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Eigenbehaviors: Identifying Structure in Routine

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2	Eigenbehaviors: Identifying Structure in Routine *
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24 Abstract

25 Longitudinal behavioral data generally contains a significant amount of structure. In this work we identify the 26 structure inherent in daily behavior with models that can accurately analyze, predict and cluster multimodal data 27 from individuals and communities within the social network of a population. We represent this behavioral 28 structure by the principal components of the complete behavioral dataset, a set of characteristic vectors we have 29 termed eigenbehaviors. In our model, an individual's behavior over a specific day can be approximated by a weighted sum of his or her primary eigenbehaviors. When these weights are calculated halfway through a day, 30 31 they can be used to predict the day's remaining behaviors with 79% accuracy for our test subjects. Additionally, 32 we demonstrate the potential for this dimensionality reduction technique to infer community affiliations within 33 the subjects' social network by clustering individuals into a "behavior space" spanned by a set of their aggregate 34 eigenbehaviors. These behavior spaces make it possible to determine the behavioral similarity between both 35 individuals and groups, enabling 96% classification accuracy of community affiliations within the population-36 level social network. Additionally, the distance between individuals in the behavior space can be used as an estimate for relational ties such as friendship, suggesting strong behavioral homophily amongst the subjects. This 37 approach capitalizes on the large amount of rich data previously captured during the Reality Mining study from 38 39 mobile phones continuously logging location, proximate phones, and communication of 100 subjects at MIT 40 over the course of nine months. As wearable sensors continue to generate these types of rich, longitudinal 41 datasets, dimensionality reduction techniques such as eigenbehaviors will play an increasingly important role in 42 behavioral research.

43

44 Introduction

45 While discrete observations of an individual's idiosyncratic behavior can appear almost random, 46 typically there are repeating and easily identifiable routines in every person's life. These patterns become more apparent when the behavior is temporally, spatially, and socially contextualized. However, building models of long-term behavior has been hampered due to the lack of contextualized behavioral data. Additionally, traditional Markov models work well for specific set of behaviors, but have difficulty incorporating temporal patterns across different timescales (Clarkson 2002). We present a new methodology for identifying the repeating structures underlying behavior. These structures are represented by *eigenbehaviors*, the principal components of an individual's behavioral dataset.

53

To capture these characteristic behaviors, we compute the principal components of an individual's 54 55 behavioral data. The principal components are a set of vectors that span a 'behavior space' and characterize the behavioral variation between each day. These eigenbehaviors are the eigenvectors of 56 the covariance matrix of behavior data; the heavily weighted vectors generally represent a type of 57 repeated behavior, such as sleeping in late and going out on the town. A linear combination of an 58 individual's eigenbehaviors can accurately reconstruct the behavior from each day in the data. 59 However, we show that our subjects' behavior can be approximated with 90% accuracy using only the 60 six primary eigenbehaviors – the ones that have the largest eigenvalues and account for the most 61 variance. By providing this type of behavioral caricature, it is possible for the primary eigenbehaviors 62 63 to be used to accurately predict an individual's subsequent behavior. We subsequently show how eigenbehaviors can be applied not only to individual behavior, but also be used to characterize the 64 65 behavior of communities within the population's social network. Particular groups of friends can have 66 their own collective 'behavior space' which corresponds to the common behaviors of the community. How well these behavior spaces approximate an individual's behavior depends on how the individual is 67 68 similar to others in her social network. Measuring the Euclidean distance between an individual's 69 behavior and the behavior space of a specific community within the social network can be used to 70 identify affiliations, relationships, and similarity between individuals.

There has been an extensive number of research efforts focused on modeling individual and group 72 behaviors. Due to the breadth of these efforts, we will be limited here to providing only a sample of 73 related research projects. Some closely related work in the Computer Supported Collaborative Work 74 (CSCW) community comes from Begole et al's techniques for "rhythm modeling" within the 75 76 workplace. Through analysis of the computer usage of workgroup members, Begole et al demonstrated the potential to extract patterns in behavior of both individuals and teams (Begole et. al 2003). 77 Although primarily used for location-based applications, electronic badges can also generate rich data 78 79 on individual behavior within a workplace. The exposed manner in which they are worn allows line-ofsight sensors, such as infrared (IR), to detect face-to-face interactions. Some of the earlier badge work 80 to sense human behavior was done in the 80's and early 90's at Olivetti Labs (Want et. al 1992). 81 Developments in ultrasound tracking have greatly improved the ability to localize the badge, enabling a 82 wide range of just-in-time information applications (Schilit et. al 1993; Addlesee et. al 2001). Fogarty 83 et al. expands this work by using low level sensor data to establish extremely accurate estimates of 84 human interruptibility (Fogarty et. al 2005). 85

