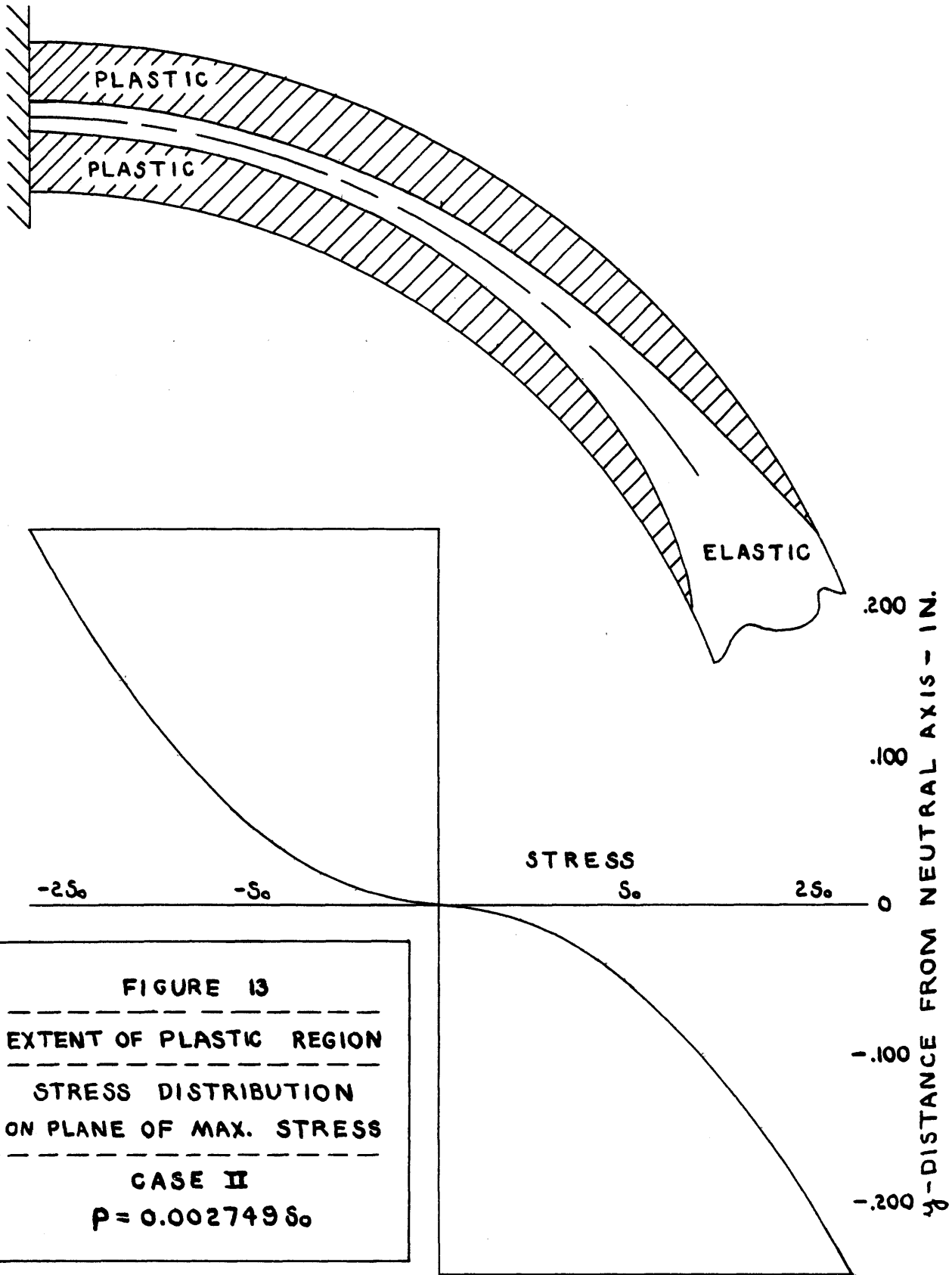


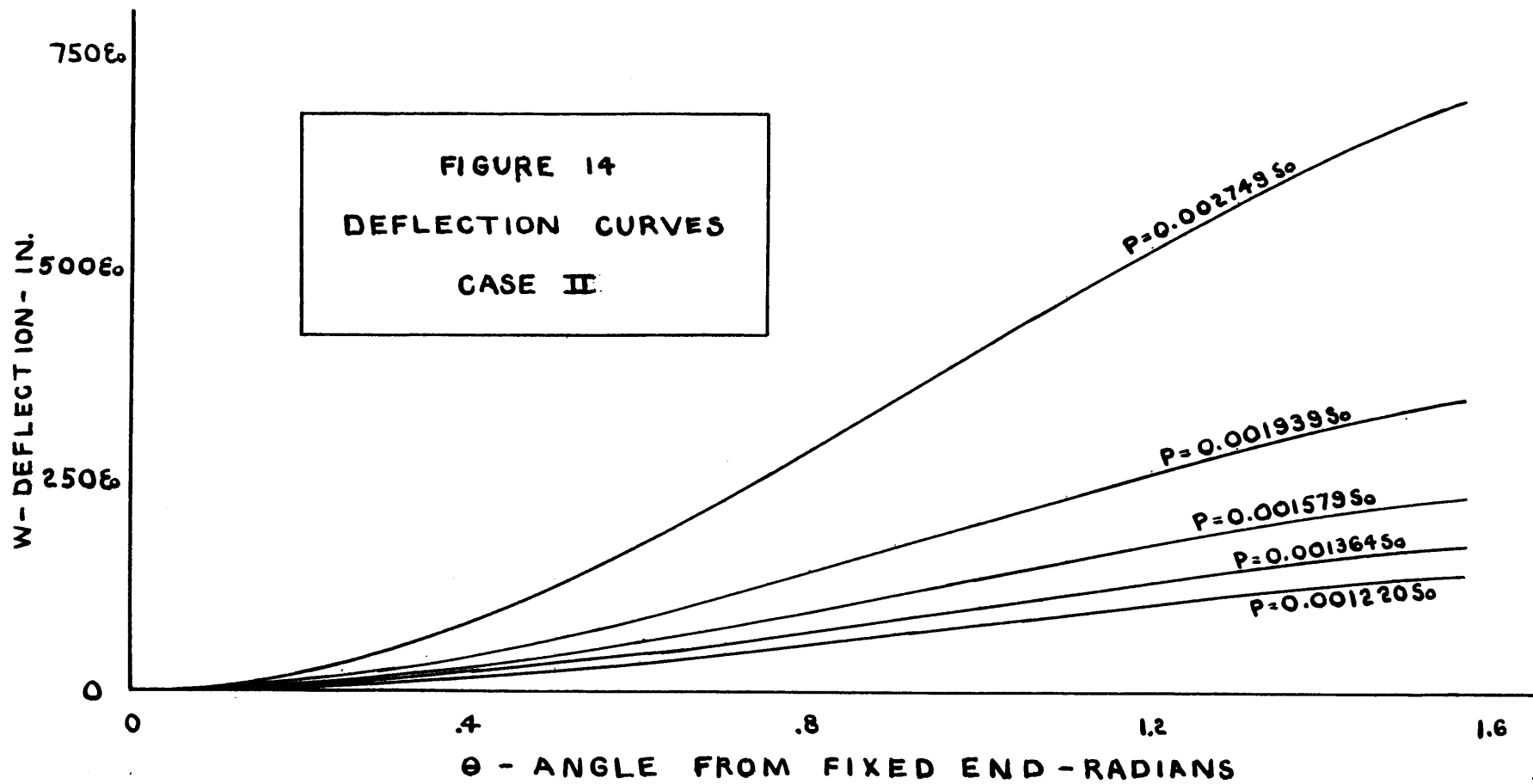
FIGURE 12

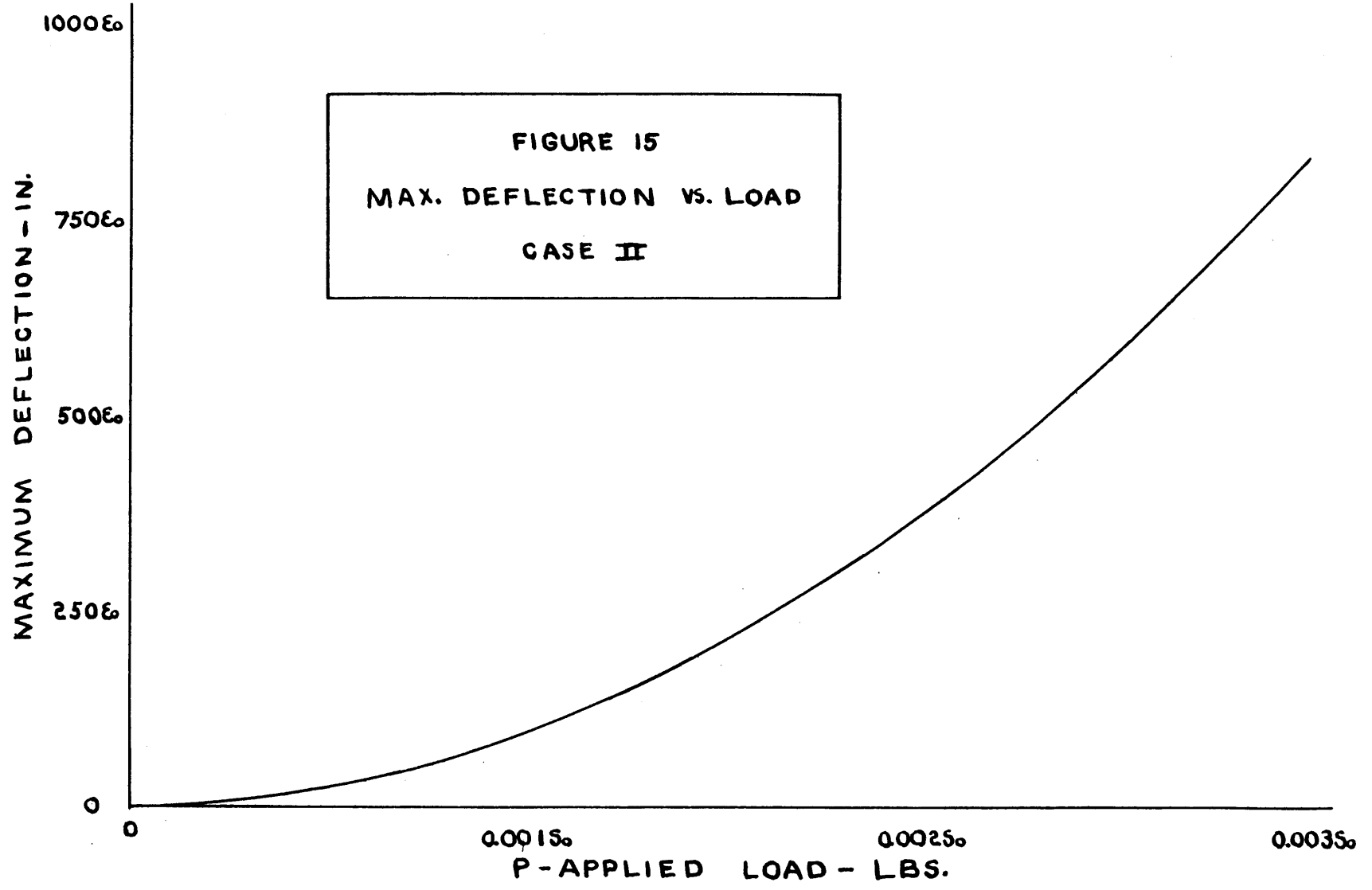
EXTENT OF PLASTIC REGION

STRESS DISTRIBUTION
ON PLANE OF MAX. STRESS

CASE II
 $P = 0.001939 S_0$





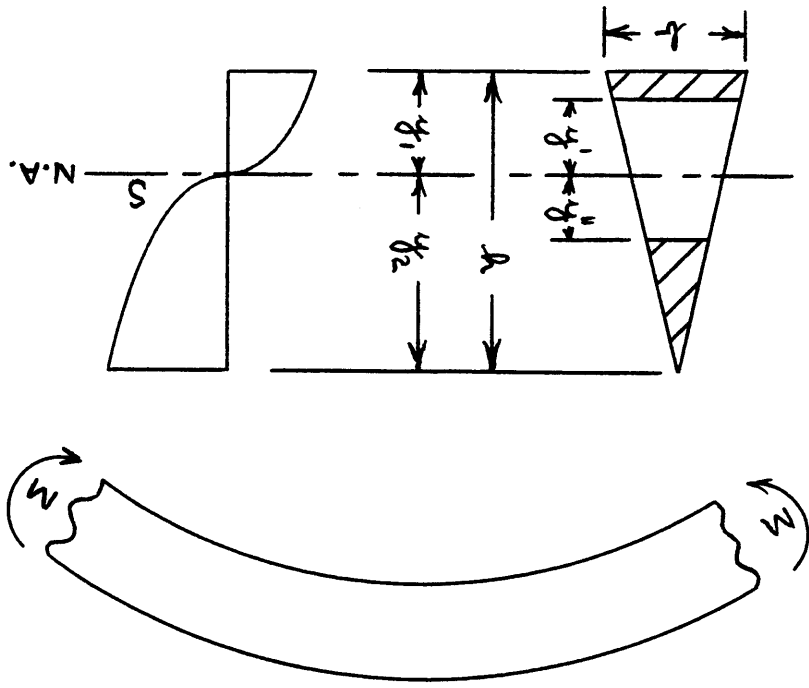


Case III

Consider a curved bar of triangular cross-section
with depth of beam small
in comparison with the radius of curvature
and a stress-strain curve of the form

$$S = S_0 \left(\frac{2\varepsilon}{\varepsilon_0} \right)^{\frac{1}{2}}$$

$$\begin{aligned}
 \text{Let } R &= S_0 \left[\frac{\epsilon_0}{2} \left(\frac{\epsilon_0}{\rho - R} \right) \right]_{\frac{2t}{R}} \\
 S &= -S_0 \left[\frac{\epsilon_0}{2} \left(\frac{\epsilon_0}{\rho - R} \right) \left(\frac{\epsilon_0}{\rho - R} \right) \right]_{\frac{2t}{R}} \quad \text{For } -y \\
 S &= S_0 \left[\frac{\epsilon_0}{2} \left(\frac{\epsilon_0}{\rho - R} \right) \left(\frac{\epsilon_0}{\rho - R} \right) \right]_{\frac{2t}{R}} \quad \text{For } +y \\
 \epsilon &= \left(\frac{\epsilon_0 - R}{\rho - R} \right) \left(\frac{\epsilon_0 + y}{\rho} \right) \\
 S &= -S_0 \left(\frac{\epsilon_0}{2\epsilon} \right) \quad \text{For } -\epsilon \\
 S &= S_0 \left(\frac{\epsilon_0}{2\epsilon} \right) \quad \text{For } +\epsilon
 \end{aligned}$$



$$\int S dA = 0$$

$$dA = Z dy$$

$$dA = \frac{b}{h} (y_2 - y) dy$$

$$\int_{y_1}^0 -k \left(\frac{-y}{\epsilon_0 + y} \right)^{\frac{1}{2}} \frac{b}{h} (y_2 - y) dy + \int_0^{y_2} k \left(\frac{y}{\epsilon_0 + y} \right)^{\frac{1}{2}} \frac{b}{h} (y_2 - y) dy = 0$$

$$-\frac{kb}{h} \left[\int_{y_1}^0 y_2 \left(\frac{-y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy - \int_{y_1}^0 y \left(\frac{-y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy \right]$$

$$+ \frac{kb}{h} \left[\int_0^{y_2} y_2 \left(\frac{y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy - \int_0^{y_2} y \left(\frac{y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy \right] = 0$$

$$\left[y_2 \int_{y_1}^0 \left(\frac{-y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy - \int_{y_1}^0 y \left(\frac{-y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy \right] =$$

$$\left[y_2 \int_0^{y_2} \left(\frac{y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy - \int_0^{y_2} y \left(\frac{y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy \right]$$

