

CHARACTERISTICS OF UPPER HEATED OCEANIC LAYER
FROM SATELLITE OBSERVATIONS

by

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SUBMITTED IN PARTIAL FULFILLMENT
OF THE REQUIREMENTS FOR THE
DEGREE OF

MASTER OF SCIENCE

at the

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

February, 1979

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Submitted to the Department of Meteorology, February, 1979, in partial fulfillment of the requirements for the degree of Master of Science.

ABSTRACT

Velocity of propagation of internal wave packets over the New England American Continental shelf were computed from Landsat A/B images taken in July and August of 1972, 1973, and 1974. A simple two-layer ocean model was used to compute from the velocity of propagation and climatological values of bottom density, the depth of the mixed layer and the amount of heat stored in the upper layer of the ocean. The comparison with in-situ observations showed a good agreement for the amount of heat. Due to the internal wave noise in the hydrographic observations the calculated values for mixed layer depth differ from those computed from satellite data. Charts of distribution of mixed layer depth and amount of heat stored based on 78 observations for the months of July and August are shown. In the Gulf of Maine heat stored values larger for July than August were found. A possible explanation for this anomaly is suggested in terms of air-sea interaction processes.

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ACKNOWLEDGEMENTS

I wish to thank Professor Erik Mollo-Christensen for the suggestion of the topic, his enormous amount of patience and faith in the author's abilities, and his guidance in all stages of the thesis.

Thanks are also extended to Dr. V. Worthington of Woods Hole Oceanographic Institution for furnishing most of the data, to Dr. G. Heimerdinger of NOAA for furnishing the new available data, to Diana Spiegel for permitting me to use hours of computer time, to Carlos Cardelino for the help with the programming problem, to Dr. Inez Fung for her valuable suggestions and help, to fellow classmates for the helpful discussions, to Virginia Mills for her excellent job of typing the manuscript and editing the Brazilian English, and finally, to the good friends on the 17th floor for their cherished friendship and incentive.

Special thanks are extended to my wife Terumi, my daughter Teozinha, and my son Jorge for their patience and understanding.

Financial support was provided by the Conselho Nacional de Desenvolvimento Científico e Tecnológico (CNPq) (Brazil) and by Universidade de São Paulo (Brazil).

1. INTRODUCTION

1.1 The Scope of the Problem

If one chooses not to classify aerial photography as Remote Sensing, the first attempt to extract information about the surface of the oceans sensing remotely came about 25 years ago. The first occasion was when Stommel and Parson (1955), using an Airborne Radiation Thermometer, surveyed the Gulf Stream from an airplane. Broad and synoptic coverage are one of the advantages of this new technique and at the present state of the art we cannot classify Remote Sensing as an independent tool of research, but we have to admit that it is a powerful auxiliary tool.

One hears the argument that only surface observations can be made from airplanes or satellites, while the oceanographers are interested in vertical information as well. This work represents an attempt to correlate information available from satellites and oceanographic platforms as well as trying to infer a three-dimensional picture of oceanic phenomena. One prominent oceanographic feature that plays an important role in the dynamics of the continental shelf waters is the presence of internal wave packets.

As a subsurface feature the internal waves cannot be detected directly by Remote Sensing, but their effects on the surface are visible. Apel and Charnell (1974) explain the internal waves sources and sinks admitting these waves as "daughter" waves generated for a few hours during the peak current velocity by the long-wavelength baroclinic tide occurring at the edges of the continental shelves and island arcs. They then propagate with very low phase speeds, of order 0.25 to 0.5 m/sec, to be absorbed near the bottom where the wave breaks on the shelf.

The association of the distinct surface slicks to internal waves was pointed out by Ewing (1950) and LaFond (1959). There are at least two explanations for why internal wave fields affect the surface of the ocean. The first one suggests that the velocity field of internal waves sweeps together surface oils and materials to form a slick in regions of surface water convergence, increasing the reflectivity of the surface (Ewing, 1950, Shand, 1953). The second explanation is that capillary wave energy is focused in the convergence zones, enhancing the small-scale roughness and decreasing the surface reflectivity (Gargett and Hughes, 1972, Thompson and West, 1972). In either case, quasi-periodic surface features will be produced under light wind conditions, and such effects are very often seen at sea. Under favorable conditions these features can be seen in satellite images as wave packets on the continental shelf areas. The packets are apparently emitted once per tidal period at the shelf edge (Apel et al., 1975). This assumption is supported by the fact that the M_2 component of the internal tide is found to be dominant (Halpern, 1971, Barbee, 1975, Ratray, 1960). Figure 1-1 shows an schematic diagram of the internal wave propagation over the continental shelf and the associated surface slicks.

The eastern coast of the United States (from Cape Hatteras to Nova Scotia) provides favorable conditions for detection of internal wave packets on their continental shelves. The prevalence of internal wave signatures in that area during summer was recognized, and their dependence on the well-defined and relatively shallow thermocline was deduced from their absence during winter months (Apel et al., 1974).

The summer heating thus provides a stratification that can be

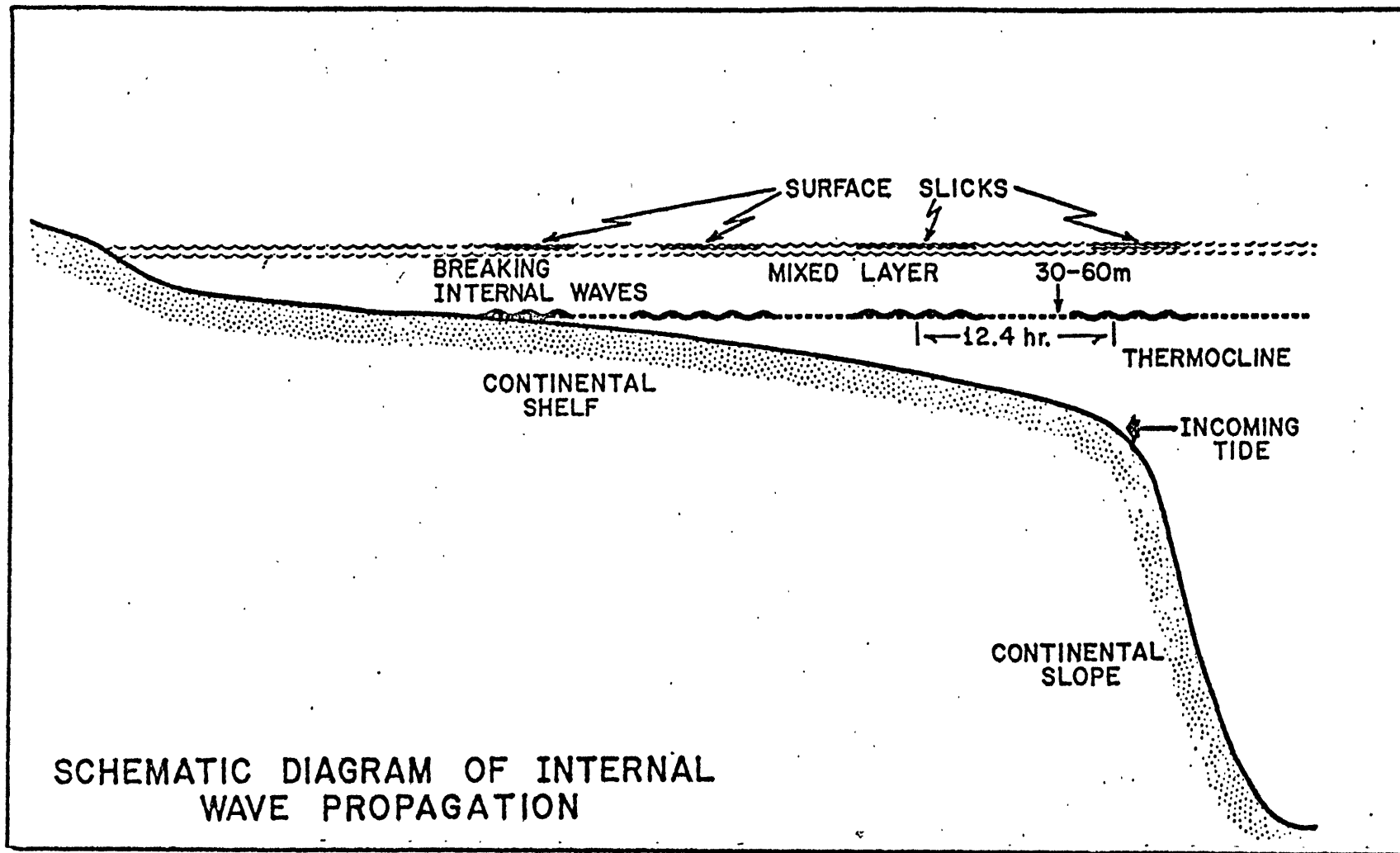


Figure 1.1 - Schematic diagram of the internal wave propagation over the continental shelf (after, Apel 1974).

approximated to an idealized stratification of two homogeneous layers which have a density difference $\Delta\rho$. This stratification supports internal gravity waves from which we know the velocity of propagation taken from the images. This information is enough to compute the depth of the mixed layer and the heat stored in the seasonal upper warm layer of the ocean.

The heat stored in the upper ocean affects weather, both climatologically and synoptically, and the mixing processes in the layer, driven by wind and thermal effects, also transport oxygen, nutrients and biota. All these processes show therefore the importance of the knowledge of the seasonal upper layer.

An extension for a three layer ocean, with the upper and lower ones homogeneous and the middle layer with a linear variation thermocline is also made, and the results of the computation are discussed.

1.2 Basic Equations and Assumptions

The basic set of equations is: conservation of momentum, mass, and equation of state for sea water. The conservation of momentum can be written (see, for instance, Phillips, 1966)

$$\frac{d\mathbf{v}}{dt} + \boldsymbol{\Omega} \times \mathbf{v} = -\frac{1}{\rho} \nabla p - \nabla \phi \quad (1.2.1)$$

where $\mathbf{v} = \mathbf{v}(\mathbf{x}, t)$ denotes the velocity of the fluid at prescribed points in space-time as in an Eulerian description. The velocity components following x , y and z are respectively u , v , and w . $\boldsymbol{\Omega}$ is the rotation vector, or twice the earth's angular velocity. Its magnitude is

$$\Omega = |\Omega| = 2\pi / 12 \text{ h}^{-1} = 1.45 \cdot 10^{-4} \text{ sec}^{-1}$$

$\nabla\Phi$, is the gravitational potential, which contains the gravitational term $\mathfrak{g} = (0, 0, -g)$ representing the apparent gravitational acceleration, or the true (central) gravitational acceleration modified by the small (centrifugal) contribution normal to the axis of the earth's rotation. The term ∇p represents the pressure gradient forces, and ρ is the density of sea water given as

$$\rho = \rho (\tau, S, P) \tag{1.2.2}$$

The conservation of mass is expressed by

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0 \tag{1.2.3}$$

As in the Eulerian formulation, the total time derivative (derivative following the motion) is the sum of the time rate of change at a fixed point and a convective rate of change

$$\frac{d}{dt} = \frac{\partial}{\partial t} + (\mathbf{v} \cdot \nabla)$$

1.2.1 The Boussinesq Approximation

If we assume a basic state being steady and at rest (1.2.1) reduces to

$$\frac{\partial p_B}{\partial z} + \rho_B g = 0 \quad (1.2.1.1)$$

and if we subtract this equation from (1.2.1) we get

$$\rho \frac{d\mathbf{v}}{dt} + \rho \mathbf{R} \times \mathbf{v} + \nabla \tilde{p} + (\rho - \rho_B) \mathbf{g} = 0 \quad (1.2.1.2)$$

where $\tilde{p} = p - p_B$

In the ocean the difference between the actual state and the reference state is the result primarily of surface heating or cooling, whose influence is distributed by the process of convection and mixing.

Surface water in regions of low salinity and high temperature has a density as low as 1.02 gm/cm^3 . Water in the deepest trenches is subjected to the highest pressures and has a density as high as 1.07 gm/cm^3 . So the maximum range is only about 5%!

Boussinesq in 1877 introduced an important approximation, namely; "The variations in the fluid density are neglected in so far as they influence the inertia terms, variations in the weight (or buoyancy) of the fluid may not be negligible."

So in (1.2.1.2) it is possible to approximate ρ by ρ_B . But taking into account the fact that in the ocean the scale of vertical movements is much less than the scale height, an even greater simplifi-

cation can be done, also since the reference density ρ_B varies little from the constant mean value ρ_0 . So we can rewrite (1.2.1.2)

$$\frac{dV}{dt} + \Omega \times V + \frac{\nabla}{\rho_0} (p - p_B) + \frac{(\rho - \rho_B)}{\rho_0} g \mathcal{J} = 0 \quad (1.2.1.3)$$

Using the fact that the mean value ρ_0 is hydrostatic, we can modify the buoyancy and pressure terms in (1.2.1.3) to get finally

$$\frac{dV}{dt} + \Omega \times V = -\frac{1}{\rho} \nabla p - g \frac{(\rho - \rho_0)}{\rho_0} \quad (1.2.1.4)$$

where p now represents the difference between the actual and the hydrostatic pressure in an ocean at rest with constant density ρ_0 .

Let us see now the effect of Boussinesq approximation in the conservation of mass equation (1.2.3). If $\rho = \rho_0$ we will not have stratification at all. Since we want Boussinesq approximation as well as stratification, we say that our density is not constant, but varies a little around the mean value ρ_0 . This statement can be written analytically as

$$\rho = \rho_0 + \bar{\rho}(z) + \rho' \quad (1.2.1.5)$$

where $\bar{\rho}(z)$ is the added stratification and ρ' is the variation in the density field due to internal waves. The expression (1.2.1.5)

is called quasi-Boussinesq approximation. The new conservation of mass equation is

$$\frac{d\rho'}{dt} + \omega \frac{\partial \bar{\rho}}{\partial z} = 0 \quad (1.2.1.6)$$

The conditions for validity of Boussinesq approximation are:

a) The actual density distribution differs only slightly from the reference state;

b) The vertical scale of motion is small compared with the scale height; $\mathcal{H} \sim O(200 \text{ km}) \gg H \sim O(4 \text{ km})$

c) The Mach number of the flow is very small; for water at 15°C, $c = 1470 \text{ m/sec}$, $u = 5 \text{ cm/sec}$, $M = 0.34 \times 10^{-4}$, so for the ocean all the requirements are fulfilled.

Expanding (1.2.2) about the basic state density ρ_B and neglecting the second order terms we get

$$\rho' = \bar{\rho} (-\alpha T' + k\rho' + \gamma S') \quad (1.2.1.7)$$

where

$$\alpha = -\frac{1}{\rho} \left(\frac{\partial \rho}{\partial T} \right)_{P,S} \quad (\text{coefficient of thermal expansion}) ;$$

$$k = \frac{1}{\rho} \left(\frac{\partial \rho}{\partial \rho} \right)_{T,S} \quad (\text{coefficient of isothermal compressibility});$$

$$\gamma = \frac{1}{\rho} \left(\frac{\partial \rho}{\partial S} \right)_{P,T} \quad (\text{fractional increase in density per unit increase in salinity keeping } T \text{ and } P \text{ constant})$$

If we substitute (1.2.1.7) in the right-hand side of (1.2.1.4), the vertical component of (1.2.1.4) has on the right-hand side the terms

$$-\frac{1}{\bar{\rho}} \frac{\partial p'}{\partial z} + g\alpha T' - gk p' - g\gamma S'$$

For oceanic motions the vertical scale of variation H is of order 10^5 cm, so that the first term has magnitude $|p'|/H$. The isothermal compressibility k has a magnitude of 4.5×10^{-11} in cgs units, so that the term $gk p'$ has a magnitude $|p'|/H_s$, where $H_s = 1/gk$ is the scale height for sea water. Its value is 2×10^7 cm, i.e. substantially larger than the vertical scale H . So the pressure fluctuation term in the equation of state is dynamically insignificant (Veronis, 1973). To be fair we need to compare the other terms; in the second one, $(52 \leq \alpha \leq 335) \times 10^{-6}$ for $S = 35 \text{‰}$, so will be of order $|T'| \times 10^{-5}$, and the last one is also of the order of $|S'| \times 10^{-5}$, so we can approximate the equation of state to

$$\rho = \bar{\rho} (1 - \alpha T' + \gamma S') \quad (1.2.1.8)$$

Phillips (1966) showed that, since the entropy of a given fluid element varies only as a result of molecular diffusion and (very near the free surface) of radiative transfer,

$$\nabla \cdot \mathbf{V} = \frac{g\omega}{c^2}$$

and also that the ratio between the left hand and right hand side of the above expression is of order Z/H , negligibly small and so

$$\nabla \cdot \mathbf{V} = 0 \quad (1.2.1.9)$$

is a good approximation for internal waves.

1.2.2 The Brunt-Väisälä frequency

At a fixed oceanographic station in the sea, continuous measurements of temperature, or any other physical or chemical property of sea water, shows variations of these properties at a fixed depth. This variability is frequently found particularly near the highly stratified thermocline.

Quoting Turner (1973):

A body of homogeneous, inviscid incompressible fluid at rest is in a state of neutral equilibrium. At every point the weight of a fluid element is then exactly balanced by the pressure exerted on it by neighboring fluid, and this continues to hold true if the elements are displaced to another position of rest. When ρ varies the hydrostatic equation

$$p = p_0 - g \int_0^z \rho dz \quad (1.2.2.1)$$

shows that the fluid (in the absence of diffusion) is in equilibrium only when the density as well as the pressure is constant in every horizontal plane. This equilibrium stratification is stable when the heavier fluid lies below, since tilting of a density surface will produce a restoring force. The resulting motion can overshoot the equilibrium position and oscillate about it, thus giving rise to internal waves.

