

22.05 Reactor Physics Part Twenty-One

Extension of Group Theory to Reactors of Multiple Region Two Energy Groups¹

1. “The basic approximation which leads to one-group theory is that $\Phi(\mathbf{r}, E)$ has a separable energy dependence $\psi^k(E)$ throughout each given material composition k . This approximation is very questionable at interfaces between regions k and l , since the form of $\psi^k(E)$ will not in general match that of $\psi^l(E)$ at such boundary. We tried to minimize this problem by matching $R^k(\mathbf{r}_c)\psi^k(E)$ and $R^l(\mathbf{r}_c)\psi^l(E)$ in an energy-integral sense. But if $\psi^k(E)$ and $\psi^l(E)$ are quite different (as will be in the case if k is core material and l is reflector material), there are bound to be significant mismatches over particular subranges of the overall energy range 0 to ∞ .

For example, at an interface between core and reflector material, the net leakage of high-energy neutrons, which are originally created by fission in the core, is from the core to the reflector, whereas the net leakage of low-energy neutrons, created in abundance by the superior moderating power of the reflector material, is in the opposite direction. A one-group model cannot describe this process. Depending on the sign of $\mathbf{n}_k \cdot D^k \nabla R^k(\mathbf{r})$ ($= \mathbf{n}_k \cdot D^l \nabla R^l(\mathbf{r})$), either a net number of neutrons having the energy distribution $\psi^k(E)$ leak from k to l per second or a net number having the distribution $\psi^l(E)$ leak from l to k .

Two-group theory represents an attempt to improve the accuracy with which the flux can be described near such interfaces. The basic idea is to split the spectrum functions $\psi^k(E)$ into two parts, $\psi_1^k(E)$ (for energy group one, extending from a “cut-point” energy E_c to ∞) and $\psi_2^k(E)$ (for energy group two, extending from 0 to E_c) and to associate separate spatial functions $R_1^k(\mathbf{r})$ and $R_2^k(\mathbf{r})$ with neutrons belonging to each of these two groups. Continuity of flux and current across an interface is then required in an integral sense, individually, for the ranges 0 to E_c and E_c to ∞ . Thus the two-group model permits a net leakage rate of group-one neutrons in one direction across an interface and a net leakage rate of group-two neutrons in the opposite direction. In the interior portions of a given region, where it is expected that the separable form $\Phi(\mathbf{r}, E) = R^k(\mathbf{r})\psi^k(E)$ will be valid over the entire energy range, the two-group approximation will yield the result that $R_1^k(\mathbf{r})$ and $R_2^k(\mathbf{r})$ have the same spatial shape, so that $R_1^k(\mathbf{r})\psi_1^k(E)$ and $R_2^k(\mathbf{r})\psi_2^k(E)$ for the two energy ranges fit together to form a single function of the form $R^k(\mathbf{r})\psi^k(E)$.

¹ Material in this section follows that of Henry pp. 162-165. Portions that are verbatim are indicated by quotations.

Mathematically the assumptions of two-group theory may be summarized as follows:

The scalar flux function may be written, for \mathbf{r} in region k , as:

$$\Phi(\mathbf{r}, E) = \begin{cases} R_1^k(\mathbf{r})\psi_1^k(E) & \text{for } E_c < E < \infty \\ R_2^k(\mathbf{r})\psi_2^k(E) & \text{for } E < E_c \end{cases}$$

Where $\psi_1^k(E)$ and $\psi_2^k(E)$ are the parts of $\psi^k(E)$.” (Henry, pp. 162-163)

2. Derivation of Two-Group Equations

a) Spectrum Equations:

The starting point is again the continuous energy diffusion equation and we follow our now standard procedure.

(i) Write out the continuous energy diffusion equation

$$\begin{aligned} & -\nabla \cdot D(\mathbf{r}, E) \nabla \Phi(\mathbf{r}, E) + \Sigma_t(\mathbf{r}, E)\Phi(\mathbf{r}, E) \\ & = \int_0^\infty \left[\sum_j \chi^j(E) \nu^j \Sigma_f^j(\mathbf{r}, E') + \Sigma_s(\mathbf{r}, E' \rightarrow E) \right] \Phi(\mathbf{r}, E') dE' \end{aligned}$$

(ii) Modify this equation for a homogeneous medium (i.e., material parameters are not position dependent.)

$$\begin{aligned} & -D(E) \nabla^2 \Phi(\mathbf{r}, E) + \Sigma_t(E)\Phi(\mathbf{r}, E) \\ & = \int_0^\infty \left[\frac{1}{\lambda} \chi(E) \nu \Sigma_f(E') + \Sigma_s(E' \rightarrow E) \right] \Phi(\mathbf{r}, E') dE' \end{aligned}$$

