## 18.03 Problem Set 9 Solutions

Each problem is worth 16 points, spread across Parts I and II. Part I values: 33: 2 points. 34: 0 points; 35: 2 points for 4G-1(a), 1 for  $e^{At}$ , 1 for A, 2 for 4G-2(a), 2 for 4G-2(b), for a total of 8 points; 36: 4 points.

**I. 35.** 4G-1:  $e^{At} = \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 \end{bmatrix} = \begin{bmatrix} -e^{3t} + e^{2t} & -e^{-3t} + e^{2t} \ 2e^{3t} - 2e^{2t} & -e^{3t} + 2e^{2t} \end{bmatrix}$ the eigenvalues and their eigenvectors:  $A\begin{bmatrix} 1\\1 \end{bmatrix} = 3 \begin{bmatrix} 1\\1 \end{bmatrix}$  and  $A\begin{bmatrix} 1\\2 \end{bmatrix} = 2 \begin{bmatrix} 1\\2 \end{bmatrix}$ . Put these equations e  $e^{3t}$ −  $+$ 2 e e 2 2 t  $t_3t = 2e^{2t}$   $-e^{3t} + 2e^{2t}$ . To find the matrix, note that we know  $\begin{bmatrix} 1 & 1 \end{bmatrix}$   $\begin{bmatrix} 3 & 2 \end{bmatrix}$   $\begin{bmatrix} 4 & -1 \end{bmatrix}$ next to each other:  $A \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 5 & 2 \\ 3 & 4 \end{pmatrix}$ , so  $A = \begin{pmatrix} 5 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 2 & 1 \end{pmatrix}$ .

**33.** (a) [8] The characteristic polynomial of  $A = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix}$  is  $\lambda^2 + 2\lambda + 1 = (\lambda + 1)^2$  which has the repeated root  $\lambda_1 = -1$ . Find a nonzero eigenvector: v killed by  $A - \lambda_1 I = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix}$ :  $\mathbf{v} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$  or any nonzero multiple. So one solution is  $\mathbf{u}_1 = e^{-t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ . For the other we have to solve  $(A - \lambda_1 I)\mathbf{w} = \mathbf{v}$ , i.e.  $\begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} \mathbf{w} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ . One solution is  $\mathbf{w} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ . (If  $\mathbf{w}$  is a solution so is  $\mathbf{w} + \mathbf{v}$  for any eigenvector.) So a second basic solution is  $\mathbf{u}_2 = e^{-t}\begin{bmatrix} 1 \\ -1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} = e^{-t}\begin{bmatrix} t+1 \\ -t \end{bmatrix}$ .

The general solution is a linear combination of these two, and any two linearly independent solutions qualify as a pair of "basic solutions."

 $\lceil x_1 \rceil$   $\lceil e^{-t} \rceil$   $\lceil x_1 \rceil$   $\lceil x_2 \rceil$   $\lceil e^{-t}t \rceil$   $\lceil t \rceil$ (b) [6] The corresponding second order equation is  $\ddot{x} + 2\dot{x} + x = 0$ . The characteristic polynomial is the same as that of its companion matrix (this is a general fact!) so there is a repeated root  $-1$ , and two basic solutions  $x_1 = e^{-t}$  and  $x_2 = te^{-t}$ . The corresponding solitions of the companion system are then  $\begin{bmatrix} x_1 \\ \dot{x}_1 \end{bmatrix} = \begin{bmatrix} e^{-t} \\ -e^{-t} \end{bmatrix} = e^{-t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$  and  $\begin{bmatrix} x_2 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} e^{-\overline{t}}t \\ e^{-t}(1-t) \end{bmatrix} = e^{-t} \begin{bmatrix} t \\ 1-t \end{bmatrix}$ . The first is exactly  $\mathbf{u}_1$ . The second is  $\mathbf{u}_2 - \mathbf{u}_1$ . Of course, there are many choices here. Any two linearly independent solutions of  $\ddot{x} + 2\dot{x} + 2x = 0$  qualifies as a pair of "basic solutions."