To find an analytic expression for this natural frequency of oscillation that stems from differences in density we take the z component of the momentum equation for an inviscid stratified fluid

$$\frac{dw}{dt} = -\frac{1}{\bar{\rho}_0} \frac{\partial p}{\partial z} - g \frac{(\bar{\rho} - \bar{\rho}_0)}{\bar{\rho}_0} = \frac{d^2 \zeta}{dt^2} \quad (1.2.2.2)$$

where ζ is the vertical displacement of a fluid element from its position of equilibrium. Using the relation

$$\bar{\rho} - \bar{\rho}_0 = -\zeta \frac{d\bar{\rho}}{dz}$$

and assuming no pressure variation during the displacement, we get the ordinary differential equation

$$\frac{d^2 \zeta}{dt^2} + \left(\frac{g}{\bar{\rho}_0} \frac{\partial \bar{\rho}}{\partial z} \right) \zeta = 0$$

which has as solution an oscillation with frequency N, where

$$N^2 = -\frac{g}{\bar{\rho}} \frac{\partial \bar{\rho}}{\partial z} \quad (1.2.2.3)$$

N is called Brunt-Väisälä frequency or stability frequency, and is the frequency at which a fluid element at rest will oscillate if displaced

from its equilibrium condition.

If in the equation (1.2.2.2) we had introduced the Boussinesq approximation, i.e. ρ_0 , the hydrostatic relation would have ρ instead of $\bar{\rho}$, and also $\rho - \rho_0 = -\zeta \frac{d\bar{\rho}}{dz}$. These changes would give us a different Brunt-Väisälä frequency, namely,

$$N^2 = -\frac{g}{\rho_0} \frac{d\bar{\rho}}{dz} \quad (1.2.2.4)$$

The former one is better when applied to exponential extratification, because it will give a constant N; meanwhile the last one is good for linear stratification, for the same reason. Typical values of N are

at pycnocline	~2 cycles per hour
at abyssal water	~ .5 cycles per hour

When we are dealing with deep water an extra term arises in the definition to take into account the compressibility. For shallow water we just need to use $\rho_{S,T,0}$ values, i.e. density at described values of temperature and salinity and at zero pressure (assumed to be the surface). So we can compute σ_t from T and S and find ρ from the relation

$$\sigma_t = (\rho_{S,T,0} - 1) \cdot 10^3 \quad (1.2.2.5)$$

1.2.3 The Equation for Internal Waves

The basic set of equations the comprises the so-called Boussinesq approximation are equations (1.2.1.4), (1.2.1.6) and (1.2.1.9), given

below in component form

$$\frac{\partial u}{\partial t} + \frac{1}{\rho_0} \frac{\partial p}{\partial x} - f v = - (\mathbf{v} \cdot \nabla) u \quad (1.2.3.1)$$

$$\frac{\partial v}{\partial t} + \frac{1}{\rho_0} \frac{\partial p}{\partial y} + f u = - (\mathbf{v} \cdot \nabla) v \quad (1.2.3.2)$$

$$\frac{\partial w}{\partial t} + \frac{1}{\rho_0} \frac{\partial p}{\partial z} - \frac{(\rho - \rho_0)}{\rho_0} g = - (\mathbf{v} \cdot \nabla) w \quad (1.2.3.3)$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad (1.2.3.4)$$

$$\frac{\partial \rho'}{\partial t} + w \frac{\partial \bar{\rho}}{\partial z} = - (\mathbf{v} \cdot \nabla) \rho' \quad (1.2.3.5)$$

where

$$\rho = \rho_0 + \bar{\rho}(z) + \rho'(x, y, z, t) \quad (1.2.3.6)$$

After some manipulation with the above equations we get the equation

$$\frac{\partial^2}{\partial t^2} (\nabla^2 w) + f^2 \frac{\partial^2 w}{\partial z^2} + N^2 \nabla_2^2 w = \mathcal{N} \quad (1.2.3.7)$$

where \mathcal{N} stands for the non linear terms and

$$\nabla_2^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$$

Equation (1.2.3.7) is the equation of the internal waves in an ocean with arbitrary Brunt-Väisälä distribution $N(z)$. For infinitesimal

disturbances in the absence of a mean shear, the right hand side of (1.2.3.7) is negligible and the governing equation is linear

$$\frac{\partial^2}{\partial t^2} (\nabla^2 \omega) + f^2 \frac{\partial^2 \omega}{\partial z^2} + N^2 \nabla^2 \omega = 0 . \quad (1.2.3.8)$$

If we have stated instead of (1.2.3.6) the following;

$$\rho = \bar{\rho}(z) + \rho' ,$$

we would get an extra term in equation (1.2.3.7), namely,

$$- \frac{N^2}{g} (\omega_{tt} + f^2 \omega) z .$$

For a time harmonic variation like

$$\omega = W(z) \exp [i(k_0 \cdot \mathcal{X} - \sigma t)] , \quad (1.2.3.9)$$

where $k = \{k, l\}$ is the horizontal wave number and
 $\mathcal{X} = \{x, y\}$ is the horizontal coordinate

The substitution of (1.2.3.9) in (1.2.3.8) gives the equation for the vertical movements of the field

$$\frac{d^2 W}{dz^2} + \frac{(\sigma^2 - N^2)}{(f^2 - \sigma^2)} \alpha^2 W = 0 , \quad (1.2.3.10)$$

where $\alpha^2 = k^2 + l^2$.

The boundary condition at the bottom is

$$W = u \frac{\partial h}{\partial x} + v \frac{\partial h}{\partial y} , \quad \text{at} \quad z = -h(x, y) \quad (1.2.3.11)$$

or for a flat bottom

$$W = 0 , \quad \text{at} \quad z = -h . \quad (1.2.3.12)$$

In the surface neglecting the atmospheric pressure input to internal waves, and non linear terms we have

$$\frac{\partial^2}{\partial t^2} \left(\frac{\partial w}{\partial z} \right) + f^2 \frac{\partial w}{\partial z} + g \nabla_2^2 w = 0 , \quad \text{at} \quad z = 0 \quad (1.2.3.13)$$

correct only to the first order. The internal waves in the ocean produce only very small vertical displacements of the free surface, so the free surface boundary condition can be taken as

$$W = 0 \quad , \quad \partial t \quad \xi \cong \eta = 0 \quad . \quad (1.2.3.14)$$

Since the condition,

$$\frac{\sigma_i^2 - f^2}{g \alpha_s} \left(\frac{N_{(0)}^2 - \sigma_i^2}{\sigma_i^2 - f^2} \right) \ll 1 \quad (1.2.3.15)$$

is usually satisfied strongly. Here σ_i stands for internal wave frequency, α_s for surface wave number and $N_{(0)}^2$ for Brunt-Vaisala frequency very near the surface.

2. THE MODELS, THEIR SOLUTION AND APPLICATIONS.

2.1 The Two Layer Model

Frequently the ocean can be approximated by a two layer model. This occurs either when the upper layer of the ocean has been well-mixed as a result of a storm or by the action of the trade winds or when it is heated during the summer months. In each case the thermocline is fairly abrupt and separates water masses above and below, each of which is almost homogeneous (see Fig. 2.1).

Let there be two layers of inviscid, incompressible homogeneous fluid, the lower one with density ρ_2 and the upper one with density ρ_1 , the bottom being described by the function $b(x,y)$. The h 's are the equilibrium thickness of each layer and the ζ 's are the deviation of the surfaces from its equilibrium position. The equation for the upper layer will be

$$\frac{du_1}{dt} - f\bar{v}_1 = -g \frac{\partial \zeta_1}{\partial x}, \quad (2.1.1)$$

$$\frac{dv_1}{dt} + fu_1 = -g \frac{\partial \zeta_1}{\partial y}, \quad (2.1.2)$$

$$\frac{\partial}{\partial t} (\zeta_1 - \zeta_2) + \frac{\partial}{\partial x} (u_1 h_1) + \frac{\partial}{\partial y} (v_1 h_1) = 0 \quad (2.1.3)$$

and for the lower layer

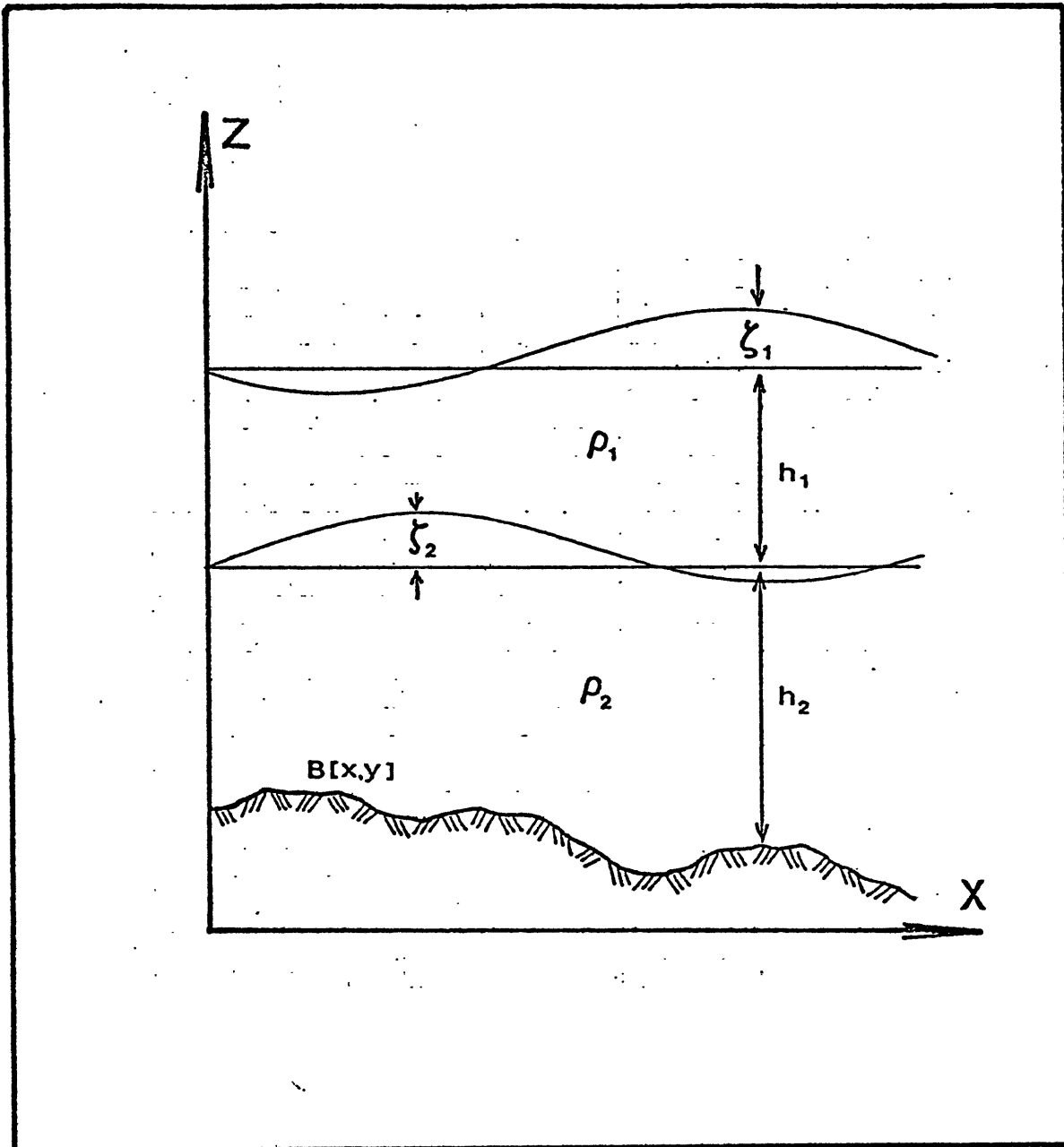


Figure 2.1 - The two-layer model schematically.

$$\frac{du_2}{dt} - fu_2 = -g \frac{\rho_1}{\rho_2} \frac{\partial \xi_1}{\partial x} - g \frac{(\rho_2 - \rho_1)}{\rho_2} \frac{\partial \xi_2}{\partial x} , \quad (2.1.4)$$

$$\frac{dv_2}{dt} + fv_2 = -g \frac{\rho_1}{\rho_2} \frac{\partial \xi_1}{\partial y} - g \frac{(\rho_2 - \rho_1)}{\rho_2} \frac{\partial \xi_2}{\partial y} , \quad (2.1.5)$$

$$\frac{\partial \xi_2}{\partial t} + \frac{\partial}{\partial x} (u_2 h_2) + \frac{\partial}{\partial y} (v_2 h_2) = 0 . \quad (2.1.6)$$

This kind of problem was first investigated by Stokes (1847), (see for instance, Lamb, 1932, article 231). He solved for a wave propagating along the x axis with the upper surface of the upper fluid free. For the special case where the depth of the lower fluid is great compared with the wavelength and the upper layer depth is much less than the wavelength he found

$$c^2 = \frac{\sigma^2}{k^2} = h_1 g \frac{\Delta \rho}{\rho_2} . \quad (2.1.7)$$

The same solution was worked out in a very elegant fashion by Phillips (1966), solving the internal wave equation (1.2.3.10) with $f=0$ and using a delta function for the Brunt-Väisälä function.

In view of the application of (2.1.7) to internal waves with semi-diurnal period over the continental shelf let us see the implication of the assumptions on this practical application. The continental shelf in the region between Nova Scotia and Cape Hatteras has a mean depth of 100 m. Very few internal waves were detected over the continental slope where

200 \bar{z} H \bar{z} 1000 meters. The measurements of the distance between the internal wave packets showed that the wavelengths of the waves vary from 400 to 2200 m. This means, assuming $h_2 = 7 \times 10^3$ cm, $1.01 \geq kh_2 \geq 0.2$ or that $5.07 \geq \coth kh_2 \geq 1.25$! So the assumption that $\coth kh_2 = 1$ is only approximately true for waves with smaller wavelengths, and if applied to larger wavelengths will give errors.

The other assumption was that the upper layer is much less than the wavelength or $kh_1 \ll 1$, for $h_1 = 3 \times 10^3$ cm. We have $8.57 \times 10^{-2} \bar{z} kh_1 \bar{z} 4.71 \times 10^{-1}$, that can be considered a fair approximation. Now remains the question, can we neglect the Coriolis parameter f in the equations? What would be the consequences if we take it into account?

If we write down equation (1.2.3.10) again

$$\frac{d^2 W}{dz^2} + \frac{(\sigma^2 - N^2)}{(f^2 - \sigma^2)} \alpha^2 W = 0 \quad (2.1.8)$$

and the patching conditions,

$$W(-d + \varepsilon/2) = W(-d - \varepsilon/2) \quad (2.1.9)$$

and

$$\left. \frac{dW}{dz} \right|_{-d+\varepsilon/2} - \left. \frac{dW}{dz} \right|_{-d-\varepsilon/2} = \frac{\alpha^2 W-d}{\sigma^2 - f^2} \left[\sigma^2 \varepsilon - g \left(\frac{\rho_2 - \rho_1}{\rho_0} \right) \right], \quad (2.1.10)$$

where $d \pm \epsilon$ is the depth of the discontinuity in density, so $N(z)$ is zero outside this region. The solution of equation (2.1.8) and the conditions (2.1.9) and (2.1.10) lead to the dispersion relation:

$$\sigma^2 = f^2 + \frac{\alpha^2 g (\rho_2 - \rho_1)}{\mu \rho_0} \left[\coth \mu d + \coth \mu (H-d) \right]^{-1}, \quad (2.1.11)$$

where $\mu^2 = \sigma^2 \alpha^2 / \sigma^2 - f^2$ and H is the depth of the flat bottom.

In this section, and when needed, we are going to choose our coordinates system such that our horizontal wave number $a = k$, can be thought of as in the x direction.

Since one of our aims is to compute the depth of the mixed layer we need to work out the expression (2.1.11). The other aim is to compute the amount of heat stored in the upper layer and as we shall see later on, only the velocity of propagation c is enough.

Under the assumption

$$\coth \mu H \sim O(1), \quad \text{consequently}$$

$$\coth \mu d + \coth \mu (H-d) \sim \coth \mu d + 1.$$

We can rewrite (2.1.11) as

$$(\sigma^2 - f^2)^{1/2} = \frac{g'}{c} (1 + \coth \mu d)^{-1},$$

and the expression for the mixed layer depth will be

$$d = \frac{(c^2 - f^2/\alpha^2)^{1/2}}{\alpha c} \coth^{-1} \left[\frac{g'}{\alpha c} \frac{1}{(c^2 - f^2/\alpha^2)^{1/2}} \right]. \quad (2.1.12)$$

The above assumption will give higher errors for shallow waters,
i.e. $h < 60$ m.

It is clear that if we make $f=0$ and $ad \ll 1$ the expression
(2.1.12) will reduce to (2.1.7). In Chapter 6 the results of computation
of d using (2.1.12) and (2.1.7) will be discussed, but we can anticipate
that the inclusion of f does not change the results at all, of course
for practical purposes.

