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QUASILINEAR THEORY OF DIOCOTRON INSTABILITY FOR NONRELATIVISTIC NONNEUTRAL ELECTRON FLOW IN A PLANAR DIODE WITH APPLIED MAGNETIC FIELD

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QUASILINEAR THEORY OF DIOCOTRON INSTABILITY FOR NONRELATIVISTIC NONNEUTRAL ELECTRON FLOW IN A PLANAR DIODE WITH APPLIED MAGNETIC FIELD

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ABSTRACT

A macroscopic cold-fluid model is used to investigate the quasilinear stabilization of the diocotron instability for sheared, nonrelativistic electron flow in a planar diode with cathode and anode located at x=0 and x=d, respectively. The nonneutral plasma is immersed in a strong applied magnetic field B_{OVa} , and the electrons are treated as a massless (m+0) guiding-center fluid with flow velocity $V_b = -(c/B_0) \nabla \phi \times \hat{e}_z$, where $\partial/\partial z = 0$ is assumed, and the fields are electrostatic with $E = -\nabla \phi$. All quantities are assumed to be periodic in the ydirection with periodicity length L. The nonlinear continuity-Poisson equations are used to obtain coupled quasilinear kinetic equations describing the selfconsistent evolution of the average density $\langle n_{b} \rangle (x,t)$ and spectral energy density ${m {m \ell}}_{_{lr}}({
m x},{
m t})$ associated with the y-electric field perturbations. Here, the average flow velocity in the y-direction is $V_E(x,t)=(c/B_0)(\partial/\partial x)<\phi>(x,t)$, where average quantities are defined by $\langle\psi>(x,t)=\int_0^L (dy/L)\psi(x,y,t)$. Several general features of the quasilinear evolution of the system are discussed, including a derivation of exact conservation constraints. Typically, if the initial profile $\langle n_{b} \rangle$ (x,t=0) corresponds to instability with $\gamma_{k}(0) \rangle 0$, the perturbations amplify, and the density profile $\langle n_h \rangle(x,t)$ readjusts in such a was as to reduce the growth rate $\gamma_k(t)$ and stabilize the instability. As a specific example, we consider the quasilinear evolution of the diocotron instability for $\langle n_h \rangle(x,0)$ corresponding to a gentle density bump superimposed on a rectangular density profile in contact with the cathode.

I. INTRODUCTION AND SUMMARY

There is a growing literature on the equilibrium and linear stability properties of sheared, nonneutral electron flow in $cylindrical^1$ and $planar^{2-6}$ models of high-voltage diodes with application to the generation of intense charged particle beams for inertial confinement fusion.⁷ These analyses 1-6 have represented major extensions of earlier theoretical work $^{8-12}$ to include the important influence of cylindrical, 1 relativistic, $^{2-6}$ electromagnetic, 2^{-6} and kinetic⁶ effects on stability behavior at moderately high electron density. Nonetheless, while there is an increased understanding of the linear stability properties of nonneutral electron flow in various parameter regimes, there has been very little progress in describing the nonlinear evolution and stabilization of the instabilities. For sufficiently strong instability, it is reasonable to expect that the amplifying field perturbations may significantly modify the electron density and flow velocity profiles, and perhaps have a deliterious effect on the operating characteristics of the diode. In addition, in circumstances involving the generation of intense ion beams, sufficiently large-amplitude field perturbations may cause unacceptably large ion deflections and poor beam collimation. Therefore, as an attempt to delineate some of the fundamental physics issues associated with the nonlinear development of instabilities driven by velocity shear, we develop here a detailed guasilinear description of the classical diocotron instability.8-12

In the present analysis, we make use of a macroscopic coldfluid model to investigate the nonlinear stabilization of the diocotron instability for sheared, nonrelativistic electron flow in a planar diode (Fig. 1). As summarized in Sec. II, the nonneutral electron plasma is immersed in a strong applied magnetic field $B_0\hat{e}_z$, and the electrons are treated as a massless (m+0), guiding-center fluid with flow velocity [Eq. (2)]

where it is assumed that $\partial/\partial z=0$ and the fields are electrostatic with $\mathcal{E}(x,y,t) = -\nabla\phi(x,y,t)$. The cold-fluid model is based on the continuity-Poisson equations [Eqs. (7) and (8)]

$$\frac{\partial}{\partial t} n_{b} + \frac{\partial}{\partial x} (n_{b} V_{bx}) + \frac{\partial}{\partial y} (n_{b} V_{by}) = 0,$$

$$\left(\frac{\partial^{2}}{\partial x^{2}} + \frac{\partial^{2}}{\partial y^{2}}\right) \phi = 4\pi e n_{b},$$

which describe the self-consistent nonlinear evolution of the electron density $n_b(x,y,t)$ and electrostatic potential $\phi(x,y,t)$. Quantities are expressed as an average value (averaged over y) plus a perturbation, e.g., $n_b(x,y,t) = \langle n_b \rangle \langle x,t \rangle + \delta n_b(x,y,t)$, where $\langle n_b \rangle \equiv \int_0^L \frac{dy}{L} n_b(x,y,t)$, $\langle \delta n_b \rangle = 0$, and L is the periodicity length in the y-direction (Fig. 1 and Sec. II). It is found, for example, that the average density profile $\langle n_b \rangle \langle x,t \rangle$ evolves non-linearly according to [Eq. (14)]

$$\frac{\partial}{\partial t} \langle n_b \rangle = \frac{c}{B_0} \frac{\partial}{\partial x} \langle \delta n_b \frac{\partial}{\partial y} \delta \phi \rangle$$
,

and the average $\mathop{E}_{\mathcal{V}} \times \mathop{B_0\hat{e}_z}_{\mathcal{O}\mathcal{V}_z}$ flow velocity in the y-direction is given

by [Eqs. (27) and (59)]

$$V_{E}(x,t) = \frac{c}{B_{0}} \frac{\partial}{\partial x} \langle \phi \rangle (x,t) = \frac{4\pi ec}{B_{0}} \int_{0}^{x} dx' \langle n_{b} \rangle (x',t).$$

Therefore, as the perturbations δn_b and $\delta \phi$ amplify, there is a corresponding readjustment of the density profile $\langle n_b \rangle$ and flow velocity V_E in response to the instability.

In Secs. III and IV, the formalism developed in Sec. II is used to obtain a lowest-order nonlinear (i.e., quasilinear) description of the evolution of the average density profile $\langle n_b \rangle (x,t)$ and the spectral energy density $\mathcal{E}_k(x,t) = (k^2 | \delta \phi_k(x) |^2 / 8\pi) \times \exp[2 \int_0^t dt' \gamma_k(t')]$ in the y-electric field perturbations, $\delta E_y(x,y,t) = -(\partial/\partial y) \delta \phi(x,y,t)$. The quasilinear analysis assumes that the initial density profile $\langle n_b \rangle (x,0)$ corresponds to linear instability with $\gamma_k(0) > 0$. Moreover, bilinear nonlinearities (proportional to $\delta n_b \delta \phi$) are neglected in describing the evolution $\delta n_b(x,y,t)$. [Compare Eqs. (19) and 26).]

To briefly summarize, we obtain coupled kinetic equations for the average density profile $\langle n_b \rangle(x,t)$ and spectral energy density $\hat{\mathcal{E}}_k(x,t)$ [Eqs. (55) and (57)]

$$\frac{\partial}{\partial t} \langle \mathbf{n}_{\mathbf{b}} \rangle = \frac{\partial}{\partial \mathbf{x}} \left(\mathbf{D} \frac{\partial}{\partial \mathbf{x}} \langle \mathbf{n}_{\mathbf{b}} \rangle \right) ,$$
$$\frac{\partial}{\partial t} \hat{\boldsymbol{\mathcal{E}}}_{\mathbf{k}} = 2\gamma_{\mathbf{k}} \hat{\boldsymbol{\mathcal{E}}}_{\mathbf{k}} ,$$

where the diffusion coefficient D(x,t) is defined by [Eq. (56)]

$$D(x,t) = \frac{8\pi c^2}{B_0^2} \int dk \frac{\gamma_k \mathcal{E}_k}{(\omega_k - kV_E)^2 + \gamma_k^2}$$

and the complex oscillation frequency $\omega_{\mathbf{k}} + i\gamma_{\mathbf{k}}$ is determined from the eigenvalue equation [Eq. (58)]

$$\frac{\partial^{2}}{\partial x^{2}} \hat{\phi}_{\mathbf{k}} - \mathbf{k}^{2} \hat{\phi}_{\mathbf{k}} = - \frac{\mathbf{k} \hat{\phi}_{\mathbf{k}}}{\omega_{\mathbf{k}} - \mathbf{k} \nabla_{\mathbf{E}} + \mathbf{i} \gamma_{\mathbf{k}}} \frac{4\pi e^{2}}{m \omega_{\mathbf{C}}} \frac{\partial}{\partial x} < n_{\mathbf{b}} >$$

Note that $\omega_k + i\gamma_k$ varies adiabatically in time in response to the slow evolution of $\langle n_h \rangle$ and V_E .

General features of the quasilinear evolution of the system are described in Sec. IV.B, including exact conservation constraints satisfied by Eqs. (55) - (58). Typically, if the initial profile $\langle n_b \rangle \langle x,t=0 \rangle$ corresponds to instability with $\gamma_k(0) > 0$, the perturbations will amplify [Eq. (57)], and the density profile $\langle n_b \rangle \langle x,t \rangle$ will readjust [Eq. (55)] in such a way as to reduce the growth rate $\gamma_k(t)$ and stabilize the instability [Eqs. (57) and (58)].

As a specific example, we consider in Sec. IV.C the quasilinear evolution of the diocotron instability for $\langle n_b \rangle (x,0)$ corresponding to a gentle density bump superimposed on a rectangular density profile in contact with the cathode (Fig. 4). Such a configuration gives a weak resonant version of the diocotron instability with $|\gamma_k| << |\omega_k|$ and growth rate given by [Eq. 81)]

$$\gamma_{\mathbf{k}} = \pi \left[\frac{\omega_{\mathbf{k}} - \mathbf{k} \mathbf{V}_{\mathbf{E}}(\mathbf{b})}{|\mathbf{k} \mathbf{V}_{\mathbf{E}}(\mathbf{b})|} - \frac{|\hat{\delta \phi}_{\mathbf{k}}^{\mathbf{I}}|_{\mathbf{x}=\mathbf{x}_{\mathbf{S}}}^{2}}{|\hat{\delta \phi}_{\mathbf{k}}^{\mathbf{I}}|_{\mathbf{x}=\mathbf{b}}^{2}} - \frac{\mathbf{b}}{\hat{n}_{\mathbf{b}}} \frac{\partial}{\partial \mathbf{x}} < \mathbf{n}_{\mathbf{b}} > \right|_{\mathbf{x}=\mathbf{x}_{\mathbf{S}}}$$

Here, the resonant location x_s is determined from [Eq. (50)].

 $\omega_{\mathbf{k}} - \mathbf{k} \mathbf{V}_{\mathbf{E}}(\mathbf{x}_{\mathbf{S}}) = \mathbf{0},$

and the surface of the electron layer is located at x=b (Fig. 4). In the resonant region of x-space, the diffusion coefficient can be expressed as [Eq. (62)]

$$D_{r} = \frac{8\pi^{2}c^{2}}{B_{0}^{2}} \int dk \boldsymbol{\mathcal{E}}_{k} \delta (\omega_{k} - kV_{E})$$

It is shown in Sec. IV.C that the system stabilizes time asymptotically by plateau formation with [Eq. (92)]

$$\frac{\partial}{\partial \mathbf{x}} < \mathbf{n}_{b} > (\mathbf{x}, t \rightarrow \infty) |_{\mathbf{x} = \mathbf{x}_{s}} = \mathbf{0}$$

and $\gamma_k(t \rightarrow \infty) = 0$.