$$y_2 \left[\sqrt{-y} \sqrt{\epsilon_0 + y} - \epsilon_0 \sin^{-1} \sqrt{\frac{-y}{\epsilon_0}} \right]_{y_1}^0$$

$$- \left[-\frac{\sqrt{-y}^3 \sqrt{\epsilon_0 + y}}{2} + \frac{3\epsilon_0}{4} \left(-\sqrt{-y} \sqrt{\epsilon_0 + y} + \epsilon_0 \sinh^{-1} \sqrt{\frac{-y}{\epsilon_0}} \right) \right]_{y_1}^0 =$$

$$y_2 \left[\sqrt{y} \sqrt{\epsilon_0 + y} - \epsilon_0 \sinh^{-1} \sqrt{\frac{y}{\epsilon_0}} \right]_0^{y_2}$$

$$- \left[\frac{\sqrt{y}^3 \sqrt{\epsilon_0 + y}}{2} - \frac{3\epsilon_0}{4} \left(\sqrt{y} \sqrt{\epsilon_0 + y} - \epsilon_0 \sinh^{-1} \sqrt{\frac{y}{\epsilon_0}} \right) \right]_0^{y_2}$$

$$\begin{aligned}
& -y_2 \left[\sqrt{-y_1} \sqrt{e_0 + y_1} - e_0 \sin^{-1} \sqrt{\frac{-y_1}{e_0}} \right] \\
& + \left[\frac{-\sqrt{-y_1^3} \sqrt{e_0 + y_1}}{2} + \frac{3e_0}{4} \left(-\sqrt{-y_1} \sqrt{e_0 + y_1} + e_0 \sin^{-1} \sqrt{\frac{-y_1}{e_0}} \right) \right] = \\
& y_2 \left[\sqrt{y_2} \sqrt{e_0 + y_2} - e_0 \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right] \\
& - \left[\frac{\sqrt{y_2^3} \sqrt{e_0 + y_2}}{2} - \frac{3e_0}{4} \left(\sqrt{y_2} \sqrt{e_0 + y_2} - e_0 \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) \right] \\
& \left(y_2 e_0 + \frac{3}{4} e_0^2 \right) \left(\sin^{-1} \sqrt{\frac{-y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) = \\
& \left(y_2 + \frac{3}{4} e_0 \right) \left(\sqrt{-y_1} \sqrt{e_0 + y_1} + \sqrt{y_2} \sqrt{e_0 + y_2} \right) - \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{e_0 + y_2} - \sqrt{-y_1^3} \sqrt{e_0 + y_1} \right) \\
e_0 = & \frac{\left(y_2 + \frac{3}{4} e_0 \right) \left(\sqrt{-y_1} \sqrt{e_0 + y_1} + \sqrt{y_2} \sqrt{e_0 + y_2} \right) - \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{e_0 + y_2} - \sqrt{-y_1^3} \sqrt{e_0 + y_1} \right)}{\left(y_2 + \frac{3}{4} e_0 \right) \left(\sin^{-1} \sqrt{\frac{-y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right)} \quad \text{EQUATION 24}
\end{aligned}$$

Using absolute values, Equation 24 becomes

$$e_0 = \frac{\left(y_2 + \frac{3}{4} e_0 \right) \left(\sqrt{-y_1} \sqrt{R_i} + \sqrt{y_2} \sqrt{R_o} \right) - \frac{1}{2} \left(\sqrt{y_2^3} \sqrt{R_o} - \sqrt{-y_1^3} \sqrt{R_i} \right)}{\left(y_2 + \frac{3}{4} e_0 \right) \left(\sin^{-1} \sqrt{\frac{-y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right)} \quad \text{EQUATION 24a}$$