2.2 The Three-Layer Models

A more realistic model is a three-layer model with a density profile and a Brunt-Vaisala frequency as shown in Figure 2.2. In the model the upper layer has a constant density ρ_1 , the bottom layer has a constant density ρ_3 , and in the middle we have a linearly varying density profile like

$$\rho_2(z) = \rho_1 + a(z + h_1) \quad , \quad (h_1 \geq z \geq h_1 + h_2) \quad (2.2.1)$$

where

$$a = \frac{\Delta\rho}{\Delta z} = \frac{\rho_3 - \rho_1}{-h_2} \quad .$$

The Brunt-Vaisala frequency in this layer is

$$N^2 = -\frac{g}{\bar{\rho}} \frac{\partial \rho}{\partial z} = \frac{2g}{h_2} \left(\frac{\rho_3 - \rho_1}{\rho_3 + \rho_1} \right) = \frac{g'}{h_2} \quad , \quad (2.2.2)$$

where $g' = g\Delta\rho/\bar{\rho}$ is the reduced gravity for a two layer ρ_1 and ρ_3 , and where we have used a mean value $(\rho_1 + \rho_3)/2$. Recalling the equation for vertical motions of internal waves (1.2.3.10)

$$\frac{d^2 w}{dz^2} + \left(\frac{\sigma^2 - N^2}{f^2 - \sigma^2} \right) \alpha^2 w = 0 \quad , \quad (2.2.3)$$

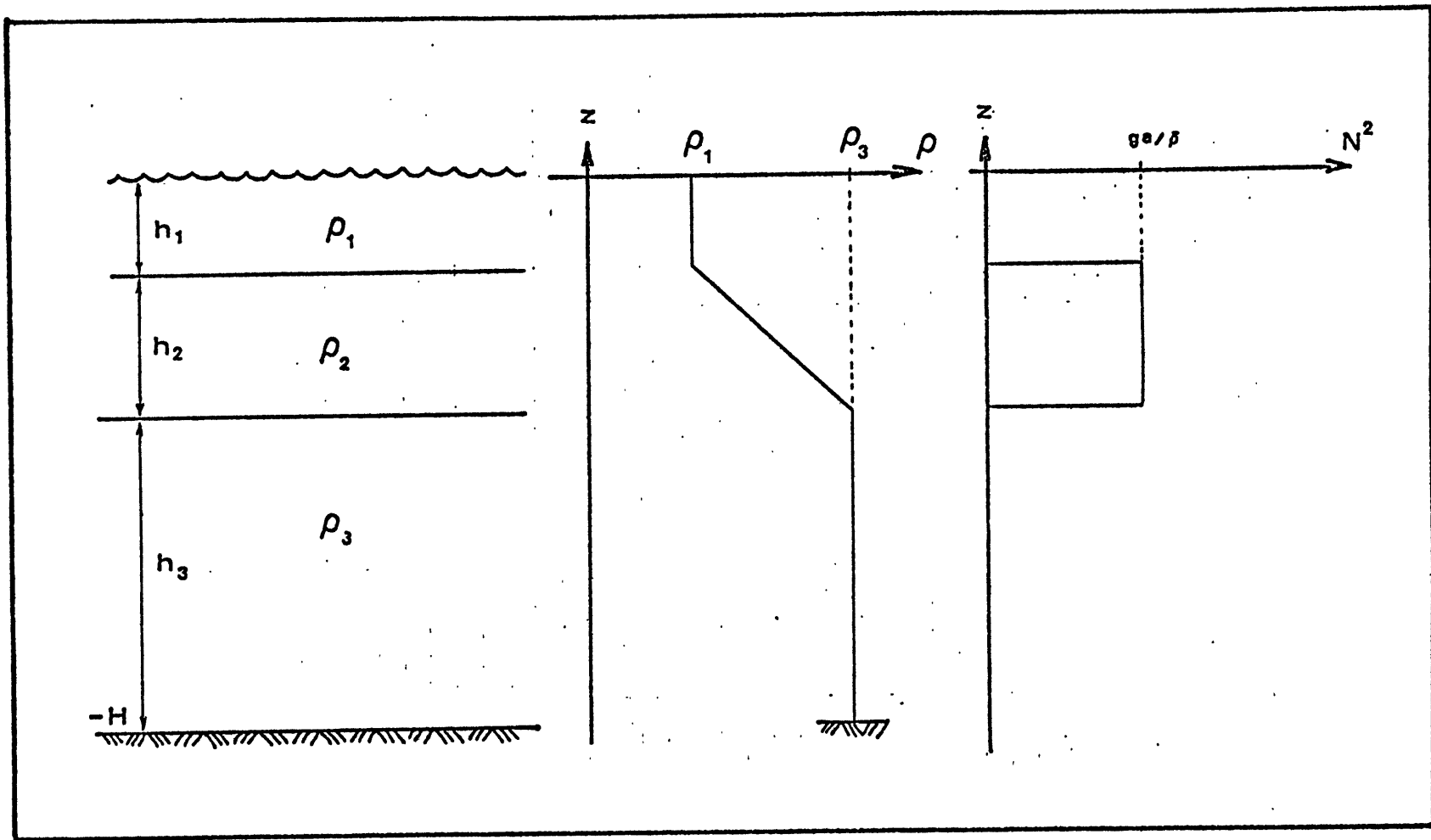


Figure 2.2 - The three-layer model, density distribution and Brunt-Vaisala frequency.

with the boundary conditions

$$W = 0 \quad , \quad \text{at} \quad z = 0, -H . \quad (2.2.4)$$

The solutions of (2.2.3) and (2.2.4) are:

$$W_1 = B_1 \sinh \mu z \quad , \quad -h_1 \leq z \leq 0 \quad , \quad (2.2.5)$$

$$W_2 = A_2 \cos \delta z + B_2 \sin \delta z \quad , \quad -h_2 - h_1 < z < -h_1 \quad , \quad (2.2.6)$$

$$W_3 = B_3 \sinh \mu (z + H) \quad , \quad -H \leq z \leq -h_1 - h_2 \quad , \quad (2.2.7)$$

where the indices 1, 2 and 3 hold for the upper, middle and bottom layers and

$$\delta^2 = \left(\frac{N^2 - \sigma^2}{\sigma^2 - f^2} \right) \alpha^2 \quad \text{and} \quad \mu^2 = \frac{\alpha^2 \sigma^2}{\sigma^2 - f^2} . \quad (2.2.8)$$

To solve the problem completely we need four more conditions, that is, the conditions in the interface between the layers. The first one is that w must be continuous across the interface, i.e.,

$$[W] = 0 \quad , \quad \text{at} \quad z = -h_1, -h_1 - h_2 . \quad (2.2.9)$$

The second one is obtained by integration of (2.2.3) across the

interfaces,

$$\left[\frac{dw}{dz} \right] = 0 \quad , \quad \text{at} \quad z = -h_1, -h_1 - h_2 . \quad (2.2.10)$$

The application of these conditions to the solutions (2.2.5-7) gives rise to a set of homogeneous equations that admit a solution different from the trivial one, only if

$$\begin{vmatrix} \sinh \mu h_1 & \cos \delta h_1 & -\sin \delta h_1 & 0 \\ 0 & \cos \delta (h_1 + h_2) & \sin \delta (h_1 + h_2) & -\sinh \mu h_3 \\ \frac{\mu}{\delta} \cosh \mu h_1 & -\sin \delta h_1 & -\cos \delta h_1 & 0 \\ 0 & -\sin \delta (h_1 + h_2) & \cos \delta (h_1 + h_2) & -\frac{\mu}{\delta} \cosh \mu h_3 \end{vmatrix} = 0 ,$$

where $h_3 = H - h_1 - h_2$. The above determinant is the dispersion relation of the wave, namely

$$\left(\frac{\mu}{\delta} \right)^2 + \cot \delta h_2 (\tanh \mu h_1 + \tanh \mu h_3) \frac{\mu}{\delta} - \tanh \mu h_1 \tanh \mu h_3 = 0 \quad (2.2.11)$$

where from (2.2.8)

$$\frac{\mu}{\delta} = \frac{\sigma^2}{N^2 - \sigma^2} \quad (2.2.12)$$

If we neglect the Coriolis parameter f the dispersion relation (2.2.11) can be rewritten as

$$\gamma^2 \tanh \alpha h_1 \tanh \alpha h_3 + \gamma \cot \delta h_2 (\tanh \alpha h_1 + \tanh \alpha h_3) = 0 \quad (2.2.13)$$

where now $\delta^2 = \frac{(N^2 - \sigma^2) \alpha^2}{\sigma^2}$, $\gamma = \frac{\mu}{\delta}$ and α is the wave number here considered only in the x direction for the sake of simplicity.

According to Roberts (1975), care must be taken in making the Boussinesq approximation when this model of density distribution is used, particularly when a finite depth is assumed (Benjamin, 1967). It seems that the Boussinesq approximation is not valid for waves which are sufficiently long compared to the thermocline thickness h_2 (Thorpe, 1968). Here we have solved separately for each layer so it is still valid to approximate

$$\begin{aligned} \tanh \alpha h_1 &\sim \alpha h_1 \\ \tanh \alpha h_3 &\sim \alpha h_3 \end{aligned}$$

since $\alpha h_1, \alpha h_3 \ll 1$. But we cannot approximate the $\cot \delta h_2$ in (2.2.11), so

$$\gamma^2 - \alpha^2 h_1 h_3 + \gamma \alpha (h_1 + h_3) \cot \delta h_2 = 0 \quad (2.2.14)$$

factor the above dispersion relation and expanding small terms

$$\gamma^2 = \alpha^2 h_1 h_3 \left[1 - \frac{\alpha (h_1 + h_3)}{\gamma} \cot \delta h_2 \right] \quad (2.2.15)$$

so to the first order,

$$c^2 = (N^2 - \sigma^2) h_1 h_3 \quad (2.2.16)$$

We see that even a first approximation of the dispersion relation for the three-layer model is useless for our purposes because it introduces variables that we cannot measure.

The first approximation for the group velocity will be

$$c_g = c (1 - \alpha^2 h_1 h_3) \quad (2.2.15)$$

where c is the phase velocity (2.2.16).

3. DATA AND MEASUREMENTS

3.1 What the Internal Gravity Waves on the Continental Shelf Look Like

Surface manifestations of oceanic internal waves have been observed by many investigators, and their dependence upon wave-associated surface currents has been recognized for at least a generation (Ewing, 1950). The surface signatures are most evident on a relatively calm sea and take the form of a quasi-periodic, long-length modulation of the capillary-ultragravity wave spectrum; the scale of the modulation is usually of the order of hundreds of meters (Gargett and Hughes, 1972). Visible manifestations on the ocean surface are theorized as being due to at least two mechanisms, either of which modulates the short surface wave structure rather than a change in optical reflectivity or absorptivity at depth. The first theory suggests that the high velocity of surface waves arising from the large internal wave amplitude sweeps together surface oils and debris to form a slick in regions of surface water convergence, thus increasing the specular reflection and decreasing the diffuse scattering over the convergence region.

On the other hand, Gargett and Hughes (1972) have suggested another mechanism based on the observation that surface waves seem to change their direction of propagation over the crests of internal waves. They therefore investigated the interaction between surface waves and a periodic mean current induced by an internal wave. They found that if $c_{g_s}(\cos \phi) > c_{p_i}$ over an internal wave crest, (c_{g_s} - surface wave group speed, c_{p_i} - internal wave phase speed, ϕ - angle between c_{g_s} and c_{p_i}) i.e., if the surface wave groups overtake the internal wave,

then the surface waves will tend to propagate in the direction of the internal wave and their amplitudes will increase. If $c_{g_s} (\cos \Phi) < c_{p_i}$ over an internal wave crest, i.e., if the surface wave groups are overtaken by the internal wave, the direction of the surface waves is turned away and their amplitudes decrease. Over troughs, the opposite effects occur. So for a given internal wave field, the system will have singularities for certain surface waves. Therefore, there will be regions where none of these surface waves can exist, and these regions will appear as surface slicks.

Periodic features observed in the United States eastern coast in certain ERTS A/B images have been identified as surface slicks, so associated with internal waves. These features are only present during northern hemisphere summer months. This suggests that these internal waves are present when summer solar heating stratifies the water sufficiently well to support such oscillations. When fall and winter wind action mixes the shelf water down to the bottom, the waves no longer appear. Figure 3.1a and 3.1b show enlargements of ERTS images where internal wave manifestations can be seen.

The common properties of these waves as they appear in these figures can be summarized as follows (Apel et al., 1974, 1975, 1976).

a) The waves occur in groups or packets of width $L = 3$ to 5 km, usually landward of the continental slope and separated by distances D , which range from 4 to 40 km;

b) the crests are nearly always oriented parallel to the local bottom topography or can be loosely associated with some topographic feature seaward of their observed position, or both;

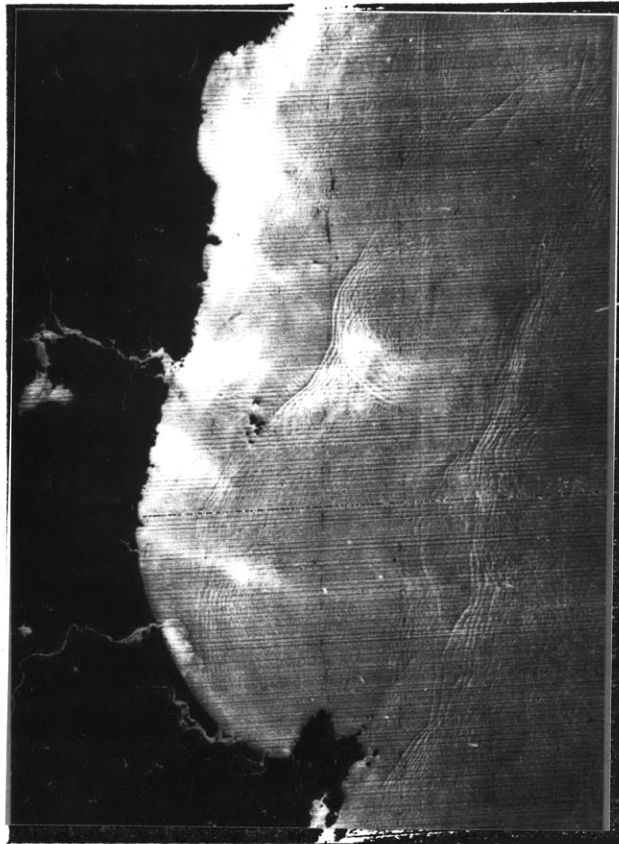


Figure 3.1a - Enlargement of Landsat image 1364-14550 taken on 23 July 1973. We can see two wave packets north of Cape Ann; the waves propagate shoreward.

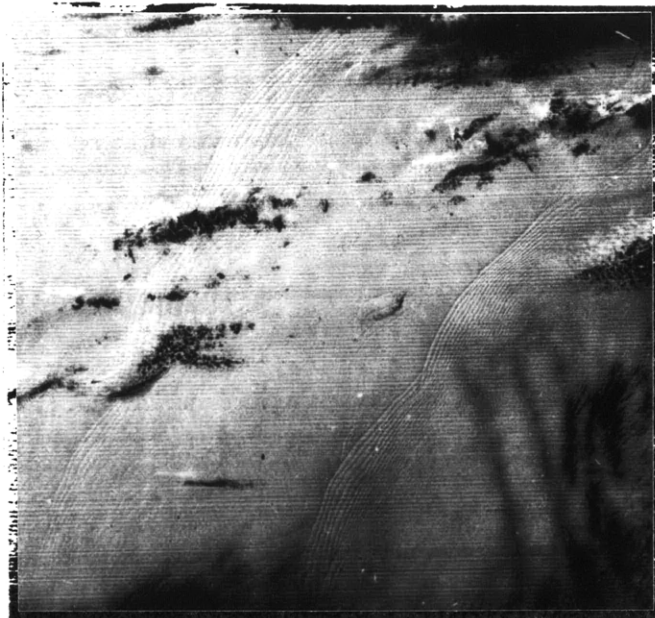


Figure 3.1b - Enlargement of Landsat image 1365-15013 taken on 23 July 1973. We can see two wave packets propagating towards the upper left corner of the image. The geographical location is south of Long Island.

c) the wavelengths fall between 400 and 2200 m, depending on the geographical area; within a given packet there often is a monotonic decrease in wavelength, varying from λ_0 at the front to $\lambda < \lambda_0$ at the back of the group;

d) the lengths of the crests, M, fall between 5 to 100 km, with a decrease in crest length occurring from front to back of the group;

e) the widths of the slicks, l_s , are often small compared to the lead wavelength λ_0 ;

f) the crests are curved in a horizontal plane with their convex sides pointed in the direction of propagation; the radii of curvature R_c , range from essentially infinity to a few kilometers;

g) as the packet progresses up on the shelf, there is some evidence of a continued increase in the wavelengths throughout; this may be accounted for by a combination of linear dispersion and nonlinear effects akin to solitary wave behavior.

All the parameters of the internal wave packets are shown in a schematic way in Fig. 3.2.

Although there is no doubt about the identification of the above discussed features as internal waves, some non-users of satellite data can argue about the identification of the same. Here are some justifications (Apel and Charnel, 1976):

i) They exhibit the correct properties and behavior of internal waves.

ii) If they were surface waves, the average wavelength of 1000 m would imply a swell with the extremely long period of 24 sec and a significant wave height less than about 15 m (assuming a maximum

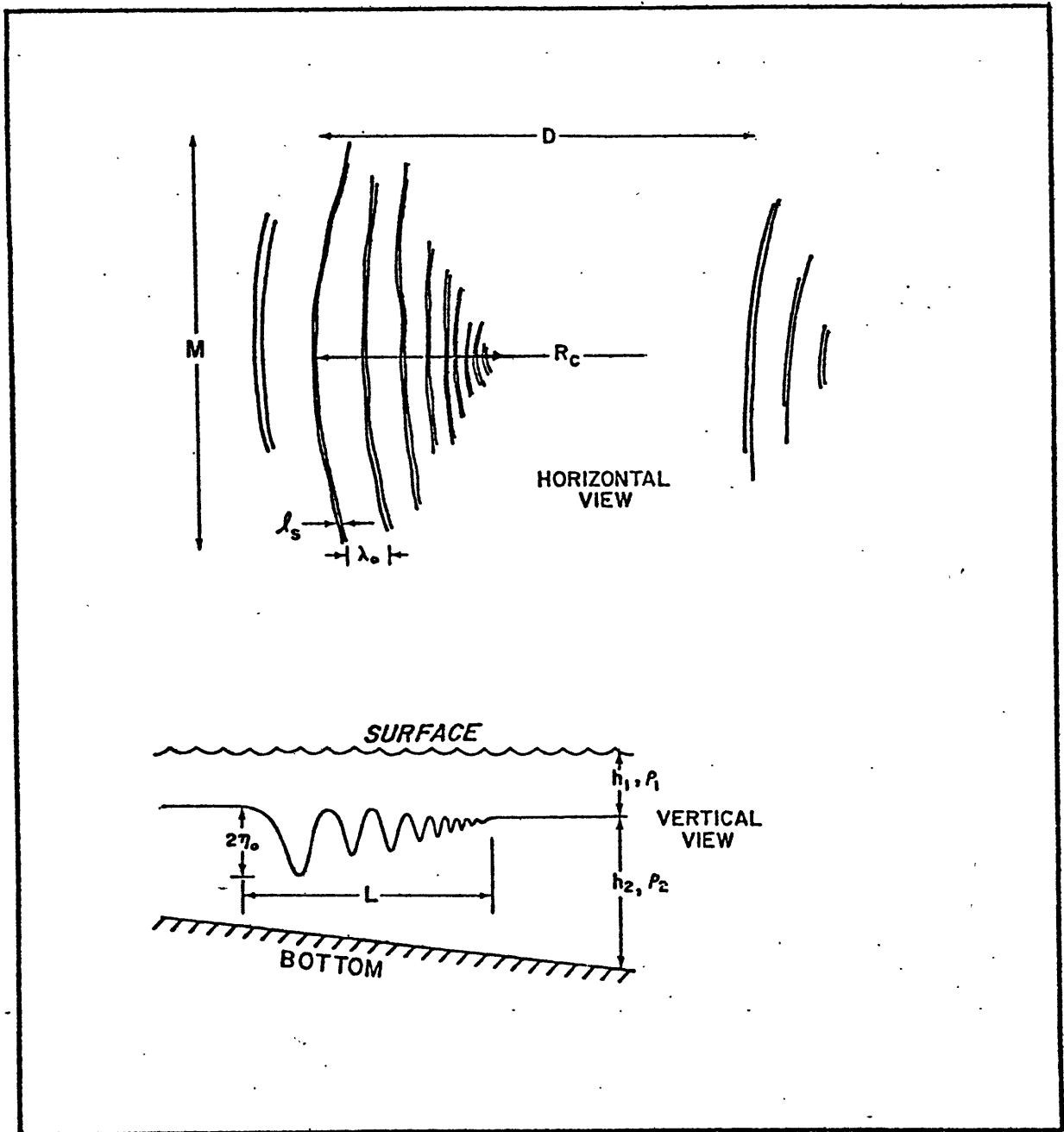


Figure 3.2 - Schematic representation of the parameters in an internal wave packet (After Apel et al. 1976).

slope of 1:30), weather information for the days registered seas have been low and the winds light (for an average swell period of 10.5 sec the wind force must be 12 in Beaufort scale, Defant, Vol II, pg. 62), thereby eliminating surface waves possibility;

iii) Atmospheric internal waves as defined by clouds are certainly visible on ERTS-A/B images. For these, the widths of the striations due to individual clouds are of the order $1/2$ of wavelength while the the pressured ocean striations have widths generally a small fraction of λ . Furthermore, the latter are most visible when the atmosphere is most cloud-free.

iv) Film or instrument artifacts have been eliminated by NASA/GSFC personnel (Apel and Charnel, 1974).