86

87 Outside the office, GPS has been used for location detection and classification (Asbrook and Starner 2003; Liao et. al 2004; Wolf et. al 2001), but the line-of-sight requirements generally prohibit it from 88 89 working indoors. As an alternate approach, there has been a significant amount of literature regarding 90 correlating cell tower ID with a user's location (Bar-Noy and Kessler 1993; Bhattacharya and Das 1999; Kim and Lee 1996). Laasonen et al. describe a method of inferring the significant locations from 91 92 the cell towers by calculating graph metrics from the adjacency matrix formed by proximate towers. 93 They were able to show reasonable route recognition rates, and most importantly succeeded in running their algorithms directly on the mobile phone (Laasonen et al 2004). In the activity and pattern 94

recognition communities, there has been a variety of work using techniques to estimate an individual's
location and projected trajectory given a variety of sensor data such as GPS, wifi base-station
positioning, and accelerometer data. Hightower and Borriello along with Patterson et al., among others,
have demonstrated the potential of particle filters for route recognition (Hightower and Borriello 2004;
Liao et al 2004; Patterson et al 2003).

100

In machine vision and computer graphics, eigenrepresentations have become one of the standard 101 techniques for many tasks. While behavior is perhaps not as characteristic of an individual as a face, 102 103 many analogies hold between the analysis of an individual's behavior and his facial features. Just as digital imaging created a wealth of data to train and test facial analysis tools, the explosive growth of 104 mobile phones is beginning to enable much more comprehensive computational models of complex 105 106 human behavior. Eigendecomposition is used in face and object recognition (Turk and Pentland 1991), shape and motion description (Pentland and Sclaroff 1991), and data interpolation (Pentland 1992), and 107 computer animation (Pentland and Williams 1989). More recently it has been used in a wide variety of 108 robotic and control applications. 109

110

111 Methods

To apply eigendecomposition for behavior and social network analysis, a large repository of behavioral data is necessary. In this paper we make use of the publically available Reality Mining dataset representing the behavior of 100 subjects at MIT during the 2004-2005 academic year (Eagle and Pentlad 2006). Seventy-five of the subjects were either students or faculty in the same laboratory, while the remaining twenty-five were incoming students at the business school adjacent to the laboratory. Of the seventy-five students and staff at the lab, twenty were incoming masters students and five were incoming freshman. The data were collected using one hundred Nokia 6600 smart phones pre-installed with a version of the Context application from the University of Helsinki (Raento et. al 2005). The information collected included call logs, Bluetooth devices in proximity, cell tower IDs, application usage, and phone status (such as charging and idle). The study generated approximately 400,000 hours of data on subjects' location, proximity, communication and device usage behavior.

123

The collection of deeply personal human behavioral data raises justifiable concerns over privacy. While these concerns are legitimate and should be explored, the dataset we are using was collected during a social science experiment, conducted with human subject approval and consent of the subjects. Additionally, these techniques for extracting the underlying structure inherent within behavioral data are not only applicable to human populations. Eigenbehaviors are suitable for analysis of any regularly sampled behavioral data, making it also a potential analysis tool for longitudinal studies of animal behavior, where concerns about privacy are greatly reduced (Krause et. al 2009).

131

Finally, this paper will not make the claim that the subjects in the Reality Mining study are a 132 representative sample of society. However, regularity in behavior is not an exclusive trait of people at 133 134 MIT. For many people, weekdays consist of leaving home in the morning, traveling to work, breaking for lunch, and returning home in the evening. People's daily routines are typically coupled with 135 routines across other temporal scales, such as going out on the town with friends on Saturday nights, or 136 137 spending time with family during the December holidays. Animals exhibit similar behavior patterns, both on a daily and seasonal cycle. The remainder of this paper will be focusing on a particular 138 technique to quantify these universal patterns in the behavior of individuals and communities within a 139 140 social network.