This expression is used to determine the position of the neutral axis. A trial and error solution is recommended since the expression is not readily solvable by algebraic means.

$$M = \int S_y dA$$

$$M = \int_{y_1}^0 -k \left(\frac{-y}{\epsilon_0 + y} \right)^{\frac{1}{2}} y \frac{b}{a} (y_2 - y) dy + \int_0^{y_2} k \left(\frac{y}{\epsilon_0 + y} \right)^{\frac{1}{2}} y \frac{b}{a} (y_2 - y) dy$$

$$M = \frac{kb}{a} \left[-y_2 \int_{y_1}^0 y \left(\frac{-y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy + \int_{y_1}^0 y^2 \left(\frac{-y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy \right. \\ \left. + y_2 \int_0^{y_2} y \left(\frac{y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy - \int_0^{y_2} y^2 \left(\frac{y}{\epsilon_0 + y} \right)^{\frac{1}{2}} dy \right]$$

$$M = \frac{kb}{a} \left[-y_2 \left\{ \frac{-\sqrt{-y^3} \sqrt{\epsilon_0 + y}}{2} - \frac{3\epsilon_0 \sqrt{-y} \sqrt{\epsilon_0 + y}}{4} + \frac{3\epsilon_0^2 \sin^{-1} \sqrt{\frac{-y}{\epsilon_0}}}{4} \right\} \right]_0^{y_1} \\ - \left\{ \frac{-\sqrt{-y^5} \sqrt{\epsilon_0 + y}}{3} - \frac{5\epsilon_0 \sqrt{-y^3} \sqrt{\epsilon_0 + y}}{12} - \frac{5\epsilon_0^2 \sqrt{-y} \sqrt{\epsilon_0 + y}}{8} + \frac{5\epsilon_0^3 \sin^{-1} \sqrt{\frac{-y}{\epsilon_0}}}{8} \right\} \right]_0^{y_1} \\ + y_2 \left\{ \frac{\sqrt{y^3} \sqrt{\epsilon_0 + y}}{2} - \frac{3\epsilon_0 \sqrt{y} \sqrt{\epsilon_0 + y}}{4} + \frac{3\epsilon_0^2 \sinh^{-1} \sqrt{\frac{y}{\epsilon_0}}}{4} \right\} \right]_0^{y_2} \\ - \left\{ \frac{\sqrt{y^5} \sqrt{\epsilon_0 + y}}{3} - \frac{5\epsilon_0 \sqrt{y^3} \sqrt{\epsilon_0 + y}}{12} + \frac{5\epsilon_0^2 \sqrt{y} \sqrt{\epsilon_0 + y}}{8} - \frac{5\epsilon_0^3 \sinh^{-1} \sqrt{\frac{y}{\epsilon_0}}}{8} \right\} \right]_0^{y_2}$$

$$\begin{aligned}
M = \frac{hb}{h} & \left[-\frac{y_2 \sqrt{-y_1^3} \sqrt{e_0 + y_1}}{2} - \frac{3e_0 y_2^2 \sqrt{-y_1} \sqrt{e_0 + y_1}}{4} \right. \\
& + \frac{3e_0^2 y_2^2 \sin^{-1} \sqrt{\frac{-y_1}{e_0}}}{4} - \frac{\sqrt{-y_1^5} \sqrt{e_0 + y_1}}{3} \\
& - \frac{5e_0 \sqrt{y_1^3} \sqrt{e_0 + y_1}}{12} - \frac{5e_0^2 \sqrt{-y_1} \sqrt{e_0 + y_1}}{8} \\
& + \frac{5e_0^3 \sin^{-1} \sqrt{\frac{-y_1}{e_0}}}{8} + \frac{y_2 \sqrt{y_2^3} \sqrt{e_0 + y_2}}{2} \\
& - \frac{3e_0 y_2^2 \sqrt{y_2} \sqrt{e_0 + y_2}}{4} + \frac{3e_0^2 y_2^2 \sinh^{-1} \sqrt{\frac{y_2}{e_0}}}{4} \\
& - \frac{\sqrt{y_2^5} \sqrt{e_0 + y_2}}{3} + \frac{5e_0 \sqrt{y_2^3} \sqrt{e_0 + y_2}}{12} \\
& \left. - \frac{5e_0^2 \sqrt{y_2} \sqrt{e_0 + y_2}}{8} + \frac{5e_0^3 \sinh^{-1} \sqrt{\frac{y_2}{e_0}}}{8} \right]
\end{aligned}$$

$$\begin{aligned}
M = S_0 & \left[\left(\frac{2}{\epsilon_0} \left(\frac{e_0 - e}{e} \right) \right)^{\frac{1}{2}} \frac{d}{h} \left[\left(\frac{3e_0^2 y_2^2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{-y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) \right. \right. \\
& + \left(\frac{y_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{y_2^3} \sqrt{e_0 + y_2} - \sqrt{-y_1^3} \sqrt{e_0 + y_1} \right) \\
& - \left(\frac{3e_0 y_2^2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{y_2} \sqrt{e_0 + y_2} + \sqrt{-y_1} \sqrt{e_0 + y_1} \right) \\
& \left. - \frac{1}{3} \left(\sqrt{y_2^5} \sqrt{e_0 + y_2} + \sqrt{-y_1^5} \sqrt{e_0 + y_1} \right) \right]
\end{aligned}$$

EQUATION 25

Using absolute values, Equation 25 becomes

$$\begin{aligned}
 M = S_0 & \left[\left(\frac{2}{\epsilon_0} \right) \left(\frac{c_0 - l}{c} \right)^{\frac{1}{2}} \ln \left[\left(\frac{3e_0^2 y^2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{y_1}{c_0}} + \sinh^{-1} \sqrt{\frac{y_2}{c_0}} \right) \right. \right. \\
 & + \left(\frac{y_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_1} \right) - \frac{1}{3} \left(\sqrt{y_2^5} \sqrt{R_0} + \sqrt{y_1^5} \sqrt{R_1} \right) \\
 & \left. \left. - \left(\frac{3e_0 y_2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_1} \right) \right] \quad \text{EQUATION 25a}
 \end{aligned}$$

Care must be taken to use a high degree of accuracy when evaluating the expression in Equation 25 (or 25a) contained in the brackets since it involves the very small difference of two comparatively large numbers.

$$\begin{aligned}
 S &= \pm S_0 \left[\left(\frac{2}{\epsilon_0} \right) \left(\frac{c_0 - l}{c} \right) \left(\frac{\pm y}{c_0 + y} \right) \right]^{\frac{1}{2}} \\
 S &= \frac{\pm M R \left(\frac{\pm y}{c_0 + y} \right)^{\frac{1}{2}}}{\ln \left[\left(\frac{3e_0^2 y^2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{y_1}{c_0}} + \sinh^{-1} \sqrt{\frac{y_2}{c_0}} \right) - \frac{1}{3} \left(\sqrt{y_2^5} \sqrt{R_0} + \sqrt{y_1^5} \sqrt{R_1} \right) \right.} \\
 & \left. + \left(\frac{y_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_1} \right) - \left(\frac{3e_0 y_2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_1} \right) \right] \\
 & \hspace{15em} \text{EQUATION 26}
 \end{aligned}$$

When using Equation 26, the signs apply to values of y , the - signs to - values of y .

From Equation 25a

$$\frac{e_0 - e}{e} = \frac{M^2 h^2 \epsilon_0}{2S_0^2 b^2 \left[\left(\frac{3e_0^2 \gamma_2^2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{\gamma_1}{\epsilon_0}} + \sinh^{-1} \sqrt{\frac{\gamma_2}{\epsilon_0}} \right) \right.}$$

$$+ \left(\frac{\gamma_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{\gamma_2^3} \sqrt{R_0} - \sqrt{\gamma_1^3} \sqrt{R_i} \right) - \frac{1}{3} \left(\sqrt{\gamma_2^5} \sqrt{R_0} + \sqrt{\gamma_1^5} \sqrt{R_i} \right)$$

$$\left. - \left(\frac{3e_0 \gamma_2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{\gamma_2} \sqrt{R_0} + \sqrt{\gamma_1} \sqrt{R_i} \right) \right]^2$$

Substituting in Equation 10

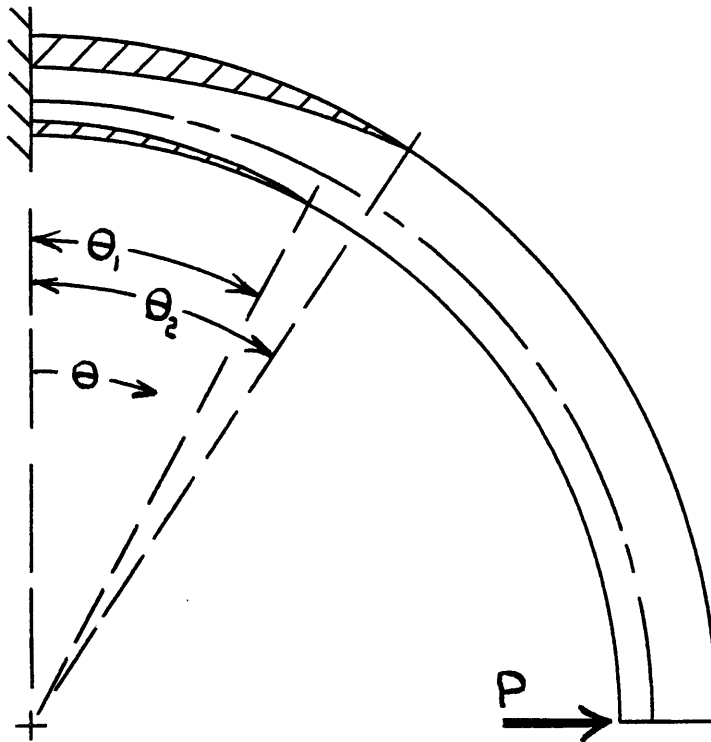
$$\frac{d^2 w}{d\theta^2} + w = \frac{e_0 M^2 h^2 \epsilon_0}{2S_0^2 b^2 \left[\left(\frac{3e_0^2 \gamma_2^2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{\gamma_1}{\epsilon_0}} + \sinh^{-1} \sqrt{\frac{\gamma_2}{\epsilon_0}} \right) \right.}$$

$$+ \left(\frac{\gamma_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{\gamma_2^3} \sqrt{R_0} - \sqrt{\gamma_1^3} \sqrt{R_i} \right) - \frac{1}{3} \left(\sqrt{\gamma_2^5} \sqrt{R_0} + \sqrt{\gamma_1^5} \sqrt{R_i} \right)$$

$$\left. - \left(\frac{3e_0 \gamma_2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{\gamma_2} \sqrt{R_0} + \sqrt{\gamma_1} \sqrt{R_i} \right) \right]^2$$