There is also the positive side of the question, that is also listed in the above referenced paper.

As to the sources and sinks for these internal waves, there is no doubt that they are "daughter" waves generated for a few hours during the peak current velocity by the long-wavelength baroclinic tide occurring at the edges of the continental shelves. They then propagate with very low phase speeds, of order 0.2 to 0.5 m/sec to be absorbed in the bottom sediments where the wave breaks on the shelf.

3.2 The Images, Climatological and Ground Truth Data

The primary source of data for the present work was the atlas of Sawyer and Apel (1976), which contains mosaics of images of LANDSAT satellite showing internal waves in the eastern coast of the United States. The images are second generation prints of ERTS images on photographic film. The scenes showing surface slicks to best advantage are usually those of channel 6 (600-700 nm) and occasionally channel 7 (700-800 nm). These scenes were enlarged to a scale 1:1,000,000 on high-contrast emulsion that enhanced the visibility of the slicks (Apel and Sawyer, 1976). The wave packets are also plotted on a nautical chart in the same scale as the satellite images.

A total of 78 measurements of the distance between two successive wave trains were performed. The images exhibiting this phenomenon were taken during summer months, June, July and August of 1972, 1973 and 1974.

Figs. 3.1a and 3.1b show enlargements of ERTS images where internal wave packets can be seen. These packets usually appear on the continental shelf, often in long lines parallel to the slope, leaving no doubt about their generation.

Since the interest is aimed at possible short-term variations, the data were divided according to the month of the event. The month of June had only very few measurements in the last days of the month, so there we added to the July set of data. For each event a point was selected such that it was located between the wave trains and at the middle of the distance D , defined in the previous section. These points are shown in Figs. 3.3 and 3.4 All data are summarized in Table I.

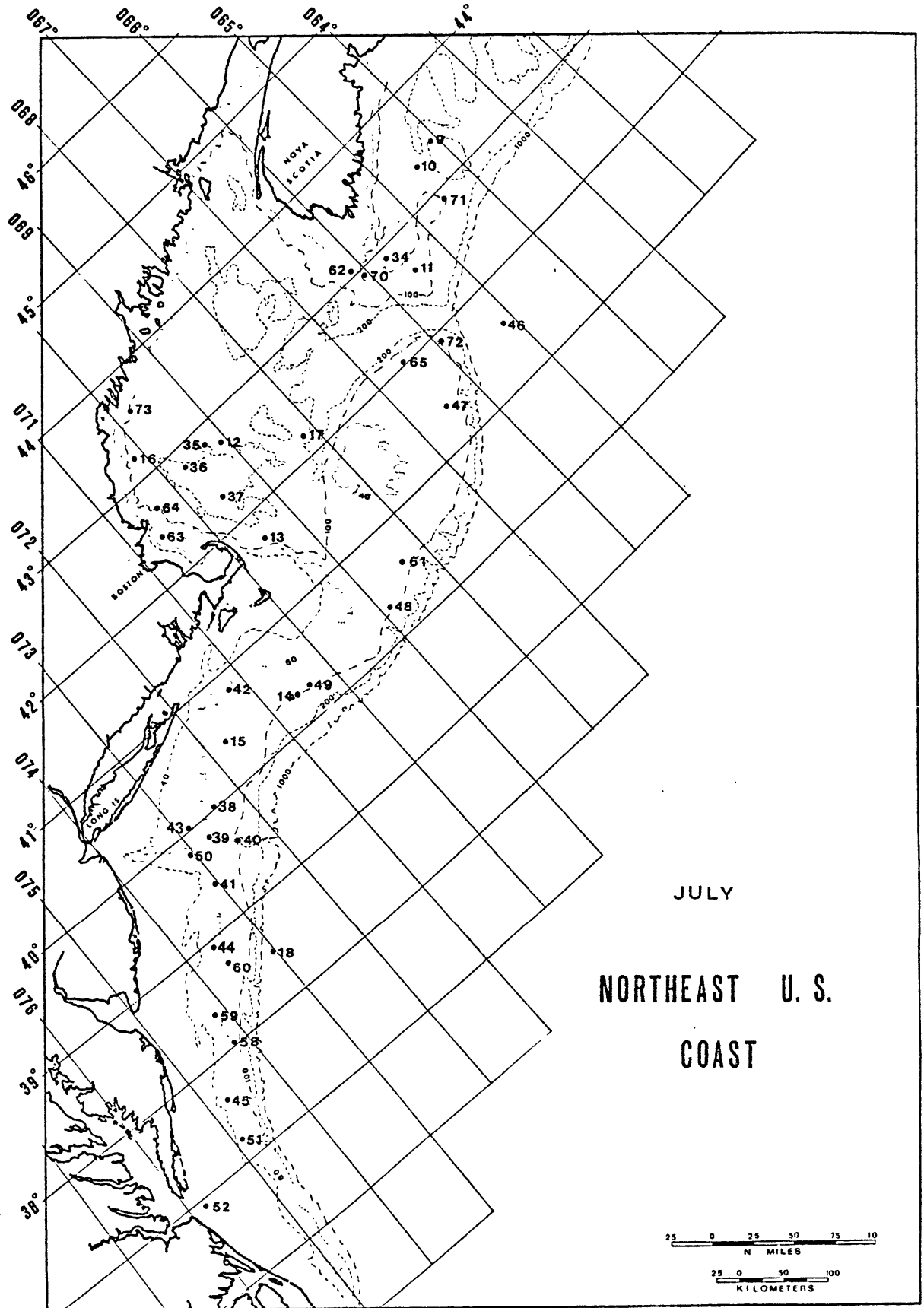


Figure 3.3 - Geographical distribution of internal waves observations for the month of July (1972, 1973 and 1974).

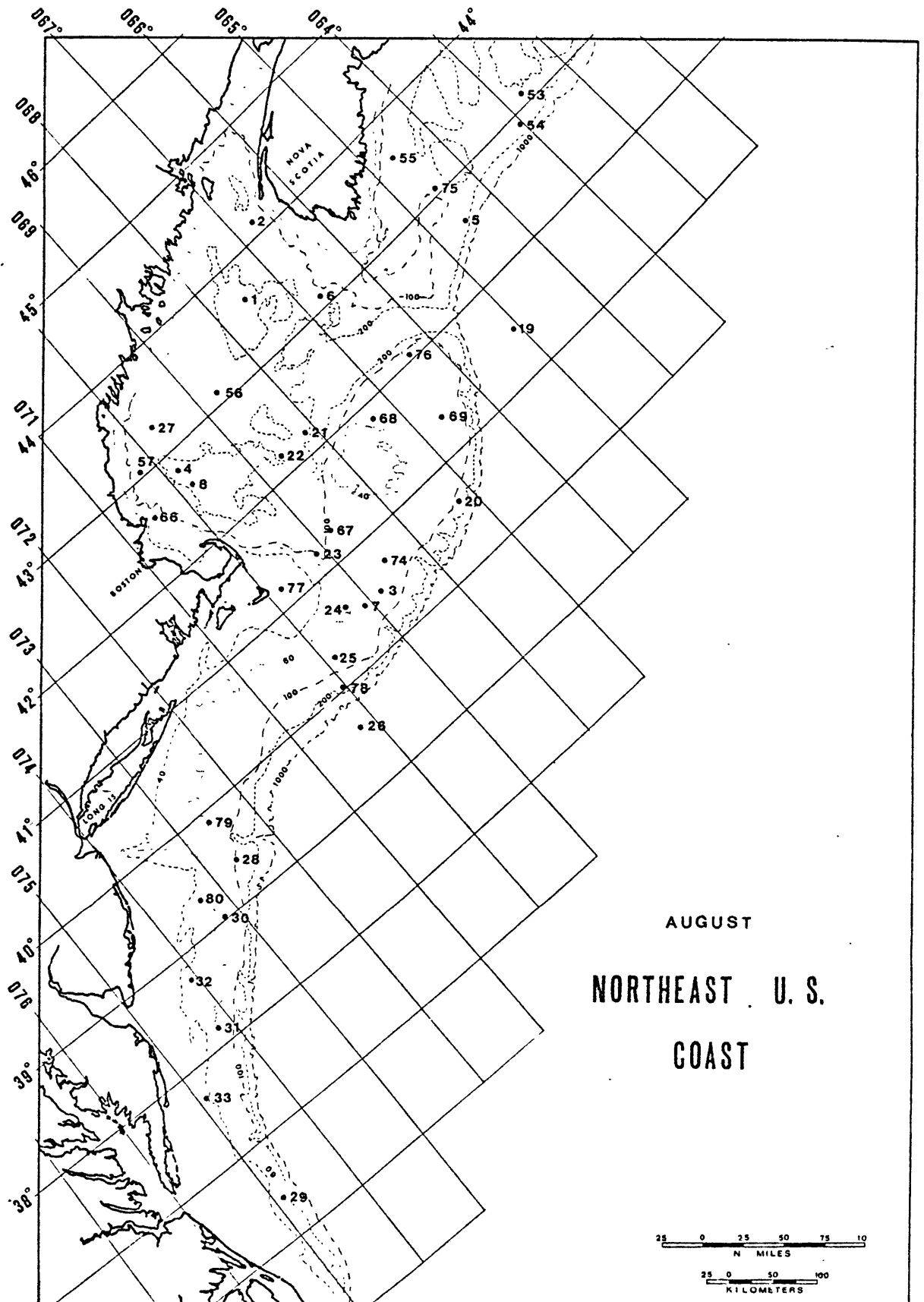


Figure 3.4 - Geographical distribution of internal waves observations for the month of August (1972, 1973 and 1974).

TABLE I

Summary of observation of internal waves from satellite: Observation Number, Day of the Year, Latitude, Longitude, Heat Stored Distance between the Packets, Mixed Layer Depth, and M.L. Depth taking F into account.

OBS.#	MO.DAY.YEAR	LATITUDE	LONGITUDE	AM.HEAT(K CAL/CM ²)	DIST(KM)	M.L.DEP(M)	M.L.D.W/F(M)
1	82074	43.6	67.5	3.6	12.0	7.7	7.7
2	82074	44.2	66.7	3.6	12.0	37.7	38.8
3	82174	40.5	68.8	3.6	12.0	8.4	8.3
4	82274	42.8	69.8	2.5	10.0	6.8	6.8
5	81174	42.6	64.5	3.0	11.0	5.2	5.1
6	80274	43.1	66.7	8.1	18.0	38.6	39.1
7	80374	40.5	69.1	3.6	12.0	4.3	4.3
8	80474	42.6	69.8	2.5	10.0	6.8	6.8
9	71374	43.4	64.1	3.6	12.0	8.8	8.7
10	71474	43.3	64.5	3.6	12.0	8.8	8.7
11	71474	42.6	65.4	6.4	16.0	35.3	35.8
12	71774	42.7	69.1	3.6	12.0	6.2	6.1
13	71774	41.7	69.6	6.4	16.0	24.4	24.4
14	71774	40.3	70.6	4.9	14.0	11.8	11.9
15	71774	40.4	71.7	1.6	8.0	2.7	2.6
17	62874	42.2	68.2	8.1	18.0	20.2	20.4
18	63074	38.5	73.0	8.1	18.0	41.4	41.6
19	80673	41.4	65.1	6.4	16.0	61.0	72.1
20	80773	40.6	67.2	4.9	14.0	22.3	22.3
21	80773	42.2	68.1	4.9	14.0	26.3	26.7
22	80873	42.2	68.6	3.6	12.0	19.3	19.4
23	80873	41.2	69.1	1.6	8.0	8.4	8.4
24	80873	40.6	69.3	3.6	12.0	4.3	4.3
25	80973	40.3	69.9	3.6	12.0	4.3	4.3
26	80973	39.6	70.2	3.6	12.0	8.3	8.3
27	80973	43.3	69.7	2.0	9.0	2.0	2.0
28	81073	39.4	72.6	1.6	8.0	5.8	5.8
29	81173	36.4	74.9	4.9	14.0	10.3	10.3
30	81173	39.0	73.2	3.6	12.0	10.3	10.4
31	81173	38.3	74.2	6.4	16.0	7.2	7.2
32	81173	38.8	74.1	2.5	10.0	2.8	2.8
33	81273	37.7	74.9	3.6	12.0	4.2	4.2
34	71973	42.9	65.7	4.9	14.0	27.0	27.1
35	72273	42.8	69.3	3.6	12.0	6.2	6.1
36	72273	42.8	69.7	3.6	12.0	6.2	6.2
37	72273	42.3	69.6	4.9	14.0	8.4	8.3
38	72373	40.0	72.4	8.1	18.0	8.8	8.8
39	72373	39.8	72.7	3.6	12.0	6.3	6.3
40	72373	39.6	72.4	6.4	16.0	11.3	11.3
41	72373	39.4	73.0	4.9	14.0	7.8	7.8
42	72373	40.8	71.2	3.6	12.0	4.6	4.6
43	72473	40.0	72.9	8.1	18.0	8.8	8.8
44	72473	38.9	73.6	3.6	12.0	18.4	18.4
45	72473	37.6	74.7	3.6	12.0	4.7	4.6
46	70173	41.6	65.2	1.6	8.0	19.7	19.6
47	70173	41.4	66.5	4.9	14.0	10.0	10.0
48	70373	40.3	68.9	1.6	8.0	4.5	4.4
49	70473	40.3	70.4	3.6	12.0	8.8	8.7
50	70673	39.8	73.0	8.1	18.0	12.9	12.9
51	70673	37.2	74.9	3.6	12.0	4.7	4.6
52	70773	36.9	75.8	2.5	10.0	1.9	1.9
53	80972	43.1	62.7	3.6	12.0	5.7	5.7
54	80972	42.9	63.0	3.6	12.0	3.5	3.5
55	81172	43.6	64.7	8.1	18.0	33.3	33.6
56	81372	43.1	68.7	2.5	10.0	8.6	8.5
58	70673	38.1	74.3	3.6	12.0	8.5	8.5
59	70673	38.4	44.2	1.6	8.0	3.8	3.7
60	70673	38.8	73.6	3.6	12.0	18.4	18.5
61	70373	40.6	68.4	4.9	14.0	13.9	14.0
62	71973	43.0	66.1	1.6	8.0	17.7	17.7
63	72273	42.4	70.6	0.6	5.0	0.9	0.9
64	72373	42.7	70.4	2.5	10.0	2.6	2.5
65	71973	42.0	66.5	6.4	16.0	23.1	23.3
66	81073	42.6	70.5	2.5	10.0	3.5	3.5
67	80873	41.3	68.8	4.2	13.0	7.8	7.8
68	80773	41.8	67.3	2.5	10.0	26.2	26.3
69	80673	41.4	66.6	2.5	10.0	19.4	19.7
70	62774	42.9	66.1	3.6	12.0	12.6	12.6
71	71474	42.9	64.5	3.6	12.0	17.5	17.7
72	71474	41.9	65.9	3.6	12.0	44.4	44.7
73	71874	43.6	69.8	2.5	10.0	2.4	2.4
74	80374	40.7	68.5	3.6	12.0	8.4	8.3
75	80174	43.1	64.4	2.5	10.0	10.3	10.3
76	80274	42.5	66.4	6.4	16.0	23.1	23.3
77	80474	41.2	69.8	0.6	5.0	2.1	2.1
78	82274	40.0	70.0	6.4	16.0	11.7	10.6
79	81672	39.9	72.6	2.5	10.0	9.0	9.0
80	81672	39.3	73.3	3.6	12.0	10.3	10.3

The other set of data used was climatological oceanographic data, which comprises mean monthly values of salinity and temperature at standard depths computed for each square of 1° latitude by 1° longitude over the continental shelf from Cape Hatteras to Nova Scotia. Those squares with large number of data were subdivided into four sub-squares of 0.5° latitude by 0.5° longitude. Most of the data was kindly offered by V. Worthington of the Woods Hole Oceanographic Institution.

