



Harvard Medical
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Biomedical Computing

Decision Support Systems
November 3rd, 2005

6.872 / HST 950



Decision Support Systems

- ✱ An intelligent system is a computer program able to emulate intelligent performances.
- ✱ Computer program:
 - ✓ A mechanical (effective) procedure.
- ✱ Intelligent performances (pragmatic definition):
 - ✓ The performance we expect to require intelligence.
- ✱ Emulate/Simulate:
 - ✓ Emulate means to achieve the same objectives.
 - ✓ Simulate means to reproduce the same behavior.



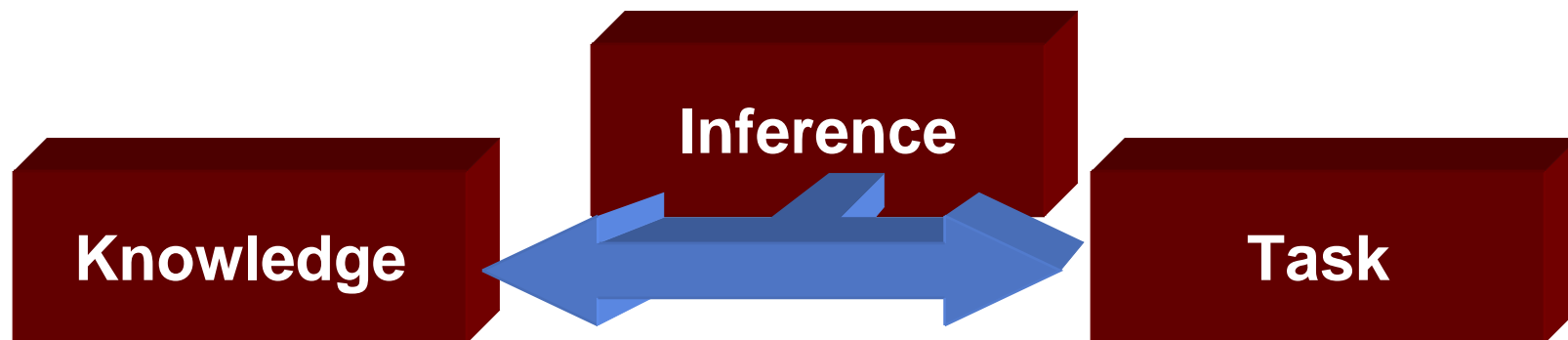
Components

Knowledge: Representation of domain knowledge.

👍 You may regard this knowledge as axioms.

Inference: Domain independent procedures to handle knowledge in order to achieve these tasks.

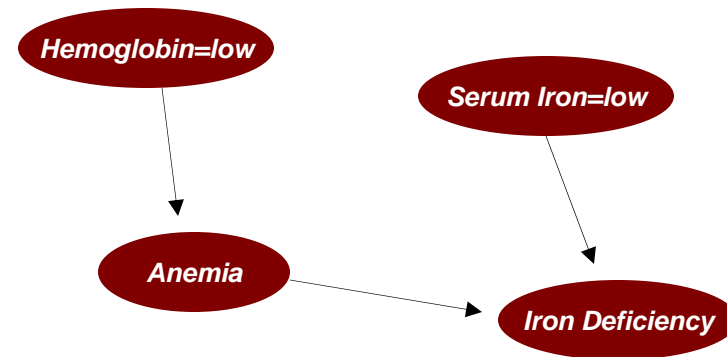
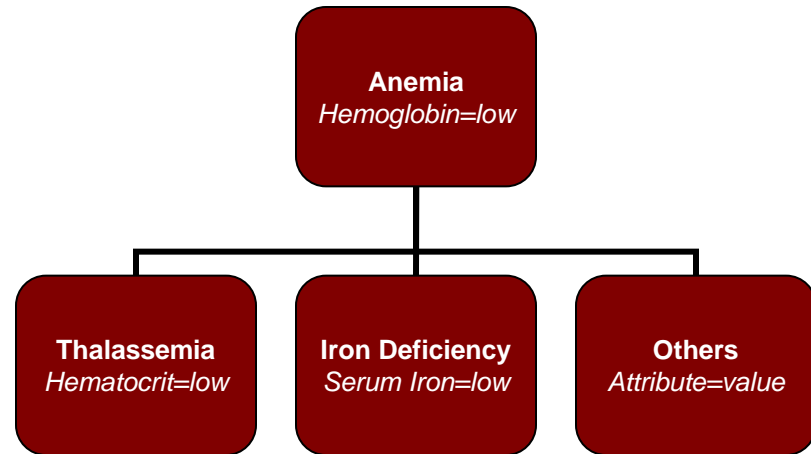
👍 You may regard these procedures as inference rules.





Knowledge Representation

- ✱ Knowledge/Information
 - ✓ Knowledge is not just information.
 - ✓ Knowledge is structured information.
- ✱ Ontology is the structure of the domain knowledge.
 - ✓ A classification of medical disorders: a hierarchy prototype definitions.
 - ✓ A network of causal relationships and influences.





Inference and Reasoning

- ✱ Once knowledge is represented, it must be **used**.
- ✱ **Inference**: The operation able to draw conclusions.
 - Sound**: draw only true conclusions.
 - Complete**: draw all the true conclusions.
 - 👉 *The truth, the whole truth, and nothing but the truth.*
- ✱ **Reasoning**: Application of inference to knowledge.
 - Truth preservative**: draw true from true.
 - Monotonic**: the conclusions drawn are always valid (!).
 - 👉 *The first 33 theorems of Euclid's Elements are drawn without the Fifth Axiom but they still hold after it.*



Problem Solving

Knowledge/inference compilation:

- if (the infection is meningitis) 1
- (the type is bacterial) 2
- (therapy is corticosteroids) 3
- (only circumstantial evidence) 4
- then
- klebsiella (0.2), e.coli (0.4) 5
- or pseudomonas (0.1) 6

- ✓ Knowledge (1 2 3 5 6) and inference (2).
- ✓ Difficult to acquire, maintain, and update.

Deep systems:

- ✓ Knowledge flows in the opposite direction.
- ✓ Inference must reverse this natural path of knowledge.

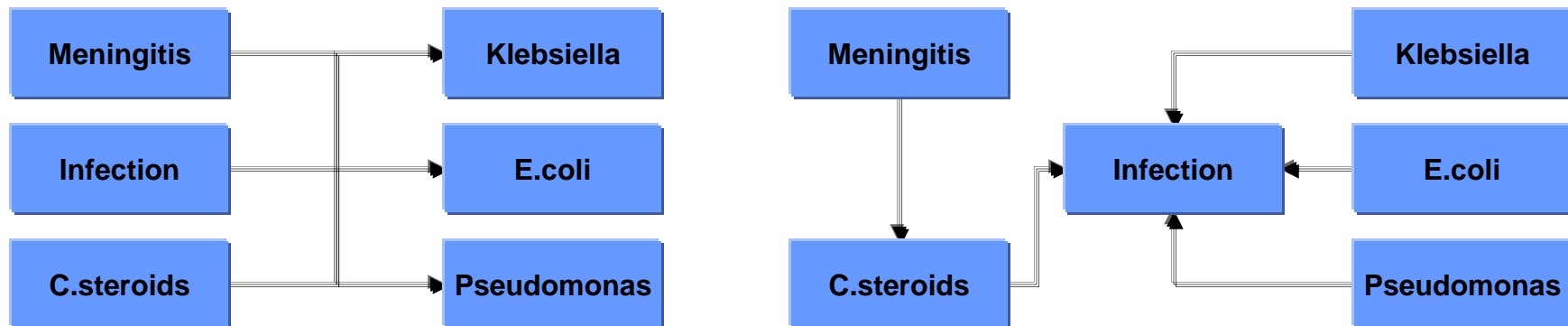


Logical Representation

★ Logical knowledge representation (**axioms**):