EQUATION 27

Calculations for the Specific Case (Figure 1)



$$M = -P e_o \cos \theta$$

$$b = 0.025''$$

A trial and error solution
of Equation 24a yields the
result that

$$h = 0.500''$$

$$R_o = 10.500''$$

$$R_i = 10.000''$$

$$e_o = 10.165''$$

By the substitution of $M = -P e_o \cos \theta$ in Equation 26

$$S = \frac{-P e_o \cos \theta h \left(\frac{1 + \nu}{e_o + y} \right)^{\frac{1}{2}}}{\ln \left[\left(\frac{3e_o^2 y^2 + 5e_o^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{y_1}{e_o}} + \sin^{-1} \sqrt{\frac{y_2}{e_o}} \right) - \frac{1}{3} \left(\sqrt{y_2^5} \sqrt{R_o} + \sqrt{y_1^5} \sqrt{R_i} \right) \right.}$$

$$\left. + \left(\frac{y_2}{2} + \frac{5e_o}{12} \right) \left(\sqrt{y_2^3} \sqrt{R_o} - \sqrt{y_1^3} \sqrt{R_i} \right) - \left(\frac{3e_o y_2}{4} + \frac{5e_o^2}{8} \right) \left(\sqrt{y_2} \sqrt{R_o} + \sqrt{y_1} \sqrt{R_i} \right) \right]$$

EQUATION 26a

Evaluating

$$\left[\left(\frac{3e_0^2 y_2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{y_1}{c_0}} + \sinh^{-1} \sqrt{\frac{y_2}{c_0}} \right) - \frac{1}{3} \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right. \\ \left. + \left(\frac{y_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{y_2} \sqrt{R_0} - \sqrt{y_1} \sqrt{R_i} \right) - \left(\frac{3e_0 y_2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right] = 0.00400$$

Initial Yielding

From Equation 26a, $S = -S_0$, $y = y'' = y_2$

$$M_1 = -0.01120 S_0 \text{ in-lb}$$

$$P = 0.001102 S_0 \text{ lb}$$

Secondary Yielding

From Equation 26a, $S = S_0$, $y = y' = y_1$

$$M_s = -0.01557 S_0 \text{ in-lb}$$

$$P = 0.001532 S_0 \text{ lb}$$

Complete Yielding

From Equation 26a, $S = S_0$, $y = y' = y'' = 0$

$$M_c = -\infty \text{ in-lb}$$

$$P = \infty \text{ lb}$$

Stress Distribution

The stress distribution at any angle θ from 0 to $\frac{\pi}{2}$ for any load P from 0 to ∞ is given by Equation 26a. This applies to both the elastic and plastic regions since the stress-strain curve also applies to both the elastic and plastic regions.

Deflection Equation

Substitution of $M = -P e_0 \cos \theta$ and $\cos^2 \theta = \frac{\cos 2\theta + 1}{2}$ in Equation 27 yields

$$\frac{d^2 w}{d\theta^2} + w = \frac{P^2 e_0^3 \epsilon_0 h^2 (\cos 2\theta + 1)}{4 S_0^2 b^2 \left[\left(\frac{3e_0^2 y_2^2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) + \left(\frac{y_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_i} \right) - \frac{1}{3} \left(\sqrt{y_2^5} \sqrt{R_0} + \sqrt{y_1^5} \sqrt{R_i} \right) - \left(\frac{3e_0 y_2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right]^2}$$

Complementary Solution

$$W = C_1 \sin \theta + C_2 \cos \theta$$

Particular Solution

$$W = \frac{-P^2 e_0^3 h^2 \epsilon_0 \left(\frac{\cos 2\theta}{3} - 1 \right)}{4 S_0^2 b^2 \left[\left(\frac{3e_0^2 y_2^2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{y_1}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) + \left(\frac{y_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_i} \right) - \frac{1}{3} \left(\sqrt{y_2^5} \sqrt{R_0} + \sqrt{y_1^5} \sqrt{R_i} \right) - \left(\frac{3e_0 y_2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right]^2}$$

General Solution

$$W = C_1 \sin \theta + C_2 \cos \theta - \frac{P^2 e_0^3 h^2 \epsilon_0 \left(\frac{\cos 2\theta}{3} - 1 \right)}{4 S_0^2 b^2 \left[\left(\frac{3e_0^2 \gamma^2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{\gamma_1}{\epsilon_0}} + \sinh^{-1} \sqrt{\frac{\gamma_2}{\epsilon_0}} \right) + \left(\frac{\gamma_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{\gamma_2^3} \sqrt{R_0} - \sqrt{\gamma_1^3} \sqrt{R_i} \right) - \frac{1}{3} \left(\sqrt{\gamma_2^5} \sqrt{R_0} + \sqrt{\gamma_1^5} \sqrt{R_i} \right) - \left(\frac{3e_0 \gamma^2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{\gamma_2} \sqrt{R_0} + \sqrt{\gamma_1} \sqrt{R_i} \right) \right]^2}$$

Boundary Conditions

$$\theta = 0, \quad W = 0, \quad \frac{dW}{d\theta} = 0$$

Evaluation of C_1 and C_2

$$C_1 = 0$$

$$C_2 = - \frac{P^2 e_0^3 h^2 \epsilon_0}{6 S_0^2 b^2 \left[\left(\frac{3e_0^2 \gamma^2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{\gamma_1}{\epsilon_0}} + \sinh^{-1} \sqrt{\frac{\gamma_2}{\epsilon_0}} \right) + \left(\frac{\gamma_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{\gamma_2^3} \sqrt{R_0} - \sqrt{\gamma_1^3} \sqrt{R_i} \right) - \frac{1}{3} \left(\sqrt{\gamma_2^5} \sqrt{R_0} + \sqrt{\gamma_1^5} \sqrt{R_i} \right) - \left(\frac{3e_0 \gamma^2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{\gamma_2} \sqrt{R_0} + \sqrt{\gamma_1} \sqrt{R_i} \right) \right]^2}$$

$$\begin{aligned}
 W = & - \frac{P^2 e_0^3 h^2 \epsilon_0 \left(\frac{2 \cos \theta}{3} + \frac{\cos 2\theta}{3} - 1 \right)}{4 S_0^2 b^2 \left[\left(\frac{3e_0^2 y_2^2}{4} + \frac{5e_0^3}{8} \right) \left(\sin^{-1} \sqrt{\frac{y_2}{e_0}} + \sinh^{-1} \sqrt{\frac{y_2}{e_0}} \right) \right.} \\
 & + \left(\frac{y_2}{2} + \frac{5e_0}{12} \right) \left(\sqrt{y_2^3} \sqrt{R_0} - \sqrt{y_1^3} \sqrt{R_i} \right) - \frac{1}{3} \left(\sqrt{y_2^5} \sqrt{R_0} + \sqrt{y_1^5} \sqrt{R_i} \right) \\
 & \left. - \left(\frac{3e_0 y_2^2}{4} + \frac{5e_0^2}{8} \right) \left(\sqrt{y_2} \sqrt{R_0} + \sqrt{y_1} \sqrt{R_i} \right) \right]^2
 \end{aligned}$$

Equation 28

This deflection equation (Equation 28) applies for all values of P from 0 to ∞ , ie, it applies over both the elastic and plastic regions. The sign of the deflection must be the same as that of the bending moment before the moment term is squared and substituted in Equation 27.

CASE IIIINITIAL YIELDING

$$(y'' = 0.335'')$$

$$M = -0.01120 \text{ So in lb}$$

$$P = 0.001102 \text{ So lb}$$

$$e_0 = 10.165 \text{ in}$$

Extent of Plastic Region

There is no plastic region.