Finally, for the configuration with gentle density bump considered in Sec. IV.C, we also make use of the quasilinear equations to obtain an order-of-magnitude estimate of the saturation level of the perturbed fields. This gives [Eq. (100)]

$$\langle \delta E_{Y}^{2}(b,\infty) \rangle \approx \frac{1}{6} \frac{\Delta_{b}^{2}}{b^{2}} - \frac{\Delta n_{b}}{\hat{n}_{b}} \langle E_{x}(b) \rangle^{2}$$
,

where Δn_b and Δ_b are the characteristic height and width, respectively, of the density bump (Fig. 4).

Note that the above saturation level can be substantial, even for small values of $\Delta n_b / \hat{n}_b$. If, for example, an ion were accelerated from rest in characteristic steady field strengths $\langle E_x(b) \rangle$ and $\Delta E_y = \langle \delta E_y^2(b, \infty) \rangle^{1/2}$, then the fractional velocity deflection of the ion would be

$$\frac{\Delta V_{yi}}{V_{xi}} \approx \frac{\Delta_b}{b} \left(\frac{\Delta n_b}{6 \hat{n}_b} \right)^{1/2}$$

Of course, this estimate of $\Delta V_{yi}/V_{xi}$ is valid for times shorter than the characteristic time scale (ω_d^{-1}) for oscillation of δE_y . Nonetheless, this deflection can be substantial, e.g., $\Delta V_{yi}/V_{xi} \approx 5\%$ for $\Delta_b/b = 1/2$ and $\Delta n_b/6\hat{n}_b = 1/100$.

II. THEORETICAL MODEL

In this section, we discuss various general aspects of the theoretical model and assumptions (Sec. II.A), the nonlinear evolution of average quantities (Sec. II.B), the nonlinear evolution of perturbed quantities (Sec. II.C), and boundary conditions at the cathode and anode (Sec. II.D).

A. Theoretical Model and Assumptions

We consider here the nonrelativistic flow of a cold, nonneutral pure electron plasma confined in the planar diode configuration illustrated in Fig. 1. The cathode is located at x = 0 and the anode at x = d. The electron fluid is immersed in a uniform applied magnetic field $B_{0\sqrt{2}}$. The analysis is based on a macroscopic cold-fluid description with the following simplifying assumptions.

(a) All fluid and field quantities are assumed to be independent of $z(\partial/\partial z = 0)$ and spatially periodic in the y-direction with periodicity length L. For example, the electron density $n_b(x,t)$ satisfies $n_b(x,y+L,t) = n_b(x,y,t)$.

(b) The fields are assumed to be electrostatic with electric field

$$E(\mathbf{x},t) = -\nabla\phi(\mathbf{x},\mathbf{y},t), \qquad (1)$$

and magnetic field $B_0 \hat{e}_z$.

(c) In the present analysis the electrons are treated as a cold, massless $(m \rightarrow 0)$, guiding-center fluid with flow velocity $V_{b} = c_{k} \times \hat{e}_{z} / B_{0}$, i.e., ^{8,9}

 $V_{b}(x,t) = -\frac{c}{B_{0}}\nabla\phi \times \hat{e}_{z} \qquad (2)$

Equivalently, Eq. (2) can be expressed as

$$V_{bx}(x,y,t) = -\frac{c}{B_0} \frac{\partial}{\partial y} \phi(x,y,t),$$

$$V_{by}(x,y,t) = \frac{c}{B_0} \frac{\partial}{\partial x} \phi(x,y,t).$$
(3)

A cold electron fluid model with $E + V_b \times B_0 \hat{e}_z / c = 0$ [Eq. (2)] is valid provided the electron density is sufficiently low and perturbations have sufficiently low frequency that ^{8,9,12}

$$\begin{aligned} & \omega_{\rm pb}^2 << \omega_{\rm c}^2 , \\ & \left| \frac{\partial}{\partial t} \right| << \omega_{\rm c} . \end{aligned}$$
 (4)

Here $\omega_c = eB_0/mc$ is the electron cyclotron frequency, $\omega_{pb}^2 = 4\pi n_b e^2/m$ is the electron plasma frequency-squared, and -e and m are the electron charge and rest mass, respectively. Note from Eq. (2) that the electron flow in the present model is incompressible with $\nabla \cdot V_b = 0$.

(d) Finally, it is also assumed that the equilibrium electron flow is space-charge limited. That is, under steady-state $(\partial/\partial t=0)$ conditions, the electrostatic potential $\phi_0(x)$ satisfies

$$E_{x}^{0}(x=0) = -\partial\phi_{0}/\partial x \Big|_{x=0} = 0,$$

$$\phi_{0}(x=0) = 0, \quad \phi_{0}(x=d) = V_{s},$$
(5)

where the anode voltage V is related to the electron density profile $n_b^0(x)$ by 1-5

$$V_{s} = 4\pi e \int_{0}^{d} dx'' \int_{0}^{x''} dx' n_{b}^{0}(x').$$
 (6)

Equation (6) follows from solving $\partial^2 \phi_0 / \partial x^2 = 4\pi e n_b^0(x)$ in the anodecathode gap and enforcing the boundary conditions in Eq. (5).

Within the context of Assumptions (a) - (c), the electron density $n_b(x,y,t)$ and electrostatic potential $\phi(x,y,t)$ are determined self-consistently from Poisson's equation and the equation of continuity, i.e.,

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right) \phi = 4\pi e n_b , \qquad (7)$$

and

$$\frac{\partial \mathbf{n}_{\mathbf{b}}}{\partial \mathbf{t}} + \frac{\partial}{\partial \mathbf{x}} (\mathbf{n}_{\mathbf{b}} \mathbf{V}_{\mathbf{b}\mathbf{x}}) + \frac{\partial}{\partial \mathbf{y}} (\mathbf{n}_{\mathbf{b}} \mathbf{V}_{\mathbf{b}\mathbf{y}}) = 0 \quad . \tag{8}$$

Making use of Eq. (3) to eliminate V_{bx} and V_{by} in favor of ϕ , the continuity equation (8) can be expressed in the equivalent form

$$\frac{\partial \mathbf{n}_{\mathbf{b}}}{\partial \mathbf{t}} - \frac{\mathbf{c}}{\mathbf{B}_{\mathbf{0}}} \left[\frac{\partial}{\partial \mathbf{x}} \left(\mathbf{n}_{\mathbf{b}} \frac{\partial \phi}{\partial \mathbf{y}} \right) - \frac{\partial}{\partial \mathbf{y}} \left(\mathbf{n}_{\mathbf{b}} \frac{\partial \phi}{\partial \mathbf{x}} \right) \right] = 0 \quad . \tag{9}$$

Equations (7) and (9) constitute coupled equations describing the nonlinear evolution of the electrostatic potential $\phi(x,y,t)$ and the electron density $n_b(x,y,t)$.

B. Nonlinear Evolution of Average Quantities

In the analysis that follows, it is convenient to express all field and fluid quantities as an average value (averaged <u>over y</u>) plus a perturbation. That is, a general quantity $\psi(x,y,t)$ is expressed as

$$\psi(\mathbf{x},\mathbf{y},\mathbf{t}) = \langle \psi \rangle (\mathbf{x},\mathbf{t}) + \delta \psi (\mathbf{x},\mathbf{y},\mathbf{t}), \qquad (10)$$

where the average value $\langle \psi \rangle(x,t)$ is defined by

$$\langle \psi \rangle (\mathbf{x}, t) \equiv \frac{1}{L} \int_{0}^{L} dy \psi (\mathbf{x}, \mathbf{y}, t).$$
 (11)

Here, L is the periodicity length in the y-direction, and it follows from Eqs. (10) and (11) that $\langle \delta \psi \rangle = 0$.

Averaging Poisson's equation (7) over y, we find that

$$\frac{\partial^2}{\partial x^2} <\phi> = 4\pi e , \qquad (12)$$

which relates the average potential $\langle \phi \rangle(x,t)$ to the average density $\langle n_b \rangle(x,t)$. Moreover, averaging the continuity equation (9) over y and making use of periodicity in the y-direction gives

$$\frac{\partial}{\partial t} \langle n_{b} \rangle = \frac{c}{B_{0}} \frac{\partial}{\partial x} \langle n_{b} \frac{\partial \phi}{\partial y} \rangle$$
(13)

for the evolution of $\langle n_b \rangle$. Expressing $n_b(x,y,t) = \langle n_b \rangle(x,t) + \delta n_b(x,y,t)$ and $\phi(x,y,t) = \langle \phi \rangle(x,t) + \delta \phi(x,y,t)$ on the righthand side of Eq. (13), and making use of $(\partial/\partial y) \langle \phi \rangle = 0$ and $\langle \delta n_b \rangle = 0$, it readily follows that Eq. (13) can be expressed in the equivalent form

$$\frac{\partial}{\partial t} \langle n_{b} \rangle = \frac{c}{B_{0}} \frac{\partial}{\partial x} \langle \delta n_{b} \frac{\partial}{\partial y} \delta \phi \rangle , \qquad (14)$$

which describes the (slow) nonlinear evolution of the average density profile $\langle n_b \rangle(x,t)$ in response to the perturbations δn_b and $\delta \phi$.

C. Nonlinear Evolution of Perturbed Quantities

In Eqs. (7) and (9), we express the potential $\phi(x,y,t)$ and electron density $n_b(x,y,t)$ as average values plus perturbations, i.e.,

$$\phi(\mathbf{x},\mathbf{y},t) = \langle \phi \rangle(\mathbf{x},t) + \delta \phi(\mathbf{x},\mathbf{y},t),$$

$$n_{b}(\mathbf{x},\mathbf{y},t) = \langle n_{b} \rangle(\mathbf{x},t) + \delta n_{b}(\mathbf{x},\mathbf{y},t),$$
(15)

where $\langle \phi \rangle$ and $\langle n_b \rangle$ evolve according to Eqs. (12) and (14). Subtracting Eq. (12) from Eq. (7) gives Poisson's equation for the perturbed potential $\delta \phi(x,y,t)$,

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right)\delta\phi = 4\pi e \delta n_b.$$
 (16)

On the other hand, substituting Eq. (15) into the continuity equation (9) and making use of $(\partial/\partial y) < \phi > = 0$, we find

$$\frac{\partial}{\partial t} (\langle \mathbf{n}_{\mathbf{b}} \rangle + \delta \mathbf{n}_{\mathbf{b}}) - \frac{\mathbf{c}}{\mathbf{B}_{\mathbf{0}}} \frac{\partial}{\partial \mathbf{x}} \left[(\langle \mathbf{n}_{\mathbf{b}} \rangle + \delta \mathbf{n}_{\mathbf{b}}) \frac{\partial}{\partial \mathbf{y}} \delta \phi \right] + \frac{\mathbf{c}}{\mathbf{B}_{\mathbf{0}}} \frac{\partial}{\partial \mathbf{y}} \left[(\langle \mathbf{n}_{\mathbf{b}} \rangle + \delta \mathbf{n}_{\mathbf{b}}) \frac{\partial}{\partial \mathbf{x}} (\langle \phi \rangle + \delta \phi) \right] = 0.$$
(17)

Defining the average $E \times B_0 \hat{e}_z$ flow velocity in the y-direction by

$$V_{E}(x,t) = -\frac{c \langle E_{X} \rangle}{B_{0}} = \frac{c}{B_{0}} \frac{\partial}{\partial x} \langle \phi \rangle (x,t), \qquad (18)$$

and eliminating $\partial < n_b > /\partial t$ from Eq. (17) by means of Eq. (14), it follows that Eq. (17) can be expressed in the equivalent form

$$\begin{pmatrix} \frac{\partial}{\partial t} + V_{\rm E} & \frac{\partial}{\partial y} \end{pmatrix} \delta n_{\rm b} - \frac{c}{B_0} \begin{pmatrix} \frac{\partial}{\partial y} & \delta \phi \end{pmatrix} \frac{\partial}{\partial x} \langle n_{\rm b} \rangle$$

$$= \frac{c}{B_0} \left[\left(\frac{\partial}{\partial y} & \delta \phi \right) \left(\frac{\partial}{\partial x} & \delta n_{\rm b} \right) - \left(\frac{\partial}{\partial x} & \delta \phi \right) \left(\frac{\partial}{\partial y} & \delta n_{\rm b} \right) \right]$$

$$- \frac{\partial}{\partial x} \langle \delta n_{\rm b} & \frac{\partial}{\partial y} & \delta \phi \rangle .$$

$$(19)$$

In Eq. (19), we have transposed all terms explicitly bilinear in $\delta \phi \delta n_{\rm b}$ to the right-hand side.