- (meningitis \Rightarrow corticosteroids)
- (corticosteroids \Rightarrow bacterial_infection)
- (klebsiella \Rightarrow bacterial_infection)
- (e.coli \Rightarrow bacteria_infection)
- (pseudomonas \Rightarrow bacterial_infection)

●^{*} (circumstantial evidence)
(0.2) (0.4) (0.1)





Logical Reasoning

✱ Inference rules (e.g. **modus [ponendi] ponens**)

- ✓ Metalinguistic inference rules:

$$\begin{array}{l} \Rightarrow \alpha \Rightarrow \beta \\ \alpha \\ \therefore \beta \end{array}$$

- ✓ Axiom schema:

$$\Rightarrow (\alpha \Rightarrow \beta) \wedge \alpha \Rightarrow \beta$$

- ✓ Example:

⇒ Axioms:

$$\triangleright (\text{cat} \Rightarrow \text{mammal}); \text{cat}$$

⇒ Application of the inference rule:

$$\begin{array}{l} \triangleright \text{cat} \Rightarrow \text{mammal} \\ \text{cat} \\ \therefore \text{mammal} \end{array}$$



Example

✱ Axioms

- (meningitis \Rightarrow corticosteroids)
- (corticosteroids \Rightarrow bacterial_infection)
- (klebsiella \Rightarrow bacterial_infection)
- (e.coli \Rightarrow bacterial_infection)
- (pseudomonas \Rightarrow bacterial_infection)

✱ Observations:

- meningitis

✱ Inference

☞ meningitis \Leftrightarrow corticosteroids \Leftrightarrow bacterial_infection

☹ But how do we infer the type of bacteria?



Limits


✱ Representation of uncertainty:


- ✓ How do we represent uncertainty about knowledge?

☞ Meningitis **may** cause brain damage.

✱ Abductive inference:

- ✓ How do we get the bacteria?

➤ cat \Rightarrow mammal
mammal
 \therefore cat 

➤ e.coli \Rightarrow bacteria
bacteria
 \therefore e.coli 

☞ *This pattern is called Fallacy of Affirming the Consequent.*



Probability

- ✱ Let's consider our propositions as **events**:
 - ✓ Probability is a function mapping an event to $[0, 1]$.

$$0 \leq p(a) \leq 1$$

☞ The probability that tomorrow will rain is 0.4: $p(\text{rain})=0.4$.

- ✱ Properties:
 - ✓ Complementation:

$$p(a) + p(\neg a) = 1$$

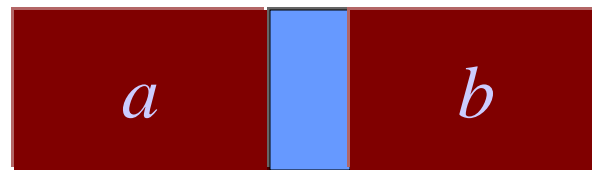
$$p(\neg a) = 1 - p(a)$$

☞ The probability that tomorrow will **not** rain: $p(\neg \text{rain})=0.6$.

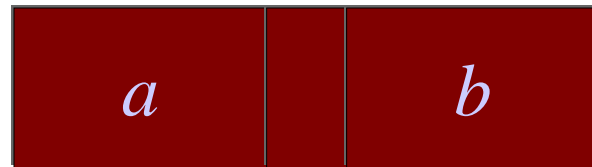


And and Or

- ★ And (\wedge) is set intersection: $p(a \wedge b)$



- ★ Or (\vee) is set union: $p(a \vee b)$



- ★ If the intersection is empty, the union is the sum:
 $p(a \wedge b) = 0 \Rightarrow p(a \vee b) = p(a) + p(b)$





Exhaustivity and Exclusivity

Exclusivity: a and b cannot be both true.

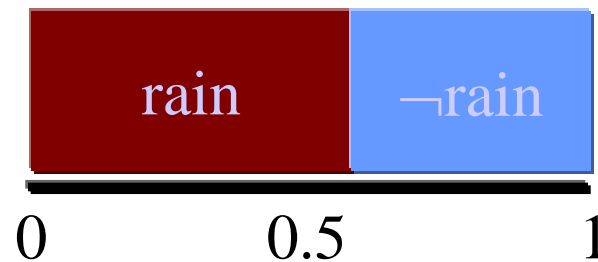
$$p(a \wedge b) = 0$$

When it rains, it may never be the case it is not raining.

Exhaustivity: Events exhaust all the possibilities:

$$p(a) + p(b) = 1$$

Either it is raining or it is not raining.





Axioms

Axiom 1: $p(a) \geq 0$

- ✓ The probability of an event cannot be negative.

Axiom 2: $p(\Omega) = 1$

- ✓ The probability of an exhaustive set is 1.

☞ $p(\text{rain}) + p(\neg \text{rain}) = 1$

- ✓ This, together with Axiom 1, implies $0 \leq p(a) \leq 1$.

Axiom 3: $p(a \vee b) = p(a) + p(b)$ if $p(a \wedge b) = 0$.

- ✓ Theorem: $p(a \vee b) = p(a) + p(b) - p(a \wedge b)$.





Variables

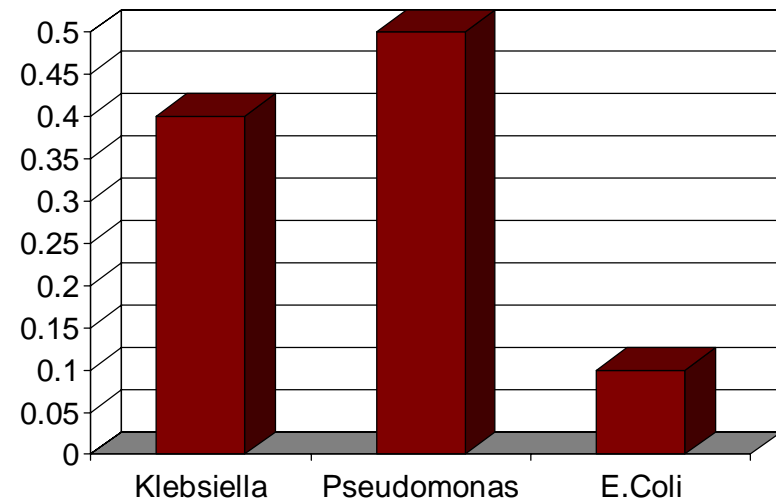
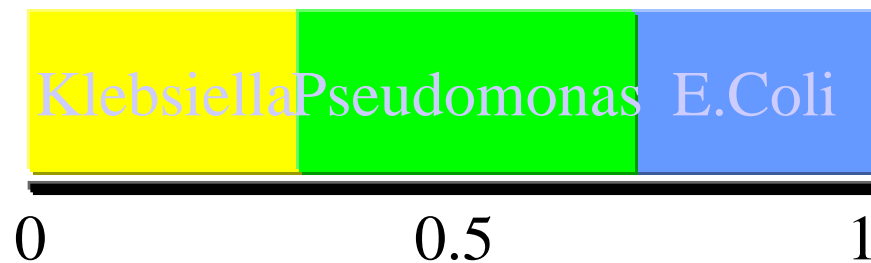
A variable is a symbol A with a set of J possible values $\{a_1, \dots, a_J\}$.