Case III - Initial YieldingStress Distributionon Plane ofDeflection CurveMaximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.335	-1.000 So	0	0
0.300	-0.948 So	0.100	0.795 ε.
0.250	-0.867 So	0.200	3.154 ε.
0.200	-0.778 So	0.300	7.010 ε.
0.150	-0.675 So	0.400	12.24 ε.
0.100	-0.553 So	0.500	19.55 ε.
0.050	-0.392 So	0.600	26.20 ε.
0.040	-0.351 So	0.700	34.52 ε.
0.030	-0.304 So	0.800	43.43 ε.
0.020	-0.248 So	0.900	52.63 ε.
0.010	-0.176 So	1.000	62.01 ε.
0	0	1.100	71.19 ε.
-0.010	0.176 So	1.200	79.99 ε.
-0.020	0.249 So	1.300	88.20 ε.
-0.030	0.305 So	1.400	95.64 ε.
-0.040	0.352 So	1.500	102.2 ε.
-0.050	0.394 So	1.5708	106.2 ε.
-0.100	0.558 So		
-0.150	0.685 So		
-0.165	0.719 So		

CASE IIIYIELDING TO ONE SIXTH OF DEPTH OF BEAM (ON TOP)

$$(y'' = 0.255'')$$

$$M = -0.01278 \text{ So in lb}$$

$$P = 0.001258 \text{ So lb}$$

$$e_0 = 10.165 \text{ in}$$

Extent of Plastic Region

y''	θ
inches	degrees
0.255	0
0.260	7°52'
0.265	11° 4'
0.275	15°27'
0.300	22°29'
0.335	28°51'

Case III - Yielding to One-sixth of Depth of Beam

Stress Distribution

on Plane of

Deflection Curve

Maximum Stress

y	S	θ	w
inches	psi	radians	inches
0.335	-1.142 S_o	0	0
0.300	-1.082 S_o	0.100	1.036 ϵ .
0.250	-0.990 S_o	0.200	4.112 ϵ .
0.200	-0.888 S_o	0.300	9.138 ϵ .
0.150	-0.771 S_o	0.400	15.96 ϵ .
0.100	-0.631 S_o	0.500	25.43 ϵ .
0.050	-0.447 S_o	0.600	34.16 ϵ .
0.040	-0.400 S_o	0.700	45.01 ϵ .
0.030	-0.347 S_o	0.800	56.62 ϵ .
0.020	-0.283 S_o	0.900	68.62 ϵ .
0.010	-0.200 S_o	1.000	80.84 ϵ .
0	0	1.100	92.81 ϵ .
-0.010	0.201 S_o	1.200	104.3 ϵ .
-0.020	0.284 S_o	1.300	115.0 ϵ .
-0.030	0.348 S_o	1.400	124.7 ϵ .
-0.040	0.402 S_o	1.500	133.2 ϵ .
-0.050	0.449 S_o	1.5708	138.5 ϵ .
-0.100	0.637 S_o		
-0.150	0.782 S_o		
-0.165	0.821 S_o		

CASE IIISECONDARY YIELDING

$$(y' = -0.165", y'' = 0.171")$$

$$M = -0.01557 S_0 \text{ in lb}$$

$$P = 0.001532 S_0 \text{ lb}$$

$$e_0 = 10.165 \text{ in}$$

Extent of Plastic Region

y''	θ
inches	degrees
0.171	0
0.175	9° 7'
0.185	16° 6'
0.200	22° 22'
0.250	34° 0'
0.300	40° 39'
0.335	44° 1'

Case III - Secondary YieldingStress Distributionon Plane ofDeflection CurveMaximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.335	-1.391 So	0	0
0.300	-1.318 So	0.100	1.537 ε.
0.250	-1.206 So	0.200	6.099 ε.
0.200	-1.081 So	0.300	13.55 ε.
0.150	-0.939 So	0.400	23.68 ε.
0.100	-0.786 So	0.500	37.71 ε.
0.050	-0.545 So	0.600	50.67 ε.
0.040	-0.487 So	0.700	66.76 ε.
0.030	-0.422 So	0.800	83.98 ε.
0.020	-0.345 So	0.900	101.8 ε.
0.010	-0.244 So	1.000	119.9 ε.
0	0	1.100	137.7 ε.
-0.010	0.244 So	1.200	154.7 ε.
-0.020	0.346 So	1.300	170.5 ε.
-0.030	0.424 So	1.400	184.9 ε.
-0.040	0.489 So	1.500	197.6 ε.
-0.050	0.547 So	1.5708	205.4 ε.
-0.100	0.794 So		
-0.150	0.953 So		
-0.165	1.000 So		

CASE IIIYIELDING TO ONE-HALF OF DEPTH OF BEAM (ON TOP)

$$(y'' = 0.110'')$$

$$M = -0.01933 S_0 \text{ in lb}$$

$$P = 0.001902 S_0 \text{ lb}$$

$$e_0 = 10.165 \text{ in}$$

Extent of Plastic Region

y'	y''	θ
inches	inches	degrees
-0.108	0.110	0
-0.113	0.115	11°59'
-0.122	0.125	20° 9'
-0.146	0.150	30°54'
-0.165		36°21'
	0.175	37°19'
	0.200	41°51'
	0.250	48° 6'
	0.300	52°20'
	0.335	54°36'

Case III - Yielding to One-half of Depth of Beam (On Top)Stress Distributionon Plane ofDeflection CurveMaximum Stress

<u>y</u>	<u>S</u>	<u>θ</u>	<u>w</u>
inches	psi	radians	inches
0.335	-1.726 So	0	0
0.300	-1.636 So	0.100	2.369 ε.
0.250	-1.497 So	0.200	9.400 ε.
0.200	-1.343 So	0.300	20.89 ε.
0.150	-1.165 So	0.400	36.49 ε.
0.100	-0.932 So	0.500	58.12 ε.
0.050	-0.676 So	0.600	78.09 ε.
0.040	-0.605 So	0.700	102.9 ε.
0.030	-0.524 So	0.800	129.4 ε.
0.020	-0.428 So	0.900	156.9 ε.
0.010	-0.303 So	1.000	184.8 ε.
0	0	1.100	212.2 ε.
-0.010	0.303 So	1.200	238.4 ε.
-0.020	0.429 So	1.300	262.9 ε.
-0.030	0.526 So	1.400	285.0 ε.
-0.040	0.607 So	1.500	304.5 ε.
-0.050	0.680 So	1.5708	316.5 ε.
-0.100	0.963 So		
-0.150	1.183 So		
-0.165	1.241 So		

CASE IIIYIELDING TO SIX-TENTHS OF DEPTH OF BEAM (ON TOP)

$$(y'' = 0.050'')$$

$$M = -0.02859 \text{ So in lb}$$

$$P = 0.002812 \text{ So lb}$$

$$e_0 = 10.165 \text{ in}$$

Extent of Plastic Region

y'	y''	θ
inches	inches	degrees
-0.050	0.050	0
-0.054	0.055	17°30'
-0.064	0.065	28°38'
-0.074	0.075	35°10'
-0.098	0.100	44°52'
-0.146	0.150	54°32'
-0.165		57° 0'
	0.200	59°46'
	0.250	63° 9'
	0.300	65°36'
	0.335	66°56'

Case III - Yielding to Six-tenths of Depth of Beam (On Top)

Stress Distribution

on Plane of

Deflection Curve

Maximum Stress

y	S	θ	w
inches	psi	radians	inches
0.335	-2.553 So	0	0
0.300	-2.420 So	0.100	5.181 ϵ .
0.250	-2.214 So	0.200	20.56 ϵ .
0.200	-1.986 So	0.300	45.69 ϵ .
0.150	-1.724 So	0.400	79.81 ϵ .
0.100	-1.411 So	0.500	127.1 ϵ .
0.050	-1.000 So	0.600	170.8 ϵ .
0.040	-0.895 So	0.700	225.0 ϵ .
0.030	-0.775 So	0.800	283.1 ϵ .
0.020	-0.633 So	0.900	343.1 ϵ .
0.010	-0.448 So	1.000	404.2 ϵ .
0	0	1.100	464.0 ϵ .
-0.010	0.449 So	1.200	521.4 ϵ .
-0.020	0.635 So	1.300	574.9 ϵ .
-0.030	0.778 So	1.400	623.4 ϵ .
-0.040	0.898 So	1.500	666.1 ϵ .
-0.050	1.005 So	1.5708	692.3 ϵ .
-0.100	1.425 So		
-0.150	1.749 So		
-0.165	1.836 So		

Case IIIMaximum Deflection

P	Wmax
lbs	inches
0	0
.0002 So	3.501 ε.
.0004 So	14.00 ε.
.0006 So	31.51 ε.
.0008 So	55.32 ε.
.0010 So	87.53 ε.
.0012 So	126.0 ε.
.0014 So	171.6 ε.
.0016 So	224.1 ε.
.0018 So	283.6 ε.
.0020 So	350.1 ε.
.0022 So	423.6 ε.
.0024 So	504.2 ε.
.0026 So	591.7 ε.
.0028 So	686.2 ε.
.0030 So	787.8 ε.