**34.** (a) [2] 
$$
A = \begin{bmatrix} 1 & 3 \\ -1 & d \end{bmatrix}
$$
 has trace  $1 + d$  and determinant  $d + 3$ . Thus det = tr + 2.

 $\sqrt{ }$ (b) [4] det  $A = 0$  when  $d = -3$ . det  $A = ((\text{tr}A)/2)^2$  when  $d+3 = ((d+1)/2)^2$ , i.e.  $4d+12 = d^2+2d+1$ (b) [4] det  $A = 0$  when  $a = -3$ . det  $A = ((tA)/2)^2$  when  $a+3 = ((a+1)/2)^2$ , i.e.  $4a+12 = a^2 + 2a + 1$ <br>or  $d^2 - 2d - 11 = 0$ . This happens when  $d = 1 \pm \sqrt{1 - (-11)} = 1 \pm 2\sqrt{3}$ , or about -2.464 and 4.464.  $tr A = 0$  when  $d = -1$ .

(c) [5] Diagram showing:  $d < -3$ —(unstable) saddle

 $d = -3$ —degenerate neutrally stable comb

 $a = -3$ —degenerate neutrally stable comb<br> $-3 < d < 1 - 2\sqrt{3}$ —stable node = nodal sink

 $-3 < a < 1 - 2\sqrt{3}$ —stable node = nodal sink<br>  $d = 1 - 2\sqrt{3}$ —stable defective node = defective nodal sink

 $a = 1 - 2\sqrt{3}$  – stable defective node = defective nodal si<br> $1 - 2\sqrt{3} < d < -1$ —clockwise stable spiral = spiral sink

 $d = -1$ : clockwise center or ellipse

 $a = -1$ : clockwise center or empse<br>  $-1 < d < 1 + 2\sqrt{3}$ —clockwise unstable spiral = spiral source

 $d = 1 + 2\sqrt{3}$ —unstable defective node = defective nodal source

 $a = 1 + 2\sqrt{3}$  — unstable defective node = defective  $1 + 2\sqrt{3} < d$ —unstable node = nodal source.

(d) [5] 9 phase portraits, illustrating the above nine conditions.

**35.** (a) [I.33 work: 
$$
A = \begin{bmatrix} 0 & 1 \ -1 & 2 \end{bmatrix}
$$
 has characteristic polynomial  $\lambda^2 - 2\lambda + 1 = (\lambda - 1)^2$  and has