Missing values at standard depths were replaced by those obtained by graphical interpolation. In few squares we have no values and these were obtained from recent cruises in the months of July and August, through the National Oceanographic Data Center. Among these data is found what can be called ground truth data, i.e. hydrographic data taken at almost the same time as the satellite pass. Two of these are five days apart and the other two are fifteen days apart from the satellite pass. These were the best we could get.

3.3 Preliminary Analysis of the Measurements

The measurements of the distance between successive wave packets taken from the satellite images is plotted in Fig. 3.5 as a histogram with 2 km interval. The distribution obtained suggests at least three dominant spacing multiples of a minimum spacing around 12 km.

The computations of the depth of the mixed layer (h) and of the heat stored (Q) based in the above measurements gave unrealistic results for large spacings, just because h and Q vary as C^2 ! We could ask - what is going wrong? But remembering that internal wave groups are only visible in surface images in the presence of capillary waves or short

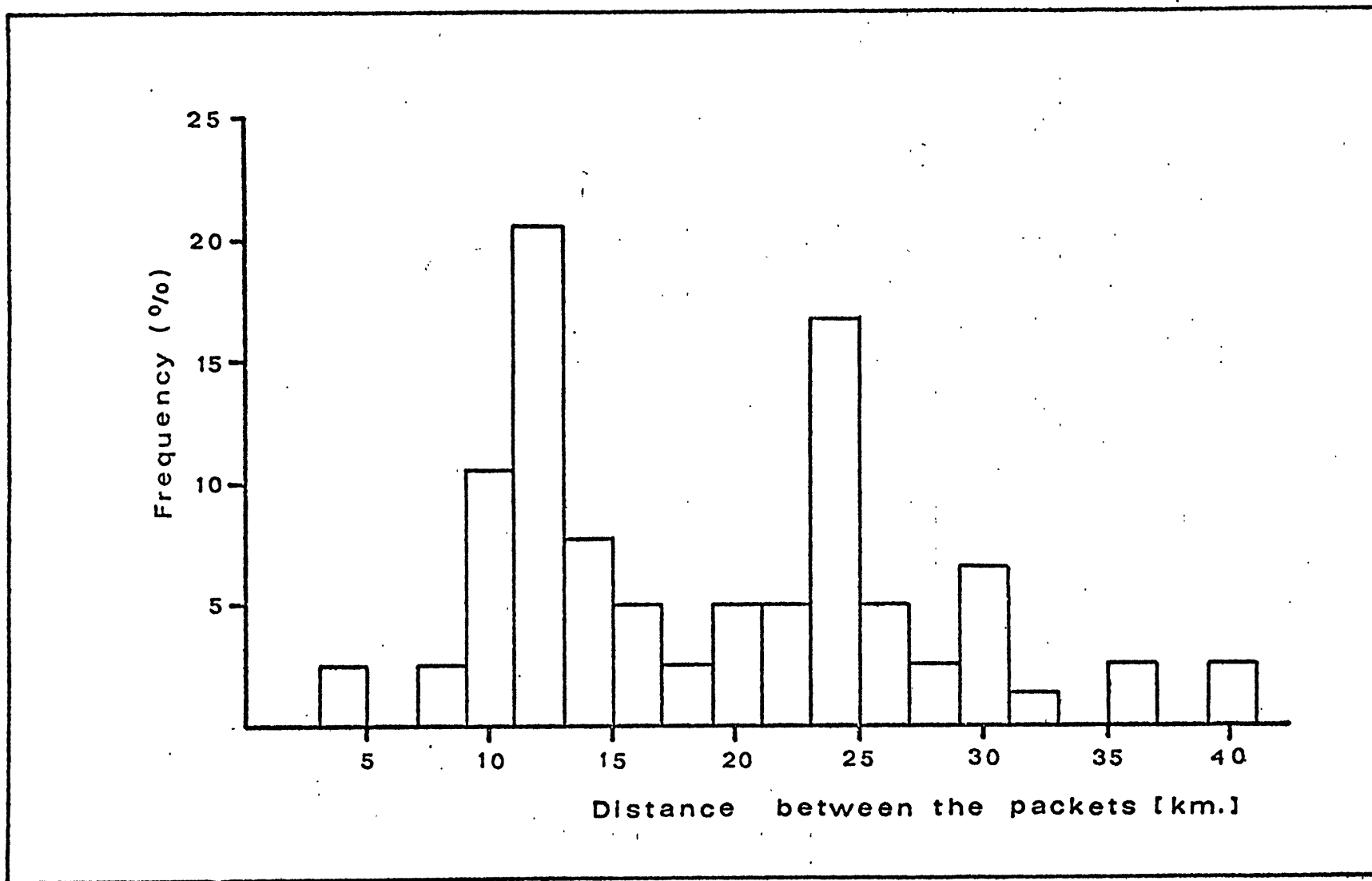


Figure 3.5 - Histogram of the original distances between the successive wave packets (78 observations).

gravity waves, which only occur when there is wind, (Gargett and Hughes, 1972), the distribution can be interpreted to mean that there is only one wave packet spacing in a given location during the period of the observations. This procedure assumes that the observation of multiple of the minimal group spacing simply means that one has missed some groups since they are not visible because of an absence of surface ripples which can be modified by the internal wave velocity field. On this hypothesis, we assumed that there is a single wave packet spacing, and obtained the histogram shown in Fig. 3.6 including all the wave packets measured.

This interpretation may give an overly provable results, since it suppresses variations from the mean longer than the mean, and since such values are modified by the subtraction of a multiple of the mean.

Over the continental shelf typical values for reduced gravity is $g' \sim 0(1)g \text{ cm}^{-3}$. For mixed layer depth it is $h \sim 0(10^3)\text{cm}$. This yields a typical velocity of propagation $c \sim 0(30)\text{cm sec}^{-1}$ and a typical spacing $D \sim 0(14)\text{km}$.

Another support for the Gaussian type of distribution is wave trains found in overlapped satellite images. The ERTS overlapped images are taken 24 hours apart in time. A wave train identified in overlapping images are supposed to be 24 hours apart if there are no topographic features able to generate internal waves in the region. Waves satisfying these requirements were found and the distances between the packets were at least 24 km, corroborating the hypothesis. The values of the depth of the mixed layer and the amount of heat stored were recalculated after this procedure and the new values were quite reasonable.

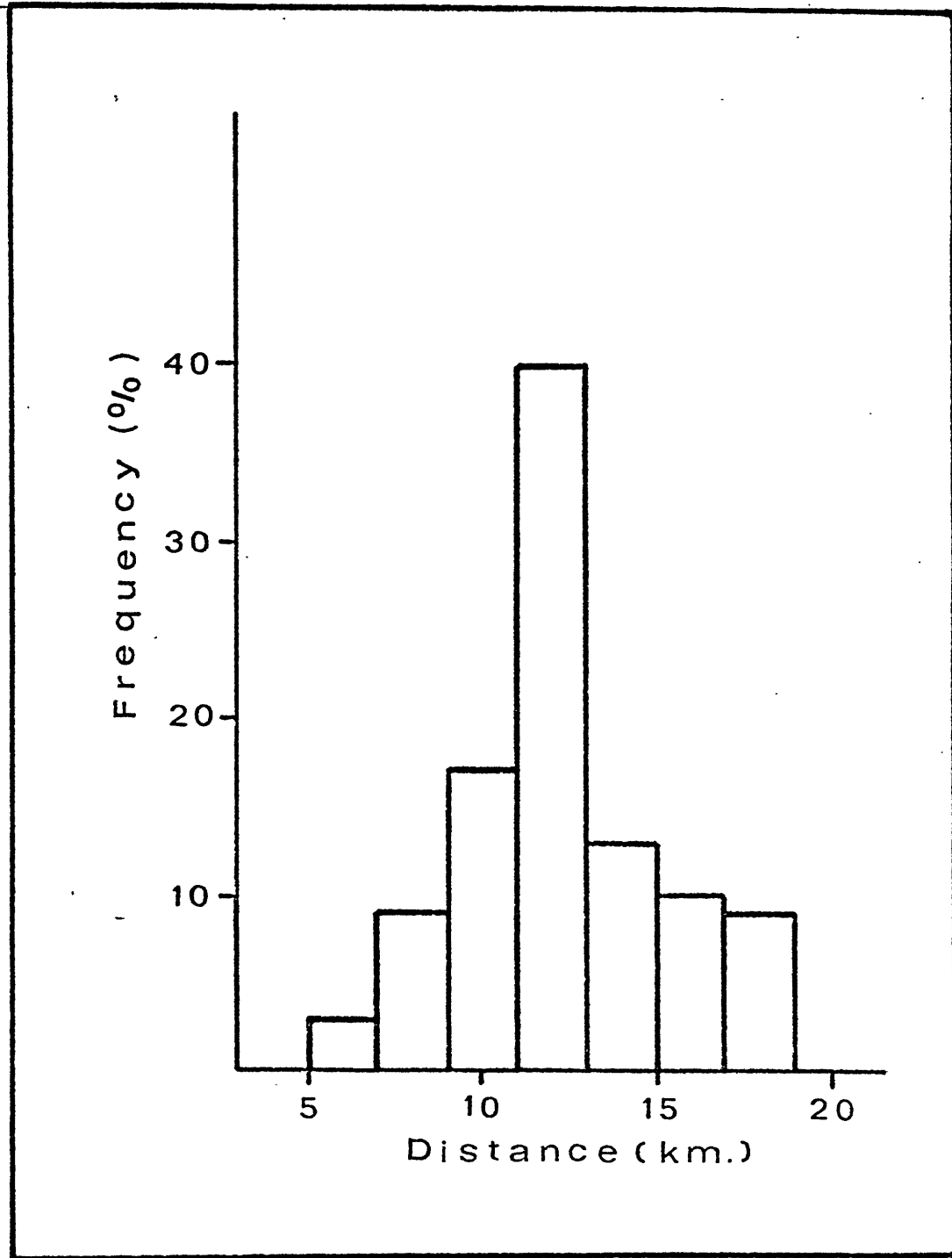


Figure 3.6 - Histogram of the distance between the wave packets corrected by the multiples of the fundamental minimum distance (78 observations).

4. THE MIXED LAYER DEPTH IN THE OCEANS

4.1 The Stablishing Factors of the Depth of Mixed Layer

In the open ocean there is generally an isothermal surface layer which extends downward from the sea surface. The thickness of this layer is the mixed-layer depth. In a region away from oceanographic boundaries and in the absence of turbulent mixing by strong currents, this depth is assumed to be influenced by two surface-induced processes - wind mixing (forced convection) and convective mixing (free convection). Wind mixing includes all the vertical turbulent mixing processes resulting initially from the transfer of momentum from the wind to the sea. These are the mechanical mixings due to wave action (Laevastu, 1960), turbulent mixing due to the shear of drift currents (Ekman, 1905; Rossby and Montgomery, 1935; Munk and Anderson, 1948), and helical vortices (Langmuir, 1938). Convective mixing occurs as a result of instability created at the surface by surface cooling and by evaporation of fresh water from the sea.

Another surface induced process, if we neglect the effect of diffusion, is the entrainment responsible for the exchange with the water below. The entrainment flow can only be directed towards the more turbulent fluid region, that is, upwards in the present case, cooling and increasing the density of the upper layer. In the absence of entrainment, all the turbulent fluxes become zero at the boundary. This means physically that there is just not enough turbulence energy available to overcome the stable stratification at the base of the layer to produce any mixing with the lower water.

Other factors that can influence the depth of the mixed layer are advection and divergence or convergence due to Ekman transports.

Although it is generally accepted that both forced and free convection are important factors influencing the upper mixed layer, wind mixing can be considered to be the main factor in the considered region and time of the year; convective mixing is assumed to be the secondary. Tabata et al. (1965) showed that there is a linear relation between the mean wind speed averaged 12 hours in advance of the bathythermograph observation and the depth of the summer isothermal surface layer at ocean station P.

In the region considered here the currents over the continental shelf are mainly driven by the meteorological conditions and the drift velocities range from 5 to 25 cm sec⁻¹ (Bumpus and Lauzier, 1965), and can be considered weak. We can say that the transport of surface waters have little effect on the properties of the water, but horizontal and vertical mixing are dominant (Ketchum and Corwin, 1964). Thus we can assume the interaction between the sea and the atmosphere to be the dominant factor affecting the upper layers of the ocean in the studied region.

4.2 Estimation of the Mixed Layer Depth

4.2.1 From 2-Layer Model

An application of the results derived in sections 2.1 and 2.2 will be discussed here. The velocity of propagation of the interfacial wave is

$$c^2 = g \frac{\rho_2 - \rho_1}{\rho_2} h_1 \quad (4.2.1.1)$$

From this relation it is seen that if we know the velocity of propagation c , the density difference $\Delta\rho$, and the density of the lower layer ρ_2 , it will be possible to compute the depth of the interface h_1 that we will call mixed layer depth.

The velocity c can be estimated from the distance between two consecutive trains of waves in the satellite images, and assuming they are 12.4 h apart in time (semi-diurnal period), the difference in density $\Delta\rho$ and ρ_2 can be obtained from climatological data. The acceleration of gravity can be assumed to be $980.665 \text{ cm sec}^{-2}$. Table I shows the result of the computation of h_1 using the relation

$$h_1 = \frac{c^2}{g'} = \frac{c^2 \rho_2}{g \Delta\rho} \quad (4.2.1.2)$$

The same computation of h was repeated, now using the equation (2.2.12) , that is, the same 2 layer model but taking into account f , (see also Table I.)

$$h_f = \frac{(c^2 - f^2/\alpha^2)^{1/2}}{\alpha c} \coth^{-1} \left[\frac{g'}{\alpha c} \frac{1}{(c^2 - f^2/\alpha^2)^{1/2}} \right] \quad (3.2.1.3)$$

The values computed using the above equation differ only slightly from those computed from (4.2.1.2), and for practical purposes they can be considered equal. So it is perfectly right to neglect f in the dynamical equations.

Computed values of the depth of the mixed layer were plotted over a chart of the New England continental shelf for the month of July and August and are shown in Figs 4.1 and 4.2.

4.2.2 Comparison with Ground Truth Data.

A comparison between the depth of the mixed layer computed using the expression (4.2.1.1) and the ground truth observations was made.

The closest hydrographic observations performed to the satellite pass are shown in Figure 4.3. From this figure we can estimate the depth of the mixed layer. We took as mixed layer depth the depth just before the pycnocline. Table II shows the results of the comparison.

We must have in mind that the standard depth for sampling in hydrography are 0 m, 10 m, 25 m, ... when using Nansen bottles.

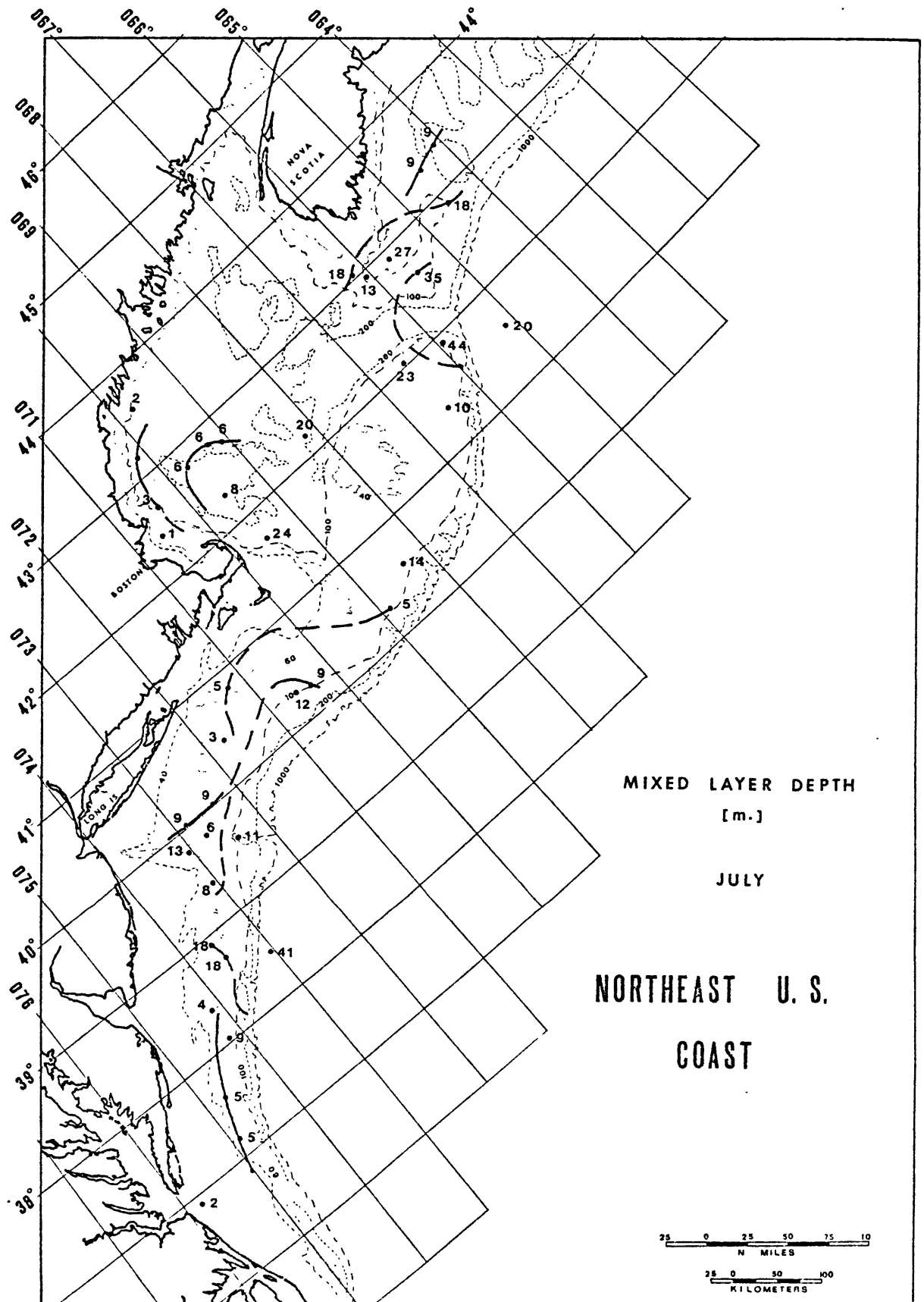


Figure 4.1 - Mixed layer depth computed from satellite observations of internal waves for the month of July (1972, 1973 and 1974);