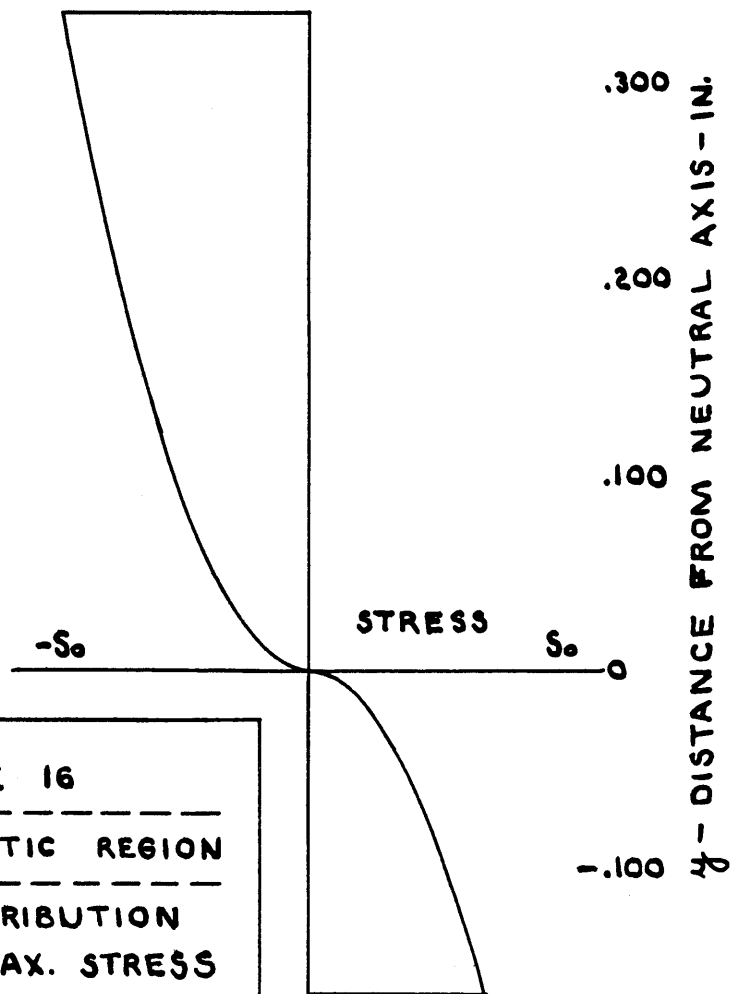
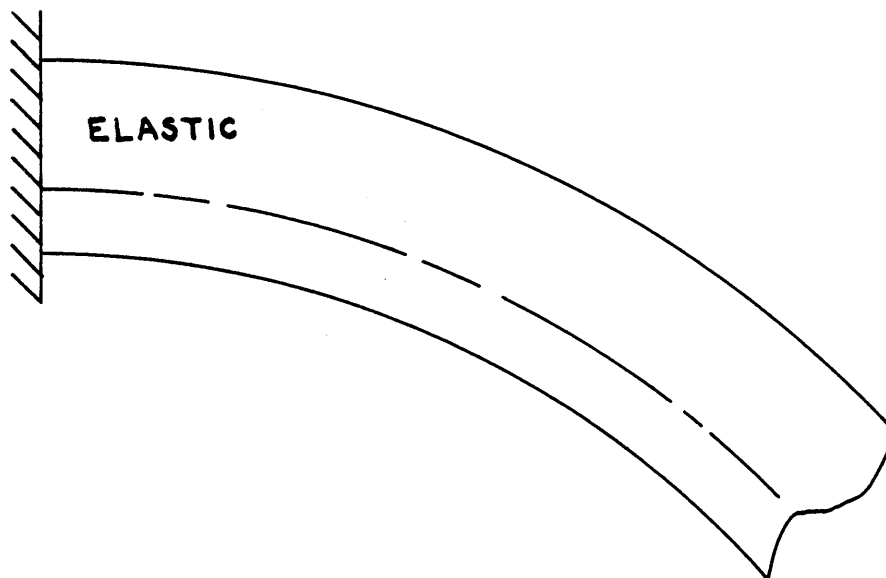


FIGURE 16

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

CASE III
 $P = 0.001102 S_0$

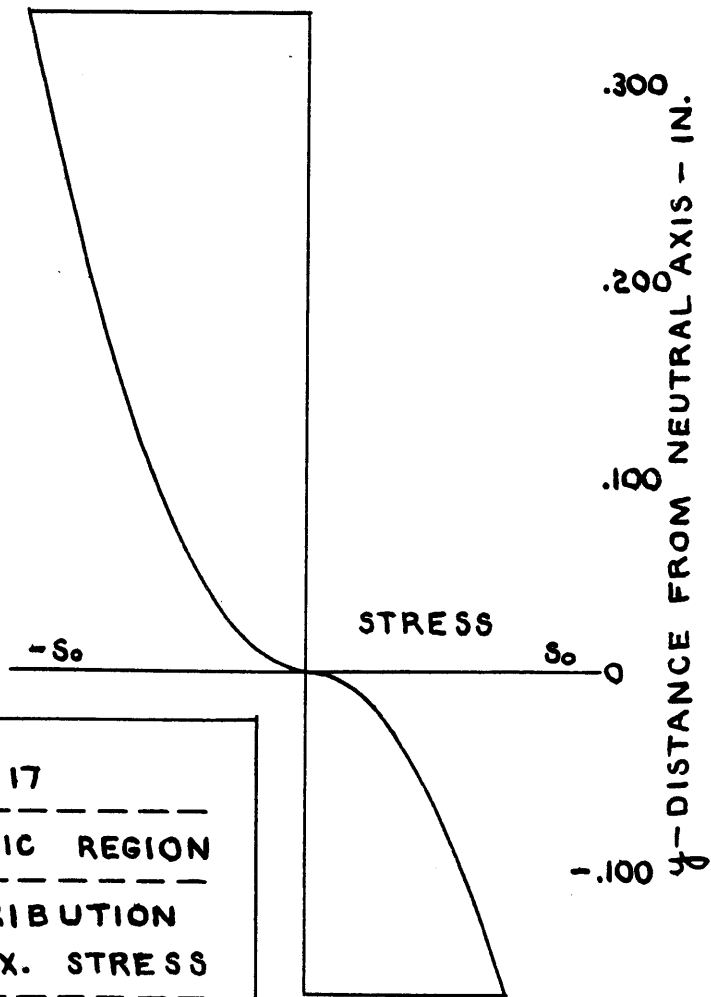
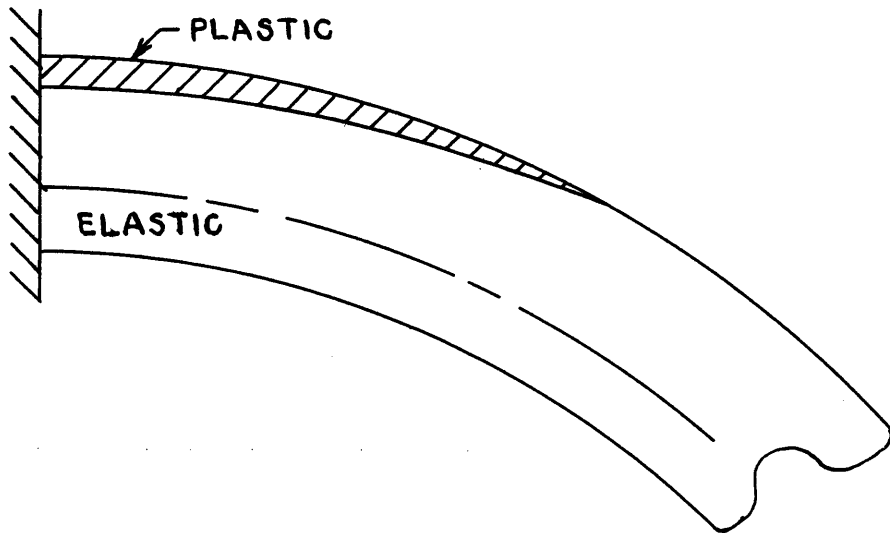


FIGURE 17

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

 CASE III
 $P = 0.001258 S_0$

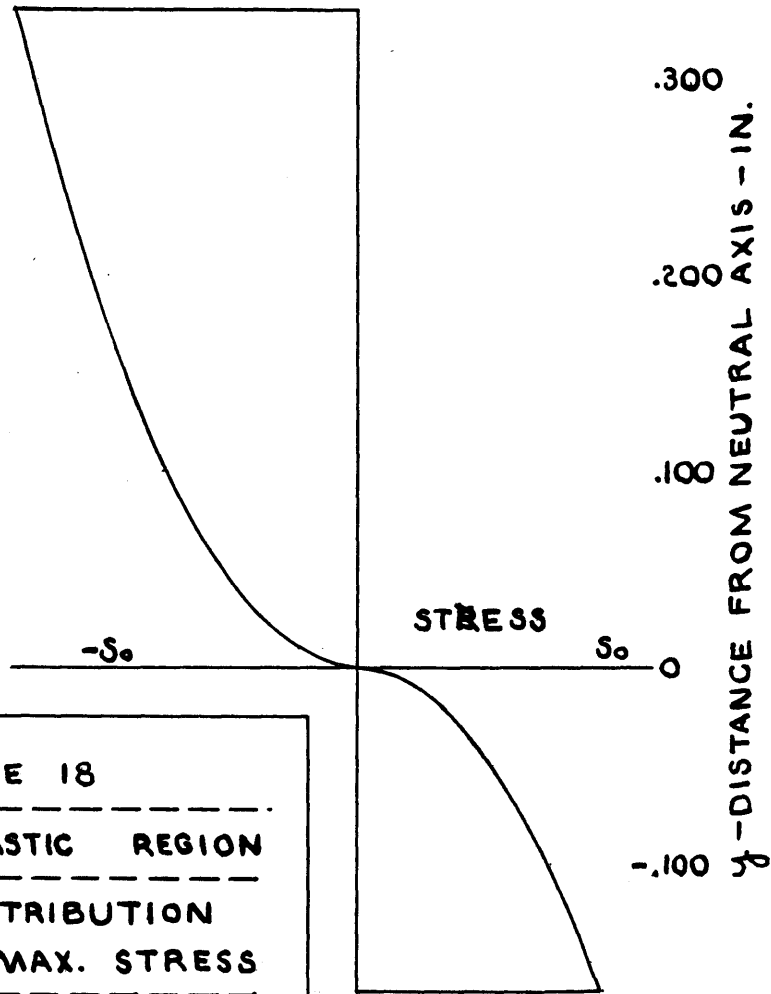
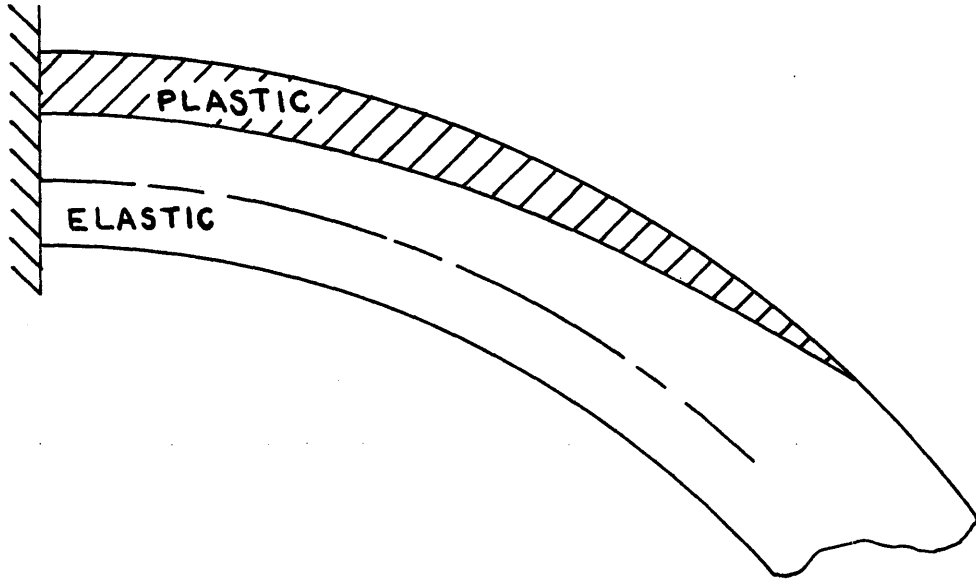