- ✓ A state a_{ij} is the assignment of a value to the variable.
- ✓ A variable can take just one value at the time.
- ✓ A variable must take at least one value.
- ✓ A variable is a set of exclusive and exhaustive states.
 - ☞ The variable Bacteria has values: {klebsiela, e.coli, psedumonas}.
 - ☞ There are three states, such as Bacteria= klebsiela.
- ✓ Our propositions are variables with just two states.
 - ☞ The variable Rain can take two values: {true,false}.
 - ☞ Rain has two states: Rain=true and Rain=false.



Probability Distribution

- ✱ We can associate a probability value to each state.
- ✱ The set of probabilities associated to a variable is called Probability Distribution.
 - ✓ Since the states are exhaustive, they sum up to 1.
 - ✓ Since the states are exclusive, their intersections are 0.





Cumulative Distributions

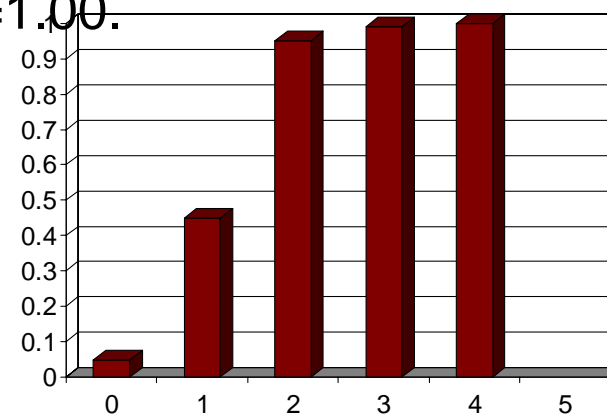
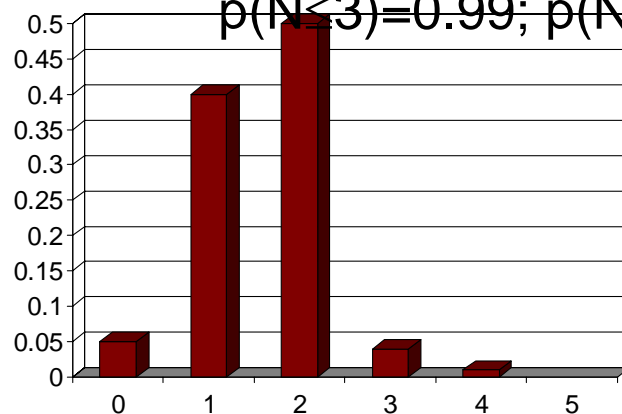
★ The cumulative distribution is given by the sum of probabilities of some states.

☞ The variable N *Number of assignments per course*.

➤ $p(N=0)=0.05$; $p(N=1)=0.40$; $p(N=2)=0.50$;
 $p(N=3)=0.04$; $p(N=4)=0.01$; $p(N \geq 5)=0.00$.

☞ The Cumulative Distribution of N .

➤ $p(N \leq 0)=0.05$; $p(N \leq 1)=0.45$; $p(N \leq 2)=0.95$;
 $p(N \leq 3)=0.99$; $p(N \leq 4)=1.00$.





Joint Probability

Conjunction is represented as joint probability.

- $p(\text{cloudy} \wedge \text{rain}) = 0.60$ 1
- $p(\text{cloudy} \wedge \neg \text{rain}) = 0.15$ 2
- $p(\neg \text{cloudy} \wedge \text{rain}) = 0.15$ 3
- $p(\neg \text{cloudy} \wedge \neg \text{rain}) = 0.10$ 4

Imagine joint events as percentages of days in a year. Note that they sum up to 1.

Inference (marginal probability):

- $p(\text{cloudy}) = 1 + 2 = 0.60 + 0.15 = 0.75$
- $p(\text{rain}) = 1 + 3 = 0.60 + 0.15 = 0.75$
- $p(\neg \text{cloudy}) = 3 + 4 = 0.15 + 0.10 = 0.25$
- $p(\neg \text{rain}) = 2 + 4 = 0.15 + 0.10 = 0.25$



Conditioning

- ✱ **Modus ponens** needs a conditional statement.
- ✱ Inference needs **conditional statements** but we cannot use standard implication (\Rightarrow):

$$p(a \Rightarrow b) = 0.7 \equiv p(\neg a \vee b) = 0.7 \equiv p(b) \leq 0.7 \text{ and } p(a) \leq 0.3 \quad \text{💣}$$

- ✱ We need a **probabilistic conditioning**.
- ✱ Fortunately, we have **conditional probability**:

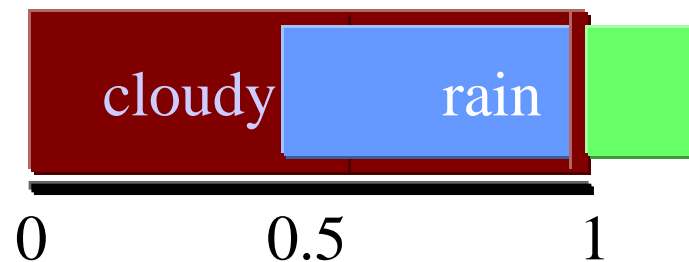
$$p(a | b) = \frac{p(a \wedge b)}{p(b)}$$

- ✱ It is read *the probability of a given b*.



Conditional Probability

- ✱ Conditional probabilities represent the **intension**:
 - ☞ If it is cloudy it is more likely to rain
 - $p(\text{rain}|\text{cloudy})=0.8$; $p(\neg\text{rain}|\text{cloudy})=0.2$
 - ☞ If it is not cloudy it is more likely not to rain.
 - $p(\text{rain}|\neg\text{cloudy})=0.6$; $p(\neg\text{rain}|\neg\text{cloudy})=0.4$
- ✱ The conditional probability is the probability of an event when another event is happening.
- ✱ It is a set **zoomed in** another set.