While we have successfully applied our eigenbehavior technique to a wide range of multimodal data, 142 for purposes of clarity in this section we will only focus on temporal location data. For this example, 143 we characterize person I by data shown in Figure 1 as B(x,y), a two-dimensional D by 24 array of 144 location information, where D is the total number of days that person I has been in the study. B contains 145 *n* labels corresponding to behavior, where in our case these labels are *{Home, Elsewhere, Work, No* 146 147 Signal, Off?. It has been previously shown that these labels were generated with a conditioned Hidden Markov Model with over 95% accuracy (Eagle and Pentland 2006), and while there still is noise in the 148 signal, for our purposes we'll take them as ground truth. To perform the analysis, we convert B into B', 149 a D by H (where H is 24*n) array of binary values, shown in Figure 1. Γ_i is row i of B' and represents 150 an individual's behavior over day *i*; Γ_i can be represented by a single point in an *H*-dimensional space. 151 A set of D days can then be described as a collection of points in this large space. 152

153

Due to the significant amount of similar structure in most people's lives, days are not distributed 154 155 randomly though this large space. Rather, they are clustered, allowing the individual to be described by a relatively low dimensional 'behavior space'. This space is defined by a subset of vectors of dimension 156 H that can best characterize the distribution of behaviors and are referred to as the primary 157 eigenbehaviors. The top three eigenbehaviors that characterize the individual shown in Figure 1 are 158 plotted in Figure 2. The first eigenbehavior corresponds to either a normal day or a day spent traveling 159 (depending on whether the associated weight is positive or negative). The second eigenbehavior has a 160 corresponding weight that is positive on weekends and negative on weekdays, analogous to the 161 characteristic behavior of sleeping in and spending that night out in a location besides home or work. 162 163 The third eigenbehavior is emphasized when the subject is in locations with poor phone reception.

165 Results

166 Eigenbehaviors for Individuals

167

For each subject, the Reality Mining data set provides us with a set of days' behaviors, $\Gamma_1, \Gamma_2, \Gamma_3 \dots \Gamma_p$, 168 for a total of D days, where an individual day's behavior vector, Γ_i , has H dimensions. Following the 169 same notation as Turk and Pentland, the average behavior of the individual is $\Psi = \frac{1}{D} \sum_{n=1}^{D} \Gamma_n$. And 170 $\Phi_i = \Gamma_i - \Psi$ is the deviation of an individual day from the mean. Principal components analysis is 171 subsequently performed on these vectors generating a set of H orthonormal vectors, u, which best 172 describes the distribution of the set of behavior data when linearly combined with their respective 173 scalar values, λ . These vectors and their corresponding scalars are the eigenvectors and eigenvalues of 174 the covariance matrix of Φ , the set's deviation from the mean. 175

176
$$C = \frac{1}{H} \sum_{n=1}^{H} \Phi_n \Phi_n^T$$
$$= A A^T$$

where the matrix $A = [\Phi_1, \Phi_2, \Phi_3, ..., \Phi_M]$. Each eigenbehavior can be ranked by the total amount of variance it accounts for in the data, which is essentially the associated eigenvalue. The vectors with the highest eigenvalues are considered an individual's primary eigenbehaviors. The next section will discuss how these primary eigenbehaviors can be used for behavioral data reconstruction and prediction.

182

An individual's primary eigenbehaviors represent a space upon which all of his days can be projected with differing levels of accuracy. Figure 3 shows the projection of each day onto spaces created using an increasing number of these primary eigenbehaviors. It can be seen that while the reconstruction of each day using 40 eigenbehaviors for this particular subject nearly perfectly matches the original data, six eigenbehaviors captures a significant portion of the variance in the individual's behavior. Figure 4 shows the accuracy of representing behavior using a varying number of eigenbehaviors for the three different groups of subjects in the Reality Mining study. It is interesting to note that the space formed by the six primary eigenbehaviors describes individuals within the business school community of the social network with 90% reconstruction accuracy, but the senior lab students with 96% accuracy. This leads us to the conclusion that senior lab students exhibit more behavioral regularity than their business school counterparts.

194

While there are many techniques for creating predictive models that can generate a sequence of future data given training, eigendecomposition differentiates itself in an important way. Although many of life's patterns can be modeled as a Markov process, whereby the future state depends on the current state and observational data, these types of models have difficulty capturing correlations that span beyond several time slices. For many subjects, sleeping late in the morning is coupled in the same eigenbehavior with going out that evening – a hard pattern to recognize when using traditional models, but one that is highlighted when generating an individual's characteristic behavior spaces.