FIGURE 18

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

 CASE III
 $P = 0.001532 S_0$

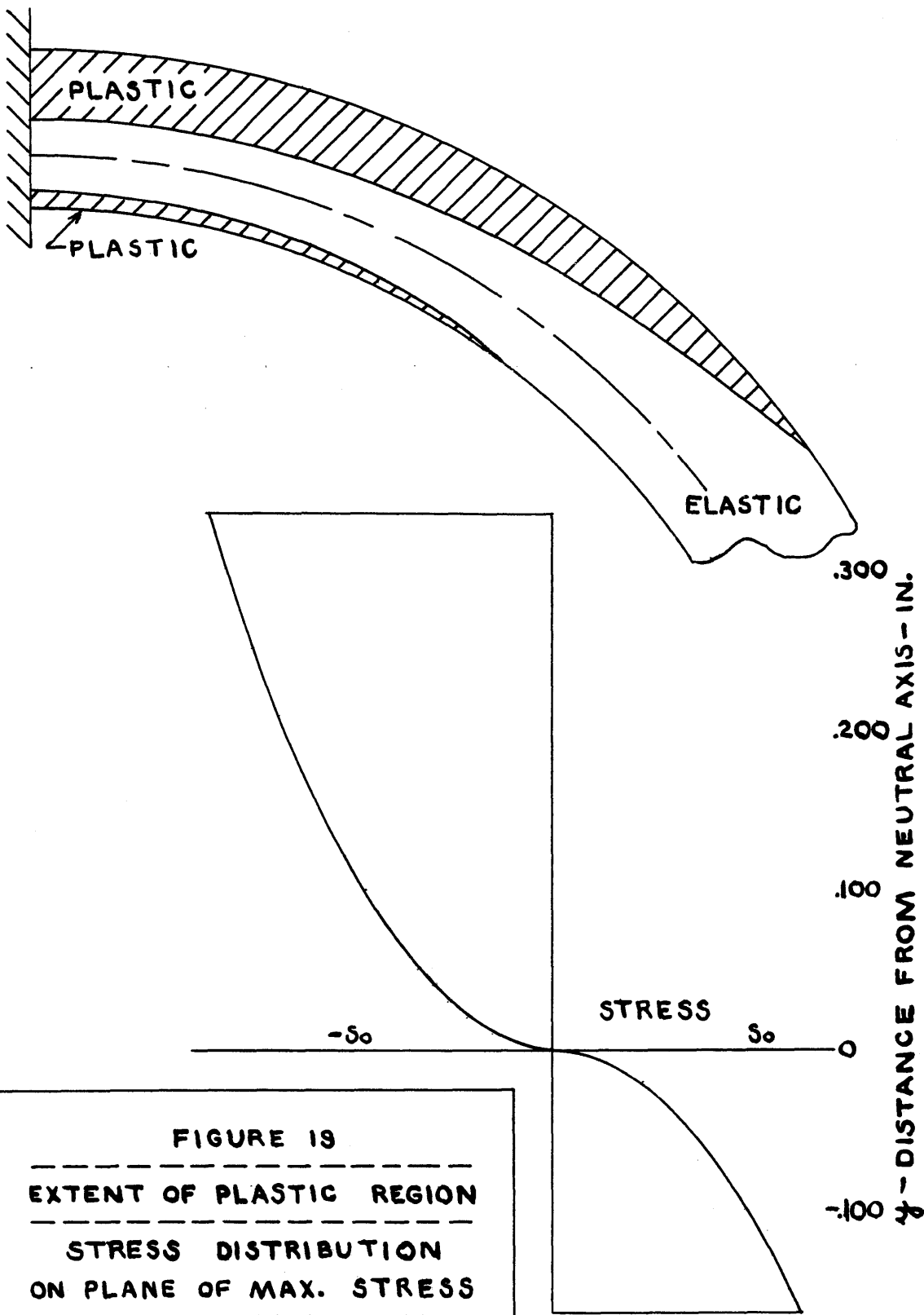


FIGURE 19

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

 CASE III
 $P = 0.001902 S_0$

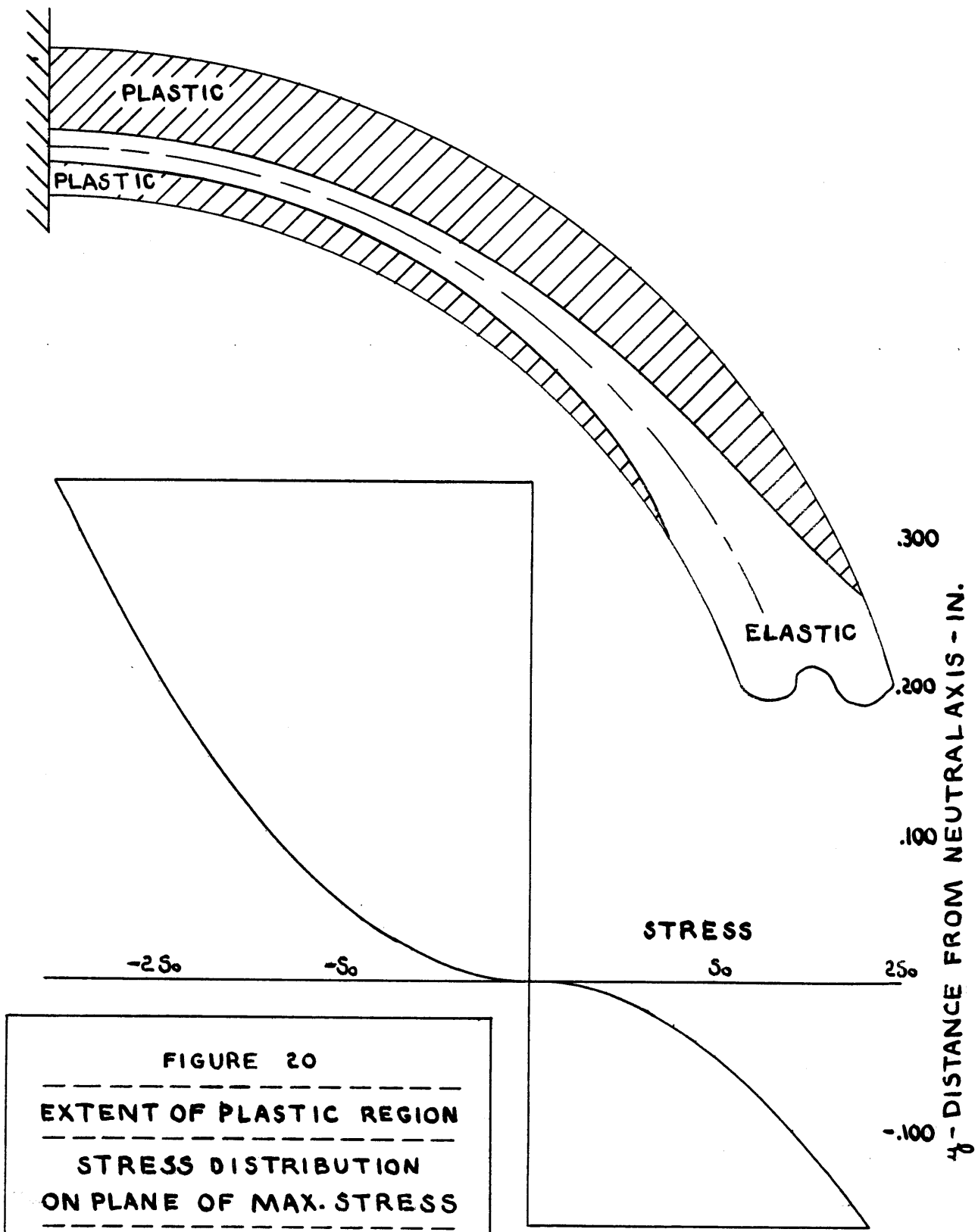
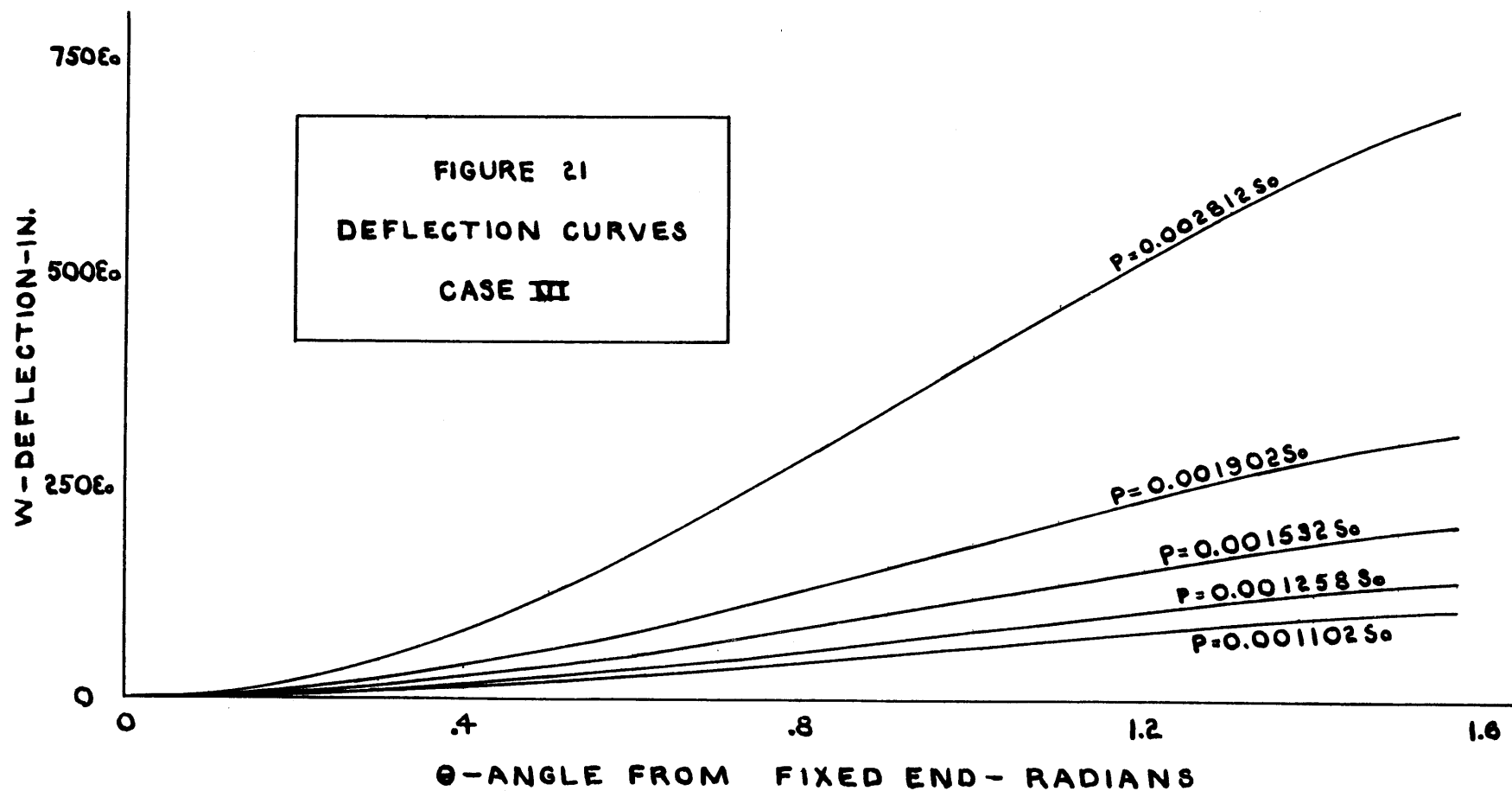