Equations (12) and (16) for $\langle \phi \rangle(\mathbf{x}, t)$ and $\delta \phi(\mathbf{x}, \mathbf{y}, t)$, and Eqs. (14) and (19) for $\langle \mathbf{n}_b \rangle(\mathbf{x}, t)$ and $\delta \mathbf{n}_b(\mathbf{x}, \mathbf{y}, t)$ constitute a closed description of the nonlinear evolution of the system, which is fully equivalent to the Poisson-continuity equations (7) and (9). In circumstances where the initial density profile $\langle \mathbf{n}_b \rangle(\mathbf{x}, 0)$ corresponds to linear instability, the perturbations $\delta \phi$ and $\delta \mathbf{n}_b$ amplify, and the average density profile $\langle \mathbf{n}_b \rangle(\mathbf{x}, t)$ readjusts in response to the unstable field perturbations according to Eq. (14).

A lowest-order <u>quasilinear</u> analysis (Sec. III)¹³ of Eqs. (12), (14), (16) and (19) proceeds by neglecting all bilinear nonlinearities on the right-hand side of Eq. (19) for δn_b . The resulting equation for δn_b is then solved in conjunction with Eq. (16) for $\delta \phi$, and the resulting expressions are substituted into Eq. (14) to determine the quasilinear response of the average density profile $\langle n_b \rangle (x,t)$ to the unstable field perturbations.

D. Boundary Conditions

For completeness, we conclude this section with a brief discussion of the boundary conditions assumed in the present analysis. In particular, it is assumed that there is zero net flux of electrons at the cathode (x = 0) and at the anode (x = d), i.e., $n_b V_{xb} = 0$ at x = 0 and x = d. Equivalently, from Eq. (3), this condition can be expressed as

$$E_{y} = -\frac{\partial}{\partial y}\phi = 0, \text{ at } x = 0 \text{ and } x = d, \qquad (20)$$

or $(\partial/\partial y) \delta \phi = 0$ at x = 0 and x = d, since $(\partial/\partial y) \langle \phi \rangle = 0$. It then follows directly from Eqs. (20) and (14) [or Eq. (13)] that

$$\frac{\partial}{\partial t} \int_{0}^{d} dx \langle n_{b} \rangle = 0.$$
 (21)

That is, however complicated the nonlinear evolution of the average density profile $\langle n_b \rangle (x,t)$, the total number of electrons in the cathode-anode region is conserved. Of course, this is expected because of the zero-net-flux boundary conditions at the cathode and anode [Eq. (20].

Finally, assuming that space-charge limited flow is maintained with $\langle E_x \rangle = - (\partial/\partial x) \langle \phi \rangle = 0$ at x = 0, it follows from Poisson's equation (12) for $\langle \phi \rangle$ that $\langle \phi \rangle$ and $\langle n_b \rangle$ are related by

$$\langle \phi \rangle (\mathbf{x}, t) = 4\pi e \int_{0}^{\mathbf{x}} d\mathbf{x}'' \int_{0}^{\mathbf{x}''} d\mathbf{x}' \langle \mathbf{n}_{b} \rangle (\mathbf{x}', t),$$
 (22)

where $\langle \phi \rangle = 0$ at x = 0. Evaluating Eq. (22) at x = d, we find that the anode voltage V_s(t) consistent with space-charge-limited flow is given by

$$V_{s}(t) = 4\pi e \int_{0}^{d} dx'' \int_{0}^{x''} dx' < n_{b} > (x', t).$$
 (23)

III. QUASILINEAR THEORY OF DIOCOTRON INSTABILITY

A. Quasilinear Kinetic Equations

With regard to Poisson's equation (16) for $\delta \phi$ and the continuity equation (19) for δn_b , it is convenient to Fourier decompose perturbed quantities with respect to their y-dependence. That is, we express

$$\begin{split} &\delta\phi(\mathbf{x},\mathbf{y},t) = \sum_{\mathbf{k}} \delta\phi_{\mathbf{k}}(\mathbf{x},t) \exp(i\mathbf{k}\mathbf{y}), \\ &\delta n_{\mathbf{b}}(\mathbf{x},\mathbf{y},t) = \sum_{\mathbf{k}} \delta n_{\mathbf{b}\mathbf{k}}(\mathbf{x},t) \exp(i\mathbf{k}\mathbf{y}), \end{split}$$
(24)

where $k = 2\pi n/L$, L is the periodicity length in the y-direction, n is an integer, and the summation is from $n = -\infty$ to $n = +\infty$. Equation (16) then gives

$$\frac{\partial^2}{\partial x^2} \delta \phi_k - k^2 \delta \phi_k = 4\pi e \delta n_{bk} , \qquad (25)$$

which relates $\delta \phi_k(x,t)$ and $\delta n_{bk}(x,t)$. At the quasilinear level of description (see discussion at the end of Sec. II.C), the right-hand side of Eq. (19) is approximated by zero, corresponding to the neglect of bilinear nonlinearities in the evolution of δn_b . Fourier decomposing Eq. (19) then gives

$$\left(\frac{\partial}{\partial t} + ikV_{\rm E}\right) \delta n_{\rm bk} = \frac{ikc}{B_0} \delta \phi_k \frac{\partial}{\partial x} \langle n_{\rm b} \rangle , \qquad (26)$$

where [from Eqs. (18) and (22)] $V_{E}(x,t)$ is given by

$$V_{\rm E}(\mathbf{x},t) = \frac{c}{B_0} \quad \frac{\partial}{\partial \mathbf{x}} <\phi> = \frac{4\pi ec}{B_0} \int_0^{\mathbf{x}} d\mathbf{x'} <\mathbf{n}_b>(\mathbf{x'},t) . \tag{27}$$

In Eqs. (26) and (27), the (slow) evolution of $\langle n_b \rangle (x,t)$ is calculated self-consistently in terms of $\delta \phi$ and δn_b from Eq. (14), which can be expressed in Fourier variables as

$$\frac{\partial}{\partial t} \langle n_{b} \rangle = \frac{c}{B_{0}} \frac{\partial}{\partial x} \sum_{k} \delta n_{bk} (-ik) \delta \phi_{-k}.$$
(28)

Equations (25) - (28) constitute coupled nonlinear equations for the evolution of $\delta \phi_k$, δn_{bk} and $\langle n_b \rangle$ at the quasilinear level of description.

To analyze Eqs. (25) and (26), we consider amplifying $(\gamma_k > 0)$ perturbations with time dependence of the form

$$\delta \phi_{k}(\mathbf{x}, t) = \hat{\delta \phi}_{k}(\mathbf{x}) \exp \left\{ \int_{0}^{t} dt' \left[-i\omega_{k}(t') + \gamma_{k}(t') \right] \right\},$$

$$\delta n_{bk}(\mathbf{x}, t) = \hat{\delta n}_{bk}(\mathbf{x}) \exp \left\{ \int_{0}^{t} dt' \left[-i\omega_{k}(t') + \gamma_{k}(t') \right] \right\}.$$
(29)

In Eq. (29), the growth rate $\gamma_k(t)$ and oscillation frequency $\omega_k(t)$ are allowed to vary slowly in time in response to the slow evolution of $\langle n_b \rangle(x,t)$ in Eq. (28). Substituting Eq. (29) into Eq. (26) and solving for δn_{bk} gives

$$\delta \mathbf{n}_{\mathbf{b}\mathbf{k}} = \frac{-(\mathbf{k}\mathbf{c}/\mathbf{B}_0)\,\delta\phi_{\mathbf{k}}}{\omega_{\mathbf{k}} - \mathbf{k}\mathbf{V}_{\mathbf{E}} + \mathbf{i}\gamma_{\mathbf{k}}} \frac{\partial}{\partial \mathbf{x}} \langle \mathbf{n}_{\mathbf{b}} \rangle . \tag{30}$$

Moreover, substituting Eq. (30) into Eq. (25), Poisson's equation for $\delta \phi_k$ becomes

$$\frac{\partial^{2}}{\partial x^{2}} \delta \phi_{k} - k^{2} \delta \phi_{k} = \frac{-(4\pi e kc/B_{0}) \delta \phi_{k}}{\omega_{k} - kV_{E} + i\gamma_{k}} \frac{\partial}{\partial x} \langle n_{b} \rangle , \qquad (31)$$

where $\gamma_k > 0$ is assumed. Note that Eqs. (30) and (31) are identical in form to the equations for δn_{bk} and $\delta \phi_k$ obtained

in standard linear theory, ^{8,9,12} assuming perturbations about quasisteady equilibrium profiles $\langle n_b \rangle$ and V_E . The only difference in the present <u>quasilinear</u> analysis is that $\langle n_b \rangle (x,t)$ is allowed to vary slowly in time [Eq. (28)], which leads to a corresponding slow (adiabatic) variation in the growth rate $\gamma_k(t)$ and oscillation frequency $\omega_k(t)$ as calculated from the eigenvalue equation (31).¹³

Substituting Eq. (30) into Eq. (28), the average density profile $\langle n_b \rangle (x,t)$ evolves according to

$$\frac{\partial}{\partial t} \langle \mathbf{n}_{b} \rangle = \left(\frac{c}{B_{0}}\right)^{2} \frac{\partial}{\partial \mathbf{x}} \left(\sum_{k} \frac{ik^{2} |\delta\phi_{k}|^{2}}{\omega_{k} - kV_{E} + i\gamma_{k}} \frac{\partial}{\partial \mathbf{x}} \langle \mathbf{n}_{b} \rangle\right) .$$
(32)

In obtaining Eq. (32), use has been made of the conjugate symmetry

$$\delta \phi_{-k}(\mathbf{x}, t) = \delta \phi_{k}^{\star}(\mathbf{x}, t), \qquad (33)$$

which follows from Eq. (24) since $\delta\phi(x,y,t)$ is a real-valued function. Consistent with Eq. (33), it follows from Eq. (29) that the oscillation frequency ω_k and growth rate γ_k satisfy the symmetries

$$\omega_{-k} = -\omega_{k} , \qquad (34)$$

$$\gamma_{-k} = \gamma_{k} , \qquad (34)$$

and the amplitude $\hat{\delta \phi}_{k}(x)$ satisfies $\hat{\delta \phi}_{-k} = \hat{\delta \phi}_{k}^{*}$. Making use of

$$\frac{1}{\omega_{k} - kV_{E} + i\gamma_{k}} = \frac{(\omega_{k} - kV_{E}) - i\gamma_{k}}{(\omega_{k} - kV_{E})^{2} + \gamma_{k}^{2}}$$

and the symmetries in Eq. (34) to eliminate the odd functions of k on the right-hand side of Eq. (32), we find that the quasilinear kinetic equation for $\langle n_b \rangle$ can be expressed as

$$\frac{\partial}{\partial t} \langle \mathbf{n}_{\mathbf{b}} \rangle = \frac{\partial}{\partial \mathbf{x}} \left[D(\mathbf{x}, t) \frac{\partial}{\partial \mathbf{x}} \langle \mathbf{n}_{\mathbf{b}} \rangle \right], \qquad (35)$$

where the diffusion coefficient D(x,t) is defined by

$$D(x,t) = \left(\frac{c}{B_0}\right)^2 \sum_{k} \frac{k^2 |\delta\phi_k|^2 \gamma_k}{(\omega_k - kV_E)^2 + \gamma_k^2} , \qquad (36)$$

and $\gamma_k > 0$ is assumed. Moreover, from Eq. (29), the quantity $|\delta \phi_k|^2$ evolves according to

$$\frac{\partial}{\partial t} \left| \delta \phi_{\mathbf{k}} \right|^{2} = 2\gamma_{\mathbf{k}} \left| \delta \phi_{\mathbf{k}} \right|^{2} .$$
(37)

To summarize, the quasilinear evolution of $\langle n_b \rangle$ and $|\delta \phi_k|^2$ is described by the coupled kinetic equations (35) and (37), where the diffusion coefficient D is defined in Eq. (36). Moreover, the growth rate $\gamma_k(t)$ and oscillation frequency $\omega_k(t)$ are determined adiabatically from the linear eigenvalue equation (31) with $\langle n_b \rangle$ changing slowly in time according to the kinetic eugation (35). Typically, if the initial profile $\langle n_b \rangle (x,t=0)$ corresponds to instability with $\gamma_k(0) > 0$, the perturbations will amplify [Eq. (37)], and the density profile $\langle n_b \rangle (x,t)$ will readjust [Eq. (35)] in such a way as to reduce the growth rate $\gamma_k(t)$ and stabilize the instability [Eqs. (31) and (37)].