(iii) Add superscripts k to denote the various regions of the reactor. We again chose $k=2$ as to describe two regions: Fuel/moderator and reflector. (Note: The regions are **NOT** the groups. The word “group” in group theory refers to the division of the neutron energies.)

$$\begin{aligned}
& -\nabla \cdot \mathbf{D}^k(E) \nabla \Phi(\mathbf{r}, E) + \Sigma_t^k(E) \Phi(\mathbf{r}, E) \\
& = \int_0^\infty \left[\frac{1}{\lambda} \chi^k(E) \nu \Sigma_f^k(E') + \Sigma_s^k(E' \rightarrow E) \right] \Phi(\mathbf{r}, E') dE' \\
& \quad (k = 1, 2, 3, \dots, K)
\end{aligned} \tag{4.9.1}$$

(iv) Approximate the leakage term in each region as:

$$-\nabla \cdot \mathbf{D}^k(E) \nabla \Phi(\mathbf{r}, E) = D^k(E) (B_m^k)^2 \Phi(\mathbf{r}, E)$$

and rewrite the diffusion equation for each region as:

$$\begin{aligned}
& \left(D^k(E) (B_m^k)^2 + \Sigma_t^k(E) \right) \Phi(\mathbf{r}, E) \\
& = \int_0^\infty \left[\frac{1}{\lambda} \chi^k(E) \nu \Sigma_f^k(E') + \Sigma_s^k(E' \rightarrow E) \right] \Phi(\mathbf{r}, E') dE'
\end{aligned}$$

for \mathbf{r} in the interior of region k ; $k = 1, 2$.

(v) Substitute the two group definition of the scalar flux

$$\Phi(\mathbf{r}, E) = \begin{cases} R_1^k(\mathbf{r}) \psi_1^k(E) & \text{for } E_c < E < \infty \\ R_2^k(\mathbf{r}) \psi_2^k(E) & \text{for } E < E_c \end{cases}$$

into the above relation and obtain two spectral equations for each region. For region 1, these would be

$$\begin{aligned}
& \left[D^1(E) (B_m^1)^2 + \Sigma_t^1(E) \right] R_1^1(r) \psi_1^1(E) \\
& = \int_{E_c}^\infty \left[\chi^1(E) \nu \Sigma_f^1(E') + \Sigma_s^1(E' \rightarrow E) \right] R_1^1(r) \psi_1^1(E') dE'
\end{aligned}$$

and

$$\begin{aligned}
& \left[D^1(E) (B_m^1)^2 + \Sigma_t^1(E) \right] R_2^1(r) \psi_2^1(E) \\
& = \int_0^{E_c} \left[\chi^1(E) \nu \Sigma_f^1(E') + \Sigma_s^1(E' \rightarrow E) \right] R_2^1(r) \psi_2^1(E') dE'
\end{aligned}$$

(Note: The difficult part of these equations is the notation. Superscripts denote regions; subscripts denote energy groups.)

The equations for region 2 are similar. These four equations are solved for the spectral functions to obtain $\psi_1(E)$ and $\psi_2(E)$.

b. Spatial Equations:

We now have the energy distribution of the scalar neutron flux and can obtain two group cross-sections.

Hence, we can proceed with the spatial analysis. We now quote again from Henry's Nuclear Reactor analysis (p. 163):

- “The scalar flux function may be written, for r in region k , as:

$$\Phi(\mathbf{r}, E) = \begin{cases} R_1^k(\mathbf{r})\psi_1^k(E) & \text{for } E_c < E < \infty \\ R_2^k(\mathbf{r})\psi_2^k(E) & \text{for } E < E_c \end{cases} \quad (4.11.1)$$

Where $\psi_1^k(E)$ and $\psi_2^k(E)$ are parts of $\psi^k(E)$ found as described above.

- Boundary conditions, for k and l indicating any two adjacent compositions and \mathbf{r}_c being a point on the interface separating them, require that

$$\int_{E_c}^{\infty} dE R_1^k(\mathbf{r}_c)\Psi_1^k(E) = \int_{E_c}^{\infty} dE R_1^l(\mathbf{r}_c)\Psi_1^l(E)$$

$$\int_0^{E_c} dE R_2^k(\mathbf{r}_c)\Psi_2^k(E) = \int_0^{E_c} dE R_2^l(\mathbf{r}_c)\Psi_2^l(E)$$

$$\int_{E_c}^{\infty} dE \mathbf{n}_k \cdot \mathbf{D}^k(E)\nabla[R_1^k(\mathbf{r}_c)\Psi_1^k(E)] = \int_{E_c}^{\infty} dE \mathbf{n}_k \cdot \mathbf{D}^l(E)\nabla[R_1^l(\mathbf{r}_c)\Psi_1^l(E)]$$

$$\int_0^{E_c} dE \mathbf{n}_k \cdot \mathbf{D}^k(E)\nabla[R_2^k(\mathbf{r}_c)\Psi_2^k(E)] = \int_0^{E_c} dE \mathbf{n}_k \cdot \mathbf{D}^l(E)\nabla[R_2^l(\mathbf{r}_c)\Psi_2^l(E)]$$

