LECTURE 18

Last time:

- Gaussian Channel Capacity as Sphere Packing
- Parallel Gaussian Channels

Lecture outline

- Waveform Channels
- Wide-band limit
- Colored Gaussian Noise

Review

• Gaussian Channel:

$$Y = X + W$$
$$E[X^2] \le P, E[W^2] = N$$
$$C = \frac{1}{2}\log(1 + \frac{P}{N})$$

• Parallel Gaussian Channels

$$Y_i = X_i + W_i$$

 $\sum E[X_i^2] = P, E[W_i^2] = N_i, i = 1, ..., k.$

water-filling.

Waveform Channel: White Gaussian Noise

Y(t) = X(t) + W(t)

- W(t) is a Gaussian random process. Any set of samples are i.i.d. Gaussian distributed with zero mean and variance $E[W(t)^2] = \frac{N_0}{2}$.
- Autocorrelation function $R(\tau) = E[W(t)W(t \tau)] = \frac{N_0}{2}\delta(\tau)$.
- Power Spectral Density is flat $\frac{N_0}{2}$ over all frequency
- Do we really have white Gaussian noise?

Front end of the receiver

Goal: provide sufficient statistics for bandlimited transmitted signals.

Assume the X(t) has non-zero frequency components only in [-W, W], can sample at $T_s = \frac{1}{2W}$.

 can be thought as a bank of matched filter matched to

$$\operatorname{sinc}\left(t-rac{n}{2W}
ight)$$

where

$$\operatorname{sinc}(t) = \frac{\sin(2\pi W t)}{2\pi W t}$$

- The front end provide sufficient statistics since
 - the out-of-band noise is independent of the transmitted signals
 - the out-of-band noise is independent of the in-band noise

Discrete-Time Channel Model

- 2W samples per second.
- The noise power in each sample is $\frac{N_0}{2}$.
- Average per symbol signal power P/2W.

We get back to

$$Y_i = X_i + W_i$$

The overall capacity in (bits/sec)

$$C = 2W \frac{1}{2} \log \left(1 + \frac{P/2W}{N_0/2}\right)$$

$$C = W \log \left(1 + \frac{P}{N_0 W} \right)$$

P has unit (watt), and N_0 (watt/hz).

Admiring Shannon's Formula

$$C = W \log \left(1 + \frac{P}{N_0 W} \right)$$

- Question 1 Do we always want more bandwidth?
- **Question 2** What can we do with infinite bandwidth?

$$C \rightarrow \frac{P}{N_0} \log_2 e(bits/sec)$$

Capacity grows linearly with the power (very power efficient).

• The energy required to send 1 bit is $E_b = P/C$ watts $\times 1$ sec,

$$\frac{E_b}{N_0} = \frac{1}{\log_2 e} = -1.59(dB)$$

• **Question 3** What can we do with infinite power?

$$\lim_{W \to \infty} \frac{C}{W} \to \log \frac{P}{N_0}$$

capacity linearly increases with W (spectral efficient)

Discussions

- Waveform channels are simply 2WT parallel channels.
- White Gaussian noise allows us to look at the signal space with any chosen basis.
- Differential entropy depends on the coordinate system, but mutual information does not.

$$I(X;Y) = h(Y) - h(Y|X)$$

Key: look at Y and Y|X from the same coordinate system.

Gaussian Channel with Colored Noise

 $Y_i = X_i + W_i, i = 1, \dots, m$

where W_i 's are not i.i.d., but have a covariance matrix

$$E[\underline{WW}^{\dagger}] = K_W$$

• Channel with memory, can only treat a block as a super-symbol

$$\underline{Y} = \underline{X} + \underline{W}$$

- Now we do not have the liberty to choose any coordinate system, since otherwise the noise components are correlated.
- Eigen value decomposition

$$K_W = U \wedge U^{\dagger}$$

• \underline{W} can be viewed as white Gaussian noise passed through a generating matrix

$$\underline{W} = U\sqrt{\Lambda}\underline{\tilde{W}}$$

where $\underline{\tilde{W}} \sim N(0, I)$

Choosing the Right Angle

• Left multiply \underline{Y} by U, does not lose any information

$$\underline{Y}' = U\underline{Y} = U\underline{X} + \sqrt{\Lambda}\underline{\tilde{W}}$$
$$= \underline{X}' + \sqrt{\Lambda}\underline{\tilde{W}}$$

Now the elements of the noise vector become independent, and we get back to the parallel Gaussian channel case.

- Water-filling among all the eigen modes.
- $h(\underline{Y})$ and $h(\underline{Y}|\underline{X})$ are computed in the rotated coordinate systems.

K-L Expansion

Theorem K-L expansion:

For a random process with autocorrelation function $R_X(t,s) = E[X(t)X(s)]$. Assume that $R_X(t,s)$ is symmetric, i.e.,

$$R_X(t,s) = R_X(s,t)$$

and

$$\int \int R_X(t,s) dt ds < \infty$$

then there exists a complete ortho-normal basis $\{\phi_i(t)\}$ which are the eigen functions of $R_X(t,s)$, i.e.,

$$\int R_X(t,s)\phi_i(s)ds = \lambda_i\phi_i(t)$$

Let

$$X_i = \langle X(t), \phi_i(t) \rangle$$

then

$$X(t) = \sum X_i \phi_i(t)$$

in L^2 norm sense. Furthermore, X_i 's are uncorrelated.

$$E[X_i X_j] = E\left[\int X(t)\phi_i(t)dt \int X(s)\phi_j(s)ds\right]$$

=
$$\int \int E[X(t)X(s)]\phi_i(t)\phi_j(s)dtds$$

=
$$\int \phi_i(t) \int R_X(t,s)\phi_j(s)dsdt$$

=
$$\lambda_j \int \phi_i(t)\phi_j(t)dt$$

=
$$\lambda_j \delta_{ij}$$

Key we can find a new basis of the signal space $\{\phi_i(t)\}$ such that the components of X(t) along different base vectors are uncorrelated. For the Gaussian random process, the components can be independent.

• compare to the vector case.

Gaussian WSS Random Process

Now consider the special case that the random process is WSS,

 $R_X(t,s) \to R_X(\tau)$

Question what are the eigen functions?

- Any WSS Gaussian random process can be obtained by passing white Gaussian noise through linear time-invariant filters.
- Sinesoid is the eigen function of LTI systems, so it is also the eigen function of WSS random processes.
- infinite time horizon vs. finite time horizon.
- Different frequency components of a Gaussian WSS process are independent, but may have different variance, given by the power spectral density.
- Water-filling over different frequency components.