For future reference, we consider Eqs. (36) and (37) in the limit of a continuous k-spectrum with

$$\sum_{k} \frac{k^{2} |\delta \phi_{k}|^{2}}{8\pi} \cdots \rightarrow \int dk \ \mathcal{E}_{k} \cdots \qquad (38)$$

Here, $\mathcal{E}_{k} = k^{2} |\delta \phi_{k}|^{2} / 8\pi$ is the spectral energy density associated with the δE_{y} electric field perturbations. In the continuum limit, Eqs. (36) and (37) become

$$D(x,t) = \frac{8\pi c^2}{B_0^2} \int dk \frac{\gamma_k \mathcal{E}_k}{(\omega_k - kV_E)^2 + \gamma_k^2} , \qquad (39)$$

and

$$\frac{\partial}{\partial t} \hat{\boldsymbol{\varepsilon}}_{k} = 2\gamma_{k} \hat{\boldsymbol{\varepsilon}}_{k} , \qquad (40)$$

where γ_k is the linear growth rate determined from Eq. (31).

B. Quasilinear Growth Rate

The growth rate γ_k and oscillation frequency ω_k are determined from the eigenvalue equation (31). In terms of the amplitude $\hat{\delta \phi}_k(x)$ [Eq. (29)], Eq. (31) can be expressed as

$$\frac{\partial^{2}}{\partial x^{2}} \hat{\phi}_{k} - k^{2} \hat{\phi}_{k} = -\frac{k \delta \phi_{k}}{\omega_{k} - k V_{E} + i \gamma_{k}} \frac{4 \pi e^{2}}{m \omega_{c}} \frac{\partial}{\partial x} \langle n_{b} \rangle , \qquad (41)$$

where $\omega_c = eB_0/mc$ is the electron cyclotron frequency. For specified $\langle n_b \rangle$ and corresponding self-consistent flow velocity V_E [Eq. (27)], Eq. (41) can be solved for the eigenfunction $\delta \phi_k$ and complex eigenfrequency $\omega_k + i\gamma_k$. This has been done in the literature for a variety of unstable profiles.^{8,9,12}

Equation (41) can also be used to derive an effective dispersion relation for $\omega_k + i\gamma_k$ in circumstances where the

functional form of $\hat{\delta \phi}_{k}(x)$ is known. Multiplying Eq. (41) by $\hat{\delta \phi}_{-k} = \hat{\delta \phi}_{k}^{\star}$, integrating from x = 0 to x = d, and making use of $\hat{\delta \phi}_{k}(x = 0) = 0 = \hat{\delta \phi}_{k}(x = d)$ [Eq. (20)] give

$$0 = \in (k, \omega_{k} + i\gamma_{k}) = \int_{0}^{d} dx \left\{ \left| \frac{\partial}{\partial x} \delta \hat{\phi}_{k} \right|^{2} + k^{2} \left| \delta \hat{\phi}_{k} \right|^{2} - \frac{k \left| \delta \hat{\phi}_{k} \right|^{2}}{\omega_{k} - kV_{E} + i\gamma_{k}} \frac{4\pi e^{2}}{m\omega_{c}} \frac{\partial}{\partial x} \langle n_{b} \rangle \right\}$$

$$(42)$$

For specified $\hat{\phi}_k(x)$, Eq. (42) plays the role of a dispersion relation that determines $\omega_k + i\gamma_k$. Setting real and imaginary parts of Eq. (42) separately equal to zero gives

$$0 = \operatorname{Re} \in = \int_{0}^{d} dx \left\{ \left| \frac{\partial}{\partial x} \hat{\delta \phi}_{k} \right|^{2} + k^{2} \left| \hat{\delta \phi}_{k} \right|^{2} - \frac{k \left(\omega_{k} - k V_{E} \right) \left| \hat{\delta \phi}_{k} \right|^{2}}{\left(\omega_{k} - k V_{E} \right)^{2} + \gamma_{k}^{2}} \frac{4 \pi e^{2}}{m \omega_{c}} \frac{\partial}{\partial x} \langle n_{b} \rangle \right\},$$

$$(43)$$

and

$$0 = Im \in = \in_{i} = k\gamma_{k} \frac{4\pi e^{2}}{m\omega_{c}} \int_{0}^{d} dx \frac{|\hat{\delta \phi}_{k}|^{2}}{(\omega_{k} - kV_{E})^{2} + \gamma_{k}^{2}} \frac{\partial}{\partial x} \langle n_{b} \rangle. \quad (44)$$

Equation (44) can be used to prove the well-known sufficient condition for stability. That is, if 9,12

$$\frac{\partial}{\partial \mathbf{x}} < \mathbf{n}_{\mathbf{b}} > \leq 0 \tag{45}$$

over the interval 0 < x < d, then Eq. (41) does not support unstable solutions with $\gamma_k > 0$. That is, $\gamma_k \leq 0$ and the perturbations are damped or purely oscillatory for monotonic decreasing density profiles of the form illustrated in Fig. 2(a). Equivalently, a <u>necessary condition for instability</u> ($\gamma_k > 0$) is that $(\partial/\partial x) < n_b >$ or $(\partial^2/\partial x^2) V_E$ [Eqs. (12) and (18)] change sign on the interval 0 < x < d. Therefore, density profiles that are instantaneously of the form illustrated in Figs. 2(b) - 2(d) are expected to yield the diocotron instability driven by a shear in the velocity profile V_E . Hollow density profiles [Figs. 2(b) and 2(c)] tend to give strong instability, whereas profiles with a gentle density bump [Fig. 2(d)] give a weak resonant instability characterized by relatively small growth rate γ_k .^{9,12}

For the case of weak resonant diocotron instability [Fig. 2(d)] characterized by $|\gamma_k| << |\omega_k|$, the effective dispersion relation (42) can be further simplified. For small γ_k , we approximate

$$0 = \epsilon(\mathbf{k}, \omega_{\mathbf{k}} + i\gamma_{\mathbf{k}}) = \epsilon_{\mathbf{r}}(\mathbf{k}, \omega_{\mathbf{k}}) + i\left[\epsilon_{\mathbf{i}}(\mathbf{k}, \omega_{\mathbf{k}}) + \gamma_{\mathbf{k}} \frac{\partial \epsilon_{\mathbf{r}}}{\partial \omega_{\mathbf{k}}}\right] + \dots, \quad (46)$$

and

$$\lim_{\gamma_{k} \to 0_{+}} \frac{1}{\omega_{k} - kV_{E} + i\gamma_{k}} = \frac{P}{\omega_{k} - kV_{E}} - i\pi\delta(\omega_{k} - kV_{E}), \qquad (47)$$

where P denotes Cauchy principal value. Substituting Eqs. (42) and (47) into Eq. (46) gives

$$0 = \epsilon_{r}(k, \omega_{k}) = \int_{0}^{d} dx \left\{ \left| \frac{\partial}{\partial x} \hat{\delta \phi}_{k} \right|^{2} + k^{2} \left| \hat{\delta \phi}_{k} \right|^{2} - \frac{kP \left| \delta \phi_{k} \right|^{2}}{\omega_{k} - kV_{E}} \frac{4\pi e^{2}}{m\omega_{c}} \frac{\partial}{\partial x} \langle n_{b} \rangle \right\},$$

$$(48)$$

and

$$\gamma_{\mathbf{k}} = -\frac{\epsilon_{\mathbf{i}}}{\partial \epsilon_{\mathbf{r}} / \partial \omega_{\mathbf{k}}} = -\pi \int_{0}^{\mathbf{d}} d\mathbf{x} |\hat{\delta \phi}_{\mathbf{k}}|^{2} \delta(\omega_{\mathbf{k}} - \mathbf{k} \mathbf{V}_{\mathbf{E}}) \frac{\partial}{\partial \mathbf{x}} < \mathbf{n}_{\mathbf{b}} >$$
(49)

 $\times \left[\int_{0}^{d} dx \frac{|\hat{\delta \phi}_{k}|^{2} p}{(\omega_{k} - k V_{E})^{2}} \frac{\partial}{\partial x} \langle n_{b} \rangle\right]^{-1}.$

Denoting by $x = x_{s}(k)$ the resonant layer where

$$\omega_{\mathbf{k}} - \mathbf{k} \mathbf{V}_{\mathbf{E}}(\mathbf{x}_{\mathbf{S}}) = 0 \quad , \tag{50}$$

it follows from Eq. (49) that the growth rate γ_k can be expressed as 9,12

$$Y_{k} = \pi \left[\frac{\left| \hat{\delta \phi}_{k} \right|^{2}}{\left| k \partial V_{E} / \partial x \right|} \frac{\partial}{\partial x} \langle n_{b} \rangle \right]_{x = x_{s}}$$
(51)

$$\times \left[\int_{0}^{d} dx \frac{\left| \hat{\delta \phi}_{k} \right|^{2} P}{\left(\omega_{k} - k V_{E} \right)^{2}} \frac{\partial}{\partial x} \langle n_{b} \rangle \right]^{-1}$$

For $\partial \epsilon_r / \partial \omega_k < 0$, and therefore $[\cdots]^{-1} > 0$ in Eq. (51), it follows from the above expression that $\gamma_k > 0$ (corresponding to instability) whenever the resonant layer x_s falls in the region of positive density slope, i.e.,

$$\frac{\partial}{\partial \mathbf{x}} < \mathbf{n}_{\mathbf{b}} > \Big|_{\mathbf{x} = \mathbf{x}_{\mathbf{s}}} > 0 , \qquad (52)$$

as illustrated in Fig. 2(d). In circumstances where the nonlinear response of the system described by Eqs. (35) and (37) is such that the density profile flattens in the vicinity of $x = x_s$ with $(\partial/\partial x) < n_b > |_{x = x_s} \neq 0$, it follows from Eq. (51) that

 $\gamma_k \neq 0$ corresponding to marginal stability and saturation of the wave spectrum [Eq. (40]. The quasilinear stabilization of the resonant diocotron instability driven by a gentle density bump is discussed in Sec. IV.C.

For future reference and use in Sec. IV.C, we summarize here the limiting forms of the diffusion coefficient D [Eq. (39)] for the case of weak resonant diocotron instability. In particular, taking $\gamma_k \neq 0_+$ in Eq. (39) in the resonant region of x-space where $\omega_k - kV_E = 0$, it follows that D can be approximated by

$$D_{r}(x,t) = \frac{8\pi^{2}c^{2}}{B_{0}^{2}} \int dk \boldsymbol{\mathcal{E}}_{k} \delta(\omega_{k} - kV_{E}). \qquad (53)$$

On the other hand, in the non-resonant region of x-space where $(\omega_k - kV_E)^2 >> \gamma_k^2$, it follows from Eq. (39) that D can be approximated by

$$D_{nr}(x,t) = \frac{8\pi c^2}{B_0^2} \int dk \frac{\gamma_k \mathcal{E}_k}{(\omega_k - kV_E)^2} .$$
 (54)

The approximate forms of D_r and D_{nr} in Eqs. (53) and (54) are calculated to the same accuracy as Eqs. (48) and (51) for ω_k and γ_k .