202

203 Figure 4 shows that the top six primary eigenbehaviors provide a characteristic behavior space from which an individual deviates less than 10% of the time. When these six eigenbehaviors are calculated 204 205 for an individual, it becomes possible to infer the projection of an entire day using only information 206 from a portion of that day. We use these approximations to develop predictions of an individual's subsequent behavior. To test this concept, for each subject we calculated a behavior space using the 207 individual's six primary eigenbehaviors and weights generated from the first twelve hours of a subject's 208 209 day. Through the linear combination of these weights and the subject's primary eigenbehaviors, a 12-210 element vector is created containing one of three location states (home, work, elsewhere). Each element

in the vector corresponds to the predicted location of the subject for the subsequent hours from noon to
midnight. Figure 5 shows the distribution of accuracy scores for the subjects when the sequence of 12
hours is compared with the subject's actual location over the same 12 hours.

214

215 Eigenbehaviors for Social Networks

In the previous section we have demonstrated that we can use data from Bluetooth-enabled mobile phones to discover a great deal about an individual's patterns of activities by reducing these complex behaviors to a set of principal components, or eigenbehaviors, characteristic of the individual. In this section we will demonstrate the possibility of inferring the relationships and community affiliations within the social network of the population based on a comparison of these eigenbehaviors.

221

222 The social network of the subjects in the Reality Mining study has a high amount of clustering based on 223 affiliation, as shown in Figure 6. It is reasonable to assume that each of these different groups of subjects (Sloan business school students, Media Lab incoming students, Media Lab senior students, and 224 MIT staff) have characteristic behaviors associated with the community affiliation. It is possible now to 225 identify the eigenbehaviors of these particular communities within the social network and project 226 individuals onto this behavior space. How well the community's behavior space explains an 227 individual's behavior, as measured by the Eucleadean distance between the individual and the principal 228 components of the community's behavior space can then be used to infer the individual's affiliation. 229 Additionally, we demonstrate that the distance between a pair of subjects within the community is 230 231 proportional to the probability the two individuals are connected within the friendship network.

232

The mathematics behind applying the eigenbehavior technique to a community of M actors is identical to that described in Section 2, with the exception that several of the variables have different interpretations. We now use a matrix B with each row corresponding to the average behavior of a particular individual in the community. After a similar transformation to B', a matrix of M by H, it becomes possible to generate eigenbehaviors of the community as a whole. The primary eigenbehaviors correspond to the community's characteristic behaviors.

239

While we later will show results that incorporate a variety of data including location, phone usage and people in proximity into the community behavior space, for explanative purposes, we will show data related to solely Bluetooth proximity events for the three main groups of subjects: incoming business school students, incoming lab students, and senior lab students. Figure 7 shows the mean behaviors for each group, Ψ_i , while Figure 8 depicts the top three eigenbehaviors $[u_i^i, u_2^j, u_3^j]$ of each group.

245

As expected, the top eigenvector in each of the groups closely corresponds to the mean. For individuals 246 247 within the business school community, there is particular emphasis during the school's coffee breaks at 10:30. Besides this emphasis, the other pattern is simply reflective of the standard course times (nine 248 until noon, a lunch break, and the subsequently afternoon courses). The lab students have less of an 249 enforced structure on their day. While the entire group of incoming lab students is taking courses, along 250 with approximately half of the senior students, these courses can be selected by the students from 251 anywhere in the institution and typically are not attended by many other subjects. However, each of the 252 lab students has an office within the lab and typically works from there when not in class. While the 253 two groups of lab students share virtually identical principal eigenbehavior, the secondary 254 255 eigenbehaviors are more telling about the differences. It is common knowledge around the lab that incoming students tend to get overwhelmed by over-commitments to coursework and research leading 256

to late nights at the workplace. This characteristic is emphasized from the group's second and third
eigenbehaviors with an emphasis from 20:00 to 2:00.

259

When a community's behavior space is created from the aggregate behavior of its individual members, 260 it becomes possible to determine the similarity of the members by identifying how accurately their 261 262 behavior can be approximated by the community's primary eigenbehaviors. Because the Reality Mining dataset contains data for both incoming and senior students, it is possible to verify the onset of 263 concordance between the incoming lab students and the rest of the laboratory. Likewise it is possible to 264 distinguish communities by their aggregate behavior, such as business school students and engineering 265 students. An individual's behavior (Γ) can be projected onto the *j* community's behavior space through 266 the following transformation. 267

268

$$\omega_k^j = u_k^j \left(\Gamma - \Psi_j \right)$$

for k=1,..., H and Ψ_j is the mean behavior of the community. Ψ_j for Bluetooth encounters of senior lab students, incoming lab students, and business school students is shown in Figure 7.