Bayes' Theorem

Bayes' Theorem is the solution to abduction:

$$p(a | b) = \frac{p(a \wedge b)}{p(b)}$$

- ✓ Since $p(a \wedge b) = p(a | b) \times p(b) = p(b | a) \times p(a)$:

$$p(b | a) = \frac{p(a | b) p(b)}{p(a \wedge b) + p(a \wedge \neg b)}$$

- ✓ Invert $p(a | b)$ into the *posterior probability* $p(b | a)$.

$$p(b | a) = \frac{p(a | b) p(b)}{p(a | b) p(b) + p(a | \neg b) p(\neg b)}$$



Exhaustive

- ★ The bacteria are values of a single variable B :

$$\text{p}(B=k) = 0.4; \text{p}(B=e) = 0.3; \text{p}(B=p) = 0.3$$

$$\text{p}(I=t | B=k) = .9; \text{p}(I=t | B=e) = .8; \text{p}(I=t | B=p) = .8$$

$$\text{p}(I=f | B=k) = .1; \text{p}(I=f | B=e) = .2; \text{p}(I=f | B=p) = .2$$

- ★ Posterior probability $p(B=k|I=t)$

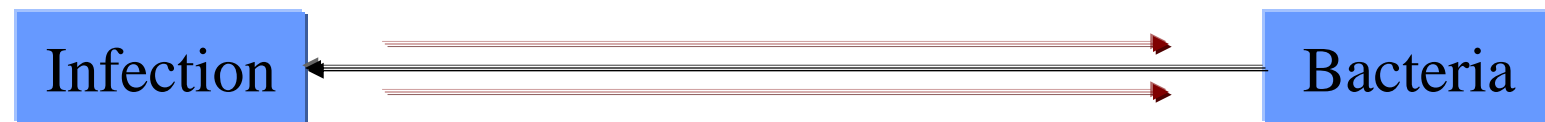
$$\frac{\text{p}(I=t|B=k) \times \text{p}(B=k)}{\text{p}(I=t|B=k) \times \text{p}(B=k) + \text{p}(I=t|B=e) \times \text{p}(B=e) + \text{p}(I=t|B=p) \times \text{p}(B=p)} =$$

$$= \frac{0.9 \times 0.4}{0.9 \times 0.4 + 0.8 \times 0.3 + 0.8 \times 0.3} = \frac{0.36}{0.84} = 0.428$$

$$\text{p}(B=e | I=t) = \frac{0.24}{0.84} = 0.286$$

$$\text{p}(B=p | I=t) = \frac{0.24}{0.84} = 0.286$$

$$\text{p}(B=k | I=t) + \text{p}(B=e | I=t) + \text{p}(B=p | I=t) = 0.428 + 0.286 + 0.286 = 1$$





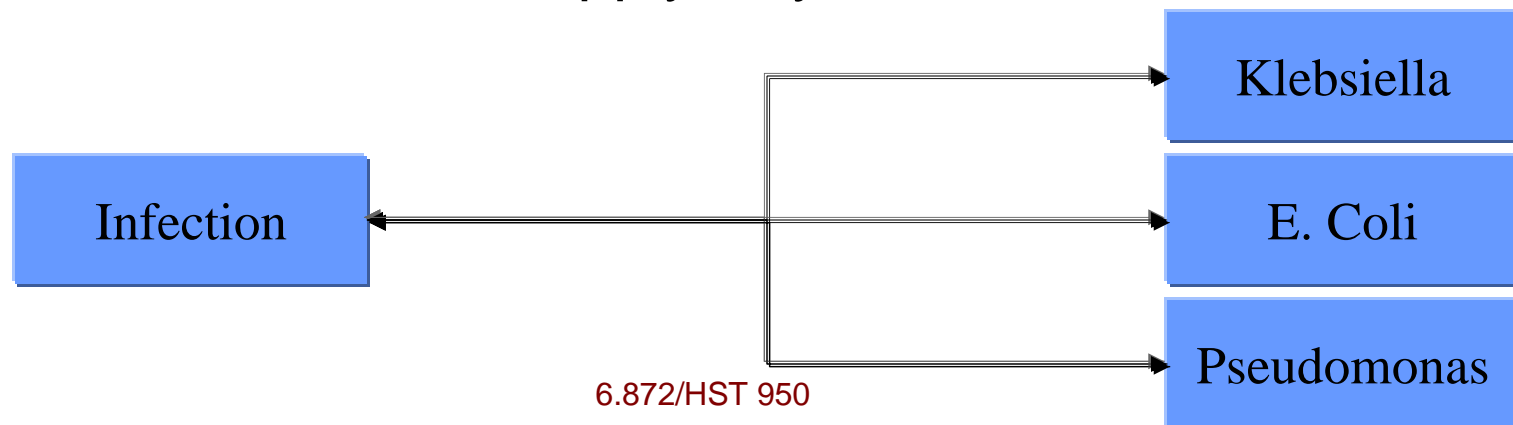
Independent

The bacteria are independent binary variables:

📖 $p(K=t) = 0.4; p(E=t) = 0.3; p(P=t) = 0.3$

📖 $p(I=t | K=t \wedge E=t \wedge P=t) = 1; p(I=t | K=t \wedge E=t \wedge P=f) = .9;$
 $p(I=t | K=t \wedge E=f \wedge P=t) = .9; p(I=t | K=f \wedge E=t \wedge P=t) = .8;$
 $p(I=t | K=t \wedge E=f \wedge P=f) = .8; p(I=t | K=f \wedge E=t \wedge P=f) = .7;$
 $p(I=t | K=f \wedge E=f \wedge P=t) = .7; p(I=t | K=f \wedge E=f \wedge P=f) = .1.$

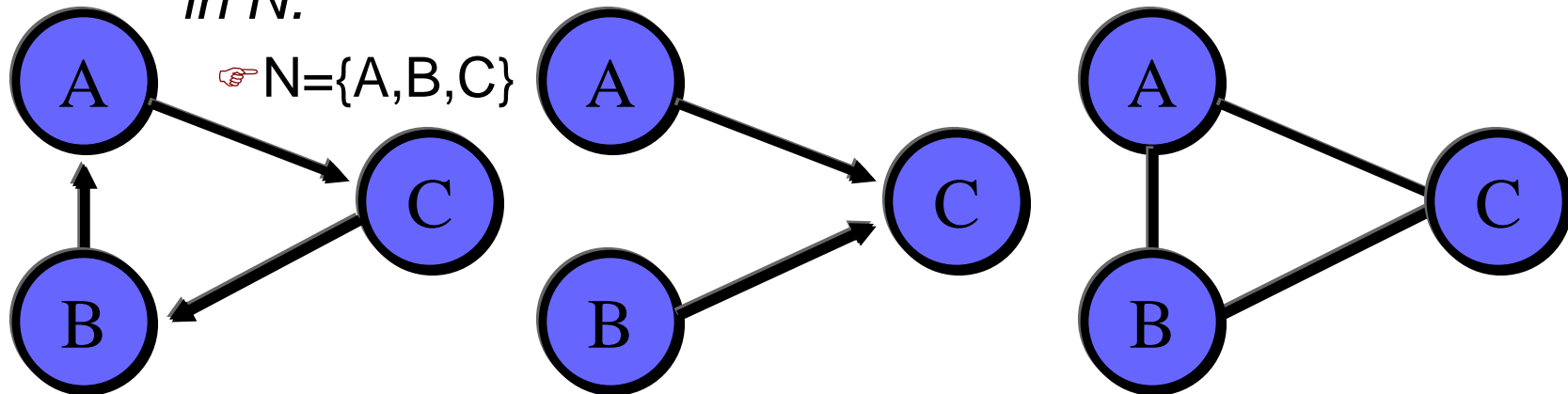
Solution: Transform the antecedents in a single variable:
antecedents defines a set of mutually exclusive and exhaustive states and Apply Bayes' Theorem.





