

1. (a) The system $Ax = b$ has a solution if and only if b is orthogonal to what subspace?
(b) Find the determinant of the 4×4 matrix A whose entries are $a_{ij} = \text{smaller of } i^2 \text{ and } j^2$.
(c) What is the relation between the determinant of A and the pivots? *Why is this true?*
2. At $t = 1, 2, 3$ we are given values b_1, b_2, b_3 . The idea is to fit the best straight line $b = C + Dt$ to those three points.
(a) What three equations in two unknowns will have a solution if the three points lie exactly on a line?
(b) Under what condition $m b_1 + n b_2 + p b_3 = 0$ (**find** m, n, p) will the three points lie on a line?
(You could use elimination or your answer to Question 1(a).)
(c) Find the best line $\bar{C} + \bar{D}t$ if the values are $(b_1, b_2, b_3) = (0, 0, 1)$.
(d) What 3×3 matrix P projects every vector onto the plane containing the column vectors $(1, 1, 1)$ and $(1, 2, 3)$?
3. (a) Suppose q_1, q_2, q_3 are orthonormal vectors in \mathbb{R}^6 . Under *what condition on the vector* v will there be a fourth orthonormal vector q_4 that is a combination of v, q_1, q_2, q_3 ?
(b) Give a formula for that fourth orthonormal vector q_4 .
(c) Suppose q_1, \dots, q_n is an orthonormal basis for \mathbf{R}^n . Define the $n \times n$ matrix $A = q_1 q_1^T + \dots + q_n q_n^T$. What does $A q_1$ equal? What does $A q_i$ equal? What is A ?