271

These weights form a vector $\Omega_j^r = [\omega_1^r, \omega_2^r, \omega_3^r, ..., \omega_{M'}^r]$ which is the optimal weighting scheme to get the new behavior as close as possible to the behavior space. Each element in the vector gives a scalar value corresponding to the amount of emphasis to place on its respective eigenbehavior when reconstructing the original behavior Γ . By treating the eigenbehaviors as a set of basis behaviors, the vector Ω^r , can be used to determine which person *k* the individual is most similar to in a particular community, *j*. We follow the method of Turk and Pentland by using Euclidean distance as our metric for describing similarity.

$$\varepsilon_{j_k}^2 = \left\| \Omega^j - \Omega_k^j \right\|$$

where Ω_k^j are the reconstruction weights for the *k*th person in community *j*. Figure 9 shows values for ε_j , the distance between one business school student and other subjects. This method can also be applied to data from a single individual to determine which days are most like the ongoing one.

283

Instead of comparing one individual to another, it is also possible to determine how much an individual 'fits in' with the community as a whole by determining the distance ε as the difference between the individual's projection onto the behavior space of a community and the individual's original behavior. We again use Euclidian distance to calculate the difference between the mean-adjusted behavior, $\Phi^{j} = \Gamma - \Psi^{j}$, and its projection onto the community's behavior space $\Phi_{b}^{j} = \sum_{i=1}^{M_{j}} \omega_{i}^{j} u_{i}^{j}$.

$$\varepsilon_j^2 = \left\| \Phi^j - \Phi_j^j \right\|$$

290 When determining the affiliation of an individual, there can be four possible outcomes, as shown on Figure 10. The dark gray plane represents the community behavior space, containing any set of 291 behaviors that would constitute being part of the community. The first option has the input behavior on 292 the behavior space as well as proximate to other individuals, Ω_{j_3} , within the behavior space. The 293 second example can be approximated accurately by the behavior space, but there are no other 294 individuals in the same area of the space. Input three appears to have something in common with some 295 296 members in the community's behavior space, however contains behavioral elements that cannot be reconciled within the behavior space. Lastly, four is a disparate input neither near the behavior space 297 nor any individual in the space. 298

299

Until now, we have been focusing on analysis of Bluetooth or location data independently, but this
technique enables us to aggregate multimodal datasets. Instead of limiting a community to only one
behavior space, for our affiliation classification we generate a set of primary eigenbehaviors for each

type of data captured. This enables us to determine every group's Bluetooth, location and phone usage
behavior space. When these spaces are computed, it is subsequently possible to calculate each
individual's Euclidian distance from each space. Figure 11 shows the distances for each subject from
the three business school behavior spaces. We used cross validation to prevent the test subject's data
from contributing to the generated behavior space, and were able to classify whether each subject was a
member of the business school community with 96% accuracy.

309

Lastly, the projected clustering of individual subjects onto the behavior space shown in Figure 11 has 310 an additional interesting characteristic beyond affiliation inference. By simply measuring the distance 311 between two individuals within this behavior space, it becomes possible to estimate the probability the 312 pair is connected within the social network of the population. Figure 12 shows that the probability of 313 friendship tails off dramatically as distance increases, until it converges on a steady-state probability of 314 friendship that appears to be irrespective of the behavioral differences between the pair. This 315 relationship follows a distribution qualitatively similar to that discovered within an online friendship 316 network and the physical, geographic distance between each pair of users (Liben-Nowell et al 2005). 317 318

319 Discussion

We have shown that eigenbehaviors can be used effectively to extract the underlying structure in the daily patterns of human behavior, predict subsequent behavior, infer community affiliations, and estimate the probability of a tie within the friendship network of the population. We are currently building applications that leverage this new technique in two main realms, behavior-based segmentation and data interpolation.

We have found that communities within a population's social network tend to be clustered within the same behavior space. It seems reasonable that this type of behavioral homophily is present in a variety of social networks. It should be possible for practitioners, using virtually any type of longitudinal behavior data, to similarly quantify the behavior space of a particular group or individual of interest using the eigenbehaviors technique described above. If strong behavioral homophily is present in the data, it should equally be possible to infer an individual's affiliations by quantifying the individual's distance from a community's behavior space.