Graph

- ★ A graph (**network**) $G(N,L)$ is defined by:
 - ✓ A finite set $N = \{A,B,\dots\}$ of nodes (**vertices**).
 - ✓ A set L of links (**edges**): ordered pair of nodes (A,B) .
 - 👉 *The set L is a subset of all possible pairs of nodes in N .*



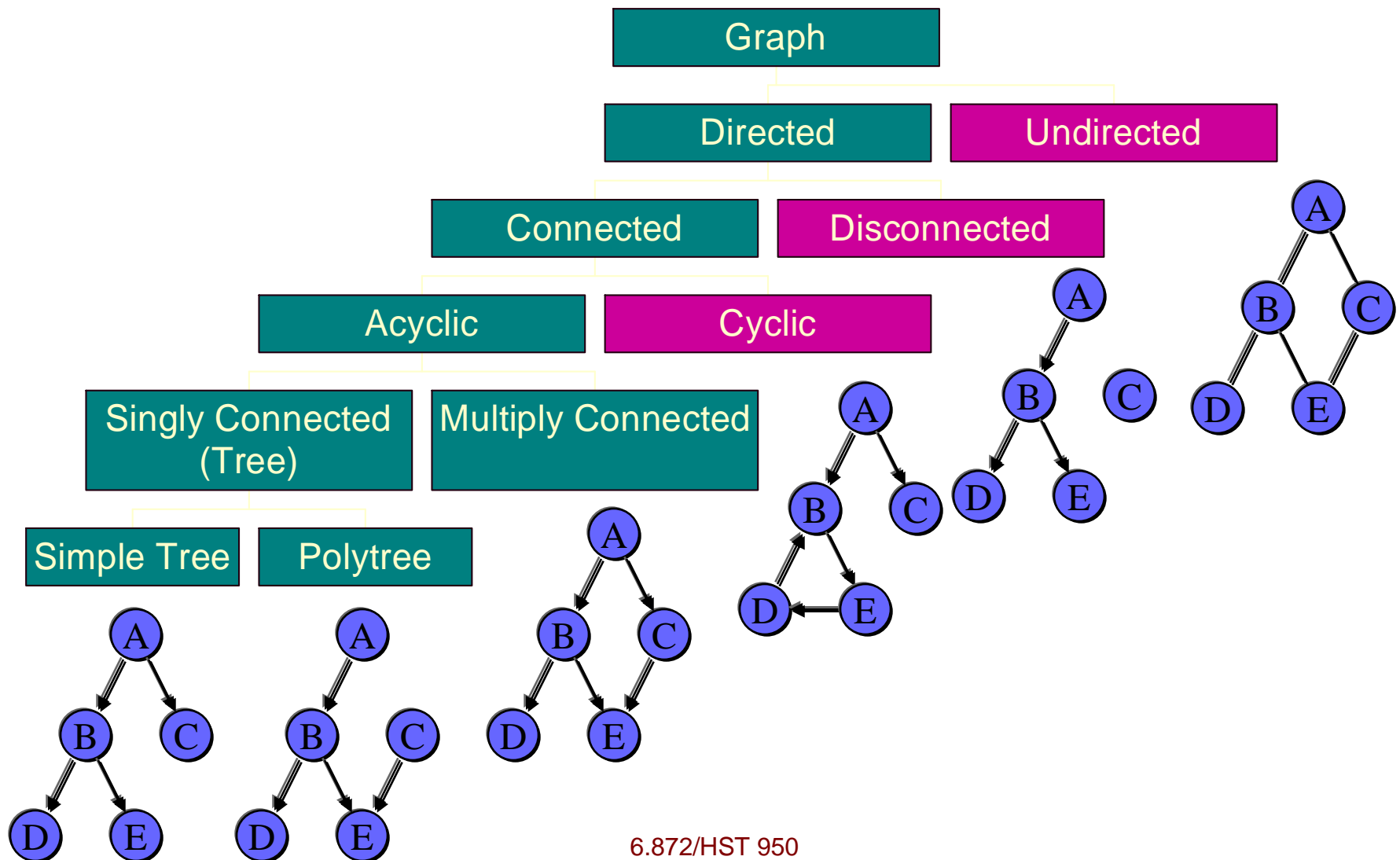
$L = \{(A, C), (B, C), (B, A)\}$

$L = \{(A, C), (B, C)\}$

$L = \{(A, C), (B, C), (B, A), (C, A), (C, B), (A, B)\}$



Types of Graph





Independence

- Two variables are independent ($I(A,B)$) if knowing one does not affect our belief in the other:

$$p(A|B)=p(A)$$

- The conjunction is exactly the Boolean conjunction, since

$$p(A \wedge B)/p(B)=p(A)$$

therefore:

$$p(A \wedge B)=p(A) \times p(B)$$

☞ $p(\text{Rain})=0.2$ $p(\text{Sprinkler})=0.9$
 $p(\text{Rain} \wedge \text{Sprinkler})=0.18$
 $p(\text{Rain})=0.2$ $p(\neg \text{Sprinkler})=0.1$
 $p(\text{Rain} \wedge \neg \text{Sprinkler})=0.02$
 $p(\neg \text{Rain})=0.8$ $p(\text{Sprinkler})=0.9$
 $p(\neg \text{Rain} \wedge \text{Sprinkler})=0.72$
 $p(\neg \text{Rain})=0.8$ $p(\neg \text{Sprinkler})=0.1$
 $p(\neg \text{Rain} \wedge \neg \text{Sprinkler})=0.08$



Conditional Independence

- When two variables are independent given a third, they are said to be conditionally independent.

$$p(A|B \wedge C) = p(A \wedge B \wedge C) / p(B \wedge C) = p(A|C)$$

T-shirt size of kids affect their literacy skills.

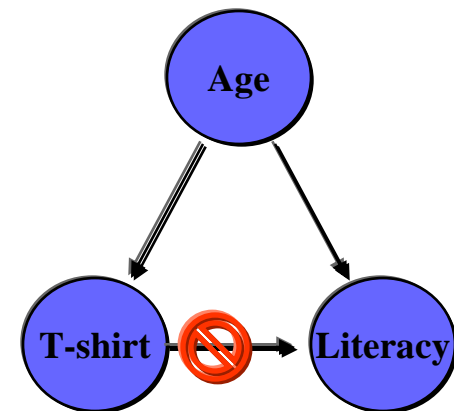
Both T-shirt size and literacy skills depend on age

T-shirt	Literacy		Age	T-shirt	Literacy	
	Yes	No			Yes	No
Small	0.32	0.68	<5	Small	0.3	0.7
Large	0.35	0.65	<5	Large	0.3	0.7
			>5	Small	0.4	0.6
			>5	Large	0.4	0.6



Bayesian Networks

- ✱ Bayesian networks use graphs to capture these statement of conditional independence.
- ✱ A Bayesian network (BBN) is defined by a graph:
 - Nodes are stochastic variables.
 - Links are dependencies.
 - 👉 *Absence of a link denotes independence given a parent.*
- ✱ There are two components in a BBN:
 - Qualitative graphical structure.
 - Quantitative assessment of probabilities.