As with the one group case, it simplifies the algebra if, after having found the shape in energy of $\psi_1^k(E)$ and $\psi_2^k(E)$ for the material of region k , we renormalize these two segments $\psi^k(E)$ so that

$$\int_{E_c}^{\infty} \Psi_1^k(E) dE = 1 \quad (k = 1, 2, \dots, K),$$

$$\int_0^{E_c} \Psi_2^k(E) dE = 1 \quad (k = 1, 2, \dots, K).$$

Then the continuity equations show that $R_1^k(\mathbf{r}_c) = R_1^l(\mathbf{r}_c)$ and $R_2^k(\mathbf{r}_c) = R_2^l(\mathbf{r}_c)$ for points \mathbf{r}_c on the interface between regions k and l . Thus, as in the one-group case, the superscript k on the functions R are superfluous, and we shall change notation by replacing the various $R_1^k(\mathbf{r})$ by the single, everywhere-continuous function $\Phi_1(\mathbf{r})$ and similarly replacing $R_2^k(\mathbf{r})$ by $\Phi_2(\mathbf{r})$. The functions $\Phi_1(\mathbf{r})$ and $\Phi_2(\mathbf{r})$ are called the two-group fluxes. Note that they are not fluxes per unit energy (in the way that $\Phi(\mathbf{r}, E) = v(E)n(\mathbf{r}, E)$ is). Physically $\Phi_1(\mathbf{r})$ is the two-group approximation to the number of neutrons per cc having energies in the range E_c to ∞ $\left(\int_{E_c}^{\infty} n(\mathbf{r}, E) dE \right)$ multiplied by the average “fast” speed.

$$v_1 = \frac{\int_{E_c}^{\infty} v(E)n(\mathbf{r}, E) dE}{\int_{E_c}^{\infty} n(\mathbf{r}, E) dE}$$

And $\Phi_2(\mathbf{r})$ is the two-group approximation to the number in the range 0 to E_c multiplied by the average thermal speed.

$$v_2 = \frac{\int_0^{E_c} v(E)n(\mathbf{r}, E) dE}{\int_0^{E_c} n(\mathbf{r}, E) dE}$$

(These interpretations are somewhat ambiguous since (4.11.1), on which they are based, is an approximation which cannot be rigorously correct.)

To find differential equations for the two-group fluxes $\Phi_1(\mathbf{r})$ and $\Phi_2(\mathbf{r})$ we substitute the approximation (4.11.1) into (4.9.1) which is the homogenized diffusion equation for two regions. This will give us different results for $E > E_c$ and $E < E_c$.

$$\begin{aligned} & -D^k(E)\psi_1^k(E)\nabla^2\Phi_1(\mathbf{r}) + \Sigma_t^k(E)\psi_1^k(E)\Phi_1(\mathbf{r}) \\ & = \int_{E_c}^{\infty} \left[\frac{1}{\lambda} \chi^k(E)v\Sigma_f^k(E')\psi_1^k(E') + \Sigma_s^k(E' \rightarrow E)\psi_1^k(E') \right] dE' \Phi_1(\mathbf{r}) \\ & \quad + \int_0^{E_c} \left[\frac{1}{\lambda} \chi^k(E)v\Sigma_f^k(E')\psi_2^k(E') \right] dE' \Phi_2(\mathbf{r}) \quad \text{for } E > E_c \end{aligned} \tag{4.11.4}$$

and

$$\begin{aligned}
& -D^k(E)\psi_2^k(E)\nabla^2\Phi_2(\mathbf{r}) + \Sigma_t^k(E)\psi_2^k(E)\Phi_2(\mathbf{r}) \\
& = \int_{E_c}^{\infty} \left[\frac{1}{\lambda} \chi^k(E) \nu \Sigma_f^k(E') \psi_1^k(E') + \Sigma_s^k(E' \rightarrow E) \psi_1^k(E') \right] dE' \Phi_1(\mathbf{r}) \\
& \quad + \int_0^{E_c} \left[\frac{1}{\lambda} \chi^k(E) \nu \Sigma_f^k(E') \psi_2^k(E') + \Sigma_s^k(E' \rightarrow E) \psi_2^k(E') \right] dE' \Phi_2(\mathbf{r}) \quad \text{for } E \leq E_c
\end{aligned} \tag{4.11.5}$$

Where on physical grounds we have omitted from (4.11.4) the scattering from $E' < E_c$ to $E > E_c$ (For thermal reactors the cut point E_c will always be such that $\chi^k(E)$ is zero for $E < E_c$; hence no fission terms will appear in (4.11.5). We retain them for possible application to fast reactors, for which E_c will be much higher.