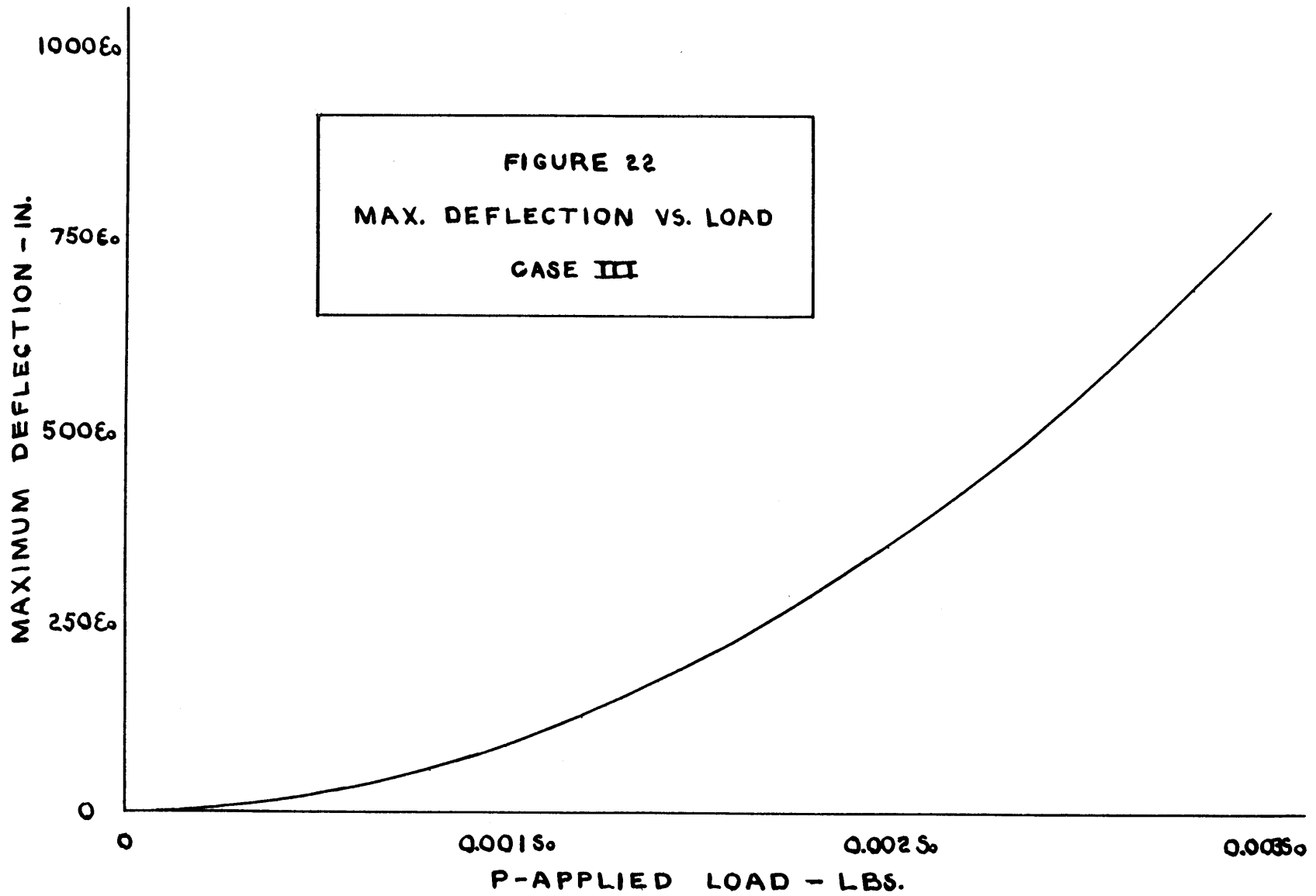
FIGURE 20

 EXTENT OF PLASTIC REGION

 STRESS DISTRIBUTION
 ON PLANE OF MAX. STRESS

 CASE III
 $P = 0.002812 S_0$





APPENDIX

B I B L I O G R A P H Y

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NOTES ON INTEGRATION

Integration of Equation 17a

$$\frac{d^2 w}{d\theta^2} + w = -e_0 \epsilon_0 \sqrt{1 + \frac{4e_0^2/3h^2}{1 - \frac{4Pe_0 \cos \theta}{S_0 b h^2}}}$$

This differential equation was integrated by the method of successive approximations using an interval in θ of 0.02 radians, which is an interval of very slightly over 1° . The three point method was chosen. The basic reason for this choice was that since some approximations had been made at various points in arriving at the equation which was being integrated the accuracy was not sufficient to warrant the use of four or five point integration. Use was made of the integrating ahead coefficients to predict points in advance. The coefficients for three point integration are:

Δ_{-1}^0	Δ_0^1	Δ_1^2
0.41667	-0.08333	0.41666
0.66666	0.66666	-1.33333
-0.08333	0.41667	1.91667

At $\theta = \theta_1$, the equation

$$w' = C_1 \sin \theta + C_2 \cos \theta - \frac{Pe_0^3 \theta \sin \theta}{2EI}$$

becomes effective. The constants, C_1 and C_2 , are evaluated from the boundary conditions that when

$$\theta = \theta_1, w = w^i, dw/d\theta = dw^i/d\theta.$$

For the case where $P = 0.001236$ So lb, $\theta_1 = 37^\circ 17'$
which is 0.65 radians.

From numerical integration

$$w = -184.99 \text{ } \epsilon.$$

$$dw/d\theta = -518.03 \text{ } \epsilon.$$

Evaluation of C_1 and C_2

$$C_1 = -495.44 \text{ } \epsilon.$$

$$C_2 = 156.88 \text{ } \epsilon.$$

For the case where $P = 0.001396$ So lb, $\theta_1 = 45^\circ 13'$
which is 0.79 radians.

From numerical integration

$$w = -360.05 \text{ } \epsilon.$$

$$dw/d\theta = -752.02 \text{ } \epsilon.$$

Evaluation of C_1 and C_2

$$C_1 = -747.86 \text{ } \epsilon.$$

$$C_2 = 266.22 \text{ } \epsilon.$$

For the case where $P = 0.001493$ So lb, $\theta_1 = 48^\circ 47'$
which is 0.85 radians.

From numerical integration

$$w = -635.30 \text{ } \epsilon.$$

$$dw/d\theta = -1072.5 \text{ } \epsilon.$$

Evaluation of C_1 and C_2

$$C_1 = -1143.6 \text{ } \epsilon.$$

$$C_2 = 369.01 \text{ } \epsilon.$$

Integration of Certain Integrals in Cases I and II

Integrals containing terms of the form $\left(\frac{c_0 + y}{c_0 + y}\right)^{\frac{1}{2}}$ can be readily integrated by substitution. For example,

consider $\int y \left(\frac{-y}{c_0 + y}\right)^{\frac{1}{2}} dy$

$$\text{LET } (-y)^{\frac{1}{2}} = x$$

$$-y = x^2$$

$$dy = -2x dx$$

$$c_0 + y = c_0 - x^2 \quad \text{LET THIS} = X$$

$$X = a + bx + cx^2$$

$$a = c_0$$

$$b = 0$$

$$c = -1$$

$$\int y \left(\frac{-y}{c_0 + y}\right)^{\frac{1}{2}} dy = 2 \int \frac{x^4 dx}{\sqrt{X}}$$

This new integral is of a form which can be readily integrated by the use of any set of integral tables.