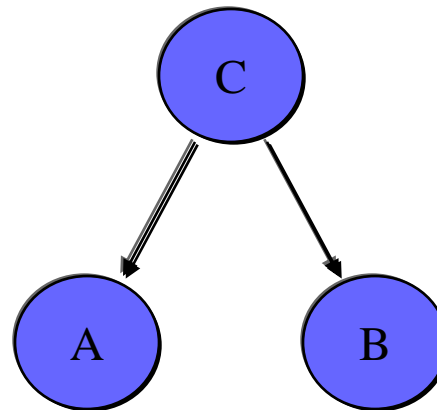
Decomposition

- ★ The power of BBNs is to decompose the joint probability distribution using the graphical structure of conditional independence.

$$p(A|B \wedge C) = p(A|C) \equiv p(A \wedge B | C) = p(A|C) \times p(B|C)$$

- ★ Therefore, the graphical structure factorizes the joint probability distribution:

$$p(A \wedge B \wedge C) = p(A|C) \times p(B|C) \times p(C)$$





Example

Background knowledge: General rules of behavior.

$$p(\text{Age}=\lt 5)=0.3$$

$$p(\text{T-shirt}=\text{small} \mid \text{Age}=\lt 5)=0.5$$

$$p(\text{T-shirt}=\text{small} \mid \text{Age}=\gt 5)=0.3$$

$$p(\text{Literacy}=\text{yes} \mid \text{Age}=\gt 5)=0.6$$

$$p(\text{Literacy}=\text{yes} \mid \text{Age}=\lt 5)=0.2$$

Problem: Observation $p(\text{T-shirt}=\text{small})$

Solution: The posterior probability distribution of the unobserved nodes given problem: $p(\text{Literacy} \mid \text{T-shirt}=\text{small})$ and $p(\text{Age} \mid \text{T-shirt}=\text{small})$

$$p(\text{Age}=\lt 5, \text{T-shirt}=\text{small}, \text{Literacy}=\text{yes})$$

$$p(\text{Age}=\lt 5, \text{T-shirt}=\text{small}, \text{Literacy}=\text{no})$$

$$p(\text{Age}=\lt 5, \text{T-shirt}=\text{large}, \text{Literacy}=\text{yes})$$

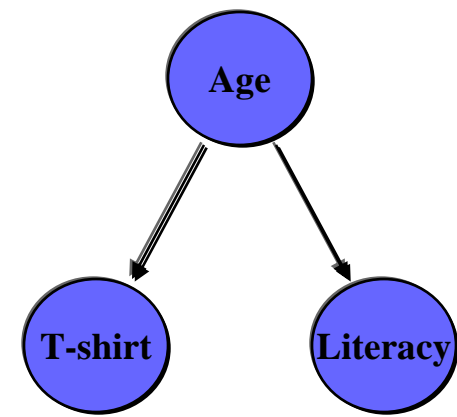
$$p(\text{Age}=\lt 5, \text{T-shirt}=\text{large}, \text{Literacy}=\text{no})$$

$$p(\text{Age}=\gt 5, \text{T-shirt}=\text{small}, \text{Literacy}=\text{yes})$$

$$p(\text{Age}=\gt 5, \text{T-shirt}=\text{small}, \text{Literacy}=\text{no})$$

$$p(\text{Age}=\gt 5, \text{T-shirt}=\text{large}, \text{Literacy}=\text{yes})$$

$$p(\text{Age}=\gt 5, \text{T-shirt}=\text{large}, \text{Literacy}=\text{no})$$





Brute Force

★ The brute force solution:

☆ Compute the Joint Probability Distribution:

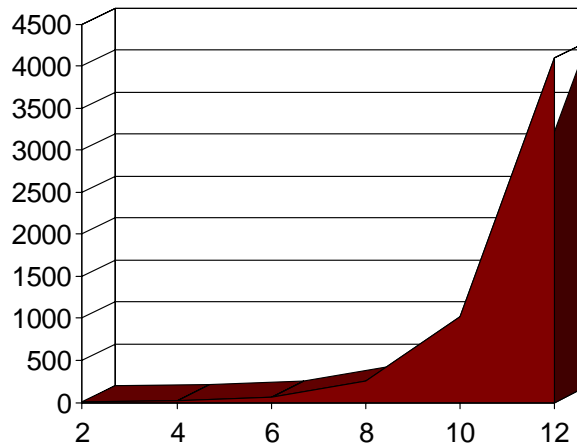
$$p(a,b,c,d,e,f,g) = p(a)p(b)p(c|d)p(d|a,b)p(e)p(f|d)p(g|d,e)$$

🕒 Marginalize out the variable of interest:

$$p(d) = \sum p(a,b,c,e,f,g)$$

✓ Note we have replace \wedge with ,

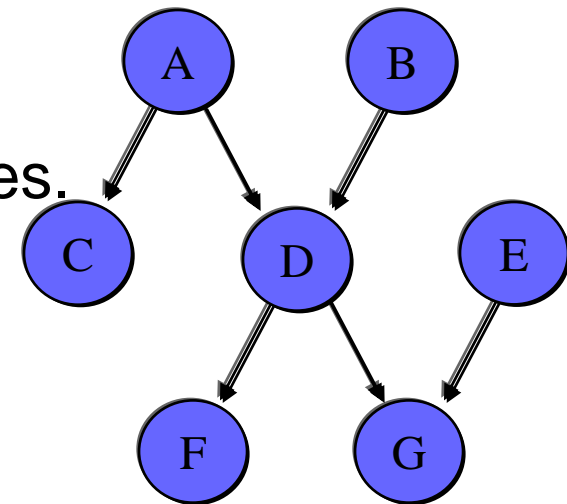
✓ Cost: we need to sum 2^n probabilities ($2^6 = 64$).





Knowledge

- ★ Components of a problem:
 Knowledge: graph and probabilities.
 Problem: $\epsilon = \{c \text{ and } g\}$.
 Solution: $p(d|c,g) = ?$.



A	p(A)
0	0.3
1	0.7

B	p(B)
0	0.6
1	0.4

E	p(E)
0	0.1
1	0.9

A	B	D	p(D A,B)
0	0	0	0.40
0	0	1	0.60
0	1	0	0.45
0	1	1	0.55
1	0	0	0.60
1	0	1	0.40
1	1	0	0.30
1	1	1	0.70

D	E	G	p(G D,E)
0	0	0	0.90
0	0	1	0.10
0	1	0	0.70
0	1	1	0.30
1	0	0	0.25
1	0	1	0.75
1	1	0	0.15
1	1	1	0.85

A	C	p(C A)
0	0	0.25
0	1	0.75
1	0	0.50
1	1	0.50

D	F	p(F D)
0	0	0.80
0	1	0.20
1	0	0.30
1	1	0.70



Method

- In a polytree, each node breaks the graph into two independent graphs and we can deal separately:

 - E^+ : evidence coming from the parents ($E^+ = \{c\}$).
 - E^- : evidence coming from the children ($E^- = \{g\}$).