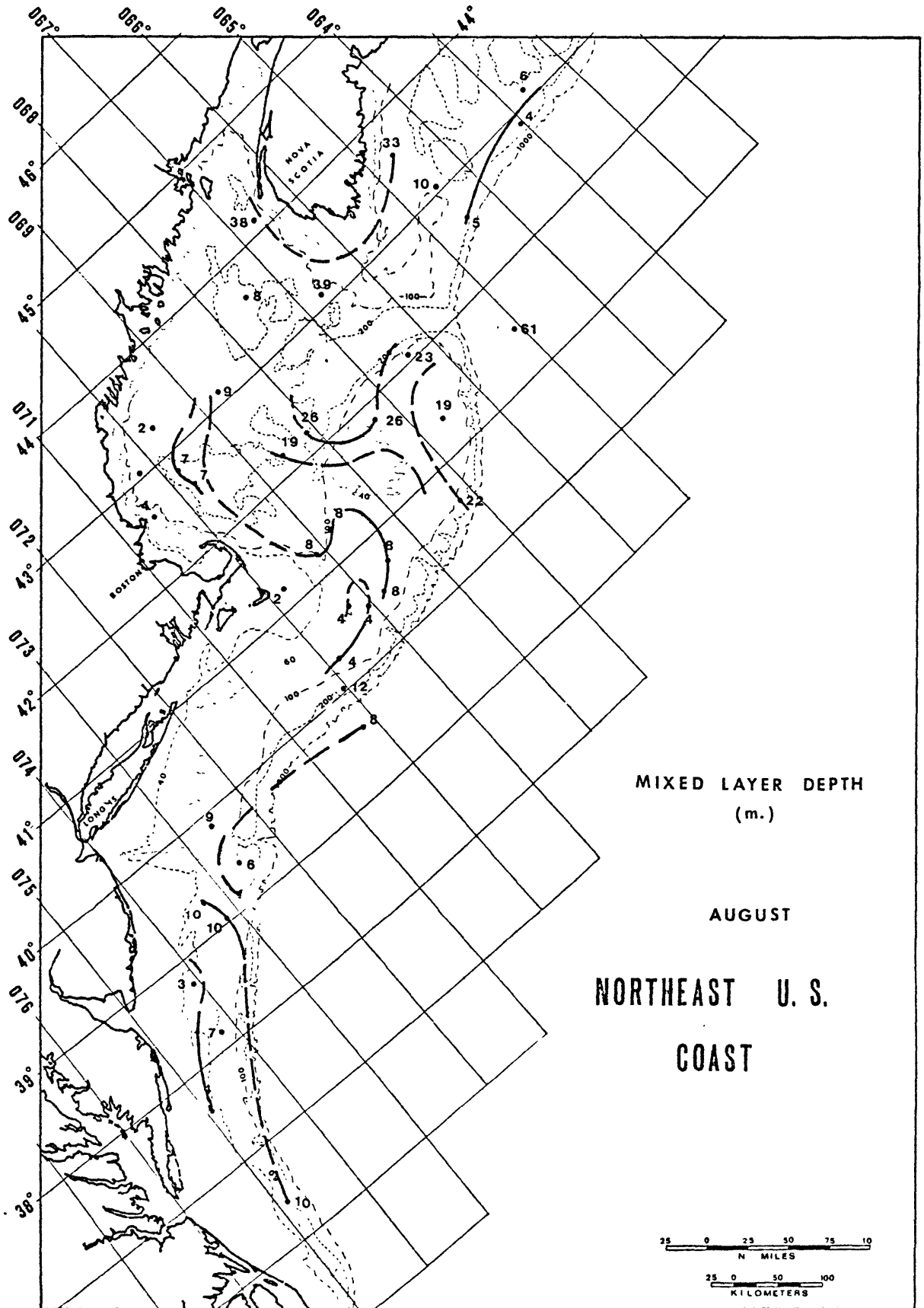


Figure 4.2 - Mixed layer depth computed from satellite observations of internal waves for the month of August (1972, 1973 and 1974).

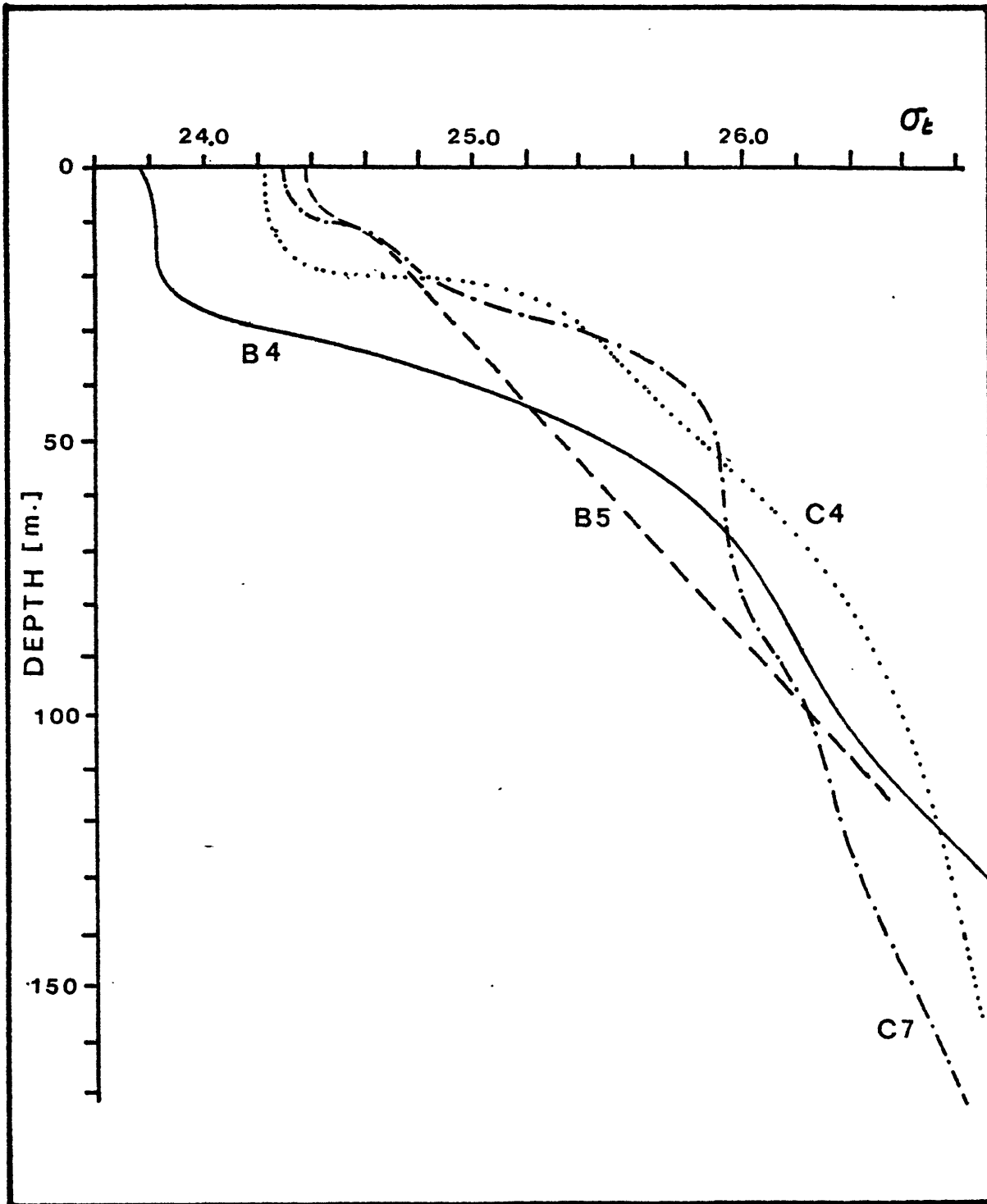


Figure 4.3 - Density profiles taken from hydrographic observations used as ground truth.

TABLE II

COMPARISON BETWEEN VALUES OF MIXED LAYER DEPTH (h) AND AMOUNT OF HEAT STORED (Q) COMPUTED FROM SATELLITE OBSERVATION AND THE CLOSEST HYDRO COST IN SPACE AND TIME.

	Date	Latitude	Longitude	h (m)	Q (k cal cm ⁻²)
sat obs #65	07-19-73	42.01°N	066.30°W	23	6.23
hydro obs B-4	07-14-73	42°26 N	066°13 W	30	9.98
sat obs #70	06-27-74	42.57°N	066.03°W	36	3.51
hydro obs C-7	07-11-74	43°03 N	066°53 W	26	5.04
sat obs #62	07-19-73	43.02°N	066.06°W	10	1.56
hydro obs B-5	07-14-73	42°42 N	066.40 W	9	3.56
sat obs #76	08-02-74	42.50°N	066.40°W	24	6.24
hydro obs C-4	07-13-74	42°31 N	066°11 W	20	9.30

Consequently if we have a sharp pycnocline between 0 and 10 meters we can not recognize it by plotting the standard depth values. This means that a lower value of mixed depth layer, computed by (4.2.1.1), could be hidden in the ground truth data due to the coarse sampling points.

5. THE AMOUNT OF HEAT STORED IN UPPER LAYERS OF THE OCEAN

5.1 The Role of the Stored Heat

An extremely important component of the earth's heat balance is the storage of heat in the summer hemisphere and its release in the winter hemisphere. Except in certain land areas where a considerable seasonal fluctuation in soil moisture takes place, heat storage is severely limited by the comparatively slow rate of heat conduction in the solid earth. The relatively low heat capacity of air restricts seasonal heat storage by the atmosphere. The hydrosphere, on the other hand, is partly transparent to short-wave radiation, has a great heat capacity, and is in nearly constant turbulent motion. It is able, therefore, to play a dominant role in seasonal heat storage.

The heat stored in the seasonal upper warm layer of the oceans comes from solar radiative input and is in part balanced by losses to the atmosphere in the form of radiation and diffusion of sensible heat and latent heat of evaporation, as well as turbulent exchanges with deeper layers of the ocean. These processes, balanced by horizontal advection, determine the temperature, depth and the salinity of the upper layer, the time of layer formation in the spring, and the overturning and disappearance of the layer in late fall.

The heat stored in the upper ocean affects, both climatologically and synoptically, the weather development and the mixing processes in the layer driven by wind and thermal effects also transport oxygen, nutrients and biota. Observations indicate that seasonal heat storage takes place in the upper one hundred to one hundred and fifty meters of the ocean.

5.2 Heat Stored Calculations from In-Situ Measurements

The heat flux from the atmosphere through the sea surface ends up in different ways:

- a) it may raise the temperature of the ocean column,
- b) it may be carried away by horizontal advection, or
- c) it may be exchanged with deep colder layer.

The above processes actually occur simultaneously in the ocean.

The annual heating cycle of the water column over the continental shelf is well known, and as examples we have Figures 5.1a, 5.1b and 5.1c. These figures show the variation of the mean monthly values of temperature of the upper water column from the early spring to late summer for three representative regions of the eastern continental shelf. These regions cover three squares where we have some internal wave observations. Figure 5.1a shows the temperature profiles for the square $(42-43)^{\circ}\text{N} \times (065-066)^{\circ}\text{W}$, covering the entrance and the north part of the Northeast Channel, Gulf of Maine. Figure 5.1b shows the profiles for the square $(40-41)^{\circ}\text{N} \times (068-069)^{\circ}\text{W}$, covering the region of the continental shelf and continental slope east of Cape Cod. Figure 5.1c shows profiles of the square $(37-38)^{\circ}\text{N} \times (074-075)^{\circ}\text{W}$ covering the continental shelf and slope off Delaware and Maryland.

From these figures we notice that the water is heated from a minimum temperature profile $T_0(z)$ (March), to a maximum profile that could be August or September. As already pointed out in Chapter 5 we can neglect the advected heat, and here we are also going to neglect the exchange with the water below. We can then define the amount of

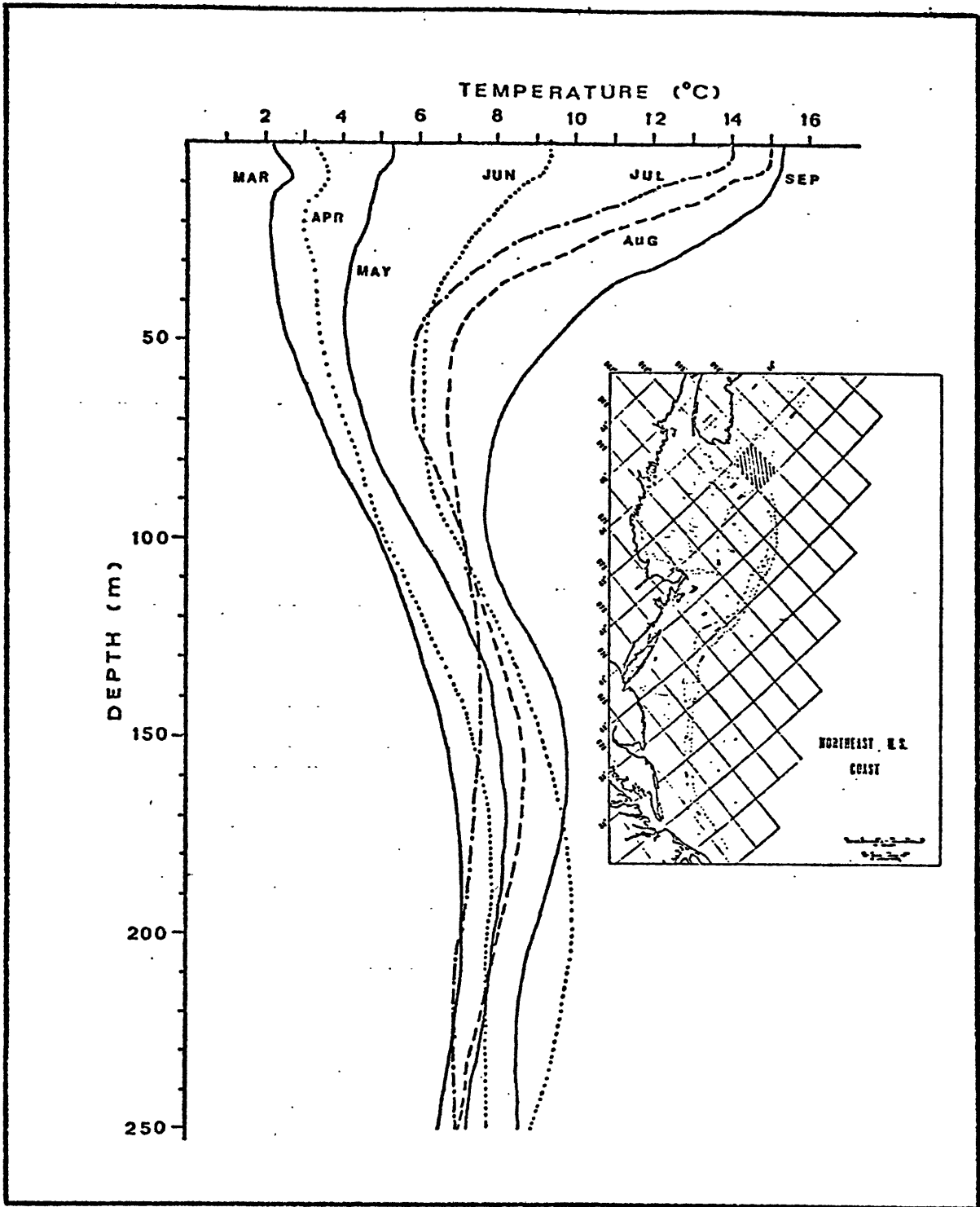


Figure 5.1a - The annual heating cycle of the upper ocean from the region (42-43)°N and (065-066)°W.

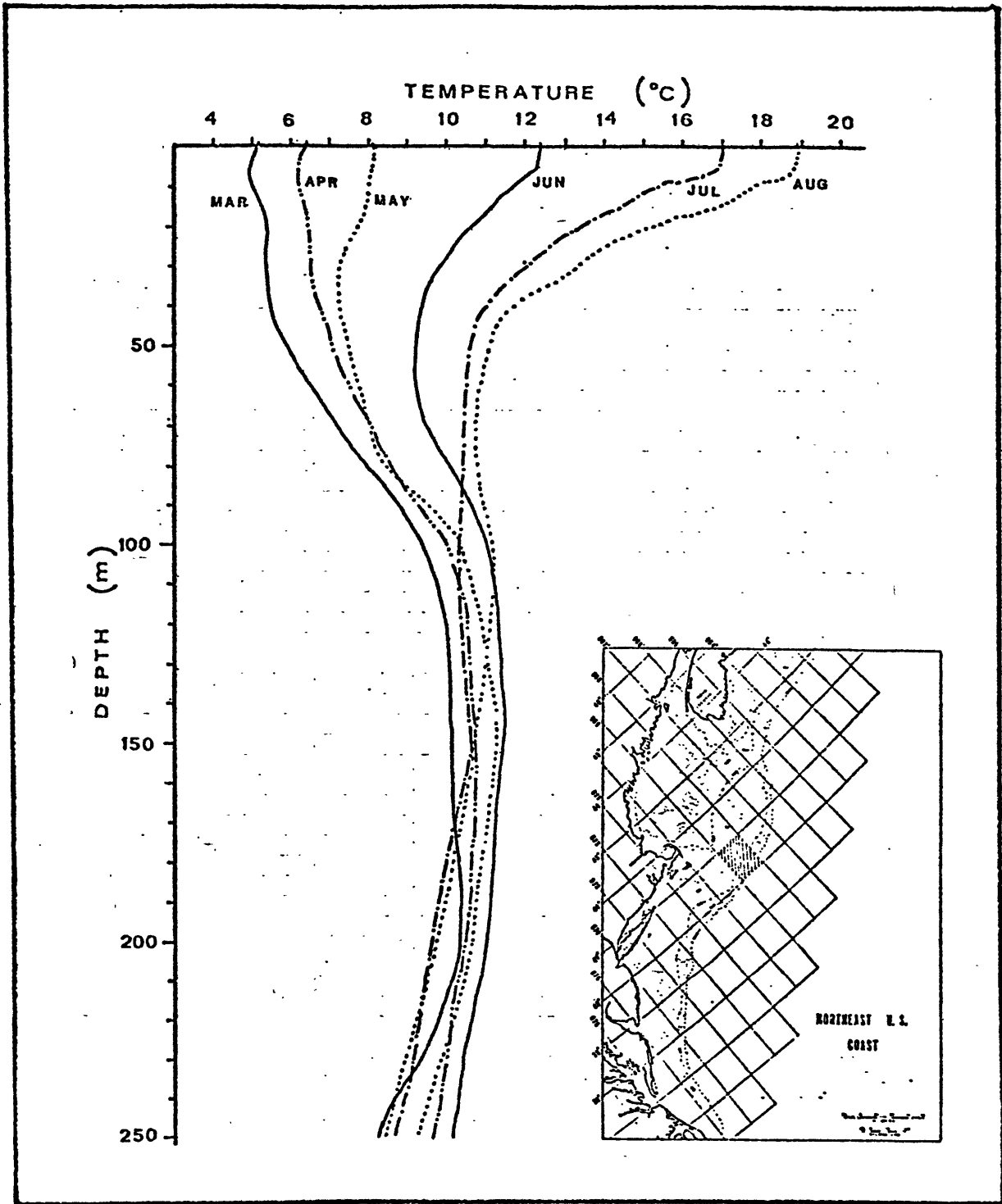


Figure 5.1b - The annual heating cycle of the upper ocean for the regions (40-41)^oN and (068-069)^oW.