There is no solution $\Phi_1(\mathbf{r})$, $\Phi_2(\mathbf{r})$ that will satisfy (4.11.4) and (4.11.5) at all energies since the form (4.11.1) is not sufficiently general. However, we can force equality of the right- and left-hand sides in an integral sense and in that way find equations which, when solved, will give us $\Phi_1(\mathbf{r})$ and $\Phi_2(\mathbf{r})$. Accordingly, we shall integrate (4.11.4) from E_c to ∞ and (4.11.5) from 0 to E_c and require that the resultant equations be valid at all \mathbf{r} . To simplify the result, we first define a set of “two-group constants”:

$$\begin{aligned}
D_1^k & \equiv \int_{E_c}^{\infty} D(E) \Psi_1^k(E) dE, & D_2^k & \equiv \int_0^{E_c} D(E) \Psi_2^k(E) dE, \\
\Sigma_{t1}^k & \equiv \int_{E_c}^{\infty} \Sigma_t^k(E) \Psi_1^k(E) dE, & \Sigma_{t2}^k & \equiv \int_0^{E_c} \Sigma_t^k(E) \Psi_2^k(E) dE \\
\chi_1^k & \equiv \int_{E_c}^{\infty} \chi^k(E) dE, & \chi_2^k & \equiv \int_0^{E_c} \chi^k(E) dE \\
\nu \Sigma_{f1}^k & \equiv \int_{E_c}^{\infty} \nu \Sigma_f^k(E) \Psi_1^k(E) dE, & \nu \Sigma_{f2}^k & \equiv \int_0^{E_c} \nu \Sigma_f^k(E) \Psi_2^k(E) dE, \\
\Sigma_{11}^k & \equiv \int_{E_c}^{\infty} dE, \int_{E_c}^{\infty} dE' \Sigma_s^k(E' \rightarrow E) \psi_1^k(E'), & \Sigma_{22}^k & \equiv \int_0^{E_c} dE, \int_0^{E_c} dE' \Sigma_s^k(E' \rightarrow E) \psi_2^k(E') \\
\Sigma_{21}^k & \equiv \int_0^{E_c} dE, \int_{E_c}^{\infty} dE' \Sigma_s^k(E' \rightarrow E) \psi_1^k(E') & \Sigma_1^k & \equiv \Sigma_{t1}^k - \Sigma_{11}^k, & \Sigma_2^k & \equiv \Sigma_{t2}^k - \Sigma_{22}^k
\end{aligned}$$

Using these definitions, integrating (4.11.4) from E_c to ∞ . and integrating (4.11.5) from 0 to E_c , we get

$$\begin{aligned}
 -D_1^k \nabla^2 \Phi_1(r) + \Sigma_1^k \Phi_1(r) &= \frac{1}{\lambda} \chi_1^k \left[\nu \Sigma_{f1}^k \Phi_1(r) + \nu \Sigma_{f2}^k \Phi_2(r) \right] \\
 -D_2^k \nabla^2 \Phi_2(r) + \Sigma_2^k \Phi_2(r) &= \frac{1}{\lambda} \chi_2^k \left[\nu \Sigma_{f1}^k \Phi_1(r) + \nu \Sigma_{f2}^k \Phi_2(r) \right] + \Sigma_{21}^k \Phi_1(r)
 \end{aligned}$$

(4.11.7)

The boundary conditions become:

1. $\Phi_1(r)$, $\Phi_2(r)$ must be continuous everywhere,
2. $n \cdot D_1 \nabla \Phi_1(r)$ and $n \cdot D_2 \nabla \Phi_2(r)$ must be continuous across interfaces separating different material compositions,
3. $\Phi_1(r) = \Phi_2(r)$ on the outer boundary of the reactor.

The above equations (4.11.7) are the “two-group diffusion equations.” They are the standard workhorses of thermal-reactor design. It can be proved that a unique, positive solution corresponding to a most-positive real eigenvalue λ always exists for the two-group equations. Thus, a physically acceptable solution for the group fluxes Φ_1 and Φ_2 can always be found, and from this the two-group approximation $(\Phi_1(r)\psi_1^k(E))$, $(\Phi_2(r)\psi_2^k(E))$ for the scalar flux $\Phi(\mathbf{r}, E)$ can be constructed throughout each material composition k .” (Henry, pp. 163-165)