IV. STABILIZATION PROCESS

In this section, we make use of the formalism developed in Sec. III to describe several features of the quasilinear stabilization process, both in the general case (Sec. IV.B) and in circumstances corresponding to weak resonant diocotron instability (Sec. IV.C).

A. Summary of Quasilinear Equations

For convenient reference, we summarize here in one location the full set of equations used in the quasilinear description of the diocotron instability derived in Sec. III. In particular, the kinetic equation describing the evolution of the average density profile $\langle n_b \rangle (x,t)$ is given by [Eq. (35)]

$$\frac{\partial}{\partial t} \langle \mathbf{n_b} \rangle = \frac{\partial}{\partial \mathbf{x}} \left(\mathbf{D} \; \frac{\partial}{\partial \mathbf{x}} \; \langle \mathbf{n_b} \rangle \right), \tag{55}$$

where the diffusion coefficient D(x,t) is defined by [Eq. (39)]

$$D(x,t) = \frac{8\pi c^2}{B_0^2} \int dk \frac{\gamma_k \mathcal{E}_k}{(\omega_k - kV_E)^2 + \gamma_k^2}$$
(56)

for $\gamma_k > 0$, and the spectral energy density \mathcal{E}_k evolves according to [Eq. (40)]

$$\frac{\partial}{\partial t} \hat{\boldsymbol{\mathcal{E}}}_{\mathbf{k}} = 2\gamma_{\mathbf{k}} \hat{\boldsymbol{\mathcal{E}}}_{\mathbf{k}} \quad .$$
 (57)

In Eqs. (55) - (57), the spectral energy density is defined by $\mathcal{E}_{k} = k^{2} |\delta \phi_{k}|^{2} / 8\pi = (k^{2} |\hat{\delta \phi}_{k}(x)|^{2} / 8\pi) \exp \left\{ 2 \int_{0}^{t} dt' \gamma_{k}(t') \right\}$, where the eigenfunction $\hat{\delta \phi}_{k}(x)$ and the complex oscillation frequency $\omega_{k} + i \gamma_{k}$ are determined from the eigenvalue equation [Eq. (41)]

$$\frac{\partial^{2}}{\partial x^{2}} \hat{\delta \phi}_{k} - k^{2} \hat{\delta \phi}_{k} = - \frac{k \delta \phi_{k}}{\omega_{k} - k \nabla_{E} + i \gamma_{k}} \frac{4 \pi e^{2}}{m \omega_{c}} \frac{\partial}{\partial x} \langle n_{b} \rangle.$$
(58)

Moreover, the average flow velocity $V_E(x,t) = (c/B_0)(\partial/\partial x) < \phi >$ in Eqs. (56) and (58) is defined by [Eq. (27)]

$$V_{E} = \frac{4\pi ec}{B_{0}} \int_{0}^{x} dx' < n_{b} > (x',t) , \qquad (59)$$

where $\langle n_b \rangle$ evolves according to Eq. (55). Note from Eq. (58) that $\omega_k + i\gamma_k$ varies adiabatically in time in response to the slow evolution of $\langle n_b \rangle$ and V_E . Making use of Eq. (20), the eigenvalue equation (58) is to be solved subject to the boundary conditions

$$\delta \phi_k = 0$$
, at $x = 0$ and $x = d$. (60)

Correspondingly, the spectral energy density satisfies $\mathscr{E}_{\mathbf{k}} = 0$ at the cathode (x = 0) and at the anode (x = d), and it follows from Eq. (56) that

$$D=0$$
, at $x=0$ and $x=d$. (61)

In the limiting case of weak resonant diocotron instability driven by a gentle density bump [Fig. 2(d)], or in circumstances where a more general initial profile for $\langle n_b \rangle$ [Fig. 2(b), say] evolves according to Eqs. (55) - (59) to a regime characterized by weak resonant instability, it follows from the analysis in Sec. III.B that $\langle n_b \rangle$ and \hat{e}_k evolve according to Eqs. (55) and (57), where the diffusion coefficient D is approximated by [Eqs. (53) and (54)]

$$D^{\simeq} \begin{cases} D_{r} = \frac{8\pi^{2}c^{2}}{B_{0}^{2}} \int dk \ \boldsymbol{\ell}_{k} \delta \left(\omega_{k} - kV_{E}\right), \text{ for } \omega_{k} - kV_{E} = 0, \\ \\ D_{nr} = \frac{8\pi c^{2}}{B_{0}^{2}} \int dk \ \frac{\gamma_{k} \boldsymbol{\ell}_{k}}{\left(\omega_{k} - kV_{E}\right)^{2}}, \text{ for } \left(\omega_{k} - kV_{E}\right)^{2} > \gamma_{k}^{2}. \end{cases}$$

$$(62)$$

Explicit expressions for the eigenfunction $\delta \hat{\phi}_k$, the growth rate γ_k , and the oscillation frequency ω_k appearing in Eq. (62) must generally be determined from the eigenvalue equation (58). However, for specified $\delta \hat{\phi}_k$, it also follows from the analysis in Sec. III.B that ω_k and γ_k can be estimated from Eqs. (48) and (51), respectively, for weak resonant instability.

B. General Features of the Stabilization Process

Consider the smooth initial density profile $\langle n_b \rangle (x,t=0)$ corresponding to instability illustrated by the solid curve in Fig. 3(a). Assume $\gamma_k (t=0) > 0$ and non-zero initial excitation of $|\delta \phi_k|^2$. In Fig. 3(a), the density maximum at t=0 is located at $x = x_m$. Moreover, from Eq. (59) and Fig. 3(a), the corresponding initial flow velocity profile $V_E(x,t=0)$ has the form illustrated by the solid curve in Fig. 3(b), with inflection point $[V_E'(x,t=0)=0]$ located at $x = x_m$.

Several important features of the general quasilinear development of the system follow directly from Eqs. (55) - (61).

(a) <u>Number Conservation</u>: First, number conservation readily follows upon integrating Eq. (55) from x = 0 to x = d and enforcing Eq. (61), i.e.,

$$\frac{\partial}{\partial t} \int_0^d dx \langle n_b \rangle (x,t) = 0 .$$
 (63)

[See also Eq. (21)].

 (b) <u>Conservation of Average x-Location</u>: Second, the densityweighted, average x-location of the electrons is also conserved, i.e.,

$$\frac{\partial}{\partial t} \int_0^d dx \ x < n_b > (x, t) = 0.$$
 (64)

The proof of Eq. (64) proceeds as follows. Multiplying Eq. (55) by x, integrating from x = 0 to x = d, and enforcing Eq. (61) gives

$$\frac{\partial}{\partial t} \int_{0}^{d} dx \ x < n_{b} > = -\int_{0}^{d} dx \ D \ \frac{\partial}{\partial x} < n_{b} > .$$
 (65)

Multiplying the eigenvalue equation (31) by $(c/4\pi eB_0)k^{\delta\phi}_{-k}$, integrating from x = 0 to x = d, and integrating over k, we obtain

$$-\int_{0}^{d} dx \left(\frac{c}{B_{0}}\right)^{2} \int dk \frac{k^{2} |\delta\phi_{k}|^{2}}{\omega_{k} - kV_{E} + i\gamma_{k}} \frac{\partial}{\partial x} < n_{b} >$$

$$= -\left(\frac{c}{4\pi eB_{0}}\right) \int_{0}^{d} dx \int dk k \left(\left|\frac{\partial}{\partial x}\delta\phi_{k}\right|^{2} + k^{2} |\delta\phi_{k}|^{2}\right) .$$
(66)

The right-hand side of Eq. (66) vanishes identically since the integrand is an odd function of k. Equation (66) readily gives

$$-\int_{0}^{d} dx \left(\frac{c}{B_{0}}\right)^{2} dk \frac{k^{2} |\delta\phi_{k}|^{2}}{\omega_{k} - kV_{E} + i\gamma_{k}} \frac{\partial}{\partial x} \langle n_{b} \rangle = -\int_{0}^{d} dx D \frac{\partial}{\partial x} \langle n_{b} \rangle = 0, \quad (67)$$

which completes the proof of Eq. (64). Equation (64) is significant in that the density-weighted average x-location of the electrons is conserved, however complicated the quasilinear evolution of the system. That is, combining Eqs. (63) and (64), we obtain

$$\bar{\mathbf{x}} = \frac{\int_{0}^{\bar{d}} d\mathbf{x} \, \langle \mathbf{n}_{b} \rangle}{\int_{0}^{\bar{d}} d\mathbf{x} \, \langle \mathbf{n}_{b} \rangle} = \text{const.}$$
(68)

(c) <u>Profile Evolution</u>: We consider Eqs. (55) and (56) for $\gamma_k > 0$, and integrate Eq. (55) from x = 0 to an arbitrary point x(0 < x < d). Enforcing the boundary condition D = 0 at x = 0 [Eq. (61)], we obtain

$$\frac{\partial}{\partial t} \int_{0}^{X} dx < n_{b} > (x, t) = D \frac{\partial}{\partial x} < n_{b} > , \qquad (69)$$

or equivalently, from Eq. (59),

$$\frac{\partial}{\partial t} V_{E}(x,t) = D \frac{\partial^{2}}{\partial x^{2}} V_{E}.$$
 (70)

Comparing with Fig. 3, it follows from Eqs. (69) and (70) that

$$\frac{\partial}{\partial t} \int_{0}^{x} dx \langle n_{b} \rangle \left| \begin{array}{c} \gtrless & 0, \text{ for } x \lessgtr x_{m}, \\ t=0 \end{array} \right|$$
(71)

and

$$\frac{\partial}{\partial t} V_{E} \begin{vmatrix} \geq 0, \text{ for } x \leq x_{m}, \\ t=0 \end{vmatrix}$$
(72)

where $x = x_m$ corresponds to the density maximum in Fig. 3. That is, at a subsequent time $t_0 > 0$, the profiles for $\langle n_b \rangle$ and V_E have evolved to the form illustrated by the dashed curves in Fig. 3, corresponding to a weakening of the density gradients, and a partial fill-in of the density depression. Therefore, during the initial stages of instability, the quasilinear response of the system is in the direction of stabilization and reducing the growth rate [Eqs. (57) and (58)].

C. Resonant Diocotron Instability

As a specific example, we now consider the quasilinear evolution of the diocotron instability for the configuration illustrated in Fig. 4. This corresponds to a gentle density bump superimposed on the rectangular profile

$$\langle n_{b} \rangle = \begin{cases} \hat{n}_{b} = \text{const.}, & 0 < x < b, \\ 0, & b < x < d. \end{cases}$$
 (73)

Such a configuration gives the weak resonant version 9,12 of the diocotron instability discussed in Sec. III.B, and the appropriate quasilinear equations describing the evolution of the system are given by Eqs. (55), (57) and (58), with diffusion coefficient D approximated by Eq. (62).