 $\lambda_1 = 1$  as repeated eigenvalue. It's not diagonal so it's defective.  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  is a nonzero eigenvector, so normal mode  $e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ . To find another solution, solve  $(A - \lambda_1 I)\mathbf{w} = \mathbf{v}_1$ , i.e.  $\begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix} \mathbf{w} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .  $\mathbf{w} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  for any constant c (using this choice of eigenvector); let's take  $\begin{bmatrix} -1 \\ 0 \end{bmatrix}$ . Basic solutions are then  $e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and  $e^t(t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \end{bmatrix}) = e^t \begin{bmatrix} t-1 \\ t \end{bmatrix}$ . [2] A fundamental matrix is given by  $\Phi(t) = e^t \begin{bmatrix} 1 & t-1 \\ 1 & t \end{bmatrix}$ .  $\Phi(0) = \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix}$ , and  $\Phi(0)^{-1} =$ (b) [3]  $\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$  has characteristic polynomial  $\lambda^2 + 1$  and eigenvalues  $\pm i$ . A nonzero eigenvector for  $\lambda = i$  is  $\begin{bmatrix} 1 \\ -i \end{bmatrix}$  (or any nonzero complex multiple), a normal mode is  $e^{it} \begin{bmatrix} 1 \\ -i \end{bmatrix}$ , and basic real solutions are given by the real and imaginary parts of this normal mode:  $\begin{bmatrix} \cos t \\ \sin t \end{bmatrix}$  and  $\begin{bmatrix} \sin t \\ -\cos t \end{bmatrix}$ . (c) [3]  $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$  has characteristic polynomial  $\lambda^2 - 2a + (a^2 + b^2)$  and eigenvalues  $a \pm \sqrt{a^2 - (a^2 + b^2)} =$  $a \pm bi$ . A nonzero eigenvector for  $\lambda_1 = a + bi$  is  $\begin{bmatrix} 1 \\ -i \end{bmatrix}$  (or any nonzero complex multiple), a normal mode is  $e^{(a+bi)t} \begin{bmatrix} 1 \\ -i \end{bmatrix}$ , and basic real solutions are given by the real and imaginary parts of this normal mode:  $e^{at} \begin{bmatrix} \cos(bt) \\ \sin(bt) \end{bmatrix}$  and  $e^{at} \begin{bmatrix} \sin(bt) \\ -\cos(bt) \end{bmatrix}$ . A fundamental matrix is  $\Phi(t) = e^{at} \begin{bmatrix} \cos(bt) & \sin(bt) \\ \sin(bt) & -\cos(bt) \end{bmatrix}$ .  $e^{at} \begin{bmatrix} \cos(bt) & -\sin(bt) \\ \sin(bt) & \cos(bt) \end{bmatrix}.$  $[A = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}]$  is the matrix representing multiplication by  $a + bi$  in the complex plane, and  $e^{At}$  is **36.** [12] The variation of parameters formula for a solution to  $\dot{\mathbf{u}} = A\mathbf{u} + \mathbf{q}(t)$  is  $\mathbf{u} = \Phi(t) \int \Phi(t)^{-1} \mathbf{q}(t) dt$ . We might as well use the exponential matrix  $e^{At} = e^t \begin{bmatrix} 1-t & t \\ -t & 1+t \end{bmatrix}$ . In that case the inverse is  $e^{-At} = e^t \begin{bmatrix} 1-t & t \\ -t & 1+t \end{bmatrix}$ .  $\begin{bmatrix} 0 & 1 \\ -1 & 1 \end{bmatrix}$ . Thus  $e^{At} = \Phi(t)\Phi(0)^{-1} = e^t \begin{bmatrix} 1 & t-1 \\ 1 & t \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 1 \end{bmatrix} = e^t \begin{bmatrix} 1-t & t \\ -t & 1+t \end{bmatrix}$ .  $\begin{bmatrix} 1 & 0 \end{bmatrix}$ A fundamental matrix is  $\Phi(t) = \begin{bmatrix} \cos t & \sin t \\ \sin t & -\cos t \end{bmatrix}$ .  $\Phi(0) = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ ,  $\Phi(0)^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ , and  $e^{At} = \Phi(t)\Phi(0)^{-1} = \begin{bmatrix} \cos t & \sin t \\ \sin t & -\cos t \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{bmatrix}.$  $\Phi(0) = \begin{bmatrix} 1 & 0 \ 0 & -1 \end{bmatrix}$ ,  $\Phi(0)^{-1} = \begin{bmatrix} 1 & 0 \ 0 & -1 \end{bmatrix}$ , and  $e^{At} = \Phi(t)\Phi(0)^{-1} = e^{at} \begin{bmatrix} \cos(bt) & \sin(bt) \ \sin(bt) & -\cos(bt) \end{bmatrix} \begin{bmatrix} 1 & 0 \ 0 & -1 \end{bmatrix} =$ the matrix representing multiplication by  $e^{(a+bi)t}$ .  $e^{-t}\begin{bmatrix} 1+t & -t \\ t & 1-t \end{bmatrix}$ . Then  $e^{-At}\begin{bmatrix} e^t \\ e^t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ , so  $\mathbf{v} = \int e^{-At} \begin{bmatrix} e^t \\ e^t \end{bmatrix} dt = \int \begin{bmatrix} 1 \\ 1 \end{bmatrix} dt = \begin{bmatrix} t \\ t \end{bmatrix} + \mathbf{c}$ .

Thus the general solution is  $\mathbf{u} = e^{At}\mathbf{v} = e^t \begin{bmatrix} t \\ t \end{bmatrix} + e^t \begin{bmatrix} 1-t & t \\ -t & 1+t \end{bmatrix} \mathbf{c}$ . However, our initial condition  $\mathbf{u}(0) = \mathbf{0}$  is already satsfied by  $\mathbf{u} = e^t \begin{bmatrix} t \\ t \end{bmatrix}$ , so that is the desired solution.