333

When collecting large amounts of data from many subjects of an extended period of time, data loss is 334 unavoidable. The Reality Mining logs account for approximately 85.3% of the time since the phones 335 have been deployed. Approximately 5% of this is due to data corruption, while the majority of the 336 missing 14.7% is due to the phones being turned off. However, with a set of these characteristic 337 eigenbehaviors defined for each individual, it becomes possible to generate a rich synthetic dataset 338 from the approximations of the individual's eigenvalues over a particular time window of interest. 339 Using the behavior space generated from an individual's six primary eigenbehaviors, we have shown 340 we can generate a 12-hour chunk of data with 79% accuracy. If we incorporated the individual's future 341 342 behavioral data as well as the past, this accuracy should continue to increase.

343

It is inevitable that the next generation of wearable sensors will be appropriate for the long-term passive monitoring of an increasing set of living creatures. The behavioral data generated from these new devices will require fundamentally new techniques for analysis. To analyze data of such magnitude, eigendecompositions are useful because they provide a low-dimensional characterization of complex phenomena. This is because the first few eigenvectors of the decomposition typically account for a very large percentage of the overall variance in the signal. Because only few parameters are required, it becomes easier to analyze the individual and community behavior, and thus possible to predict the behavior of the individual elements as well as the behavior of the system as a whole.

352

These unique properties make eigenbehaviors ideal as a representation of daily movements, 353 interactions, and communication behaviors. The low dimensional representation provided by the 354 355 eigendecomposition will allow us to characterize an individual quickly, match him to similar individuals, and predict his behavior in the near future. The technique also provides us with a 356 representation of the behavior characteristic of a community as a whole and enables us to estimate the 357 probability of a tie within the larger social network of the population. As rich, longitudinal behavioral 358 data becomes increasingly available, it is our hope that these techniques will prove useful to researchers 359 studying a wide range of human and animal behavior. 360

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Fig 1. Transformation from *B* to *B'*. The plot on the left corresponds to the subject's behavior over the course of 113 days for 5 situations.

410 The same data can be represented as a binary matrix of 113 days (*D*) by 120 (*H*, which is 24 multiplied by the 5 possible situations).



413

Fig 2. The top three eigenbehaviors, $[u_1, u_2, u_3]$, for Subject 4. The first eigenbehavior (represented with the first column of three figures) corresponds to whether it is a normal day, or whether the individual is traveling. If the first weight is positive, then this eigenbehavior shows that the subject's typical pattern of behavior consists of midnight to 9:00 at home, 10:00 to 20:00 at work, and then the subject returns home at approximately 21:00. The second eigenbehavior (and similarly the middle column of three figures) corresponds to typical weekend behavior. It is highly likely the subject will remain at home past 10:00 in the morning and will be out on the town ('elsewhere') later that evening. The third eigenbehavior is most active when the individual is in locations where the phone has no signal.





435 Fig 4. Approximation error (y-axis) for the different subject groups as a function of the number of eigenbehaviors used (x-axis) with the

436 states off and no signal removed.

- . -



445 Fig 5. Behavior prediction accuracy for behaviors from noon to midnight given the previous 12 hours of behavioral data and the six

446 primary eigenbehaviors for each subject, an average of 79% accuracy is obtained.

-



л	E	E
4	Э	J

456 Fig 6. The social network of the population. The blue circles represent the community of business school students. The red triangles are457 senior lab students, the orange diamonds represent the incoming students, and the white squares represent the laboratory staff and faculty.



466 Fig 7. The average number of Bluetooth devices seen, Ψ_j , for the senior lab students, incoming lab students, and incoming business 467 school students. The values in these plots correspond to the total number of devices discovered in each hour of scanning over the course of 468 a day (with time of day on the x-axis).

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473 Fig 8. The top three eigenbehaviors $[u_1^j, u_2^j, u_3^j]$ for each group, *j*, comprised of the incoming business school students, incoming lab 474 students and senior lab students. The business school coffee break at 10:30 is highlighted in their first eigenbehavior. Comparing the 475 second eigenbehaviors for the Media Lab students, it can be seen that the incoming students have developed a routine of staying later in 476 lab than the more senior students.

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Fig 9. Values corresponding to ε_i , the Euclidian distance between each subject and a single business school student. The distance

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- between two individuals reflects the similarity of their behavior.





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522 Fig 11. The cross-validated distance ε_j between the three groups of students and the Bluetooth, Location and Phone Usage business

⁵²³ school behavior spaces.



Fig 12. Behavioral Distance vs. Probability of Friendship. The Euclidean distance between every subject's projection onto the behavior
space is calculated and compared with whether a friendship was reported between the two individuals. The figure suggests strong
behavioral homoplipy, that is, subjects with similar behavior are more likely to be friends.