(a) <u>Real Oscillation Frequency</u>: For the configuration with gentle density bump illustrated in Fig. 4, the real frequency ω_k and eigenfunction $\delta \phi_k(x)$ are calculated to good accuracy from the eigenvalue equation (58), approximating the density profile by the rectangular form in Eq. (73). The eigenvalue equation (58) becomes

$$\frac{\partial^2}{\partial \mathbf{x}^2} \hat{\delta \phi}_{\mathbf{k}} - \mathbf{k}^2 \hat{\delta \phi}_{\mathbf{k}} = \frac{\mathbf{k} \hat{\delta \phi}_{\mathbf{k}} \omega_{\mathbf{d}}}{\omega_{\mathbf{k}} - \mathbf{k} \mathbf{V}_{\mathbf{E}}} \delta(\mathbf{x} - \mathbf{b}), \qquad (74)$$

where $\omega_d \equiv \hat{\omega}_{pb}^2 / \omega_c = 4\pi \hat{n}_b ec/B_0$, and the right-hand side of Eq. (74) corresponds to a surface-charge perturbation at x = b. Referring to Fig. 4, the solutions to Eq. (74) in Region I (0 < x < b) and Region II (b < x < d) that are continuous at the surface (x = b) of the electron layer are:

$$\hat{\delta \phi}_{k}^{I} = \hat{\phi}_{k} \sinh kx, \ 0 < x < b ,$$

$$\hat{\delta \phi}_{k}^{II} = \hat{\phi}_{k} \sinh kb \frac{\sinh k(d-x)}{\sinh k(d-b)}, \ b < x < d ,$$
(75)

where $\hat{\phi}_k$ is the amplitude (independent of x). Note from Eq. (75) that $\hat{\delta \phi}_k^{I}(x=0) = 0 = \hat{\delta \phi}_k^{II}(x=d)$ [Eq. (60)] at the cathode and anode. To determine ω_k , we integrate the eigenvalue equation across the surface at x = b from $x_- = b(1-\delta)$ to $x_+ = b(1+\delta)$ and take the limit $\delta \neq 0_+$. This gives

$$\begin{bmatrix} \frac{\partial}{\partial \mathbf{x}} & \hat{\boldsymbol{\delta}} \boldsymbol{\phi}_{\mathbf{k}}^{\mathrm{I}} \end{bmatrix}_{\mathbf{x}=\mathbf{b}} - \begin{bmatrix} \frac{\partial}{\partial \mathbf{x}} & \hat{\boldsymbol{\delta}} \boldsymbol{\phi}_{\mathbf{k}}^{\mathrm{I}} \end{bmatrix}_{\mathbf{x}=\mathbf{b}} = \frac{\mathbf{k} \begin{bmatrix} \hat{\boldsymbol{\delta}} \boldsymbol{\phi}_{\mathbf{k}}^{\mathrm{I}} \end{bmatrix}_{\mathbf{x}=\mathbf{b}}^{\omega} \mathbf{d}}{\omega_{\mathbf{k}} - \mathbf{k} \mathbf{V}_{\mathrm{E}}^{(\mathbf{x}=\mathbf{b})}} .$$
(76)

Substituting Eq. (75) into Eq. (76) readily gives

$$-\hat{\phi}_{k} \sinh kb \frac{\cosh k (d-b)}{\sinh k (d-b)} - \hat{\phi}_{k} \cosh kb = \frac{\omega_{d} \hat{\phi}_{k} \sinh kb}{\omega_{k} - kV_{E} (x=b)} .$$
(77)

Solving Eq. (77) for the real oscillation frequency ω_k , we find

$$\omega_{\mathbf{k}} - \mathbf{k} \mathbf{V}_{\mathbf{E}} (\mathbf{x} = \mathbf{b}) = -\frac{\omega_{\mathbf{d}}}{\coth \mathbf{k} \mathbf{b} + \coth \mathbf{k} (\mathbf{d} - \mathbf{b})} \cdot$$
(78)

From Eqs. (59) and (73), it follows that $V_E(x=b)$ in Eq. (78) can be expressed as $V_E(x=b) = \omega_d b$, where $\omega_d = \hat{\omega}_{pb}^2 / \omega_c = 4\pi \hat{n}_b ec/B_0$.

In the short-wavelength limit, it follows from Eq. (78) that $\omega_{\mathbf{k}}$ can be approximated by

$$\omega_{k} = kV_{E} (x = b) \left(1 - \frac{1}{2kb} \right) , \qquad (79)$$

for kb, k(d-b) >> 1. Moreover, for long wavelengths with kb, k(d-b) << 1, Eq. (78) gives

$$\omega_{\mathbf{k}} = \mathbf{k} \mathbf{V}_{\mathbf{E}} (\mathbf{x} = \mathbf{b}) \frac{\mathbf{b}}{\mathbf{d}} \quad . \tag{80}$$

A typical plot of ω_k versus kb is shown in Fig. 5 for d/b = 2.

(b) <u>Quasilinear Growth Rate</u>: Referring to Fig. 4, the resonant growth rate γ_k can be estimated from Eq. (51). Making use of $V_E = \omega_d x$ for 0 < x < b [Eq. (59)], and evaluating the [...]⁻¹ factor in Eq. (51) with $(\partial/\partial x) < n_b >$ approximated by $-\hat{n}_b \delta(x-b)$, we obtain from Eq. (51)

$$\gamma_{k} = \pi \frac{\left[\omega_{k} - kV_{E}(b)\right]^{2}}{\left|kV_{E}(b)\right|} \frac{\left|\hat{\delta\phi}_{k}^{I}\right|_{x=x_{S}}^{2}}{\left|\hat{\delta\phi}_{k}^{I}\right|_{x=b}^{2}} \frac{b}{\hat{n}_{b}} \frac{\partial}{\partial x} \langle n_{b} \rangle}{\left|x=x_{s}\right|}$$
(81)

In Eq. (81), $kV_E(b) = (kb)\omega_d$ and ω_k is determined from Eq. (78). Moreover, it follows from Eq. (75) that

$$\frac{\left|\hat{\delta\phi}_{k}^{I}\right|_{x=x_{s}}^{2}}{\left|\hat{\delta\phi}_{k}^{I}\right|_{x=b}^{2}} = \frac{\sinh^{2}kx_{s}}{\sinh^{2}kb} , \qquad (82)$$

and the resonant location $x = x_s(k)$ is determined from $\omega_k - kV_E(x_s) = 0$ [Eq. (50)]. Note from Eq. (81) that $\gamma_k > 0$ (corresponding to instability) whenever x_s falls in the region of positive density slope in Fig. 4.

Combining Eq. (78) with $\omega_k - kV_E(x_s) = 0$ gives for $x_s(k)$

$$k(b - x_s) = \frac{1}{\coth kb + \coth k(d - b)} \quad . \tag{83}$$

In the limits of short and long wavelengths, Eq. (83) reduces to the approximate results

$$\frac{x_s}{b} = \left(1 - \frac{1}{2kb}\right) , \text{ for } kb, k(d-b) >> 1, \qquad (84)$$

and

$$\frac{x}{b} = \frac{b}{d}, \text{ for } kb, k(d-b) << 1.$$
(85)

Therefore, from Eqs. (83) - (85), the <u>resonant</u> region of x-space covers the range (see also Fig. 4)

$$\frac{b^2}{d} \simeq x_{s1} < x_s < x_{s2} \simeq b, \qquad (86)$$

with the upper limit (x_{s2}) in Eq. (86) corresponding to short wavelengths, and the lower limit (x_{s1}) corresponding to long wavelengths. Referring to Eq. (86) and Fig. 4, we find for b/d = 1/2 (for example) that x_s covers the range $1/2 \leq x_s/b \leq 1$.

Finally, it readily follows that the nonresonant region of x-space satisfying $[\omega_k - kV_E(x)]^2 >> \gamma_k^2$ corresponds to

$$\left(\frac{x-x_s}{b}\right)^2 >> \frac{\gamma_k^2}{k^2 V_E^2(b)} , \qquad (87)$$

where $V_E(b) = \omega_d b$, and γ_k and x_s are defined in Eqs. (81) and (83).

(c) <u>Quasilinear Stabilization</u>: In the resonant region of x-space satisfying $\omega_k - kV_E(x) = 0$, the quasilinear diffusion equation (55) for $\langle n_b \rangle$ can be expressed as

$$\frac{\partial}{\partial t} \langle n_{b} \rangle = \frac{\partial}{\partial x} \left(D_{r} \frac{\partial}{\partial x} \langle n_{b} \rangle \right) , \qquad (88)$$

where the resonant diffusion coefficient D_r is given by [Eq. (62)]

$$D_{r} = \frac{16\pi^{2}c^{2}}{B_{0}^{2}} \int_{0}^{\infty} dk \, \hat{\mathcal{E}}_{k} \delta \left(\omega_{k} - kV_{E}\right)$$

$$= \frac{16\pi^{2}c^{2}}{B_{0}^{2}} \left[\frac{\hat{\mathcal{E}}_{k}(x,t)}{\left|\frac{\partial \omega_{k}}{\partial k} - V_{E}\right|} \right]_{k = k_{s}} (x)$$

$$(89)$$

In Eq. (89), $k_s(x)$ solves the resonance condition $\omega_{k_s} - k_s V_E(x) = 0$, where $V_E(x) = \omega_d x$ and ω_k is defined in Eq. (78). Substituting Eq. (78) into $\omega_{k_s} = k_s V_E(x)$ gives the transcendental equation for $k_s(x)$:

$$k_{s}b[\coth k_{s}b + \cosh k_{s}(d - b)] = \frac{b}{b - x} .$$
(90)

The spectral energy density $\hat{\mathcal{E}}_k$ in Eq. (89) of course evolves according to $(\partial/\partial t)\hat{\mathcal{E}}_k = 2\gamma_k \hat{\mathcal{E}}_k$ [Eq. (57)], where the linear growth rate $\gamma_k(t)$ is given in terms of $\langle n_b \rangle$ by Eq. (81).

An H-theorem describing the stabilization process in the resonant region of x-space $(x_{sl} \lesssim x \lesssim x_{s2})$ follows readily from Eqs. (88) and (89). Multiplying Eq. (88) by $\langle n_b \rangle$ and integrating over x gives

$$\frac{\partial}{\partial t} \int dx \langle n_{b} \rangle^{2} = -\int dx D_{r} \left(\frac{\partial}{\partial x} \langle n_{b} \rangle \right)^{2}$$

$$= -\frac{16\pi^{2}c^{2}}{B_{0}^{2}} \int dx \int_{0}^{\infty} dk \delta (\omega_{k} - kV_{E}) \mathcal{E}_{k}(x,t) \left(\frac{\partial}{\partial x} \langle n_{b} \rangle \right)^{2} \leq 0.$$
(91)

Analogous to the quasilinear stabilization of the one-dimensional bump-in-tail instability in velocity space,¹³ the time-asymptotic $(t \rightarrow \infty)$ solution inferred from Eq. (91) necessarily satisfies

$$\frac{\partial}{\partial x} < n_b > (x, t \to \infty) |_{x=x_s} = 0$$
 (92)

in the resonant region $(x_{s1} \stackrel{<}{_{\sim}} x \stackrel{<}{_{\sim}} x_{s2})$. We conclude from Eqs. (81) and (92) that

$$\gamma_{k}(t \to \infty) = 0, \qquad (93)$$

corresponding to plateau formation and quasilinear stabilization of the instability. From Eq. (93) and $(\partial/\partial t)\mathcal{E}_k = 2\gamma_k \mathcal{E}_k$, we conclude that the spectral energy density saturates at a steady asymptotic level $\mathcal{E}_k(x,\infty)$.