- Task: $p(d|c,g)$: $p(d|E^+,E^-)$:

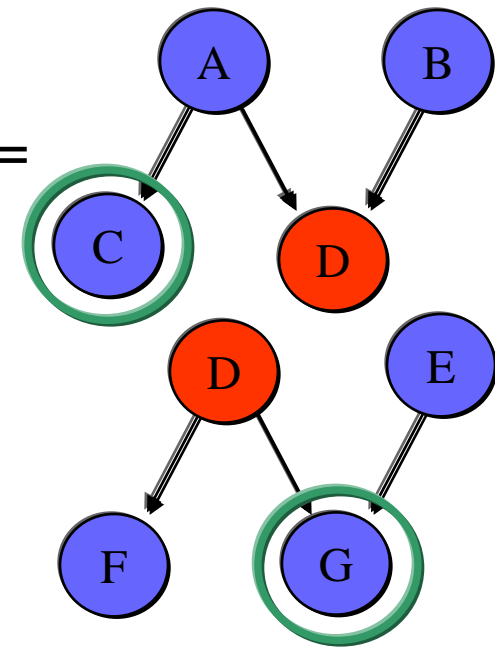
$$\begin{aligned}
 \text{✎ } p(d|E^+,E^-) &= p(E^+,E^-|d)p(d)/p(E^+,E^-) = \\
 &= k p(E^+|d)p(E^-|d)p(d) = k p(E^+,d)p(E^-|d) = \\
 &= k \lambda_D(d)\pi_D(d).
 \end{aligned}$$

$$\text{✎ } k = 1/p(E^+,E^-) \text{ (Normalizing constant)}$$

$$\pi(d) = p(E^+,d) \text{ (Parents messages)}$$

$$\lambda(d) = p(E^-|d) \text{ (Children messages)}$$

$$\text{✎ } p(d|E^+,E^-) = k \pi(d)\lambda(d)$$





Summary

A				
a	ρ	λ	β	p
0	0.3	1.0	0.3	0.3
1	0.7	1.0	0.7	0.7

B				
b	ρ	λ	β	p
0	0.6	1.0	0.6	0.6
1	0.4	1.0	0.4	0.6

a	ρ	λ
0	0.3	1.0
1	0.7	1.0

a	ρ	λ
0	0.3	1.0
1	0.7	1.0

b	ρ	λ
0	0.6	1.0
1	0.4	1.0

C				
C	ρ	λ	β	p
0	0.425	1.0	0.425	0.425
1	0.575	1.0	0.575	0.575

D				
d	ρ	λ	β	p
0	0.462	1.0	0.462	0.462
1	0.538	1.0	0.538	0.538

E				
b	ρ	λ	β	p
0	0.1	1.0	0.1	0.1
1	0.9	1.0	0.9	0.9

d	ρ	λ
0	0.462	1.0
1	0.538	1.0

d	ρ	λ
0	0.462	1.0
1	0.538	1.0

e	ρ	λ
0	0.1	1.0
1	0.9	1.0

F				
f	ρ	λ	β	p
0	0.531	1.0	0.531	0.531
1	0.469	1.0	0.469	0.469

G				
C	ρ	λ	β	p
0	0.419	1.0	0.419	0.419
1	0.581	1.0	0.581	0.581



Summary

A				
a	ρ	λ	β	p
0	0.3	0.42	0.126	0.273
1	0.7	0.48	0.336	0.727

B				
b	ρ	λ	β	p
0	0.6	0.540	0.324	0.701
1	0.4	0.345	0.138	0.299

a	ρ	λ
0	0.3	1.0
1	0.7	1.0

a	ρ	λ
0	0.3	0.42
1	0.7	0.48

b	ρ	λ
0	0.6	0.540
1	0.4	0.345

C				
C	ρ	λ	β	p
0	0.432	1.0	0.432	0.432
1	0.568	1.0	0.568	0.568

D				
d	ρ	λ	β	p
0	1.0	1.0	1.0	1.0
1	0.0	1.0	0.0	0.0

E				
b	ρ	λ	β	p
0	0.1	1.0	0.1	0.1
1	0.9	1.0	0.9	0.9

d	ρ	λ
0	1.0	1.0
1	0.0	1.0

d	ρ	λ
0	1.0	1.0
1	0.0	1.0

e	ρ	λ
0	0.1	0.462
1	0.9	0.462

F				
f	ρ	λ	β	p
0	0.8	1.0	0.8	0.8
1	0.2	1.0	0.2	0.2

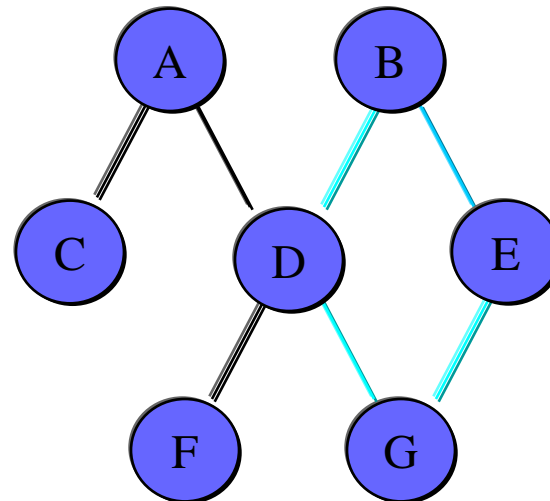
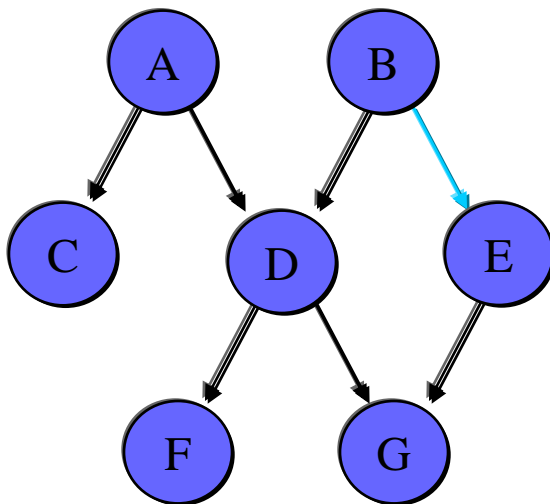
G				
C	ρ	λ	β	p
0	0.72	1.0	0.72	0.72
1	0.28	1.0	0.28	0.28



Multiply Connected BBN

When the BBN is a Multiply connected graph

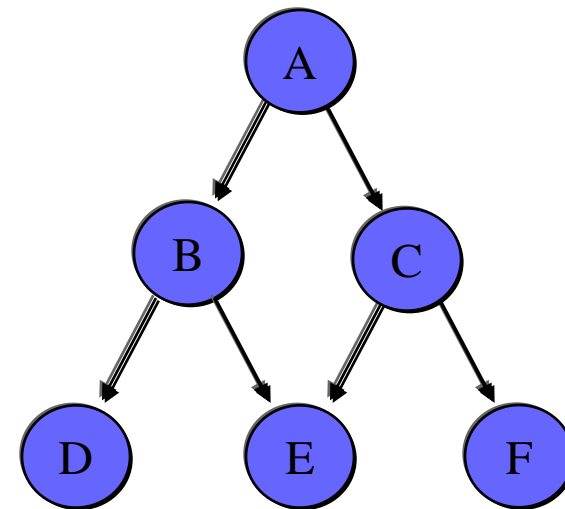
The associated undirected graph contains a loop.
Each node does not break the network in two parts.
Information may flow through more than one paths.
Pearl's Algorithm is no longer applicable.