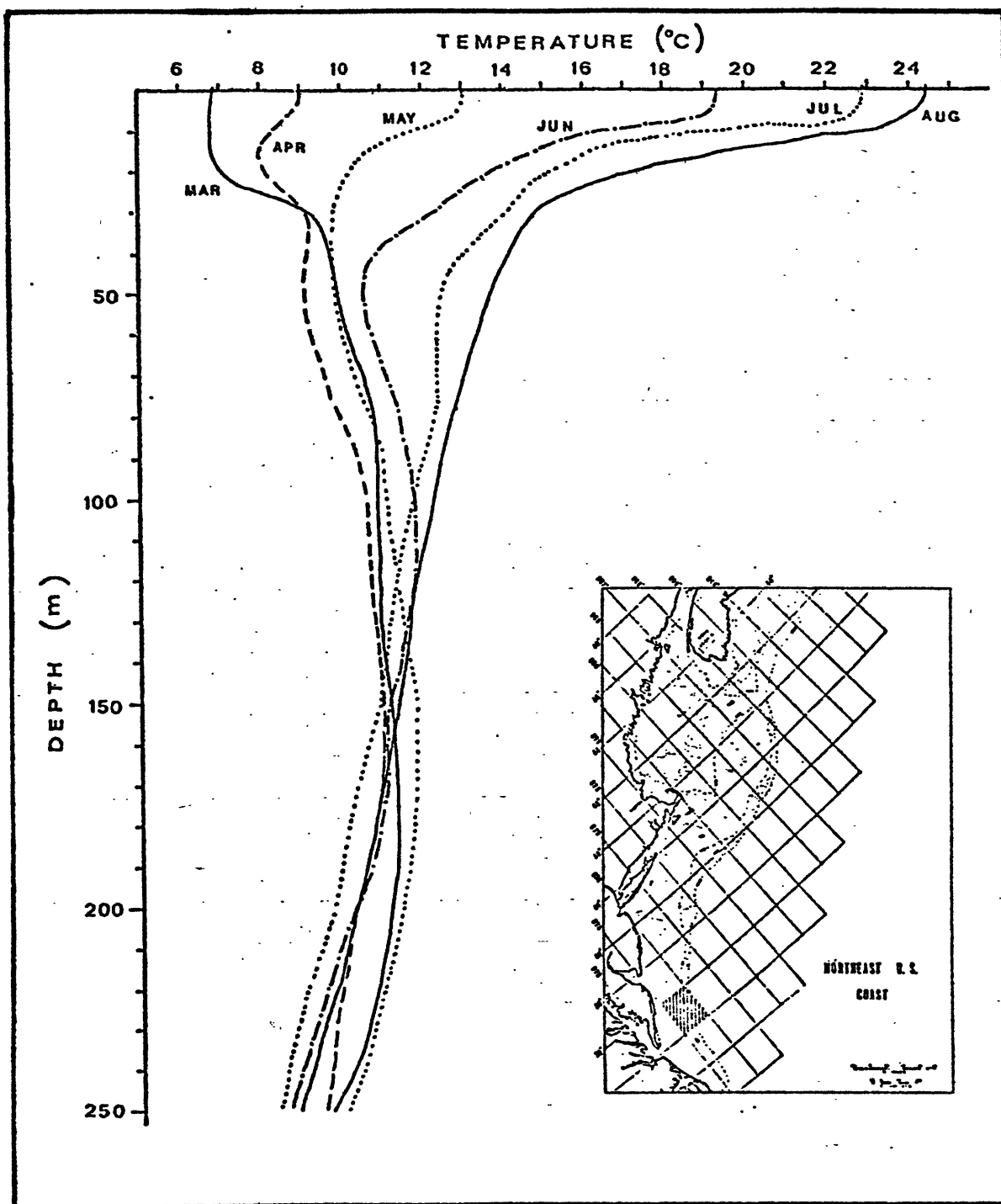


Figure 5.1.c - The annual heating cycle of the upper ocean for the region $(37-38)^{\circ}$ and $(074-075)^{\circ}$ W.

heat contained in the upper layer of the ocean as the heat accumulated from the minimum temperature profile $T_0(z)$ to a given profile $T(z)$ in absence of advection and exchange with water below as

$$Q_s = \int_{-h}^0 \rho c_p [T(z) - T_0(z)] dz \quad , \quad (5.2.1)$$

where ρ is the density of the sea water, c_p is the specific heat at constant pressure and h is the depth of the thermocline. When using this definition we must be aware that we are overestimating its value. To overcome this overestimation instead of using $T_0(z)$ for the month of March, we have chosen the minimum profile two months latter.

5.3 Heat Storage Calculations from Satellite Images

5.3.1 Based on Two-Layer Model

The most important application of the internal wave images from satellites is without doubt the fact that we can actually compute the amount of heat stored in the upper layer using only the velocity of propagation of the packets. Let us see how this can be done. Start with the amount of heat stored defined as

$$Q = \rho_1 c_p \Delta T h \quad , \quad (5.3.1)$$

Now we rewrite our equation of state (1.2.13) assuming that the changes in salinity are negligible when accounting for changes in density, and since we are dealing with a two-layer ocean,

$$\rho_1 = \rho_2 (1 - \alpha \Delta T) \quad (5.3.2)$$

The above assumption is critical because in estuaries, for example, the density is controlled mainly by the salinity gradient.

Figure 5.2 is a plot of values of $-\alpha\Delta T$ against $\beta\Delta S$, for the regions shown in the chart inside the figure. Besides the point drawn as an open circle, the other points indeed support the assumption that $\beta\Delta S$ is not so important as $-\alpha\Delta T$ in account for density changes.

The anomalous point describes the density changes for the coastal region east of Delaware, being under the influence of the Chesapeake Bay waters. Since we did not plot points for all regions we can expect the same behavior for coastal regions in the vicinity of large river mouths. Fortunately there are very few internal wave observations under such conditions. After all, these regions are no problem because we can overcome this fact by taking into account the salinity dependence by determining a function $g=g(T,S)$ through a T,S relationship for these regions and still keep a linear dependence on temperature. This procedure would also improve the determination of the density in other regions. From (2.1.7)

$$\frac{\Delta \rho}{\rho_2} = \frac{c^2}{gh} \quad (5.3.3)$$

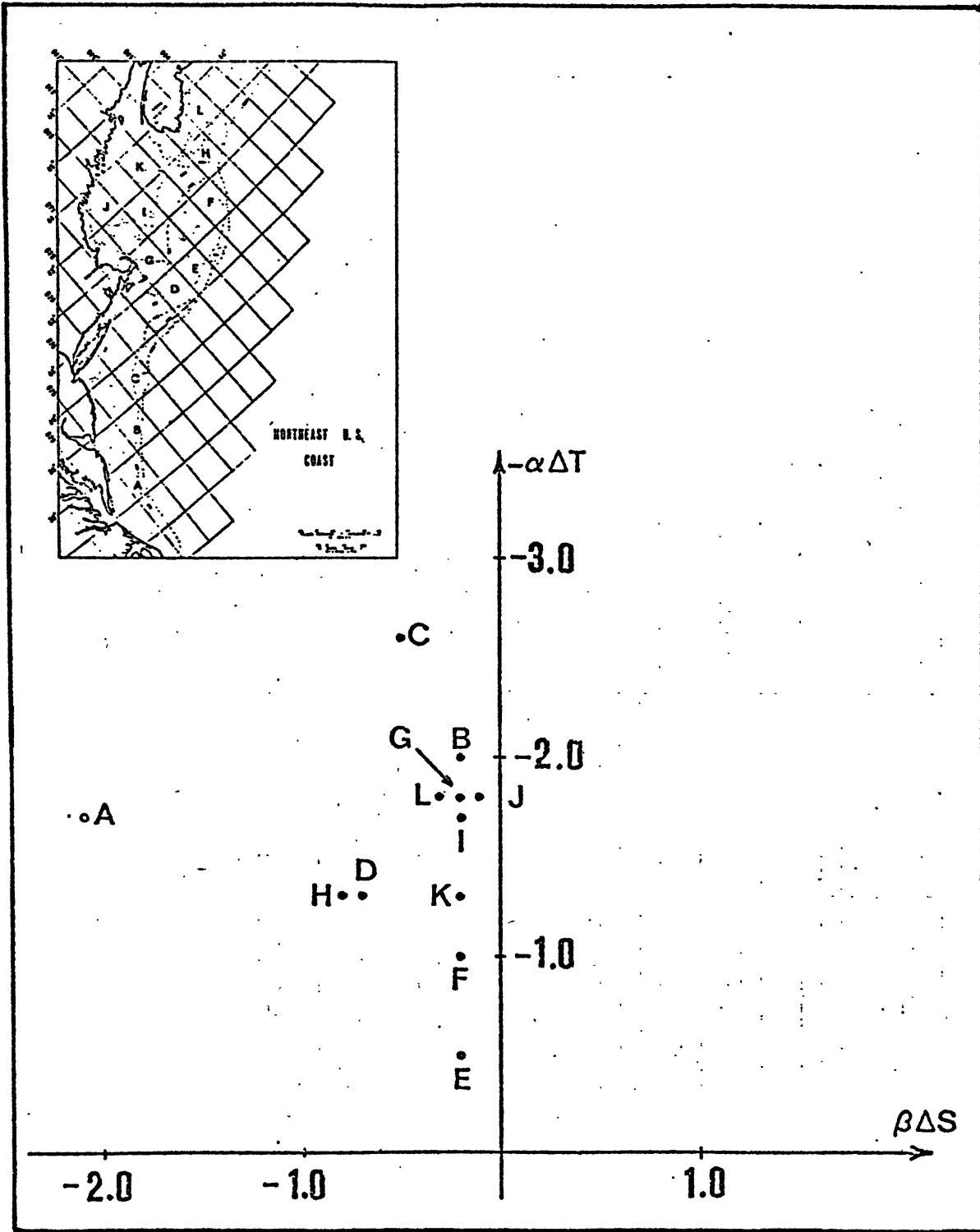


Figure 5.2 - Values of $-\alpha\Delta T$ and $\beta\Delta S$ from mean monthly values of T and S for the regions shown in the chart.

from (5.3.2)

$$\frac{\Delta \rho}{\rho_2} = \alpha \Delta T \quad (5.3.4)$$

Combining the relations (5.3.4), (5.3.3) and (5.3.1) and also assuming $\rho_1 \approx \rho_2$, which numerically will not make any computational difference, we get

$$Q = \frac{\rho_2 c_p c^2}{\alpha g} \quad (5.3.5)$$

The expression (5.3.5) gives us in cal cm^{-2} , if we use cgs units, the amount of heat stored in the upper layer, under the above assumptions. Assuming c_p , g and α constants, the only variables are c^2 , that is measurable from satellite images, and ρ_2 that can be inferred from climatological data.

The motivation to use ρ_2 instead of ρ_1 is that, although both are of order 1, the former one is less subject to small term variations than the last one.

The comparison with the scarce ground truth data available is shown in Figure 5.3. The values of heat stored inferred from satellite observations are less than the one computed from in-situ data and this will be discussed later. Charts of the heat stored in the upper layer over the New England continental shelf for the month of July and August are shown in Figures 5.4 and 5.5.

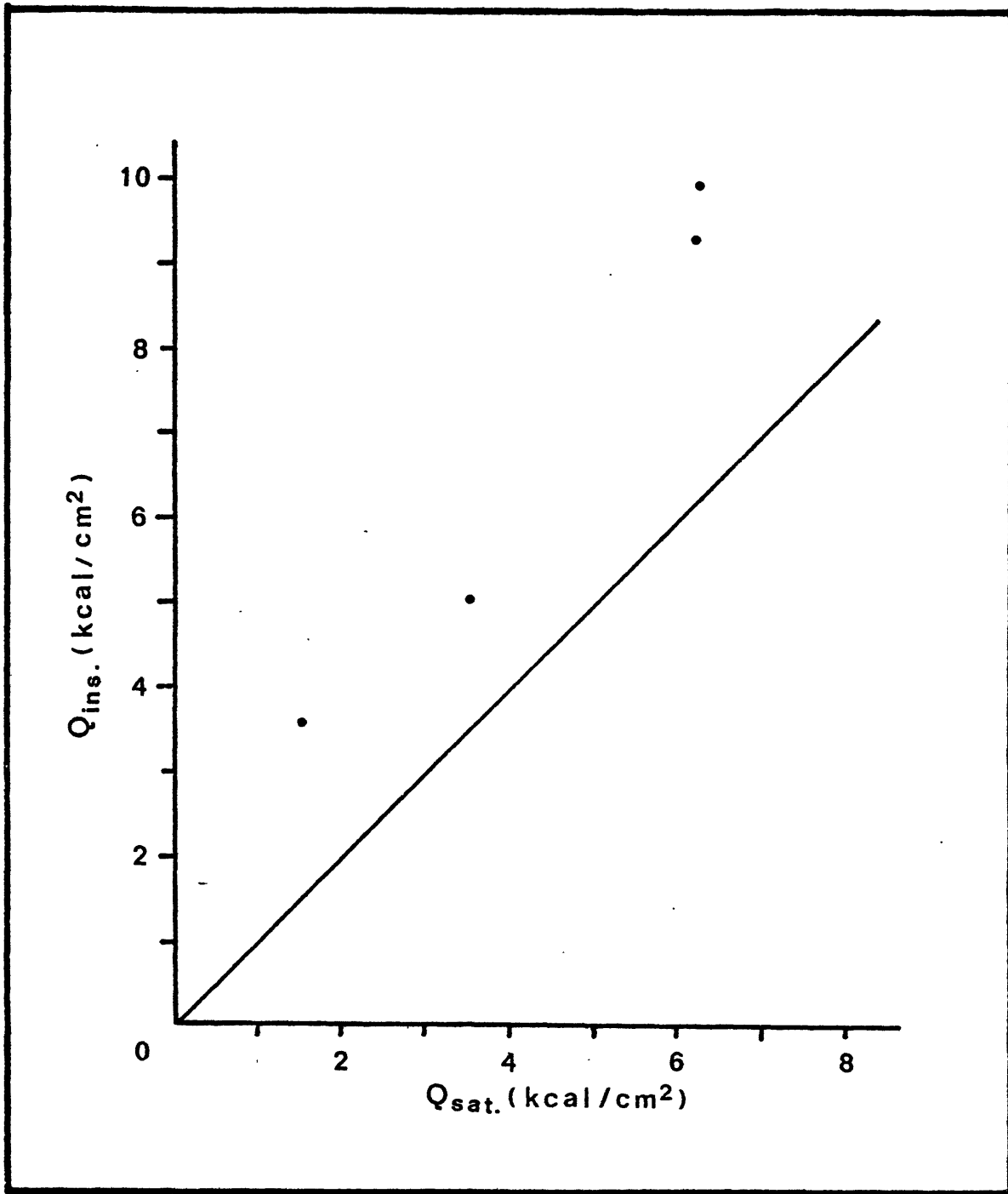


Figure 5.3 - Comparison of stored heat computed from satellite observations (Q_{sat}) of internal waves and those computed from in-situ data (Q_{ins}).