(d) Estimate of Saturation Level: To obtain a detailed estimate of the saturation level of the instability, it is generally necessary to solve the coupled quasilinear kinetic equations for $\langle n_b \rangle$ and \mathcal{E}_k for specified initial profile $\langle n_b \rangle (x,0)$. To obtain a simple order-of-magnitude estimate, however, it is adequate to make use of the conservation relation satisfied by

 $\int dx \ x < n_b >$ in the resonant region. Multiplying $(\partial/\partial t) < n_b > =$ $(\partial/\partial x) (D_r \partial < n_b > /\partial x)$ by x and integrating over x for the resonant particles gives

$$\left(\frac{\partial}{\partial t} \int d\mathbf{x} \, \mathbf{x} \, \langle \mathbf{n}_{b} \rangle \right)_{r} = - \frac{8\pi^{2}c^{2}}{B_{0}^{2}} \int d\mathbf{x} \int d\mathbf{k} \boldsymbol{\mathcal{E}}_{k} \, \delta \left(\boldsymbol{\omega}_{k} - \mathbf{k} \mathbf{V}_{E} \right) \frac{\partial}{\partial \mathbf{x}} \, \langle \mathbf{n}_{b} \rangle$$

$$= - \frac{8\pi^{2}c^{2}}{B_{0}^{2}} \int d\mathbf{k} \left| \frac{\boldsymbol{\mathcal{E}}_{k} \left(\mathbf{x}_{s}, t \right)}{|\mathbf{k}\mathbf{V}_{E}(\mathbf{b})|} \right| \quad \mathbf{b} \left| \frac{\partial}{\partial \mathbf{x}} \left\langle \mathbf{n}_{b} \right\rangle \right|_{\mathbf{x}_{s}}$$

$$(94)$$

where $x_s(k)$ solves $\omega_k - kV_E(x_s) = 0$ [Eq. (83)], and use has been made of $V_E(x) = \omega_d x$ and the definition of D_r in Eq. (62). Making use of Eq. (81) to eliminate $(\partial/\partial x) < n_b > |_{x=x_s}$, we can express Eq. (94) as

$$\left(\frac{\partial}{\partial t} \int d\mathbf{x} \, \mathbf{x} \, \langle \mathbf{n}_{b} \rangle \right)_{r} = - \frac{4\pi c^{2} \hat{\mathbf{n}}_{b}}{B_{0}^{2}} \int d\mathbf{k} \, \frac{2\gamma_{k} \boldsymbol{\mathcal{E}}_{k}(\mathbf{b}, t)}{\left[\omega_{k} - kV_{E}(\mathbf{b})\right]^{2}}$$

$$= - \frac{4\pi c^{2} \hat{\mathbf{n}}_{b}}{B_{0}^{2}} \, \frac{\partial}{\partial t} \int d\mathbf{k} \, \frac{\boldsymbol{\mathcal{E}}_{k}(\mathbf{b}, t)}{\left[\omega_{k} - kV_{E}(\mathbf{b})\right]^{2}} ,$$

$$(95)$$

where use has been made of $(\partial/\partial t) \hat{\mathcal{E}}_{k} = 2\gamma_{k} \hat{\mathcal{E}}_{k}$ and $\hat{\mathcal{E}}_{k}(x_{s},t) = \hat{\mathcal{E}}_{k}(b,t) \left| \hat{\delta \phi}_{k}^{I} \right|_{x=x_{s}}^{2} / \left| \hat{\delta \phi}_{k}^{I} \right|_{x=b}^{2}$, and the time variation of ω_{k} has been neglected in Eq. (95). Integrating Eq. (95) with respect to time gives the conservation relation

$$\Delta \left(\int d\mathbf{x} \, \mathbf{x} \, \langle \mathbf{n}_{\mathbf{b}} \rangle \right)_{\mathbf{r}} = - \frac{4\pi c^2 \hat{\mathbf{n}}_{\mathbf{b}}}{B_0^2} \Delta \left(\int d\mathbf{k} \, \frac{\mathcal{E}_{\mathbf{k}}(\mathbf{b}, \mathbf{t})}{\left[\omega_{\mathbf{k}} - \mathbf{k} \mathbf{V}_{\mathbf{E}}(\mathbf{b})\right]^2} \right) \quad , \quad (96)$$

where ΔF denotes F(t) - F(t = 0). As a point of consistency, if we make use of Eq. (62) for D_{nr} and the approximate form of $\langle n_b \rangle$ given in Eq. (73) in evaluating $\int dx D_{nr}(\partial/\partial x) < n_b > \text{for the non-resonant particles, then it is straightforward to show$

$$\left(\frac{\partial}{\partial t}\int dx \ x \ \langle n_b \rangle \right)_r + \left(\frac{\partial}{\partial t}\int dx \ \langle n_b \rangle \right)_n = 0, \quad (97)$$

which is consistent with the conservation law (64) proved in Sec. IV.B in the general case.

Equation (96) can be used to estimate the t $\rightarrow \infty$ saturation level of the perturbed fields. For present purposes, we make use of Eq. (78) to estimate $[\omega_k - kV_E(b)]^{-2} \approx 1/\omega_d^2$ in the integrand in Eq. (96), and denote the change in perturbed field energy density by $\Delta \mathcal{E}_F(t) = \int dk \mathcal{E}_k(b,t) - \int dk \mathcal{E}_k(b,0)$. Equation (96) then gives the order-of-magnitude estimate

$$\Delta \left(\int d\mathbf{x} \, \mathbf{x} \, \langle \mathbf{n}_{b} \rangle \right)_{r} \approx - \frac{4 \pi c^{2} \hat{n}_{b}}{B_{0}^{2} \omega_{d}^{2}} \Delta \mathcal{E}_{F} . \qquad (98)$$

As a simple model to estimate the left-hand side of Eq. (98), we assume that $\langle n_b \rangle$ initially has the <u>linear</u> profile $\hat{n}_b + (\Delta n_b / \Delta_b) [x - (b - \Delta_b / 2)]$ over the interval $b - \Delta_b \langle x \langle b \rangle$ at t = 0, and the <u>flat</u> profile \hat{n}_b as $t \to \infty$. That is, the initial density gradient in the bump region is assumed to be $(\partial/\partial x) \langle n_b \rangle = \Delta n_b / \Delta_b$, where Δ_b is the width of the density bump. Equation (98) then gives

$$\Delta \mathscr{E}_{F}(\infty) \approx \frac{1}{6} \frac{\Delta n_{b}}{\hat{n}_{b}} \frac{\Delta b^{2} \omega^{2}}{c^{2}} \frac{B^{2}}{8\pi}$$

$$= \frac{1}{6} \frac{\Delta n_{b}}{\hat{n}_{b}} \frac{\Delta b^{2}}{b^{2}} \frac{V_{E}^{2}(b)}{c^{2}} \frac{B^{2}}{8\pi}$$

$$= \frac{1}{6} \frac{\Delta n_{b}}{\hat{n}_{b}} \frac{\Delta b^{2}}{b^{2}} \frac{\langle E_{x}(b) \rangle^{2}}{8\pi} . \qquad (99)$$

Here, $\omega_{d} = \hat{\omega}_{pb}^{2} / \omega_{c} = 4\pi \hat{n}_{b} ec/B_{0}$, $V_{E}(b) = \omega_{d}b$, and $\langle E_{x}(b) \rangle = -4\pi \hat{n}_{b}b$ for the configuration considered here.

Equation (99) gives a useful order-of-magnitude estimate for the saturation level of the perturbed field for an initially unstable configuration characterized by a small density bump (Δn_b) with spatial width Δ_b . Assuming that the saturated field level $(t \rightarrow \infty)$ is much larger than the initial field level, then $\Delta \mathcal{E}_F(\infty) \simeq \int dk \mathcal{E}_k(b,\infty)$. Moreover $\int dk \mathcal{E}_k(b,\infty) = \int dk \ k^2 |\delta \phi_k(b,\infty)|^2 / 8\pi = \langle \delta E_V^2(b,\infty) \rangle / 8\pi$. Therefore, Eq. (99) reduces to

$$\langle \delta E_{y}^{2}(b,\infty) \rangle \approx \frac{1}{6} \quad \frac{\Delta_{b}^{2}}{b^{2}} \quad \frac{\Delta n_{b}}{\hat{n}_{b}} \langle E_{x}(b) \rangle^{2} \quad .$$
 (100)

It is clear from Eq. (100) that the perturbed fields can saturate at a substantial level, even for a moderately small density bump as measured by $\Delta n_{\rm b}/\hat{n}_{\rm b}$.

V. CONCLUSIONS

In the present analysis, a macroscopic cold-fluid model was used to investigate the quasilinear stabilization of the diocotron instability for sheared, nonrelativistic electron flow in a planar diode (Fig. 1). The nonneutral electron plasma was treated as a massless $(m \rightarrow 0)$ guiding-center fluid with flow velocity $\chi_b = -(c/B_0) \nabla \phi \times \hat{e}_z$ (Sec. II), and the continuity-Poisson equations were used to obtain coupled guasilinear kinetic equations describing the self-consistent evolution of the average density $<n_{b}>(x,t)$ and spectral energy density $\hat{e}_{k}(x,t)$ associated with the y-electric field perturbations (Sec. III). Several general features of the quasilinear evolution of the system were discussed in Sec. IV including a derivation of exact conservation constraints. Typically, if the initial profile $\langle n_b \rangle (x,t=0)$ corresponds to instability with $\gamma_k(0) > 0$, the perturbations amplify [Eq. (57)], and the density profile $\langle n_b \rangle (x,t)$ readjusts [Eq. (55)] in such a way as to reduce the growth rate $\gamma_{\mu}(t)$ and stabilize the instability [Eqs. (57) and (58)].

Finally, as a specific example, in Sec. IV.C we considered the quasilinear evolution of the diocotron instability for $\langle n_b \rangle (x,0)$ corresponding to a gentle density bump superimposed on a rectangular density profile in contact with the cathode (Fig. 4). Such a configuration gives a weak version of the diocotron instability. It was shown that the system stabilizes time-asymptotically by plateau formation [Eqs. (92) and (93)] in the resonant region

of x-space where $\omega_{\rm k} - {\rm kV}_{\rm E}({\rm x}) = 0$. Making use of the quasilinear equations to obtain an order-of-magnitude estimate [Eq. (100)] of the saturation level of the perturbed fields, it was shown that $\langle \delta E_{\rm y}^2({\rm b},\infty) \rangle / 8\pi \approx (1/6) (\Delta_{\rm b}/{\rm b})^2 (\Delta {\rm n}_{\rm b}/{\rm n}_{\rm b}) \langle E_{\rm x}({\rm b}) \rangle^2 / 8\pi$, where $\Delta {\rm n}_{\rm b}$ and $\Delta_{\rm b}$ are the characteristic height and width, respectively, of the density bump (Fig. 4).

Strictly speaking, for application to high-voltage diodes in inertial confinement fusion, the present analysis should be extended to include relativistic and electromagnetic effects as well as electron inertial effects. However, the present nonrelativistic treatment of the diocotron instability can be applied to low-voltage microwave generation devices such as magnetrons, traveling wave tubes and ubitrons, at least in the low-density regime with $\omega_{\rm pb}^2 \ll \omega_{\rm c}^2$.

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FIGURE CAPTIONS

- Fig. 1 Planar diode configuration with $B_0 = B_0 e_z$, and cathode and anode located at x = 0 and x = d, respectively.
- Fig. 2 Plot of <n_b> versus x for several density profiles with different stability properties. Solutions to eigenvalue equation (41) correspond to: (a) stable oscillations; (b) and (c) strong diocotron instability; and (d) weak resonant diocotron instability.
- Fig. 3 Quasilinear response of (a) average density profile $\langle n_b \rangle (x,t)$, and (b) average flow velocity $V_E(x,t)$, in response to the amplifying field perturbations [Eqs. (55) (59) and Eqs. (69) (72)].
- Fig. 4 Initial density profile $\langle n_b \rangle(x,0)$ corresponding to weak resonant diocotron instability. The resonant region of x-space satisfying $\omega_k - kV_E(x_s) = 0$ [Eq. (83)] covers the range $b^2/d \simeq x_{s1} < x_s < x_{s2} \simeq b$ [Eq. (86)].
- Fig. 5 Plot of normalized frequency $\omega_k/kV_E(b)$ versus kb obtained from Eq. (78) for d/b = 2.