Example

A Multiply connected BBN



A	p(A)
0	0.3
1	0.7

A	B	p(B A)
0	0	0.4
0	1	0.6
1	0	0.1
1	1	0.9

A	C	p(C A)
0	0	0.2
0	1	0.8
1	0	0.50
1	1	0.50

B	D	p(D B)
0	0	0.3
0	1	0.7
1	0	0.2
1	1	0.8

C	F	p(F C)
0	0	0.1
0	1	0.9
1	0	0.4
1	1	0.6

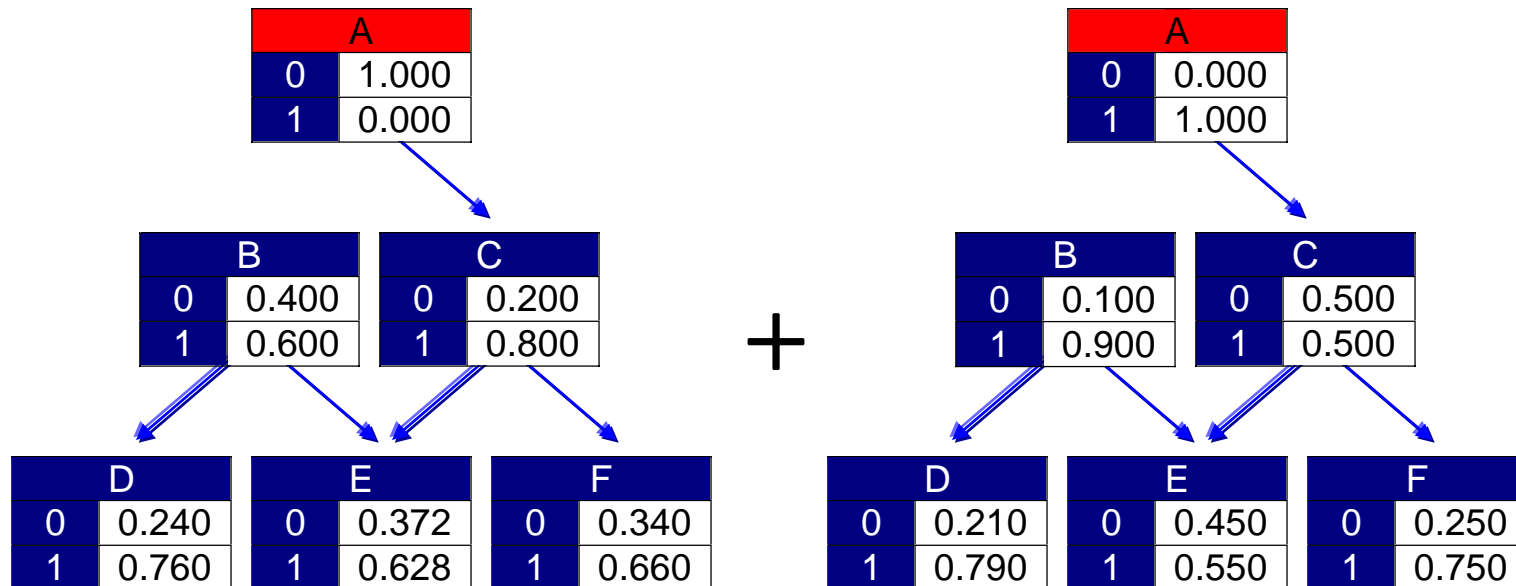
B	C	E	p(E B,C)
0	0	0	0.4
0	0	1	0.6
0	1	0	0.5
0	1	1	0.5
1	0	0	0.7
1	0	1	0.3
1	1	0	0.2
1	1	1	0.8



Conditioning

✱ Loop cutset: {A}.

✱ $p(B=0) = p(B=0|A=0)p(A=0) + p(B=0|A=1)p(A=1)$.



A	
0	0.300
1	0.700

B	
0	0.190
1	0.810

C	
0	0.410
1	0.590

D	
0	0.219
1	0.781

E	
0	0.427
1	0.573

F	
0	0.277
1	0.723



Decision Problems

- ✱ A Decision Problem has three components:
 - ✓ A set of chance variables.
 - ✓ A set of possible alternative decisions.
 - ✓ A utility function ranking the possible outcomes.
- ✱ A set of possible decisions is called a strategy
 - ☞ An antibiotic is given together with vitamins: dosage of antibiotics is one decision, dosage of vitamin another, the strategy identifies the two dosages together.
- ✱ The solution is the strategy that maximizes the expected (value of the) utility. This is called Maximum Expected Utility (MEU) Principle.



Expected Value

- ★ When values are numerical, a BBN can be used to predict the expected value given the evidence:

$$E(A) = \sum_i (p(A=a_i) \times a_i)$$

that is, the sum of each possible value a_i of A times its probability $p(A=a_i)$ of being assigned to A :

1. Propagate the evidence in the BBN.
2. Apply the formula to calculate expected value.

A	p(A)
0	0.2
1	0.1
2	0.3
3	0.1
4	0.3

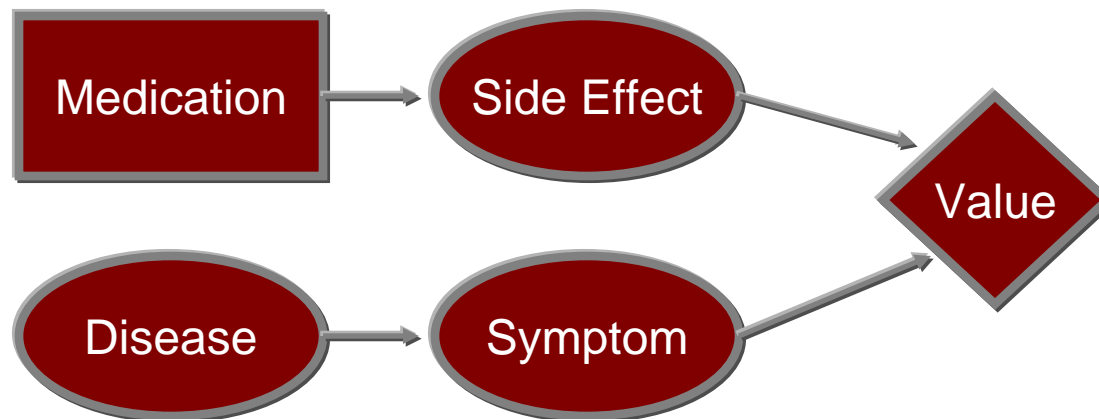


$$E(A) = (0.2 \times 0) + (0.1 \times 1) + (0.3 \times 2) + (0.1 \times 3) + (0.3 \times 4) = 2.2$$



Influence Diagrams

- ★ Influence diagrams are BBN with 3 kinds of nodes:
 - Chance nodes:** stochastic variables (oval)
 - Decision nodes:** variables to be set the value (square).
 - Utility nodes:** variables ranking the outcomes.



Sy	SE	V
0	0	100
0	1	80
1	0	10
1	1	-100



Making Decisions

- ★ The solution of a decision problem is the decision that maximizes the expected utility, and expected utility is the expected value of a utility node.