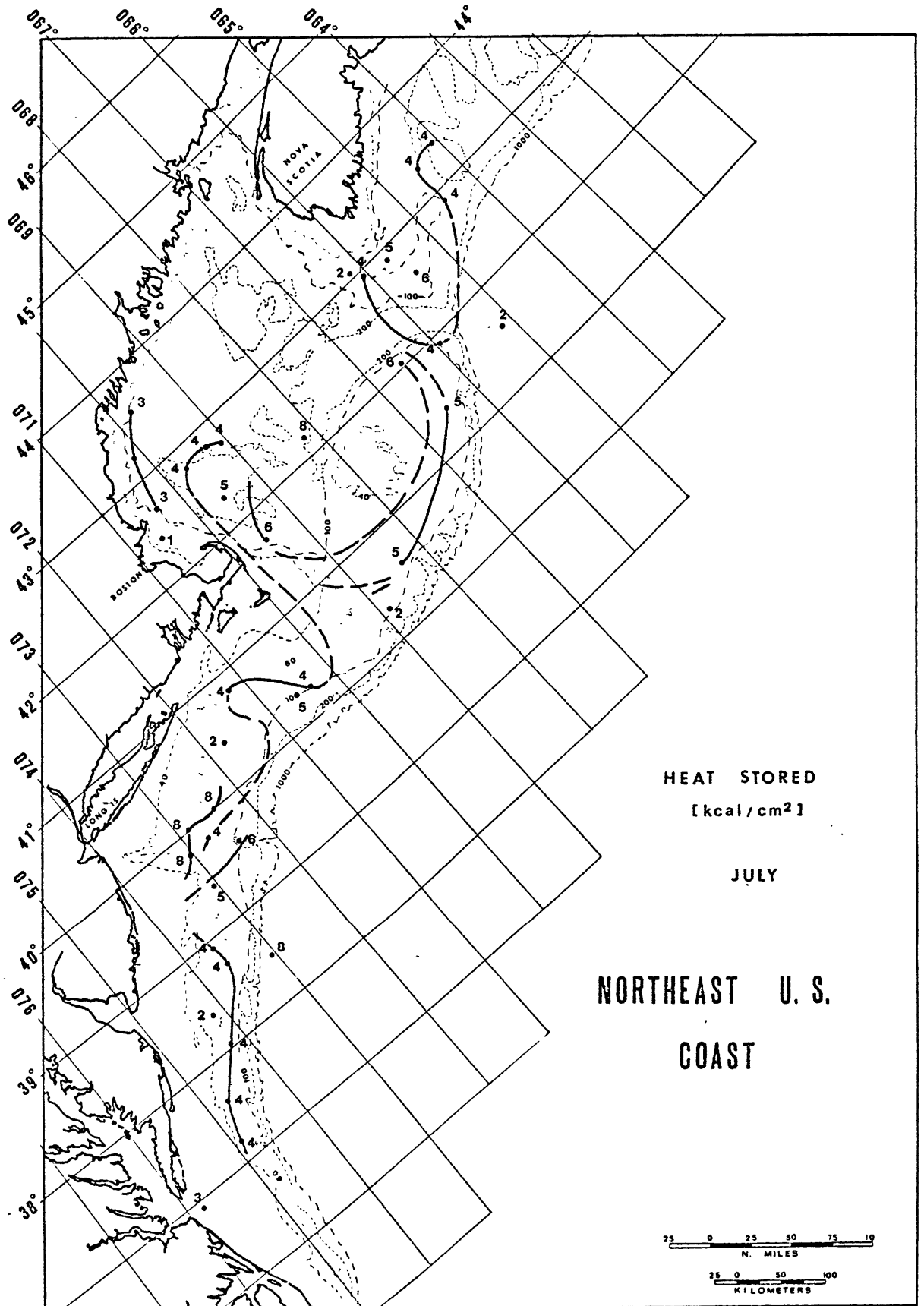


Figure 5.4 - Amount of heat stored computed from satellite observations of internal waves for the month of July.

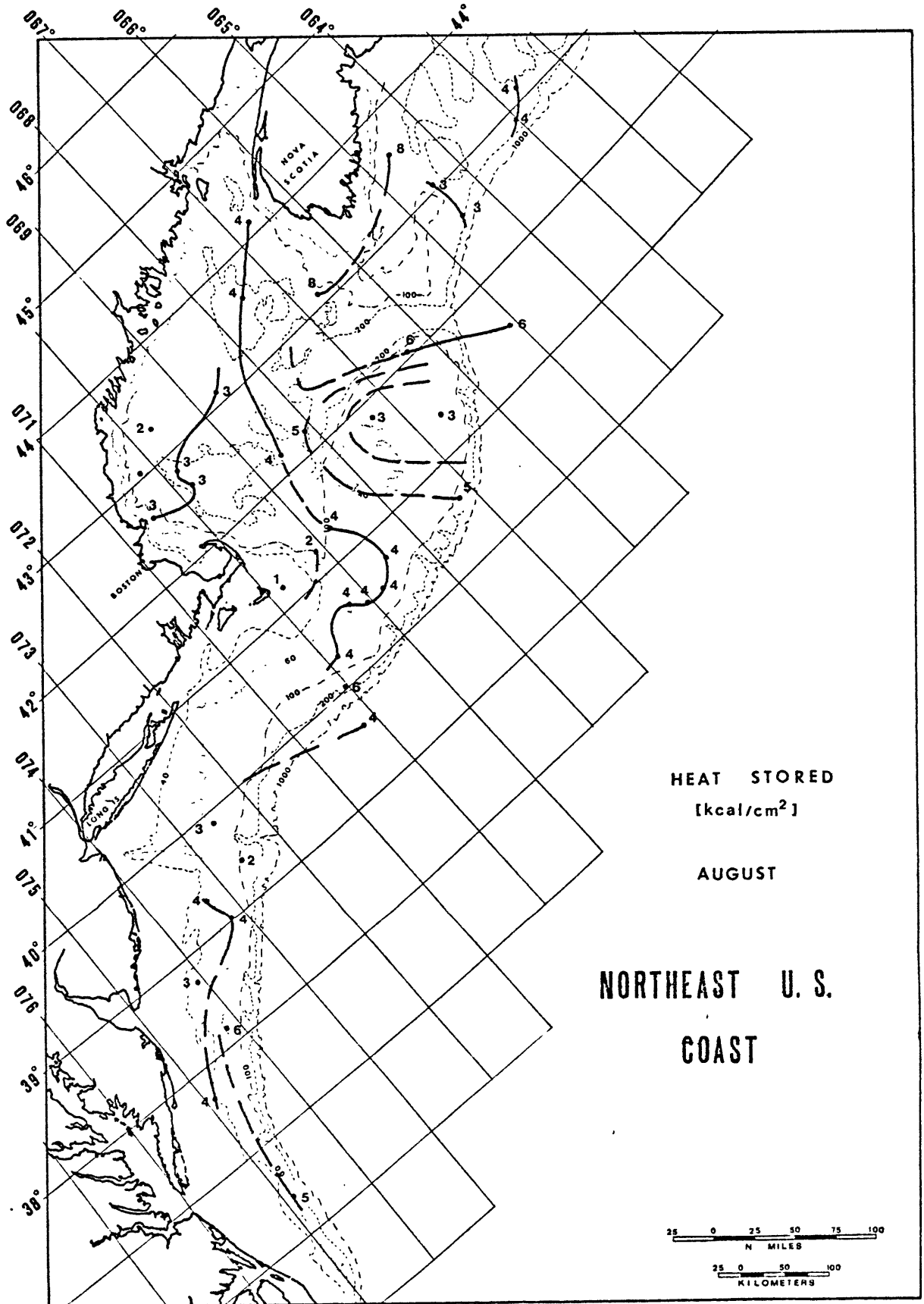


Figure 5.5 - Amount of heat stored computed from satellite observations of internal waves for the month of August.

6. RESULTS

6.1 The Accuracy and Dispersion of Q and h.

The scope of the work is not to verify the accuracy of the distance between the packets, but to show that these measurements can be used to compute mixed layer depth and amount of heat stored. Due to the nature of the experiment discussed here, that is, measurements scattered in space and time, it is rather difficult to discuss accuracy of the estimates of h and Q. To get an estimate for this accuracy, we are going to make a simple analysis of error in the analytic expressions for Q and h. From the measurements we can attribute a fractional error of 0.5 km or 4% relative to the mean value in the determination of the spacing D. Since we are using climatological mean values of $\Delta\rho$ and ρ , we are not going to use the error in the computation of ρ from in-situ measurements but rather the dispersion around the mean value. This yields respectively a fractional error of 0.07% for ρ_2 and 40% for $\Delta\rho$. Taking the expression for Q as

$$Q = \frac{c_p}{g\alpha T^2} \rho_2 D^2 = k \rho_2 D^2 \quad (6.1.1)$$

the fractional error will be at worst conditions:

$$f_Q = 8.1 \%$$

Similarly using the expression for h as

$$h = \frac{D^2 \rho_2}{gT^2 \Delta \rho} = k \frac{D^2 \rho_2}{\Delta \rho} \quad (6.1.2)$$

the fractional error in h will be at worst

$$f_h = 32 \%$$

In order to enhance time variability an analysis of the dispersion of the variables about the mean value was done for each month separately, and the results are shown in Table III. From (6.1.1) we see that only two quantities contribute to a dispersion in Q. These are the distance between the packets D and the bottom density ρ_2 . The fractional standard deviation of Q is

$$\frac{\sigma_Q}{\bar{Q}} = \left[4 \frac{\sigma_D^2}{D^2} + \frac{\sigma_{\rho_2}^2}{\rho_2^2} \right]^{1/2} \approx 2 \frac{\sigma_D}{D}$$

or using the values of Table III, $\sigma_Q/\bar{Q} = 0.51$ (for July) and the standard "error" of the mean will be .34, a value that agrees well with the one calculated from the statistics of the data. The same applied to h yields

$$\frac{\sigma_{h_1}}{h_1} = \left[4 \frac{\sigma_D^2}{D^2} + \frac{\sigma_{\rho_2}^2}{\rho_2^2} + \frac{\sigma_{\Delta \rho}^2}{\Delta \rho^2} \right]^{1/2} \approx \left[4 \frac{\sigma_D^2}{D^2} + \frac{\sigma_{\Delta \rho}^2}{\Delta \rho^2} \right]^{1/2}$$

TABLE III

STATISTICS OF THE PARAMETERS MEASURED IN THE IMAGES, OBTAINED FROM CLIMATOLOGY
AND COMPUTED FROM THE TWO-LAYER MODEL

Parameter	June/July (40 data)			August (38 data)		
	mean	stand. dev.	sd. error mean	mean	stand. dev.	sd. error mean
Distance between the packets (km)	12.6	3.2	0.1	11.9	2.7	0.44
Bottom density (g cm ⁻³)	1.02384	0.00075	0.00012	1.02383	0.00090	0.00015
Density difference (g cm ⁻³)	0.00104	0.00059	0.00009	0.00095	0.00058	0.00009
Amount of heat stored (k cal/cm ²)	4.2	2.0	0.32	3.7	1.7	0.28
Mixed layer depth (m)	13.0	10.4	1.24	13.0	12.6	2.04

and a value of $\sigma_{h_1}/h_1 = 0.76$ or a standard "error" of the mean 1.56. We found similar agreement for the same quantities computed for the month of August.

The dispersion in h is enormous and among the reasons for this we can mention large variations of the mixed layer depth due to the internal tides and the high dispersion in $\Delta\rho$. This value is sometimes subjected to large variations in a time scale smaller than a month. The difference between the mean values of mixed layer depth and amount of heat stored for July and August was not found to be significant. This would be expected since these values were averaged over a month and over a large area.

6.2 Discussion of the Results for a Two-Layer Model

6.2.1 Mixed Layer Depth

The computation of the mixed layer depth (h) using (4.2.1.2) rely on the measurements of distance D and on the climatological values of $\Delta\rho$. While the former has a percentage error of 4% the last one has an error of 40%. The propagation of error analysis gives an error of 32% in the estimation of h . Table II shows a comparison of h computed from satellite and taken from in-situ hydrographic cast. In three out of four observations the satellite estimation gives deeper values than the hydro cast. Here actually we cannot take the hydro cast values as standard for comparison because first, they were not taken at the same time, and second, because of the effect of the internal tide over the sampling.

Halpern's data (1971) show that the apparent depth of the upper layer may vary by 30% or more during a tidal period. Rattray (1969) and Halpern (1971) have shown that the internal tide propagates on the seasonal pycnocline as a wave packet, the front of which starts with a depression of the thermocline, followed by a series of undulations which leaves the pycnocline lower than ahead of the wave packet. The pycnocline then slowly rises to reach its maximum height just before the wave packet belonging to the succeeding tide arrives. The effect of this over the observations taken in a hydrographic station can be foreseen since the amplitude of the waves range from 4 to 20 m in crest-to-trough distance. It should be pointed out that the error in the observations would probably be more serious for STD casts than for

Nansen casts, because an STD cast is a near-instantaneous profile of temperature and salinity, whereas Nansen bottles are allowed to "soak" at a given depth and provide an average temperature over about a 10 min. interval (R. Williams and F. Godshall, 1977). Figure 3.3 shows a schematic drawing of this wave packet.

Generally speaking, the mixed layer depth charts show deeper values for July. The reason for this is that in July the winds are stronger than in August (Navy Hydrographic Office, 1959). There is a general tendency of h to get shallower shoreward. Unusual deep values are observed on the Nova Scotia coast in August. Deep values of h are expected over the Banks region due to the wind mixing.

To have an idea of the possible one month time variations we choose the spatially closest repeated observation we have, and the comparison is made in Table IV. There is one observation off the continental shelf (Obs #19, 46) and probably the generation mechanism is the same as those over the continental shelf, so we can consider the same population's data. This observation gives a much deeper value for August than for July.

Usually in open ocean we find deeper values of mixed layer depth than over the continental shelf. It seems that the free convection also plays a more important role here.

Two of the values in Table IV show that differences within the limit of accuracy are not actually one month apart. They are around fifteen days apart so they cannot be considered representative.

TABLE IV

ONE MONTH VARIATION IN MIXED LAYER DEPTH AND AMOUNT OF
HEAT STORED FROM SATELLITE INTERNAL WAVE OBSERVATION

MONTH	OBS.#	h(m)	Q(k cal/cm ²)
July August	46 19	20 61	1.6 6.4
July August	65 76	23 23	6.4 6.4
July August	61 74	14 8	4.9 3.6
July August	47 69	10 19	4.9 2.5
June August	17 21	20 26	8.1 4.9
July August	45 33	5 4	3.6 3.6

The effect of the inclusion of the Coriolis parameter in the computation of the mixed layer is shown in Table I. As pointed out before, it is negligible because the correction term f^2/α^2 is small compared to c^2 ; it varies from 1 to 10. Meanwhile c^2 is of order 10^3 .

6.2.2 Amount of Heat Stored

Unlike the mixed layer depth, the computation of the amount of heat relies only on D, consequently the propagation of error analyses yield an error of 8% for Q. The comparison with the available ground truth shows that the heat stored computed from satellite is lower than those computed from in-situ hydrocast. This is due to the fact that at the leading wave of the group the pycnocline is shallower.

The heat storage charts show the unexpected result that in some regions the values of stored heat are larger in July than in August. A possible reason for this anomalous result is air sea interaction. During July in the Gulf of Maine there is fog, mostly in the night and early morning, that acts as a radiative blanket reducing losses by radiation. It also functions as an evaporation shield preventing the increasing loss of sensible heat by evaporation. In August the fog is reduced and the losses are increased.

In the one month variation Table IV the observation outside the continental shelf (obs. #46,19) follow the general trend of higher values of Q for August than July.

6.3 Additional Comments

Some questions arise from the results discussed in the previous sections.

a) Under which conditions do the two methods of calculating heat storage give comparable results?

b) What is the real depth of the layer?

c) Can short term variations of the mixed layer depth induce variations in the amount of heat stored?

d) How large are these variations?

Let us try to comment on the above questions.

a) The expression giving Q from in-situ measurements (5.2.1) is an integral that involves time, while equation (5.3.5) does not. In order to compare the computations we have to assume $T_0(z)$ constant. This means that the deep water temperature is constant all year. The recalculation of Q using the assumption $T_0 = \text{const.}$ yields values closer to those computed from satellite data.

b) Since we have measured the distance between the leading waves of the packets we are assuming the depth at this point, i.e., shallower than the observed in-situ, as already discussed. This depth is going to vary from the leading wave to the back of the packet, and the point plotted in the charts would have to be shifted a half spacing backward or forward. The only way to compare the depth of the mixed layer discussed here is to moor a buoy with temperature sensors at a geographical location chosen on the basis of satellite image.

c) The amount of heat stored in the upper layer is subject to diurnal variations due to the heating during the day and cooling during the night.

The internal waves only redistribute the heat vertically and this is done twice a day. So we can not expect large variations in the amount of heat induced by short term variations.

d) It is difficult based in what was done here, to have a figure; we can guess 5% of the amount of heat.

Another possible application of the results obtained is the following: Assume the amount of heat for a given day in a given geographical position is $Q(t_1)$ and that n days latter is $Q(t_2)$. The sea surface temperature difference between these two days will be

$$T(t_2) - T(t_1) = \frac{1}{\rho c_p} \left[\frac{Q(t_2)}{h(t_2)} - \frac{Q(t_1)}{h(t_1)} \right] \quad (6.3.1)$$

The expression (6.3.1) can be used to estimate the accuracy of sea surface temperature measured from satellite

Another point that deserves some comments is the fact that since the waves observed are of a non-linear nature, how could the features discussed be reasonably well explained by such a crude model?

Note that (2.1.7) is a first approximation to

$$c = c_0 \left[1 - \frac{1}{6} k^2 \left(\frac{K \rho_2 h_i^2 + 3 \rho_1 h_i}{k \rho_2} \right) + O(k^4 h_i^4) \right]$$

where

$$c_0^2 = g \frac{(\rho_2 - \rho_1) h_1}{\rho_2}$$

and this is a dispersion relation of a non-linear wave as explained in Benjamin (1967).

7. CONCLUSIONS

Landsat A/B images taken in July and August of 1972, 1973 and 1974 were used with a simple two-layer ocean model to compute the mixed layer depth and the amount of heat stored over the continental shelf between Nova Scotia and Cape Hatteras.

It was found that a comparison of mixed layer depth computed from satellite and observed from the few in-situ observations is almost impossible due to the internal wave noise introduced in the hydrographic observations. The comparison between the values of the amount of heat stored gives a reasonable agreement. The values of the heat stored from in-situ observation are larger.

During the month of July the mixed layer depth was found deeper than for August. The reason is wind mixing; the winds are stronger in July. The amount of heat in August is less than in July, probably because the larger amount of fog in July acts as a radiative blanket and also as an evaporation shield.

An estimation of the accuracy in determination of the amount of heat Q and the mixed layer depth h , was done resulting in a fractional percentage error of 8% for Q and 32% for h . The effect of the inclusion of the Coriolis parameter in the mixed layer depth computation was found to be negligible.

An extension for a three-layer model was unsuccessful because of the appearance of new variables which we cannot estimate either from satellite or from climatology. The Boussinesq approximation applied to the three-layer model put some constraints on the waves described.

The model can be used to estimate the accuracy of sea surface temperature taken from satellites. As a recommendation for an improvement in the comparisons we suggest a buoy moored at a geographical location chosen on the basis of satellite image.

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