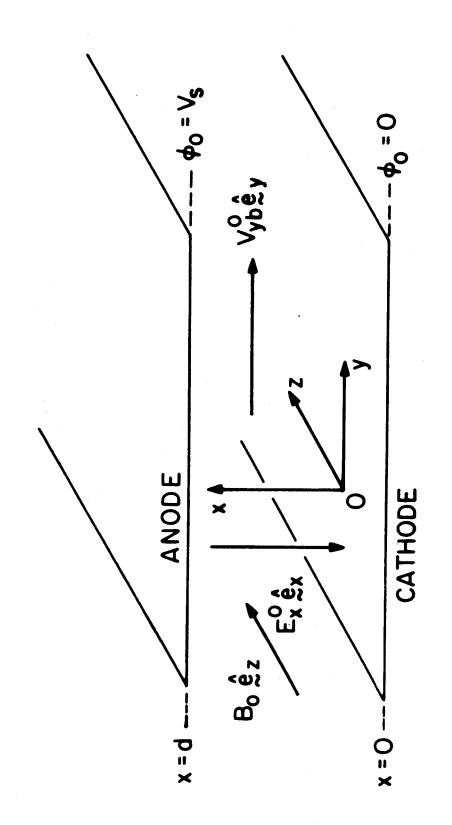


Fig. l

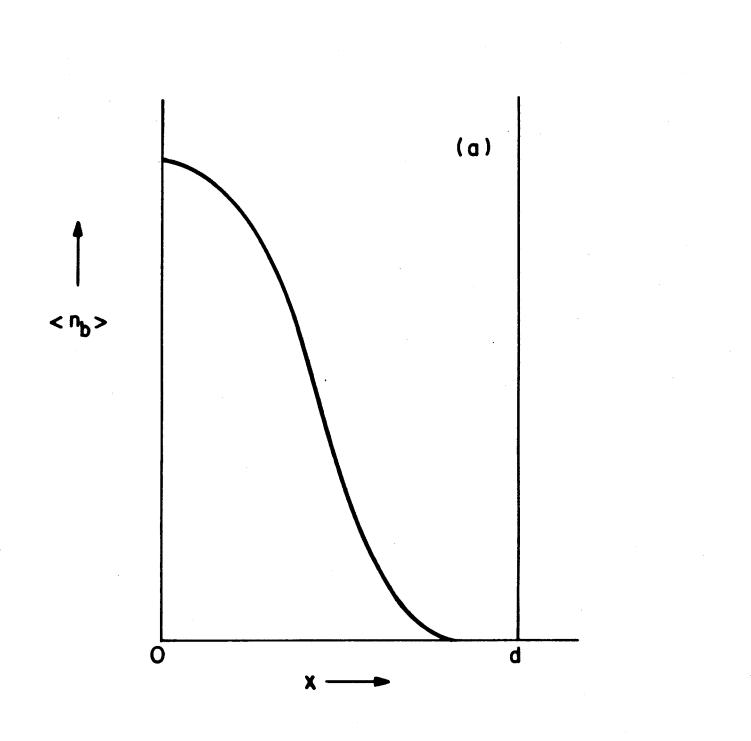
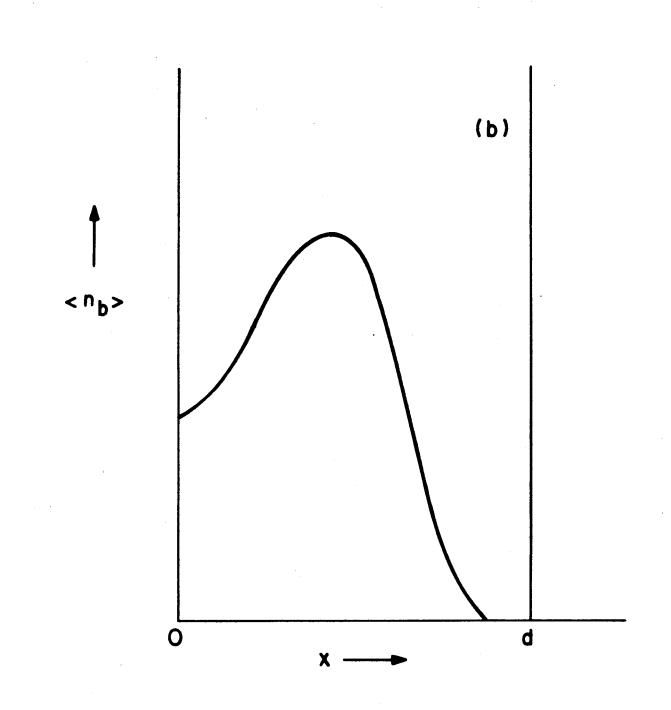


Fig. 2(a)





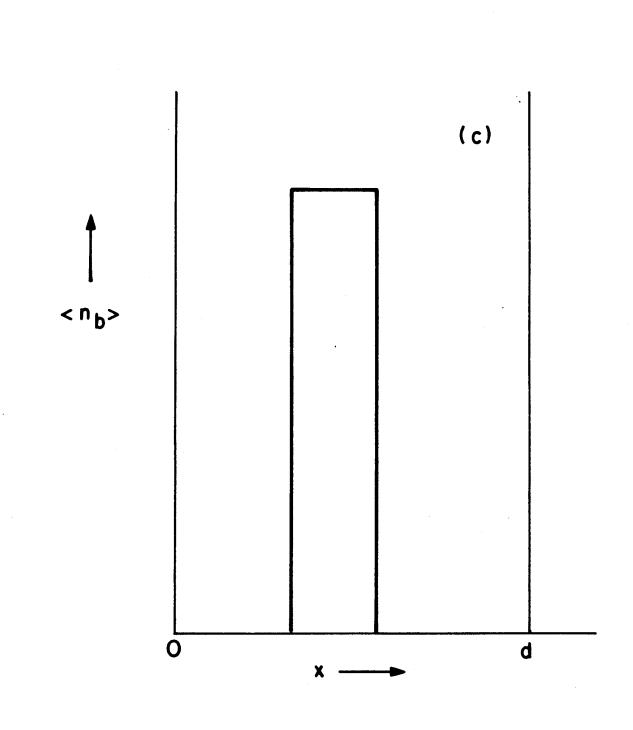


Fig. 2(c)

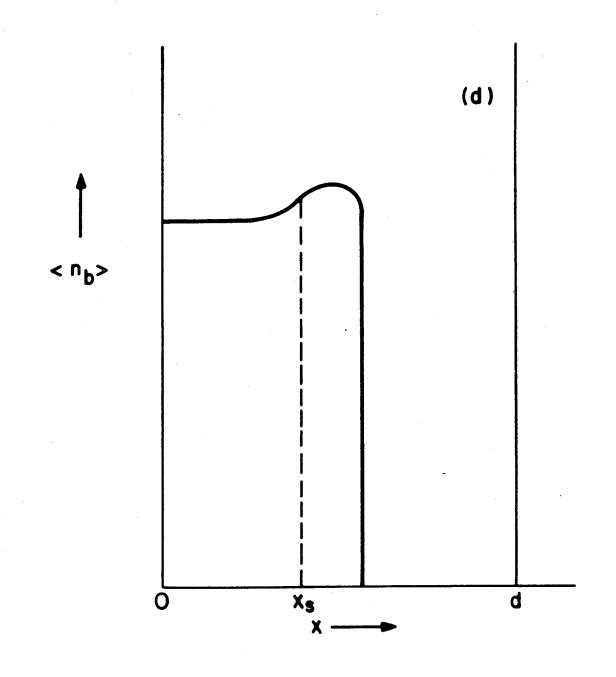


Fig. 2(d)

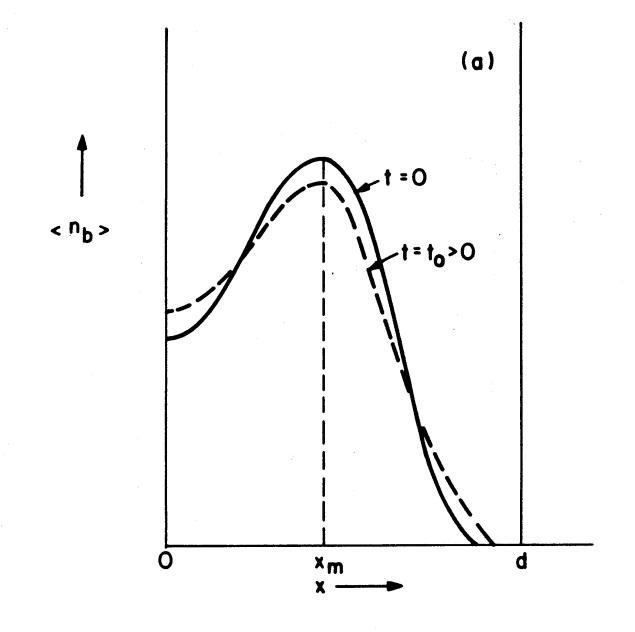


Fig. 3(a)

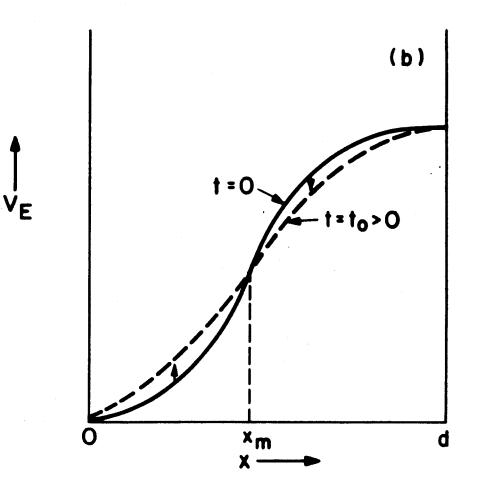


Fig. 3(b)

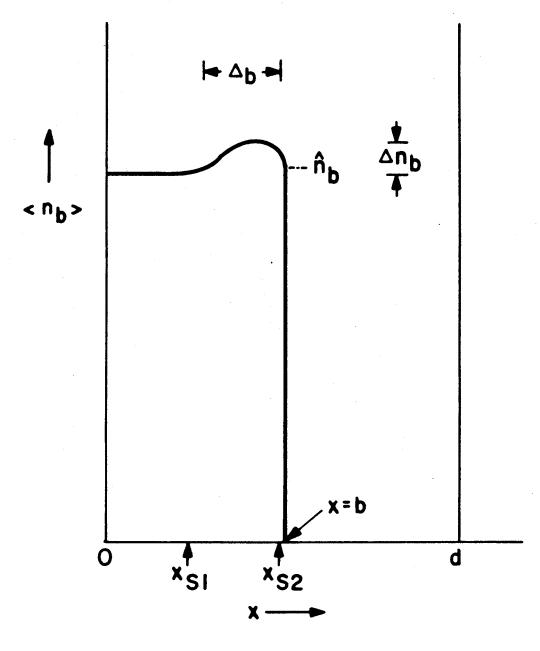


Fig. 4

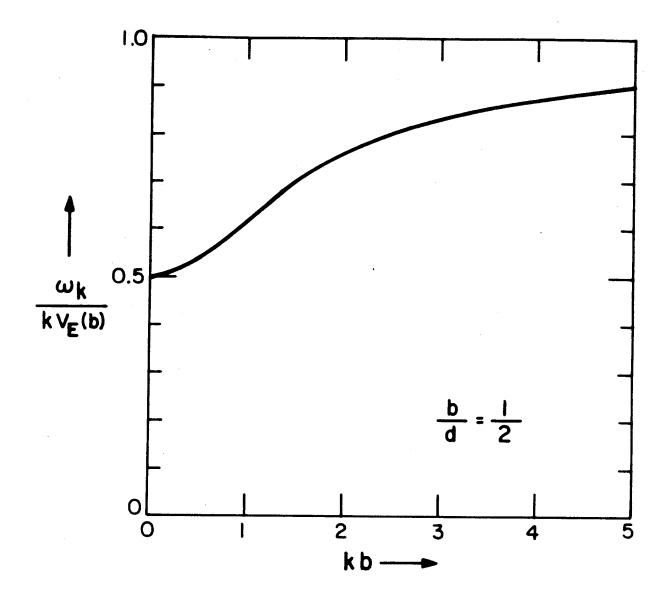


Fig. 5